

Trans-D Methods for Quantifying Uncertainty in Seismic Inversion



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Acknowledgments:

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Problems with the FWI objective function



$$\arg \min \phi(\mathbf{m}) = \|\mathbf{W}(\mathbf{d} - \mathbf{f}(\mathbf{m}))\|_2^2 + \lambda^2 \|\mathbf{R}\mathbf{m}\|_p^p$$

Limitations in conventional approach

Bad choices for \mathbf{R} and λ^2 lead to slow convergence

Solution requires linearization

Local minima abound

No convergence guarantees exist

Model \mathbf{m} is high dimensional

Problems with the FWI objective function



$$\arg \min \phi(\mathbf{m}) = \|\mathbf{W}(\mathbf{d} - \mathbf{f}(\mathbf{m}))\|_2^2 + \lambda^2 \|\mathbf{R}\mathbf{m}\|_p^p$$

Limitations in conventional approach	Bayesian solutions
Bad choices for \mathbf{R} and λ^2 lead to slow convergence	Appeal to a parsimonious model basis
Solution requires linearization	Do not linearize
Local minima abound	Sample in parallel (parallel tempering)
No convergence guarantees exist	Sample the model space (Markov chain Monte Carlo or McMC)
Model \mathbf{m} is high dimensional	Appeal to parsimony (trans-D McMC)

A traditional Bayesian view



updated belief \propto likelihood of belief \cdot prior belief

$$p(\mathbf{m}|\mathbf{d}) \propto p(\mathbf{d}|\mathbf{m}) \cdot p(\mathbf{m})$$

Given the
observed
seismic data
d, new belief
in model **m**

Given the
model **m**,
accuracy of
seismic
prediction

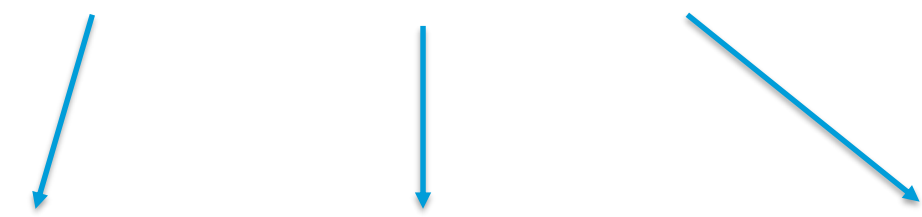
m is a model
obtained from
prior notions,
e.g., well data,
geology, etc.

Equivalence of Bayes' theorem with optimization



updated belief \propto likelihood of belief \cdot prior belief

$$p(\mathbf{m}|\mathbf{d}) \propto p(\mathbf{d}|\mathbf{m}) \cdot p(\mathbf{m})$$


$$\arg \min \phi(\mathbf{m}) = \|\mathbf{W}(\mathbf{d} - \mathbf{f}(\mathbf{m}))\|_2^2 + \lambda^2 \|\mathbf{R}\mathbf{m}\|_p^p$$

But non-linearity (i.e., non-uniqueness), high model dimension and model parametrization make equivalence more of a *theoretical* comfort

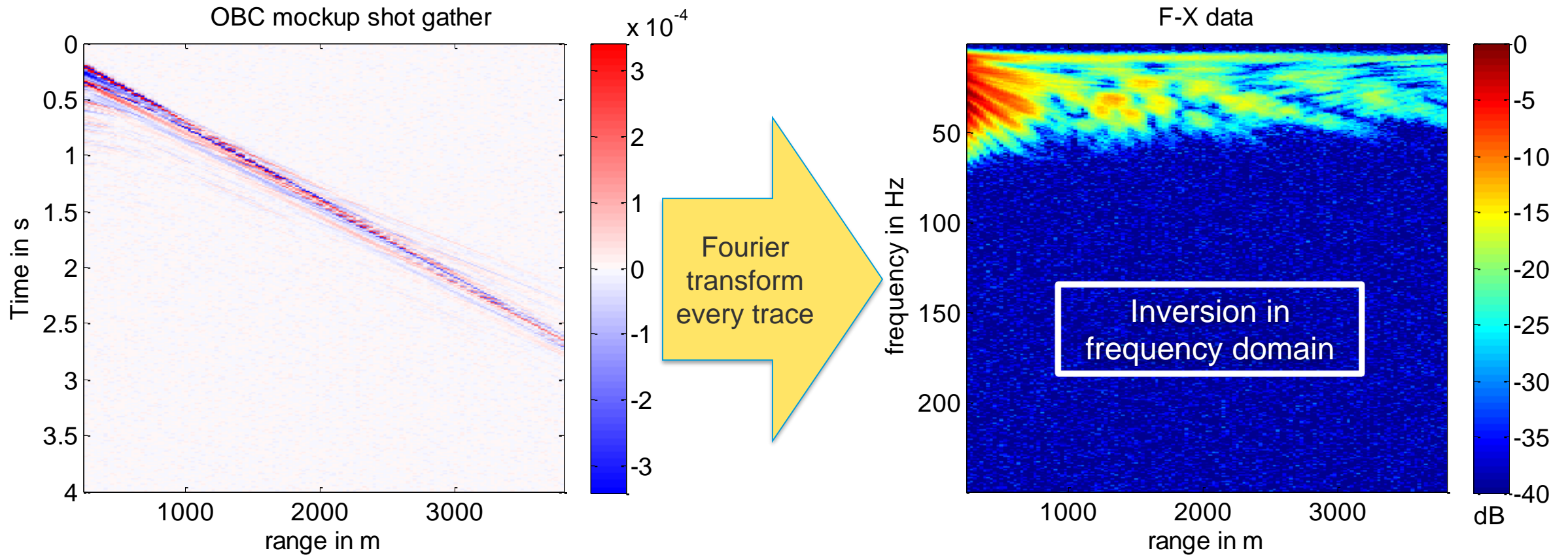
Trans-dimensional (trans-D) Bayesian inversion



Ordinary McMC	Change model parameters while sampling
trans-D McMC	Add/delete parameters while sampling

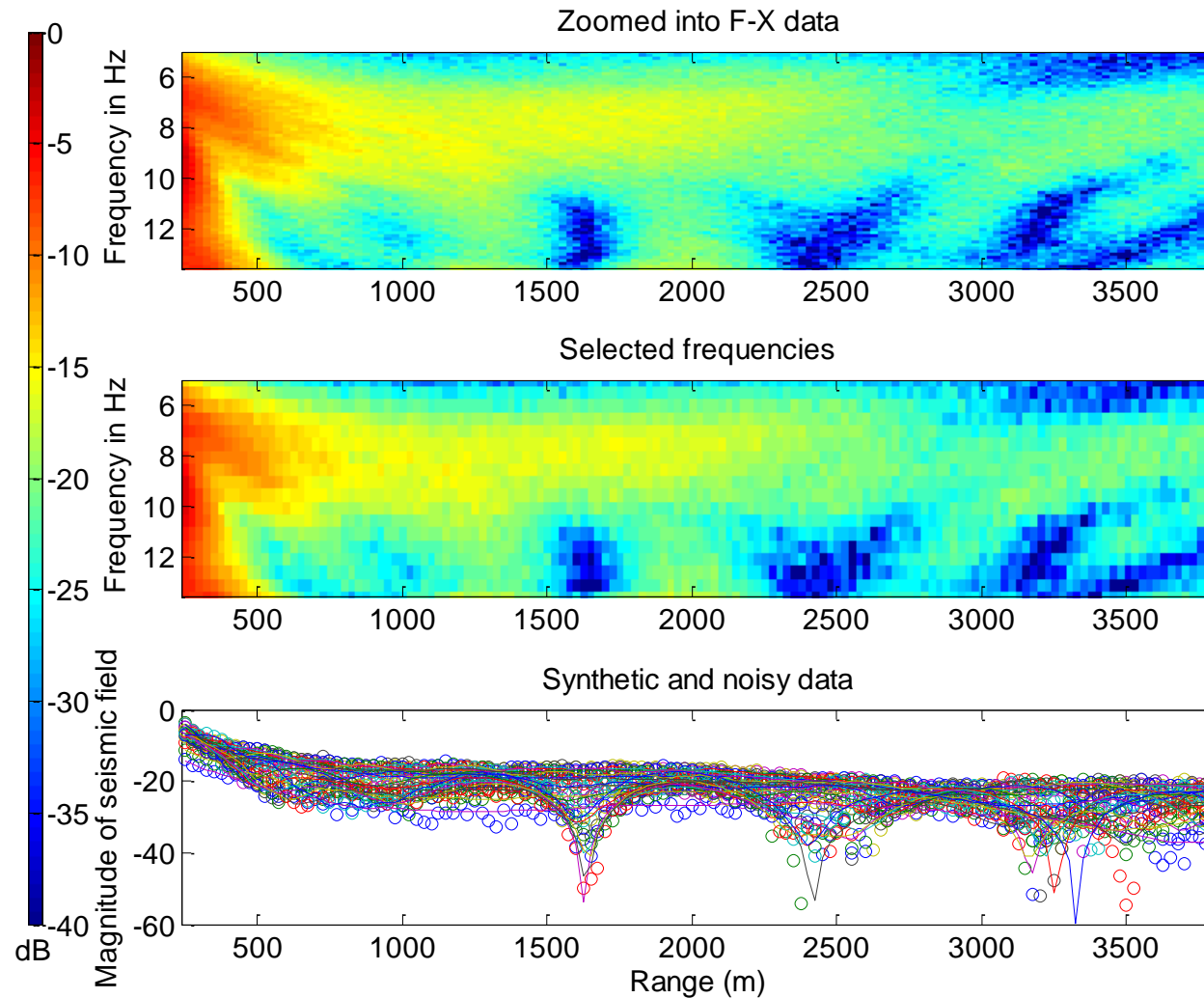
$$p(k|\mathbf{d}) \propto p(\mathbf{d}|\mathbf{m}_k, k) \cdot \left[f_1 \cdot f_2 \cdots f_k \right].$$

