



# **SKETCHING BASED MATRIX COMPUTATIONS FOR LARGE-SCALE DATA ANALYSIS**

Haim Avron

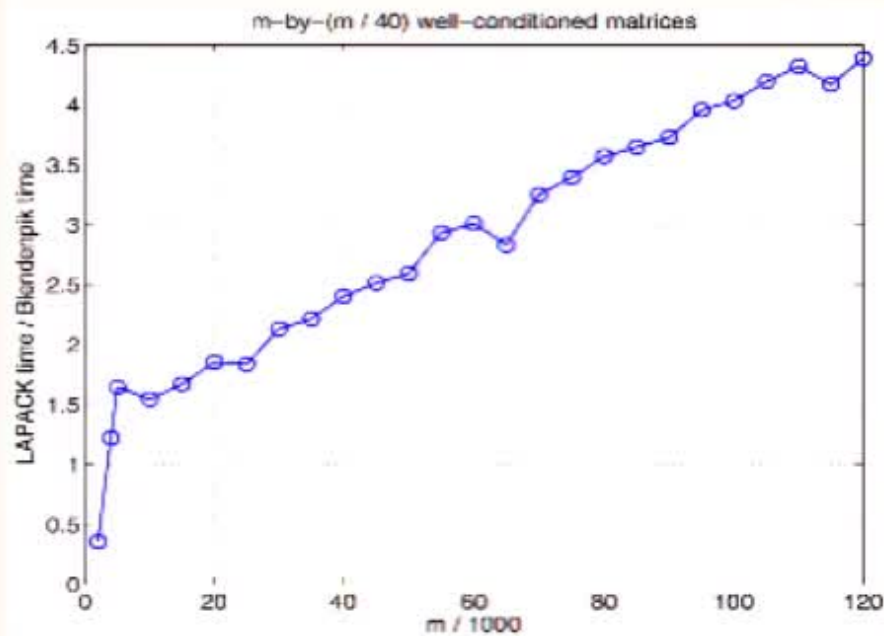
Tel Aviv University

(work performed while at IBM Research)



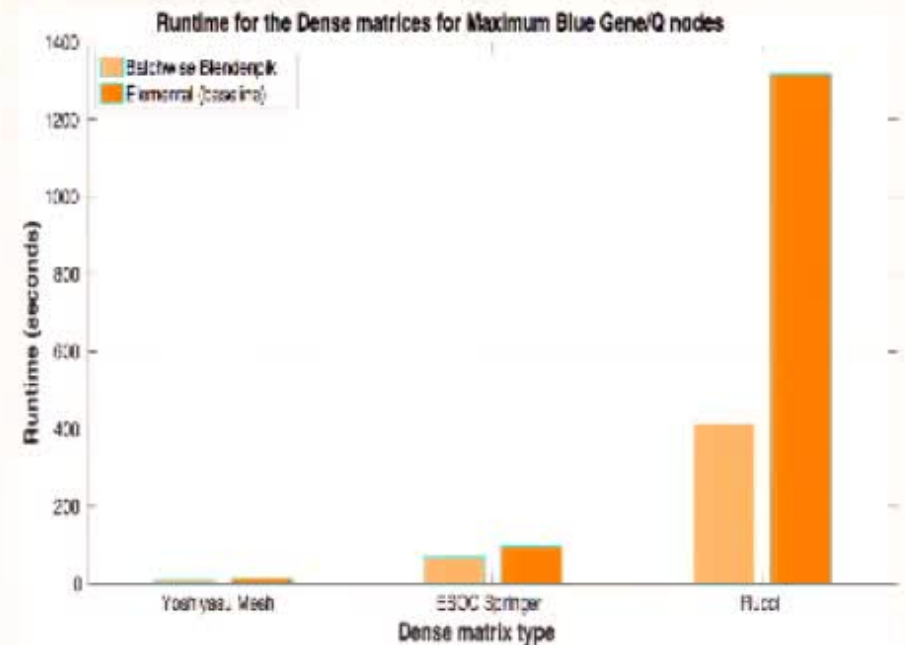
## The Success of Sketching-based Linear Regression

Sequential on a laptop (2009):



(from Avron, Maymounkov and Toledo 2010)

Distributed-memory on BlueGene/Q (2015):



(from Chander et al. 2015)

## Matrix Sketching

- A (randomized) transform that maintains some notion of geometry, e.g. Euclidean distance
$$\|S\mathbf{x}\|_2 = (1 \pm \epsilon)\|\mathbf{x}\|_2,$$
on a subspace, e.g. for all  $\mathbf{x} \in \mathcal{V}$  (with high probability).
- Two 'flavors' of use: "sketch-and-solve" and "sketch-to-precondition".

