Analysis of Pattern Emergence in Turing Systems with Inhomogeneity in Reaction Term

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SIAM Conference on Applications of Dynamical Systems, Snowbird

23rd May 2017

Introduction: Classical Turing's model of pattern formation

Reaction-diffusion system:

$$\frac{\partial_t u = d_1 \Delta u + f(u, v)}{\partial_t v = d_2 \Delta v + g(u, v)} \quad \text{in } (0, \infty) \times \Omega,$$

with Neumann boundary conditions.

Let (u^*, v^*) be stationary, spatially homogeneous solution (ground state) which is

- stable without diffusion,
- unstable with diffusion.

Evolution of perturbations around (u^*, v^*) :

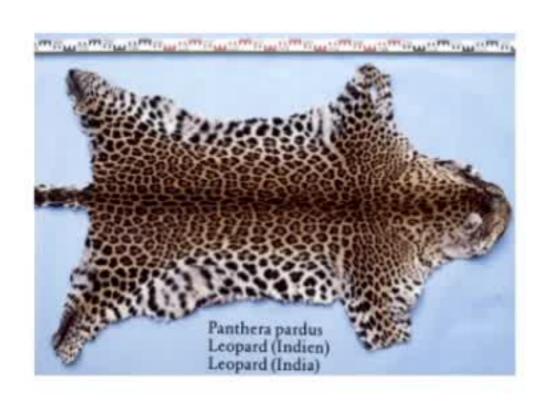
$$\partial_t \widetilde{u} = d_1 \Delta \widetilde{u} + b_{11} \widetilde{u} + b_{12} \widetilde{v} + n_1 (\widetilde{u}, \widetilde{v}),$$

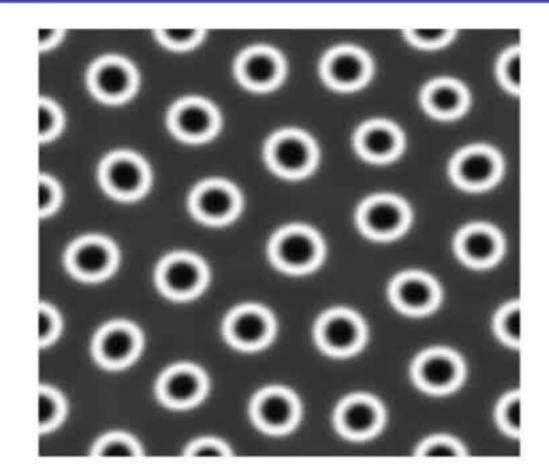
$$\partial_t \widetilde{v} = d_2 \Delta \widetilde{v} + b_{21} \widetilde{u} + b_{22} \widetilde{v} + n_2 (\widetilde{u}, \widetilde{v}).$$

Conditions for Turing instability:

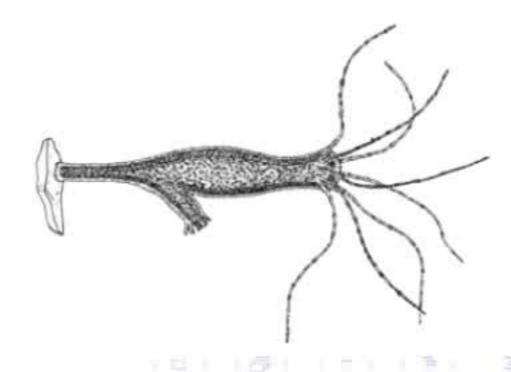
tr
$$B < 0$$
, $b_{11}d_2 + b_{22}d_1 > 0$,
det $B > 0$, $(b_{11}d_2 + b_{22}d_1)^2 > 4d_1d_2$ det B .

Introduction: Biological motivation









Linear kinetics: Summary of numerical experiments

• $T1^L \wedge T1^R \wedge T2^L \wedge T2^R$:

	$T3^R \wedge T4^R$	$\neg T3^R \wedge T4^R$	$T3^R \wedge \neg T4^R$	$\neg T3^R \land \neg T4^R$
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• $\neg (T1^L \wedge T1^R \wedge T2^L \wedge T2^R)$:

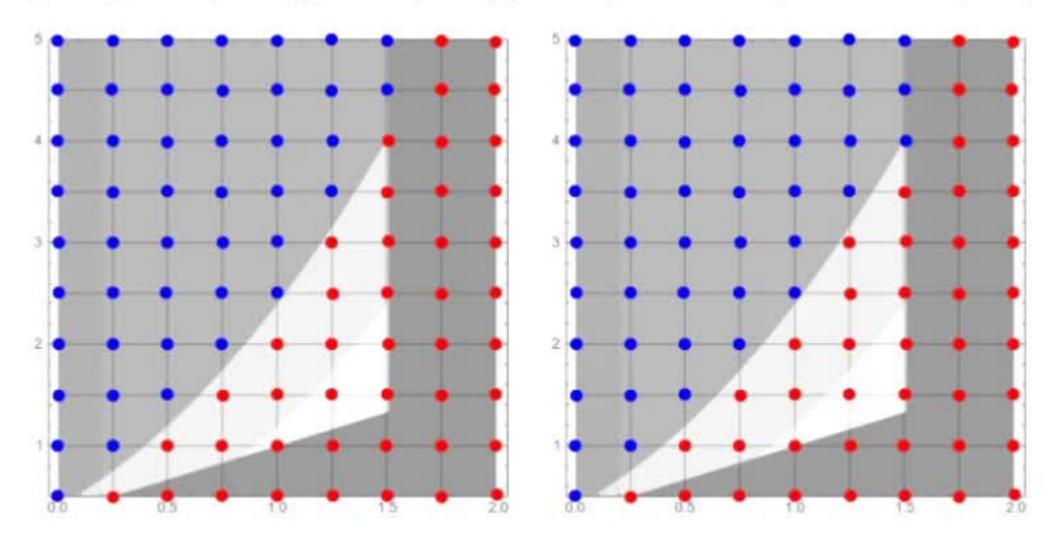
Crucial observations:

- the results are constant in each cell (except at the boundary),
- results of both methods correspond.

Linear kinetics: Ilustration of numerical results

Parameters:

$$d_1 = 1$$
, $d_2 = 10$, $b_{21} = -3$, $b_{22} = -2$, $s = 0.5$, $L = 100$, $\xi = 30$.



one positive real part unbounded all real parts negative

spectrum : evolution

no pattern

Non-linear kinetics: Conditions and numerical verification

Hypothetical distinction of pattern types:

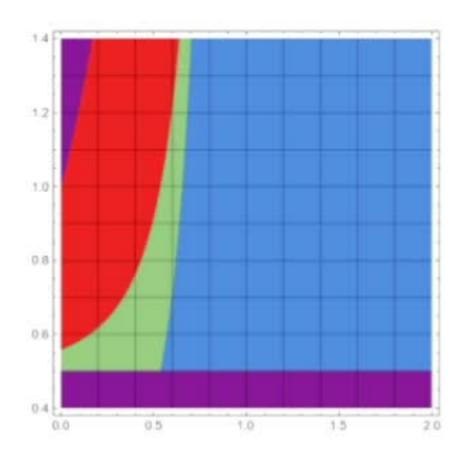
Verifiable by numerical simulations of evolution problem with Schnakenberg's kinetics

$$f(u,v) = a - u + u^2 v$$
 $g(u,v) = b - u^2 v$.

and Gierer-Meinhardt's kinetics

$$f(u, v) = a - bu + \frac{u^2}{v}$$
 $g(u, v) = u^2 - v$,

with a,b positive constants.



