

Nontrivial Dynamics in the Forced Navier-Stokes Equations: A Computer-Assisted Proof

SIAM Conference on Applications of Dynamical Systems
Snowbird, UTAH
5.21.2017

Jean-Philippe Lessard



UNIVERSITÉ
LAVAL

Nontrivial Dynamics in the Forced Navier-Stokes Equations: A Computer-Assisted Proof

Joint work with



J.B. van den Berg
VU Amsterdam



Maxime Breden
ENS / U. Laval



Lennaert van Veen
UOIT

SIAM Conference on Applications of Dynamical Systems
Snowbird, UTAH
5.21.2017

Jean-Philippe Lessard



McGill

starting August 1st

Periodic orbits in the 3D Navier-Stokes equations

The incompressible Navier-Stokes equations on the 3D torus \mathbb{T}^3 are given by

$$\begin{cases} \partial_t u + (u \cdot \nabla)u - \nu \Delta u + \frac{1}{\rho} \nabla p = f, & \text{on } \mathbb{T}^3 \times \mathbb{R} \\ \nabla \cdot u = 0, & \text{on } \mathbb{T}^3 \times \mathbb{R}, \end{cases}$$

Periodic orbits in the 3D Navier-Stokes equations

The **incompressible Navier-Stokes equations** on the 3D torus \mathbb{T}^3 are given by

$$\begin{cases} \partial_t u + (u \cdot \nabla)u - \nu \Delta u + \frac{1}{\rho} \nabla p = f, & \text{on } \mathbb{T}^3 \times \mathbb{R} \\ \nabla \cdot u = 0, & \text{on } \mathbb{T}^3 \times \mathbb{R}, \end{cases}$$

where

- $u = u(x, t) = (u_1(x, t), u_2(x, t), u_3(x, t)) \in \mathbb{R}^3$ is the **velocity field**
- $p = p(x, t) \in \mathbb{R}$ is the **pressure**
- $x = (x_1, x_2, x_3) \in \mathbb{T}^3$ and $t \geq 0$
- ρ is the **density of the fluid** and ν is the **kinematic viscosity**
- $[(u \cdot \nabla)u]_k = u_1 \frac{\partial u_k}{\partial x_1} + u_2 \frac{\partial u_k}{\partial x_2} + u_3 \frac{\partial u_k}{\partial x_3}$, for $k = 1, 2, 3$
- $f = f(x, t)$ is the **external forcing term**.

Goal: prove the existence (constructively) of periodic orbits

Periodic orbits in the 3D Navier-Stokes equations

$$\begin{cases} \partial_t u + (u \cdot \nabla)u - \nu \Delta u + \frac{1}{\rho} \nabla p = f & \text{on } \mathbb{T}^3 \times \mathbb{R} \\ \nabla \cdot u = 0 & \text{on } \mathbb{T}^3 \times \mathbb{R} \end{cases}$$

Does not lead to a diagonal dominant derivative in Fourier space

→ We consider the vorticity equation

$$\nabla \left(\begin{cases} \partial_t u + (u \cdot \nabla)u - \nu \Delta u + \frac{1}{\rho} \nabla p = f & \text{on } \mathbb{T}^3 \times \mathbb{R} \\ \nabla \cdot u = 0 & \text{on } \mathbb{T}^3 \times \mathbb{R} \end{cases} \right)$$

Periodic orbits in the 3D Navier-Stokes equations

Let the vorticity $\omega \stackrel{\text{def}}{=} \nabla \times u$. Using $(u \cdot \nabla)u = \nabla \left(\frac{u^2}{2} \right) - u \times \omega$:

$$\begin{aligned} \nabla \times ((u \cdot \nabla)u) &= \nabla \times (\omega \times u) \\ &= (u \cdot \nabla)\omega - (\omega \cdot \nabla)u + \omega(\nabla \cdot u) - u(\nabla \cdot \omega), \end{aligned}$$

and since u and ω are divergence free :

$$\nabla \times ((u \cdot \nabla)u) = (u \cdot \nabla)\omega - (\omega \cdot \nabla)u.$$

Periodic orbits in the 3D Navier-Stokes equations

Let the vorticity $\omega \stackrel{\text{def}}{=} \nabla \times u$. Using $(u \cdot \nabla)u = \nabla \left(\frac{u^2}{2} \right) - u \times \omega$:

$$\begin{aligned} \nabla \times ((u \cdot \nabla)u) &= \nabla \times (\omega \times u) \\ &= (u \cdot \nabla)\omega - (\omega \cdot \nabla)u + \omega(\nabla \cdot u) - u(\nabla \cdot \omega), \end{aligned}$$

and since u and ω are divergence free :

$$\nabla \times ((u \cdot \nabla)u) = (u \cdot \nabla)\omega - (\omega \cdot \nabla)u.$$

The **vorticity equation** is then given by

$$\partial_t \omega + (u \cdot \nabla)\omega - (\omega \cdot \nabla)u - \nu \Delta \omega = g \quad \text{on } \mathbb{T}^3 \times \mathbb{R},$$

where $g \stackrel{\text{def}}{=} \nabla \times f$.

Periodic orbits in the 3D Navier-Stokes equations

$$\partial_t \omega + (u \cdot \nabla) \omega - (\omega \cdot \nabla) u - \nu \Delta \omega = g$$

still depends on the velocity

We express u in term of ω by solving

$$\begin{cases} \nabla \times u = \omega \\ \nabla \cdot u = 0. \end{cases}$$

Applying a curl to the first equation, and using that $\nabla \cdot u = 0$, we get

$$-\Delta u = \nabla \times \omega,$$

and so

$$u = -\Delta^{-1} \nabla \times \omega.$$

Periodic orbits in the vorticity equation

$$\partial_t \omega - \nu \Delta \omega - \left((\Delta^{-1} \nabla \times \omega) \cdot \nabla \right) \omega + (\omega \cdot \nabla) (\Delta^{-1} \nabla \times \omega) = g$$

diagonal dominant linear part in Fourier space

Periodic orbits in the vorticity equation

$$\partial_t \omega - \nu \Delta \omega - \left(((\Delta^{-1} \nabla \times \omega) \cdot \nabla) \omega + (\omega \cdot \nabla) (\Delta^{-1} \nabla \times \omega) \right) = g$$

nonlinear terms



Periodic orbits in the vorticity equation

$$\partial_t \omega - \nu \Delta \omega - \left((\Delta^{-1} \nabla \times \omega) \cdot \nabla \right) \omega + (\omega \cdot \nabla) (\Delta^{-1} \nabla \times \omega) = g$$

