SIAM Annual Meeting (AN16) Minisymposium: Forecasting from Big, Noisy Data: Challenges and Techniques
Alex Memory (speaker)

July 12, 2016



contributors (partial list):

Tifani O'Brien (PI), CC Michael (Co-PI), Leidos Autonomy and Analytics





Professor S. Jay Yang (PI) Professor Katie McConky (Co-PI)



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UNIVERSITY
Professor Alan Ritter (PI)

Challenges

Challenges

Challenges

Challenges

Three steps:

Challenges

Three steps: Signals

Challenges

Three steps: Signals

Challenges

Training data

Three steps: Signals

Challenges

Training data (Volume)

Three steps: Signals

Challenges

Training data (Volume)



Techniques

Three steps:

Signals



Fusion

Challenges

Training data (Volume)



Techniques

Three steps:

Signals



Fusion

Challenges

Training data (Volume)

Diverse evidence

1

Techniques

Three steps:

Signals



Fusion

Challenges

Training data (Volume)

Diverse evidence (Variety)

1

Techniques

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Fusion

Challenges

Training data (Volume)

Diverse evidence (Variety)



1

Techniques

Weak supervision

Probabilistic logical models

Three steps:

Signals



Fusion



Projection

Challenges

Training data (Volume)

Diverse evidence (Variety)



1

Techniques

Weak supervision

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Three steps:

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Fusion



Projection

Challenges

Training data (Volume)

Diverse evidence (Variety)

Incomplete, evolving



Weak supervision



Probabilistic logical models

Three steps:

Signals



Fusion



Projection

Challenges

Training data (Volume)

Diverse evidence (Variety)

Incomplete, evolving (Veracity, Velocity)



Weak supervision



Probabilistic logical models



Three steps:

Signals



Fusion



Projection

Challenges

Techniques

Training data (Volume)



Weak supervision

Diverse evidence (Variety)



Probabilistic logical models

Incomplete, evolving (Veracity, Velocity)



Mini-theories, Variable Length Markov Model (VLMM)

Three steps:

Signals



Fusion



Projection

Challenges

Training data (Volume)

Diverse evidence (Variety)

Incomplete, evolving (Veracity, Velocity)



Probabilistic

logical models



Techniques

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Mini-theories, Variable Length Markov Model (VLMM)







Social Media, e.g., Twitter



Social Media, e.g., Twitter Information Extraction



Social Media, e.g., Twitter Information Extraction

7/4/2014 Phishing Attack

Victim: Bitcoins Reserve





Social Media, e.g., Twitter Information Extraction

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4/25/2015 Account Hijacking

Victim: Tesla





Social Media, e.g., Twitter

Information Extraction

7/4/2014 Phishing Attack

Victim: Bitcoins Reserve

4/25/2015 Account Hijacking

Victim: Tesla

5/16/2015 **DDOS**

Victim: PSN





1) Humans Annotate Text



1) Humans Annotate Text

2) Train Supervised Machine Learning Models

$$\frac{1}{Z(w_1, \dots, w_n, \theta)} \prod_{i=1}^n e^{\theta \cdot f(t_i, t_{i-1}, w_1, \dots, w_n, i)}$$

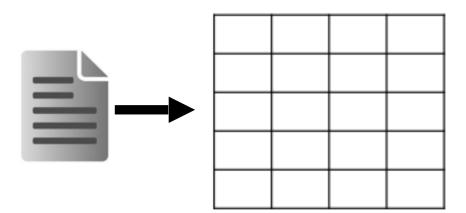


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3) Apply Models to **New Documents**



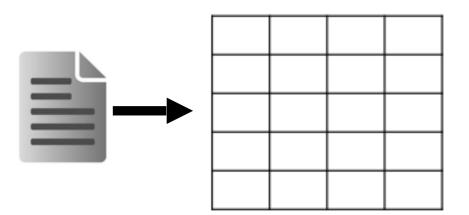


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3) Apply Models to **New Documents**



Weakly Supervised Learning Unstructured Text







Weakly Supervised Learning Unstructured Text











Weakly Supervised Learning Unstructured Text









Structured Data



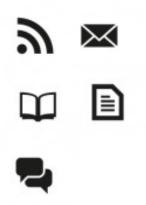




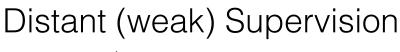


Weakly Supervised Learning

Unstructured Text







Structured Data









Weakly Supervised Learning

Unstructured Text







5

Information Extraction

Distant (weak) Supervision













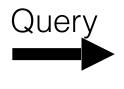


Seed Examples + Keyword

(Associated Press, 4/23/2013)

Seed Examples + Keyword

Seed Examples + Keyword



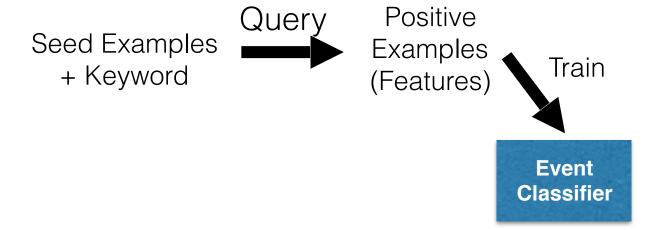
Positive Examples (Features)

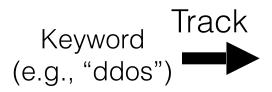
Seed Examples
+ Keyword

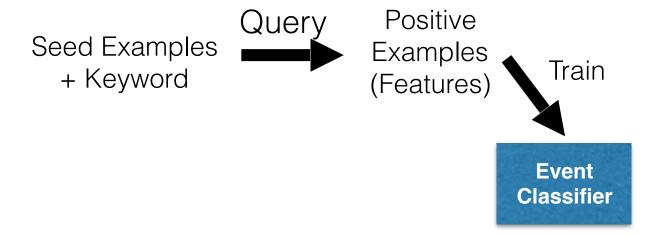
Query
Examples
(Features)

Train

Event
Classifier

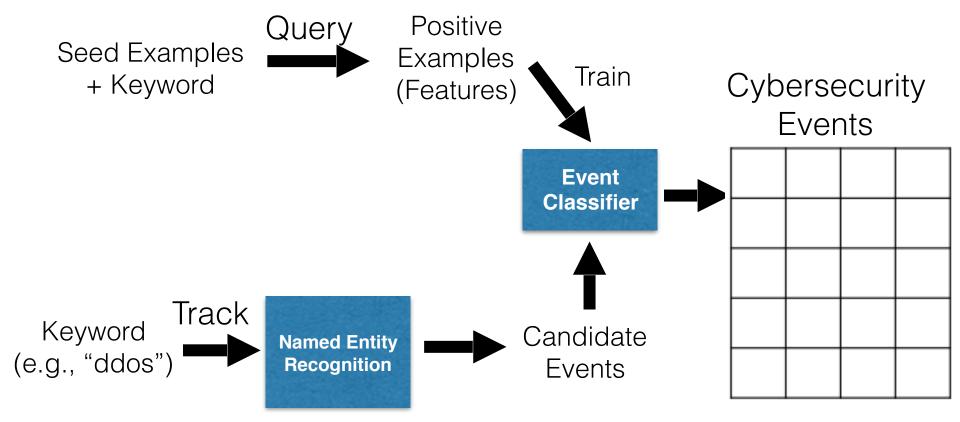












$$O(\theta) = \underbrace{\sum_{i}^{N} \log p_{\theta}(y_{i}|x_{i})}_{\text{Log Likelihood}}$$

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Safe to assume all unlabeled are negatives?

