

A multiscale model and variance reduction method for wave propagation in heterogeneous materials

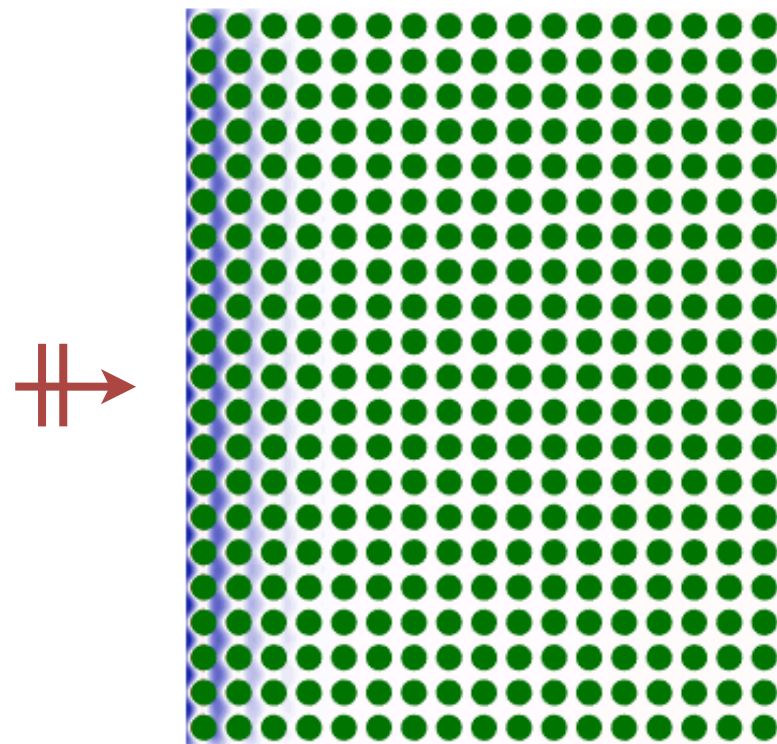
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Siam Annual Meeting
July 14th 2016

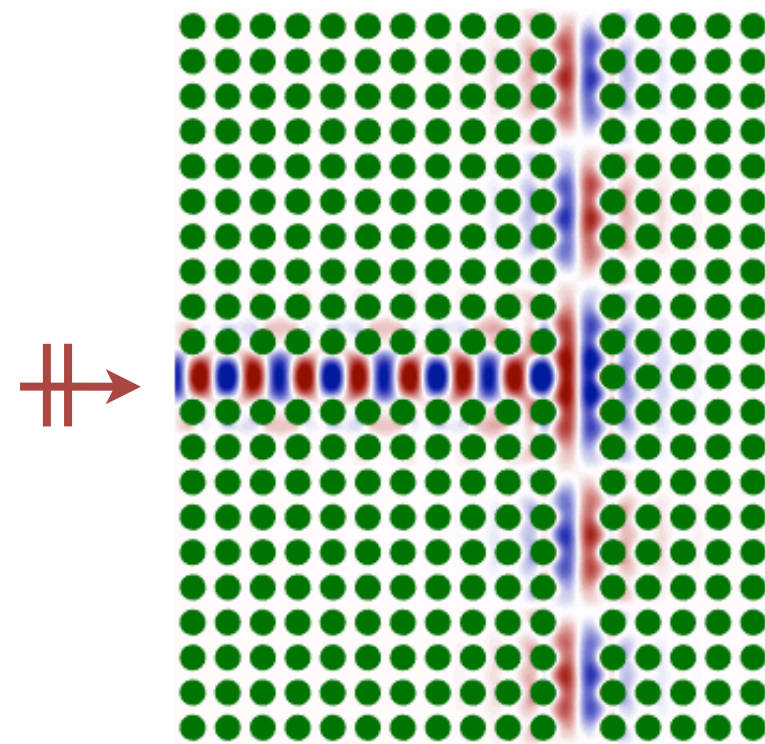


Motivation

- Metamaterials are heterogeneous materials microscopically engineered to exhibit properties that cannot be found in homogeneous materials
- Study wave propagation in metamaterials: **photonic bandgap**