### Sketch-and-solve:

- Use  $S$  to build a smaller problem, e.g.
$$\tilde{\mathbf{w}} = \operatorname{argmin}_{\mathbf{w}} \|S\mathbf{X}\mathbf{w} - S\mathbf{y}\|_2$$
- Problems:
  - *Not practical for high quality approximations*
  - *Might fail.*
- Advantages:
  - *Very fast for low quality approximations.*
  - *Usually good results for machine learning and data analysis applications.*

### Sketch-to-precondition:

- Use  $S$  to precondition the problem, e.g.
  - *Factorize  $S\mathbf{X} = \mathbf{Q}\mathbf{R}$ .*
  - *Solve*
$$\mathbf{z} = \operatorname{argmin}_{\mathbf{z}} \|\mathbf{X}\mathbf{R}^{-1}\mathbf{z} - \mathbf{y}\|_2.$$
  - *Return  $\mathbf{w} = \mathbf{R}^{-1}\mathbf{z}$ .*
- Advantages:
  - *Fast even for high quality approximations.*
  - *Failure results only in longer running times, and not in bad output.*

## Warm-up: Linear Ridge Regression (also called 'Tikhonov Regularization')

- Suppose  $d \gg n$ , and assume  $\mathbf{X}$  is full rank.
- There are infinite solutions to  $\mathbf{X}\mathbf{w} = \mathbf{y}$ .
- It is common to add a "ridge regularizer" to make the solution unique

$$\mathbf{w} = \arg \min \|\mathbf{X}\mathbf{w} - \mathbf{y}\|_2^2 + \lambda \|\mathbf{w}\|_2^2$$

- Equivalent over-determined least squares:

$$\mathbf{w} = \arg \min \left\| \begin{bmatrix} \mathbf{X} \\ \sqrt{\lambda} \mathbf{I}_d \end{bmatrix} \mathbf{w} - \begin{bmatrix} \mathbf{y} \\ 0 \end{bmatrix} \right\|_2^2$$

- However  $n + d \approx d$  so previously presented algorithms are not applicable.

## Preconditioning by Sketching on the “Right”

- Rewriting the problem:

$$\mathbf{w} = \arg_{\mathbf{w}} \min \|\mathbf{w}\|_2^2 + \|\mathbf{z}\|_2^2 \quad \text{s. t.} \quad \mathbf{X}\mathbf{w} + \sqrt{\lambda}\mathbf{z} = \mathbf{y}$$

- We we need to find the minimum norm solution for  $\hat{\mathbf{X}}\hat{\mathbf{w}} = \mathbf{y}$   
$$\hat{\mathbf{X}} = \begin{bmatrix} \mathbf{X} & \sqrt{\lambda}\mathbf{I}_n \end{bmatrix}$$

- “sketch on the right”:

- Sketch only  $\mathbf{X}$ , compute  $\mathbf{X}\mathbf{S}^T$
- Factorize  $\begin{bmatrix} \mathbf{X}\mathbf{S}^T & \sqrt{\lambda}\mathbf{I}_n \end{bmatrix} = \mathbf{L}\mathbf{Q}$ .
- Use  $\mathbf{L}$  as a preconditioner.

- Remarks:

- Sketching only  $\mathbf{X}$  is motivated by the nonlinear case (later in the talk).
- Keeping the regularizer un-sketched costs very little (and we actually gain from it!).

## Analysis of Sketch-based Preconditioned Ridge Regression (with Clarkson and Woodruff)

- An  $S$  “works” if for a fixed  $A$  and  $B$  and a selected  $c$  we have

$$\|A^T S^T S B - A^T B\|_F \leq c \|A\|_F \|B\|_F$$

with high probability (aka probability of at least  $1 - \delta$ ).

- Sketching dimension (number of rows in  $S$ ) depend on  $c, \delta$  and #rows in  $A$  and  $B$ .

- The relevant condition number is  $\kappa(\mathbf{X}\mathbf{X}^T + \lambda\mathbf{I}_n, \mathbf{X}\mathbf{S}^T\mathbf{S}\mathbf{X}^T + \lambda\mathbf{I}_n)$

- Suppose that  $\mathbf{X} = \mathbf{L}_\lambda \mathbf{Q}_\lambda$  such that  $\mathbf{L}_\lambda \mathbf{L}_\lambda^T = \mathbf{X}\mathbf{X}^T + \lambda\mathbf{I}_n$ . Then,

$$\begin{aligned} \kappa(\mathbf{X}\mathbf{X}^T + \lambda\mathbf{I}_n, \mathbf{X}\mathbf{S}^T\mathbf{S}\mathbf{X}^T + \lambda\mathbf{I}_n) &= \kappa(\mathbf{X}\mathbf{S}^T\mathbf{S}\mathbf{X}^T + \lambda\mathbf{I}_n, \mathbf{X}\mathbf{X}^T + \lambda\mathbf{I}_n) = \kappa(\mathbf{X}\mathbf{S}^T\mathbf{S}\mathbf{X}^T + \lambda\mathbf{I}_n, \mathbf{L}_\lambda \mathbf{L}_\lambda^T) \\ &= \kappa(\mathbf{Q}_\lambda \mathbf{S}^T \mathbf{S} \mathbf{Q}_\lambda^T + \lambda \mathbf{L}_\lambda^{-1} \mathbf{L}_\lambda^{-T}) \end{aligned}$$

