

The Primal-Dual Hybrid Gradient Method for Semiconvex Splittings

SIAM Conference on Imaging Science, Albuquerque
Minisymposium on Non-Convex Regularization Methods in Image Restoration

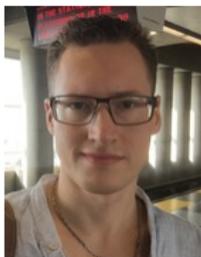
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Evgeny Strelakovsky



Michael Moeller



Daniel Cremers

Motivation: First-Order Splitting Methods

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- ▶ Well-established theory in the convex setting

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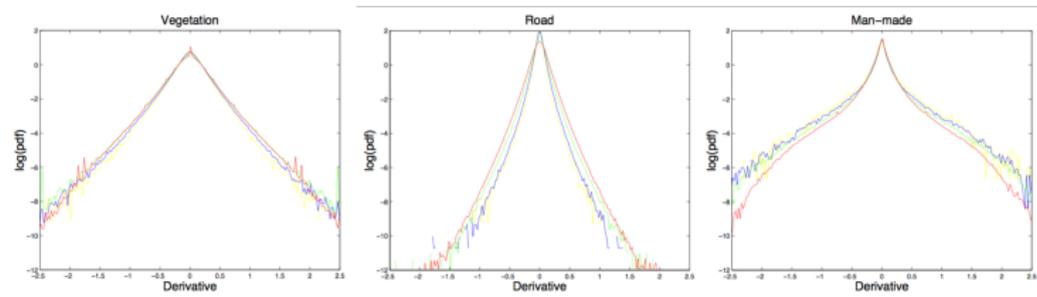
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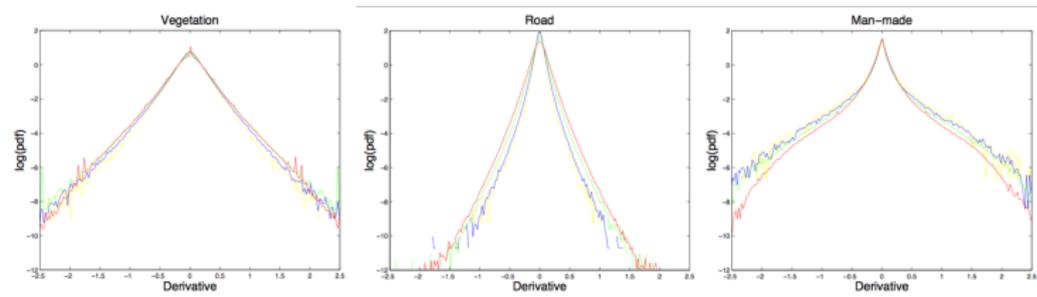
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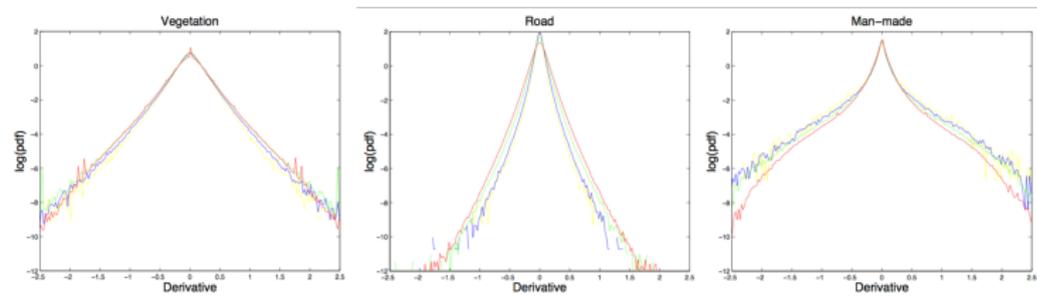
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- ▶ Piecewise smooth approximations [Blake, Zisserman '87], [Geman, Geman '84]

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- ▶ Remark: many other possibilities exist for nonsmooth nonconvex optimization

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- ▶ **Proposition:** Equivalent to original algorithm for convex F
- ▶ Can be applied to nonconvex F in a meaningful way