Noisy synthetic data



Hydrophones receive mode converted data as well

F-X data for inversion (SYNTHETIC EXAMPLE)

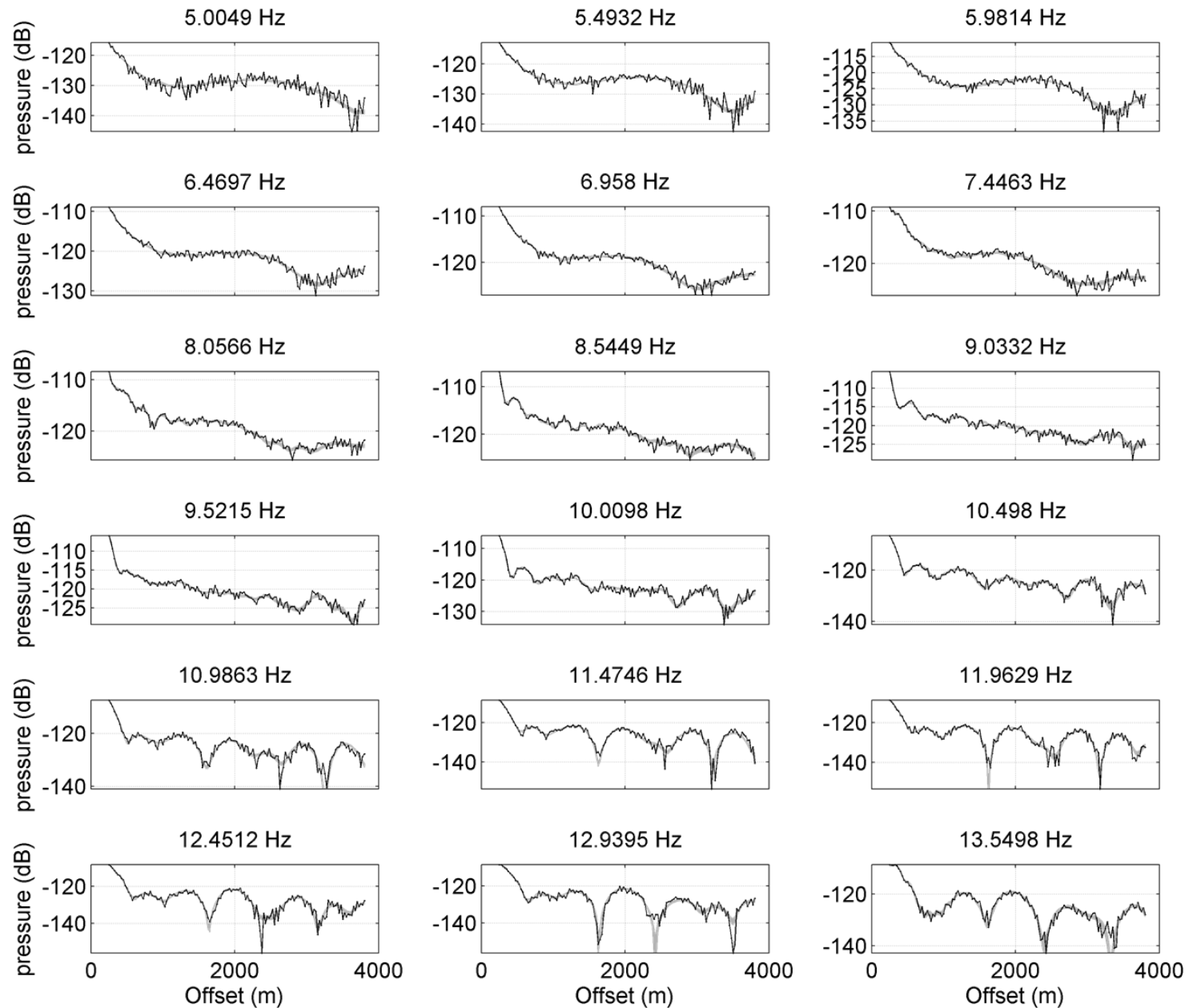


18 frequencies
selected every
0.5 Hz

18 frequency inversion

Black = noisy data

Grey = 500 calculated responses, randomly selected from posterior models





0. Compute
Green's function

1. Estimate
wavelet

2. Calculate
forward

3. Calculate
misfit

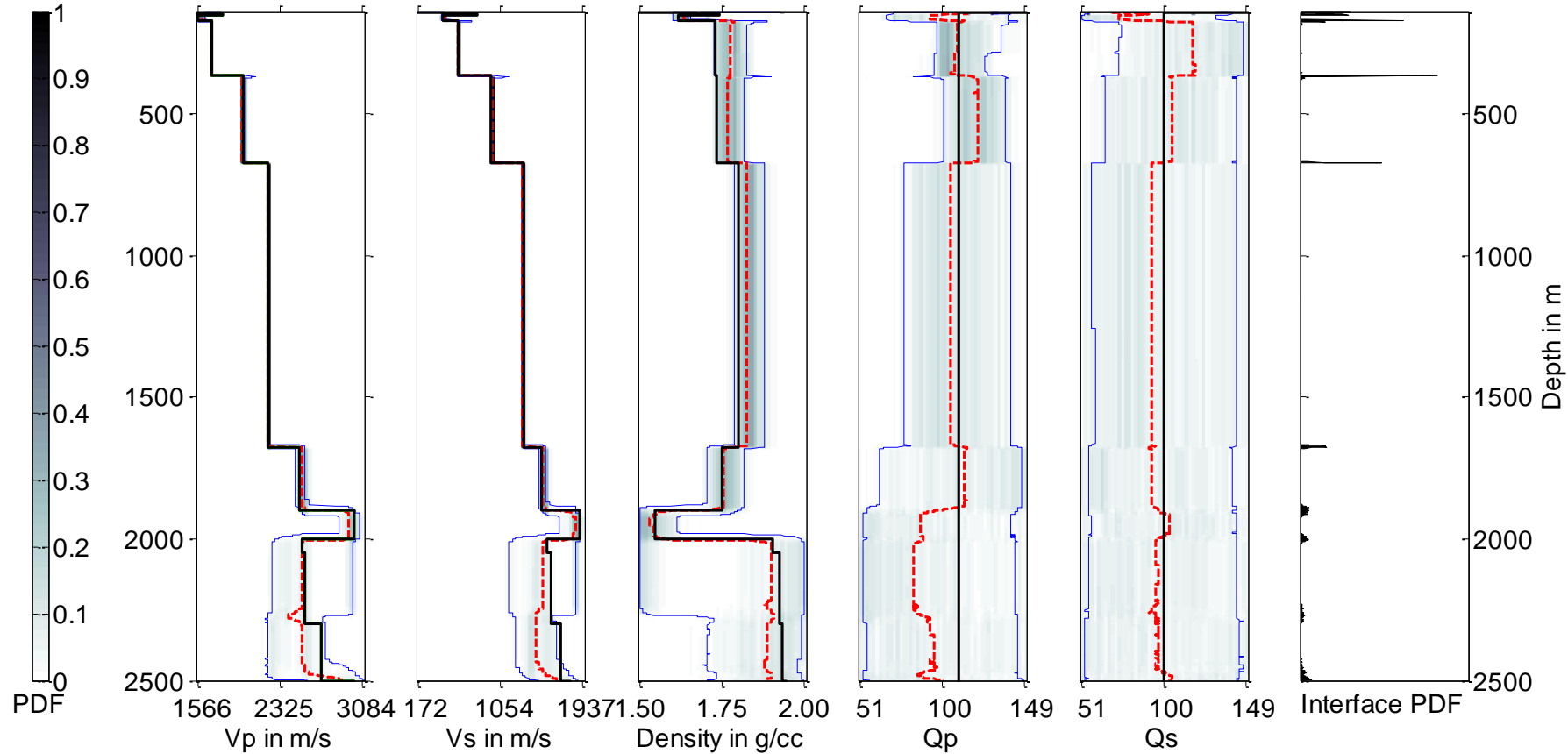
For model $\mathbf{m} = [\mathbf{z}, \mathbf{V}_p, \nu, \rho, \mathbf{Q}_p, \mathbf{Q}_s]$,

$$\hat{S}_l(\mathbf{m}) = \frac{\mathbf{G}_l^\dagger(\mathbf{m})\mathbf{d}_l}{\mathbf{G}_l^\dagger(\mathbf{m})\mathbf{G}_l(\mathbf{m})},$$