- To bound this we note that  $\mathbf{Q}_\lambda \mathbf{Q}_\lambda^T + \lambda \mathbf{L}_\lambda^{-1} \mathbf{L}_\lambda^{-T} = \mathbf{I}_n$ , so

$$\|\mathbf{Q}_\lambda \mathbf{S}^T \mathbf{S} \mathbf{Q}_\lambda^T + \lambda \mathbf{L}_\lambda^{-1} \mathbf{L}_\lambda^{-T} - \mathbf{I}_n\|_F = \|\mathbf{Q}_\lambda \mathbf{S}^T \mathbf{S} \mathbf{Q}_\lambda^T - \mathbf{Q}_\lambda \mathbf{Q}_\lambda^T\|_F$$

- So, select enough rows such that this term  $\leq \frac{1}{2}$ , which guarantees  $\kappa \leq 3$ .



## Sparse Sketching (COUNTSKETCH)

■ Defined by:

- Random hash function  $h: \{1, \dots, d\} \rightarrow \{1, \dots, s\}$
- Random sign function  $g: \{1, \dots, d\} \rightarrow \{-1, +1\}$
- $(\mathbf{Sx})_i = \sum_{j \mid h(j)=i} g(j)x_j$ , so  $\mathbf{Sx}$  can be computed in  $O(\mathbf{nnz}(\mathbf{x}) + s)$ .

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Alternative matrix definition:

- $\mathbf{S} = \mathbf{HD}$ , where
- $\mathbf{D}$  is random diagonal, with  $\pm 1$ .
- $\mathbf{H} \in \mathbb{R}^{s \times d}$  has  $H_{*,j}$  chosen randomly from  $\mathbf{e}_1, \dots, \mathbf{e}_s$ .

Lemma (Thorup and Zhang, 2012):

$$\Pr\left(\|\mathbf{A}^T \mathbf{S}^T \mathbf{S} \mathbf{B} - \mathbf{A}^T \mathbf{B}\|_F \leq \frac{3\sqrt{2}\|\mathbf{A}\|_F \|\mathbf{B}\|_F}{\sqrt{s\delta}}\right) \geq 1 - \delta$$

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## Sketch Size for Preconditioned Ridge Regression

- Recall:
  - If  $\kappa(\mathbf{Q}_\lambda \mathbf{S}^T \mathbf{S} \mathbf{Q}_\lambda^T + \lambda \mathbf{L}_\lambda^{-1} \mathbf{L}_\lambda^{-T}) \leq 3$  then we have a good preconditioner.
  - If  $\|\mathbf{Q}_\lambda \mathbf{S}^T \mathbf{S} \mathbf{Q}_\lambda^T - \mathbf{Q}_\lambda \mathbf{Q}_\lambda^T\|_F \leq \frac{1}{2}$ , then  $\kappa(\mathbf{Q}_\lambda \mathbf{S}^T \mathbf{S} \mathbf{Q}_\lambda^T + \lambda \mathbf{L}_\lambda^{-1} \mathbf{L}_\lambda^{-T}) \leq 3$ .
- The last lemma ensures that with  $s = O(\|\mathbf{Q}_\lambda\|_F^2)$  we have a good preconditioner.
- We have:

$$\mathbf{rank}_\lambda \equiv \|\mathbf{Q}_\lambda\|_F^2 = \sum_{i=1}^n \frac{\sigma_i^2}{\sigma_i^2 + \lambda}$$

- Always:  $\mathbf{rank}_\lambda \leq n$ , and can be much smaller (for large  $\lambda$ ).  
(So: we benefit from not sketching the ridge term!)

**$\mathbf{rank}_\lambda$**  is known as the effective degrees of freedom in the statistics literature.

## What about Sketch-and-Solve?

Chen et al. 2015:

- Compute  $\tilde{\mathbf{w}} = \mathbf{X}^T (\mathbf{X} \mathbf{S}^T \mathbf{S} \mathbf{X}^T + \lambda \mathbf{I}_n)^{-1} \mathbf{y}$ .
- With enough rows (depends on  $n$ ),  $\|\mathbf{w} - \tilde{\mathbf{w}}\|_2 \leq \epsilon \|\mathbf{w}\|_2$ .
- Doesn't work well when moving to nonlinear modeling...

(with Clarkson and Woodruff):

- Solve  $\tilde{\mathbf{w}} = \arg \min \|\mathbf{X} \mathbf{S}^T \mathbf{w} - \mathbf{y}\|_2^2 + \lambda \|\mathbf{w}\|_2^2$ .
- With  $O(\frac{\text{rank}_\lambda^2}{\epsilon^2})$  rows in  $\mathbf{S}$   
 $(1 - \epsilon)(\|\mathbf{X} \mathbf{w} - \mathbf{y}\|_2^2 + \lambda \|\mathbf{w}\|_2^2) \leq \|\mathbf{X} \mathbf{S}^T \tilde{\mathbf{w}} - \mathbf{y}\|_2^2 + \lambda \|\tilde{\mathbf{w}}\|_2^2 \leq (1 + \epsilon)(\|\mathbf{X} \mathbf{w} - \mathbf{y}\|_2^2 + \lambda \|\mathbf{w}\|_2^2)$ .
- Rationale: at optimum, both objectives behave similarly.

