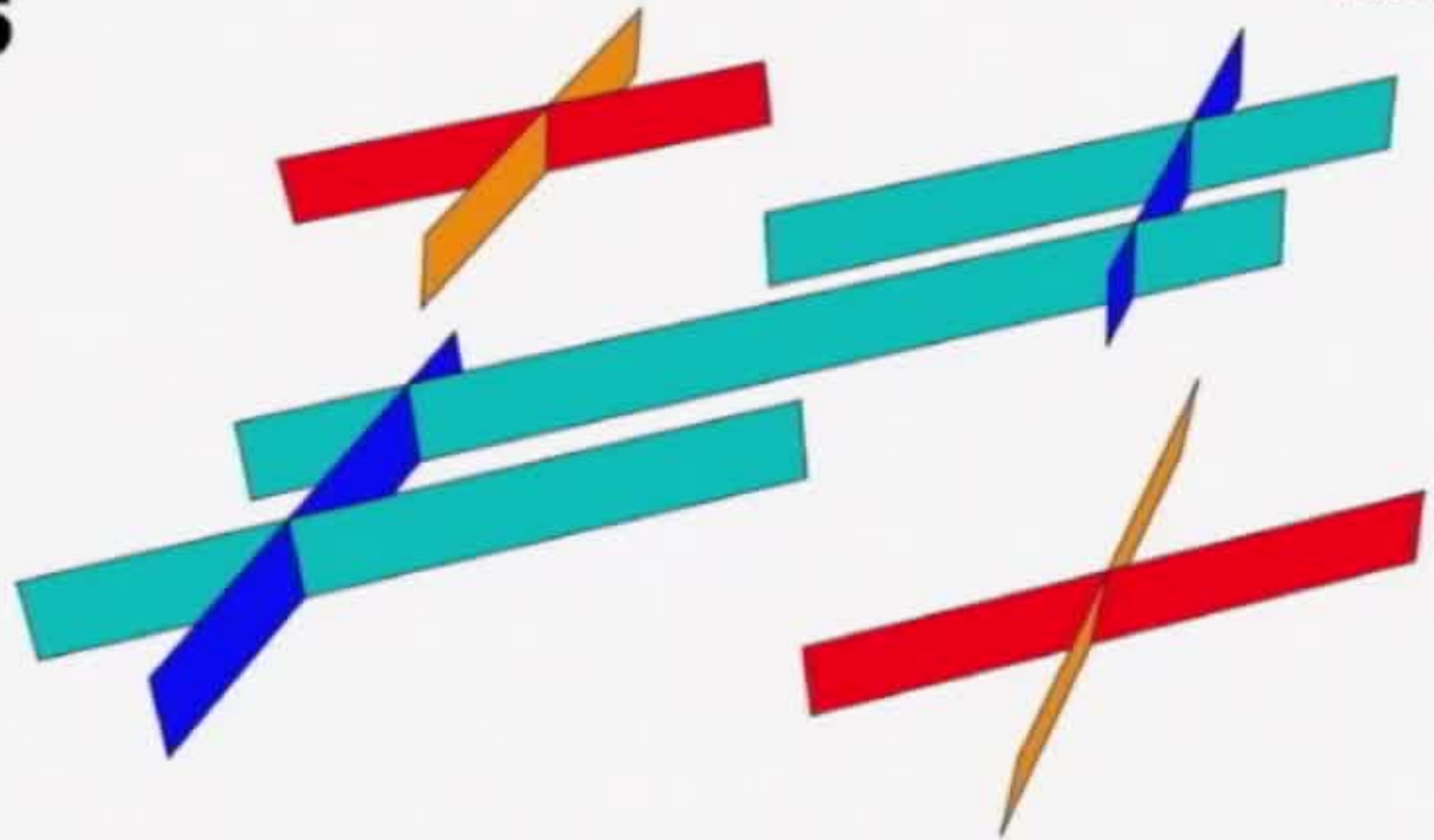


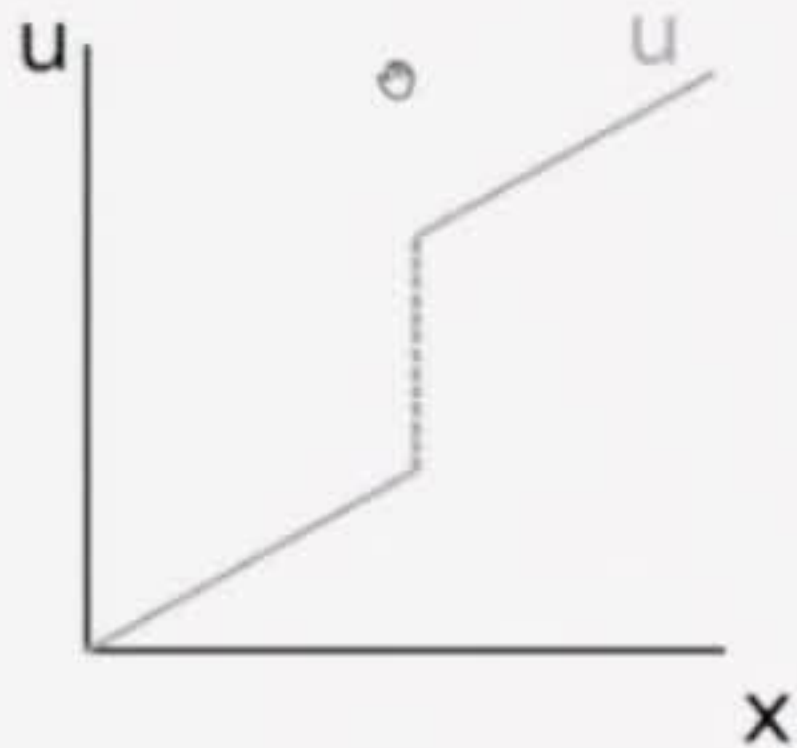
An Embedded Discontinuity Model for the Simulation of Fracture Deformations



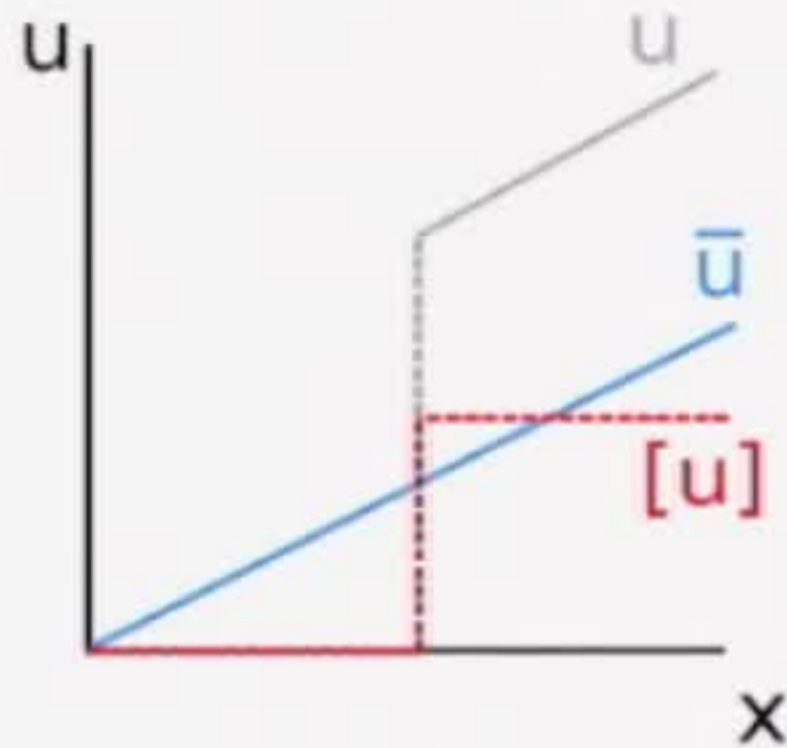
Igor Shovkun
Timur Garipov
Hamdi Tchelepi