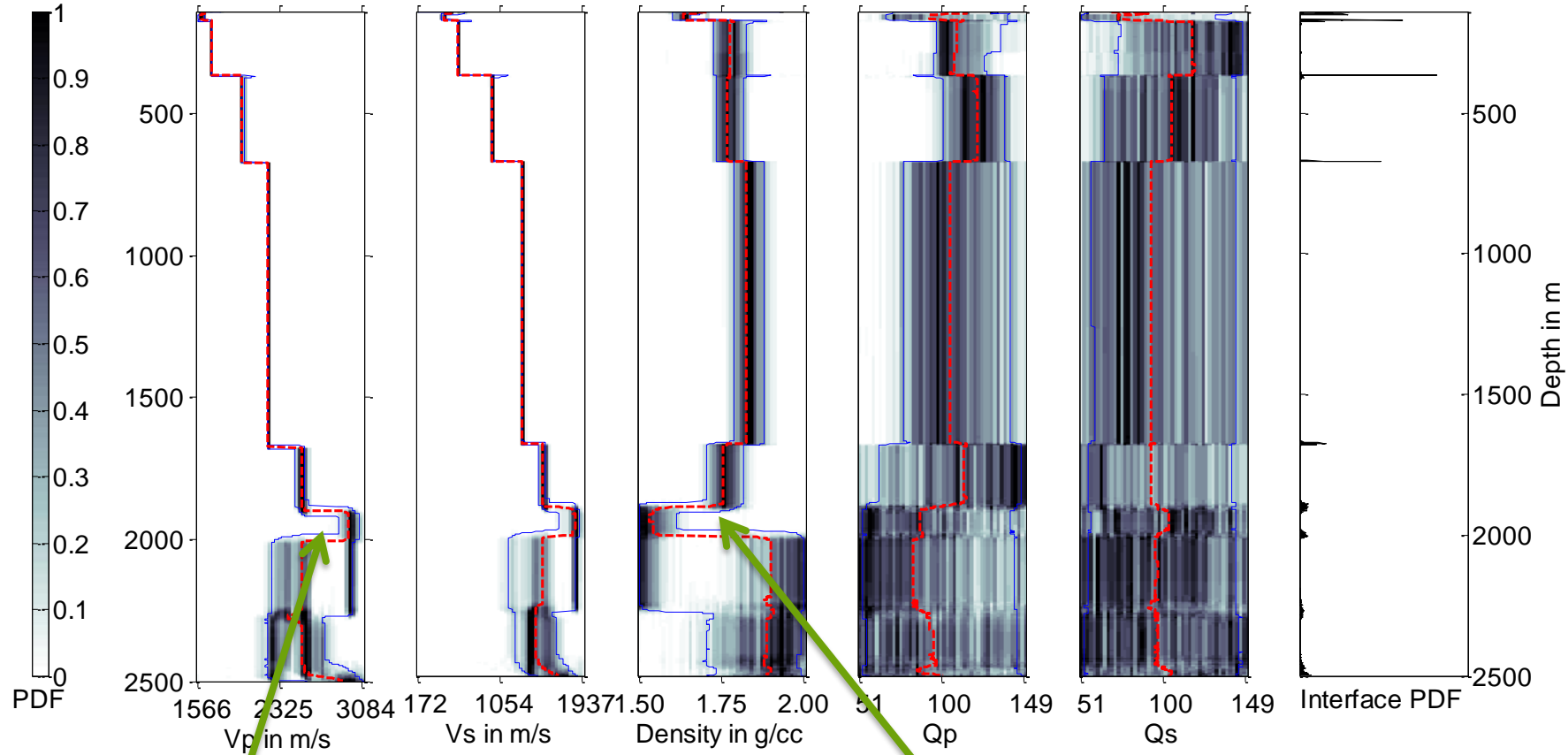
$$\mathbf{f}_l(\mathbf{m}) = \hat{S}_l(\mathbf{m}) \cdot \mathbf{G}_l(\mathbf{m}).$$

$$-\log \mathcal{L}(\mathbf{m}) = n_r \sum_{l=1}^{n_f} [\mathbf{d}_l - \mathbf{f}_l(\mathbf{m})]^\dagger [\mathbf{d}_l - \mathbf{f}_l(\mathbf{m})].$$

Bayesian posterior model PDFs (SYNTHETIC EXAMPLE)



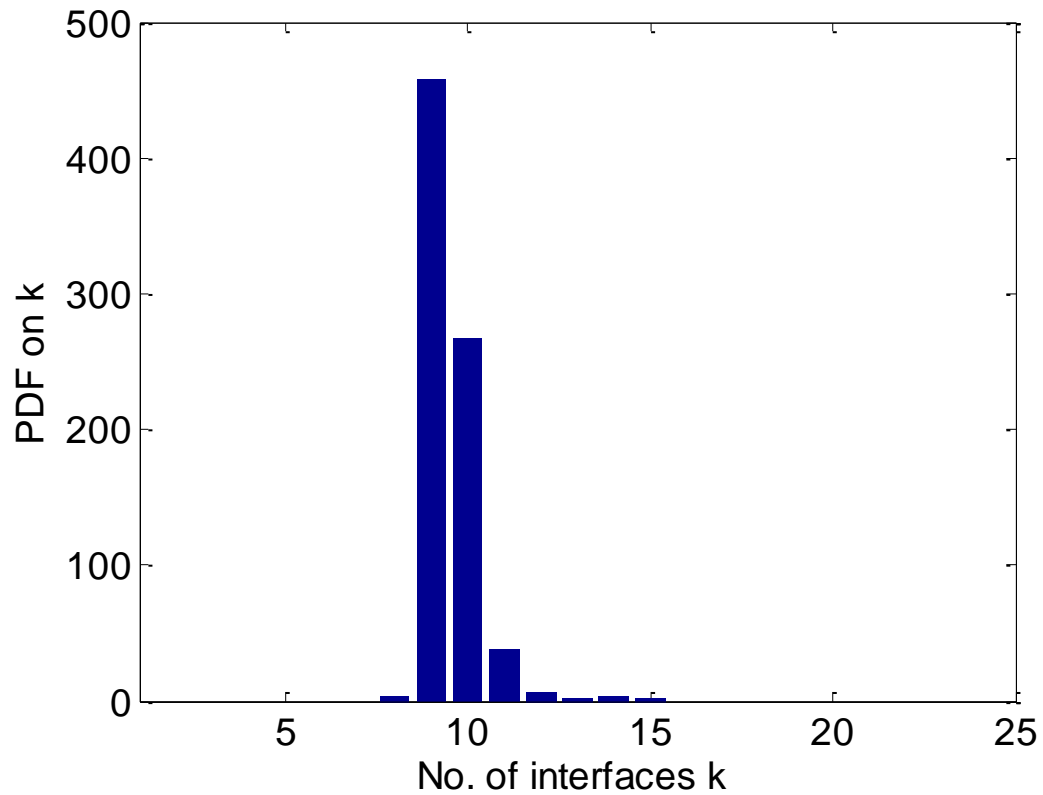
PDFs normalized at every depth (SYNTHETIC EXAMPLE)



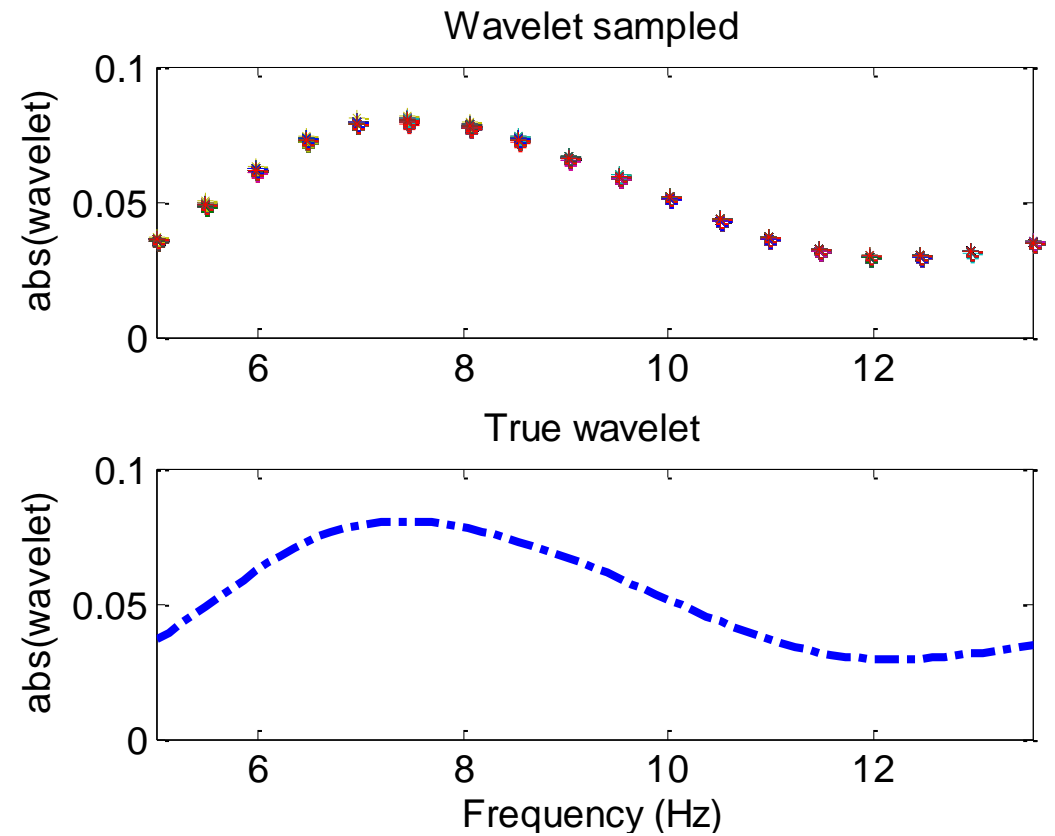
Vp PDFs cluster at high values

Rho PDFs cluster at low values

Posterior vs true wavelet (SYNTHETIC EXAMPLE)



$$\hat{S}_l(\mathbf{m}) = \frac{\mathbf{G}_l^\dagger(\mathbf{m})\mathbf{d}_l}{\mathbf{G}_l^\dagger(\mathbf{m})\mathbf{G}_l(\mathbf{m})},$$