## Regularized Multivariate Polynomial Regression

- Let  $q$  be some degree parameter.
- We now try to fit a multivariate polynomial, i.e.  $y \approx p_q(\mathbf{x})$ .
- Interested in: biggish  $n$  (data size), small  $q$  (degree), moderate  $d$  (data dimension)
  - E.g.  $n = 200,000$ ,  $q = 3$ ,  $d = 1000$ .
  - Assume  $d^q \gg n$ .
- The problem is underdetermined, so we need to regularize:
  - Let  $\mathbf{w}(p_q)$  be a vector of  $p_q$ 's monomial coefficients. Use regularizer  $\lambda \|\mathbf{w}(p_q)\|_2^2$ , i.e. solve
$$p_q = \arg \min_{p_q} \sum_{i=1}^n (p_q(\mathbf{x}_i) - y_i)^2 + \lambda \|\mathbf{w}(p_q)\|_2^2$$
  - Remark: not clear if this is a good way to regularize the problem, but it is used in practice.

## As Linear Ridge Regression

- Define  $V_q(\mathbf{X})$ , a multivariate analogue of the Vandermonde matrix
  - $V_q(\mathbf{X}) \in \mathbb{R}^{n \times (d+1)^q}$
  - Columns corresponds to monomials (a monomial may appear more than once).
  - Rows corresponds to a data points.
  - A row  $\mathbf{x}$  is mapped to  $\phi([\mathbf{x} \ 1]) = [\mathbf{x} \ 1] \otimes \dots \otimes [\mathbf{x} \ 1]$  ( $q$  times).
  - Example:

$$V_2 \left( \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix} \right) = \begin{bmatrix} 1 & x_{11} & x_{12} & x_{11} & x_{12} & x_{11}x_{12} & x_{12}x_{11} & x_{11}^2 & x_{12}^2 \\ 1 & x_{21} & x_{22} & x_{21} & x_{22} & x_{21}x_{22} & x_{22}x_{21} & x_{21}^2 & x_{22}^2 \end{bmatrix}$$

- Compute

$$\mathbf{w} = \arg \min \left\| V_q(\mathbf{X})\mathbf{w} - \mathbf{y} \right\|_2^2 + \lambda \|\mathbf{w}\|_2^2$$

and output is  $p_q$  such that  $\mathbf{w}(p_q) = \mathbf{w}$ . Specifically,  $p_q(\mathbf{x}) = \phi([\mathbf{x} \ 1]) \cdot \mathbf{w}$ .

Seems very expensive when  $d$  is not tiny.



## Alternative Algorithm

- Observation 1:  $\mathbf{w} = V_q(\mathbf{X})^T (V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda \mathbf{I}_n)^{-1} \mathbf{y}$
- Observation 2:  $(V_q(\mathbf{X})V_q(\mathbf{X})^T)_{ij} = (\mathbf{x}_i \cdot \mathbf{x}_j + 1)^q$
- Efficient Multivariate Polynomial Regression:
  - Use observation 2 to compute  $V_q(\mathbf{X})V_q(\mathbf{X})^T$  in  $O(n^2 d \log q)$ .
  - Compute  $\alpha = (V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda \mathbf{I}_n)^{-1} \mathbf{y}$  in  $O(n^3)$ .
  - Via observation 1 we found polynomial  $p_q(\mathbf{x}) = \phi(\mathbf{x})V_q(\mathbf{X})^T \alpha$ .
  - Similar to observation 2,  $\phi(\mathbf{x})V_q(\mathbf{X})^T$  can be computed in  $O(nd \log q)$ .
  - So,  $p_q(\mathbf{x})$  can be computed in  $O(nd \log q)$ .

**Goal: accelerate this using sketching!**

## TENSOR SKETCH (Pham and Pagh, 2013)

■  $\mathbf{S} \in \mathbb{R}^{s \times (d+1)^q}$  defined by:

- $q$  random hash functions  $h_1, \dots, h_q: \{1, \dots, d+1\} \rightarrow \{1, \dots, s\}$
- $q$  random sign functions  $g_1, \dots, g_q: \{1, \dots, d+1\} \rightarrow \{-1, +1\}$
- These define new sign and hash functions:

$$H(i_1, \dots, i_q) = \sum_{j=1}^q h_j(i_j) \bmod s$$

$$G(i_1, \dots, i_q) = \prod_{j=1}^q g_j(i_j)$$

- $\mathbf{S}$  is the COUNTSKETCH matrix defined by  $H$  and  $G$  (after indexing rows by tuples).

TENSOR SKETCH can sometimes be applied quickly ( $O(q(\text{nnz}(\mathbf{x}) + s \log s))$ ):

$$\phi(\mathbf{x}) \mathbf{S}^T = \text{FFT}^{-1} \left( \text{FFT}(\mathbf{x} \mathbf{S}_1^T) \odot \dots \odot \text{FFT}(\mathbf{x} \mathbf{S}_q^T) \right)$$

where  $\mathbf{S}_j$  is the COUNTSKETCH matrix defined by  $h_j$  and  $g_j$ .

