

A Generalized Forward-Backward Splitting

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Class of composite problems

$$\min_{x \in \mathcal{H}} f(x) + \sum_{i=1}^n g_i(x)$$

Assumptions :

- $f, g_i : \mathcal{H} \rightarrow \mathbb{R} \cup \{+\infty\}$, $f, g_i \in \Gamma_0(\mathcal{H})$;
- f C^1 with β -Lipschitz gradient, all g_i 's are simple.
- Domain qualification condition : $(0, \dots, 0) \in \text{sri}(\{(x - y_1, \dots, x - y_n) : x \in \mathcal{H} \text{ and } y_i \in \text{dom}(g_i)\})$;
- Set of minimizers $\mathcal{M}^* \neq \emptyset$.

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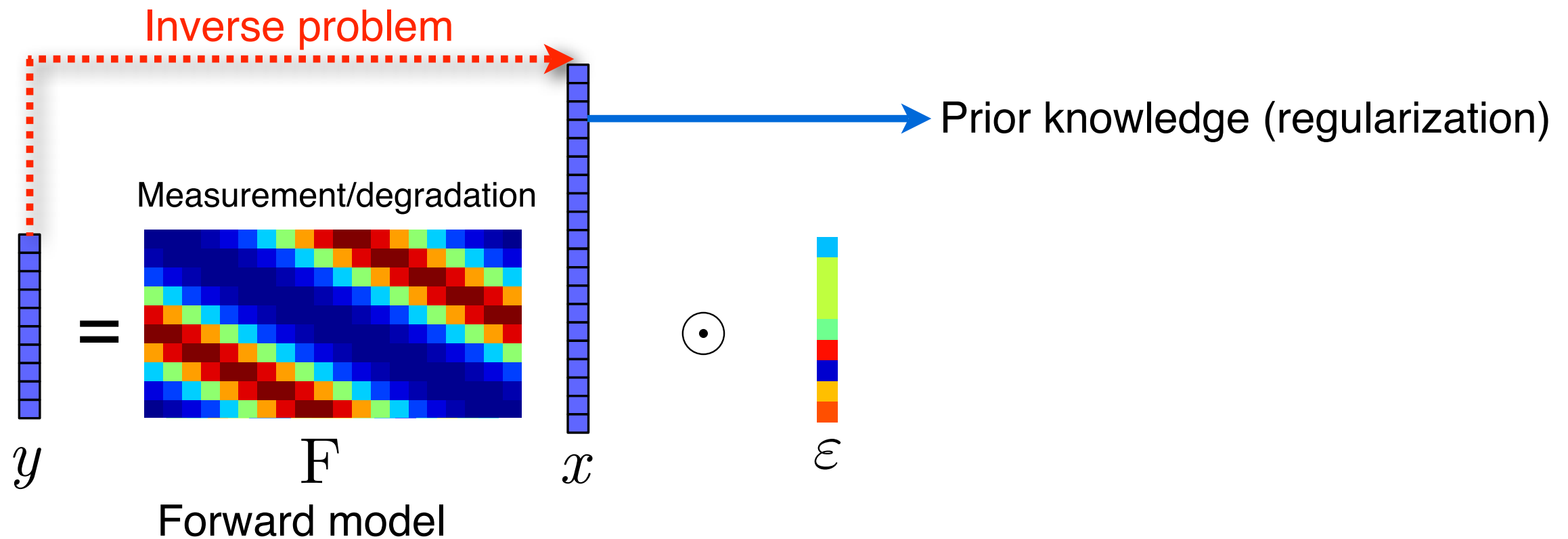
Requirements :

- Exploit the (composite) additive structure of the objective.
- Exploit the properties of the individual functions : g_i simple (proximity operator easy to compute) and f smooth.
- Deal with large scale data.
- Avoid nested algorithms.

Motivations

- Inverse problems with mixed regularization, e.g. :

$$\min_{x \in \mathcal{H}} \underbrace{f(x)}_{\text{Data fidelity}} + \underbrace{g_1(x) + \dots + g_n(x)}_{\text{Regularization, constraints}}$$



Typical models

Smooth, piecewise-smooth, sparse, cartoon, etc..