Trans-dimensional (trans-D) Bayesian inversion






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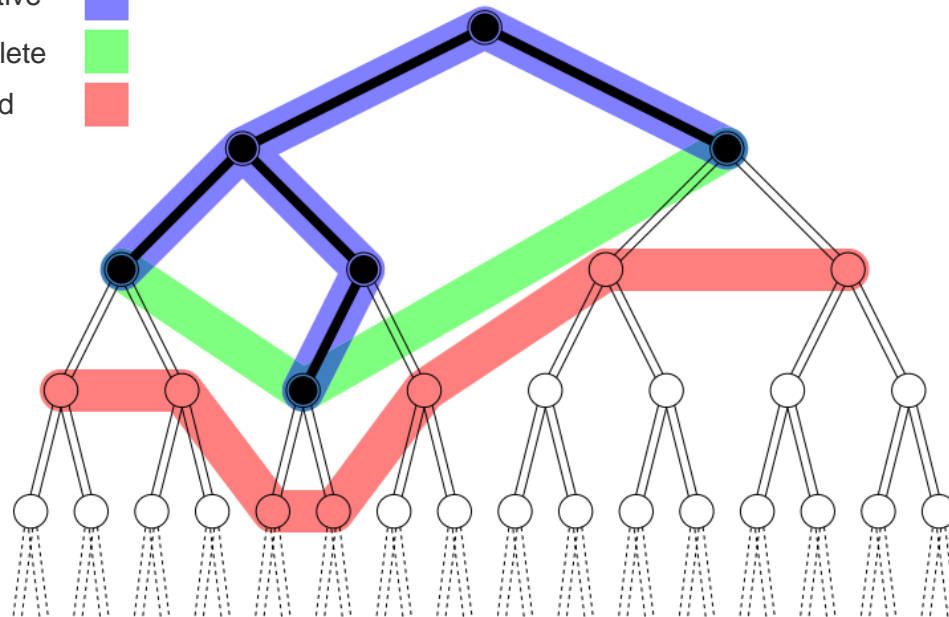
$$p(k|\mathbf{d}) \propto p(\mathbf{d}|\mathbf{m}_k, k) \cdot \left[f_1 \cdot f_2 \cdots f_k \right].$$

Feasible Trans-D beyond 1D



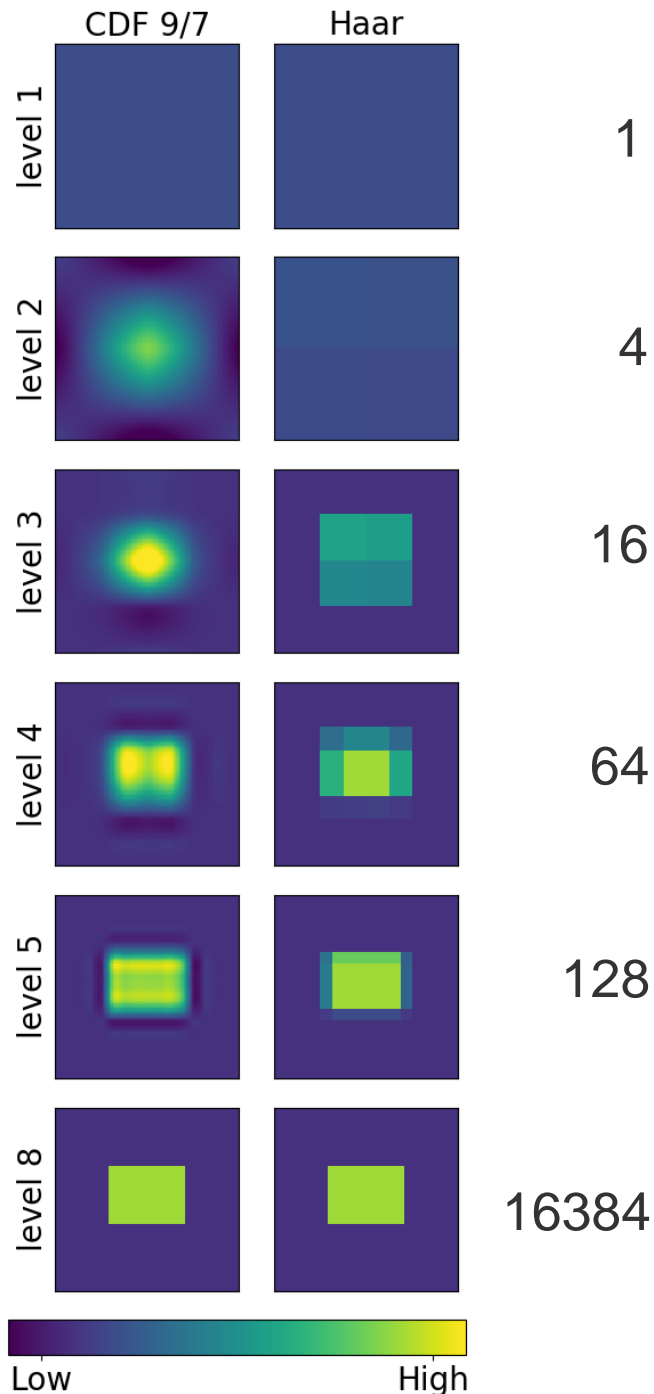
Ordinary McMC	Change model parameters while sampling
trans-D McMC	Add/delete parameters while sampling
tree based trans-D McMC	Do trans-D on wavelet transform trees

Active 
Delete 
Add 



Works for 1D, 2D or 3D

After *Hawkins and Sambridge (2015)*



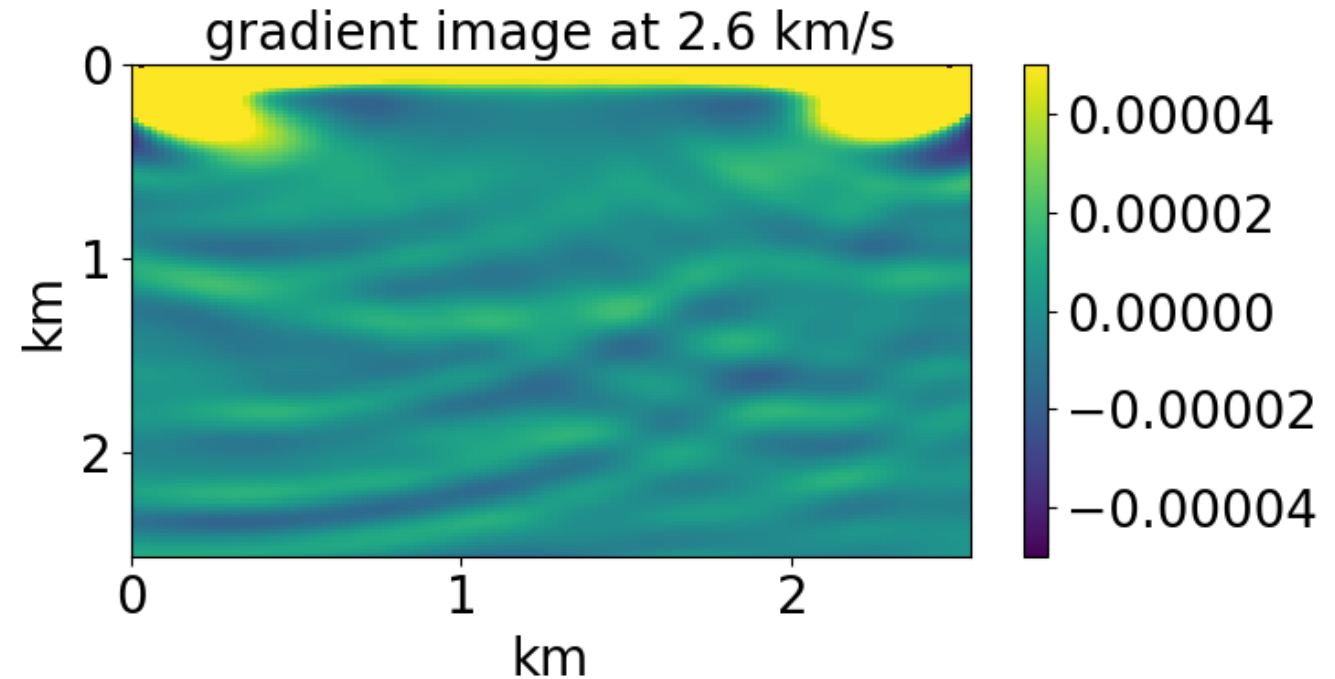
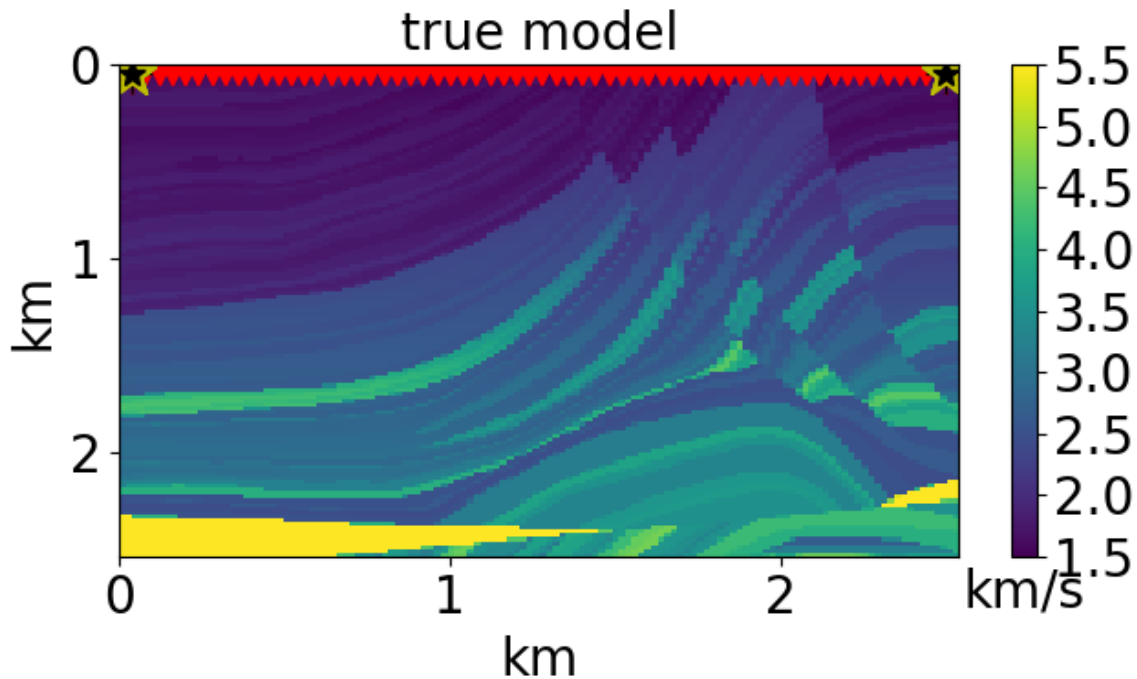
Required coefficients



