

Reduced Basis ANOVA for PDEs with High-Dimensional Random Inputs

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- 1 ANOVA decomposition for stochastic PDEs
- 2 Reduced Basis ANOVA
- 3 Numerical Study

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Partial Differential Equations with Uncertain Coefficients

Let $\xi \in I^M$ be a random vector. We find a random function $u(x, \xi)$:

$$\mathcal{L}(x, \xi; u(x, \xi)) = f(x, \xi), \quad (x, \xi) \in D \times I^M,$$

$$\mathfrak{b}(x, \xi; u(x, \xi)) = g(x, \xi), \quad (x, \xi) \in \partial D \times I^M.$$

- \mathcal{L} : a partial differential operator.
- \mathfrak{b} : a boundary operator.
- Both of \mathcal{L} and \mathfrak{b} can have random coefficients.
- The random source ξ is high dimensional.

ANOVA decomposition (Cao, Chen, Gunzburger, Gao, Hesthaven, ...)

$$\mathcal{L}(x, \xi; u(x, \xi)) = f(x, \xi), \quad (x, \xi) \in D \times I^M,$$

$$\mathbf{b}(x, \xi; u(x, \xi)) = g(x, \xi), \quad (x, \xi) \in \partial D \times I^M.$$

Decompose the (global) random solution $u(x, \xi)$ w.r.t ξ :

$$u(x, \xi) = u_{\emptyset}(x) + u_1(x, \xi_1) + \dots + u_{1,2}(x, \xi_{1,2}) + \dots = \sum_{t \in \mathcal{P}} u_t(x, \xi_t).$$

Given anchor point $c = (c_1, \dots, c_M) \in I^M$

Define index set $\mathcal{P} := \{\mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_M\}$ \rightarrow

$$\mathcal{P}_0: \{\emptyset\}$$

$$\mathcal{P}_1: \{1, \dots, M\}$$

$$\mathcal{P}_2: \{(1, 2), (1, 3), \dots, (2, 3), \dots\}$$

...

$$\mathcal{P}_M: \{(1, 2, \dots, M)\}$$

- $u_{\emptyset}(x) := u(x, c)$

- $u_1(x, \xi_1) := u(x, (\xi_1, c_2, \dots, c_M)) - u_{\emptyset}(x)$

- Define a local solution for $t \in \mathcal{P}$: $u(x, c, \xi_t) := u(x, (c_1, \dots, \xi_{t_1}, \dots, \xi_{t_2}, \dots))$

- $u_t(x, \xi_t) := u(x, c, \xi_t) - \sum_{s \subset t} u_s(x, \xi_s)$

Stochastic collocation for each ANOVA term

$$u(x, \xi) = \sum_{t \in \mathcal{P}} u_t(x, \xi_t), \quad u_t(x, \xi_t) := u(x, c, \xi_t) - \sum_{s \subset t} u_s(x, \xi_s), \\ u(x, c, \xi_t) := u\left(x, (c_1, \dots, \xi_{t_1}, \dots, \xi_{t_2}, \dots)\right).$$

$$u(x, c, \xi_t) \text{ satisfies: } \begin{cases} \mathcal{L}(x, \xi_t; u(x, c, \xi_t)) = f(x), & (x, \xi_t) \in D \times I^{|t|}, \\ \mathfrak{b}(x, \xi_t; u(x, c, \xi_t)) = g(x), & (x, \xi_t) \in \partial D \times I^{|t|}. \end{cases}$$

- $|t|$ (dimension of t) is expected to be $\ll M$.
- Approximate $u(x, c, \xi_t)$ using stochastic collocation:

$$u^q(x, c, \xi_t) := \sum_{\xi_t^{(k)} \in \Theta_q^{|t|}} u\left(x, c, \xi_t^{(k)}\right) \Phi_{\xi_t^{(k)}}(\xi_t) \approx u(x, c, \xi_t).$$

- Overall approximation: $u(x, \xi) \approx u^q(x, \xi) := \sum_{t \in \mathcal{P}} u_t^q(x, \xi_t),$
 $u_t^q(x, \xi_t) := u^q(x, c, \xi_t) - \sum_{s \subset t} u_s(x, \xi_s).$

- **Stochastic collocation:** Xiu, Hesthaven, Babuška, Nobile, Tempone, Webster ...
- **ANOVA-Collocation:** Ma, Zabararas, Yang, Lin, Karniadakis ...