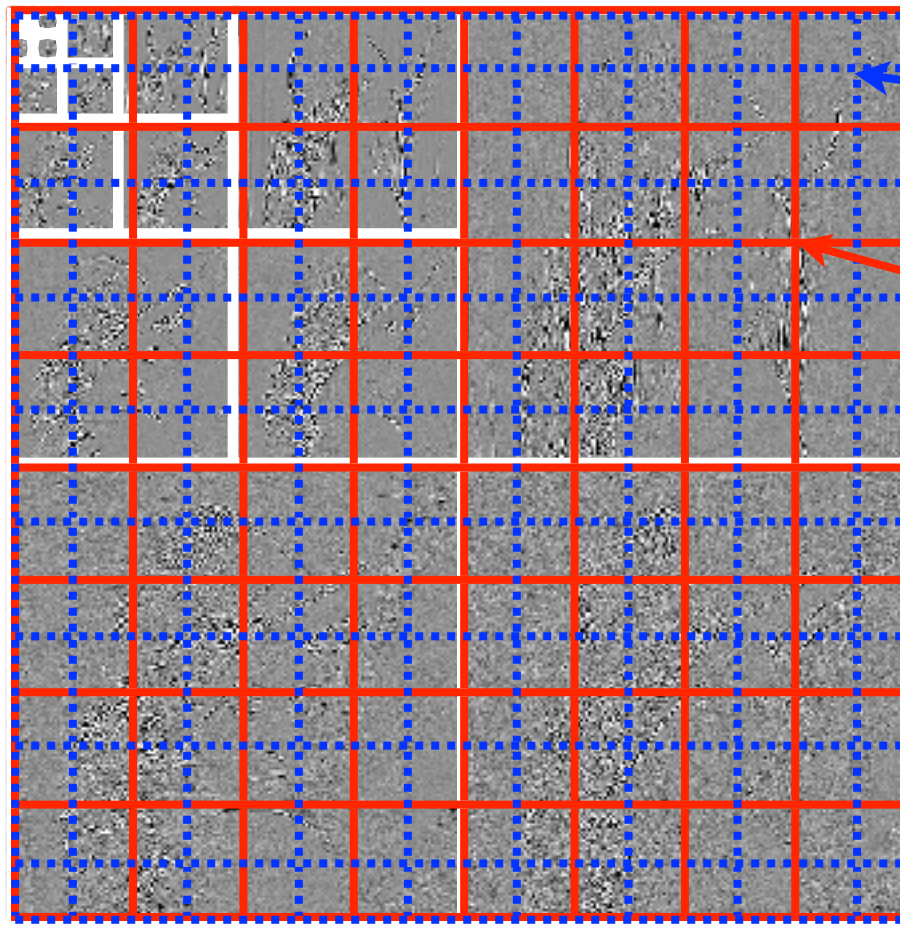
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● Inverse problems with structured sparsity, e.g. :

$$\min_{x \in \mathcal{H}} \underbrace{f(x)}_{\text{Data fidelity}} + \underbrace{g_1(x) + \cdots + g_n(x)}_{\text{Structured sparsity (e.g. } \ell_p - \ell_q \text{ norm on overlapping blocks)}}$$



$$g_2(x) = \sum_{b \in \mathcal{B}_2} \|x_b\|_2$$

$$g_1(x) = \sum_{b \in \mathcal{B}_1} \|x_b\|_2$$

Motivations

• Inverse problems with mixed regularization, e.g. :

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• Other potential applications : signal and image processing, machine learning, classification, statistical estimation, etc..

Monotone operator splitting

Find the zeros of a maximal monotone operator :

$$0 \in Ax + \sum_{i=1}^n B_i x$$

- $A, B_i : \mathcal{H} \rightarrow 2^{\mathcal{H}}$ and their sum are maximal monotone ;
- A single-valued with $\beta A \in \mathcal{A}(\frac{1}{2})$, B_i simple $\forall i$;
- $\text{zer}(A + \sum_i B_i) \neq \emptyset$.

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Example (Convex programming) : $A = \nabla f$, $B_i = \partial g_i$.

Outline

- A GFB splitting algorithm.
- Convergence.
- Stylized applications.
- Conclusion and future work.

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\rightharpoonup and \rightarrow are weak and strong convergence in \mathcal{H} .

For $w_i \in]0, 1]$ with $\sum_{i=1}^n w_i = 1$, let \mathcal{H} be the real Hilbert space obtained by endowing the Cartesian product \mathcal{H}^n with the scalar product $\sum_i w_i \langle x_i, y_i \rangle$.

$$\mathcal{S} = \{(x_1, \dots, x_n) \in \mathcal{H} : x_1 = x_2 = \dots = x_n\},$$

$$\mathbf{\Pi} : \mathcal{H} \rightarrow \mathcal{S}, x \mapsto (x, \dots, x) \quad (\text{canonical isometry}).$$

A GFB for monotone operator splitting

Initialization : Choose $(z_{i,0})_{1 \leq i \leq n} \in \mathcal{H}$, $\gamma_k \in [\epsilon, 2\beta - \epsilon]$, a sequence $(\lambda_k)_k$ in $[\epsilon, 1/\alpha]$, weights $w_i \in]0, 1]$ (e.g. $1/n$). Let $x_0 = \sum_{i=1}^n w_i z_{i,0}$.