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- ▶ Reformulated PDHG applied to Mumford-Shah [Stekalovskiy, Cremers '14]

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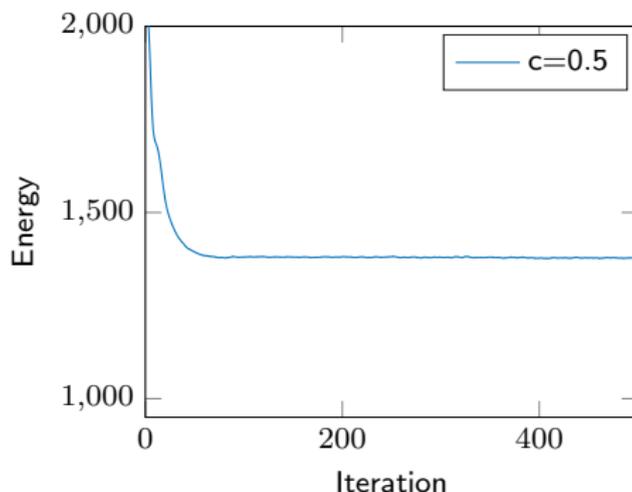
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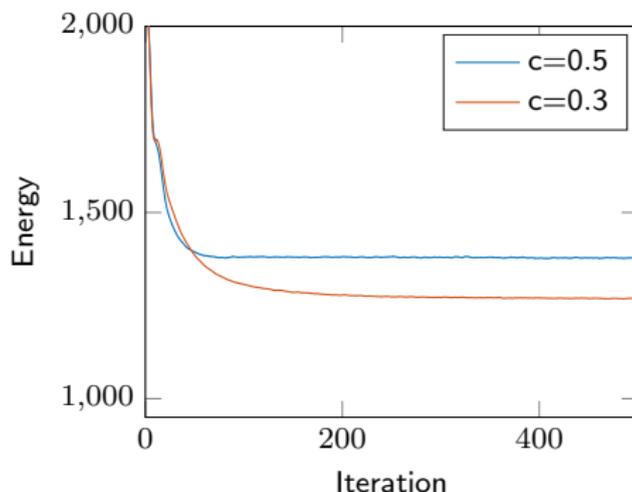


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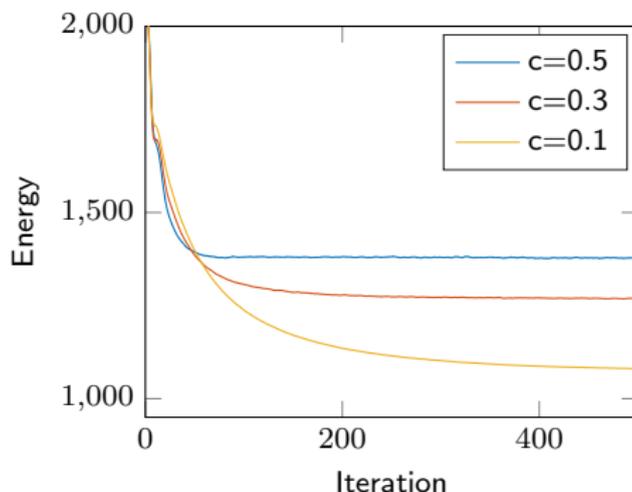


