

From IB to IIM, from Solution to Gradient Computations

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Happy Birthday
to Charlie!!!

Outline

- From IB (Peskin) to IIM (LeVeque/Li)
- Motivations of this talk: Accurate gradient computation *at* the interface/boundary for *Cartesian* grid methods
- *A new augmented IIM*
 - FD Poisson equations, regular problem → piecewise constant coef. → Variable coef.
 - Optimal complexity $O(N \log(N))$, 2nd accurate solution & *gradient* and proof (Claim to be the '*best*')
- Numerical results
- Convergence analysis
- Conclusions

From IB to IIM

- Peskin's IB method
 - Mathematical modeling
 - Numerical method: discrete delta function
 - Simple, robust, many applications
 - First order, elliptic (Li, elliptic with Dirichlet BC), Stokes with periodic BC (Mori)
- IIM (LeVeque/Li)
 - Second order or higher
 - Use jump conditions (from PDE or physics) instead of `delta functions
 - Best discrete delta function?
 - Finite difference (IIM, AIIM) and element (IFEM)
- ***How to compute the solution & gradient accurately?***

Motivations for Accurate Gradient

- Many free boundary/moving interface problems depend on the first order *derivatives* of the solution
- For finite difference (**FD**) methods based on **Cartesian meshes**, there are a number of 2nd or higher order methods, but the derivatives are less accurate especially near the boundary/interface
- FEM: $L^2: O(h^2)$, $H^1: O(h)$, **at interface?**

Some Examples

- The 1D Stefan problem modeling the ice-water interface, let $\mathbf{s}(t)$ be the free boundary, $\mathbf{u}(x,t)$ be the temperature

$$\frac{\partial u}{\partial t} = \beta^2 \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < s(t)$$

$$-\frac{\partial u}{\partial t}(0,t) = f(t), \quad \text{inlet heat flux at left end}$$

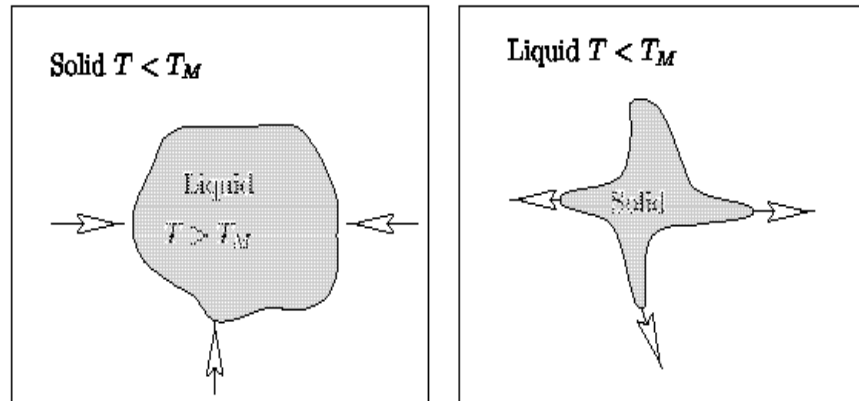
$$u(s(t),t) = 0, \quad \text{the right end is the freezing temperature}$$

$$\frac{ds}{dt} = -\frac{\partial u}{\partial x}(s(t),t), \quad \text{the Stefan condition}$$

$$u(x,0) = 0, \quad s(t) = 0, \quad \text{Initial conditions}$$

Stefan problem in 2D & Crystal Growth

- Left: 2D Stefan problem. Right: Formulations of Snowflakes. Heat equation with *non-linear BC*

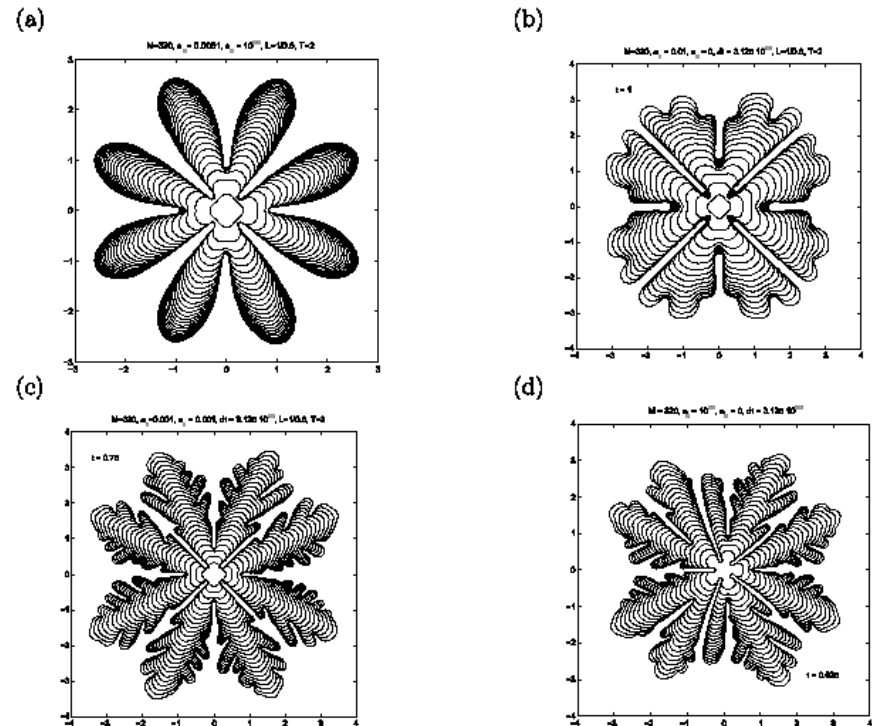


$$\rho c \frac{\partial T}{\partial t} = \nabla \cdot (\beta \nabla T), \quad \rho L V = - \left[\beta \frac{\partial T}{\partial n} \right]$$

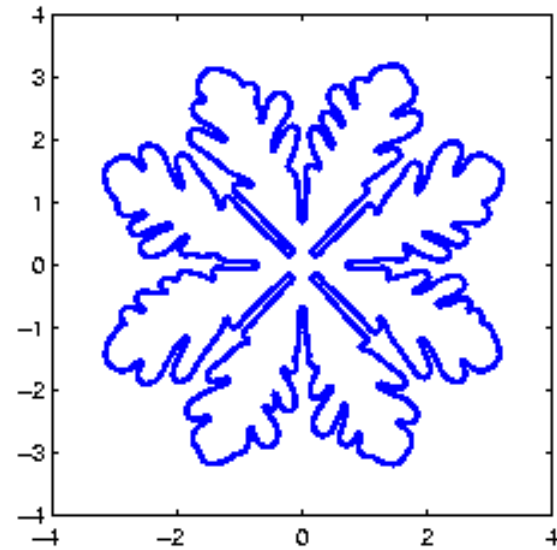
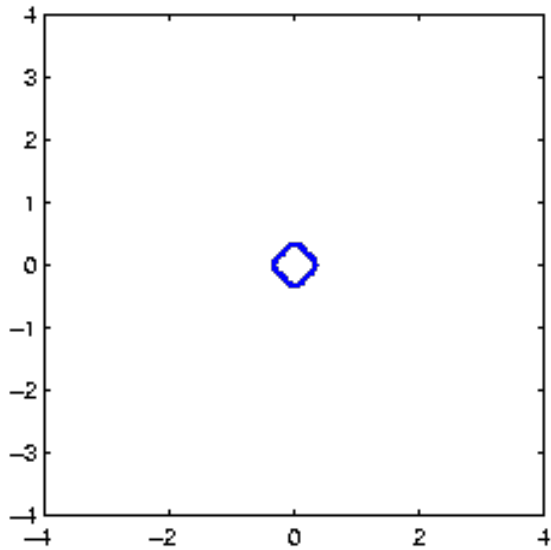
$$T(x, t) = -\varepsilon_c \mathcal{K} - \varepsilon_v V, \quad \frac{dX}{dt} \cdot n = V$$

Stefan Problem and Crystal Growth

- **1st derivatives are involved**
- **Stability analysis:**
dynamically unstable for some medium modes ($\exp(-k | t)$)