Describes the “dynamics” of the vorticity as time evolves

Periodic orbits in the vorticity equation

$$\partial_t \omega - \nu \Delta \omega - \left((\Delta^{-1} \nabla \times \omega) \cdot \nabla \right) \omega + (\omega \cdot \nabla) (\Delta^{-1} \nabla \times \omega) = g$$

Plugging the space-time expansion $\omega(x, t) = \sum_{n=(\tilde{n}, n_4) \in \mathbb{Z}^4} \omega_n e^{i(\tilde{n} \cdot x + n_4 \Omega t)}$ in the vorticity equation leads to $F(W) = (F_n(W))_{n \in \mathbb{Z}^4} = 0$, where

$$F_n(W) = \begin{cases} \omega_0, & n = 0 \\ (i\Omega n_4 + \nu \tilde{n}^2) \omega_n + i \left[M\omega \cdot (\tilde{D} \otimes \omega) \right]_n \\ \quad - i \left[\omega \cdot (\tilde{D} \otimes M\omega) \right]_n - g_n, & n \neq 0 \end{cases}$$

with $W \stackrel{\text{def}}{=} (\Omega, (\omega_n)_{n \in \mathbb{Z}^4})$, $M\omega = (M_n \omega_n)_{n \in \mathbb{Z}^4}$ and

leads to a diagonal dominant derivative

$$M_n \stackrel{\text{def}}{=} \begin{cases} i \begin{pmatrix} 0 & -n_3 & n_2 \\ n_3 & 0 & -n_1 \\ -n_2 & n_1 & 0 \end{pmatrix} & \tilde{n} \neq 0, \\ 0 & \tilde{n} = 0. \end{cases}$$

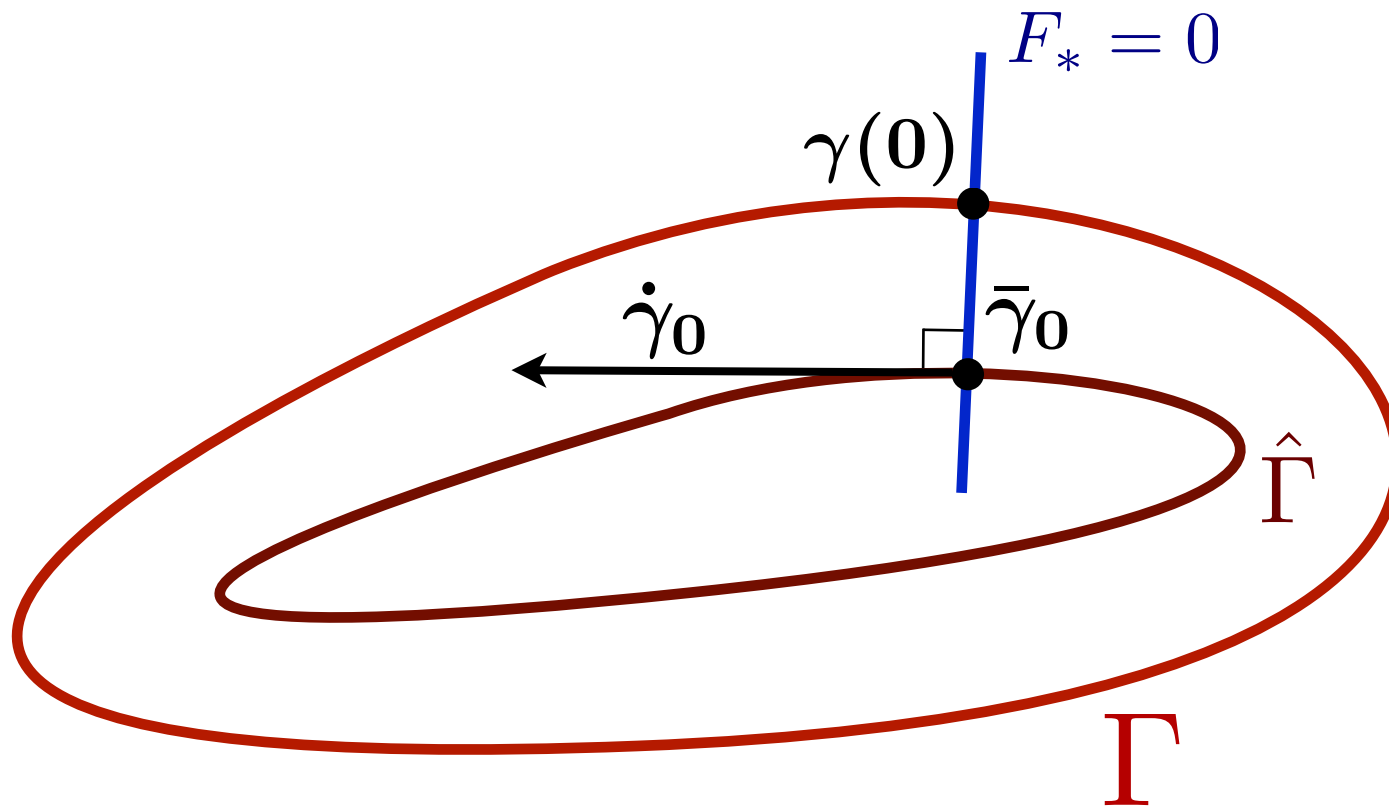
$$u = -\Delta^{-1} \nabla \times \omega$$

Periodic orbits in the vorticity equation

$$\partial_t \omega - \nu \Delta \omega - \left((\Delta^{-1} \nabla \times \omega) \cdot \nabla \right) \omega + (\omega \cdot \nabla) (\Delta^{-1} \nabla \times \omega) = g$$

The periodic orbits need to be isolated fixed points

To eliminate arbitrary time shift, we impose a *Poincaré phase condition*.

