



Cluster-based reduced-order modelling

From shear flows to engine tumble motion

E. Kaiser^{1,7} B. R. Noack¹ L. Cordier¹ A. Spohn¹ M. Segond²
 M. Abel² G. Daviller³ J. Östh⁴ S. Krajnović⁴ Y. Cao¹ J. Borée¹
 Lionel Thomas¹ Stéphane Guilain⁵ R. K. Niven⁶ L. N. Cattafesta⁷

¹Institut P^r, CNRS – Université de Poitiers – ENSMA, France, ²Ambrosys GmbH, Germany, ³CERFACS, France

⁴Chalmers University, Sweden, ⁵Renault s.a.s., France, ⁶UNSW/ADFA, Australia, ⁷Florida State University / FCAAP, USA

– supported by TUCOROM, SepaCoDe, Poitou-Charentes/France, PIRE, ADFA@UNSW –

SIAM conference CSE, 14-18 March 2015



Motivation



Brown & Roshko (1974)



Barros et al. (2014)

How can we identify physical mechanisms in an unsupervised manner directly from data?

- ▶ Analysis of physical mechanisms.
- ▶ Quick exploratory studies for optimization and parameter analysis.
- ▶ Robust models for real-time feedback control applications.



Cluster analysis for structure identification

- ▶ Part of pattern recognition/machine learning
How to find a hidden structure or groups in data?
- ▶ Applications: Data compression, Tracking, 3D reconstruction, territorial behavior, etc.
- ▶ Goal: Organize data $\{\mathbf{x}^m\}_{m=1}^M$ into clusters such that there is a
 - high intra-cluster similarity and
 - low inter-cluster similarity
- ▶ What does “similar” mean? E.g.:
 $d(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|_2$
- ▶ What are the points \mathbf{c}_k that generate these subsets?

original

Original Image: Colourful Bird



$K = 3$

k-Means Clustering of 3 Colours



$K = 6$

k-Means Clustering of 6 Colours



K-means algorithm

Given a data points/observations $\{\mathbf{x}^m\}_{m=1}^M$ where $\mathbf{x} = [x_1, \dots, x_N]^T$

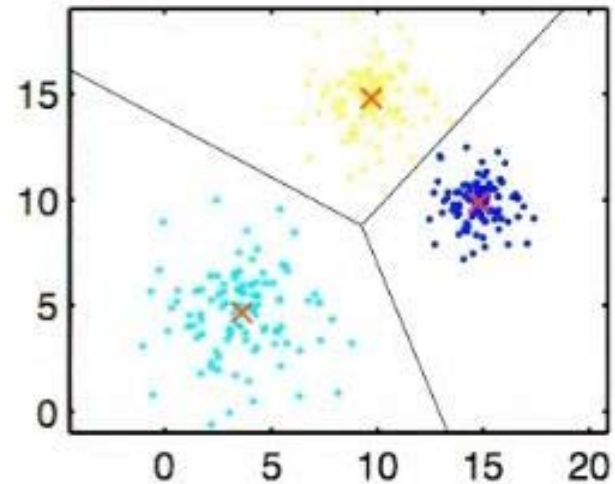
- ▶ **Initialization:** K cluster centers $\mathbf{c}_1, \dots, \mathbf{c}_K$
- ▶ **Assign** each \mathbf{x}^m to its closest cluster center \mathbf{c}_k

- ▶ **Update** each cluster center \mathbf{c}_k

$$\mathbf{c}_k = \frac{1}{n_k} \sum_{\mathbf{x}^m \in \mathcal{C}_k} \mathbf{x}^m$$

- ▶ **Iterate** until converged
- ▶ **Minimization** of total cluster variance

$$J(\mathbf{c}_1, \dots, \mathbf{c}_K) = \sum_{k=1}^K \sum_{\mathbf{x}^m \in \mathcal{C}_k} \|\mathbf{x}^m - \mathbf{c}_k\|^2$$



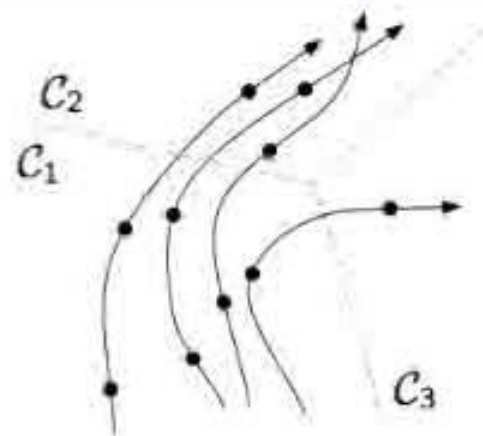
Dynamical model

Cluster transition probability matrix

$$P_{jk} = \frac{n_{jk}}{n_k}$$

$n_{jk} := \#$ of transitions from C_k to C_j

$n_k := \#$ of data points in cluster C_k



- ▶ \mathbf{P} defines a *one-step time-homogeneous Markov chain* where

$$P_{jk} = \text{Prob}(\mathbf{c}_j | \mathbf{c}_k)$$

- ▶ Evolution of probability distribution

$$\mathbf{p}_{m+1} = \mathbf{P} \mathbf{p}_m \quad \rightarrow \quad \mathbf{p}_m = \mathbf{P}^m \mathbf{p}_0$$

- ▶ Convergence to unique, stationary distribution

$$\mathbf{p}_\infty = \lim_{m \rightarrow \infty} \mathbf{P}^m \mathbf{p}_0$$



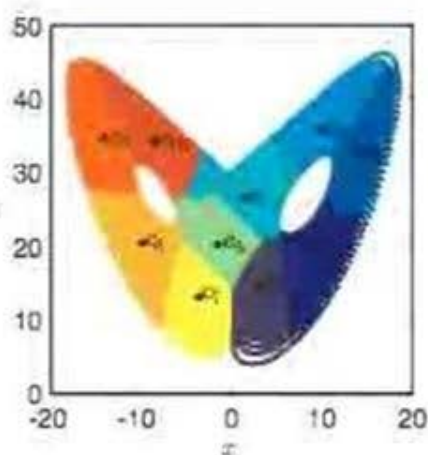
CROM applied to Lorenz attractor data

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Östh, Krajnović, Niven, 2014, JFM