Simulation: Crystal Growth



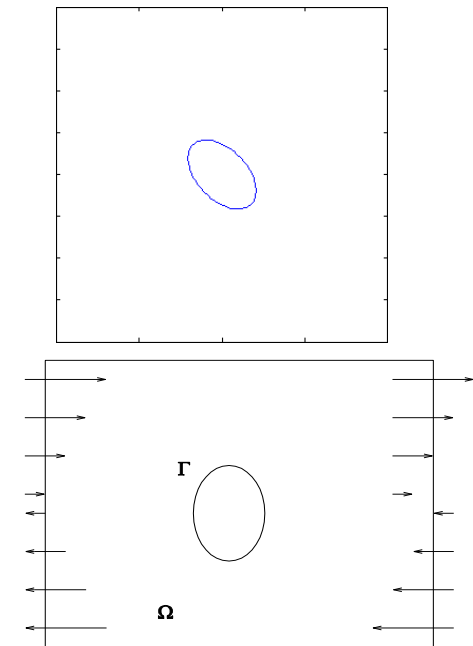
A moving interface example

- **NSE** equations with *unknown surface tension*, an inverse problem
- Both the area/length should be preserved.

$$\rho \left(\frac{\partial u}{\partial t} + u \cdot \nabla u \right) + \nabla p = \mu \Delta u + \int_{\Gamma} f(s,t) \delta(x - X(s,t)) ds + g$$

$$\begin{aligned} f(s,t) &= \frac{\partial}{\partial s} (\sigma(t,s) \tau) + f_b \\ &= \sigma(s,t) \kappa n + \frac{\partial \sigma(s,t)}{\partial s} \tau + f_b \end{aligned}$$

$$\nabla \cdot u = 0, \quad (\partial_s \cdot u)_{\Gamma} = \frac{\partial u}{\partial \tau} \cdot \tau = 0$$

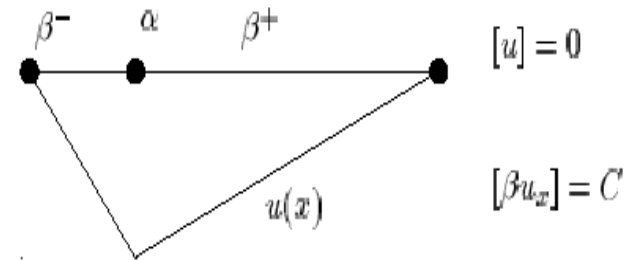


Model Problems

□ 1D:

$$(\beta u')' - \sigma u = C \delta(x - \alpha) \quad 0 < x < 1$$

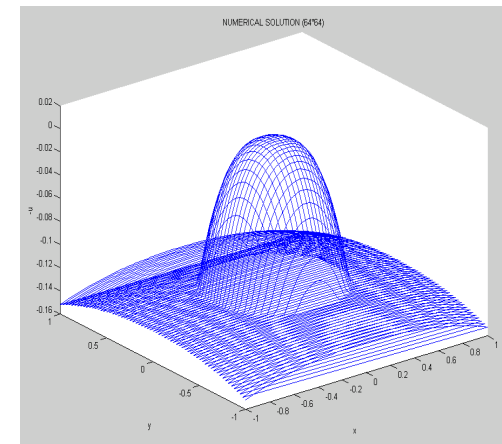
$$u(0) = 0, \quad u(1) = 0$$



□ 2D

$$\nabla \cdot (\beta \nabla u) - \sigma u = f + \int_{\Gamma} C(s) \delta(x - X(s)) ds$$

$$\text{or } \nabla \cdot (\beta \nabla u) - \sigma u = f, \quad [u] = w, \quad [\beta u_n] = C(s)$$



Methods for *Gradients* Review

- ❑ FD with Cartesian mesh and central FD scheme:
For ***regular*** problem & ***regular*** domain, the derivatives have the ***same*** order as the solution.
- ❑ The difficulty is for *general* boundaries and interfaces.
 - In FEM, ***posterior error analysis*** to get more accurate derivatives, depends on mesh quality
 - In FEM, ***mixed*** FEM or least squares FEM. It will lead to saddle problem and computationally expensive
 - DG for conservation laws
 - FD for elliptic and parabolic problems: ???

Results (old & *new*) in 1D

Accuracy of u_x at the boundary/interface

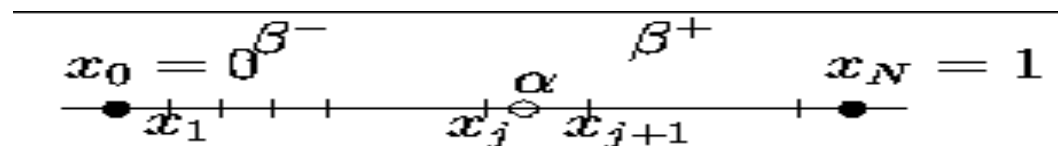
□ At the boundary, 3-point *one-sided*, provide 2nd u_x

□ At the interface (singular source or discontinuous coef

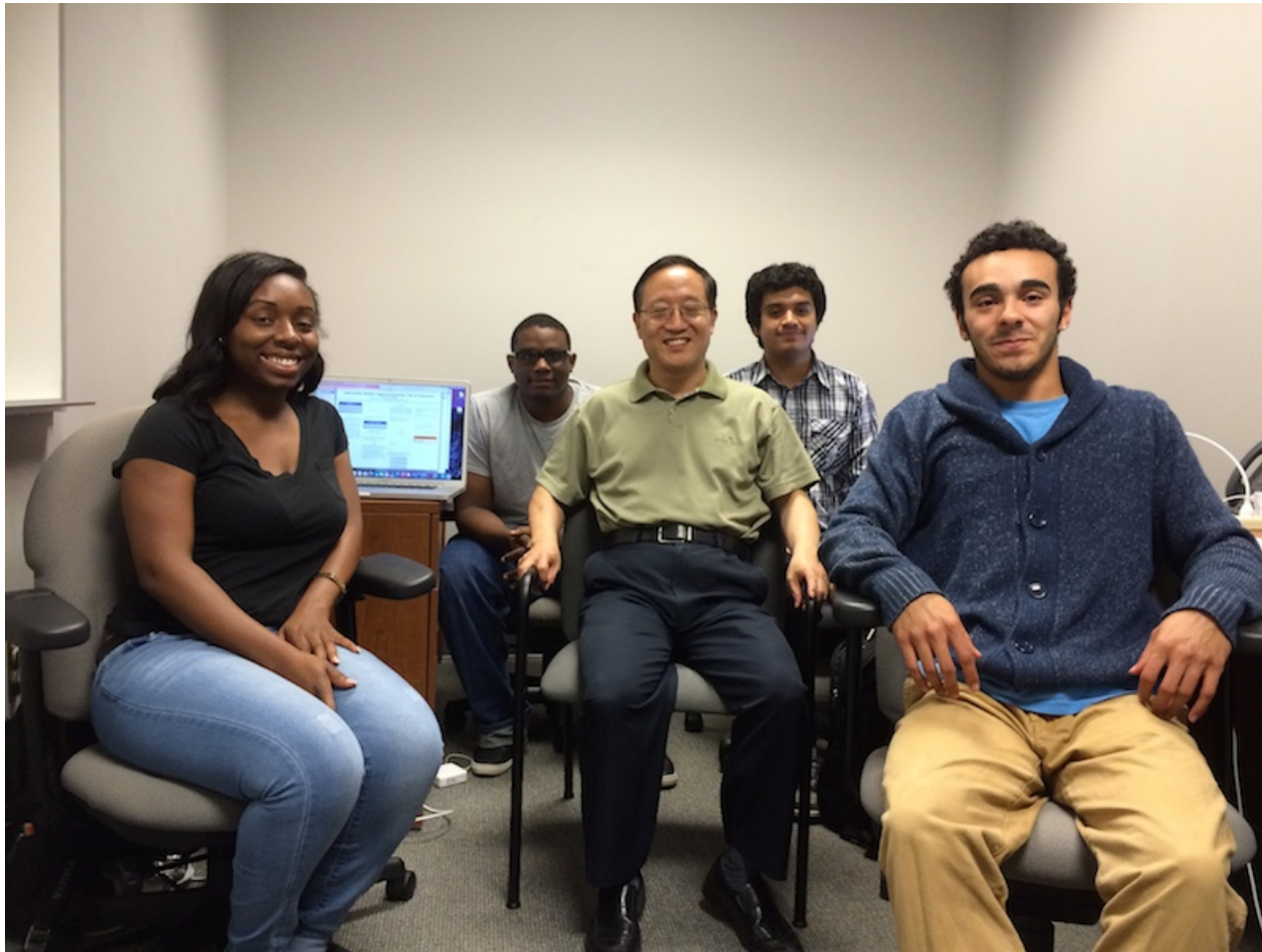
➤ 3-point one-sided FD scheme is 1st order

➤ ***IIM (compact FD, two-sided) is 2nd order in Cartesian, polar, and spherical.*** NCSU-2015 REU project.