Main iteration :

repeat

1. Compute the resolvent points (in parallel if desired) :

for $i = 1$ **to** n **do**

$$z_{i,k+1} = z_{i,k} + \lambda_k \left(\underbrace{J_{\gamma_k/w_i B_i}}_{\text{Implicit step}} \left(2x_k - z_{i,k} - \gamma_k \left(\underbrace{A(x_k)}_{\text{Explicit step}} + \underbrace{e_{2,k}}_{\text{Errors}} \right) \right) + \underbrace{e_{1,i,k}}_{\text{Errors}} - x_k \right) .$$

2. Update by averaging :

$$x_{k+1} = \sum_{i=1}^n w_i z_{i,k} .$$

3. $k \leftarrow k + 1$.

until *Convergence*;

Output : x_k .

$$\text{Resolvent : } J_{\mu B_i} = (\text{Id} + \mu B_i)^{-1}$$

A GFB for convex optimization

Initialization : Choose $(z_{i,0})_{1 \leq i \leq n} \in \mathcal{H}$, $\gamma_k \in [\epsilon, 2\beta - \epsilon]$, a sequence $(\lambda_k)_k$ in $[\epsilon, 1/\alpha]$, weights $w_i \in]0, 1]$ (e.g. $1/n$). Let $x_0 = \sum_{i=1}^n w_i z_{i,0}$.

Main iteration :

repeat

1. Compute the resolvent points (in parallel if desired) :

for $i = 1$ **to** n **do**

$$z_{i,k+1} = z_{i,k} + \lambda_k \left(\underset{\text{Implicit step}}{\text{prox}_{\gamma_k/w_i g_i}} \left(\underset{\text{Explicit step}}{2x_k - z_{i,k} - \gamma_k (\nabla f(x_k) + e_{2,k})} + \underset{\text{Errors}}{e_{1,i,k}} - x_k \right) \right).$$

2. Update by averaging :

$$x_{k+1} = \sum_{i=1}^n w_i z_{i,k}.$$

3. $k \leftarrow k + 1$.

until *Convergence*;

Output : x_k .

$$\text{Proximity operator : } \text{prox}_{\mu g_i} = (\text{Id} + \mu \partial g_i)^{-1}$$

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- **Convergence.**
- Stylized applications.
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The key: a fixed point equation

Theorem Let $\gamma > 0$. Then $x \in \text{zer}(A + \sum_i B_i)$ if and only if $x = \sum_{i=1}^n w_i z_i$, where $z = (z_1, \dots, z_n) \in \text{Fix}(T)$, and

$$T = \underbrace{\left(\frac{I_{\mathcal{H}} + R_{\gamma B} \circ R_{N_S}}{2} \right)}_{T_{1,\gamma} \in \mathcal{A}\left(\frac{1}{2}\right)} \circ \underbrace{(I_{\mathcal{H}} - \gamma A \circ J_{N_S})}_{T_{2,\gamma} \in \mathcal{A}\left(\frac{\gamma}{2\beta}\right)}$$

where $\mathcal{S} = \{(y_1, \dots, y_n) \in \mathcal{H} : y_1 = y_2 = \dots = y_n\}$, $N_{\mathcal{S}}$ its normal cone,

$$J_{N_{\mathcal{S}}} = \text{proj}_{\mathcal{S}} : \mathcal{H} \rightarrow \mathcal{S}, z \mapsto \Pi \left(\sum_i w_i z_i \right),$$

$$\Pi : \mathcal{H} \rightarrow \mathcal{S}, x \mapsto (x, \dots, x) \quad (\text{canonical isometry}),$$

$$A, B : \mathcal{H} \rightarrow 2^{\mathcal{H}}, \quad Bz = \times_{i=1}^n w_i^{-1} B_i z_i, \quad A(z) = \times_{i=1}^n A z_i.$$

Moreover, for $\gamma \in]0, 2\beta[$, $T \in \mathcal{A}(\alpha)$, with $\alpha = \frac{2\beta}{4\beta - \gamma}$.

Convergence

- A.1 $(\lambda_k)_{k \in \mathbb{N}}$ is a sequence in $]0, 1/\alpha[$ such that $\sum_k \lambda_k(1 - \alpha\lambda_k) = +\infty$, where $\alpha = \frac{2\beta}{4\beta - \gamma}$, and $\sum_{t \in \mathbb{N}} \lambda_k(\|e_{1,k}\|_{\mathcal{H}} + \|e_{2,k}\|_{\mathcal{H}}) < +\infty$.
- A.2 $\lambda_k \in]0, 1]$ with $\liminf_k \lambda_k > 0$, and the errors are summable.
- A.3 $(\gamma_k)_{k \in \mathbb{N}}$ s.t. $0 < \underline{\gamma} \leq \gamma_k \leq \bar{\gamma} < 2\beta$, $\gamma \in [\underline{\gamma}, \bar{\gamma}]$, and $(\lambda_k |\gamma_k - \gamma|)_{k \in \mathbb{N}}$ is summable.