As a sum of basis functions, this is how many coefficients we need for a given level of approximation.

Choice of basis is important!

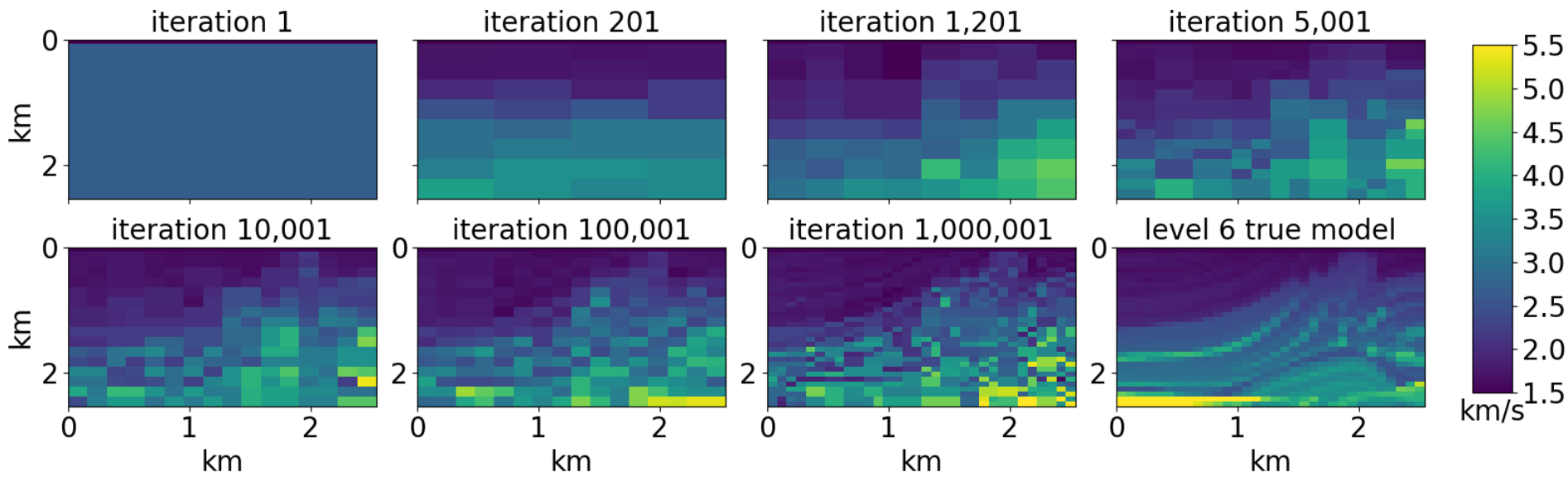
Gauss-Newton: Fails due to cycle skipping



G-N was not able to update with incorrect background velocity.

$$\phi(\mathbf{m}) = \frac{1}{2}[\mathbf{d} - \mathbf{f}(\mathbf{m})]^t[\mathbf{d} - \mathbf{f}(\mathbf{m})]$$
$$\nabla_{\mathbf{m}}\phi = \mathbf{J}^t[\mathbf{f}(\mathbf{m}) - \mathbf{d}]$$

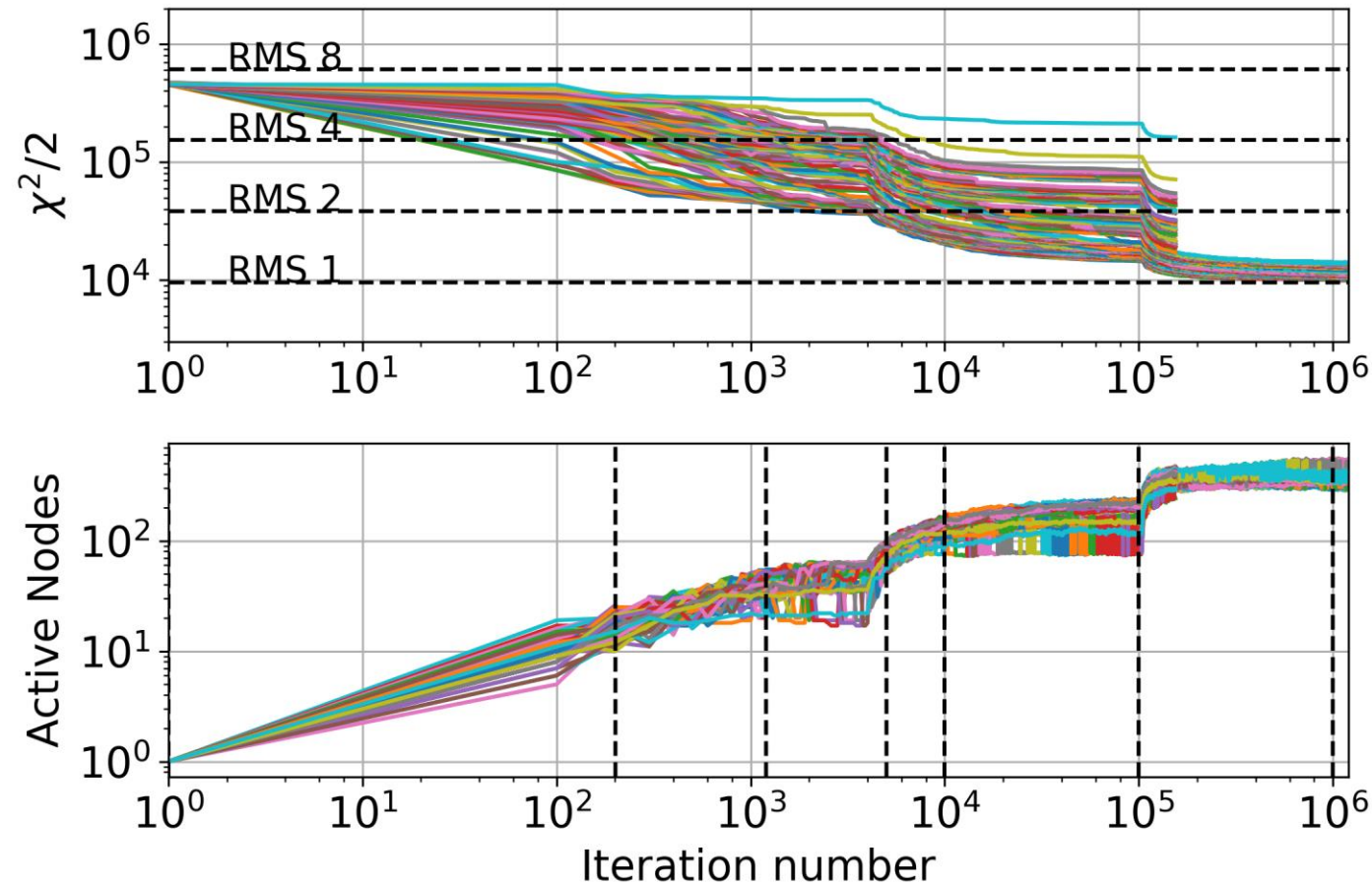
Trans-D sampling: On the other hand ...