Displacement Enrichment



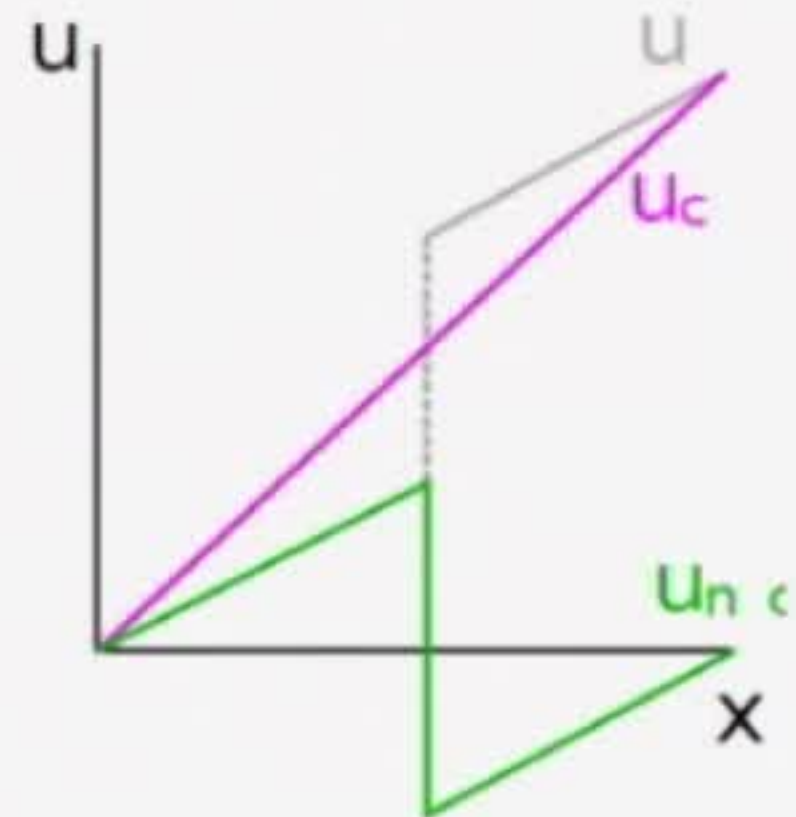
Discontinuous displacement



Decomposition:

$$u = \bar{u} + [u]H_{\Gamma}$$

H_{Γ} – unit step function



Regularization:

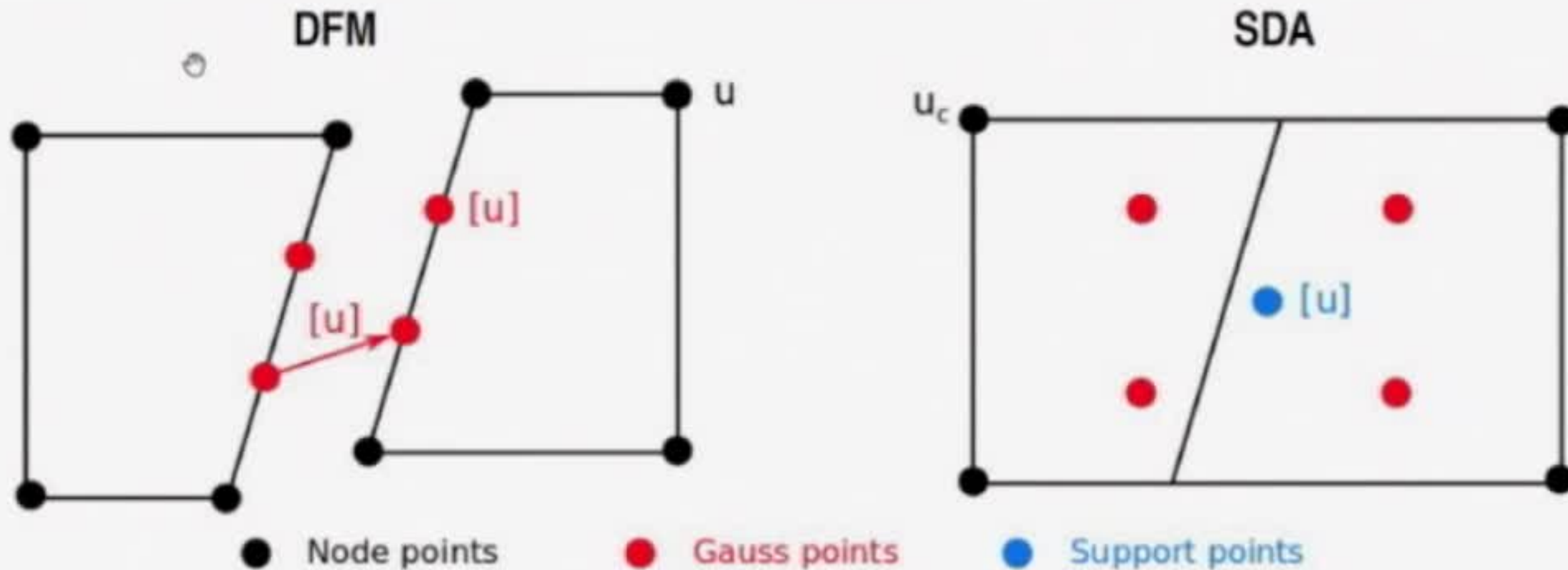
$$u = \underbrace{\bar{u} + f[u]}_{u_c} + \underbrace{(H_{\Gamma} - f)[u]}_{u_{nc}}$$

u_c : conforming displacement

u_{nc} : non-conforming displacement

f : level set function

Discretization



Global variable: displacement u
Local variables: jump $[u]$

Jump $[u]$ obtained from displacement
by interpolation

Cannot interpolate to obtain $[u]$

Analogy with Plasticity

System of plasticity:

$$\left\{ \begin{array}{l} \dot{\sigma} = \mathbf{C} : (\dot{\varepsilon} - \dot{\varepsilon}^p) \\ \dot{\varepsilon}^p = \lambda \frac{\partial G}{\partial \sigma} \\ \dot{q} = -\lambda H \frac{\partial G}{\partial \sigma^\Gamma} \\ F(\sigma, q) = 0 \end{array} \right. \begin{array}{l} \leftarrow \text{Stress-strain equation} \\ \leftarrow \text{Plastic strain evolution} \\ \leftarrow \text{Softening/hardening} \\ \leftarrow \text{Flow rule} \end{array}$$

Stress continuity \leftarrow

σ : stress
 \mathbf{C} : elastic stress-strain tensor
 ε : total strain
 ε^p : plastic strain
 λ : Lagrange multiplier
 q : internal state variable (cohesion)
 H : hardening modulus
 G, F : plastic potential and flow rule

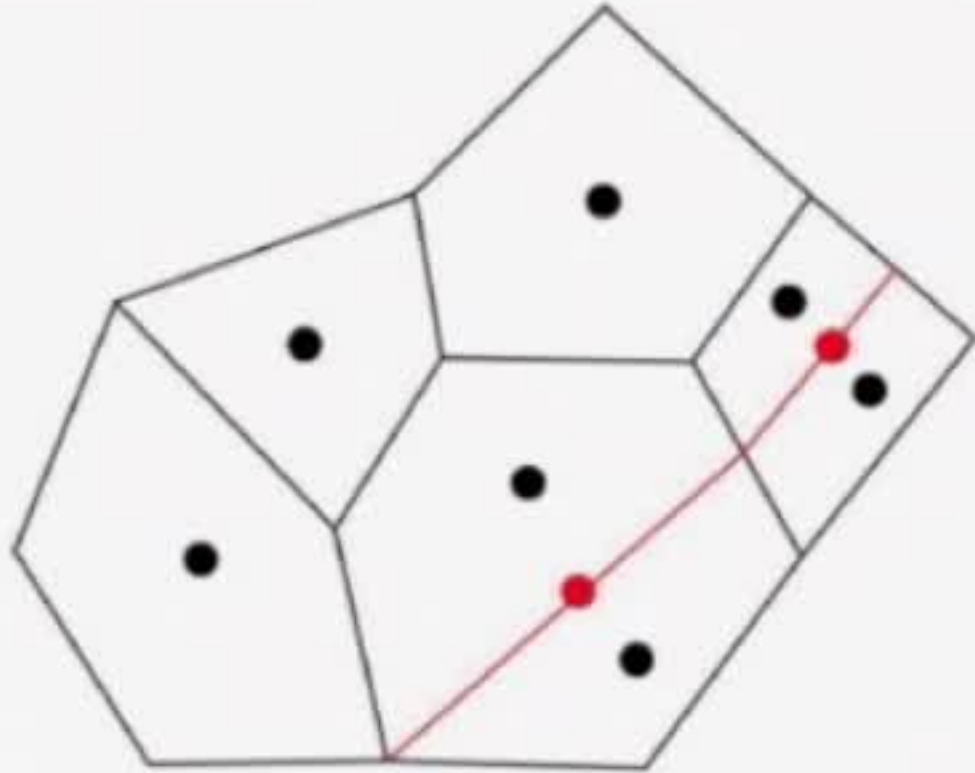
SDA system:

$$\left\{ \begin{array}{l} \dot{\sigma} = \mathbf{C} : [\nabla^s u_c - ([\dot{u}] \otimes \nabla f)^s] \\ [\dot{u}] = \lambda_\Gamma \frac{\partial G}{\partial t} \\ \dot{q} = -\lambda_\Gamma H_\Gamma \frac{\partial G}{\partial q} \\ F(t, q) = 0 \\ t = \langle \sigma \rangle \cdot n \end{array} \right. \begin{array}{l} \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \end{array}$$