photonic crystal

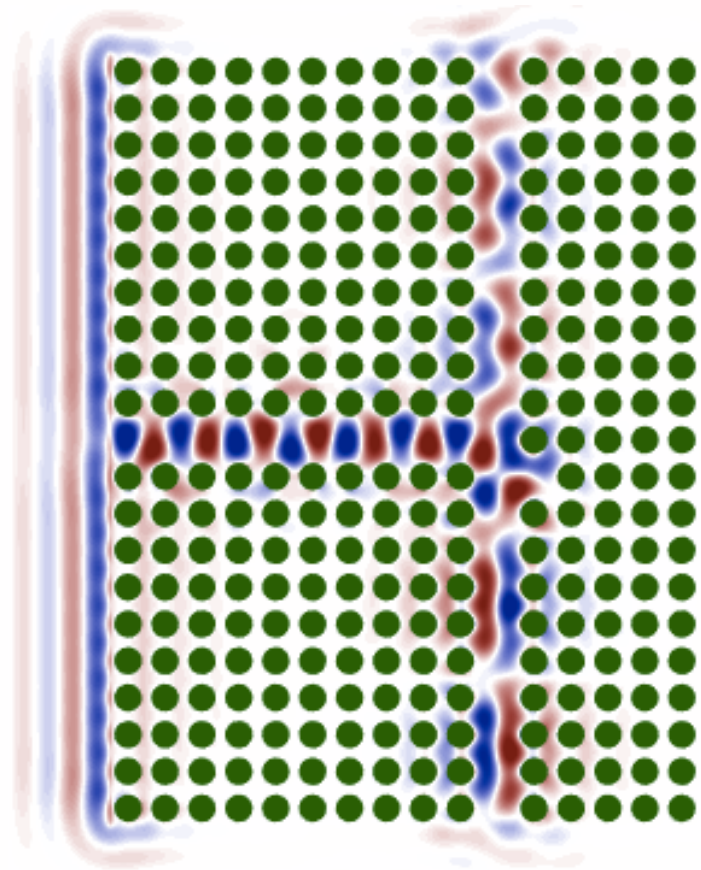


waveguide splitter

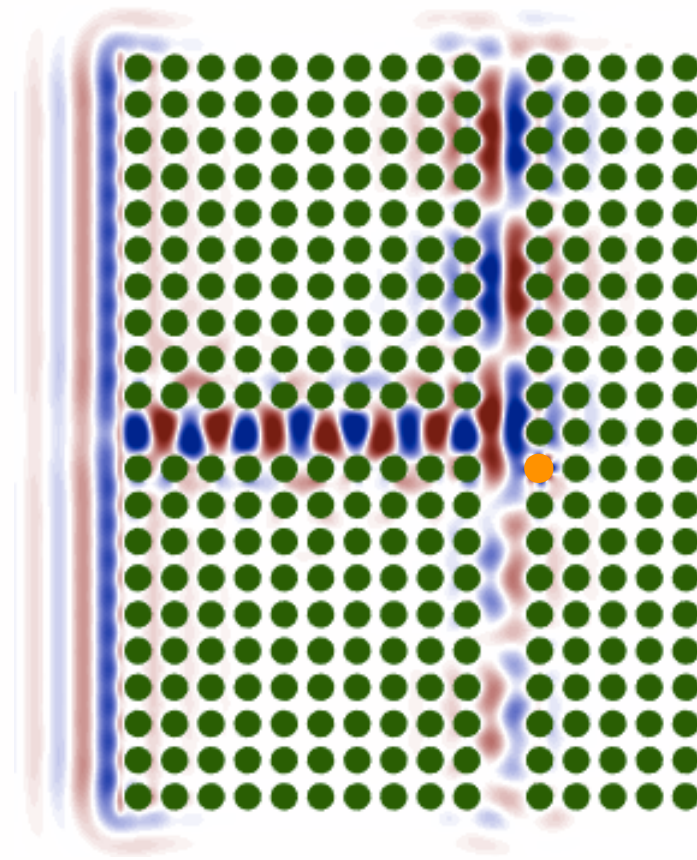
applications → waveguides, fibers, cavities...