$$L = 400$$
, $\xi = 120$, $d_1 = 1$, $d_2 = 100$, $s = 0.5$,

axis: (a, b),

both-side pattern right-side pattern left-side pattern no pattern unknown

Non-linear kinetics: Conditions and numerical verification

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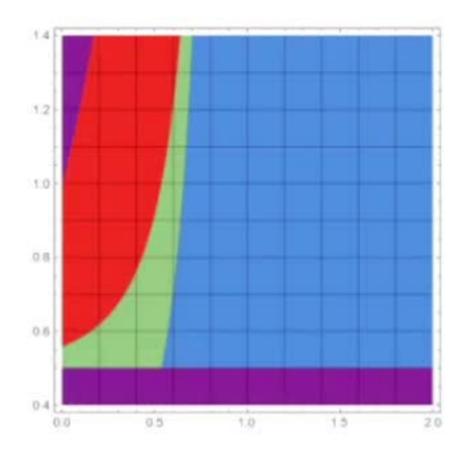
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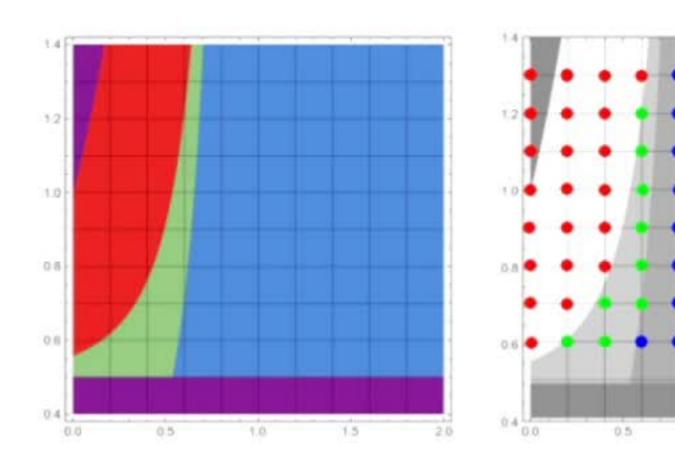
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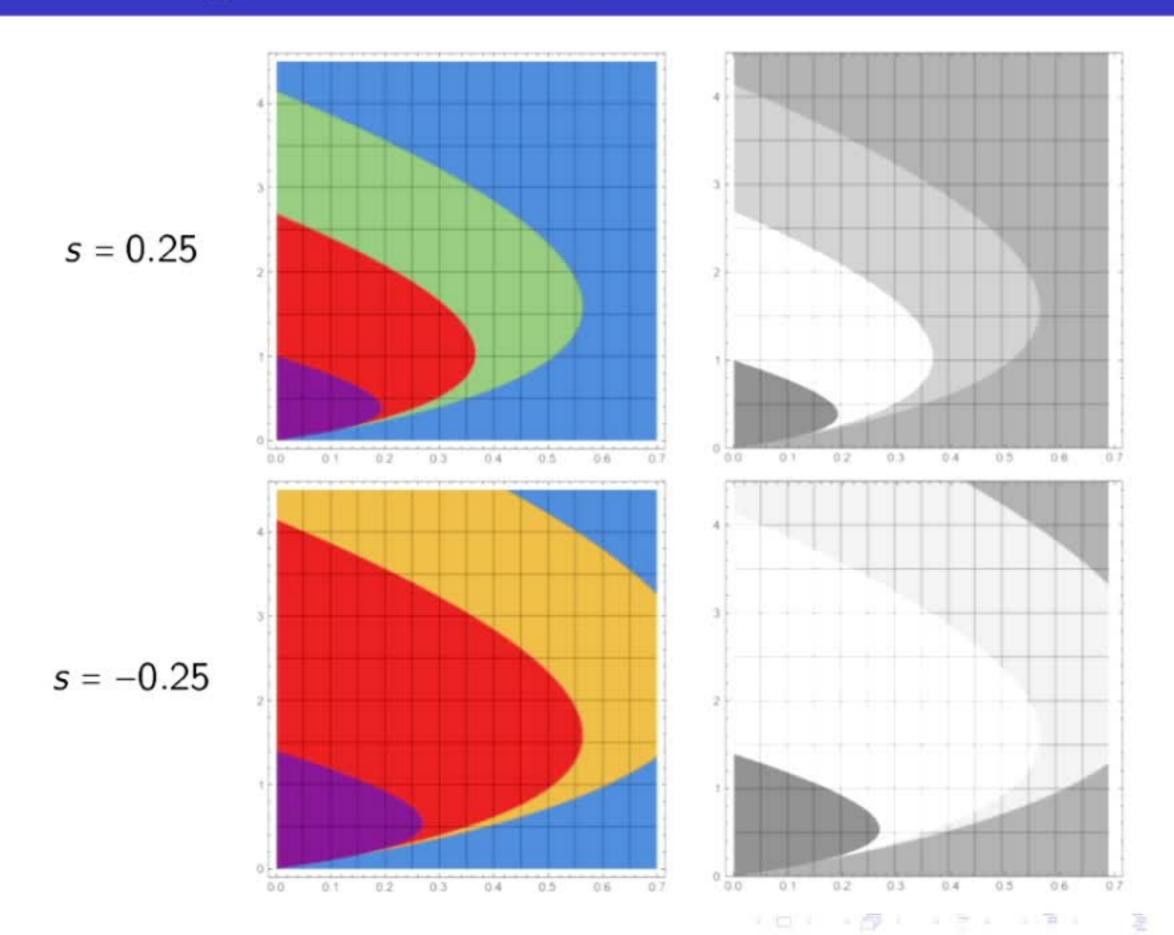
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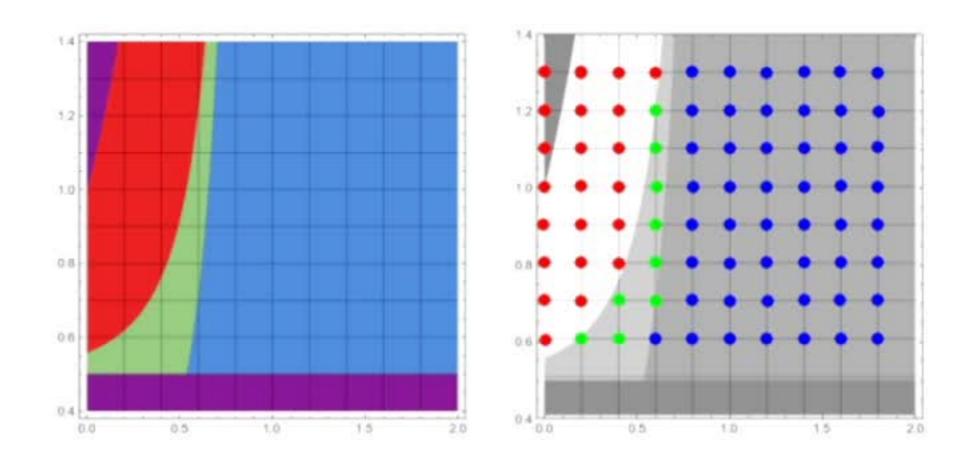
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1.0