Augment conditional likelihood with label regularization:

$$O(\theta) = \sum_{i}^{N} \log p_{\theta}(y_{i}|x_{i}) - \underbrace{\lambda^{U}D(\tilde{p}||\hat{p}_{\theta}^{\mathrm{unlabeled}})}_{\mathrm{Label\ regularization}}$$

Safe to assume all unlabeled are negatives?

Augment conditional likelihood with label regularization:

Kullback-Leibler (KL) divergence

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$$D(\tilde{p}||\hat{p}_{\theta}) = \tilde{p}\log\frac{\tilde{p}}{\hat{p}_{\theta}} + (1 - \tilde{p})\log\frac{1 - \tilde{p}}{1 - \hat{p}_{\theta}}$$





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User-provided target expectation of frequency of positives ("ddos" vs. "breach")

Augment conditional likelihood with label regularization:

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Safe to assume all unlabeled are negatives?

Empirical expectation of positives on unlabeled examples

$$D(\tilde{p}||\hat{p}_{ heta}) = \tilde{p}\log\frac{\tilde{p}}{\hat{p}_{ heta}} + (1-\tilde{p})\log\frac{1-\tilde{p}}{1-\hat{p}_{ heta}}$$

User-provided target expectation of frequency of positives ("ddos" vs. "breach")

KL Divergence Gradient

$$\frac{\partial}{\partial \theta_k} D(\tilde{p}||\hat{p}_{\theta}) =$$

$$\frac{1}{N} \left(\frac{1 - \tilde{p}}{1 - \hat{p}_{\theta}} - \frac{\tilde{p}}{\hat{p}_{\theta}} \right) \sum_{i=1}^{N} p_{\theta}(y_i = 1 | x_i) (1 - p_{\theta}(y_i = 1 | x_i)) x_{i,k}$$

KL Divergence Gradient

$$\frac{\partial}{\partial \theta_k} D(\tilde{p}||\hat{p}_{\theta}) =$$

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No Change if $\, ilde{p}=\hat{p}_{ heta}$

Otherwise push weights up or down



KL Divergence Gradient

$$\frac{\partial}{\partial \theta_k} D(\tilde{p}||\hat{p}_{\theta}) =$$

Give more weight to uncertain cases

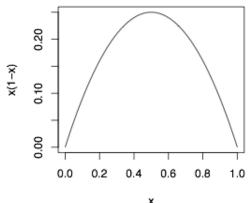


$$\frac{1}{N} \left(\frac{1 - \tilde{p}}{1 - \hat{p}_{\theta}} - \frac{\tilde{p}}{\hat{p}_{\theta}} \right) \sum_{i=1}^{N} p_{\theta}(y_i = 1 | x_i) (1 - p_{\theta}(y_i = 1 | x_i)) x_{i,k}$$



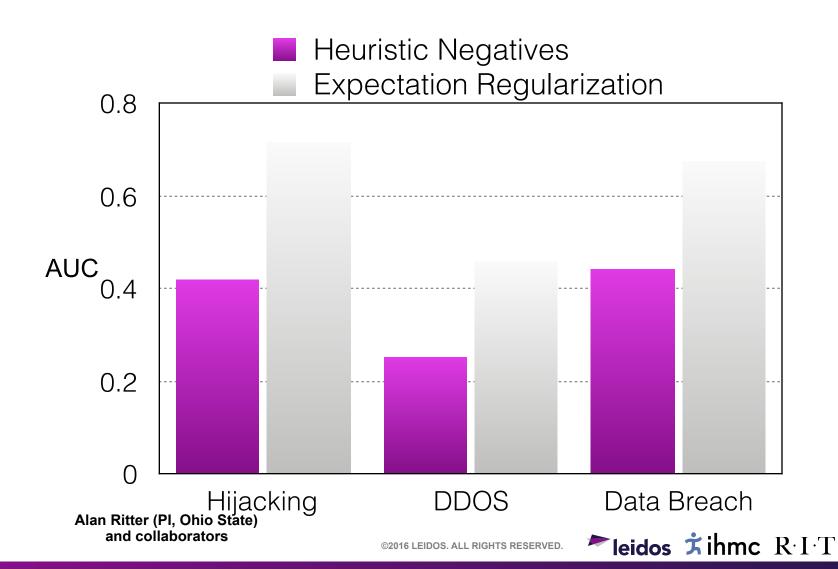
No Change if $\tilde{p} = \hat{p}_{\theta}$

Otherwise push weights up or down





Area Under Precision / Recall Curve



Forecasting Cyber Attacks Using Big Data

Signals Fusion Projection Training Incomplete, Diverse **Challenges** data evidence evolving Weak **Probabilistic** Mini-theories, **Techniques** logical models supervision **VLMM**

Forecasting Cyber Attacks Using Big Data

Signals Fusion Projection Training Incomplete, Diverse **Challenges** data evidence evolving Probabilistic Weak Mini-theories, **Techniques** ogical models supervision **VLMM**

Signals from Diverse Sensors



Signals from Diverse Sensors



Probabilistic Dependencies + Most Probable Explanation (MPE) Inference

Signals from Diverse Sensors



Knowledge Graph

Probabilistic Dependencies + Most Probable Explanation (MPE) Inference

Signals from Diverse Sensors



Knowledge Graph

Probabilistic Dependencies
+ Most Probable Explanation (MPE) Inference



Signals from Diverse Sensors



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Signals from Diverse Sensors



Knowledge Graph

Probabilistic Dependencies
+ Most Probable Explanation (MPE) Inference

 $AgentGroup(Name_1, Sensor_1) \land AgentGroup(ame_2, Sensor_2) \land Similar(Name_1, Name_2) \rightarrow SameEnt(Name_1, Name_2)$



Signals from Diverse Sensors



Knowledge Graph

Probabilistic Dependencies
+ Most Probable Explanation (MPE) Inference

 $AgentGroup(Name_1, Sensor_1) \land AgentGroup(Name_1, Sensor_2) \land Similar(Name_1, Name_2) \rightarrow SameEnt(Name_1, Name_2)$ (entity resolution)



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 $MutuallyExclusive(Hacktivist, NationState) \land Hacktivist(Name_1, Sensor_1) \land NationState(Name_2, Sensor_2) \rightarrow \neg SameEnt(Name_1, Name_2)$



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 $Attack(Time_1, Attacker, Victim, Vulnerability) \rightarrow \exists \ Time_2.$ $AcquiredExploit(Time_2, Attacker, Vulnerability) \land (Time_2 < Time_1)$



Signals from Diverse Sensors



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(Leidos)



Signals from Diverse Sensors



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(Leidos)



[Broecheler et al., 2010]

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$$w: b_1(\vec{X}) \wedge \ldots \wedge b_n(\vec{X}) \to h_1(\vec{X}) \vee \ldots \vee h_m(\vec{X})$$

[Broecheler et al., 2010]

PSL program = set of weighted first order rules

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ground atoms have soft truth values in [0,1];
 are variables in Markov random field (MRF)

[Broecheler et al., 2010]

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$$d_r(I) = \max\{0, I(body) - I(head)\}\$$

[Broecheler et al., 2010]

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$$d_r(I) = \max\{0, I(body) - I(head)\}$$

Lukasiewicz t-norm

$$I(v_1 \wedge v_2) = \max\{0, I(v_1) + I(v_2) - 1\}$$

 $I(v_1 \vee v_2) = \min\{I(v_1) + I(v_2), 1\}$
 $I(\neg l_1) = 1 - I(v_1)$

[Broecheler et al., 2010]

PSL program = set of weighted first order rules

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$$w: b_1(\vec{X}) \wedge \ldots \wedge b_n(\vec{X}) \to h_1(\vec{X}) \vee \ldots \vee h_m(\vec{X})$$

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- features in MRF = ground rules
- MRF feature value for some interpretation (assignment of truth values to all atoms) = ground rule's distance to satisfaction