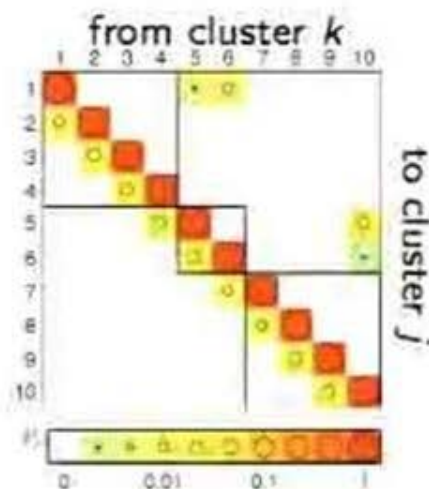
Lorenz system (Lorenz, 1963) with $\sigma = 10$, $\beta = 8/3$ and $\rho = 28$.

Data set: $\mathbf{x}^m := \mathbf{x}(t_m) = [x(t_m), y(t_m), z(t_m)]^T$

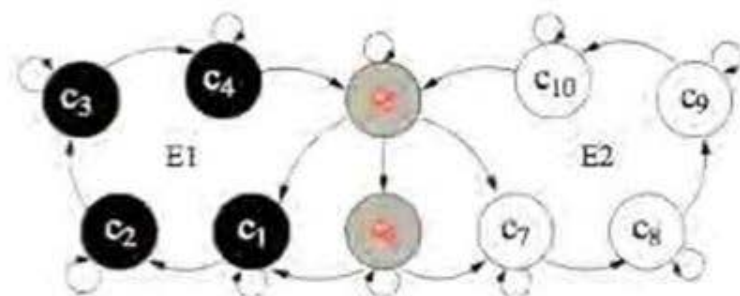
Kinematics



Dynamics



Graphical representation



- ▶ Coarse-grained state space
- ▶ Homogeneous partitioning around fixed points \rightarrow phase averaging
- ▶ Identification of oscillation and transition clusters



Interpretation as generalization of Ulam's method

Dynamical system:

$$\frac{d\mathbf{x}}{dt} = \mathbf{f}(\mathbf{x})$$

Liouville equation:

$$\frac{\partial \rho(\mathbf{x}, t)}{\partial t} = -\nabla \cdot (\mathbf{f}\rho(\mathbf{x}, t)) = \mathcal{L}(\rho(\mathbf{x}, t))$$

Perron-Frobenius operator:

$$\mathcal{P} = \exp(\mathcal{L}t)$$

Ulam-Galerkin method (*Li, 1976, J. Approx. Theory*):

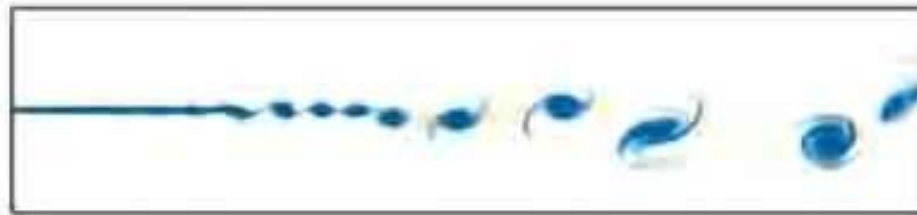
$$P_{jk} = \frac{\text{card}(\{\mathbf{x}^m | \mathbf{x}^m \in B_k \text{ and } \mathbf{f}(\mathbf{x}^m) \in B_j\})}{\text{card}(\{\mathbf{x}^m \in B_k\})}$$

CROM:

- ▶ Low dimension
- ▶ Other distance metrics



Spatially developing mixing layer



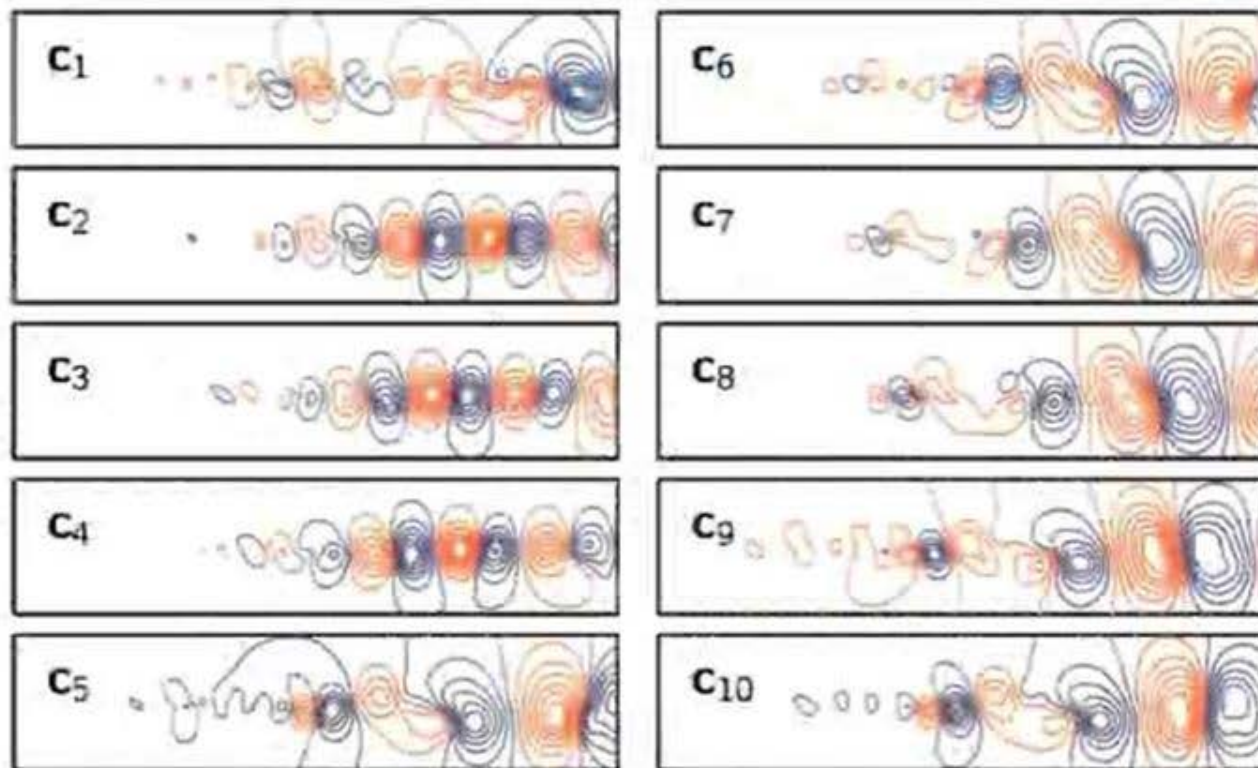
- ▶ 2D mixing layer simulation with Kelvin-Helmholtz vortices undergoing vortex pairing
- ▶ $Re = \Delta U \delta_w / \nu = 500$; $Ma = 0.3$; $r = U_1 / U_2 = 3$
- ▶ Finite-difference Navier-Stokes solver (*Daviller, PhD thesis (2010)*, *Cavalieri et al. (2011)*)
- ▶ Data compression using proper orthogonal decomposition (used for all following examples)



CROM of the mixing layer

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Östh, Krajnović, Niven, 2014, JFM

Kinematics: Cluster centroids



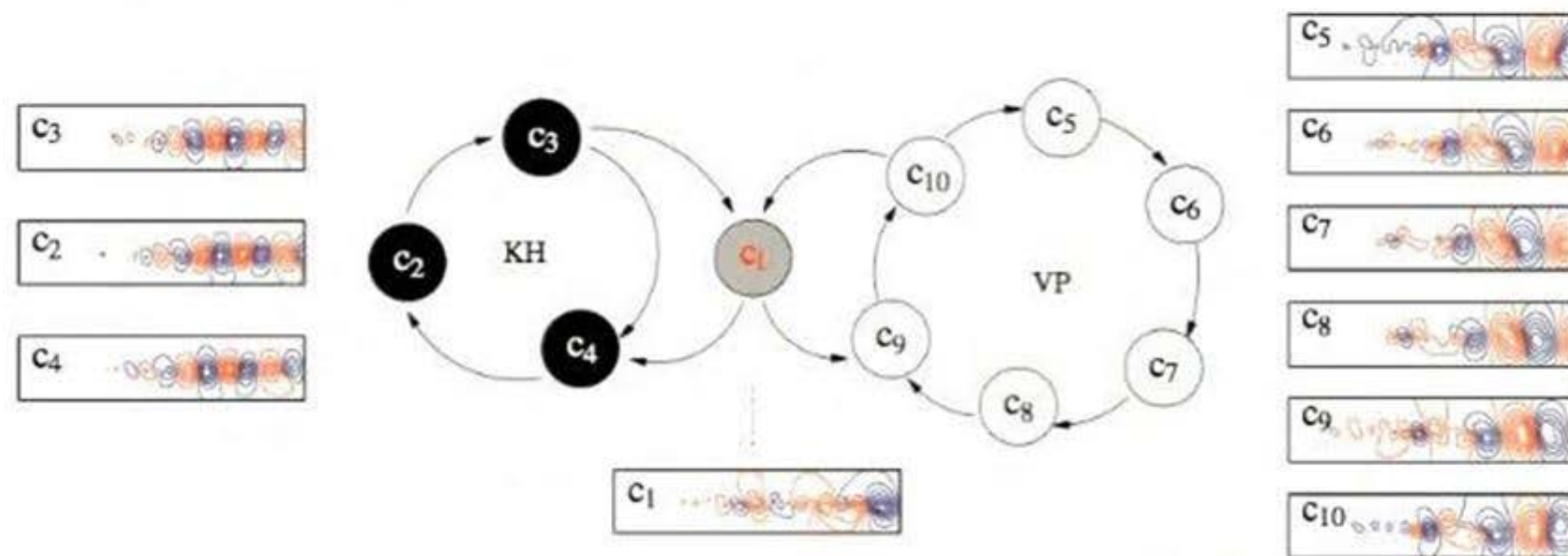
► Most clusters are “phase bins”



CROM of the mixing layer

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Östh, Krajnović, Niven, 2014, JFM

Dynamics: Graph of the transition probability matrix



- ▶ Identification of two shedding regimes.
- ▶ Flipper cluster acts as a switch between both shedding regimes.