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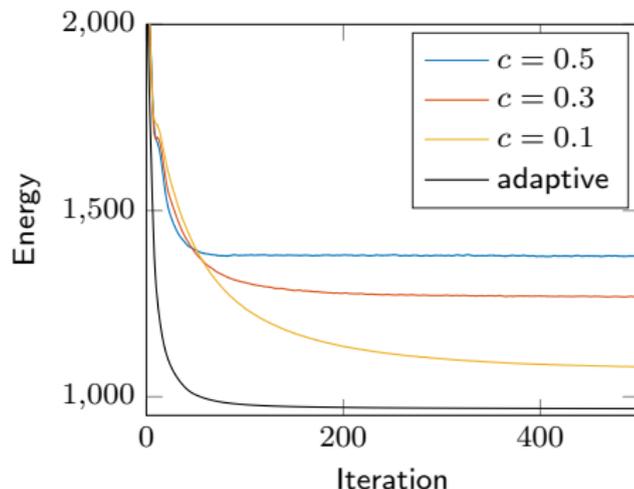
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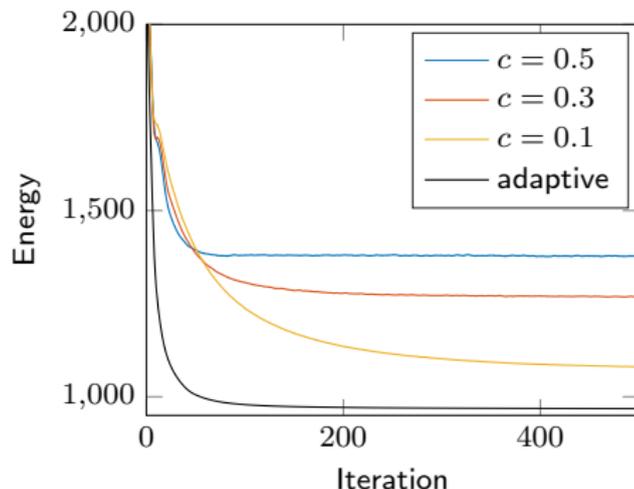


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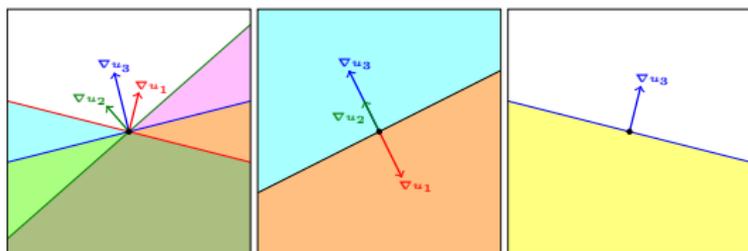
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- ▶ On recent GPU: ≈ 30 ms for 640×480 color image [Stekalovskiy, Cremers '14] (\rightarrow application: real-time video cartooning!)

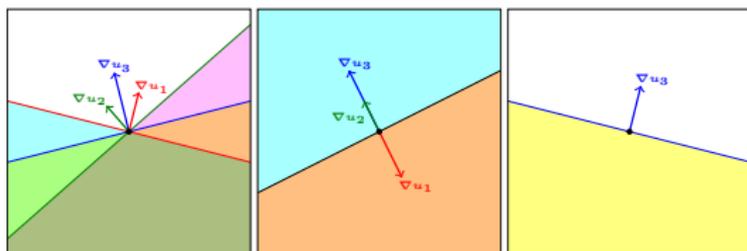
TV^q and TGV^q -like Regularization for Color Images



- For color images $u : \Omega \rightarrow \mathbb{R}^3$, consider at every pixel $i \in \Omega$ the Jacobian matrix

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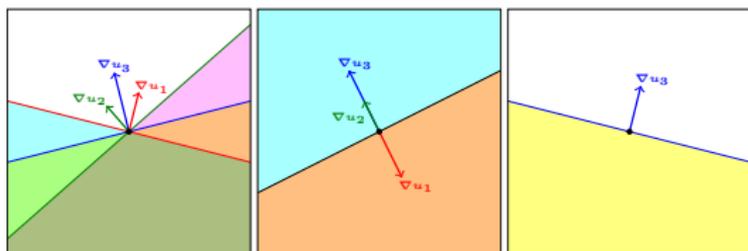


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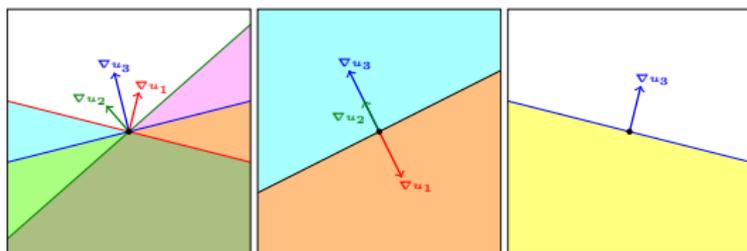
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- ▶ Nonconvex generalizations of above [M., Strelakovski, Moeller, Cremers '15]

$$TV_F^q(u) = \sum_{i \in \Omega} \|(\nabla u)_i\|_F^q, \quad TV_{S^q}^q(u) = \sum_{i \in \Omega} \|(\nabla u)_i\|_{S^q}^q, \quad q < 1$$