Computational aspects of ANOVA-Collocation approximation

ANOVA-Collocation: $u(x, \xi) \approx u^q(x, \xi) := \sum_{t \in \mathcal{P}} u_t^q(x, \xi_t),$

$$u_t^q(x, \xi_t) := u^q(x, c, \xi_t) - \sum_{s \subset t} u_s(x, \xi_s),$$

$$u^q(x, c, \xi_t) := \sum_{\xi_t^{(k)} \in \Theta_q^{|t|}} u(x, c, \xi_t^{(k)}) \Phi_{\xi_t^{(k)}}(\xi_t).$$

Computation challenges

- Many ANOVA terms ($|\mathcal{P}|$ is large)

Adaptive ANOVA (selecting important terms)

■ Ma, Zabaras (2010); Yang, et al. (2012)

- Spatial *d.o.f* can be very large

(computing each collocation coefficient $u(x, c, \xi_t^{(k)})$ is expensive).

Reduced basis collocation:

■ Elman, Liao (2013)

$$\mathcal{P} := \{\mathcal{P}_0, \mathcal{P}_1, \dots, \mathcal{P}_M\}$$

$$\mathcal{P}_0: \{\emptyset\}$$

$$\mathcal{P}_1: \{1, \dots, M\}$$

$$\mathcal{P}_2: \{(1, 2), (1, 3), \dots, (2, 3), \dots\}$$

...

$$\mathcal{P}_M: \{(1, 2, \dots, M)\}$$

Adaptive ANOVA—selecting important terms (indices)

ANOVA-Collocation: $u(x, \xi) \approx u^q(x, \xi) := \sum_{t \in \mathcal{P}} u_t^q(x, \xi_t)$.

\mathcal{P}_0 : $\{\emptyset\}$

\mathcal{P}_1 : $\{1, 2, 3, 4, 5\}$

\mathcal{P}_2 : $\{(1, 2), (1, 3), (1, 4), (1, 5), (2, 3), (2, 4), (2, 5), (3, 4), (3, 5), (4, 5)\}$

\mathcal{P}_3 : $\{(1, 3, 5)\}$

\mathcal{P}_4 : No 4th order terms.

Figure: A example of adaptive index selection.

Selecting criterion:

- Relative mean value \rightarrow

$$\text{relative-mean}_t := \frac{\|\mathbb{E}(u_t^q)\|}{\left\| \mathbb{E} \left(\sum_{s \in \mathcal{P}, |s| \leq |t|-1} u_s^q \right) \right\|}$$

■ **Adaptive ANOVA:** Ma and Zabarar (2010); Yang, et al. (2012).

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Reduced Basis Methods for Parameter Dependent PDEs

$$u^q(x, \xi) := \sum_{t \in \mathcal{P}} u_t^q(x, \xi_t), \quad u_t^q(x, \xi_t) := u^q(x, c, \xi_t) - \sum_{s \subset t} u_s(x, \xi_s),$$
$$u^q(x, c, \xi_t) := \sum_{\xi_t^{(k)} \in \Theta_q^{|t|}} u(x, c, \xi_t^{(k)}) \Phi_{\xi_t^{(k)}}(\xi_t).$$

Finite element methods

- Let $\mathfrak{B}_{\xi_t}(\cdot, \cdot) = l(\cdot)$ denote a weak form, and X^h a FEM space.
- Seek $u_h(\cdot, c, \xi_t) \in X^h \rightarrow \mathfrak{B}_{\xi_t}(u_h(\cdot, c, \xi_t), v) = l(v), \quad \forall v \in X^h.$

Each FEM solution $u_h(\cdot, c, \xi_t)$ is called a *snapshot*.