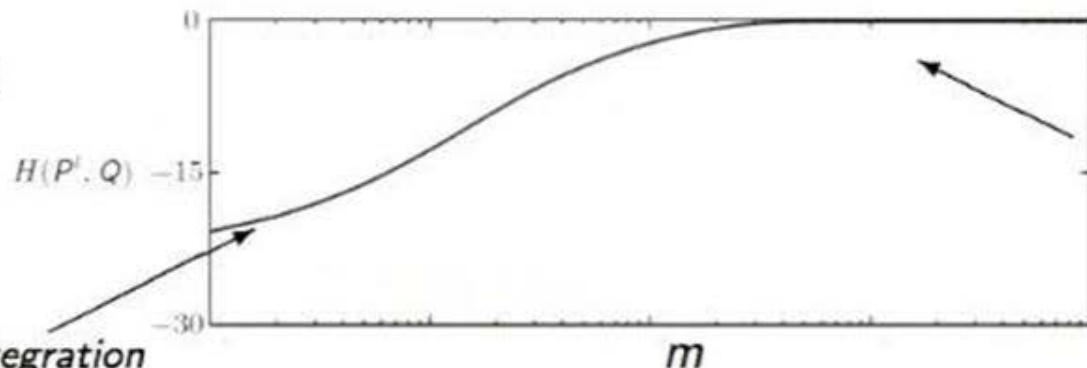
Attractor properties of the mixing layer

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Morzyński, Östth, Krajnović, Niven, 2014, AIP Conf. Proc. (MaxEnt2013)

Analysis of model convergence to its asymptotic state via relative entropy (negative of Kullback-Leibler function D):

$$H(\mathbf{P}^m, \mathbf{Q}) = -D(\mathbf{P}, \mathbf{Q}) := - \sum_{j=1}^K \sum_{k=1}^K P_{jk}^m \ln \frac{P_{jk}^m}{Q_{jk}}$$

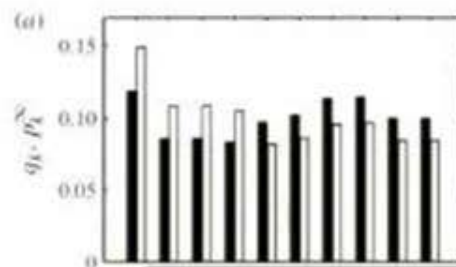
Transients:



All information on initial conditions is lost

Backwards integration possible

Attractor:



■ Model

□ Data

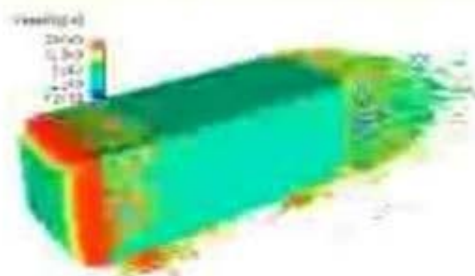
Probability distributions: Model \mathbf{p}_∞ compared to data \mathbf{q}



Turbulent wake of a bluff body

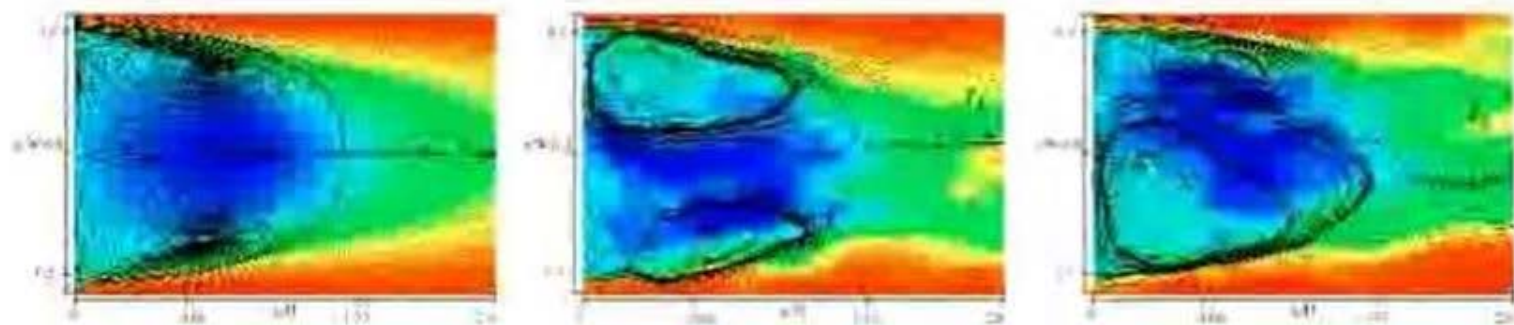
☰ Östh, Noack, Krajnović, Barros & Boreé, 2014, JFM

- ▶ 3D incompressible turbulent flow around a bluff body (finite-volume LES)
- ▶ $Re = U_\infty H/\nu = 3 \times 10^5$
- ▶ Data compression using POD