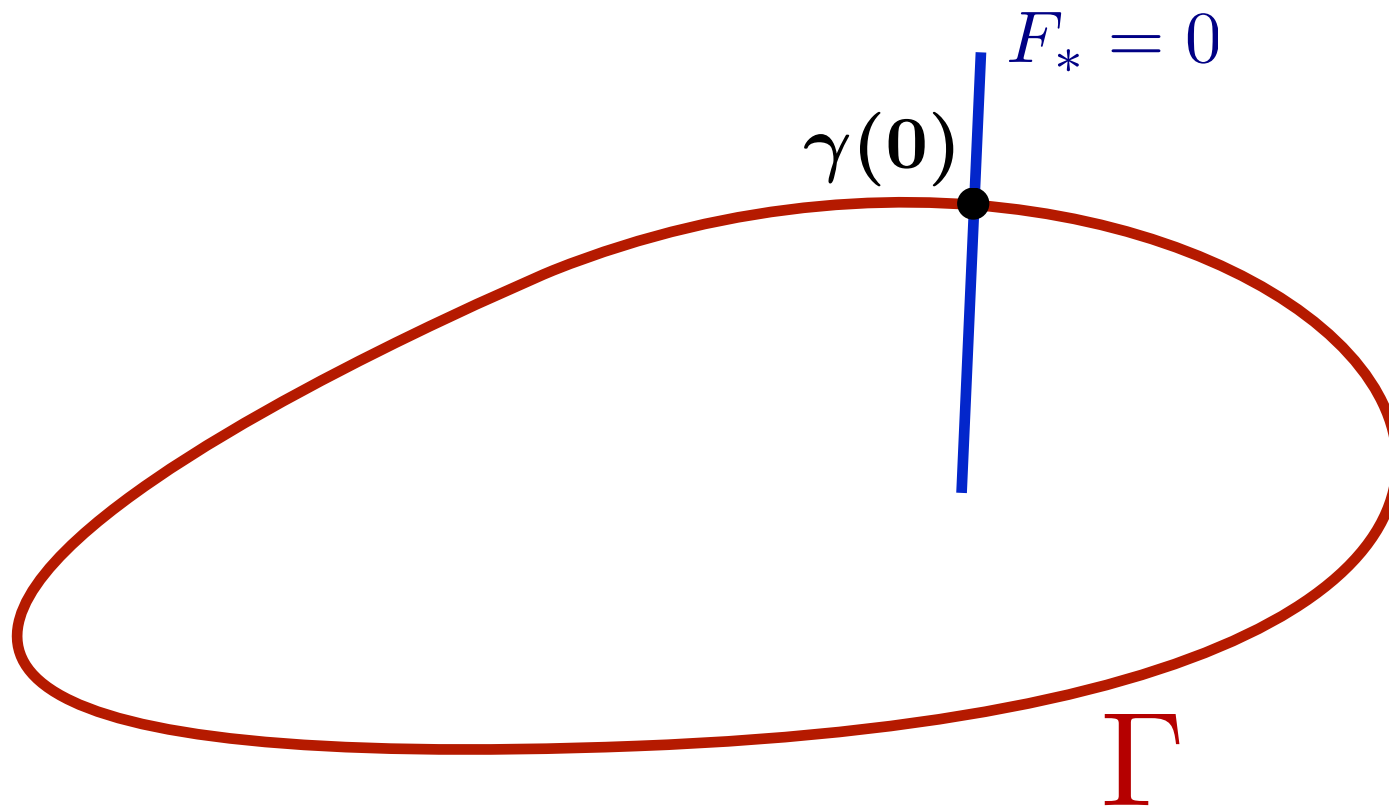


Periodic orbits in the vorticity equation

$$\partial_t \omega - \nu \Delta \omega - \left((\Delta^{-1} \nabla \times \omega) \cdot \nabla \right) \omega + (\omega \cdot \nabla) (\Delta^{-1} \nabla \times \omega) = g$$

The periodic orbits need to be isolated fixed points

To eliminate arbitrary time shift, we impose a *Poincaré phase condition*.



Periodic orbits in the vorticity equation

Looking for periodic orbits of the vorticity equation boils down to solve

$$\mathcal{F}(W) = \begin{pmatrix} F_*(W) \\ (F_n(W))_{n \in \mathbb{Z}^4} \end{pmatrix} = 0, \quad W \stackrel{\text{def}}{=} \begin{pmatrix} \Omega \\ (\omega_n)_{n \in \mathbb{Z}^4} \end{pmatrix}.$$

we solve using computer-assisted analysis

Lemma : Assume that the external forcing term f does not depend on time, that $\mathcal{F}(W) = 0$ and that $\nabla \cdot \omega = 0$. Let $u \stackrel{\text{def}}{=} M\omega$. Then there exists a pressure term p such that (u, p) is a $\frac{2\pi}{\Omega}$ -periodic solution of the forced incompressible Navier-Stokes equations on the 3D torus \mathbb{T}^3

$$\begin{cases} \partial_t u + (u \cdot \nabla)u - \nu \Delta u + \frac{1}{\rho} \nabla p = f, & \text{on } \mathbb{T}^3 \times \mathbb{R} \\ \nabla \cdot u = 0, & \text{on } \mathbb{T}^3 \times \mathbb{R}. \end{cases}$$

A general nonlinear problem

$$\mathcal{F}(x) = 0$$

to solve in a Banach space

X

● x_1

● x_3

● x_2

● x_4

● x_6

● x_5

● x_7

Most of the time impossible to compute exactly !

A general nonlinear problem

$$\mathcal{F}(x) = 0$$

to solve in a Banach space

X

Alternative: find small balls in which it is demonstrated (in a mathematically rigorous sense) that a unique solution exists.

How to find these small isolating balls ?

- I. Let \bar{x} a numerical approximation of $\mathcal{F}(x) = 0$ in X computed using a finite dimensional reduction.

How to find these small isolating balls ?

1. Let \bar{x} a numerical approximation of $\mathcal{F}(x) = 0$ in X computed using a finite dimensional reduction.
2. Construct with the help of the computer a linear operator A that is an approximate inverse of $D\mathcal{F}(\bar{x})$.

How to find these small isolating balls ?

1. Let \bar{x} a numerical approximation of $\mathcal{F}(x) = 0$ in X computed using a finite dimensional reduction.
2. Construct with the help of the computer a linear operator A that is an approximate inverse of $D\mathcal{F}(\bar{x})$.
3. Verify that A is an injective linear operator.