Motivation: Photonic Bandgap

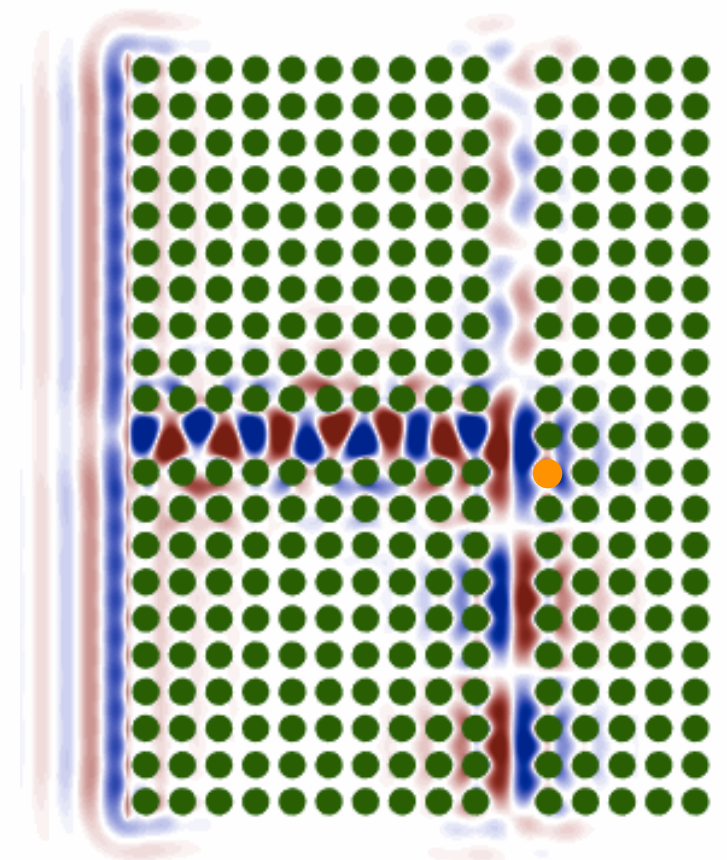
Highly **sensitive** to material properties and geometry **variations**



Remove rod



+15% permittivity



-3% radius

Accurate simulations are required

Problem statement

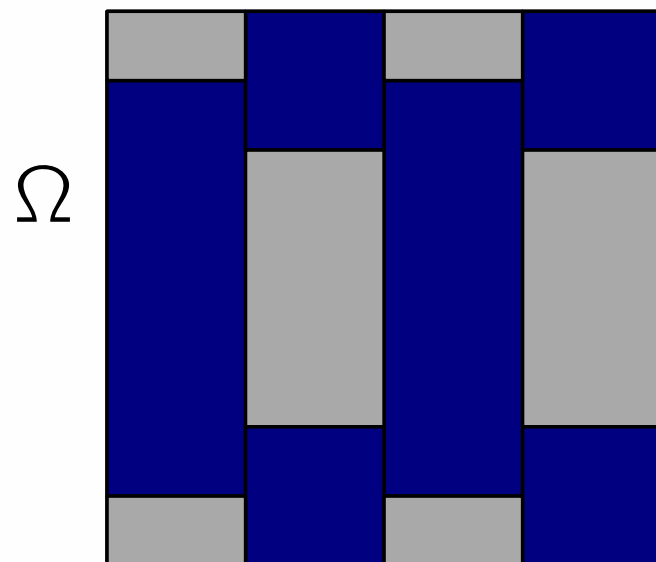
Consider the **Helmholtz** equation in 2d

$$-\nabla \cdot (\rho(\mathbf{x}) \nabla u) - k^2(\mathbf{x}) u = f \quad + \text{B.C.}$$

where $\rho(\mathbf{x})$, $k^2(\mathbf{x})$ represent material properties

- ✓ Time-harmonic solutions of scalar wave equation
- ✓ 2d Maxwell's equations for TE and TM polarizations $\longrightarrow$
TE: $u = H_z$
TM: $u = E_z$

Wave propagation is considered for **structured** materials



Material 1 $\rho(\mathbf{x})$, $k^2(\mathbf{x})$

Material 2 $\rho(\mathbf{x})$, $k^2(\mathbf{x})$

piecewise constant

$$\Omega = \bigcup_{m=1}^M \Omega^m$$

Develop methods for **robust design** of heterogeneous materials to control **wave propagation**

Simulate wave propagation in structured media

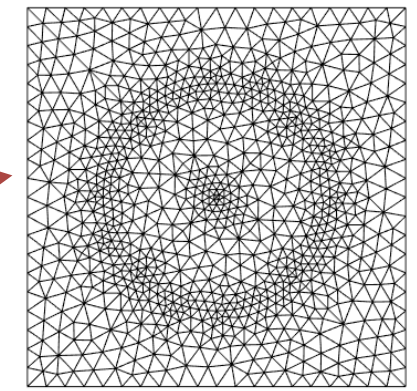
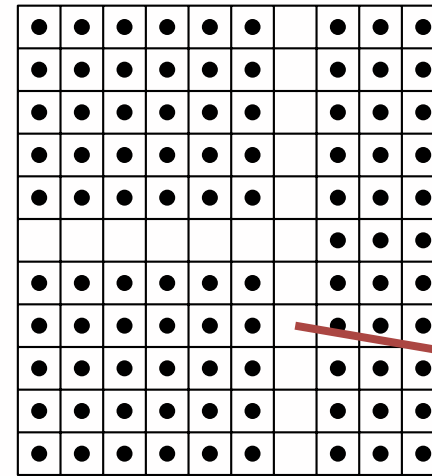
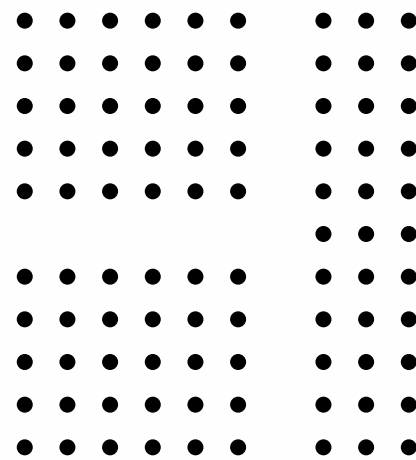
- Wave equation is **non-coercive**, need **high accuracy**
- Complex **geometries**, repeated **patterns**, mismatch in **length scales**