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- ▶ For color images $u : \Omega \rightarrow \mathbb{R}^3$, consider at every pixel $i \in \Omega$ the Jacobian matrix

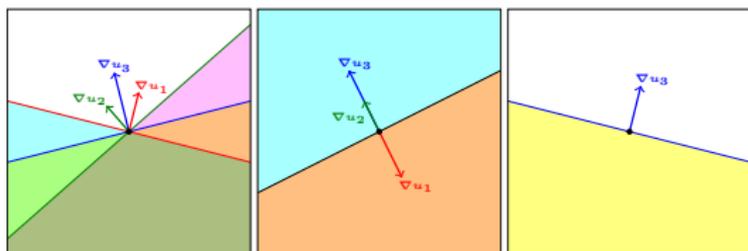
$$(\nabla u)_i = \begin{pmatrix} (\partial_x u_1)_i & (\partial_x u_2)_i & (\partial_x u_3)_i \\ (\partial_y u_1)_i & (\partial_y u_2)_i & (\partial_y u_3)_i \end{pmatrix}$$

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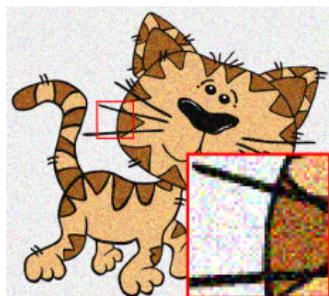
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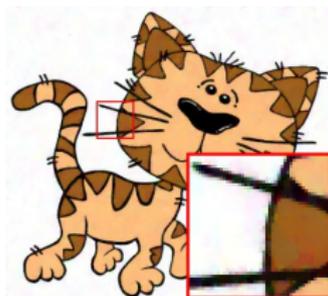
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- ▶ Can be efficiently solved using the nonconvex PDHG

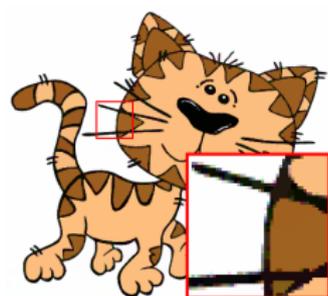
TV^q and TGV^q -like Regularization for Color Images, $q = 1/2$