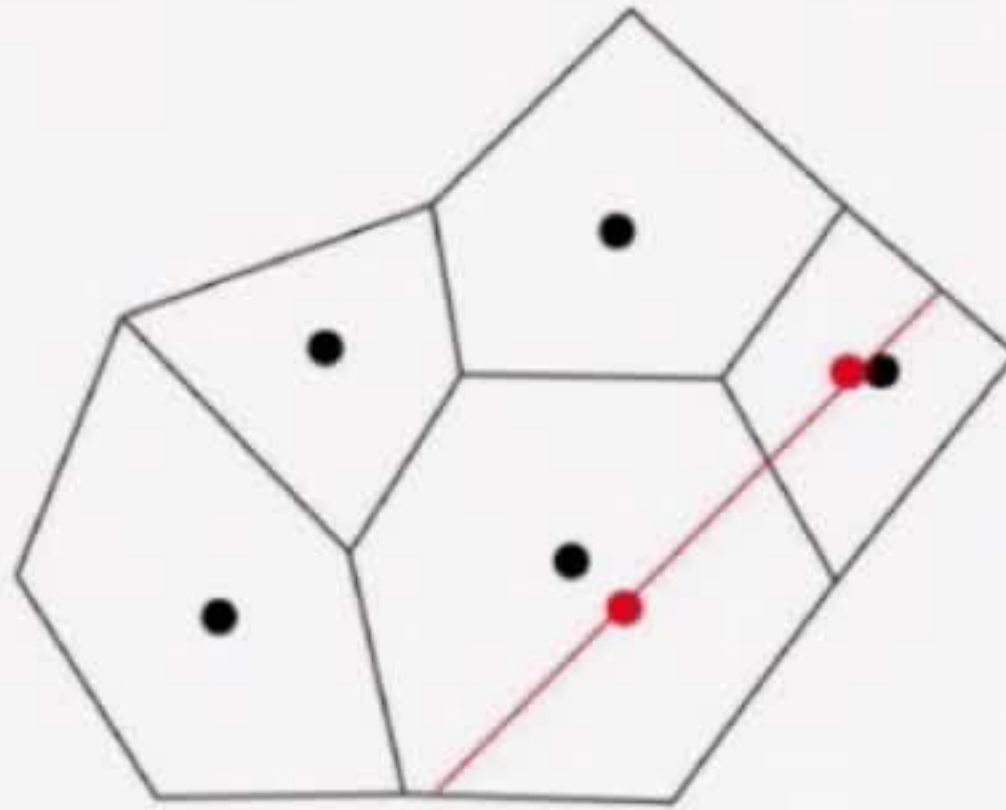
t : traction of fracture surface
 u_c : conforming displacement
 $[u]$: jump
 f : level set
 n : fracture normal
 λ_Γ : Lagrange multiplier
 H_Γ : Hardening modulus

Embedded Fractures: Fluid Flow

I
Discrete Fractures (DFM)



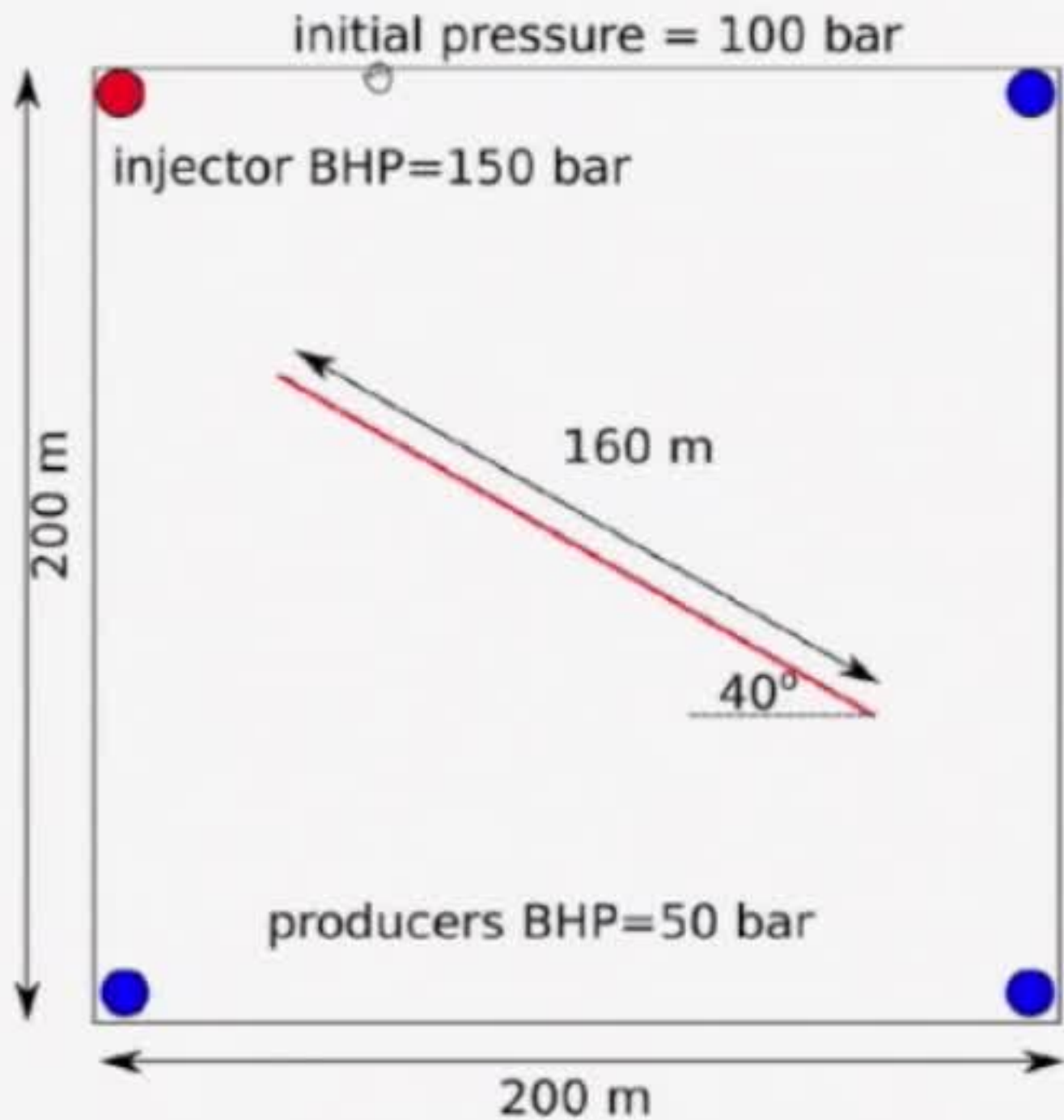
Embedded Fractures (EDFM)



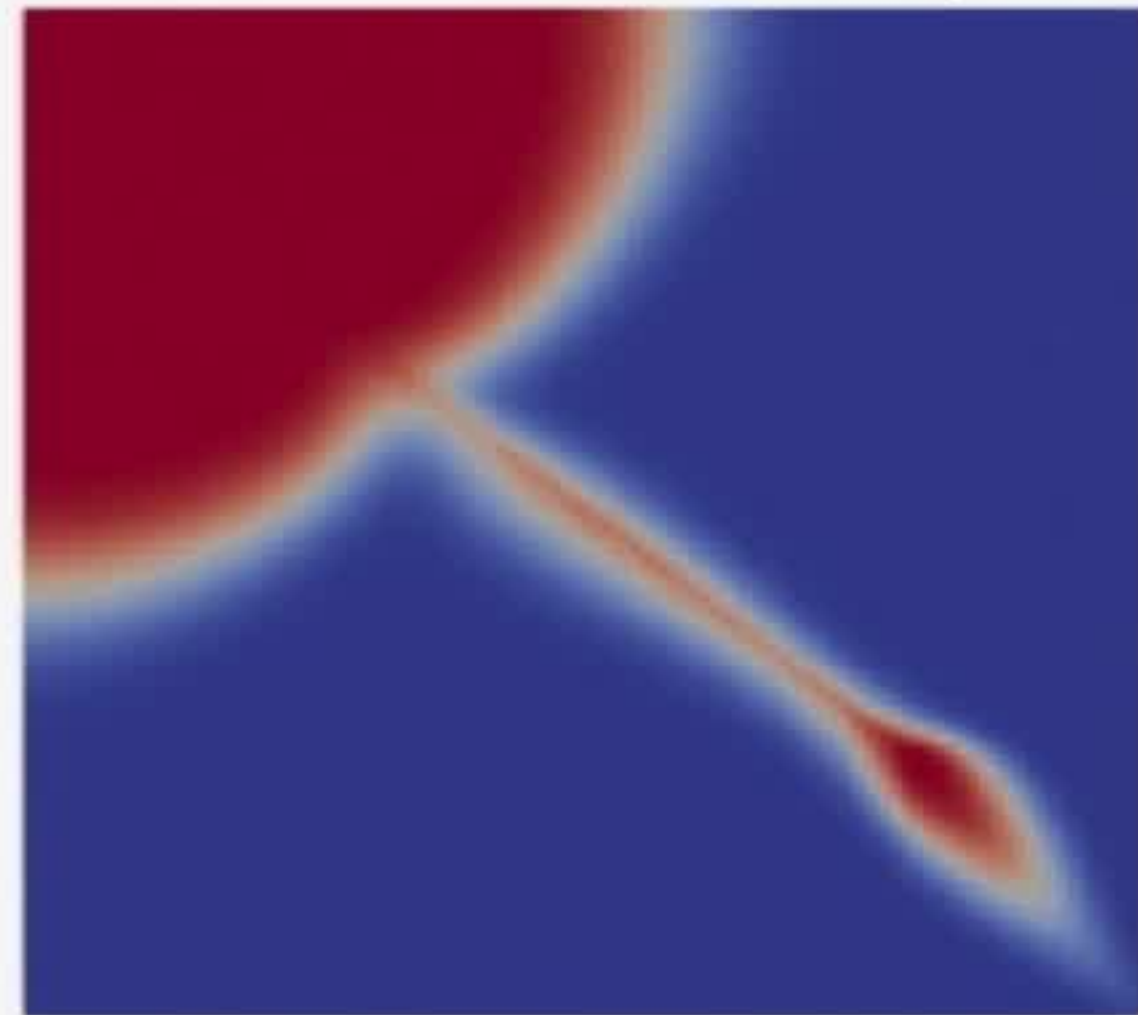
EDFM Matrix-Fracture
Transmissibility:

$$T_{MF} = \frac{2Akn}{\langle d \rangle}$$

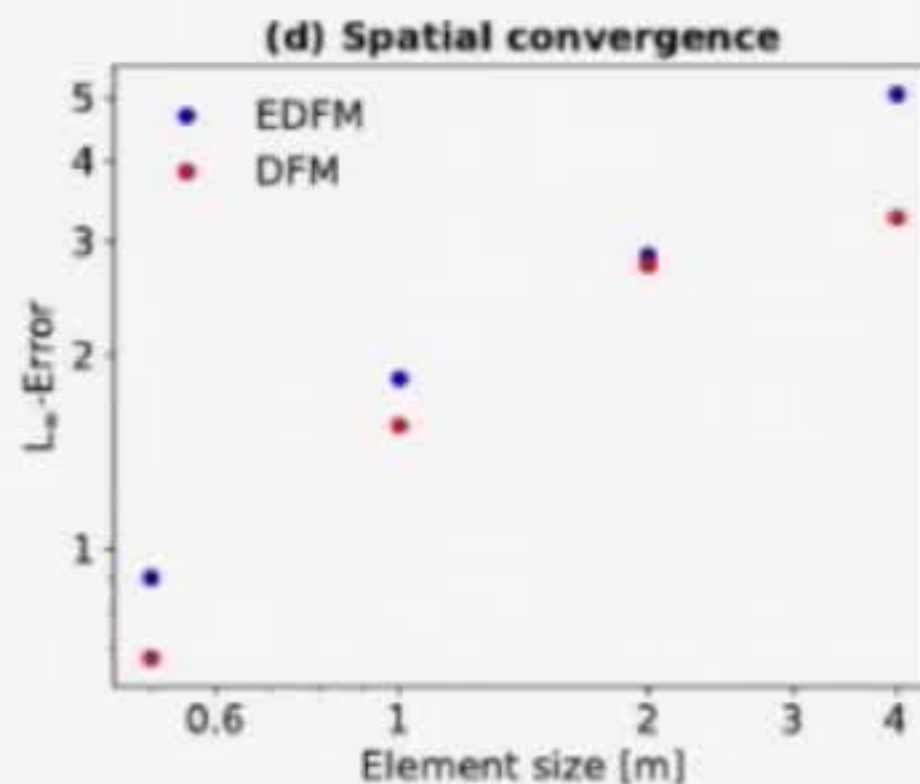
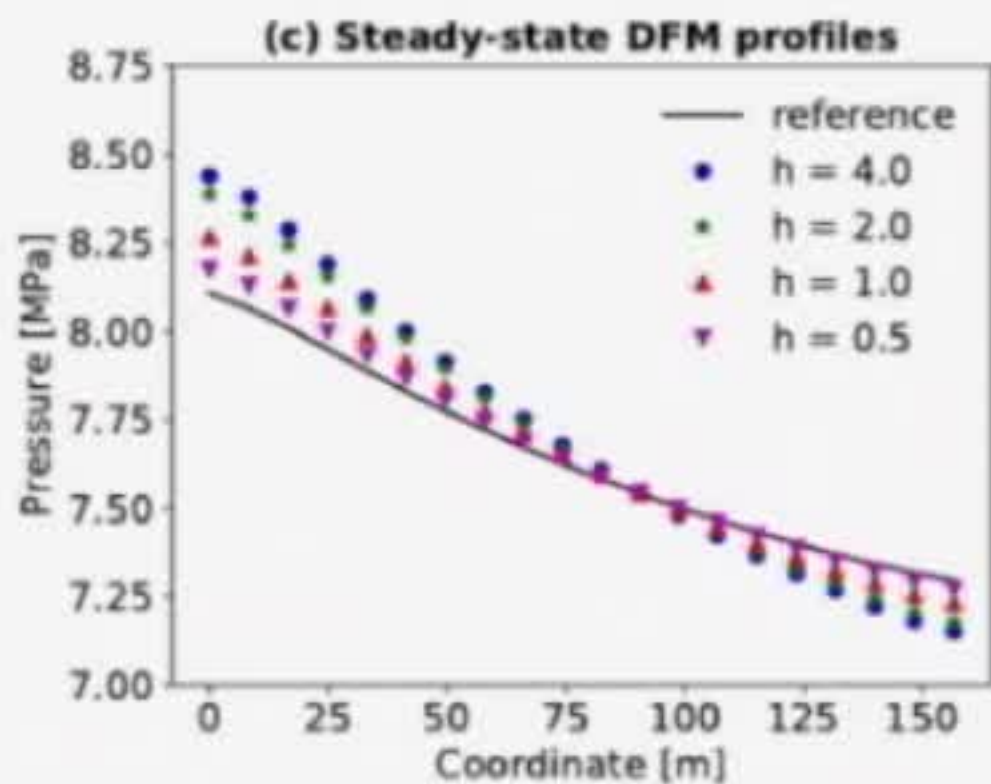
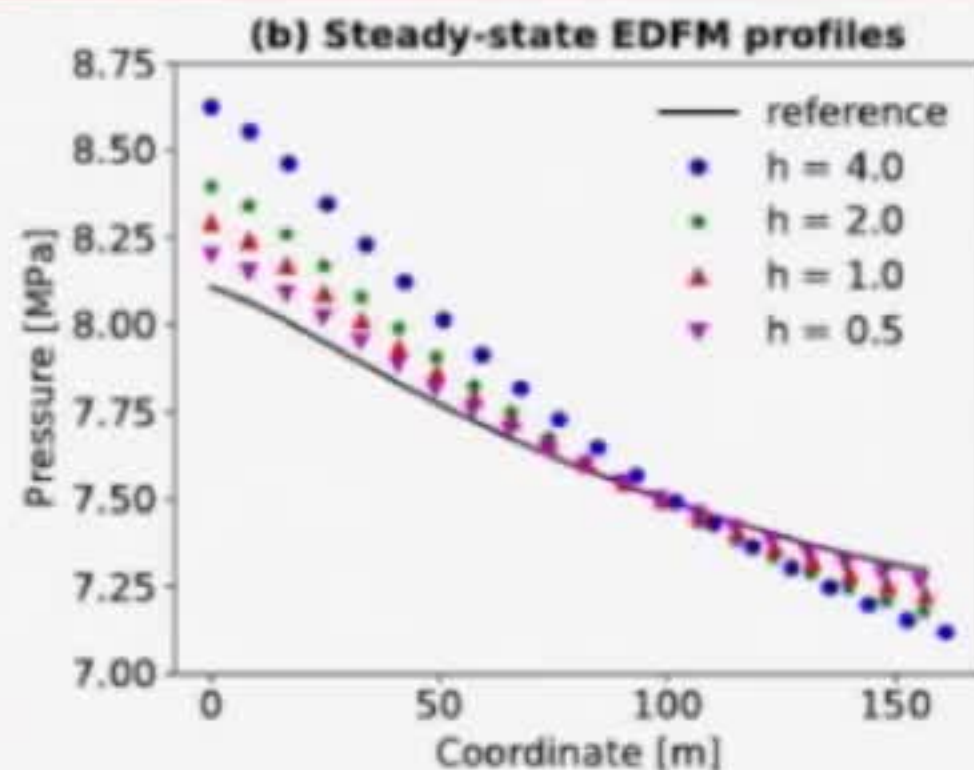
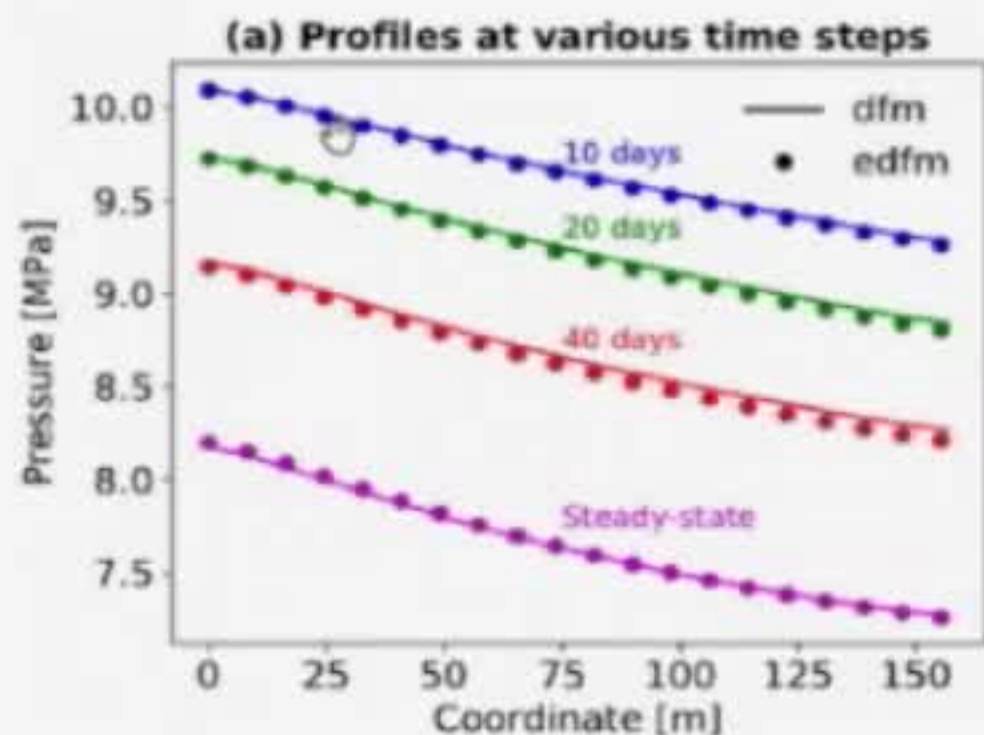
Test Problem: Single-Phase Fluid Flow