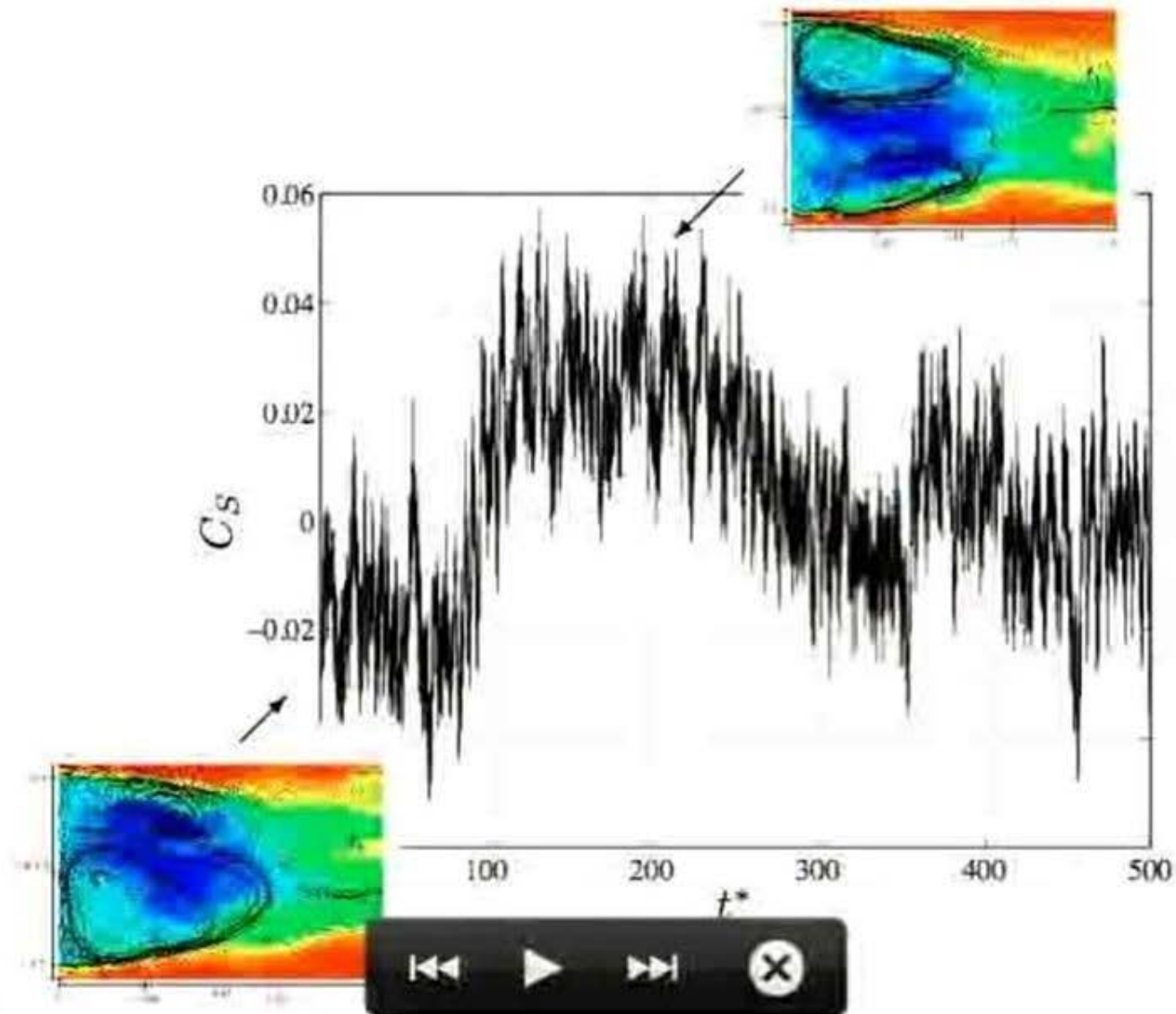
Bi-modal behaviour of the wake (*Grandmange et al. 2013*):

Flow changes between two asymmetric states over time scales of order $T_s \approx 100 J/U_\infty \Rightarrow$ Challenge for ROM.



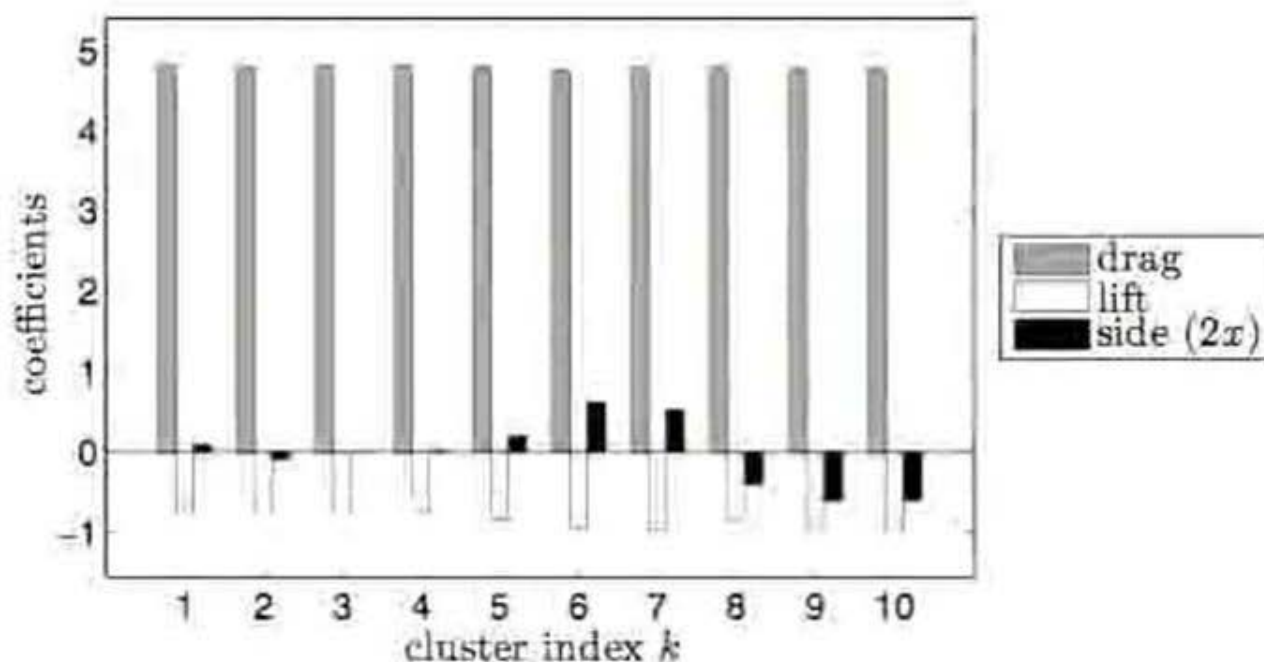
Side force of the bluff body

Östh, Noack, Krajnović, Barros & Boreé, 2014, JFM



Mean cluster forces of the bluff body wake

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Östh, Krajnović, Niven, 2014, JFM