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Fusion Results Example: Aligning Data Sources

leidos ; ihmc R·I·T THE OHIO STATE UNIVERSITY

A complex mapping between schemas is less probable

$$\mathsf{size}(F): in(F) \to \bot$$

A complex mapping between schemas is less probable

$$size(F): in(F) \rightarrow \bot$$

The most probable mapping can reconstruct missing answers from the sources

$$1: J(T) \to \exists F.\mathsf{covers}(F,T) \land in(F)$$

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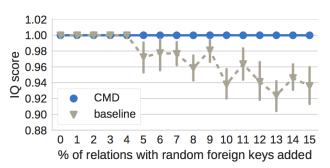
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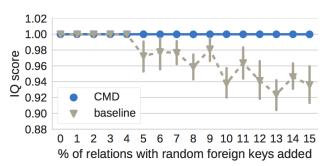
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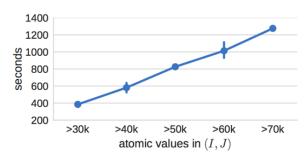
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Inference running time is linear with table size



Forecasting Cyber Attacks Using Big Data

Signals Fusion Projection Training Incomplete, Diverse **Challenges** data evidence evolving Probabilistic Weak Mini-theories, **Techniques** logical models supervision **VLMM**

Forecasting Cyber Attacks Using Big Data

Signals



Fusion



Projection

Challenges

Training data

Diverse evidence

Incomplete, evolving



1



Techniques

Weak supervision

Probabilistic logical models

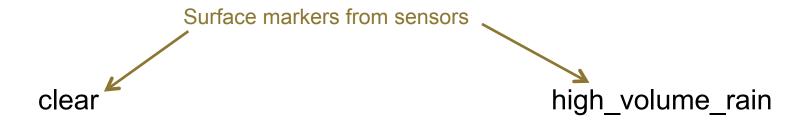
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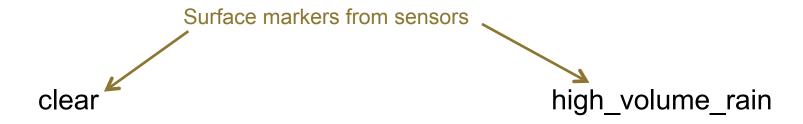
clear







Event of Interest







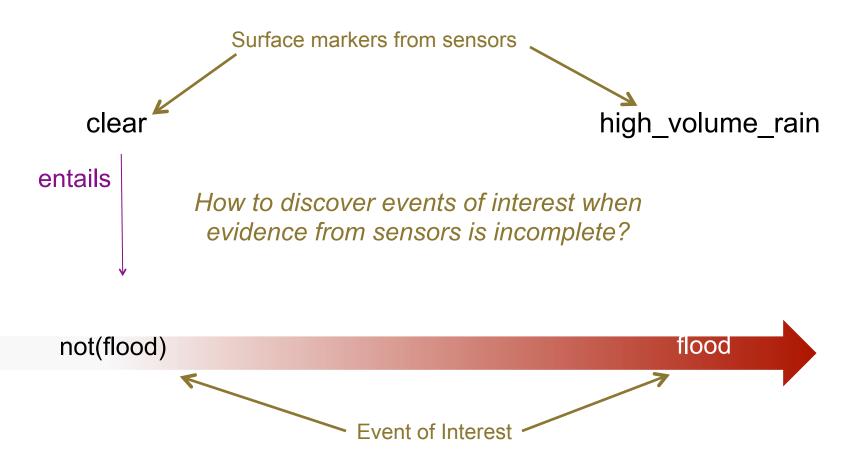


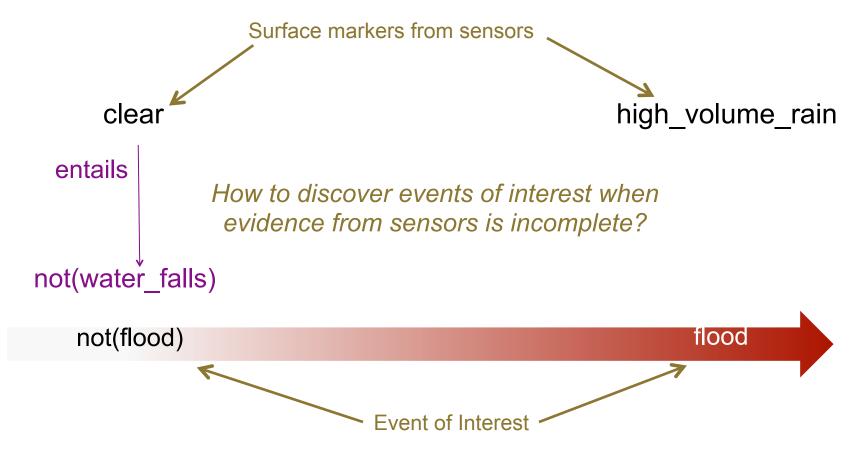


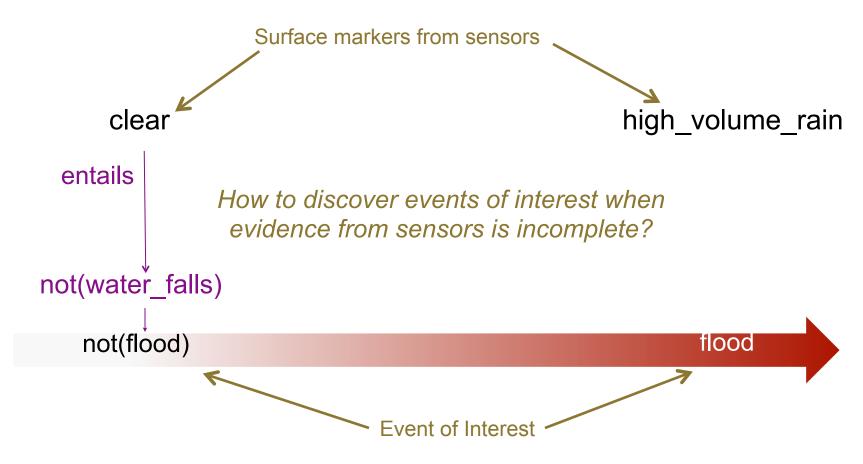
How to discover events of interest when evidence from sensors is incomplete?