How to find these small isolating balls ?

1. Let \bar{x} a numerical approximation of $\mathcal{F}(x) = 0$ in X computed using a finite dimensional reduction.
2. Construct with the help of the computer a linear operator A that is an approximate inverse of $D\mathcal{F}(\bar{x})$.
3. Verify that A is an injective linear operator.
4. Define $T(x) = x - A\mathcal{F}(x)$ a Newton-like operator about the numerical approximation \bar{x} .

How to find these small isolating balls ?

1. Let \bar{x} a numerical approximation of $\mathcal{F}(x) = 0$ in X computed using a finite dimensional reduction.
2. Construct with the help of the computer a linear operator A that is an approximate inverse of $D\mathcal{F}(\bar{x})$.
3. Verify that A is an injective linear operator.
4. Define $T(x) = x - A\mathcal{F}(x)$ a Newton-like operator about the numerical approximation \bar{x} .
5. Consider $B_{\bar{x}}(r) \subset X$ the closed ball of radius r centered at \bar{x} .

How to find these small isolating balls ?

1. Let \bar{x} a numerical approximation of $\mathcal{F}(x) = 0$ in X computed using a finite dimensional reduction.
2. Construct with the help of the computer a linear operator A that is an approximate inverse of $D\mathcal{F}(\bar{x})$.
3. Verify that A is an injective linear operator.
4. Define $T(x) = x - A\mathcal{F}(x)$ a Newton-like operator about the numerical approximation \bar{x} .
5. Consider $B_{\bar{x}}(r) \subset X$ the closed ball of radius r centered at \bar{x} .
6. Find $r > 0$ such that $T : B_{\bar{x}}(r) \rightarrow B_{\bar{x}}(r)$ is a contraction mapping (tool : **radii polynomials**).

A Newton-Kantorovich type argument

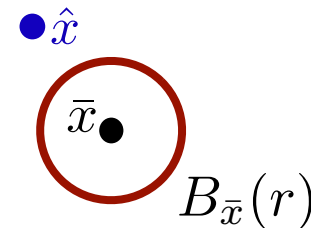
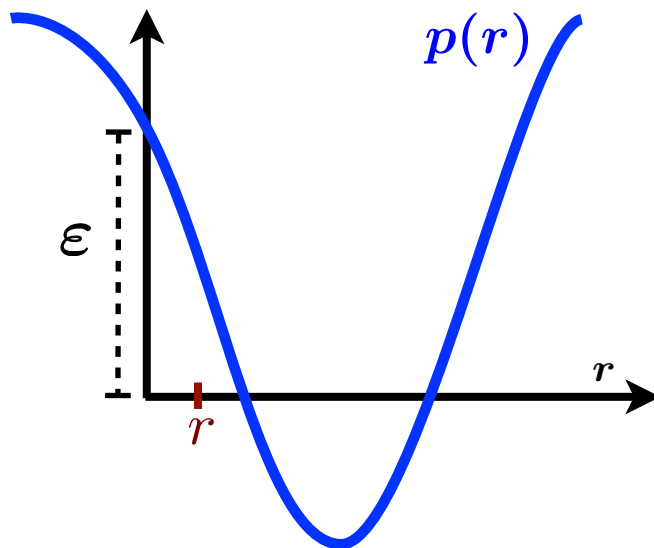
Theorem : Let $T : X \rightarrow X$ defined by $T(x) = x - A\mathcal{F}(x)$ with $T \in C^1(X)$. Let $r > 0$ and consider bounds ε and $\kappa = \kappa(r)$ satisfying

$$\begin{aligned} \|T(\bar{x}) - \bar{x}\|_X &= \|A\mathcal{F}(\bar{x})\|_X \leq \varepsilon \\ \sup_{w \in B_{\bar{x}}(r)} \|DT(w)\|_X &= \sup_{w \in B_{\bar{x}}(r)} \|I - A \cdot D\mathcal{F}(w)\|_X \leq \kappa(r). \end{aligned}$$

If

$$p(r) \stackrel{\text{def}}{=} \varepsilon + r\kappa(r) - r < 0 \quad \textbf{(radii polynomial)}$$

then $T : B_{\bar{x}}(r) \rightarrow B_{\bar{x}}(r)$ is a contraction with Lipschitz constant $\kappa(r) < 1$. Moreover A is injective and therefore $\mathcal{F} = 0$ has a unique solution in $B_{\bar{x}}(r)$.



A Newton-Kantorovich type argument

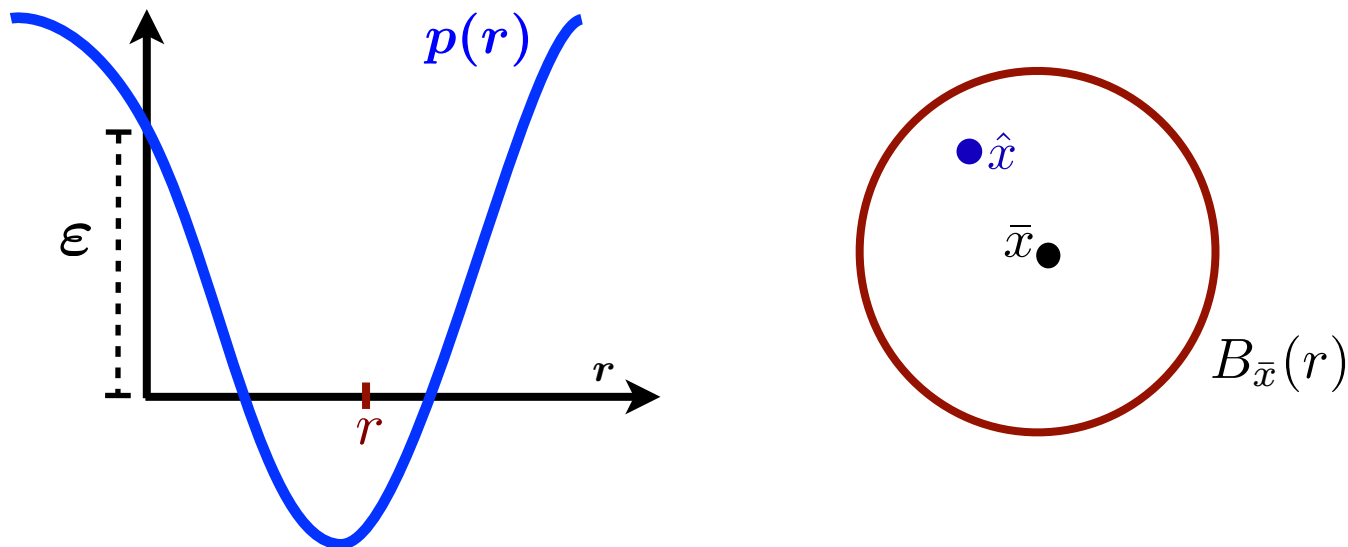
Theorem : Let $T : X \rightarrow X$ defined by $T(x) = x - A\mathcal{F}(x)$ with $T \in C^1(X)$. Let $r > 0$ and consider bounds ε and $\kappa = \kappa(r)$ satisfying