Reduced basis approximation

- Introduce a reduced basis Q with a small size, $\text{span}(Q) \subset X^h.$
- Seek $u_r(\cdot, c, \xi_t) \in \text{span}(Q) \rightarrow \mathfrak{B}_{\xi_t}(u_r(\cdot, c, \xi_t), v) = l(v), \quad \forall v \in \text{span}(Q).$

Each $u_r(\cdot, c, \xi_t)$ is called a *reduced solution*.

What information should Q contain, and how large is it?

- Ideally, $\text{span}(Q) \supset \{u_h(\cdot, c, \xi_t), \xi_t \in I^{|t|}\}, \quad (\text{the full snapshot set}).$
- Size of $Q = \text{rank of } \{u_h(\cdot, c, \xi_t), \xi_t \in I^{|t|}\} \ll N_h? \quad (N_h: \text{FEM d.o.f})$ 9/22

Algebraic Issue and Error Indicator, Linear PDEs

Original finite element approximation: $\mathbf{A}_{\xi_t} \in \mathbb{R}^{N_h \times N_h} \rightarrow$

$$\mathbf{A}_{\xi_t} \mathbf{u}_h = \mathbf{f}.$$

Reduced basis approximation: $\mathbf{Q} \in \mathbb{R}^{N_h \times N_r}$ with $N_r \ll N_h \rightarrow$

$$\mathbf{Q}^T \mathbf{A}_{\xi_t} \mathbf{Q} \mathbf{u}_r = \mathbf{Q}^T \mathbf{f}.$$

Reduced basis approximation is a projection:

- projects a large $N_h \times N_h$ system to a small $N_r \times N_r$ system \rightarrow very cheap to solve.

To estimate the error $e = \mathbf{u}_h - \mathbf{Q} \mathbf{u}_r$, we use the residual indicator:

$$\text{error-indicator}_{\xi_t} = \|\mathbf{A}_{\xi_t} \mathbf{Q} \mathbf{u}_r - \mathbf{f}\|.$$

- The cost of this residual indicator is $O(N_r^2)$, independent of N_h .

Greedy Algorithm (Patera, Boyaval, Bris, Lelièvre, Maday, Nguyen, ...)

Goal for reduced solution: $u_r \approx u_h, \leftrightarrow \text{span}(Q) \approx \{u_h(\cdot, c, \xi_t), \xi_t \in I^{|t|}\}$.

- SVD approach: get Q from $SVD\{u_h(\cdot, c, \xi_t), \xi_t \in I^{|t|}\}$, but may be **expensive**.
- Greedy approach: **find most important samples** $\rightarrow Q$.

Given: a set of candidate parameters $\chi = \{\xi_t\}$,

an initial choice $\xi_t^{(1)} \in \chi$, and compute the snapshot $u_h(\cdot, c, \xi_t^{(1)})$.

Initialize: $Q = \{u_h(\cdot, c, \xi_t^{(1)})\}$

for each $\xi_t \in \chi$

compute reduced solution $u_r(\cdot, c, \xi_t)$

compute error-indicator $_{\xi_t}$ (an error indicator for $\|u_h - u_r\|$)

If error-indicator $_{\xi} > tol$

compute $u_h(\cdot, c, \xi_t)$, and update $Q = \{Q, u_h(\cdot, c, \xi_t)\}$

endif

endfor

■ **Greedy on sparse grids:** Elman and Liao (2013); Chen et al. (2015)

12 / 22

Reduced bases for ANVOA-Collocation terms

ANOVA-Collocation: $u(x, \xi) \approx u^q(x, \xi) := \sum_{t \in \mathcal{P}} u_t^q(x, \xi_t),$

$$u_t^q(x, \xi_t) := u^q(x, c, \xi_t) - \sum_{s \subset t} u_s(x, \xi_s),$$

$$u^q(x, c, \xi_t) := \sum_{\xi_t^{(k)} \in \Theta_q^{|t|}} u(x, c, \xi_t^{(k)}) \Phi_{\xi_t^{(k)}}(\xi_t).$$