➤ 1D



My NCSU 2015 REU Group



IIM in 1D, simple case

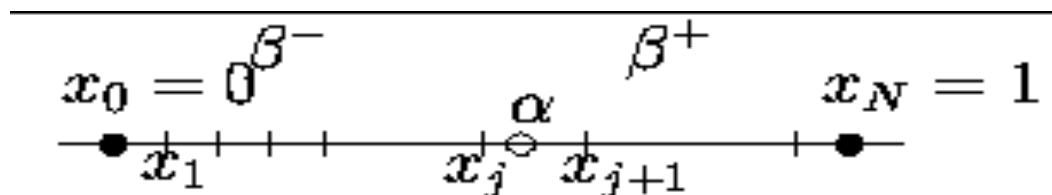
□ FD scheme for $(\beta u')' - \sigma u = C \delta(x - \alpha)$

$$\gamma_{j-1} U_{j-1} + \gamma_j U_j + \gamma_{j+1} U_{j+1} = f_j + C_j$$

□ Determine the coefficients and the correction term $\gamma_{j-1}, \gamma_j, \gamma_{j+1}, C_j$

□ Interface relations:

$$u^+ = u^-, \quad u_x^+ = \frac{\beta^-}{\beta^+} u_x^- + C, \quad u_{xx}^+ = \frac{\beta^-}{\beta^+} u_{xx}^-$$



IIM in 1D: Set-up equation

□ The linear system for the coefficients

$$\gamma_{j-1} + \gamma_{j-1} + \gamma_{j+1} = 0$$

$$\gamma_{j-1}(x_{j-1} - \alpha) + \gamma_j(x_j - \alpha) + \gamma_{j+1} \frac{\beta^-}{\beta^+} (x_{j+1} - \alpha) = 0$$

$$\gamma_{j-1} \frac{(x_{j-1} - \alpha)^2}{2} + \gamma_j \frac{(x_j - \alpha)^2}{2} + \gamma_{j+1} \frac{\beta^-}{\beta^+} \frac{(x_{j+1} - \alpha)^2}{2} = \beta^-$$

□ The correction term is

$$C_j = C \gamma_{j+1} \frac{\beta^-}{\beta^+} (x_{j+1} - \alpha)$$

Interpolation scheme for u_x

- Three points from both sides plus correction term

$$u_x(\alpha-) = \tilde{\gamma}_{j-1} U_{j-1} + \tilde{\gamma}_j U_j + \tilde{\gamma}_{j+1} U_{j+1} + \tilde{C}_j$$

$$\tilde{\gamma}_{j-1} + \tilde{\gamma}_j + \tilde{\gamma}_{j+1} = 0$$

$$\tilde{\gamma}_{j-1} (x_{j-1} - \alpha) + \tilde{\gamma}_j (x_j - \alpha) + \tilde{\gamma}_{j+1} \frac{\beta^-}{\beta^+} (x_{j+1} - \alpha) = 1$$

$$\tilde{\gamma}_{j-1} \frac{(x_{j-1} - \alpha)^2}{2} + \tilde{\gamma}_j \frac{(x_j - \alpha)^2}{2} + \tilde{\gamma}_{j+1} \frac{\beta^-}{\beta^+} \frac{(x_{j+1} - \alpha)^2}{2} = 0$$

2D Results for Gradients (old & new)

Accuracy of u_x & u_y at the interface

- ❑ Singular source only (i.e. $\beta=1$, $[u] \neq 0$, $[u_n] \neq 0$)
 - One-sided FD scheme is **1st order**.
 - IIM (compact FD, two-sided) is 2nd order (Beale & Layton). **One of the basis of the new method.**
- ❑ Direct: Maximum principle preserving (Li/Ito): soln 2nd, gradient, not sure yet
- ❑ Piecewise constant β , FIIM (Li, SINUM, 1997), 2nd solution (proved), 2nd gradient (observed before, now **proved**)
- ❑ **Variable β , $[\beta] \neq 0$, 2nd solution and gradient ($h^2 \log h$) with proof, 2015.**

2D Problem & Analysis

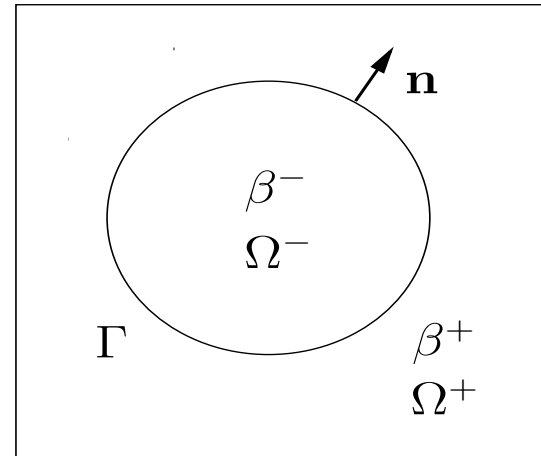
□ Elliptic interface problems with **variable** & **discontinuous** coefficient

$$\nabla \cdot (\beta \nabla u) + \sigma u = f + \int_{\Gamma} C(s) \delta(x - X(s)) ds$$

or $\nabla \cdot (\beta \nabla u) + \sigma u = f, \quad [u] = w, \quad [\beta u_n] = C(s)$

$$\beta(x,y) = \begin{cases} \beta^-(x,y) & \text{if } (x,y) \in \Omega^- \\ \beta^+(x,y) & \text{if } (x,y) \in \Omega^+ \end{cases}$$

$$[\beta(x,y)]_{\Gamma} \neq 0$$



Why elliptic interface problems?

- It is most expensive part for many simulations processes, e.g. projection method

$$\rho(u_t + u \cdot \nabla u) + \nabla p = \mu \Delta u + g$$

$$\nabla \cdot u = 0$$

$$\frac{u^* - u^k}{\Delta t} + (u \cdot \nabla u)^{k+1/2} + (\nabla p)^{k-1/2} = \frac{\mu}{2} (\Delta u^k + \Delta u^*) + F^{k+1/2}$$

$$\Delta \phi = \frac{\nabla \cdot u^*}{\Delta t}, \quad \frac{\partial \phi}{\partial n} = 0$$

$$u^{k+1} = u^* - \Delta t \nabla \phi$$

$$\nabla p^{k+1/2} = \nabla p^{k-1/2} + \nabla \phi$$

Cartesian Grid Methods

- ❑ Peskin's IB method, 1st order, inconsistent (Li, MathCom, 2014)
- ❑ Fast IIM (Li, SINUM), for piecewise constant β
- ❑ **Maximum principle preserving IIM** (Li/Ito)
- ❑ Ghost fluid method (Fedkiw/Liu) 1st -2nd order?
- ❑ Boundary integral method (~~X-F. Li~~, M. Siegel, Mayo, Greengard, ...)
- ❑ MIB (Wei/Zhao)
- ❑ Virtual node method (Teran)
- ❑ IFEM (Li/Lin², He,...), Petrov-Galerkin (Hou, Ji/Chen/Li ...), IFEV ...
- ❑ XFEM (~~X-D. Wang~~, W-K. Liu, J. Doby, ...)
- ❑ **Augmented IIM** (Li *et al*), Kernel free method (W. Ying *et. al*)

Which one gives 2nd derivatives? FAST IIM

Key Ideas

$$\nabla \cdot (\beta \nabla u) + \sigma u = f, \quad [u] = w, \quad [\beta u_n] = v$$

$$\rightarrow \Delta u + \frac{1}{\beta} \nabla u \cdot \nabla \beta + \frac{\sigma}{\beta} u = \frac{f}{\beta}$$

$$[u] = w, \quad [u_n] = q, \quad [\beta u_n] = v$$

- **Reformulate the problem** near the interface by introduce augmented variable $[u_n]$
- **Derive** different *new* interface relations using the new formulation
- Apply the *upwind* scheme near Γ for the advection term(s) to get an M-matrix
- Apply the GMRES for the Schur complement ($[u_n]$)

Poisson Eqn. with singular sources

$$\Delta u = f(x) + \int_{\Gamma} c(s) \delta(x - X(s)) ds + g$$

BC (e.g., Dirichlet, Neuman, Mixed)