$$\begin{aligned} \|T(\bar{x}) - \bar{x}\|_X &= \|A\mathcal{F}(\bar{x})\|_X \leq \varepsilon \\ \sup_{w \in B_{\bar{x}}(r)} \|DT(w)\|_X &= \sup_{w \in B_{\bar{x}}(r)} \|I - A \cdot D\mathcal{F}(w)\|_X \leq \kappa(r). \end{aligned}$$

If

$$p(r) \stackrel{\text{def}}{=} \varepsilon + r\kappa(r) - r < 0 \quad \textbf{(radii polynomial)}$$

then $T : B_{\bar{x}}(r) \rightarrow B_{\bar{x}}(r)$ is a contraction with Lipschitz constant $\kappa(r) < 1$. Moreover A is injective and therefore $\mathcal{F} = 0$ has a unique solution in $B_{\bar{x}}(r)$.



Periodic orbits in the vorticity equation

We consider the Banach space $\mathcal{X}_\eta = \mathbb{C} \times (\ell_\eta^1(\mathbb{C}))^3$ with the norm

$$\|W\|_{\mathcal{X}_\eta} = \max \left(|\Omega|, \max_{1 \leq l \leq 3} \|\omega^{(l)}\|_{\ell_\eta^1} \right),$$

where for a complex valued sequence $a \in \mathbb{C}^{\mathbb{Z}^4}$,

$$\|a\|_{\ell_\eta^1} = \sum_{n \in \mathbb{Z}^4} |a_n| \eta^{|n|_1}.$$

Periodic orbits in the vorticity equation

We consider the Banach space $\mathcal{X}_\eta = \mathbb{C} \times (\ell_\eta^1(\mathbb{C}))^3$ with the norm

$$\|W\|_{\mathcal{X}_\eta} = \max \left(|\Omega|, \max_{1 \leq l \leq 3} \|\omega^{(l)}\|_{\ell_\eta^1} \right),$$

where for a complex valued sequence $a \in \mathbb{C}^{\mathbb{Z}^4}$,

$$\|a\|_{\ell_\eta^1} = \sum_{n \in \mathbb{Z}^4} |a_n| \eta^{|n|_1}.$$

We solve the problem $\mathcal{F}(W) = 0$ in the subspace of \mathcal{X}_η of divergence free sequences

$$\mathcal{X}_\eta^{div} \stackrel{\text{def}}{=} \{W \in \mathcal{X}_\eta, \nabla \cdot \omega = 0\}.$$

The approximate inverse A

$$D\mathcal{F}(\bar{W}) = \left[\begin{array}{c|c} D\mathcal{F}^{(m)}(\bar{W}) + \mathcal{E} & * \nearrow 0 \\ \hline * \searrow 0 & \begin{array}{c} \mu_n \\ * \nearrow 0 \\ * \searrow 0 \end{array} \end{array} \right]$$

≈ 0

$$\mathcal{F}_n(W) = \mu_n \omega_n + i \left[M\omega \cdot \left(\tilde{D} \otimes \omega \right) \right]_n - i \left[\omega \cdot \left(\tilde{D} \otimes M\omega \right) \right]_n - g_n, \quad \mu_n \stackrel{\text{def}}{=} i\Omega n_4 + \nu \tilde{n}^2$$

The approximate inverse A

$$D\mathcal{F}(\bar{W}) \approx \left[\begin{array}{c|c} D\mathcal{F}^{(m)}(\bar{W}) & 0 \\ \hline 0 & \begin{array}{c} \mu_n \\ \text{---} \\ 0 \end{array} \end{array} \right]$$

$$\mathcal{F}_n(W) = \mu_n \omega_n + i \left[M\omega \cdot \left(\tilde{D} \otimes \omega \right) \right]_n - i \left[\omega \cdot \left(\tilde{D} \otimes M\omega \right) \right]_n - g_n, \quad \mu_n \stackrel{\text{def}}{=} i\Omega n_4 + \nu \tilde{n}^2$$

The approximate inverse A

$$D\mathcal{F}(\bar{W})^{-1} \approx \begin{bmatrix} A_m & 0 \\ 0 & \begin{array}{c} \mu_n^{-1} \\ 0 \end{array} \end{bmatrix}$$

$$A_m \approx D\mathcal{F}^{(m)}(\bar{W})^{-1}$$

(Computer-assisted computation)

$$\mu_n \stackrel{\text{def}}{=} i\Omega n_4 + \nu \tilde{n}^2$$

The approximate inverse A

$$A \stackrel{\text{def}}{=} \begin{bmatrix} A_m & 0 \\ 0 & \begin{array}{c} \mu_n^{-1} \\ 0 \end{array} \end{bmatrix}$$

$$A_m \approx D\mathcal{F}^{(m)}(\bar{W})^{-1}$$

(Computer-assisted computation)

$$\mu_n \stackrel{\text{def}}{=} i\Omega n_4 + \nu \tilde{n}^2$$

The approximate inverse A

$$A \stackrel{\text{def}}{=} \begin{bmatrix} A_m & 0 \\ 0 & \begin{array}{c} \mu_n^{-1} \\ 0 \end{array} \end{bmatrix}$$

Final step : prove that $T(W) = W - A\mathcal{F}(W)$ is a contraction on $B_r(\bar{W})$.