## Approximate Matrix Multiplication Properties

(with Nguyen and Woodruff)

Lemma:

Suppose  $\mathbf{S}$  is a TENSORSKETCH matrix with  $s \geq \frac{2+3^q}{c^2\delta}$  rows, then

$$\Pr\left(\|\mathbf{A}^T\mathbf{S}^T\mathbf{S}\mathbf{B} - \mathbf{A}^T\mathbf{B}\|_F \leq c\|\mathbf{A}\|_F\|\mathbf{B}\|_F\right) \geq 1 - \delta$$

Corollary:

$s = O(\mathbf{rank}_\lambda(V_q(\mathbf{X})^2))$  rows suffice for  $V_q(\mathbf{X})\mathbf{S}^T\mathbf{S}V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$  to be a good preconditioner for  $V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$ .

## Efficient Use of the Preconditioner

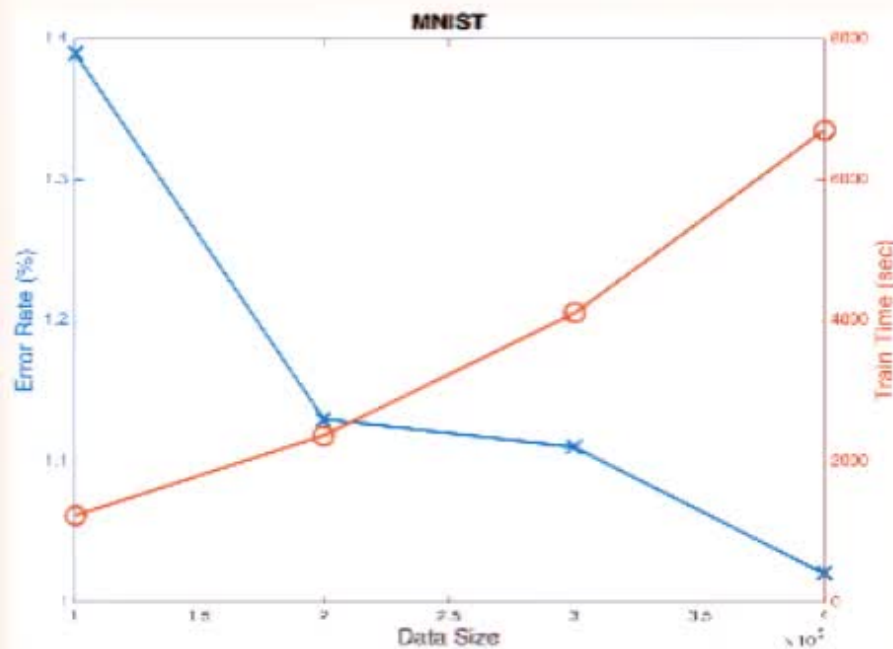
- The preconditioner is only useful if  $s < n$ .
  - Otherwise, we might as well compute and factor  $V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$ .
- For  $s < n$ , we can do better than computing and factoring  $V_q(\mathbf{X})\mathbf{S}^T\mathbf{S}V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$ .
- The Woodbury matrix identity imply that
$$(V_q(\mathbf{X})\mathbf{S}^T\mathbf{S}V_q(\mathbf{X})^T + \lambda\mathbf{I}_n)^{-1} = \lambda^{-1}(\mathbf{I}_n - V_q(\mathbf{X})\mathbf{S}^T(\mathbf{S}V_q(\mathbf{X})^TV_q(\mathbf{X})\mathbf{S}^T + \lambda\mathbf{I}_s)^{-1}\mathbf{S}V_q(\mathbf{X})^T)$$
- So, with  $O(ns^2)$  preprocessing we can apply the preconditioner efficiently.