Only **2 shots** were used for this inversion

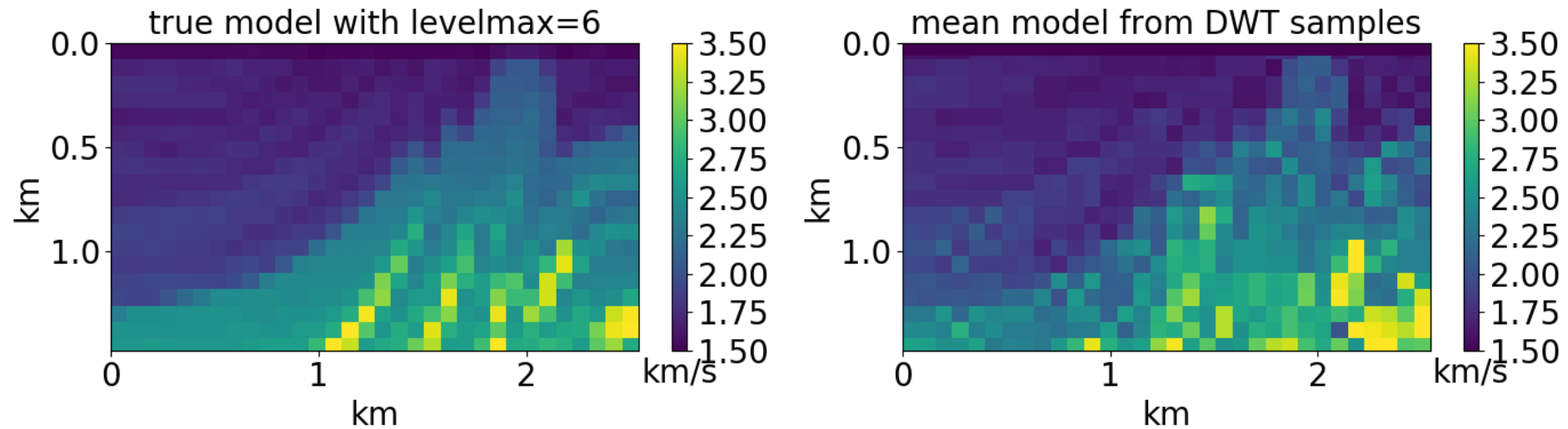
Background velocities are quickly recovered, with more detail appearing later

Trans-D sampling progress



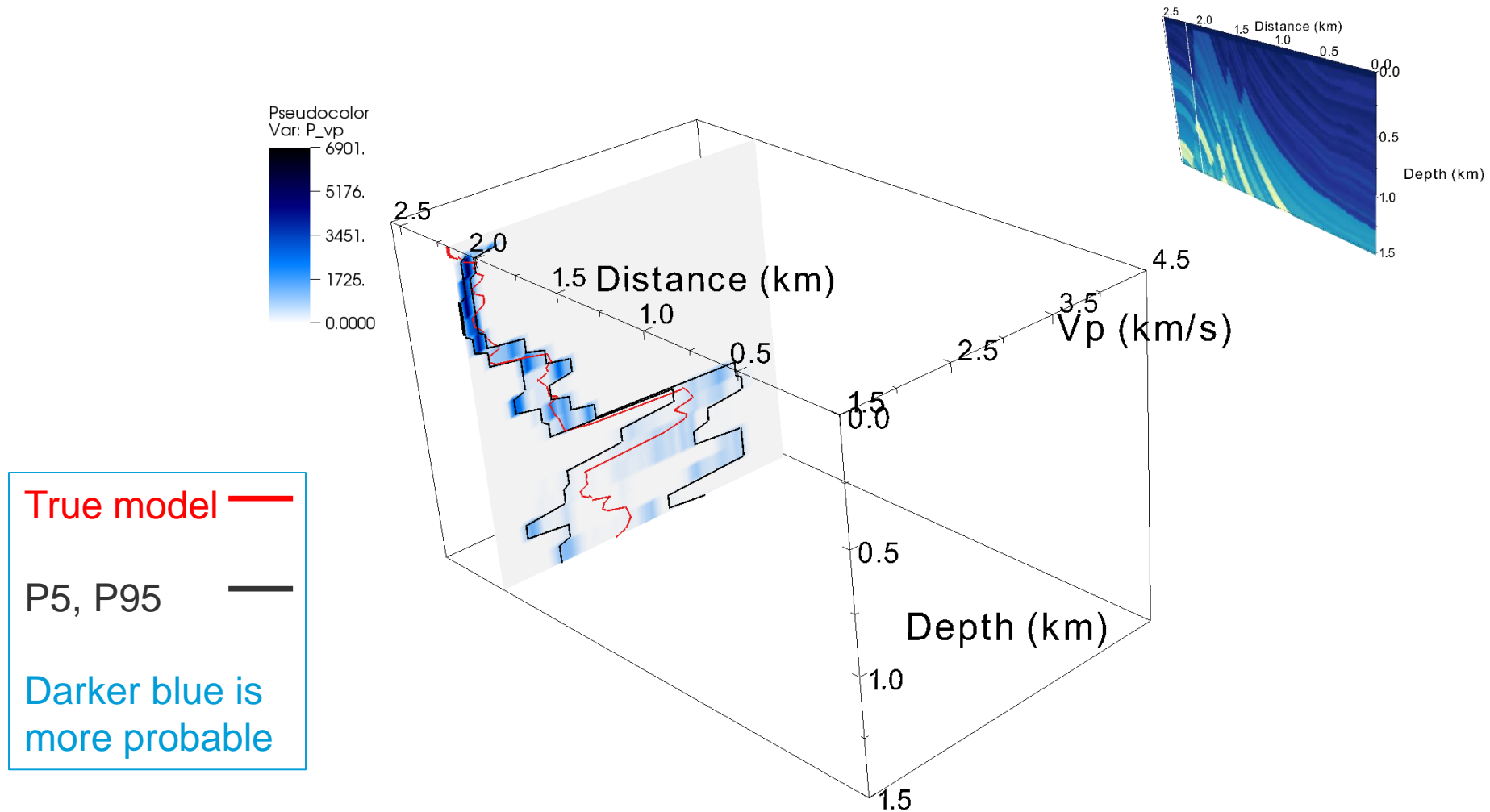
No more than 450 coefficients used

Level 6 DWT of true model and mean recovered model at same level

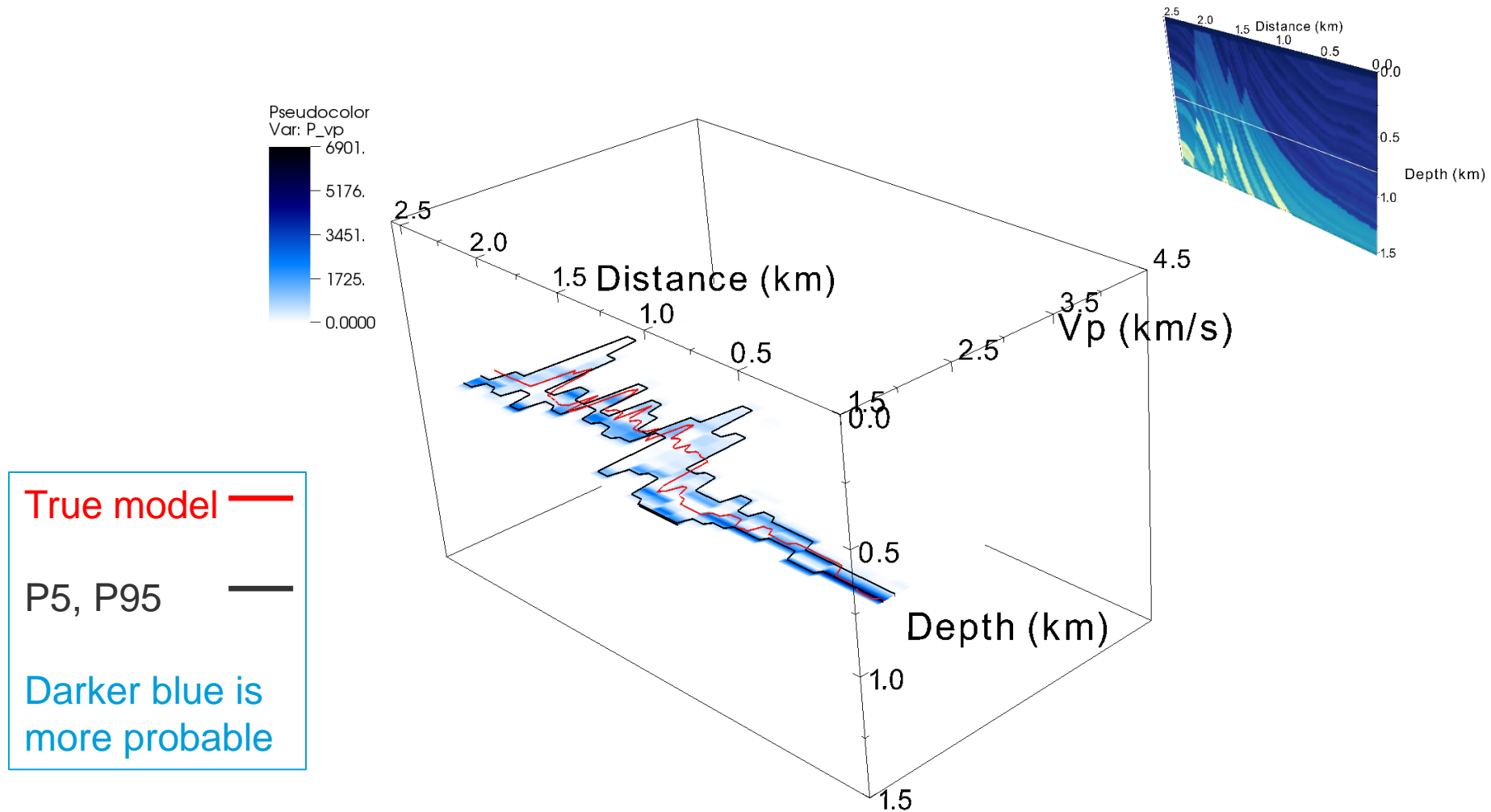


But why provide only a summary statistic - What if the uncertainties are multi-modal?