Using the symmetries to reduce the dimension

The equation

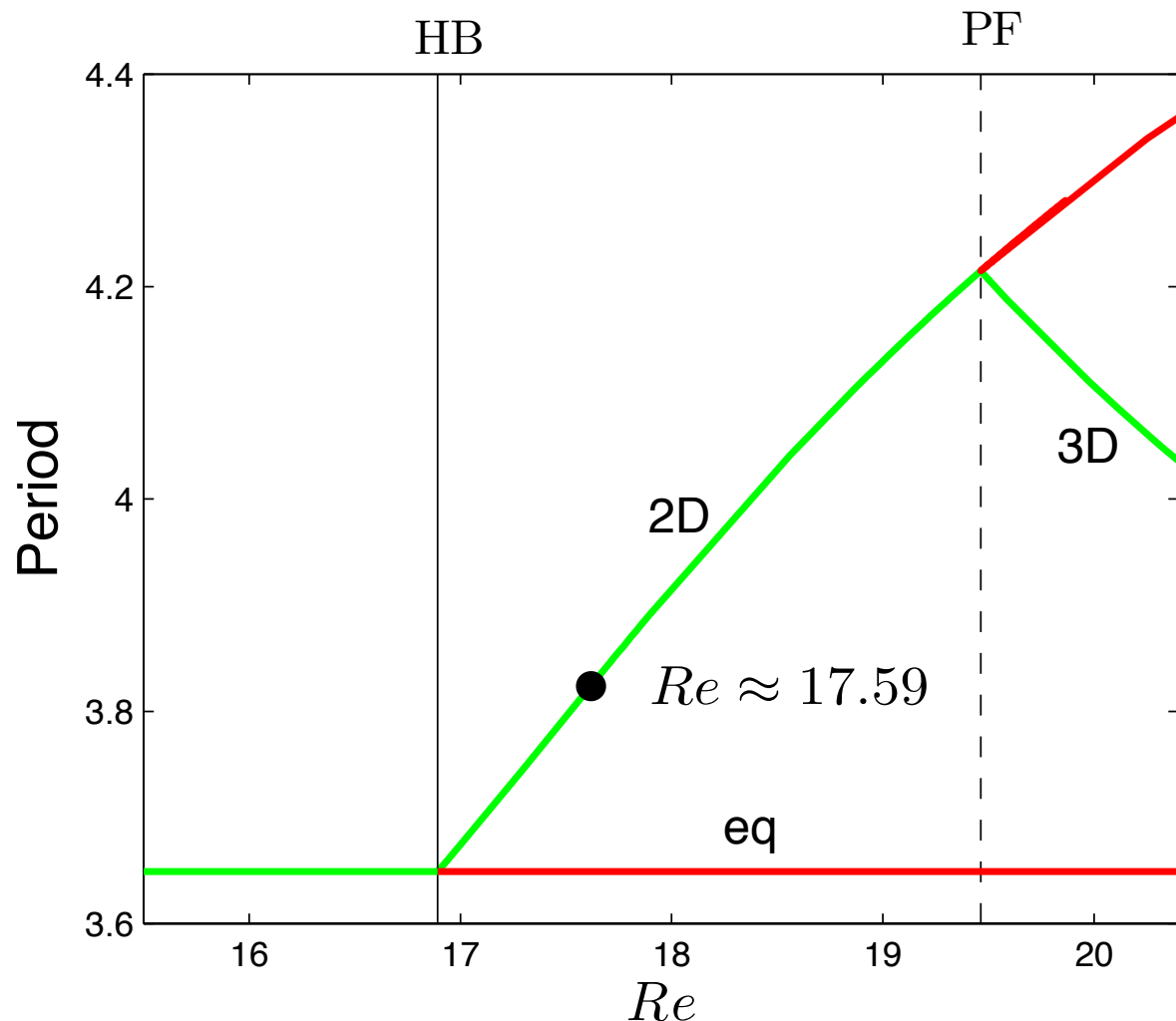
$$F_n(W) = \begin{cases} \omega_0, & n = 0 \\ (i\Omega n_4 + \nu \tilde{n}^2)\omega_n + i \left[M\omega \cdot \left(\tilde{D} \otimes \omega \right) \right]_n \\ \quad - i \left[\omega \cdot \left(\tilde{D} \otimes M\omega \right) \right]_n - g_n, & n \neq 0 \end{cases}$$

has a rather large group of symmetries, generated by the following elements.

- Reflection in the x -direction : $S_x(\omega_n) = \left(\omega_{(-n_x, n_y, n_z)}^{(x)}, -\omega_{(-n_x, n_y, n_z)}^{(y)}, -\omega_{(-n_x, n_y, n_z)}^{(z)} \right)$.
- Reflection in the y -direction : $S_y(\omega_n) = \left(-\omega_{(n_x, -n_y, n_z)}^{(x)}, \omega_{(n_x, -n_y, n_z)}^{(y)}, -\omega_{(n_x, -n_y, n_z)}^{(z)} \right)$.
- Reflection in the z -direction : $S_z(\omega_n) = \left(-\omega_{(n_x, n_y, -n_z)}^{(x)}, -\omega_{(n_x, n_y, -n_z)}^{(y)}, \omega_{(n_x, n_y, -n_z)}^{(z)} \right)$.
- Translation over $d = \frac{2\pi}{l}$ in the vertical direction : $T_l(\omega_n) = \left(e^{\frac{2i\pi}{l}} \right)^{n_z} \omega_n$.
- Translation over $s = \frac{\tau}{l}$ in time (where τ is the period) : $P_l(\omega_n) = \left(e^{\frac{2i\pi}{l}} \right)^{n_t} \omega_n$.
- A shift over π in both the x and y directions $D(\omega_n) = (-1)^{n_x + n_y} \omega_n$.
- Rotation about the axis $x = y = 0$ over $\pi/2$ followed by a shift over π in the x -direction : $R(\omega_n) = (-1)^{n_y} \left(-\omega_{(-n_y, n_x, n_z)}^{(y)}, \omega_{(-n_y, n_x, n_z)}^{(x)}, \omega_{(-n_y, n_x, n_z)}^{(z)} \right)$.