Theorem Let $\gamma \in]0, 2\beta[$. Let $z_0 \in \mathcal{H}$. Define

$$z_{k+1} = z_k + \lambda_k(T_{1,\gamma}(T_{2,\gamma}z_k + e_{2,k}) + e_{1,k} - z_k).$$

(i) Assume that either (A.1 or A.2) and A.3 hold. Then,

- $z_k \rightharpoonup z \in \text{Fix}(T_{1,\gamma} \circ T_{2,\gamma})$, and $x_k \rightharpoonup x \in \text{zer}(A + \sum_i B_i)$.
- $T_{1,\gamma} \circ T_{2,\gamma}z_k - z_k \rightarrow 0$.

(ii) Moreover, if A.1, A.2 and A.3 hold, then

- $A(x_k) \rightarrow A(x)$.
- $x_k \rightarrow x$ if one of the following holds :
 - A is uniformly monotone,
 - $\times_{i=1}^n w_i^{-1} B_i$ is uniformly monotone. The latter is true for instance if $\forall i \in \{1, \dots, n\}$, B_i is uniformly monotone with its modulus being also subadditive or convex.

Convergence: Rates

$$u_{i,k+1} = J_{\frac{\gamma}{\omega_i} B_i} (2x_k - z_{i,k} - \gamma_k A x_k), \quad i \in \{1, \dots, n\}$$

Theorem (i) Suppose that A.1-A.2 hold, that $0 < \inf_{k \in \mathbb{N}} \lambda_k \leq \sup_{k \in \mathbb{N}} \lambda_k < \frac{4\beta - \gamma}{2\beta}$, $((k+1) \|e_{1,k}\|)_{k \in \mathbb{N}} \in \ell_+^1$ and $\forall i, ((k+1) \|e_{2,i,k}\|)_{k \in \mathbb{N}} \in \ell_+^1$, then

(a)

$$\text{dist} \left(0, \sum_i B_i u_{i,k+1} + A \left(\sum_i \omega_i u_{i,k+1} \right) \right) = O(\sqrt{1/k}).$$

(b) If moreover $e_{j,i,k} \equiv 0$, then

$$\text{dist} \left(0, \sum_i B_i u_{i,k+1} + A \left(\sum_i \omega_i u_{i,k+1} \right) \right) = o(\sqrt{1/k}).$$

(ii) If A is strongly monotone, then x_k converges to x^* linearly.

Special instances

● GFB encompasses many special cases :

● $n = 1 \Rightarrow$ Classical Forward-Backward splitting ($\lambda_k \in]0, 1]$) [Combettes04] :

$$x_{k+1} = x_k + \lambda_k (\text{prox}_{\gamma_k g_1} \circ (\text{I} - \gamma_k \nabla f))(x_k) - x_k .$$

● $f = 0 \Rightarrow$ Spingarn method [Spingarn83] and also parallel DR splitting on a product space [Combettes09] ($\lambda_k \in]0, 2[$) :

$$z_{k+1} = \left(1 - \frac{\lambda_k}{2}\right) z_k + \frac{\lambda_k}{2} (\text{rprox}_{\gamma/w_i g_i})_i \circ \text{rproj}_{\mathcal{S}}(z_k) .$$

Strong convergence appears new.

● $f = \frac{1}{2} \|y - \cdot\|^2, y \in \text{Im}(\text{I} + \sum_i \partial g_i) \Rightarrow$ Proximity operator of $\sum_i g_i$ by absorbing f in the g_i 's and use proximal calculus.

● Non-relaxed stationary GFB can be derived from BD-HPE [MonteiroSvaiter10].

Extensions

- Find $x \in \mathcal{H}$ such that

$$\min_{x \in \mathcal{H}} f(x) + g_i \circ L_i(x) \iff 0 \in \nabla f(x) + \sum_i L_i^* \circ \partial g_i(L_i x),$$

$\nabla f \in \beta\text{-Lip}(\mathcal{H})$, and $\forall i$, g_i simple and L_i bounded linear operator on \mathcal{H} .

Approach 1

- Decompose $g_i \circ L_i = \sum_k g_{i,k} \circ L_{i,k}$, $L_{i,k}$ a tight frame (e.g. overlapping block sparsity, convolution with a FIR, etc.);
- Apply the GFB.