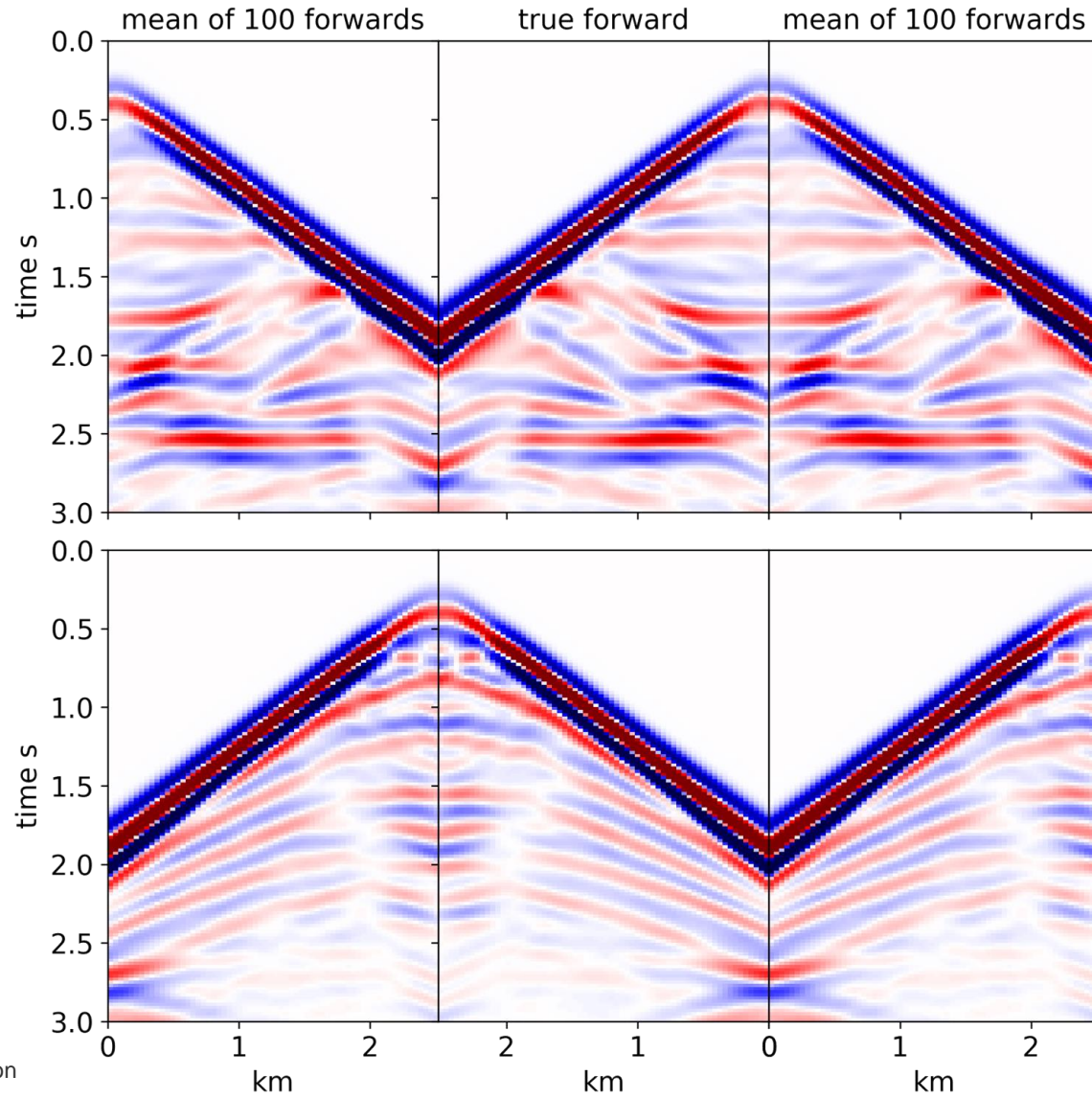
Uncertainty on inverted Vp



Uncertainty on inverted Vp



Data match for 2 shots



The AVO characteristics as well as kinematics for both shot gathers are well matched

This includes multiples, refractions as well as reflections!

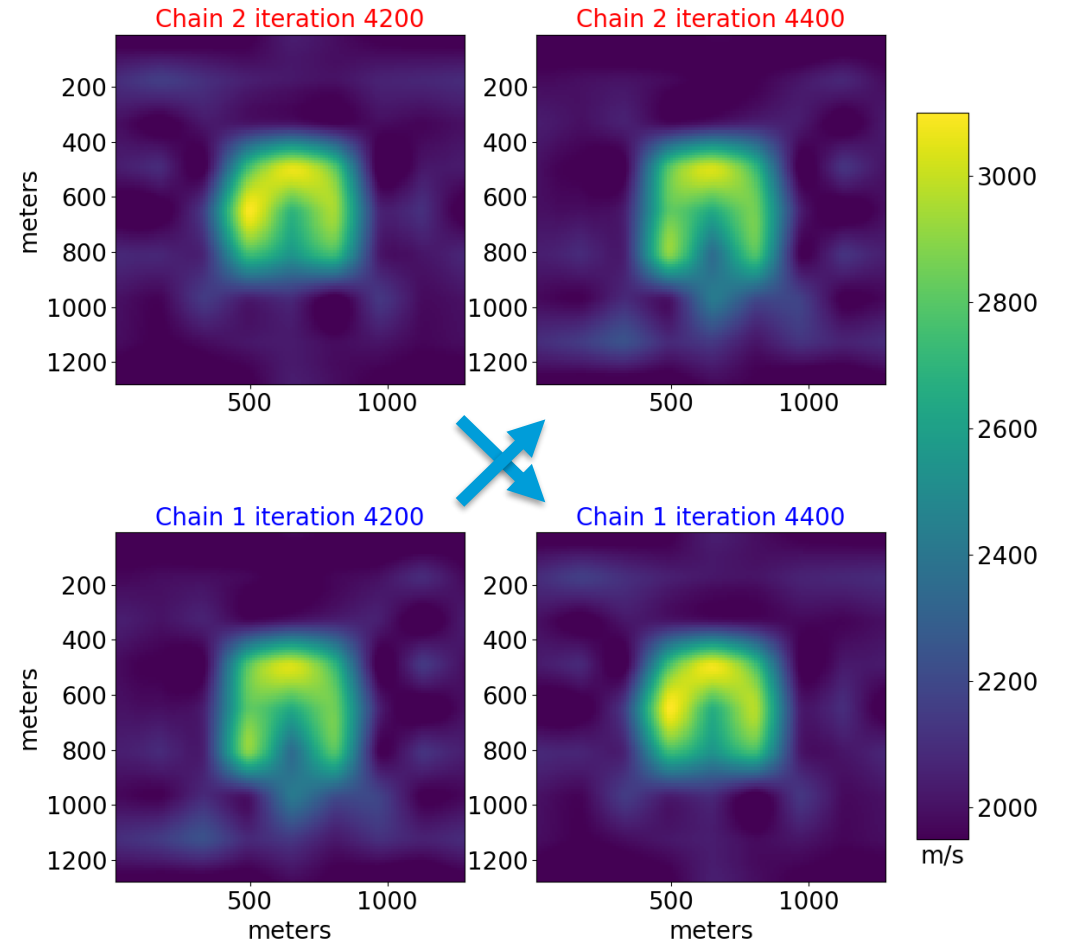
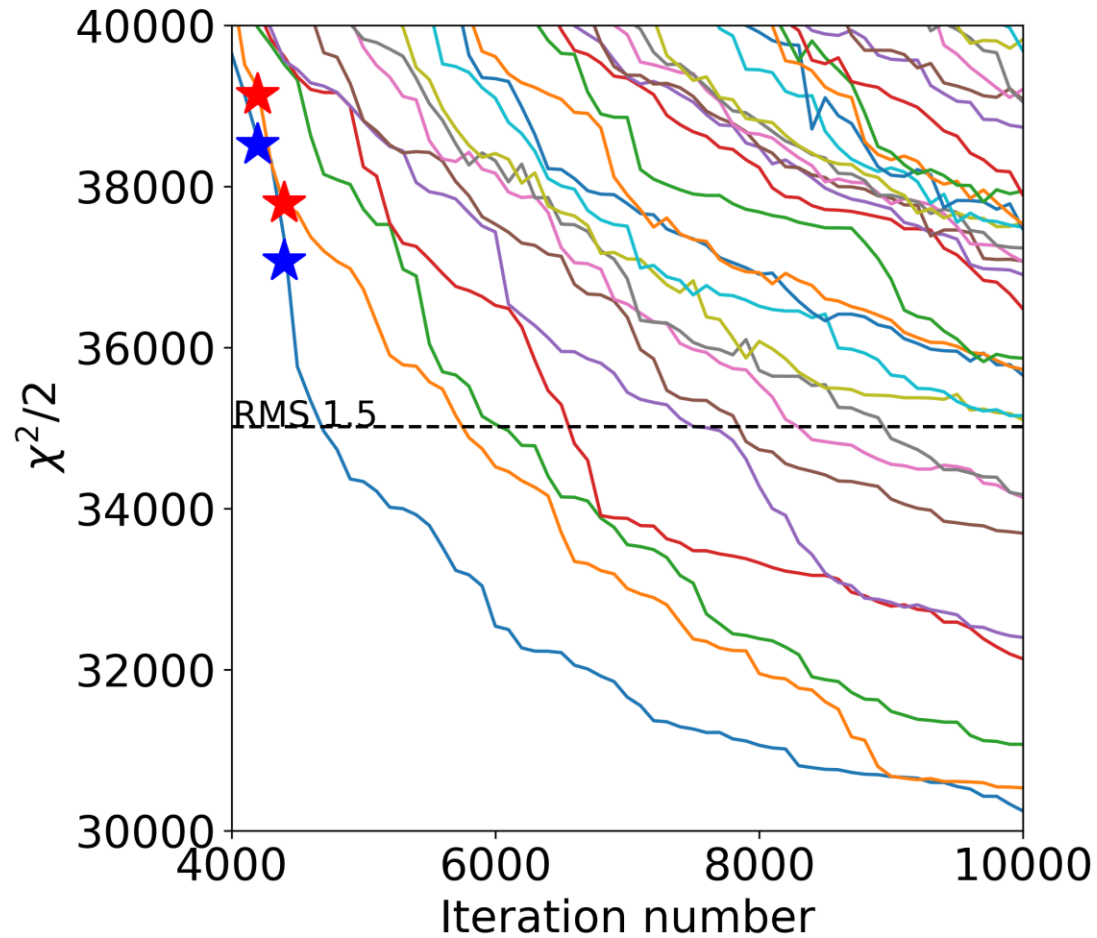
- Current **production methods** (AVA inversion) for elastic parameters have **large uncertainty**
 - May even be **Zoeppritz incompatible**
- **Standard** optimization methods (FWI) suffer from
 - Local minima problem (**cycle skips**)
 - Massive **crosstalk** problem (trade-offs)
- **Stochastic methods** can avoid these problems by
 - Dimension reduction, **Trans-D, Parallel Tempering**
- Key challenges
 - **Large number** of forwards, **cost** of forwards is very high
 - **can be addressed** using
 - **gradient** based sampling
 - using **optimized FD** engines
 - Modeling a **reduced basis** set directly
 - Using **less** shots