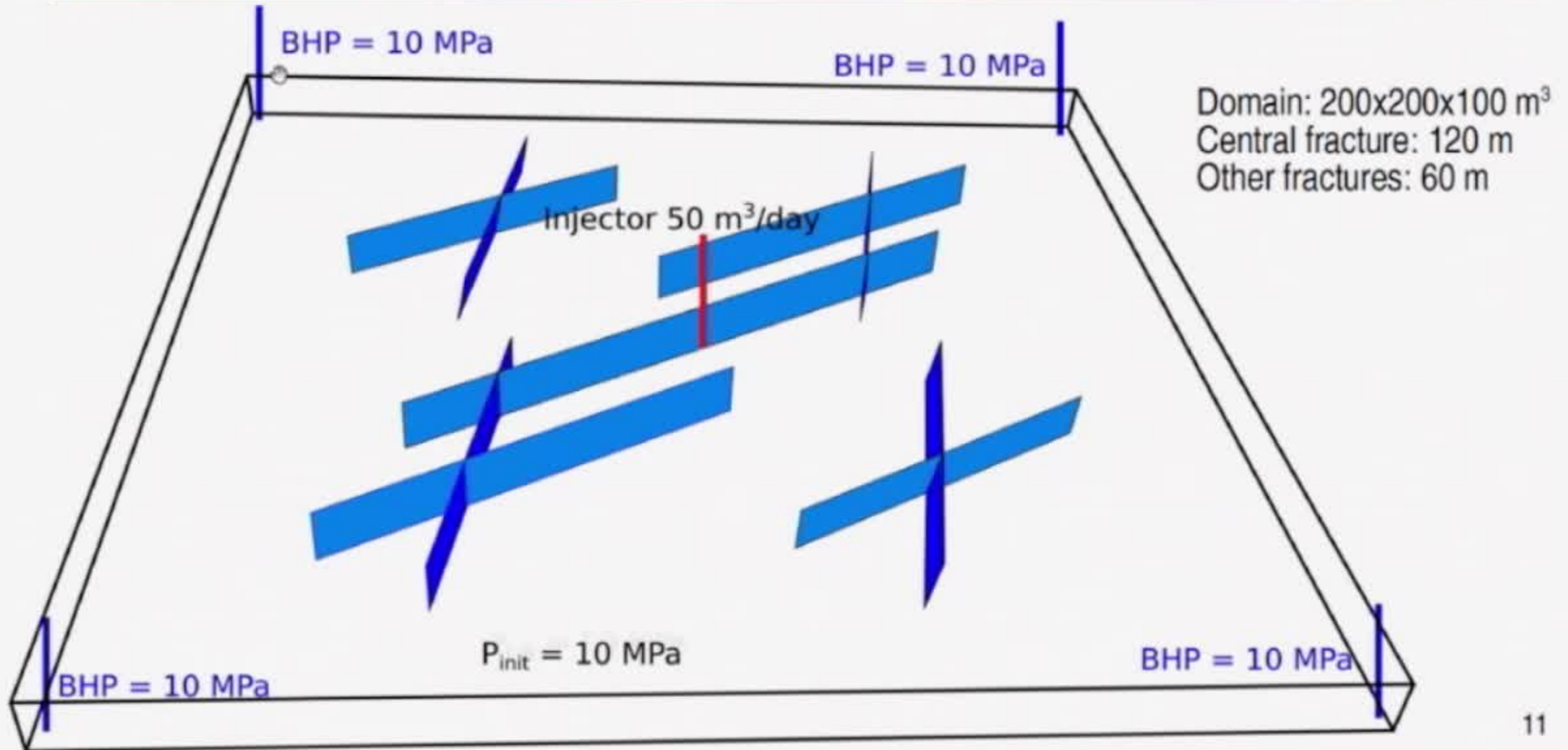
Saturation Profile at 100 days



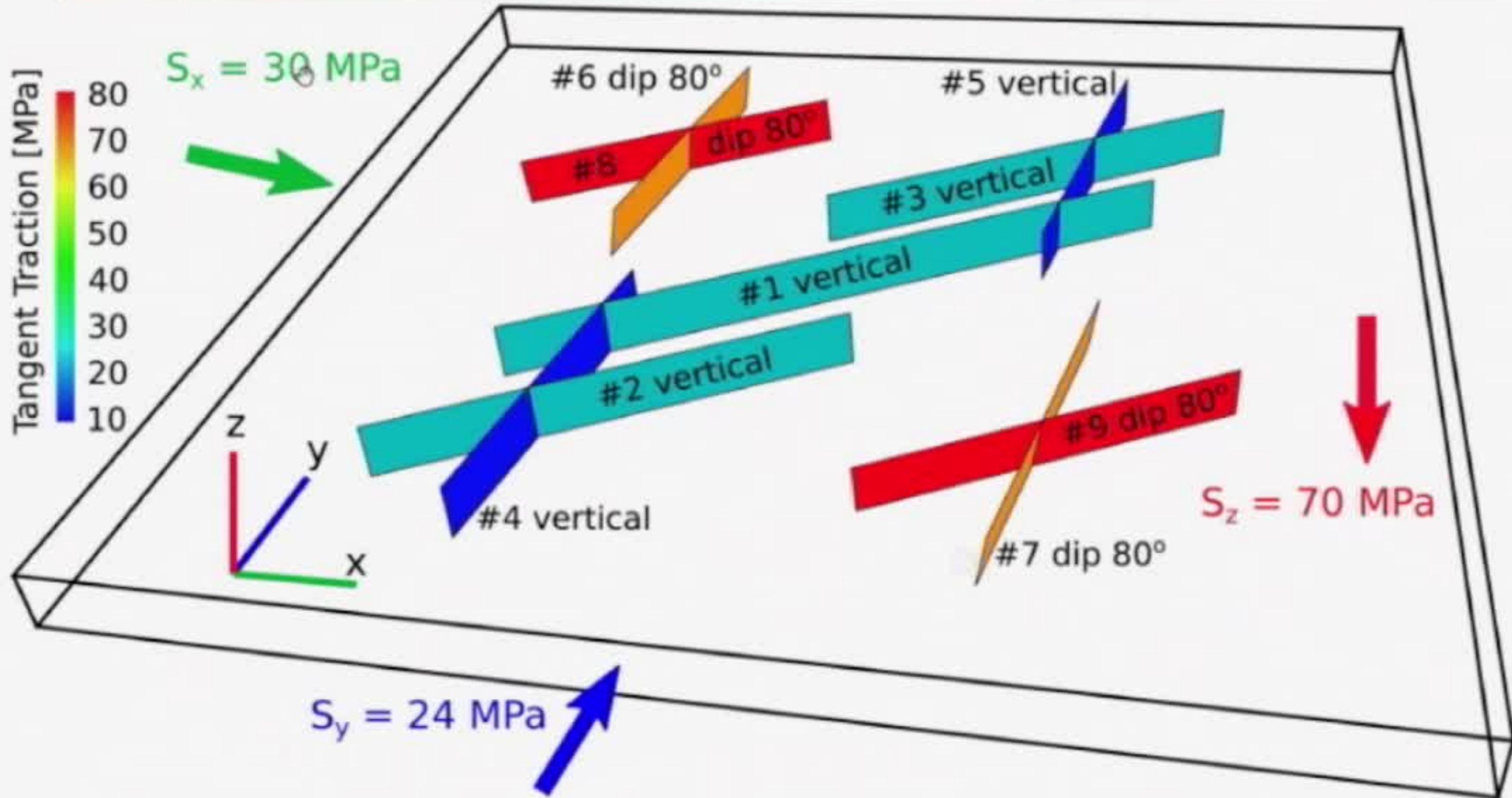
Test Problem: Single-Phase Fluid Flow (cont.)