Approach 2 $L_i^* \circ L_i$ (or $L_i \circ L_i^*$) easily diagonalized :

- Introduce auxiliary variables : find $x \in \mathcal{H}$ and $(u_1, \dots, u_n) \in \mathcal{K}_1 \times \dots \times \mathcal{K}_n$

$$\min_{x, (u_i)_i} f(x) + \sum_i \left(g_i(u_i) + \iota_{\ker [I_{\mathcal{K}_i} \quad -L_i]}(u_i, x) \right).$$

- Apply the GFB.

Outline

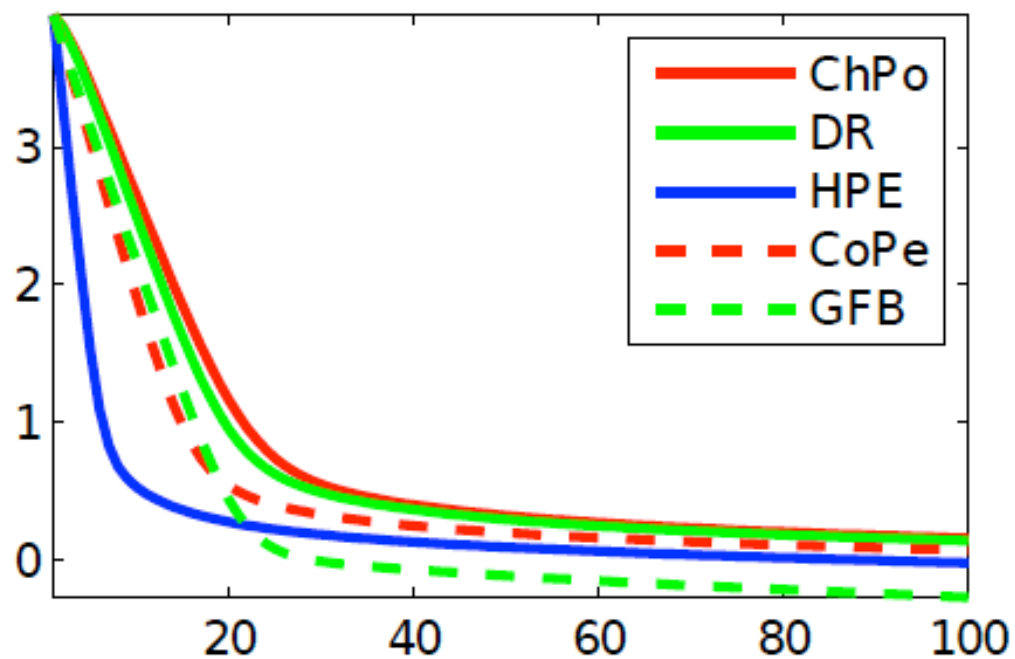
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Deconvolution

Overlapping block-sparsity (TI-DWT)

$$\min_{x \in \mathbb{R}^P} \frac{1}{2} \|y - H\Phi x\|_2^2 + \lambda \sum_{k=1}^4 \|x_{\mathcal{B}_k}\|_{2,1}$$

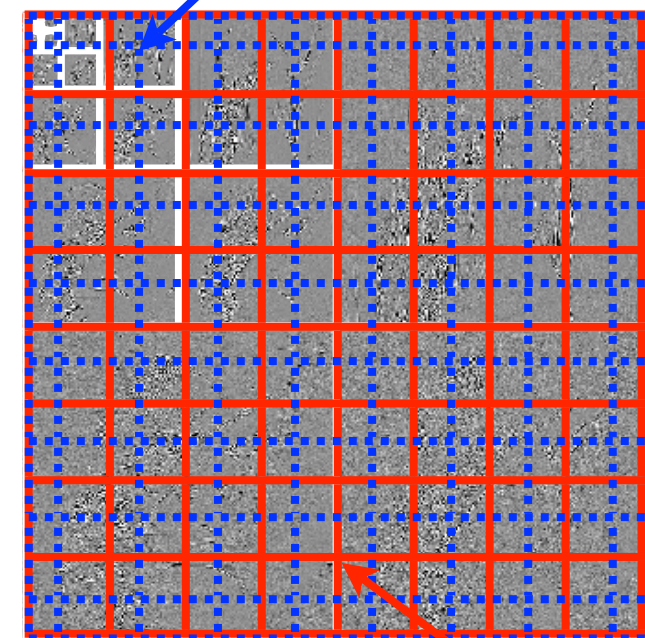
(a) $\log(\Psi - \Psi_{\min})$ vs. iteration #