□ Equivalent Problem

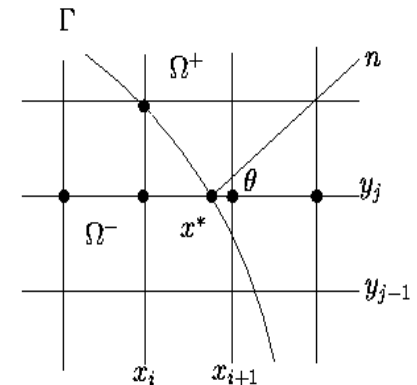
$$\Delta u = f(x), \quad x \in \Omega \setminus \Gamma, \quad [u]_{\Gamma} = 0, \quad \left[\frac{\partial u}{\partial n} \right]_{\Gamma} = C(s)$$

BC (e.g., Dirichlet, Neuman, Mixed)

□ FD scheme (x_j, y_j) , regular/irregular

$$\frac{u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} - 4u_{i,j}}{h^2} = L_h u_{i,j} = f_{ij}$$

$$\frac{u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} - 4u_{i,j}}{h^2} = L_h u_{i,j} = f_{ij} + C_{ij}$$



Poisson Eqn. with singular sources

- IB , IIM both work, what's the **best** discrete delta function? → Source removal technique (Li/Lai/Wang)
- $AU=F+BC$; A : Discrete Laplacian. Can be solved by a fast Poisson solver
- IIM is second order both in solution and **gradient** (T. Beale/Layton), now to NS equations with fixed/exact interface

Augmented approach/Fast IIM

- If β is two constants, flux jump condition $[\beta u_n] = C(s)$ along $[u] = w(s)$.

- Idea:
$$\nabla \cdot (\beta \nabla u) = f + \int_{\Gamma} C(s) \delta(x - X(s)) ds$$

or $\nabla \cdot (\beta \nabla u) = f, [u] = 0, [\beta u_n] = C(s)$

or $\Delta u = \frac{f}{\beta} + \int_{\Gamma} \frac{C(s)}{?} \delta(x - X(s)) ds$

- Idea of the method: divide β from the equation to get Poisson eqn., but can not from the flux jump.

- Set $[u_n] = g$ as unknown, the augmented variable, the augmented equation is the flux jump condition

Fast IIM

- Idea, given $[u_n] = g$ solve the problem with one FFT

$$AU + BG = F + C = F_1$$

- Discretize the flux condition $[\beta u_n] = v$

$$SU + EG = F_2$$

- Schur complement:

$$(E - SA^{-1}B)G = F_2 - SA^{-1}F_1 = \bar{F}$$

$$\begin{bmatrix} A & B \\ S & E \end{bmatrix} \begin{bmatrix} U \\ G \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$

$$R(G) - R(0) = (E - SA^{-1}B)G = [\beta u_n(G)] - C - ([\beta u_n(0)] - C)$$

Properties of FIIM

- Second solution, proved
- $O(N \log(N))$ optimal computation cost.
The Number of GMRES iterations
 - Independent of jump in the coefficient
 - Independent of the mesh size
 - Dependent on the geometry
- **Second** order accurate 1st order derivatives, observed before, now we have proof.

Challenges with *Variable Coef*

- *Maximum* preserving FD scheme (*direct*) for

$$\nabla \cdot (\beta \nabla u) + \sigma u = f$$

$$[u] = w, \quad [\beta u_n] = v$$

- 5-point at regular, 9-point stencil at irregular grids
- Using a *quadratic* optimization to force the maximum principle (Li/Ito)
- Using a structured multigrid method to solve the linear system whose condition is proportional to $O(\max(\beta^+/\beta^-, \beta^-/\beta^+) / h^2)$.
- *The derivative is often 1st order accurate near the interface*

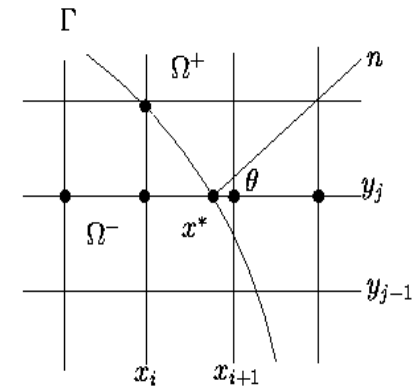
New Method

□ Reformulate the problem:

$$\nabla \cdot (\beta \nabla u) + \sigma u = f, \quad [u] = w, \quad [\beta u_n] = v$$

$$\rightarrow \Delta u + \frac{1}{\beta} \nabla u \cdot \nabla \beta + \frac{\sigma}{\beta} u = \frac{f}{\beta}$$

$$[u] = w, \quad [u_n] = q, \quad [\beta u_n] = v$$



□ Conservative FD scheme at regular grid

$$\frac{\beta_{i-1/2,j} u_{i-1,j} + \beta_{i+1/2,j} u_{i+1,j} + \beta_{i,j-1/2} u_{i,j-1} + \beta_{i,j+1/2} u_{i,j+1} - \bar{\beta} u_{i,j}}{\bar{\beta} h^2} + \frac{\sigma_{ij}}{\bar{\beta}} U_{ij} = \frac{f_{ij}}{\bar{\beta}}$$

$$\bar{\beta} = \beta_{i-1/2,j} + \beta_{i+1/2,j} + \beta_{i,j-1/2} + \beta_{i,j+1/2}$$

FD scheme at irregular grid

□ Regular method + corrections

$$\frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h^2} = u_{xx}(x_i, y_j) + \frac{[u]}{h^2} + \frac{[u_x]}{h^2}(x_{i+1} - x_i^*) + \frac{[u_{xx}]}{2h^2}(x_{i+1} - x_i^*)^2 + O(h)$$

□ We know $[u]$, if we know $[u_\eta]$, then we know $[u_x]$ and $[u_y]$; how about $[u_{xx}]$?

$$u_{\xi\xi}^+ = \left(\frac{\beta_\xi^-}{\beta^+} - \chi'' \right) u_\xi^- + \left(\chi'' - \frac{\beta_\xi^+}{\beta^+} \right) u_\xi^+ + \frac{\beta_\eta^-}{\beta^+} u_\eta^- - \frac{\beta_\eta^+}{\beta^+} u_\eta^+ \\ + (\rho - 1) u_{\eta\eta}^- + \rho u_{\xi\xi}^- - w'' + \frac{[f]}{\beta^+} + \frac{[\sigma] u^- + \sigma^+ [u]}{\beta^+},$$

$$u_{\eta\eta}^+ = u_{\eta\eta}^- + (u_\xi^- - u_\xi^+) \chi'' + w'',$$

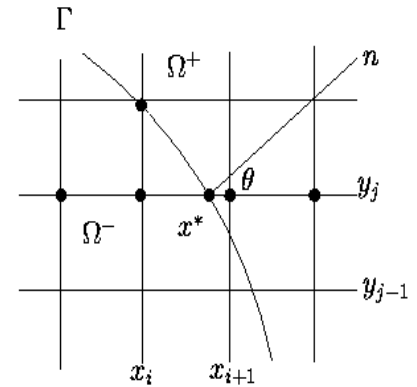
$$u_{\xi\eta}^+ = \frac{\beta_\eta^-}{\beta^+} u_\xi^- - \frac{\beta_\eta^+}{\beta^+} u_\xi^+ + (u_\eta^+ - \rho u_\eta^-) \chi'' + \rho u_{\xi\eta}^- + \frac{v'}{\beta^+},$$

How to get second order jumps?