Backup

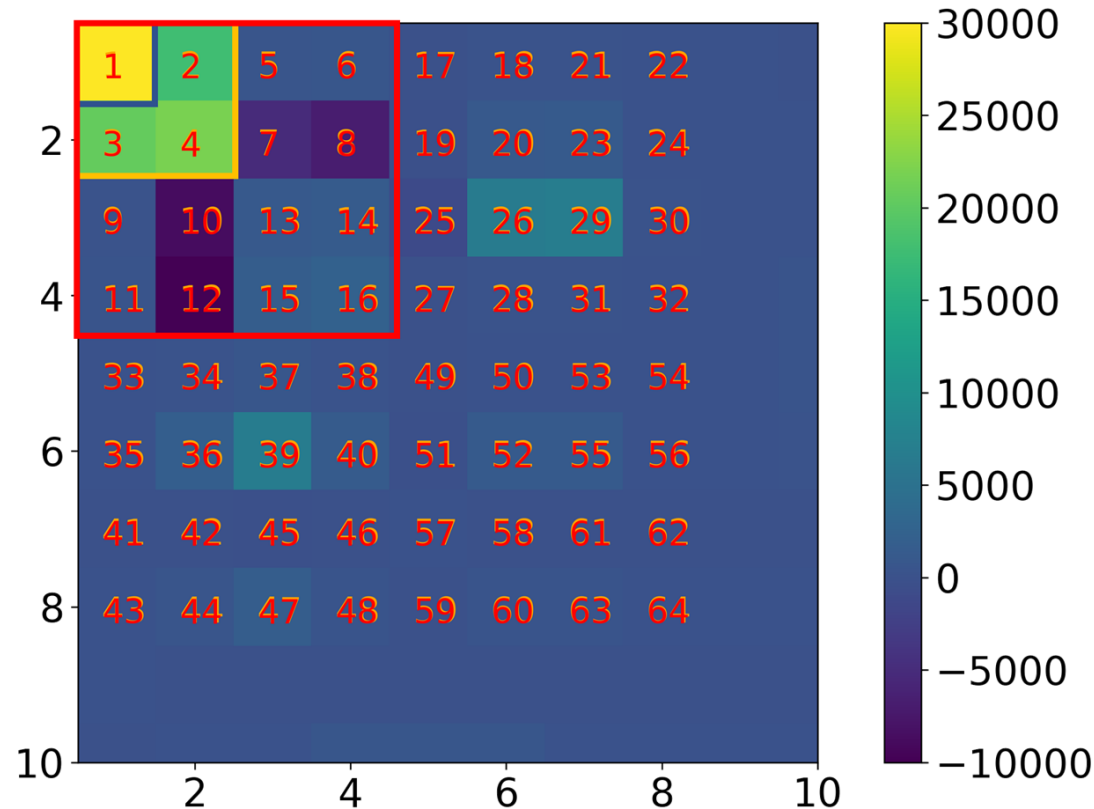
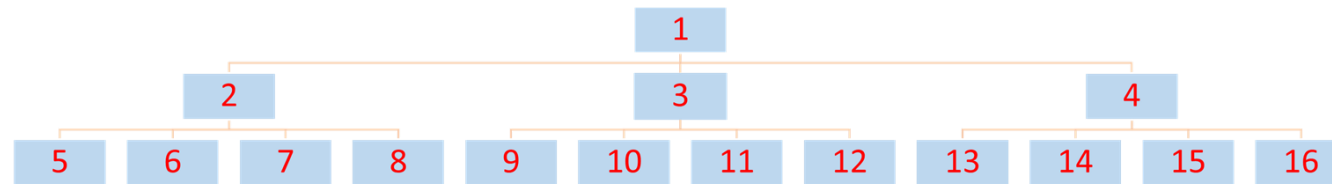


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Parallel tempering in action



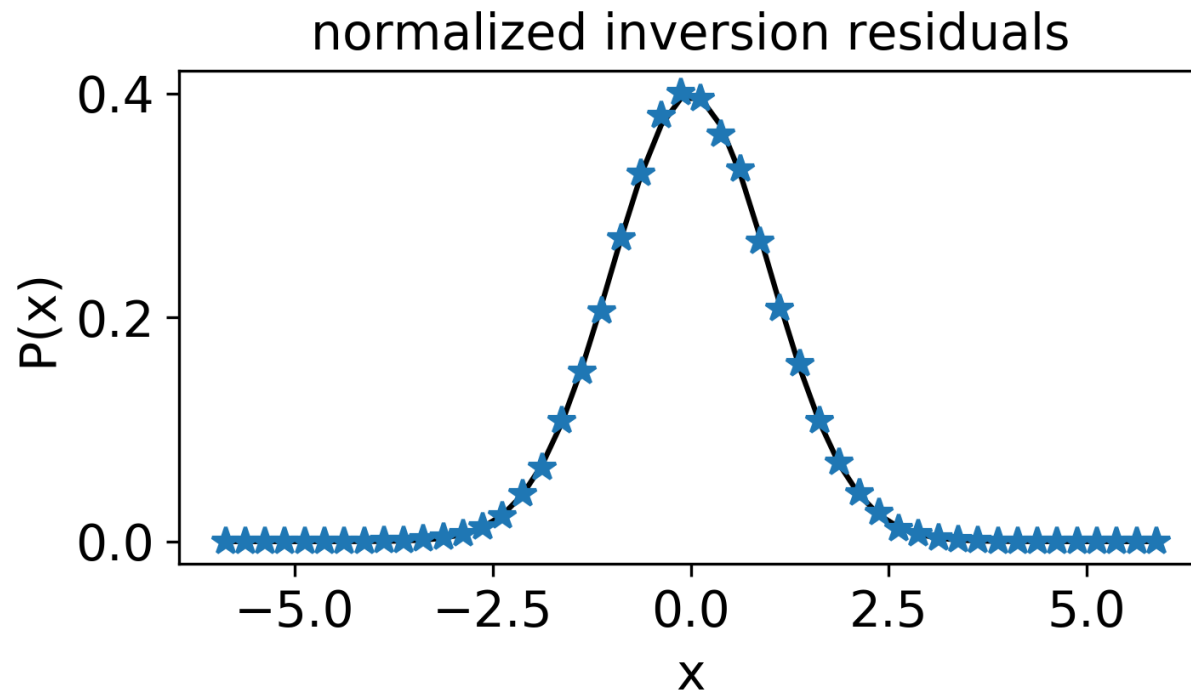
The discrete wavelet transform and its tree representation



Most elements are near zero!

Possibility of sparse representations

Histogram of residuals from 100 sampled models



Gaussian assumption is met