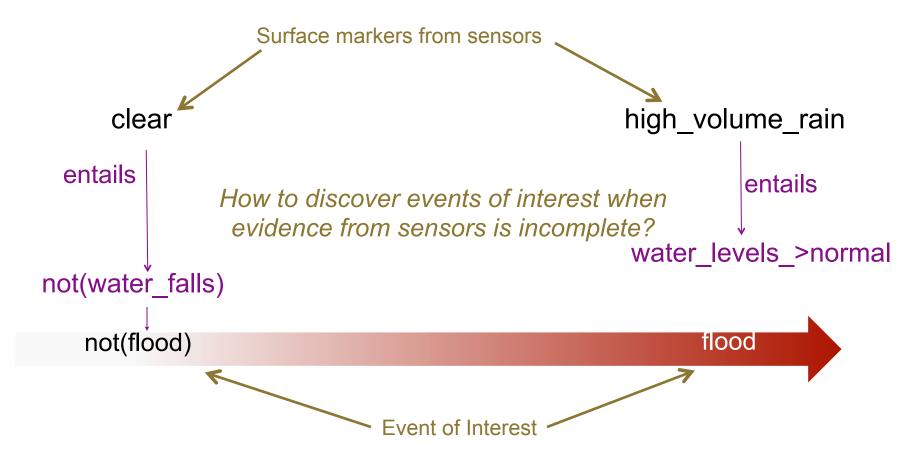


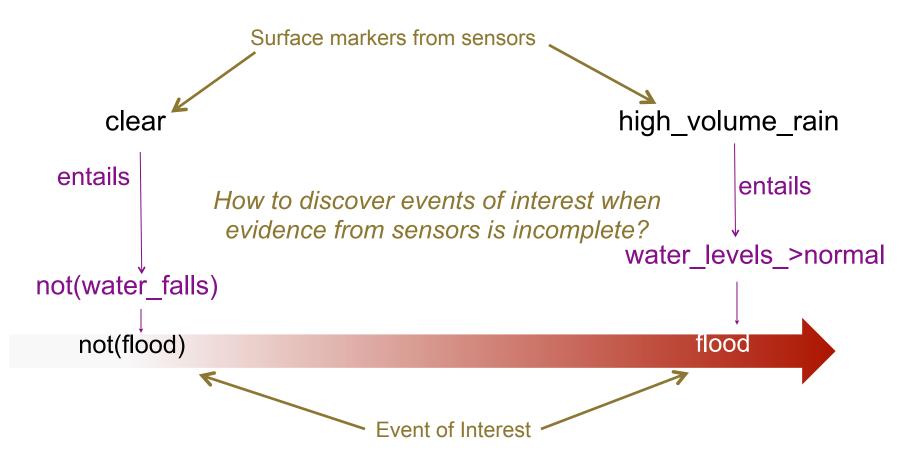


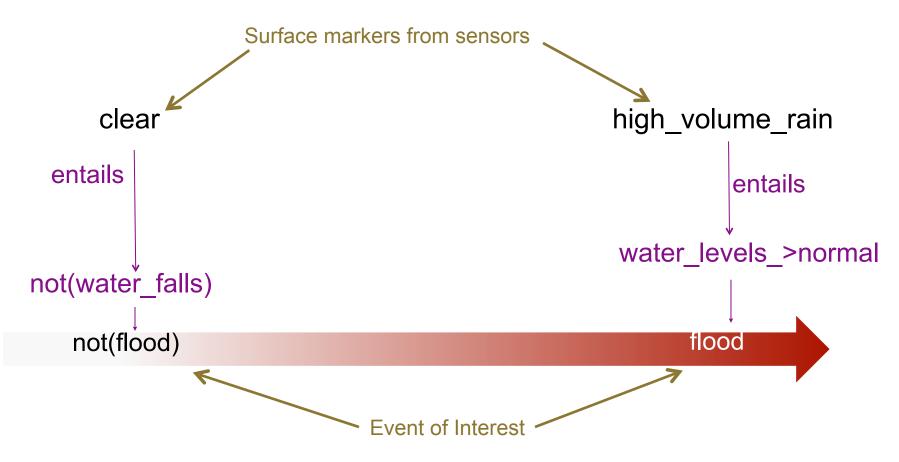


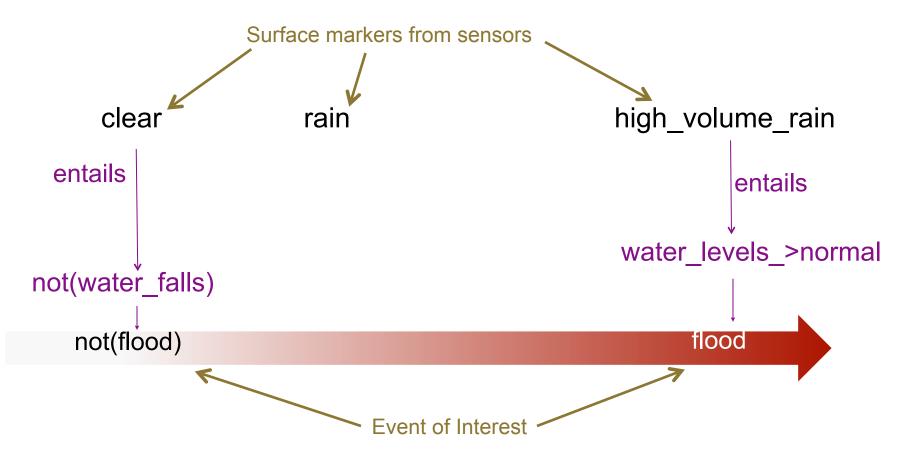


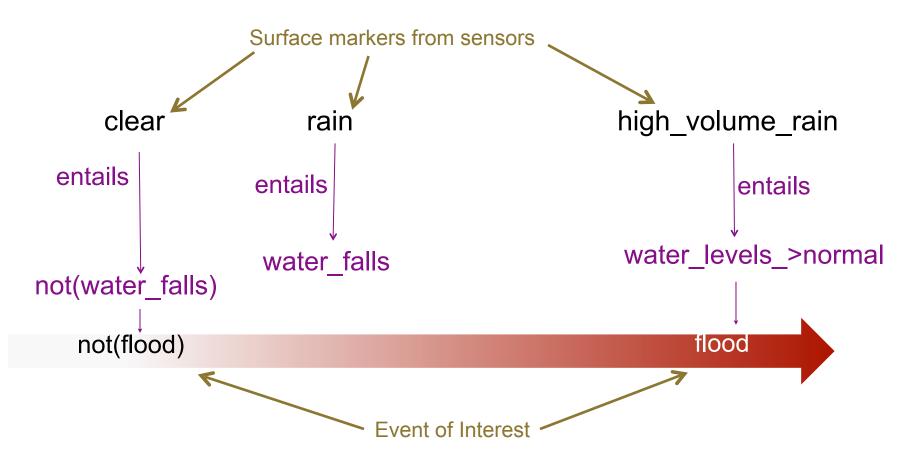


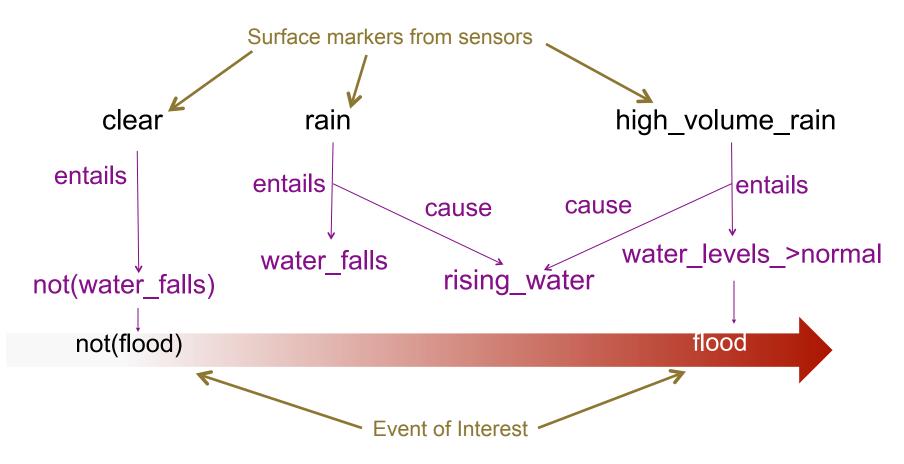


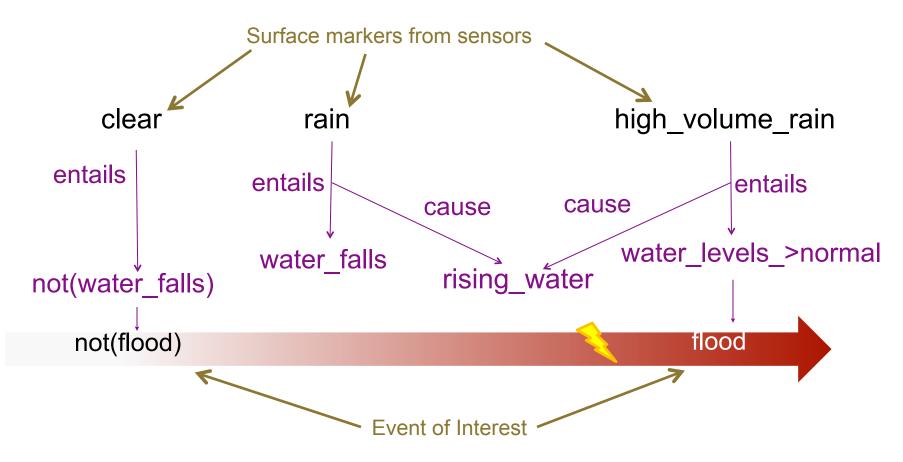












"Whaling protesters hacked Japanese PM's website."