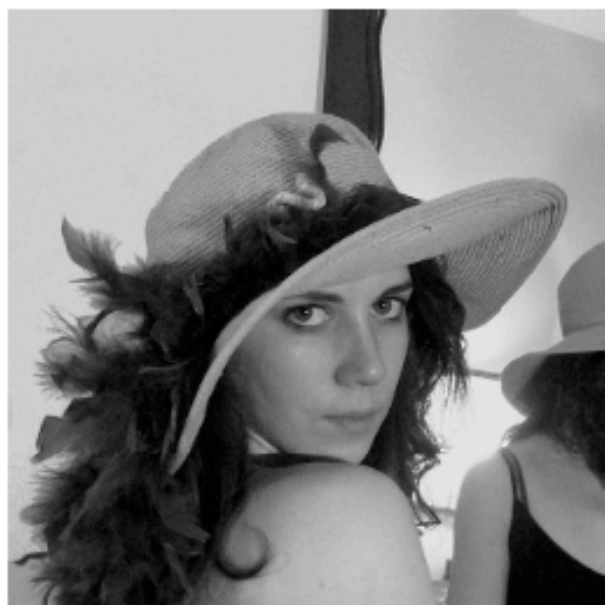
(b) computing time

t_{ChPo}	=	153 s
t_{DR}	=	95 s
t_{HPE}	=	148 s
t_{CoPe}	=	235 s
t_{GFB}	=	73 s

$$\|x_{\mathcal{B}_1}\|_{2,1} = \sum_{b \in \mathcal{B}_1} \|x_b\|_2$$



$$\|x_{\mathcal{B}_2}\|_{2,1} = \sum_{b \in \mathcal{B}_2} \|x_b\|_2$$



(c) LaBoute y_0



(d) $y = Ky_0 + w$, 19.63 dB



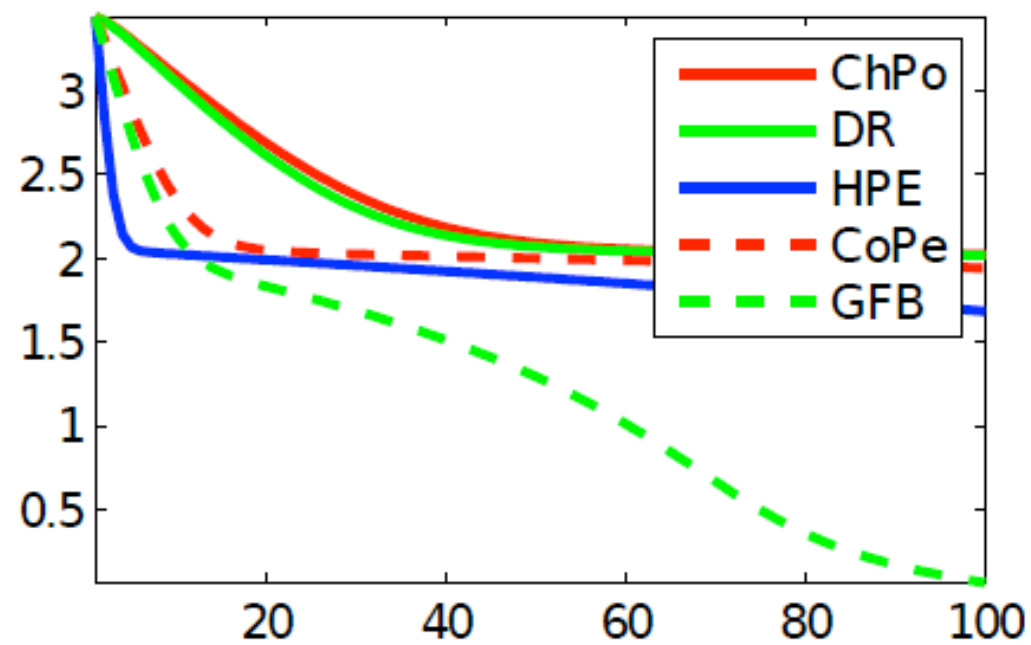
(e) $\hat{y}_0 = W\hat{x}$, 22.45 dB

Inpainting

Overlapping block-sparsity (TI-DWT)