- 1 Use collocation points $\Theta_q^{|t|}$ as candidate set χ .
- 2 Use reduced solution $u_r \rightarrow u_c := u(x, c, \xi_t^{(k)})$ whenever possible.
- 3 Different reduced basis Q_t for different t , but use them hierarchically \rightarrow

$$\mathcal{P}_0: \quad \{\emptyset\}$$

$$\mathcal{P}_1: \quad \{1, 2, 3, 4, 5\}$$

$$\mathcal{P}_2: \quad \{(1, 2), (1, 3), (1, 4), (1, 5), (2, 3), (2, 4), (2, 5), (3, 4), (3, 5), (4, 5)\}$$

$$\mathcal{P}_3: \quad \{(1, 3, 5)\}$$

...

...

Algorithm (Reduced Basis ANOVA)

- 1 Start with ANOVA level $i = 0$, initialize the index set $\mathcal{P}_0 = \{\emptyset\}$.
- 2 Set $Q_\emptyset := \{u_h(\cdot, c)\}$.
- 3 Set $\mathcal{P}_1 = \{1, \dots, M\}$.
- 4 Update ANOVA level $i = i + 1$.
- 5 Loop over each $t \in \mathcal{P}_i$, i.e. $|t| = i$
 - Initialize local reduced basis: $Q_t := SVD \{q \mid q \in \cup_{s \subset t} Q_s\}$.
 - For each $\xi_t^{(k)} \in \Theta_q^{|t|}$ (collocation points), compute the reduced solution $u_r(\cdot, c, \xi_t^{(k)})$ and error-indicator $\xi^{(k)}$.
If $\text{error-indicator}_{\xi^{(k)}} < \text{tol}$, $u_c \leftarrow u_r(\cdot, c, \xi_t^{(k)})$.
If $\text{error-indicator}_{\xi^{(k)}} \geq \text{tol}$, $u_c \leftarrow u_h(\cdot, c, \xi_t^{(k)})$ and $Q_t := \{Q_t, u_h\}$.
 - Compute relative-mean $_t$.
 - If $\text{relative-mean}_t < \text{tol}_{ANOVA}$, remove the index t : $\mathcal{P}_i = \mathcal{P}_i \setminus t$.
- 6 Generate \mathcal{P}_{i+1} based on \mathcal{P}_i , and repeat step 5 for next level $i = i + 1$.

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Test Problem

Diffusion equation: $-\nabla \cdot (a \nabla u) = f$ in $[0, 1]^2$

The permeability coefficient a is a random field:

- mean function: $a_0(x) = 1$, standard deviation: $\sigma = 0.25$
- covariance function $C(x, y)$:

$$C(x, y) = \sigma^2 \exp\left(-\frac{|x_1 - y_1|}{c} - \frac{|x_2 - y_2|}{c}\right),$$

where c is the correlation length.

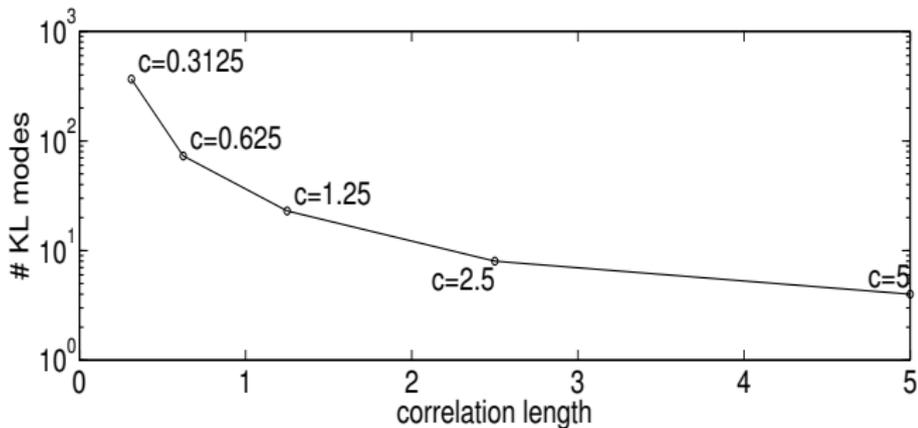
Parameterizing a using truncated KL expansion:

$$a(x, \xi) \approx a_0(x) + \sum_{k=1}^M \sqrt{\lambda_k} a_k(x) \xi_k,$$

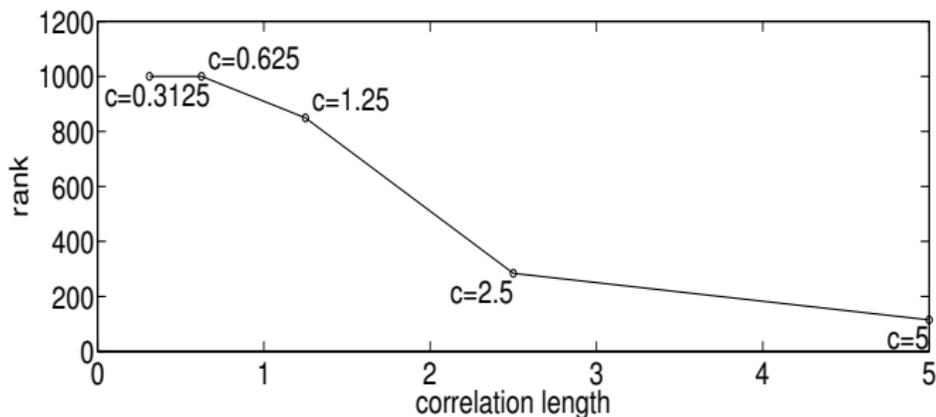
random vector $\xi = (\xi_1, \dots, \xi_M)$ is uniformly distributed in $\Gamma = [-1, 1]^M$.

- Small correlation length c leads to many KL terms.
- **We consider small c situations (high-dimensional problems).**

of KL modes (M)
for capturing 95% of
the total variance



Rank of
 $\{u_h(\cdot, \xi), \xi \in I^{|M|}\}$



• FEM *d.o.f* : $N_h = 1089$

• Directly applying reduced basis methods may not be efficient for $c \leq 0.625$ 17/22

Direct combination of MC and reduced basis (for comparison)

For each MC input sample $\xi^{(k)}$,

compute reduced solution $u_r(\cdot, \xi^{(k)})$ and error-indicator $\xi^{(k)}$:

if error-indicator $\xi^{(k)} < tol$, MC sample $\leftarrow u_r(\cdot, \xi^{(k)})$;

if error-indicator $\xi^{(k)} \geq tol$, MC sample $\leftarrow u_h(\cdot, \xi^{(k)})$ and $Q := \{Q, u_h\}$.

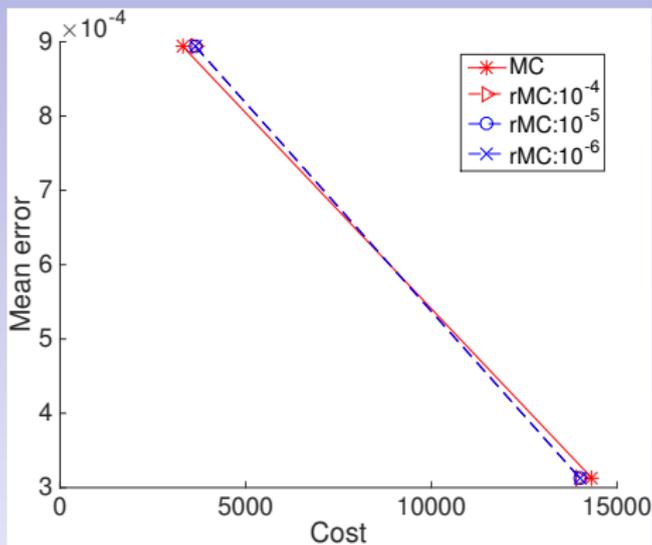
Computational cost assessment model:

- Cost unit: 1 FEM system solve.
- Cost of a reduced system solve: N_r/N_h ,
(N_r : reduced basis size; N_h : FEM *d.o.f.*).
- Cost of a full MC with N samples: N .
- Cost of a reduced basis MC with N samples and \tilde{N} FEM solves:

$$\tilde{N} + \sum_{k=1}^N \frac{N_r(\xi^{(k)})}{N_h},$$

reduced basis size $N_r(\xi^{(k)})$ is dependent on $\xi^{(k)}$ in the greedy procedure.

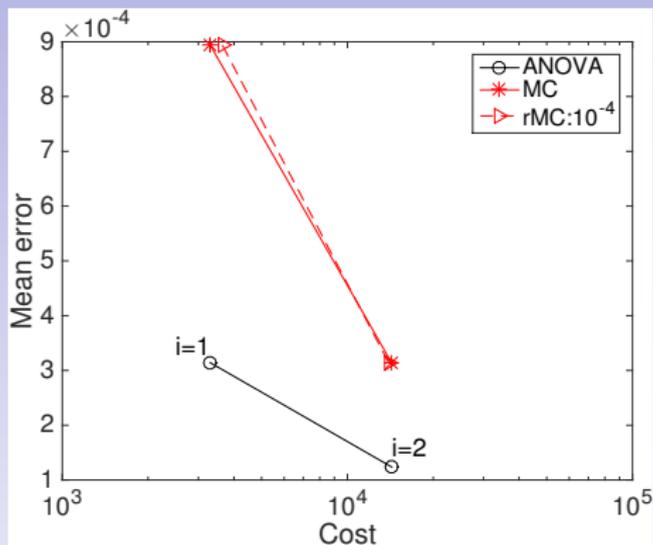
Direct reduced MC test, for $c = 0.3125$, $M = 367$; $\text{rank} \approx N_h = 1089$.



For this test, comparing MC and reduced basis MC (rMC),

- costs of the reduced basis MC are still large.

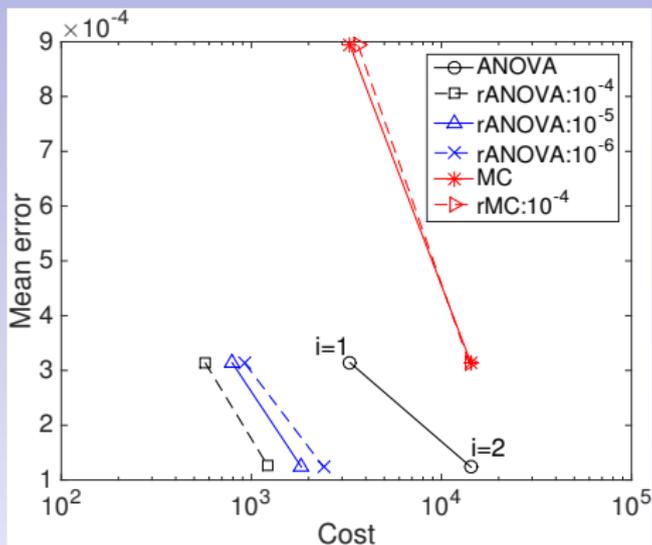
ANOVA vs MC, for $c = 0.3125$, $M = 367$; rank $\approx N_h = 1089$.



For this test,

- ANOVA has very small mean errors.

Reduced basis ANOVA, for $c = 0.3125$, $M = 367$; rank $\approx N_h = 1089$.



For this test,

- Reduced basis ANOVA (rANOVA) is very cheap.

Summary

- ANOVA methods have been designed to solve PDEs with high-dimensional random inputs.
- Many PDE solves can be involved for generating ANOVA-Collocation approximation.
- Our hierarchically-generated reduced bases can reduce the computational costs of ANOVA methods.