Simulation Domain: Wells



Initial Stress State



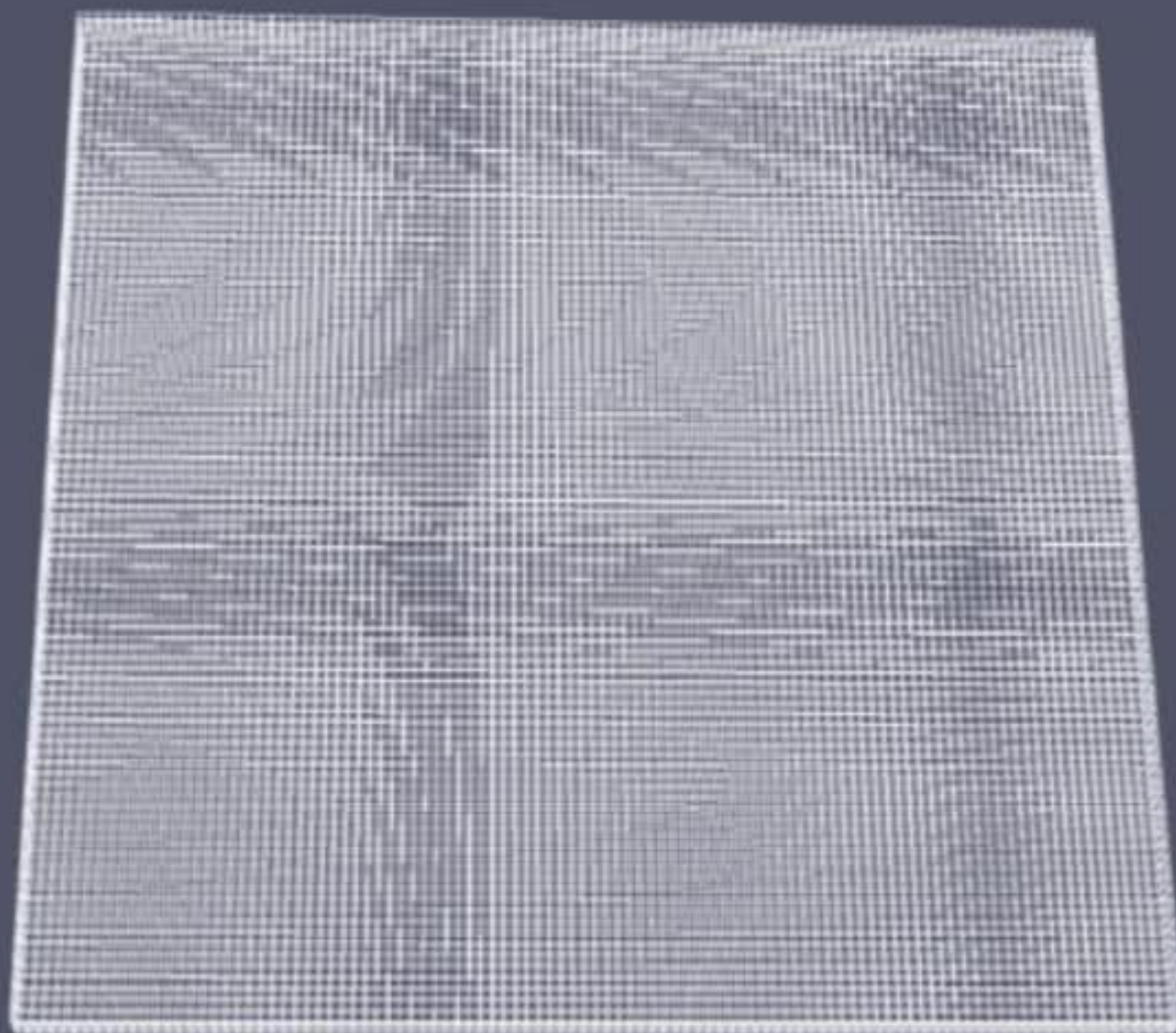
Gridding

DFM



59032 prisms
2.2 m near fractures
10 m at boundaries

EDFM



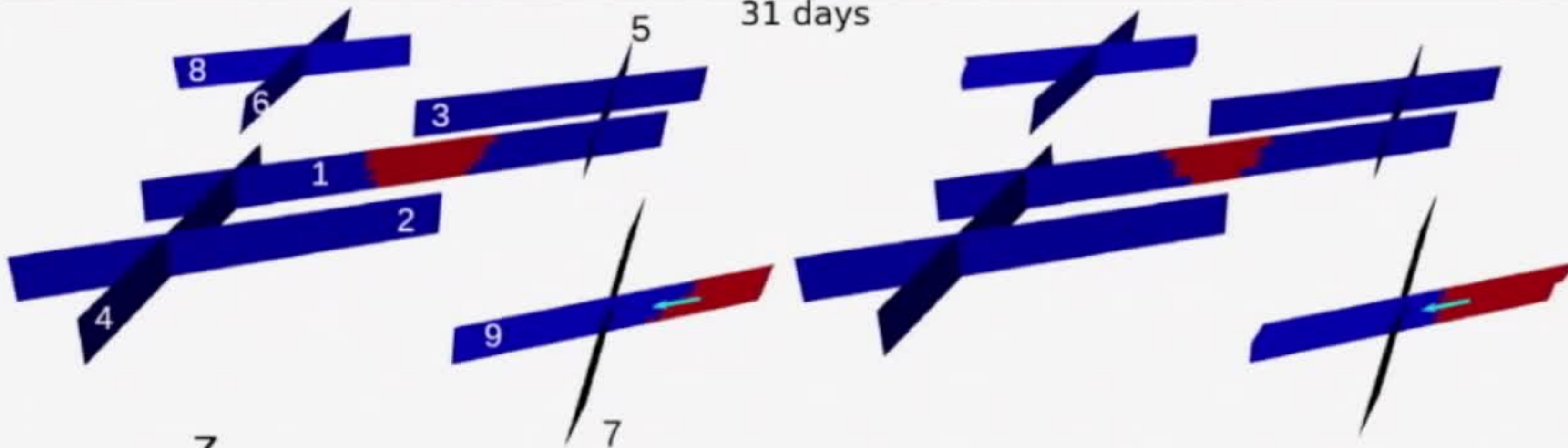
40804 hexahedrons
2.0 m

Fracture Reactivation: 31 days

Discrete Fractures

Embedded Fractures

31 days

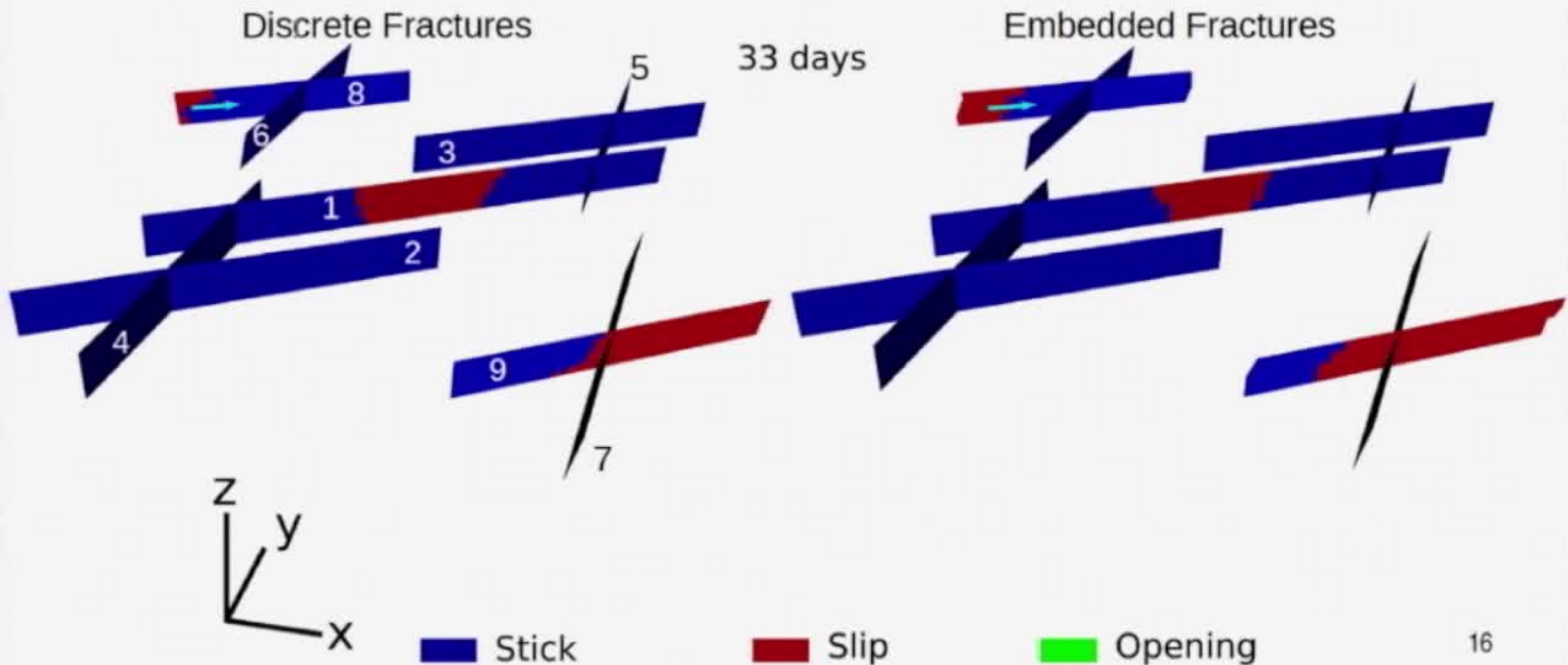


Stick

Slip