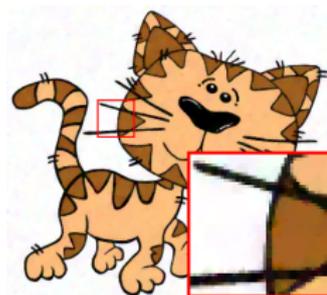
Noisy
 $\sigma = 0.15$



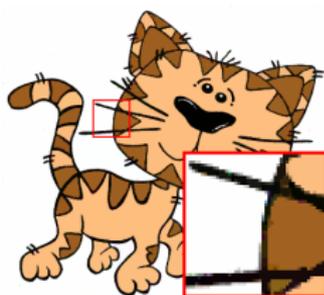
TV_F
PSNR=26.9



TV_F^q
PSNR=28.4

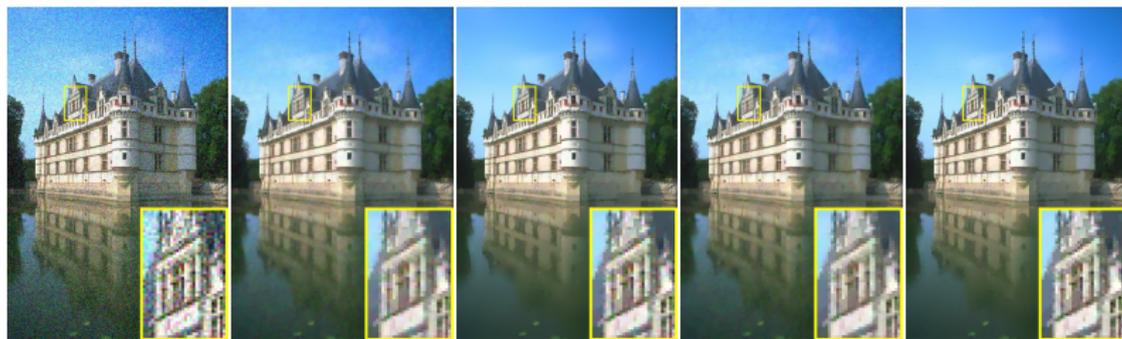


TV_{S^1}
PSNR=27.9



TV_{S^q}
PSNR=29.8

TV^q and TGV^q -like Regularization for Color Images, $q = 3/4$



Noisy
 $\sigma = 0.1$

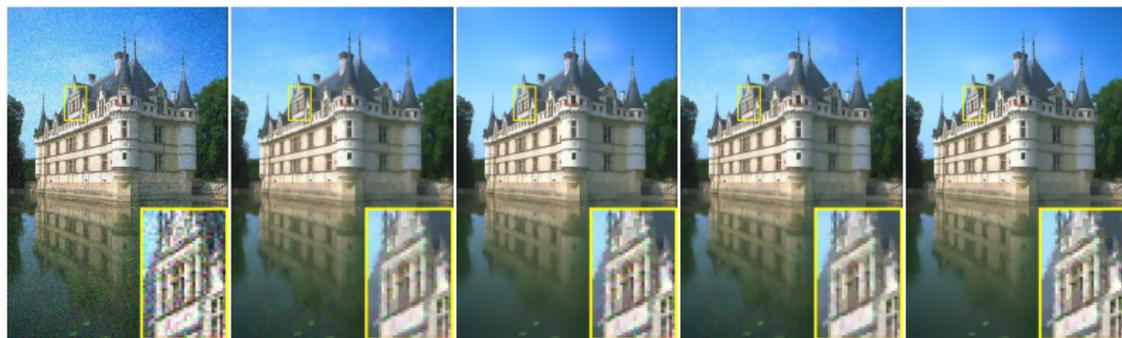
TGV_F
PSNR=28.5

TGV_F^q
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TGV_{S1}
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PSNR=29.4

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Algorithm works well in practice. Theoretical convergence properties?

Convergence Analysis of Nonconvex PDHG

Theorem ([M., Strelakovsky, Moeller, Cremers '15])

Let $G = \frac{c}{2} \|\cdot\|^2$ and $F = \frac{\omega}{2} \|\cdot\|^2$ be convex with $c > \omega \|K\|^2$. Then the (ergodic) iterates (X^k) produced by the PDHG converge to the (unique) global minimizer

$$\hat{x} = \arg \min_x G(x) + F(Kx),$$

with $\|X^k - \hat{x}\|^2 = \mathcal{O}(1/k)$ for $0 < \sigma = 2\omega$, $\tau\sigma\|K\|^2 \leq 1$, and any $\theta \in [0, 1]$.

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$$\text{prox}_{1/\sigma, F}(\tilde{z}) = \arg \min_z F(z) + \frac{\sigma}{2} \|z - \tilde{z}\|^2$$

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- ▶ **Theory-practice gap II:** for adaptive step sizes, experiments indicate that the algorithm converges for general nonconvex energies

Sharpness of the Step-Size Restriction and Consequences

- ▶ Consider the minimization of $\frac{\lambda-1}{2}x^2$ for some $\lambda > 1$:

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- ▶ Application: convex non-convex (CNC) models [Parekh, Selesnick '15], [Lanza, Morigi, Sgallari '16]

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- ▶ Local convergence result for nonlinear K [Valkonen '13], can also be used to do nonconvex regularization [Shekhovtsov, Reinbacher, Graber, Pock '16]

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Thank you for your attention!

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