Result: a 2D periodic orbit in the Navier-Stokes equations

$$\begin{cases} \partial_t u + (u \cdot \nabla)u - \nu \Delta u + \frac{1}{\rho} \nabla p = f & \text{on } \mathbb{T}^3 \times \mathbb{R} \\ \nabla \cdot u = 0 & \text{on } \mathbb{T}^3 \times \mathbb{R} \end{cases}$$



$$f(x_1, x_2, x_3) = \begin{pmatrix} -\sin(x_1) \cos(x_2)/2 \\ \cos(x_1) \sin(x_2)/2 \\ 0 \end{pmatrix}$$

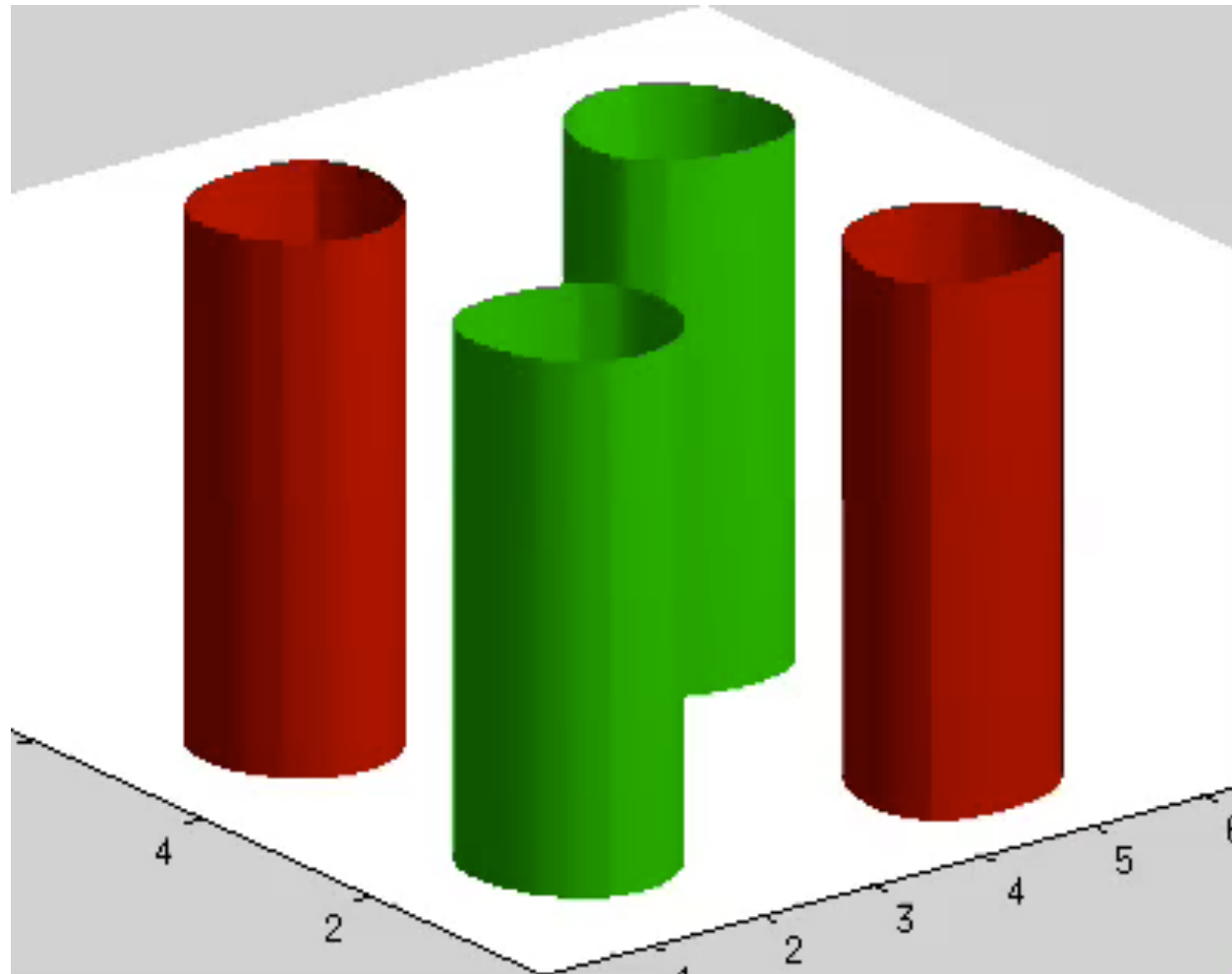
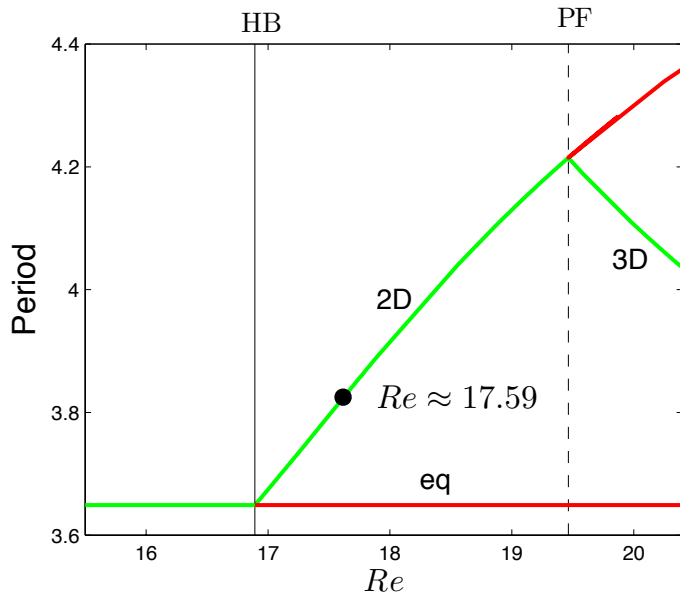
$$(N_x, N_y, N_z, N_t) = (17, 17, 0, 9)$$