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not(hacked) hacked

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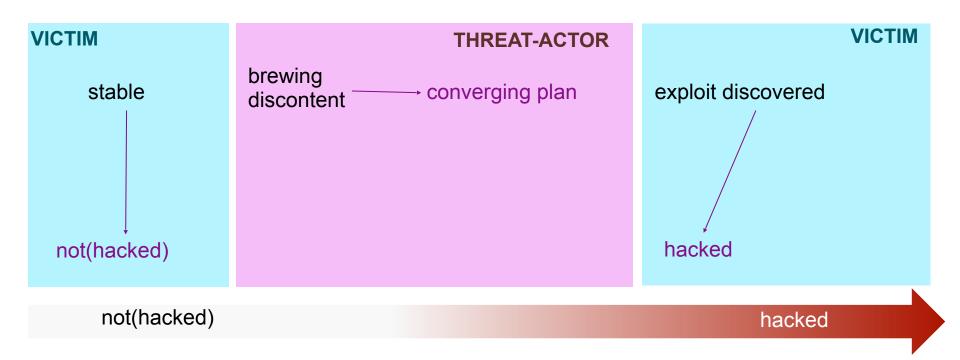
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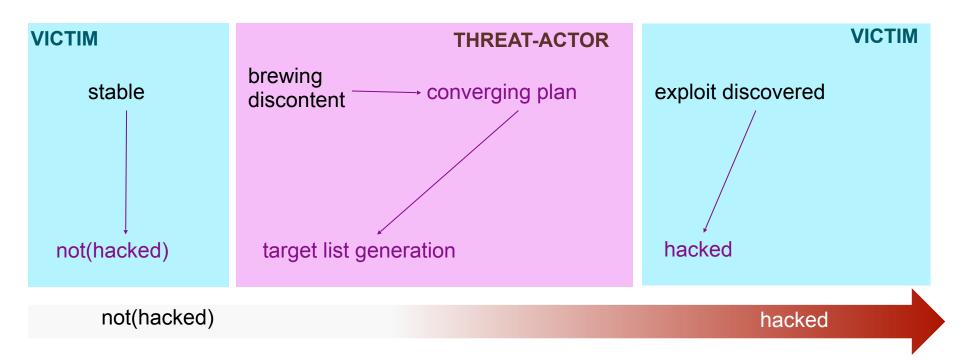
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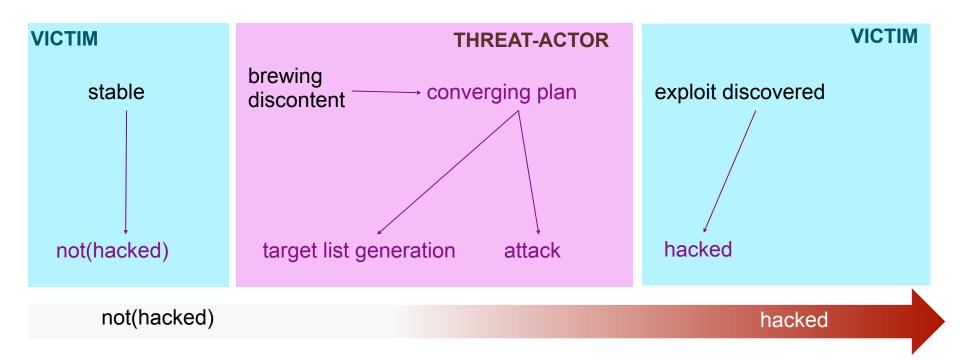
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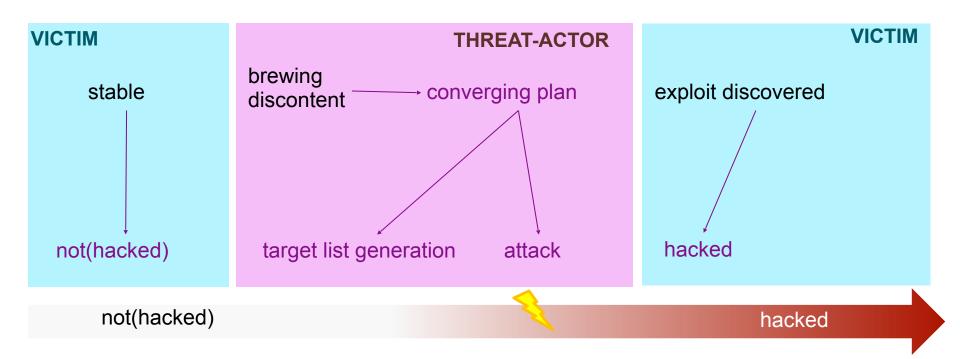
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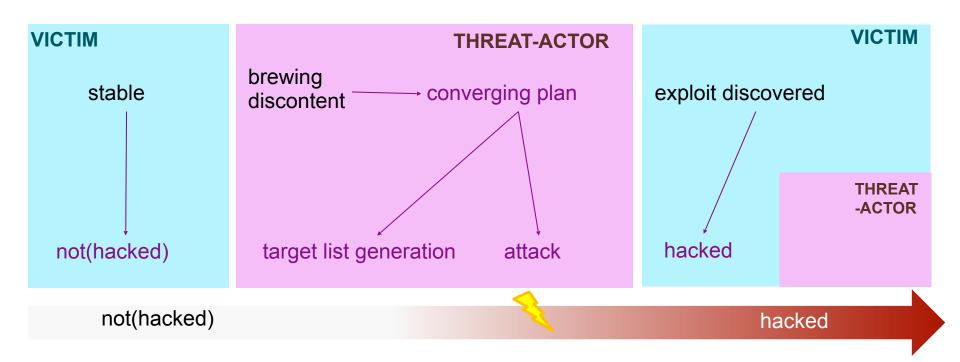
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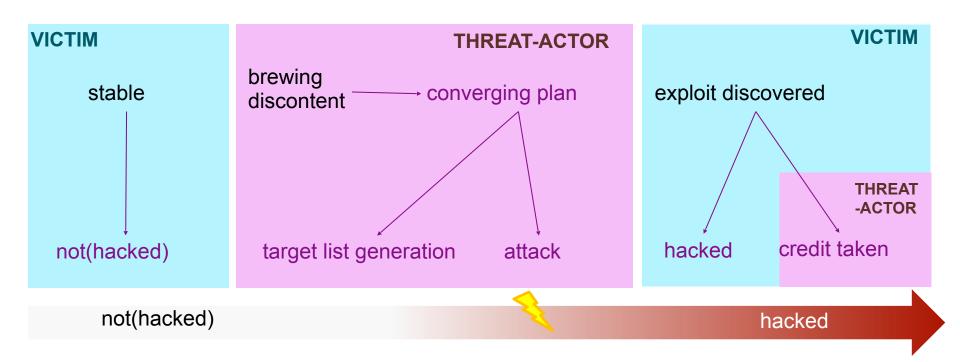
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- 19:00 (Mike) It's been raining really hard.
- 19:02 (Joan) Cats and dogs all day!
- 19:13 (Michelle) I had lamb curry for dinner.
- 19:15 (Mark) There are six inches of water in the yard.
- 19:21 (Michelle) It's pouring like mad.
- 19:32 (Jessica) I've been developing pictures in the darkroom all day.
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Signals



Fusion



Projection

Challenges

Training data

Diverse evidence

Incomplete, evolving



1



Techniques

Weak supervision

Probabilistic logical models

Mini-theories, VLMM

Signals Fusion Projection Training Incomplete, Diverse **Challenges** data evidence evolving Mini-theories, Weak **Probabilistic Techniques** supervision logical models VLMM

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For details please see: Fava, Daniel S., Stephen R. Byers, and Shanchieh Jay Yang. "Projecting cyberattacks through variable-length markov models." IEEE Transactions on Information Forensics and Security 3, no. 3 (2008): 359-369.