## Faster Regularized Multivariate Polynomial Regression

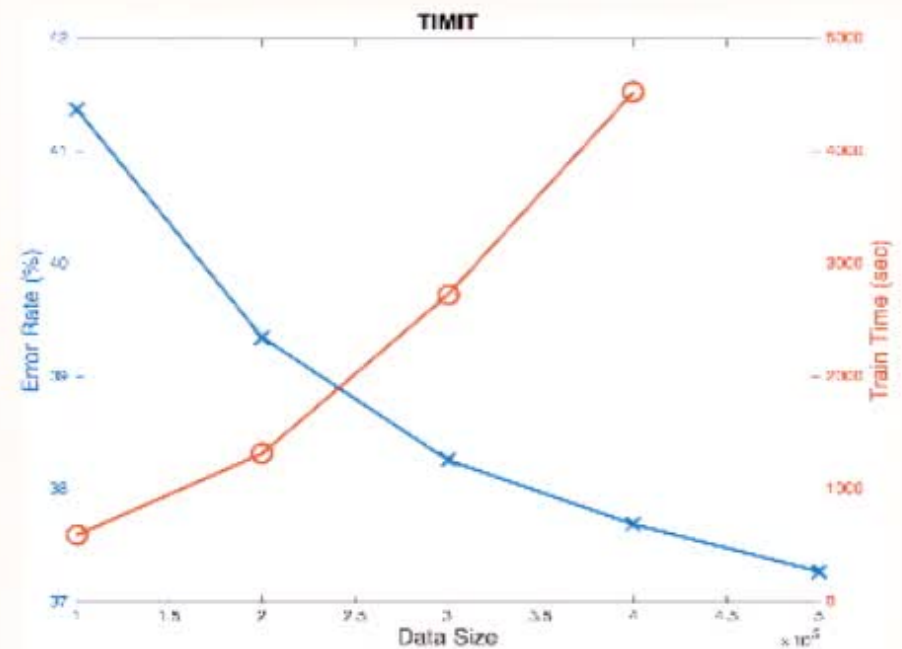
1. Compute  $\mathbf{K} = V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$  (cost:  $O(n^2 d \log q)$ )
2. Compute  $\mathbf{Z} = V_q(\mathbf{X})\mathbf{S}^T$  (cost:  $O(q(\text{nnz}(\mathbf{X}) + s \log s))$ )
3. Factorize  $\begin{bmatrix} \mathbf{Z} \\ \sqrt{\lambda}\mathbf{I}_s \end{bmatrix} = \mathbf{QR}$  (cost:  $O(ns^2)$ )
4. Use CG to solve  $\mathbf{K}\boldsymbol{\alpha} = \mathbf{y}$  using  $\lambda^{-1}(\mathbf{I}_n - \mathbf{Z}\mathbf{R}^{-1}\mathbf{R}^{-T}\mathbf{Z}^T)$  as preconditioner (cost:  $O(n^2)$  per iteration)

## Large Scale Multivariate Polynomial Regression

Dataset from an image processing application:



Dataset from a speech recognition application:



- Classification problems; solved via regression using standard techniques.
- Degree of polynomial is 3 for MNIST and 4 for TIMIT. For both datasets we rescale the features.
- Run on BlueGene/Q using 128 nodes (= 2,048 cores).



## Sketching for the Gaussian Kernel: Random Fourier Features

(Rahimi and Recht, 2007)

- Observation (due to Bochner's Theorem):

$$k(\mathbf{x}, \mathbf{z}) = \mathbb{E}_{\mathbf{w}}(\exp(-i\mathbf{w}^T(\mathbf{x} - \mathbf{z}))), \quad \mathbf{w} \sim N(0, \sigma^{-2}\mathbf{I}_d)$$

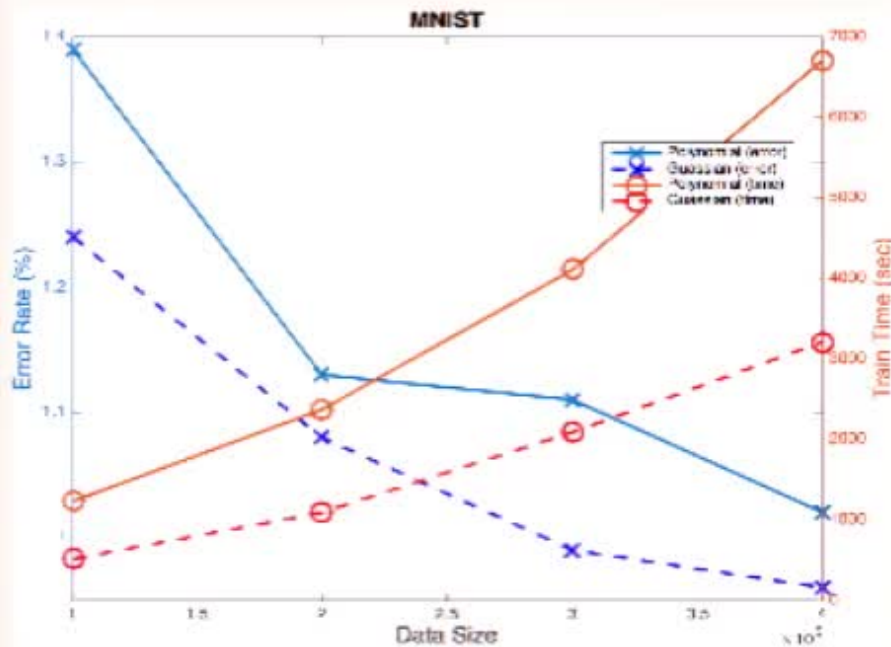
- The sketch: sample  $\mathbf{w}_1, \dots, \mathbf{w}_s$  and map

$$\mathbf{x} \rightarrow \frac{1}{\sqrt{s}} [e^{-i\mathbf{w}_1^T \mathbf{x}} \quad \dots \quad e^{-i\mathbf{w}_s^T \mathbf{x}}].$$