$$n = 12803$$

$$\nu = \frac{\sqrt{8\pi}}{Re} \approx 0.285$$

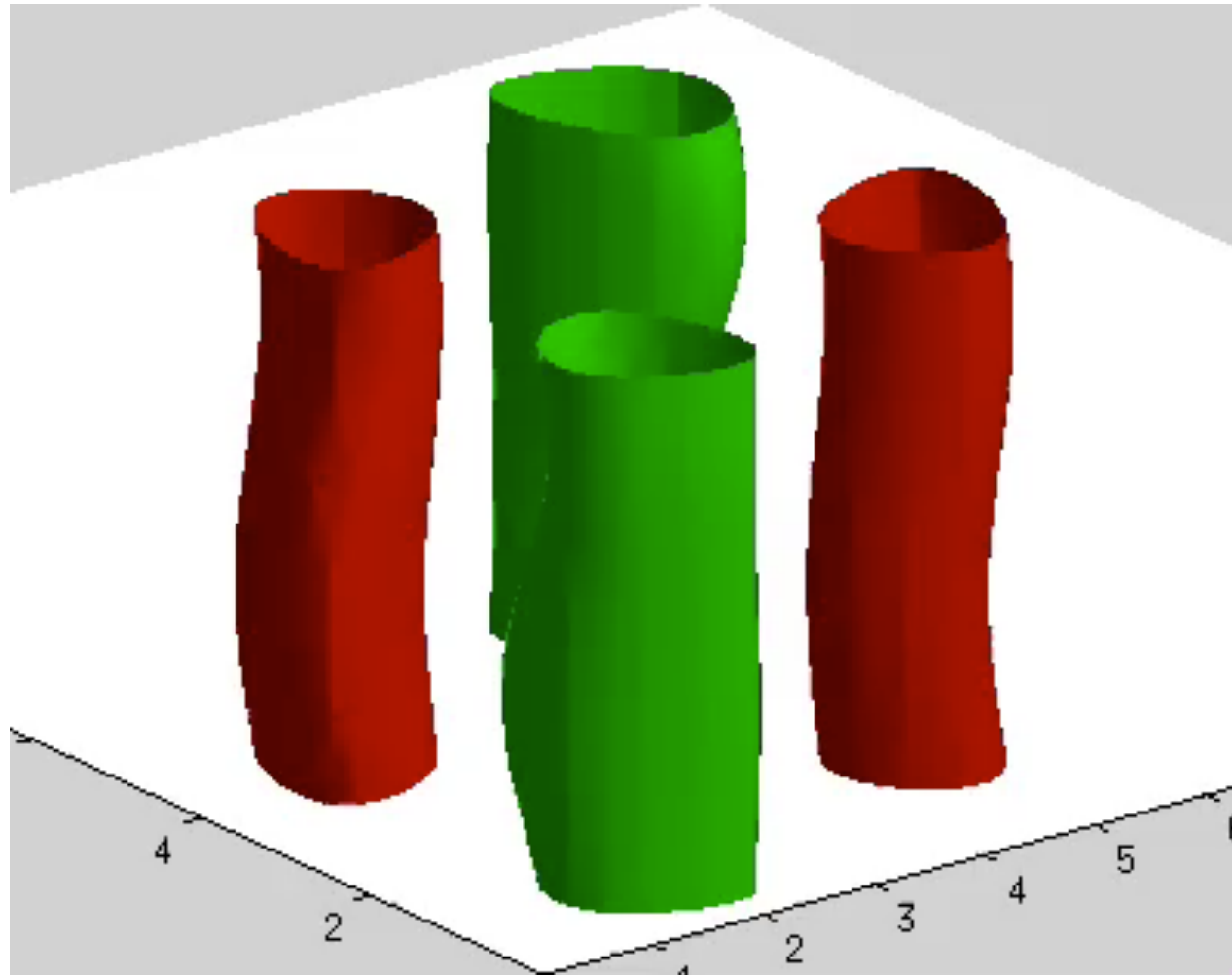
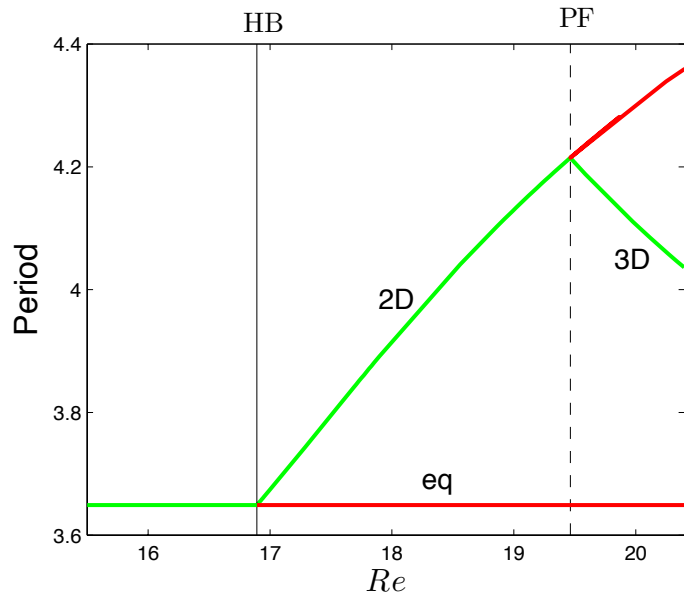
Periodic orbits in the 2D Navier-Stokes equations

3 days computation with INTLAB (MATLAB)
on an Apple MacBook Pro



Isosurfaces of the vertical vorticity $\omega_3 = \partial_{x_1} u_2 - \partial_{x_2} u_1$ (the last component of $\omega = \nabla \times u$). For the forcing function g , the isosurfaces would be perfectly cylindrical, equal in size and stationary. Red and green indicate positive and negative values for the isosurfaces (at about 80% of the maximal value in each frame). The tubular structures represent vortex tubes, with anticlockwise (green) and clockwise (red) rotational motion around them.

Fully 3D periodic orbits in the Navier-Stokes equations?



Isosurfaces of the vertical vorticity $\omega_3 = \partial_{x_1} u_2 - \partial_{x_2} u_1$ (the last component of $\omega = \nabla \times u$). For the forcing function g , the isosurfaces would be perfectly cylindrical, equal in size and stationary. Red and green indicate positive and negative values for the isosurfaces (at about 80% of the maximal value in each frame). The tubular structures represent vortex tubes, with anticlockwise (green) and clockwise (red) rotational motion around them.

Thanks to my collaborators



J.B. van den Berg
VU Amsterdam



Maxime Breden
ENS / U. Laval



Lennaert van Veen
UOIT