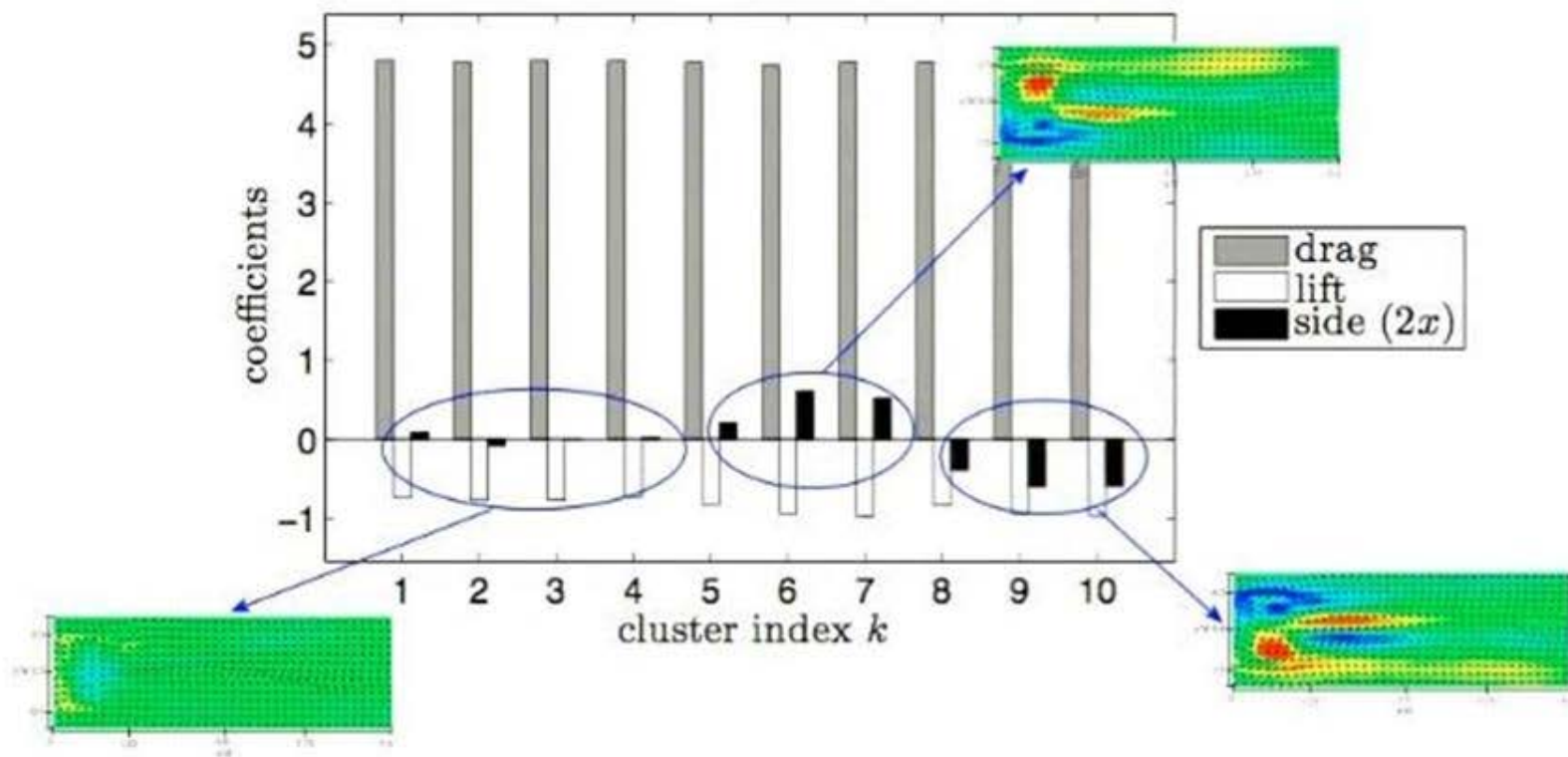


- ▶ Clusters are associated with different mean forces
- ▶ Desirable state space regions



Mean cluster forces of the bluff body wake

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Östh, Krajnović, Niven, 2014, JFM



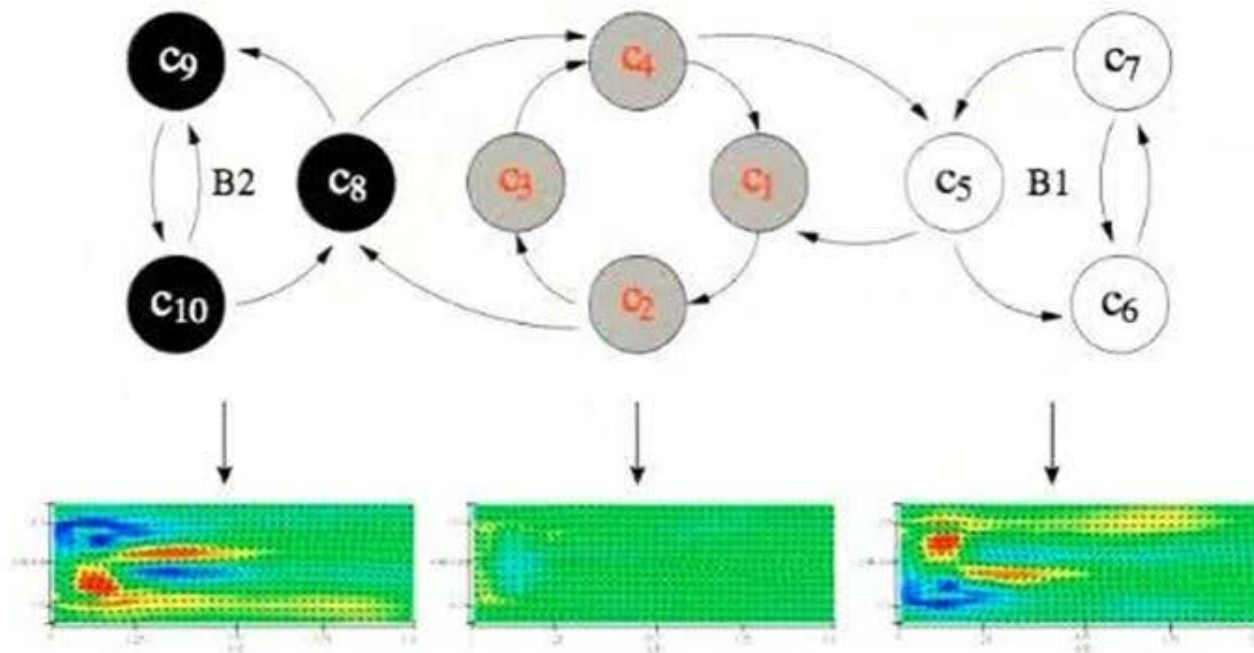
- ▶ Clusters are associated with different mean forces
- ▶ Desirable state space