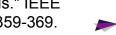


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 - Routines, habits, human preference
 - Uses of toolkits, ...

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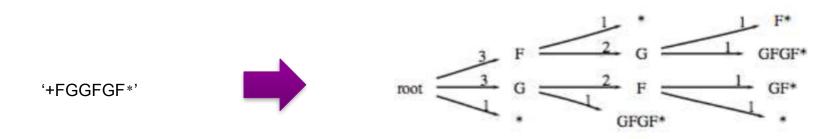
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'+FGGFGF*'

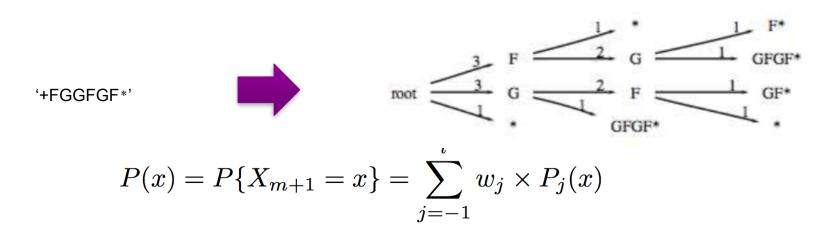




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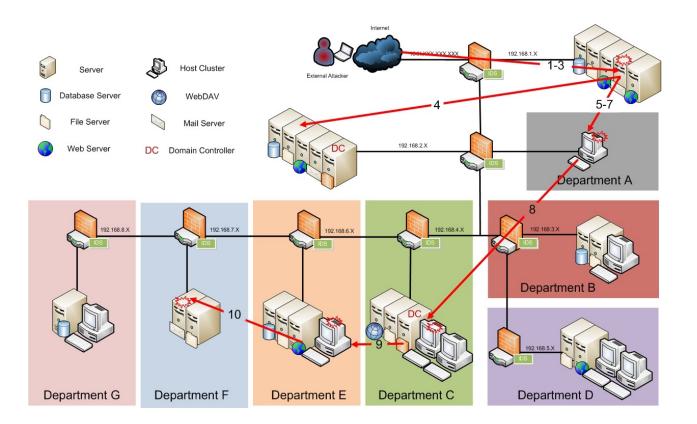


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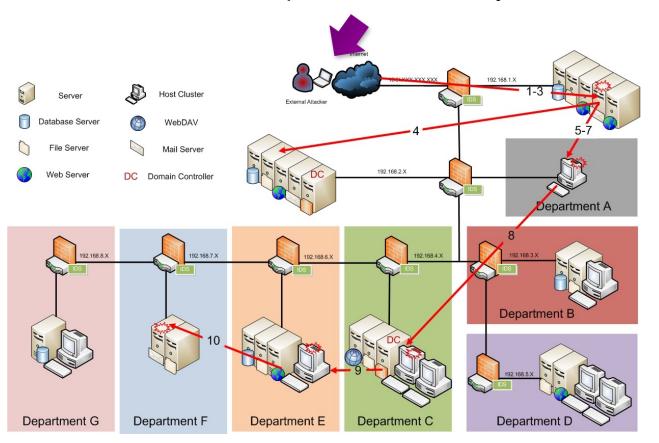




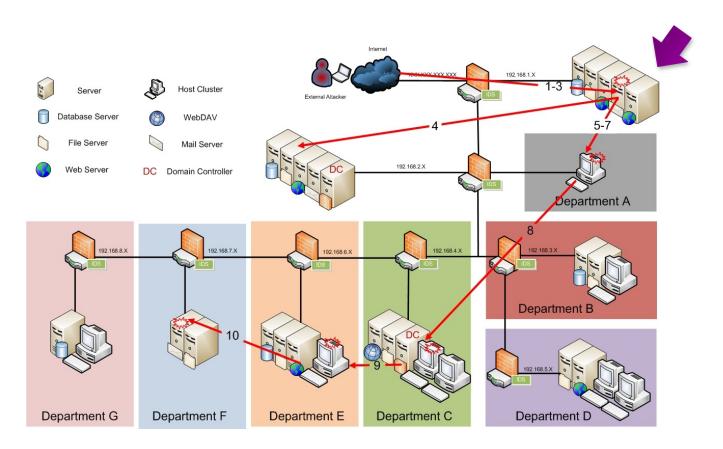
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 - Critical and can be predicted relatively well