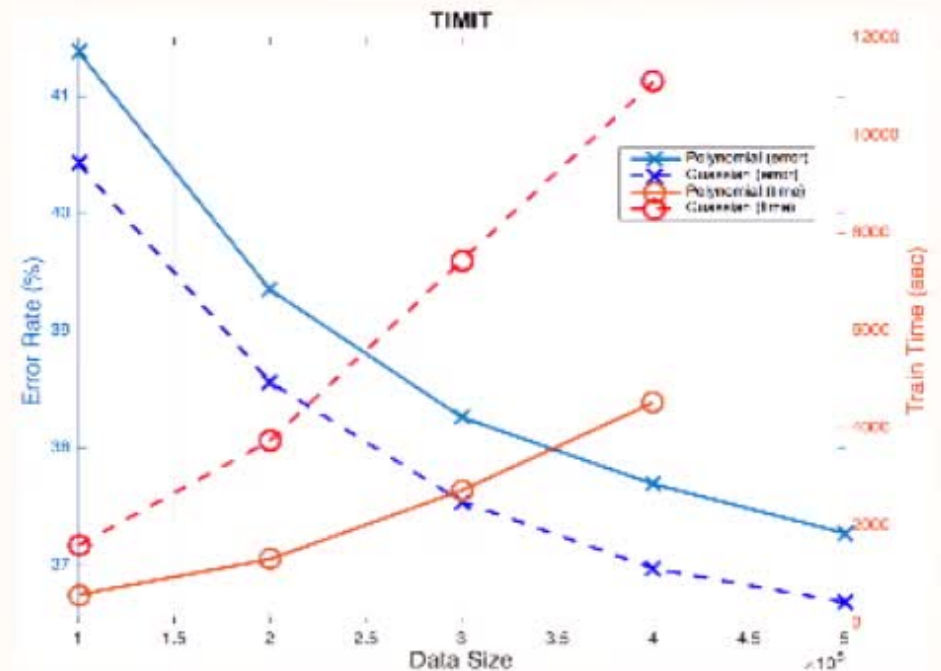
- There is no proof that this sketch has strong matrix multiplication guarantees.

## Preconditioned Solver Works Well

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## Conclusions

- Matrix sketching is a powerful technique for designing new exciting algorithms.
- So far, it mostly addressed problems motivated by linear modeling.
- However, effectively leveraging “big data” requires nonlinear and nonparametric modeling.
- Matrix sketching can help for nonlinear modeling as well, but there is still much to be done.

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- Collaborators:
  - *Ken Clarkson, Christopher Carothers, Petros Drineas, Po-sen Huang, Yves Ineichen, Chander Iyer, Georgios Kollias, Petar Maymounkov, Huy Nguyen, Bhuvana Ramabhardan, Tara Sainath, Vikas Sindhwani, Sivan Toledo, David Woodruff*
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## More General: Kernel Ridge Regression

- Multivariate polynomial regression is a special case of kernel ridge regression.
- In kernel ridge regression we start with a kernel  $k: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ .
- The kernel defines an Hilbert space  $\mathcal{H}$ .
- We search for functions in  $\mathcal{H}$ , i.e. solve

$$\arg \min_{f \in \mathcal{H}} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2 + \lambda \|f\|_{\mathcal{H}}^2.$$