□ Key: Use the transformed eqn

$$\Delta u + \frac{1}{\beta} \nabla u \cdot \nabla \beta + \frac{\sigma}{\beta} u = \frac{f}{\beta}$$

$$[u] = w, [u_n] = q, [\beta u_n] = v$$



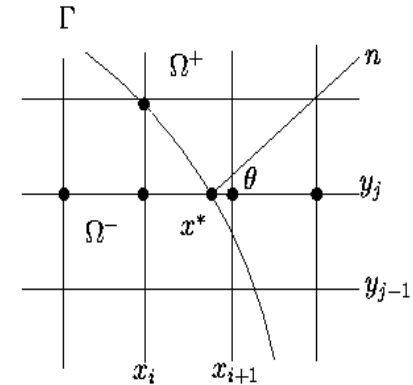
□ Use the local coordinates and lower order jumps and quantities

$$u_{\xi\xi}^+ = u_{\xi\xi}^- + \frac{\beta_{\xi}^-}{\beta^+} u_{\xi}^- - \frac{\beta_{\xi}^+}{\beta^+} u_{\xi}^+ - [u_n] \kappa + \dots$$

$$u_{\eta\eta}^+ = u_{\eta\eta}^- - [u_n] \kappa + [w]''$$

$$u_{\xi\eta}^+ = u_{\xi\eta}^- + \frac{\beta_{\eta}^-}{\beta^+} u_{\xi}^- - \frac{\beta_{\eta}^+}{\beta^+} u_{\xi}^+ - [u_n] \kappa + \frac{[u_n]'}{\beta^+}$$

How to get jumps in x-y direction?



$$[u_x] = [u_\xi] \cos \theta - [u_\eta] \sin \theta,$$

$$[u_y] = [u_\xi] \sin \theta + [u_\eta] \cos \theta,$$

$$[u_{xx}] = [u_{\xi\xi}] \cos^2 \theta - 2[u_{\xi\eta}] \cos \theta \sin \theta + [u_{\eta\eta}] \sin^2 \theta,$$

$$[u_{yy}] = [u_{\xi\xi}] \sin^2 \theta + 2[u_{\xi\eta}] \cos \theta \sin \theta + [u_{\eta\eta}] \cos^2 \theta.$$

How to approximate lower order terms?

- To deal with $u_x \beta_x$, $u_y \beta_y$, u_ξ^- , u_η^- , we use upwinding discretization so that we get an ***M-matrix***, more diagonally dominant

$$x_j \leq \alpha < x_{j+1}$$

$$[u_{xx}] = \left[\frac{f}{\beta} \right] - \frac{\beta_x^+}{\beta^+} [u_x] - \left[\frac{\beta_x}{\beta} \right] u_x^-$$

FD scheme

$$[u_{xx}] \approx \begin{cases} \left[\frac{f}{\beta} \right] - \frac{\beta_x^+}{\beta^+} G - \left[\frac{\beta_x}{\beta} \right] \frac{U_j - U_{j-1}}{h} & \text{if } \left[\frac{\beta_x}{\beta} \right] \leq 0 \\ \left[\frac{f}{\beta} \right] - \frac{\beta_x^+}{\beta^+} [u_x] - \left[\frac{\beta_x}{\beta} \right] \left(\frac{U_{j+1} - U_j}{h} + C_j \right) & \text{otherwise} \end{cases}$$

Use GMRES to solve the Schur complement

- Matrix-vector form: $AU + BG = F_1$
- Use a second order least square interpolation to discretize $[\beta u_n] = v$

$$SU + EG = F_2$$

$$\begin{bmatrix} A & B \\ S & E \end{bmatrix} \begin{bmatrix} U \\ G \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$

- Put together
- Schur complement

$$(E - SA^{-1}B)G = F_2 - SA^{-1}F_1 = \bar{F}$$

A new preconditioner

- Efficient one for FIIM, it does not work well for variable coef.

$$\text{If } \beta^+ < \beta^- \left\{ \begin{array}{l} U_n^+ \text{ is computed from interpolation} \\ U_n^- = \frac{v - \beta^- G}{[\beta]} \text{ from the flux condition} \end{array} \right.$$

New one: Simple scaling

$$\frac{\beta^+ U_n^+ - \beta^- U_n^-}{\bar{\beta}} - \frac{v}{\bar{\beta}} = 0, \quad \bar{\beta} = \frac{\beta^+ + \beta^-}{2}$$

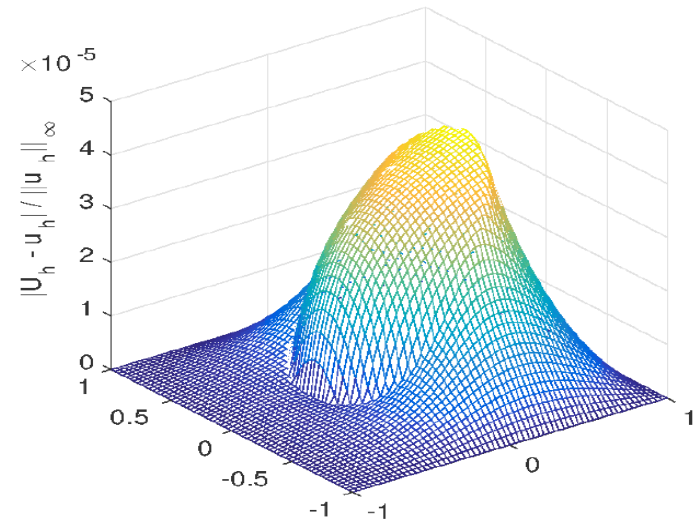
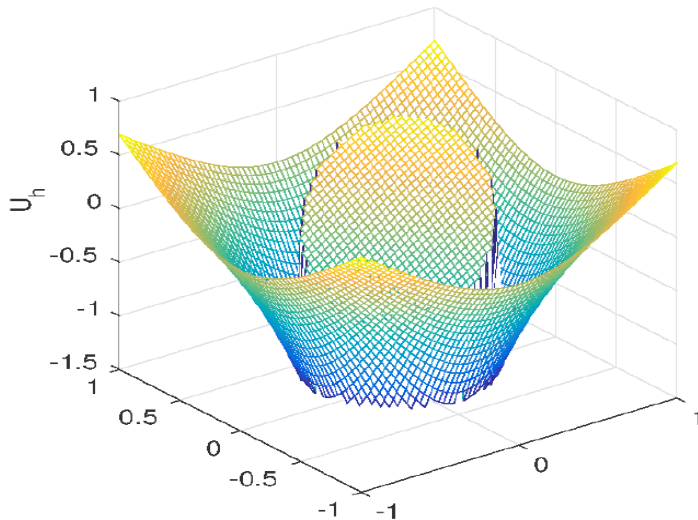
Numerical examples

$$u(x, y) = \begin{cases} \sin(x + y) & \text{if } x^2 + y^2 \leq 1 \\ \log(x^2 + y^2) & \text{if } x^2 + y^2 > 1 \end{cases}$$

$$\beta(x, y) = \begin{cases} e^{10x} & \text{if } x^2 + y^2 \leq 1 \\ \sin(x + y) + 2 & \text{if } x^2 + y^2 > 1 \end{cases}$$

Numerical Example I

N_{finest}	N_b	$E(U)$	$order$	$E(U_{\mathbf{n}}^+)$	$order$	$E(U_{\mathbf{n}}^-)$	$order$	Iter	CPU(s)
66	96	0.28805E-01		0.88682E-01		0.12769E-01		8	0.160
130	184	0.98473E-02	1.58	0.32375E-01	1.49	0.46012E-02	1.51	8	0.533
258	368	0.25642E-02	1.96	0.88674E-02	1.89	0.13434E-02	1.80	8	2.272
514	728	0.66291E-03	1.96	0.23339E-02	1.94	0.35159E-03	1.94	8	11.284
1026	1452	0.16604E-03	2.00	0.58702E-03	2.00	0.88848E-04	1.99	8	38.851
2050	2900	0.42837E-04	1.96	0.15218E-03	1.95	0.22854E-04	1.96	8	174.056