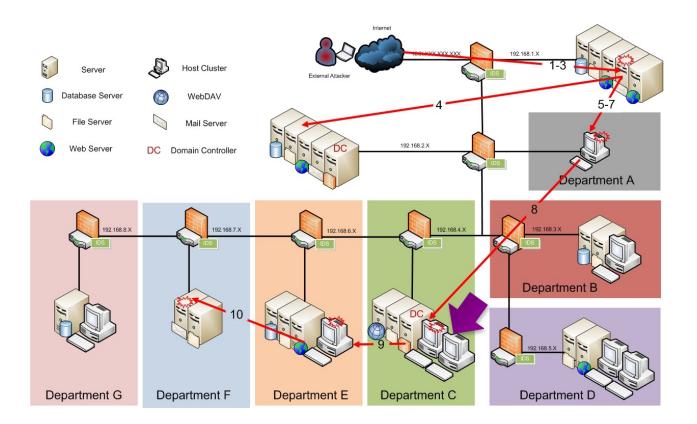
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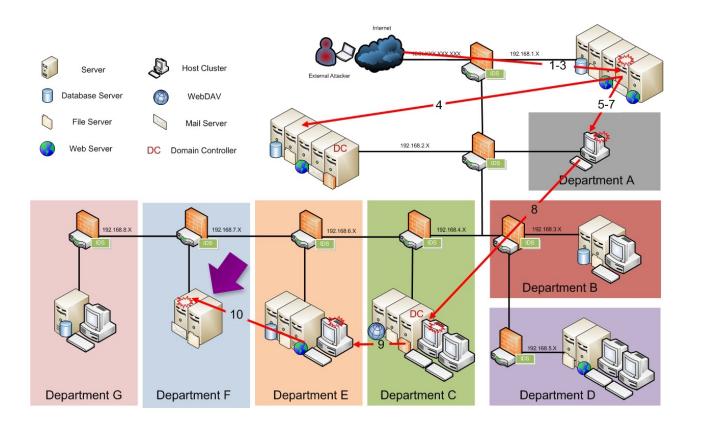
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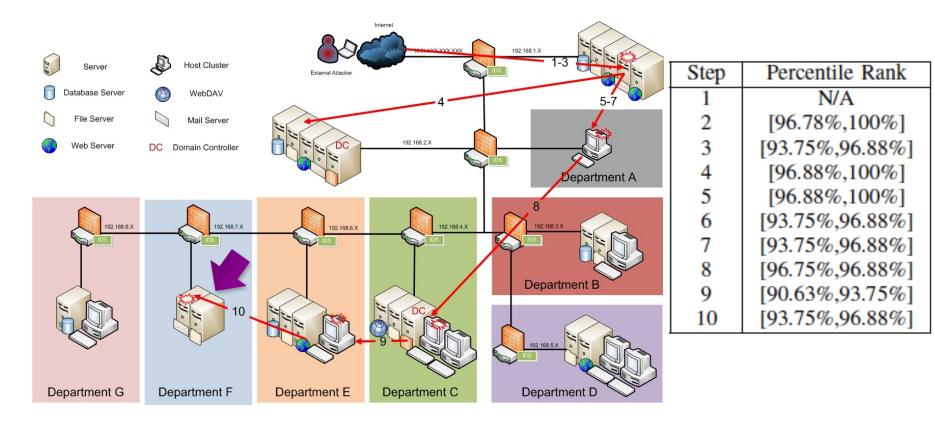
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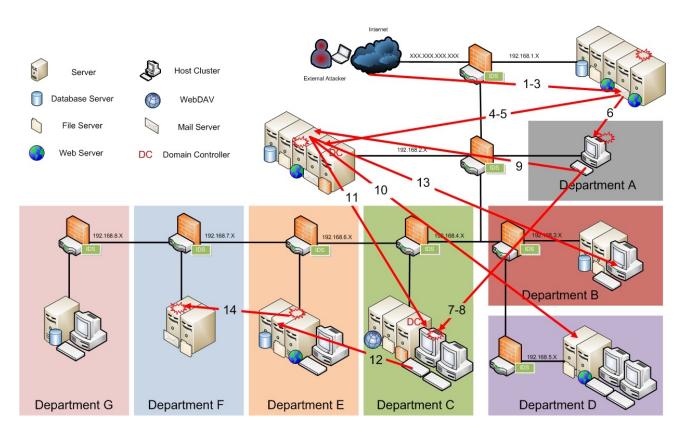
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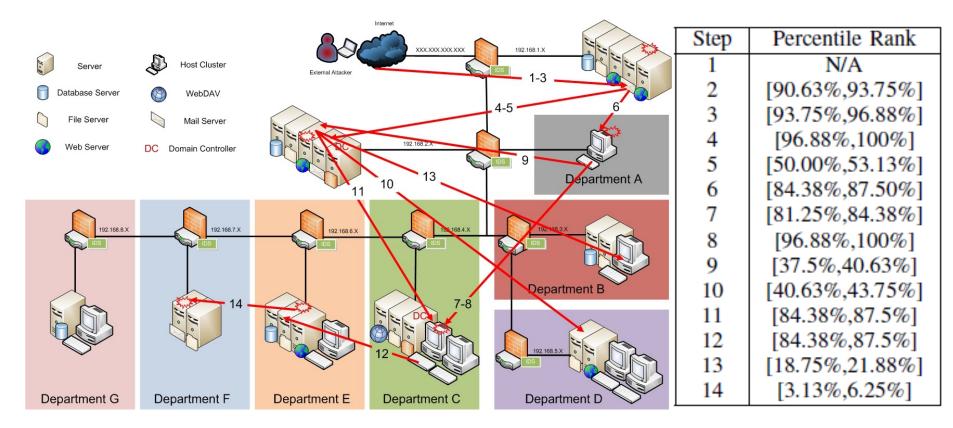
- Direct attack penetrating through the network
 - Critical and can be predicted relatively well



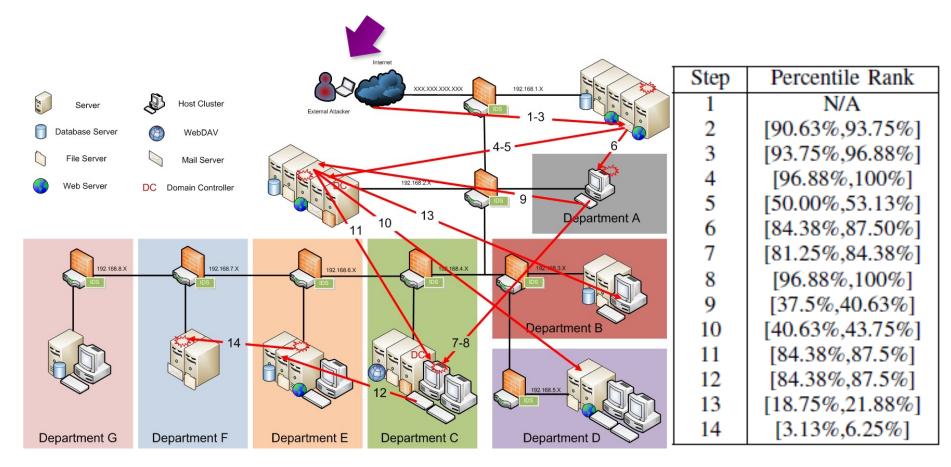
- Random movements spreading all over the network
 - Noisy with some less predictable movement



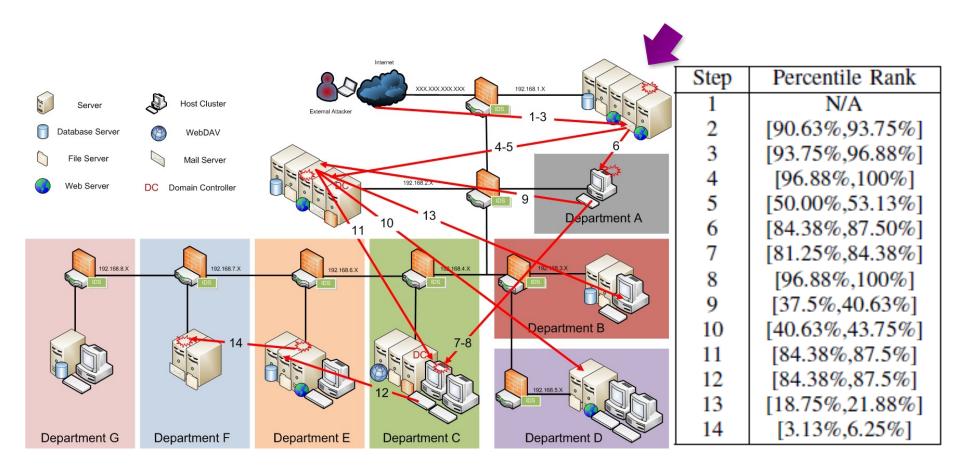
- Random movements spreading all over the network
 - Noisy with some less predictable movement