- Skipping ... some ... mathematical ... details, the solution is

$$f(\mathbf{x}) = \sum_{i=1}^n \alpha_i k(\mathbf{x}_i, \mathbf{x})$$

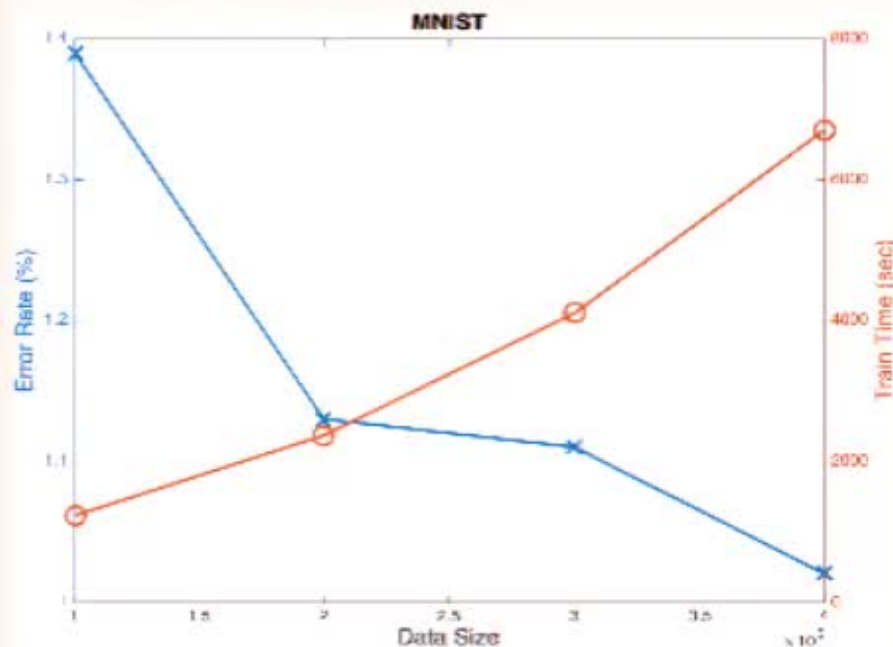
where

$$(\mathbf{K} + \lambda \mathbf{I}_n) \boldsymbol{\alpha} = \mathbf{y}$$

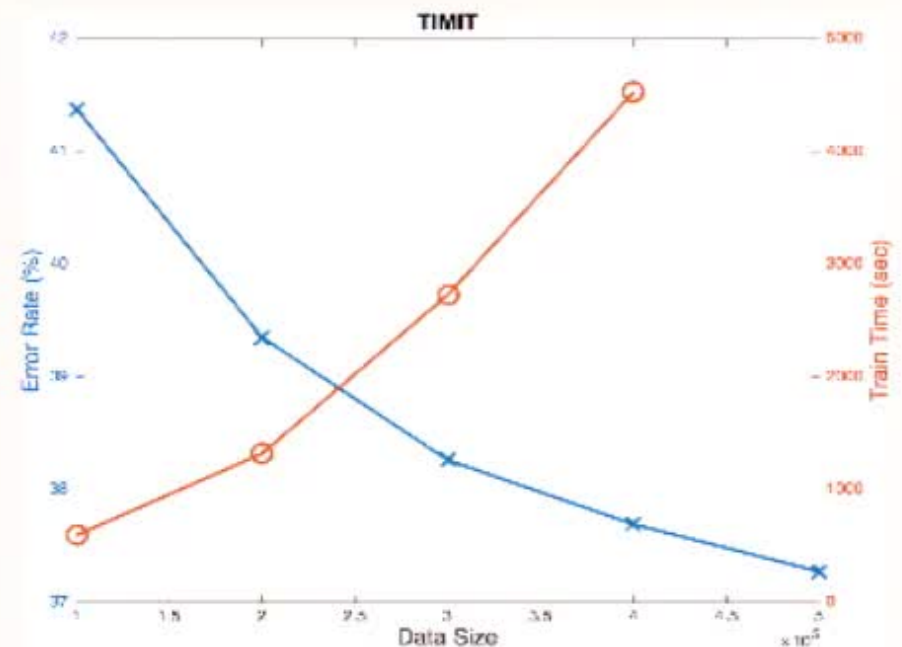
with  $\mathbf{K}_{ij} = k(\mathbf{x}_i, \mathbf{x}_j)$ .

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- $\mathbf{S}$  is the COUNTSKETCH matrix defined by  $H$  and  $G$  (after indexing rows by tuples).

TENSOR SKETCH can sometimes be applied quickly ( $O(q(\text{nnz}(\mathbf{x}) + s \log s))$ ):

$$\phi(\mathbf{x}) \mathbf{S}^T = \text{FFT}^{-1} \left( \text{FFT}(\mathbf{x} \mathbf{S}_1^T) \odot \dots \odot \text{FFT}(\mathbf{x} \mathbf{S}_q^T) \right)$$

where  $\mathbf{S}_j$  is the COUNTSKETCH matrix defined by  $h_j$  and  $g_j$ .

## Efficient Use of the Preconditioner

- The preconditioner is only useful if  $s < n$ .
  - Otherwise, we might as well compute and factor  $V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$ .
- For  $s < n$ , we can do better than computing and factoring  $V_q(\mathbf{X})\mathbf{S}^T\mathbf{S}V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$ .
- The Woodbury matrix identity imply that
$$(V_q(\mathbf{X})\mathbf{S}^T\mathbf{S}V_q(\mathbf{X})^T + \lambda\mathbf{I}_n)^{-1} = \lambda^{-1}(\mathbf{I}_n - V_q(\mathbf{X})\mathbf{S}^T(\mathbf{S}V_q(\mathbf{X})^T V_q(\mathbf{X})\mathbf{S}^T + \lambda\mathbf{I}_s)^{-1}\mathbf{S}V_q(\mathbf{X})^T)$$
- So, with  $O(ns^2)$  preprocessing we can apply the preconditioner efficiently.

## Approximate Matrix Multiplication Properties

(with Nguyen and Woodruff)

Lemma:

Suppose  $\mathbf{S}$  is a TENSORSKETCH matrix with  $s \geq \frac{2+3^q}{c^2\delta}$  rows, then

$$\Pr\left(\|\mathbf{A}^T\mathbf{S}^T\mathbf{S}\mathbf{B} - \mathbf{A}^T\mathbf{B}\|_F \leq c\|\mathbf{A}\|_F\|\mathbf{B}\|_F\right) \geq 1 - \delta$$

Corollary:

$s = O(\mathbf{rank}_\lambda(V_q(\mathbf{X})^2))$  rows suffice for  $V_q(\mathbf{X})\mathbf{S}^T\mathbf{S}V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$  to be a good preconditioner for  $V_q(\mathbf{X})V_q(\mathbf{X})^T + \lambda\mathbf{I}_n$ .