CROM of the bluff body wake

☰ Kaiser, Noack, Cordier, Spohn, Segond, Abel, Daviller, Östh, Krajnović, Niven, 2014, JFM

Cluster dynamics



- ▶ Bi-modal behavior and transition processes are distilled
- ▶ Identification of branching clusters (C_5 and C_8)



Engine tumble motion of an IC engine

Voisine et al. 2011, *Exp. Fluids*

Four-stroke internal combustion engine

Intake



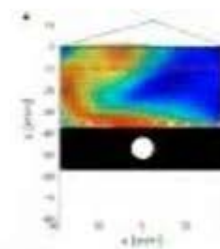
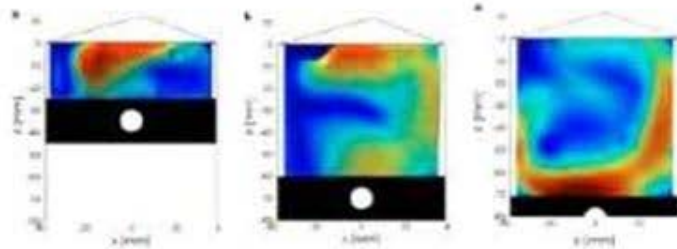
Compression



Ignition



Exhaust



Mid-compression
(270 CAD)

- ▶ Tumble breakdown from large-scale to small-scale structures
- ▶ Large-scale cycle-to-cycle variability effects engine efficiency and emissions

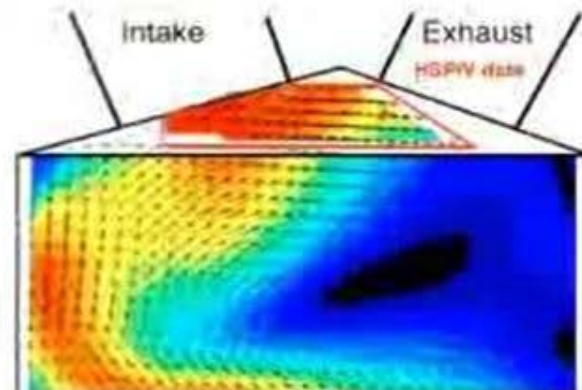


Data set of IC engine

Voisine et al. 2011, Exp. Fluids



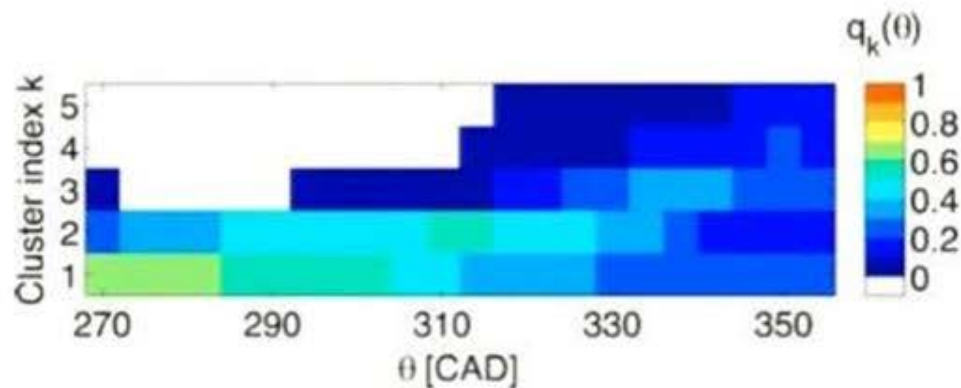
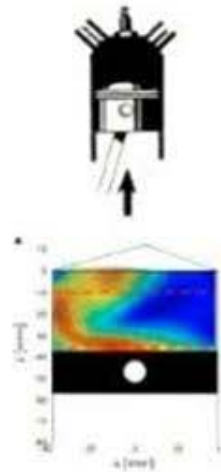
- ▶ HSPIV in symmetry plane of cylinder head/ pent-roof chamber
- ▶ From mid-compression to end of compression phase ($\theta = 270 \dots 354 \text{ CAD}$, $\Delta\theta = 4 \text{ CAD}$)
- ▶ $N = 161$ consecutive engine cycles are measured with $M = 22$ snapshots/cycle