A benchmark example

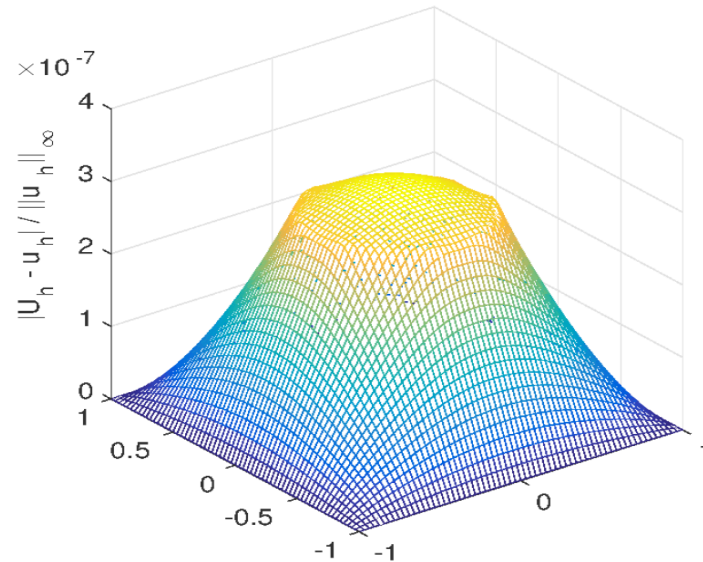
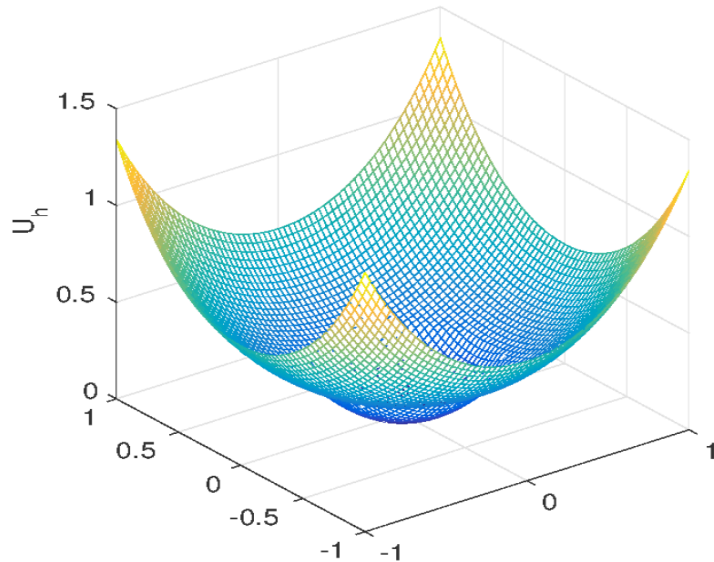
$$u(x, y) = \begin{cases} x^2 + y^2 & \text{if } x^2 + y^2 \leq 1 \\ \frac{1}{4} \left(1 - \frac{9}{8b} \right) + \frac{r^4 / 2 + r^2}{b} + \frac{C \log(r)}{b} & \text{if } x^2 + y^2 > 1 \end{cases}$$

$$\beta(x, y) = \begin{cases} b & \text{if } x^2 + y^2 \leq 1 \\ x^2 + y^2 + 1 & \text{if } x^2 + y^2 > 1 \end{cases}$$

$$\sigma(x, y) = 0, \quad f(x) = 8(x^2 + y^2) + 4$$

Results of benchmark example

N_{finest}	N_b	$E(U)$	$order$	$E(U_{\mathbf{n}}^+)$	$order$	$E(U_{\mathbf{n}}^-)$	$order$	Iter	CPU(s)
66	96	0.11806E-02		0.10858E-01		0.93667E-02		6	0.103
130	188	0.29244E-03	2.06	0.29057E-02	1.94	0.25065E-02	1.94	6	0.342
258	368	0.71380E-04	2.06	0.70487E-03	2.07	0.60806E-03	2.07	5	1.258
514	732	0.16640E-04	2.11	0.17465E-03	2.02	0.15052E-03	2.03	5	5.540
1026	1456	0.41334E-05	2.01	0.44847E-04	1.97	0.38020E-04	1.99	4	20.863
2050	2908	0.10796E-05	1.94	0.11771E-04	1.93	0.98363E-05	1.95	4	201.511



A more general example

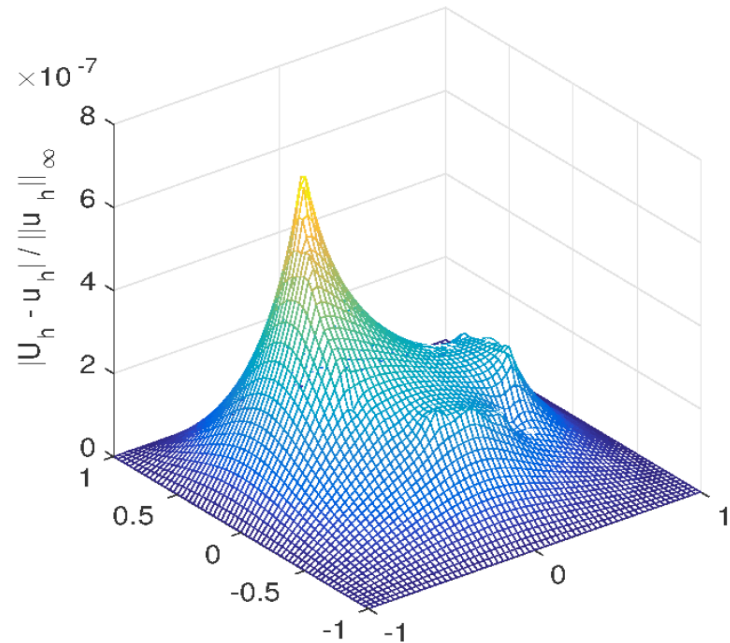
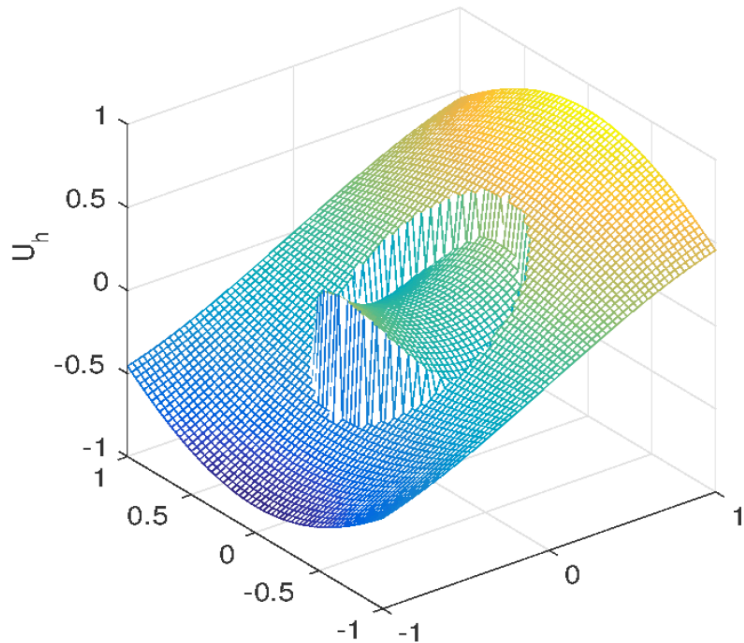
$$u(x, y) = \begin{cases} x^2 - y^2 & \text{if } x^2 + y^2 \leq 1 \\ \sin x \cos y & \text{if } x^2 + y^2 > 1 \end{cases}$$

$$\beta(x, y) = \begin{cases} e^x & \text{if } x^2 + y^2 \leq 1 \\ x^2 + y^2 = 1 & \text{if } x^2 + y^2 > 1 \end{cases}$$

$$-\sigma(x, y) = \begin{cases} \sqrt{x^2 + 4y^2} & \text{if } x^2 + y^2 \leq 1 \\ \log(x^2 + y^2 + 1) & \text{if } x^2 + y^2 > 1 \end{cases}$$

Grid refinement analysis

N_{finest}	N_b	$E(U)$	$order$	$E(U_n^+)$	$order$	$E(U_n^-)$	$order$	Iter	CPU(s)
66	96	0.85969D-03		0.95542D-02		0.59623D-02		4	0.077
130	184	0.18786E-03	2.24	0.25599E-02	1.94	0.15968E-02	1.94	4	0.318
258	368	0.55591E-04	1.78	0.74684E-03	1.80	0.49691E-03	1.70	4	1.272
514	728	0.12783E-04	2.13	0.18721E-03	2.01	0.12500E-03	2.00	4	6.473
1026	1452	0.26051E-05	2.30	0.46393E-04	2.02	0.31318E-04	2.00	4	23.586
2050	2900	0.74611E-06	1.81	0.11647E-04	2.00	0.81641E-05	1.94	4	107.544



A complicated interface

$$u(x, y) = \begin{cases} x^2 + y^2 & \text{if } x^2 + y^2 \leq 1 \\ \frac{r^4}{b} + \frac{C \log(r)}{b} & \text{if } x^2 + y^2 > 1 \end{cases}$$