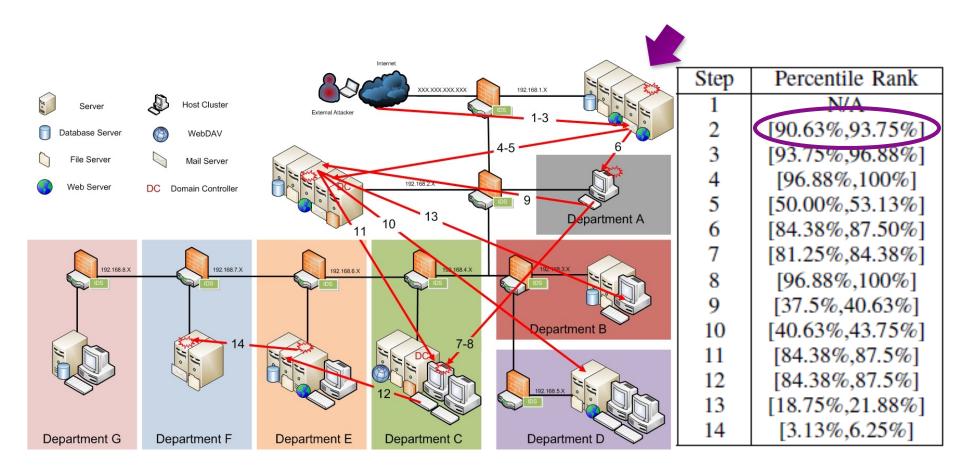
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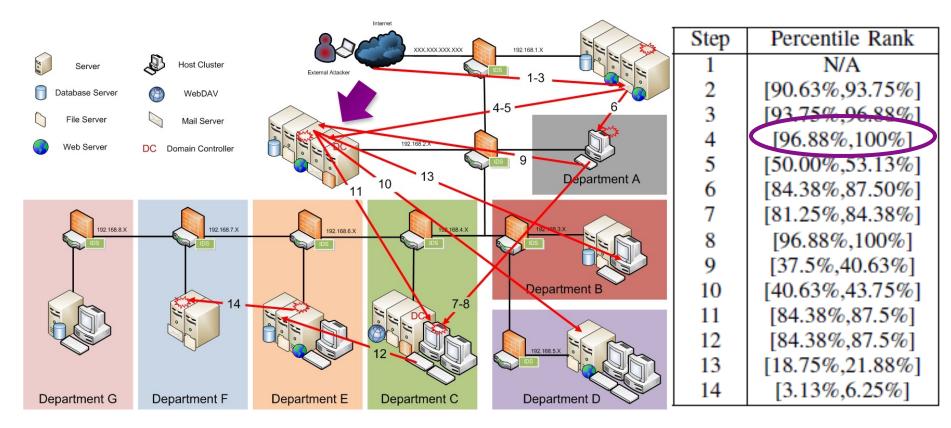
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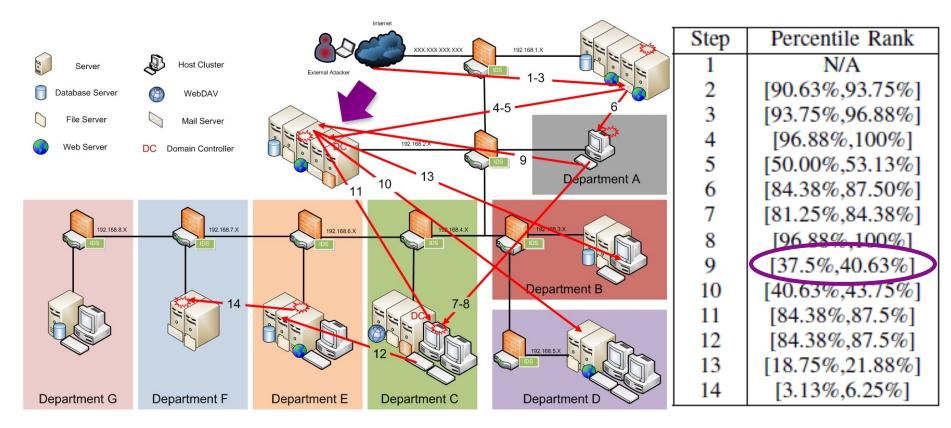
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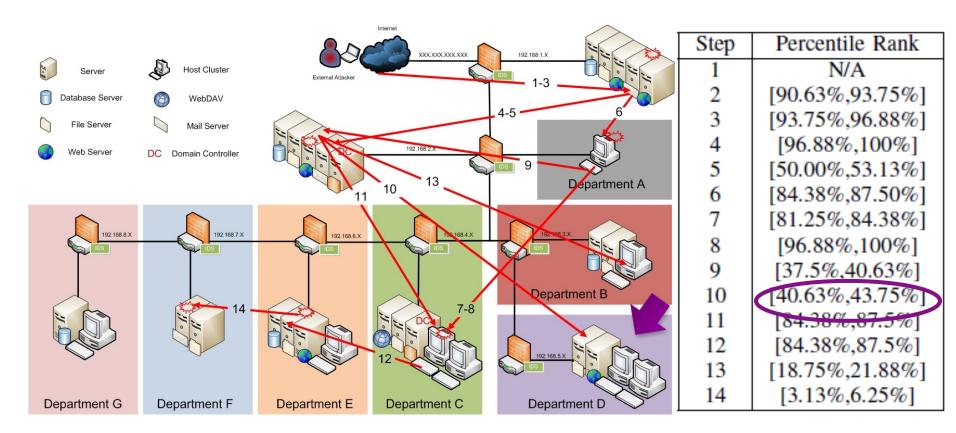
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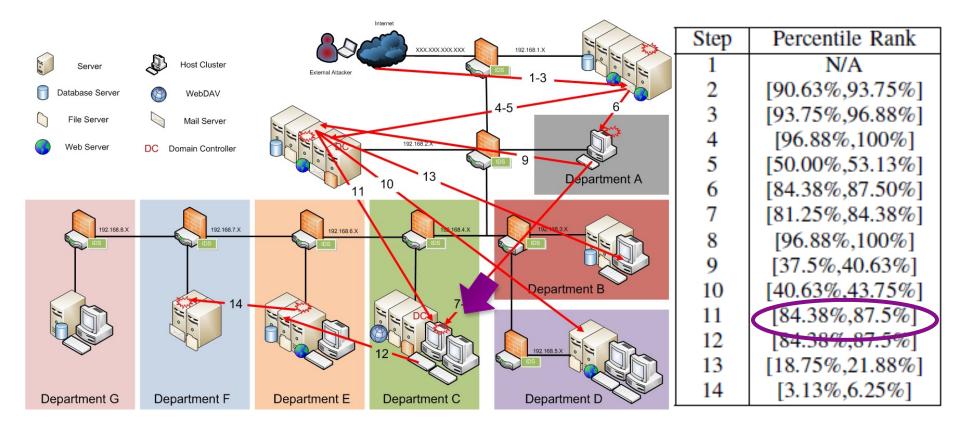
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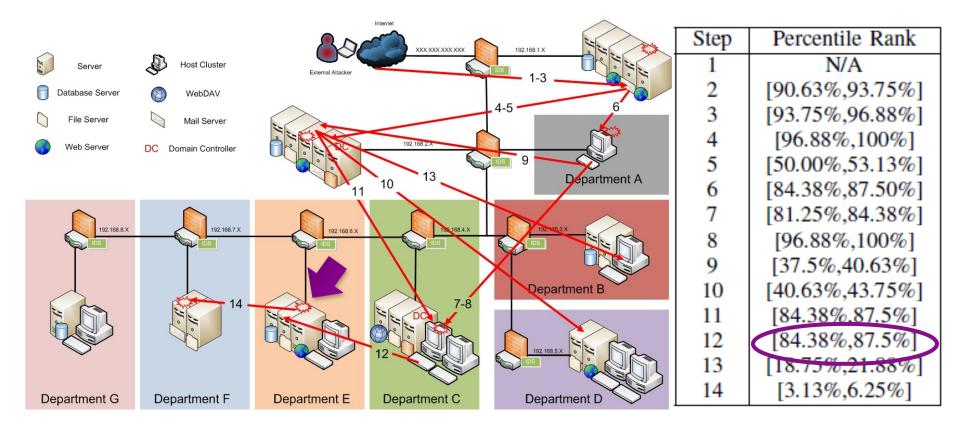
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- Random movements spreading all over the network
 - Noisy with some less predictable movement



- Random movements spreading all over the network
 - Noisy with some less predictable movement



Signals



Fusion



Projection

Challenges

Training data

Diverse evidence

Incomplete, evolving



1



Techniques

Weak supervision

Probabilistic logical models

Mini-theories, VLMM

Exploiting Leading Latent Indicators in Predictive Sensor Environments (ELLIPSE)



Tifani O'Brien (PI), CC Michael (Co-PI), Jonathan Herr, Alex Memory, Leora Morgenstern, Ibrahim Shafi, Viren Shah, Jevon Spivey, Chris Williams, Mark Williams, Ning Yu







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