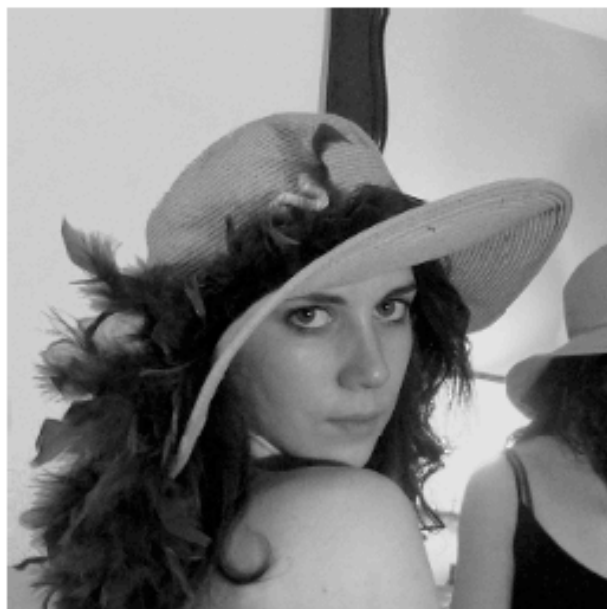
$$\min_{x \in \mathbb{R}^P} \frac{1}{2} \|y - M\Phi x\|_2^2 + \lambda \sum_{k=1}^4 \|x_{\mathcal{B}_k}\|_{2,1}$$