Evolution of cluster probability distribution

☰ Cao, Kaiser, Boree, Noack, Thomas, Guilain, 2014, Exp. Fluids

Mid-Compression



Ignition

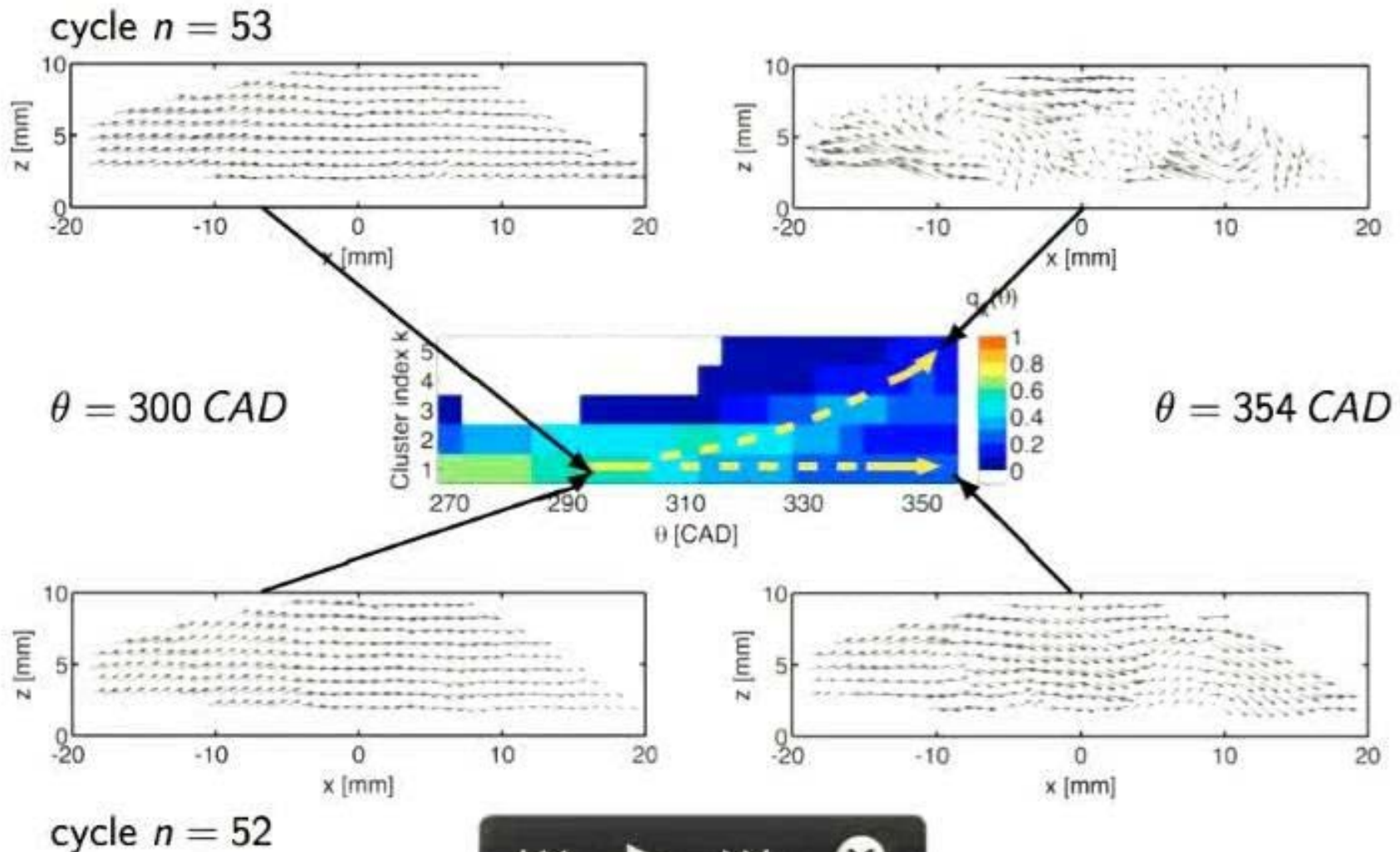


- ▶ Cluster probability $q_k(\theta) = \frac{n_k(\theta)}{N}$
 - $N = 161$: total # cycles
 - $n_k(\theta)$: # snapshots at $\theta \in \mathcal{C}_k$
- ▶ Spreading of flow fields during tumble breakdown
- ▶ Almost uniform PDF at ignition



Large variation of flow patterns at ignition

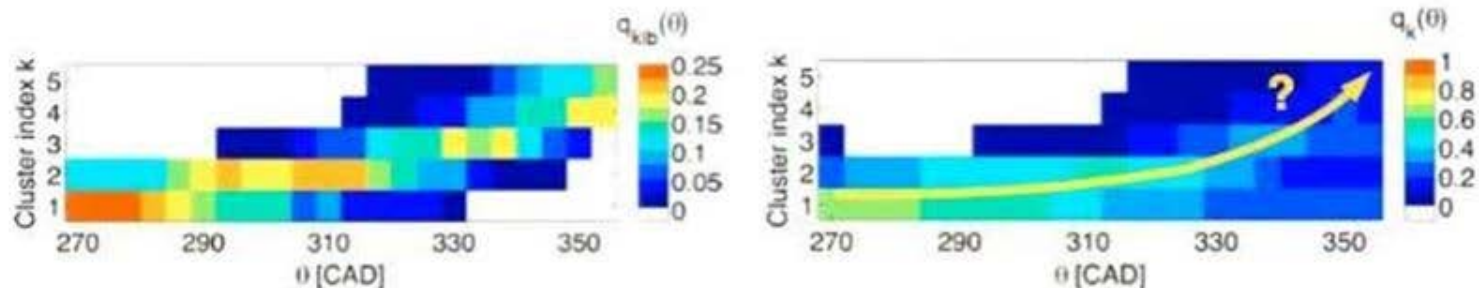
☰ Cao, Kaiser, Boreé, Noack, Thomas, Guilain, 2014 Exp. Fluids



A stable and potentially cleaner engine

☰ Cao, Kaiser, Boreé, Noack, Thomas, Guilain, 2014, Exp. Fluids

- ▶ Identification of important clusters: C_4 and C_5 are the most desirable states for the end of compression phase.



- ▶ Evolution of probability distribution estimated from trajectories ending in C_4/C_5 : Gradual destabilisation of the large-scale flow structures
- ▶ Goal: Completion of tumble breakdown in each cycle



Conclusions and outlook

- ▶ Data-driven approach to extract physical mechanisms in an unsupervised manner
- ▶ Tuning parameters:
 - total number of clusters
 - time step of data
 - distance metric
- ▶ Cluster sociology
- ▶ Linear model taking into account nonlinear actuation dynamics