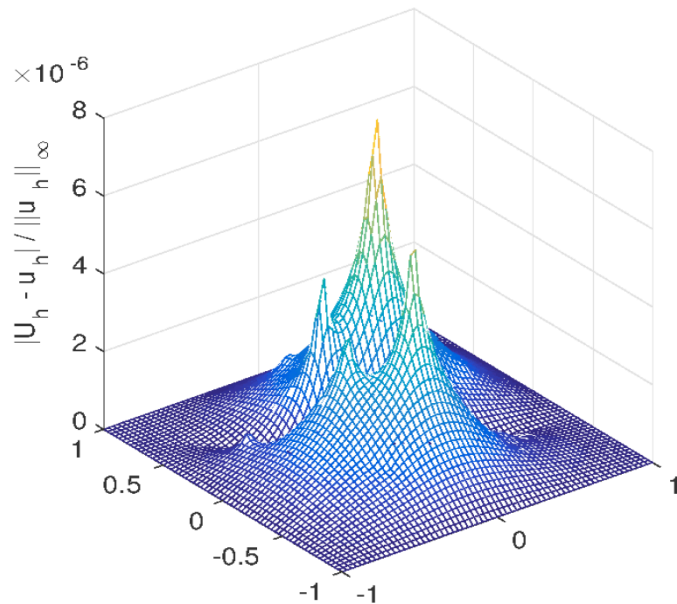
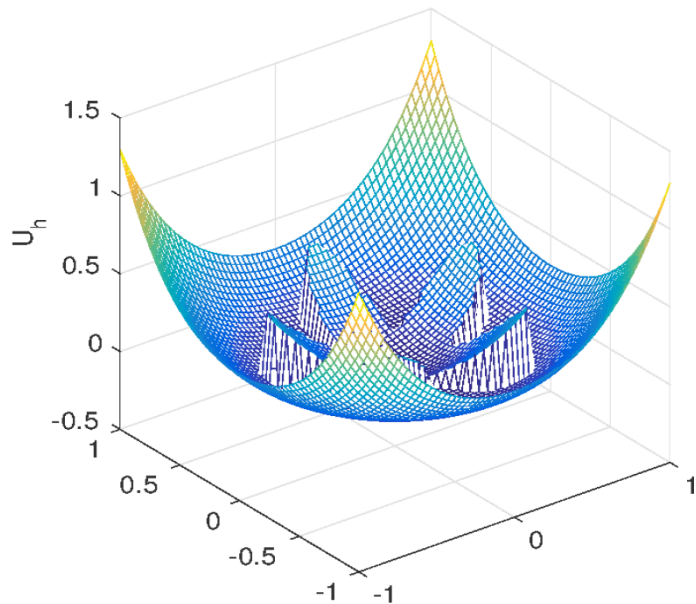
$$\beta(x, y) = \begin{cases} b & \text{if } x^2 + y^2 \leq 1 \\ x^2 + y^2 + 1 & \text{if } x^2 + y^2 > 1 \end{cases}$$

$$X = (r_0 + \varepsilon \sin(k\theta)) \cos(\theta), \quad k = 5$$

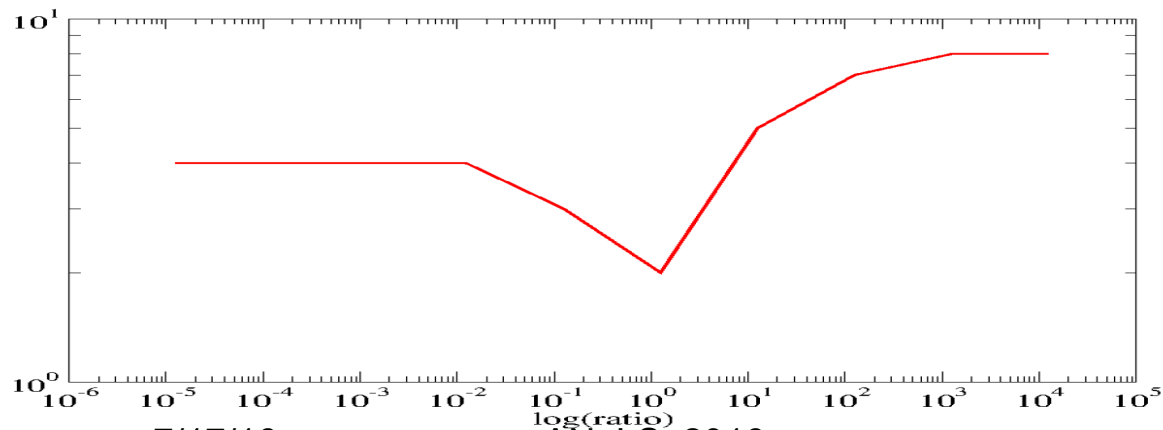
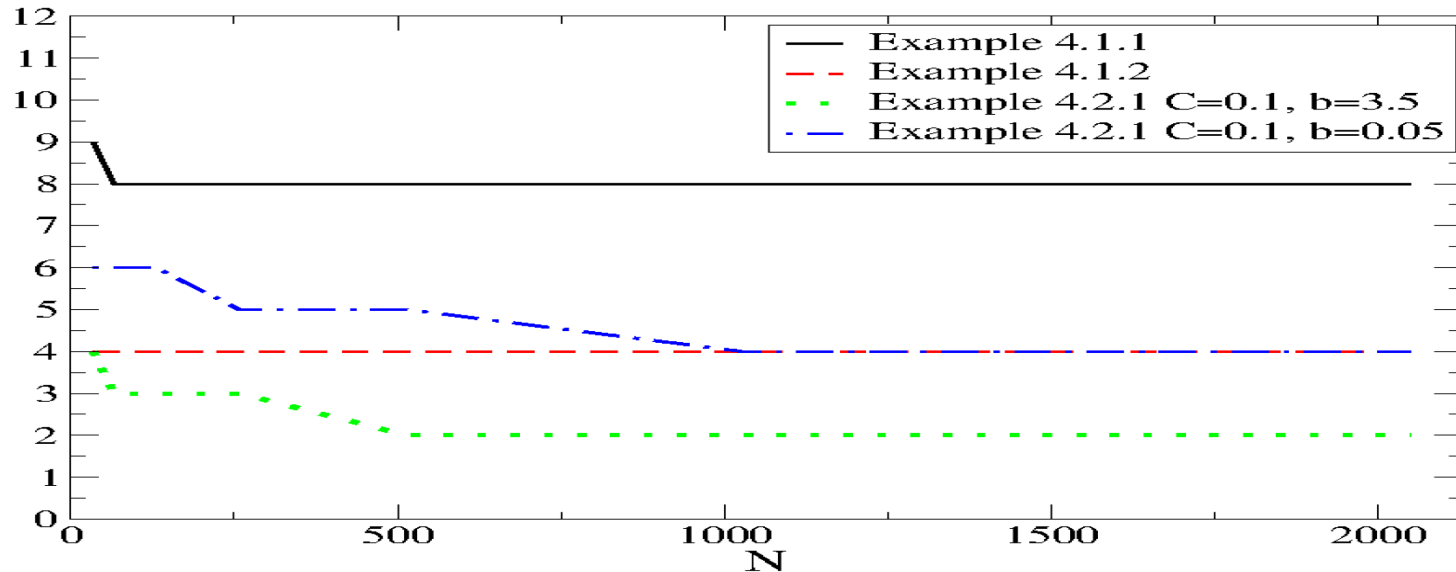
$$Y = (r_0 + \varepsilon \sin(k\theta)) \sin(\theta), \quad r_0 = 0.5, \quad \varepsilon = 0.2$$

Results for Complicated Γ

N_{finest}	N_b	$E(U)$	$order$	$E(U_{\mathbf{n}}^+)$	$order$	$E(U_{\mathbf{n}}^-)$	$order$	Iter	CPU(s)
130	312	0.36754E-02		0.23305E+00		0.26544E+00		7	0.576
258	618	0.10946E-02	1.77	0.55982E-01	2.08	0.63760E-01	2.08	7	2.175
514	1230	0.17091E-03	2.69	0.15400E-01	1.87	0.17541E-01	1.87	7	13.775
1026	2452	0.30145E-04	2.51	0.42371E-02	1.87	0.48265E-02	1.87	7	41.462
2050	4898	0.92522E-05	1.71	0.10589E-02	2.00	0.12065E-02	2.00	7	276.882



Number of GMRES Iteration



Convergence Analysis

- Discrete Green function for 1D problem, the Schur complement is non-singular if $[\beta] \neq 0$.
- Thm: If \mathbf{G} is a second order accurate $O(h^2)$, then \mathbf{u}_h and \mathbf{u}_h' is also second order in L-infinity norm (from comparison theorem and Beale's proof)
- Thm: If the interpolation scheme is second order for $[\beta \mathbf{u}_x] = \mathbf{v}$, then computed $[\mathbf{u}_x]$ is also second order. Thus \mathbf{u}_h is also second order.