(a) $\log(\Psi - \Psi_{\min})$ vs. iteration #

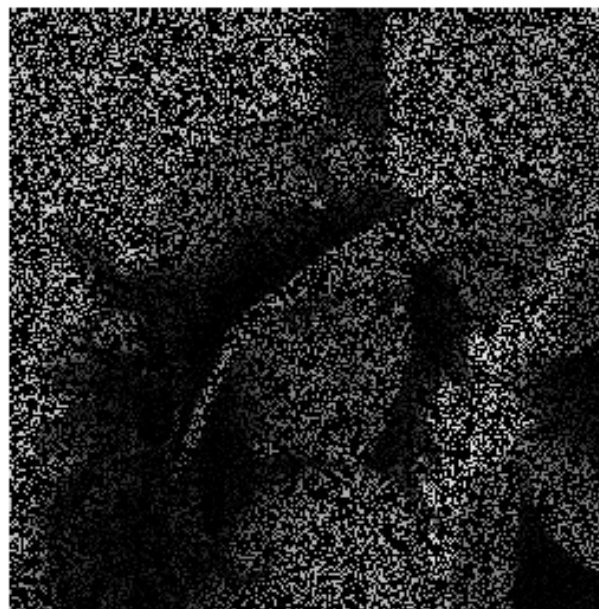


(b) computing time

t_{ChPo}	= 229 s
t_{DR}	= 219 s
t_{HPE}	= 352 s
t_{CoPe}	= 340 s
t_{GFB}	= 203 s



(c) LaBoute y_0



(d) $y = My_0 + w$, 1.54 dB



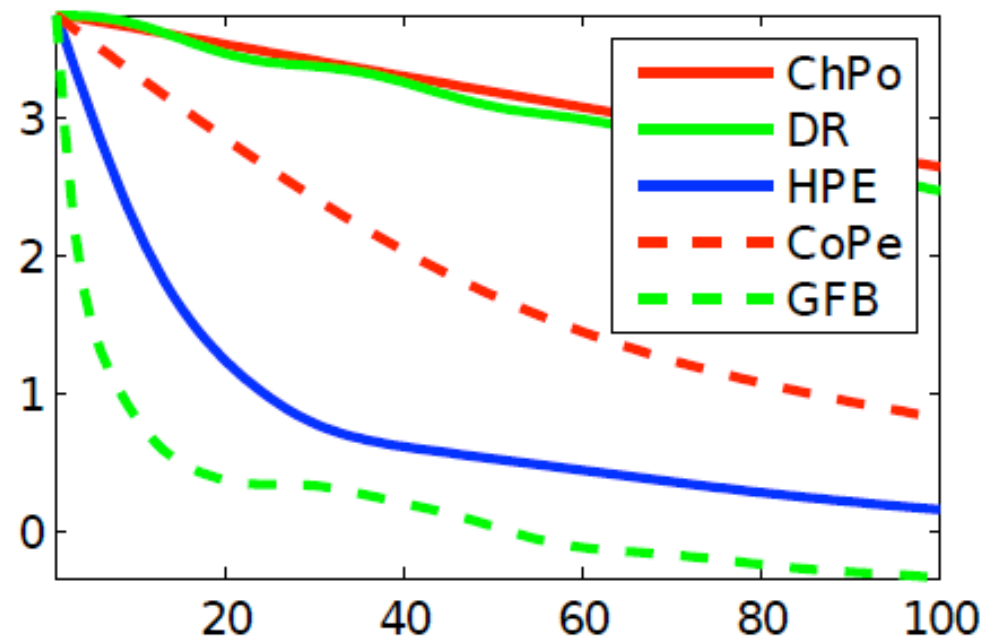
(e) $\hat{y}_0 = W\hat{x}$, 21.66 dB

Deconvolution and inpainting

Overlapping block-sparsity and TV

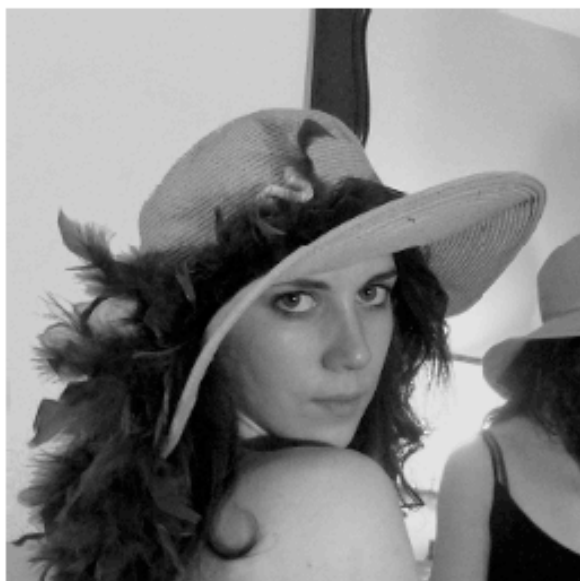
$$\min_{x \in \mathbb{R}^P} \frac{1}{2} \|y - M\mathbb{H}\Phi x\|_2^2 + \lambda \sum_{k=1}^4 \|x_{\mathcal{B}_k}\|_{2,1} + \mu \|\Phi x\|_{\text{TV}}$$

(a) $\log(\Psi - \Psi_{\min})$ vs. iteration #

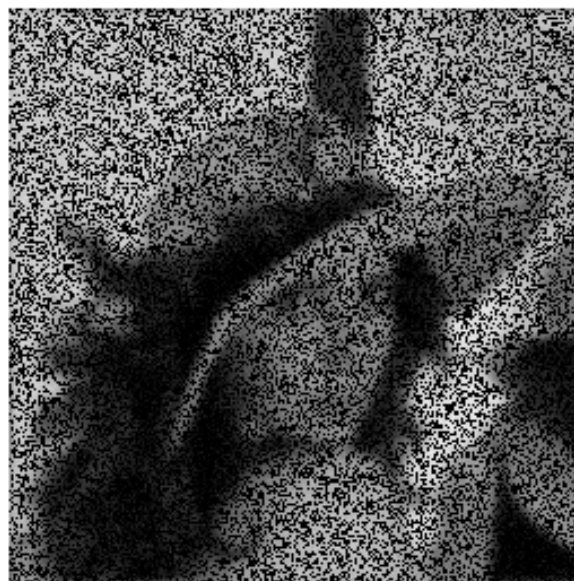


(b) computing time

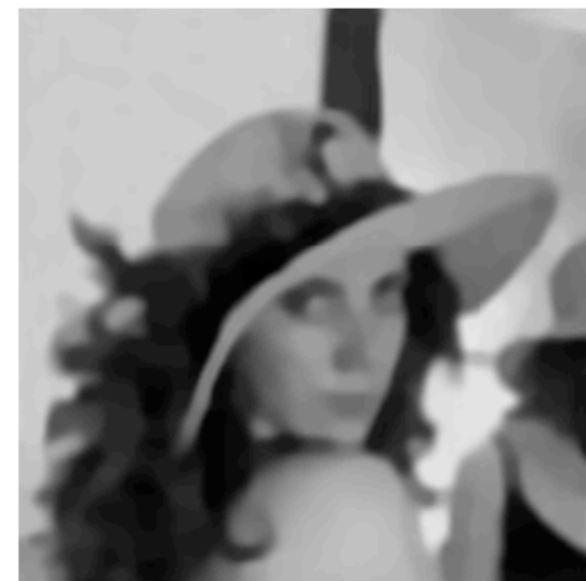
t_{ChPo}	= 358 s
t_{DR}	= 294 s
t_{HPE}	= 409 s
t_{CoPe}	= 441 s
t_{GFB}	= 286 s



(c) LaBoute y_0



(d) $y = MK y_0 + w$, 3.93 dB



(e) $\hat{y}_0 = W\hat{x}$, 22.48 dB

***Many other problems can be solved
within this framework.***

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Take away messages

- **Convex analysis** and **monotone operator splitting** are a powerful framework for solving sparse recovery problems, **non-necessarily smooth**.
- A new splitting algorithm that exploits the structure of the problem (**smoothness+simplicity**).
- **A fast** solver for **large-scale** problems with **theoretical** guarantees (convergence, robustness, rates).
- Acceleration (inertial, variable metric): done.

Preprints on arxiv and papers on

<https://fadili.users.greyc.fr/>

Thanks
Any questions ?