Opening

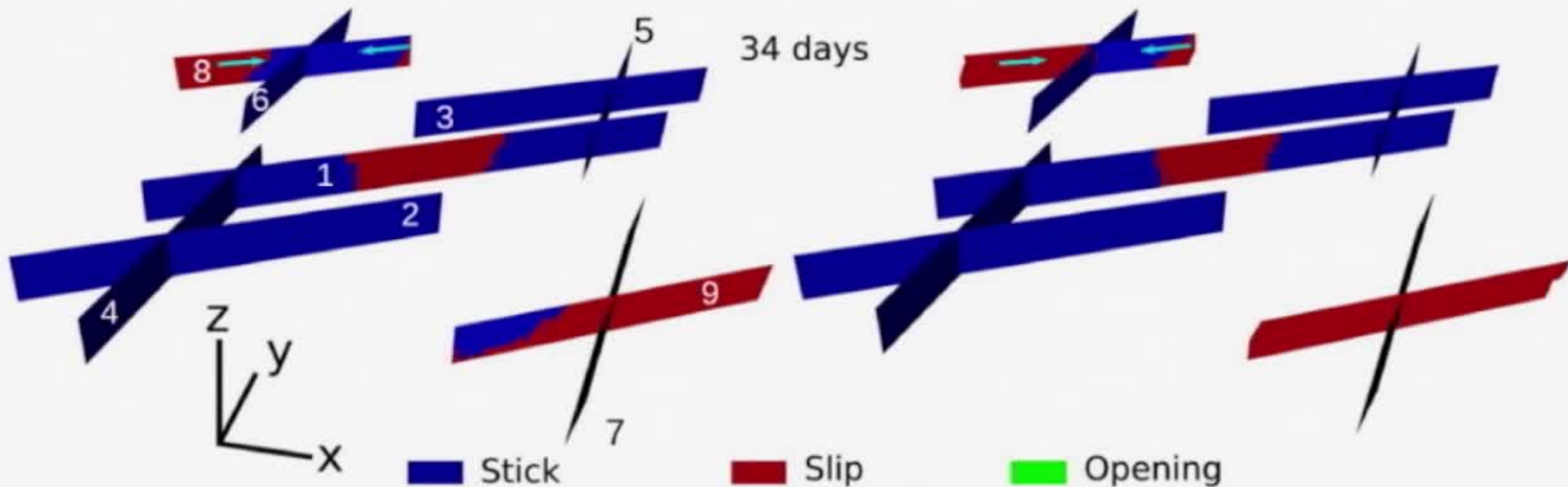
Fracture Reactivation: 33 days



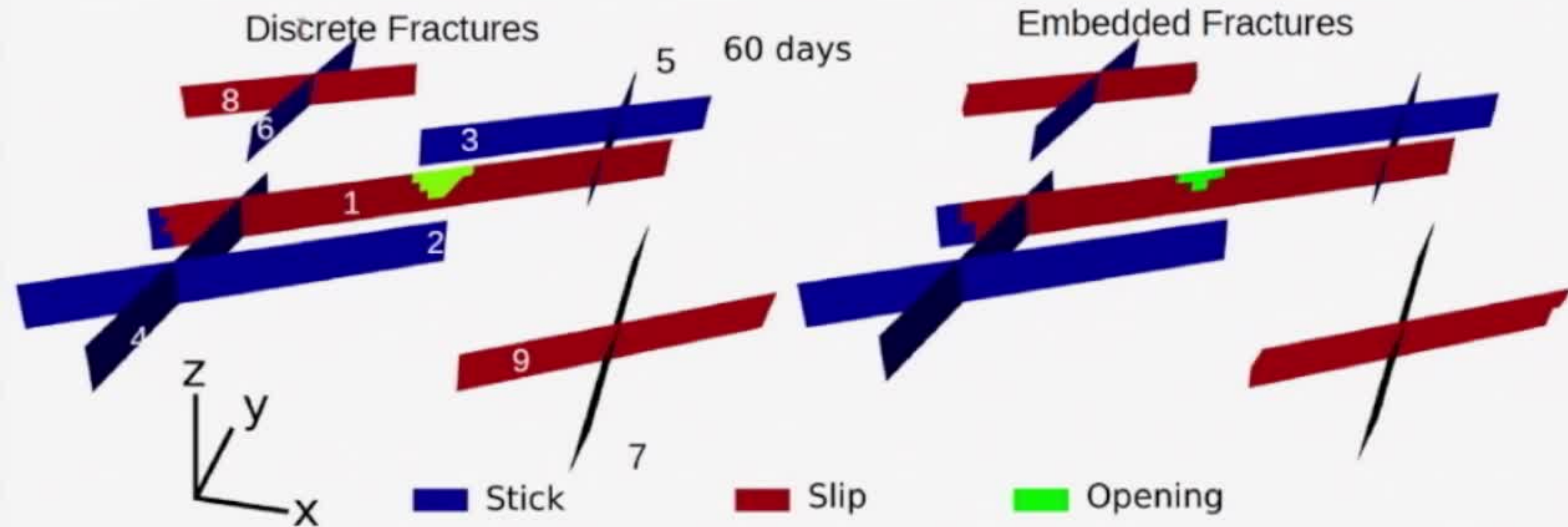
Fracture Reactivation: 34 days

Discrete Fractures

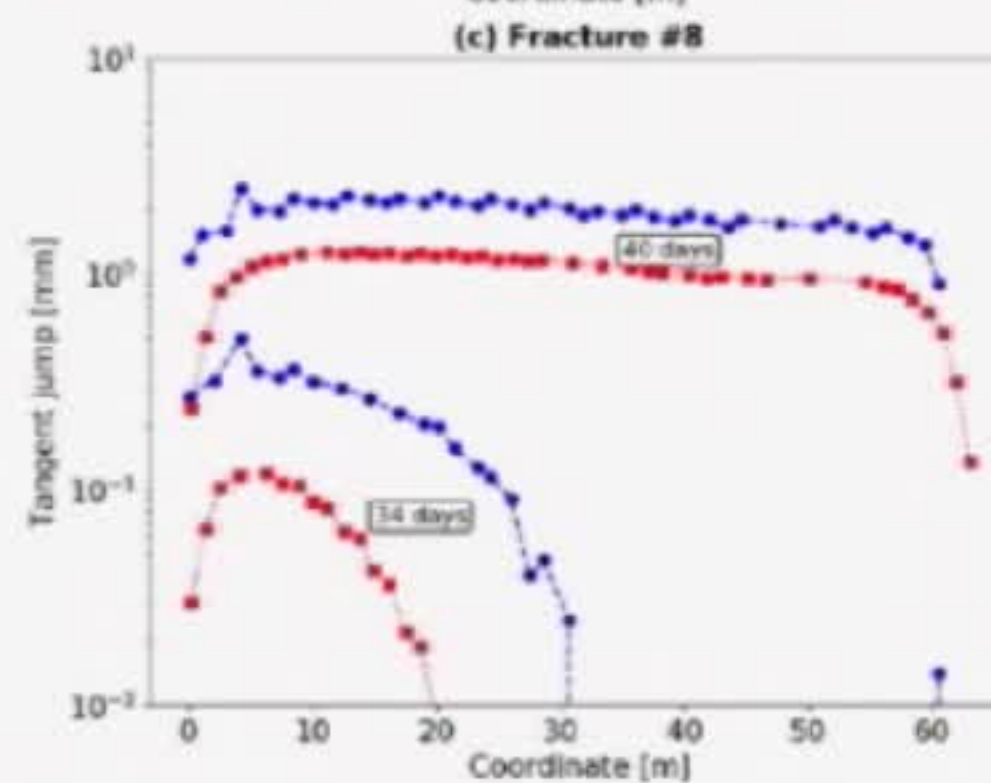
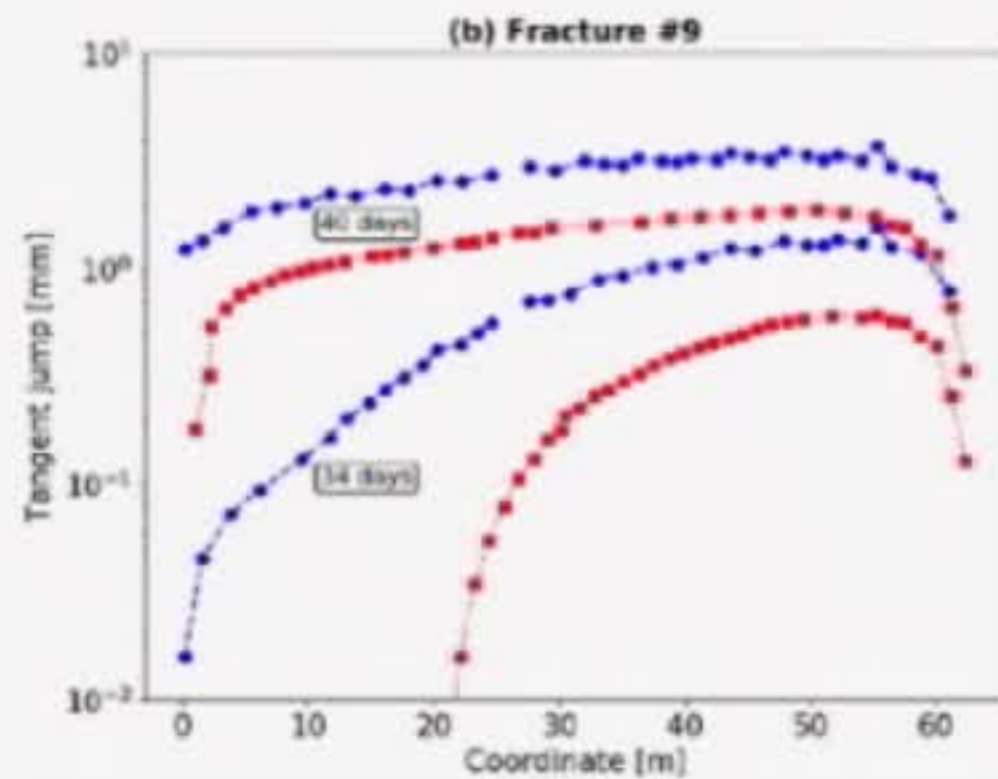
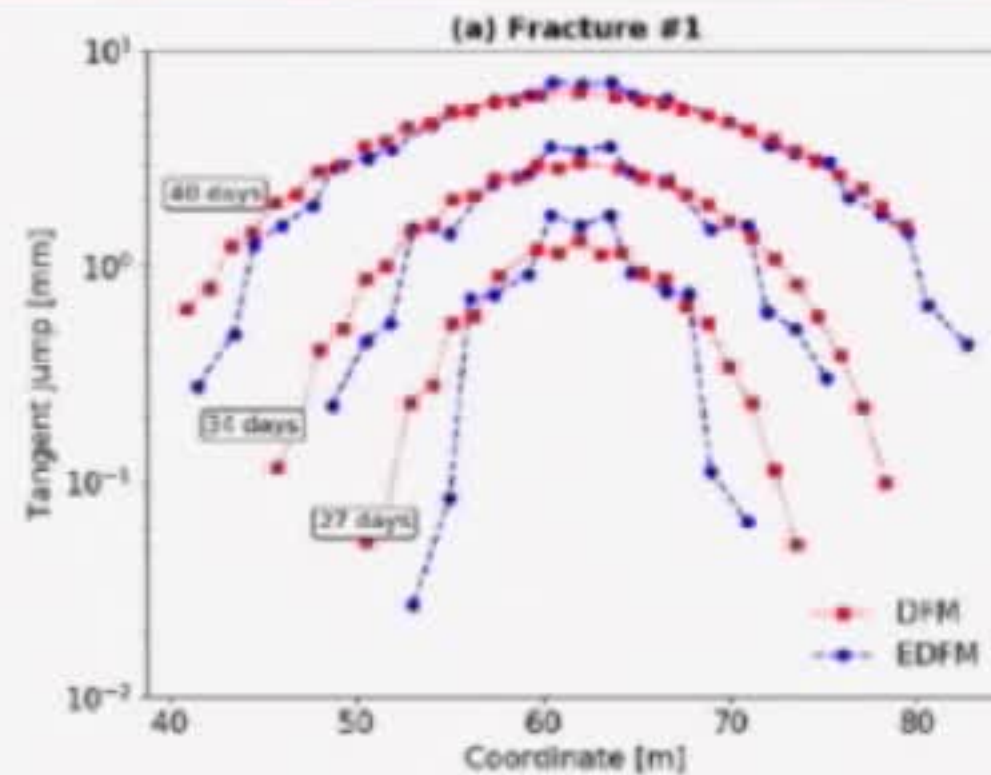
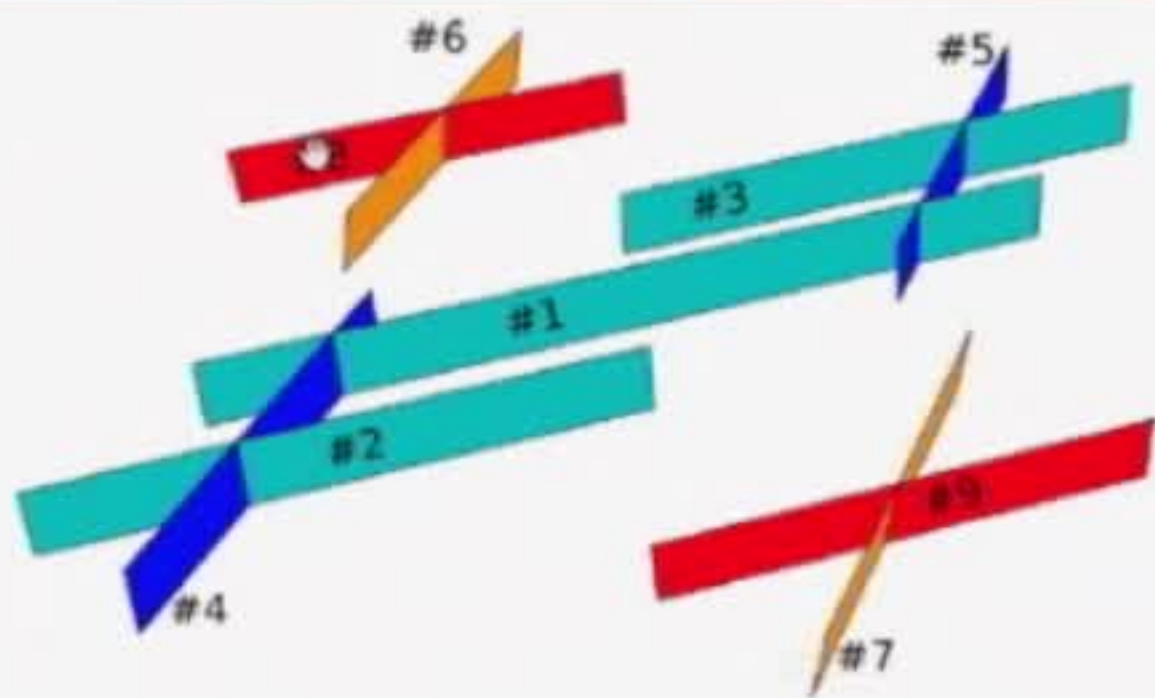
Embedded Fractures



Fracture Opening: 60 days



Fracture Jump Comparison



Summary

- EDFM overestimates slip whereas DFM underestimates slip
- Both EDFM and DFM exhibit super-linear convergence
- Using EDFM on non-conforming grids results in non-smooth fracture jump profiles
- EDFM and DFM give similar results even in complex coupled cases

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⊙

Thank You!