Discrete Green functions for piecewise constant coef

$$G(x, y) = \begin{cases} x(1-y) & \text{if } x \leq \alpha \\ y(1-x) & \text{if } x > \alpha \end{cases}$$

$$A_{ij}^{-1} = hG(x_i, x_j)$$

$$E_i^u = h \sum_{j=1}^N f_j^u G(x_i, x_j)$$

Property of Schur complement

$$(D - CA^{-1}B) = [\beta u_x]_{[u_x]=1} - [\beta u_x]_{[u_x]=0}$$

$$(D - CA^{-1}B)E^q = -\tau^q - CA^{-1}\tau^u$$

$$\tau^u = \tau_{reg}^u + \tau_{ireg}^u = O(h^2) + O(h)$$

$$A^{-1}\tau^u = O(h^2), \quad CA^{-1}\tau^u = O(h^2)$$

Conclusions

- A new method for general elliptic interface problem with both 2nd order solution and the first order derivatives
 - Introduce an augmented variable
 - A second order discretization leading to an M-matrix plus a second interpolation scheme for the flux
 - No optimization is needed
 - The number of GMRES iteration is independent of the mesh size and jump in the coefficient
 - Convergence proof
- Best method in FD using Cartesian meshes? (accept challenges!)
- Second order derivatives (curvature etc)
- Q: Why does the preconditioning work so well?

Thank you!

Solving Poisson Eqn. (regular)

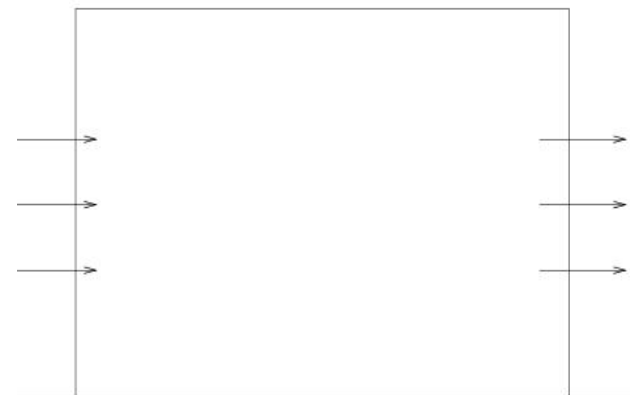
- Regular domain (rectangular, circles,..), no interface/singularity

$$\Delta u = f(x)$$

BC (e.g. Dirichlet, Neuman, Mixed)

- The FD scheme at (x_i, y_j)

$$\frac{u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} - 4u_{i,j}}{h^2} = L_h u_{i,j} = f_{ij}$$



- **$AU=F$** ; **A** : Discrete Laplacian. Can be solved by a fast Poisson solver (e.g. FFT, $O(N^2)\log(N)$), e.g., Fish-pack, or structured multigrid

Flow chart to the new method

Regular Problem/Regular Method \leftrightarrow

Interface Problem with Singular Source

(Regular Method + Correction Terms)

$\leftrightarrow [\beta] \neq 0$, Augmented variable $[u_n]$

(bigger equations) *and* interpolation of

the flux condition (smaller equation) \leftrightarrow

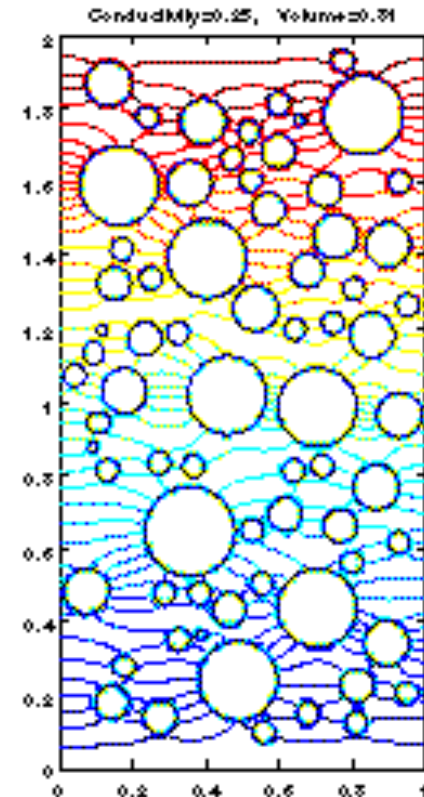
Schur complement (GMRES iteration + preconditioning)

Some Examples of Irregular Domain

- Estimate the permeability of concrete (IMSM problem): 5 minutes to solve the Laplace eqn. external to the particles! Compared with Monte Carlo estimates (168 hrs.)

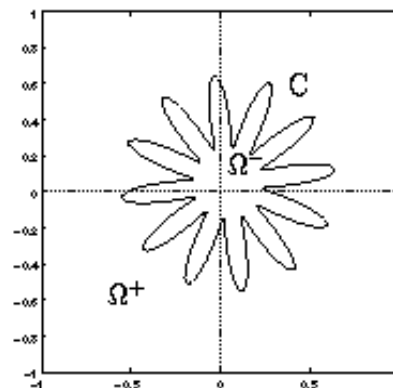
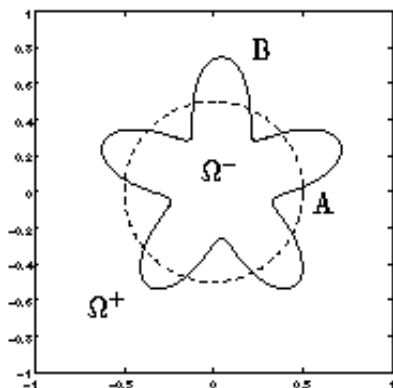
$$\Delta u = 0,$$

$$u|_R = 0, \quad u_n = C, \quad u_n = 0 \quad \text{etc.}$$



An example of Fast IIM

□ Interface: $r(\theta) = r_0 + 0.2 \sin(k\theta), \quad 0 \leq \theta \leq 2\pi$



□ Exact soln:

$$u(\mathbf{x}, y) = \begin{cases} \frac{r^2}{\beta^-} & \text{if } (\mathbf{x}, y) \in \Omega^- \\ \frac{r^2 + C_0 \log(2r)}{\beta^+} + C_1 \left(\frac{r_0^2}{\beta^-} - \frac{r_0^2 + C_0 \log(2r_0)}{\beta^+} \right) & \text{if } (\mathbf{x}, y) \in \Omega^+, \end{cases}$$

An example of Fast IIM

n	β^+	β^-	E_1	E_2	E_3	r_1	r_2	r_3	k
40	2	1	$2.285 \cdot 10^{-9}$	$2.23 \cdot 10^{-9}$	$7.434 \cdot 10^{-9}$				7
80	2	1	$5.225 \cdot 10^{-4}$	$5.956 \cdot 10^{-9}$	$1.987 \cdot 10^{-2}$	4.37	3.74	3.74	7
160	2	1	$1.269 \cdot 10^{-4}$	$1.827 \cdot 10^{-4}$	$6.101 \cdot 10^{-4}$	4.12	3.26	3.26	7
320	2	1	$2.988 \cdot 10^{-5}$	$5.038 \cdot 10^{-5}$	$1.678 \cdot 10^{-4}$	4.25	3.63	3.64	7

n	β^+	β^-	E_1	E_2	E_3	r_1	r_2	r_3	k
40	10000	1	$6.552 \cdot 10^{-6}$	$6.331 \cdot 10^{-4}$	$2.110 \cdot 10^{-4}$				8
80	10000	1	$7.847 \cdot 10^{-6}$	$8.366 \cdot 10^{-5}$	$2.785 \cdot 10^{-5}$	8.35	7.57	7.58	8
160	10000	1	$5.988 \cdot 10^{-7}$	$9.192 \cdot 10^{-7}$	$3.033 \cdot 10^{-6}$	13.1	9.10	9.18	8
320	10000	1	$5.859 \cdot 10^{-8}$	$2.058 \cdot 10^{-7}$	$6.887 \cdot 10^{-7}$	10.2	4.47	4.40	7

Special Cases & Idea

- If $\beta=1$, then *IIM* has both second order solution and derivatives (Beale/Layton)
- If β is a piecewise constant (e.g. 1000:1 or 1:1000), then the augmented IIM has both second order solution & derivatives (observed before and has been proved now)
 - *I think it is the **best** Cartesian method with optimal cost?*
- What's new: *second order solution & derivative for variable coefficients with proof based on the augmented IIM*