15

Schnakenberg's kinetics with s=0.25 and s=-0.25



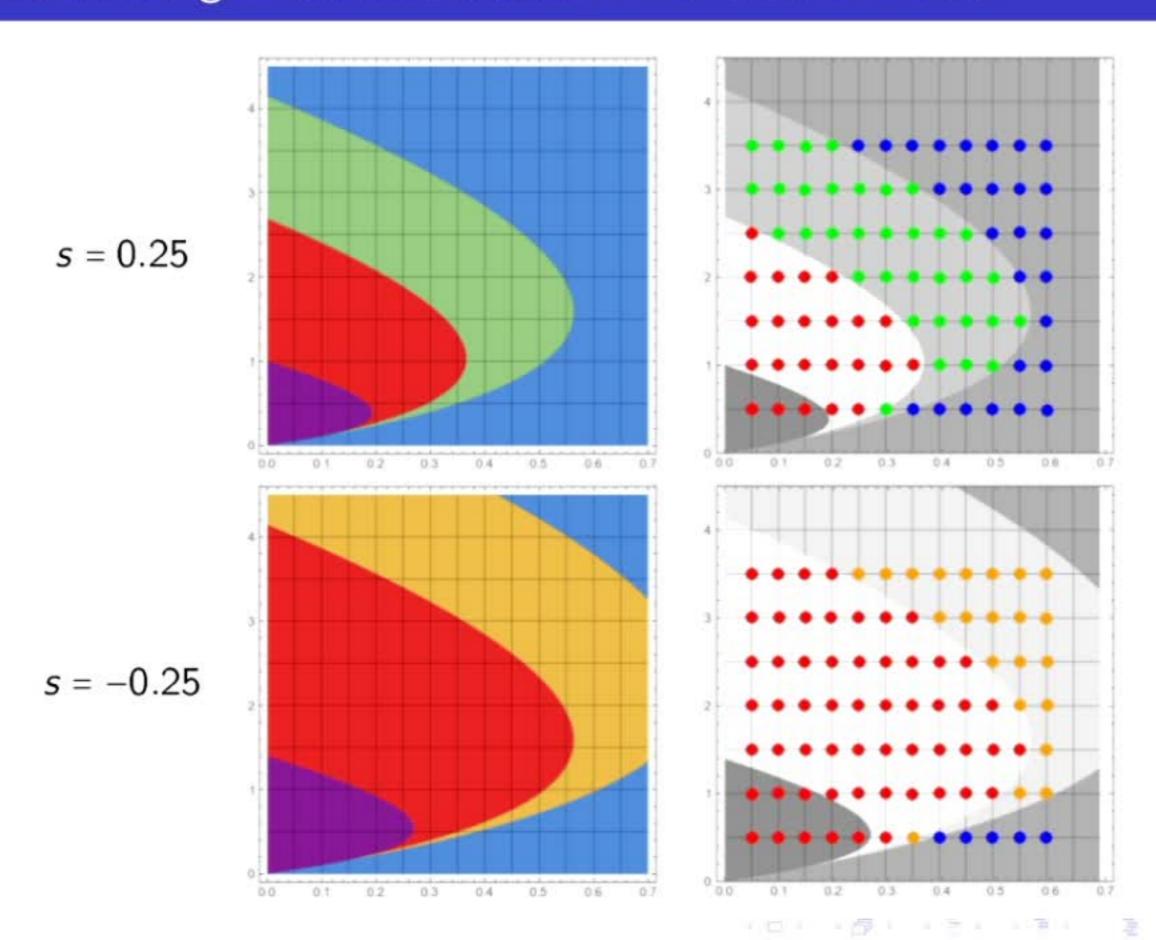


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Schnakenberg's kinetics with s=0.25 and s=-0.25



Outline and conclussions

Summary

- effect of small spatial dependence of coefficient was analysed,
- pattern with different frequencies emerges,
- Turing's idea was extended to this case,
- conditions to distinguish patterns in general case was stated,
- and verified by an analytical-numerical approach.

Remarks

- positive: helpful conditions,
- negative: accuracy of the conditions; only analytical approach?
- should work for any linear coefficient,
- should work for N steps.

Thank you for your attention.

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