Stochastic simulation of wave propagation

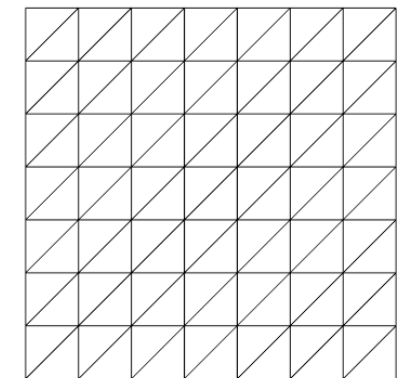
- Framework to deal with **geometry** variations
- Models are expensive: develop **surrogates**, use **control variates**

MultiScale continuous Galerkin (MSCG) method

Identify **repeated geometries** in domain



two classes of subdomains

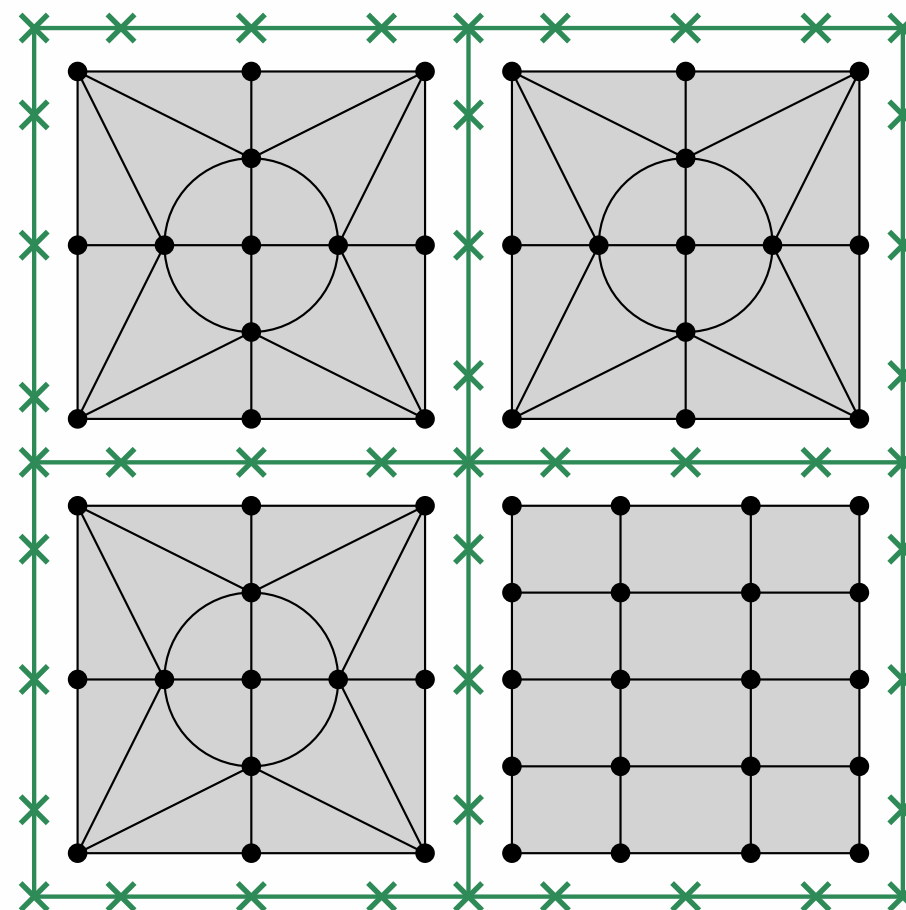


Discretize subdomains and **global skeleton**

Local problem

High-order CG
discretization

Capture small features

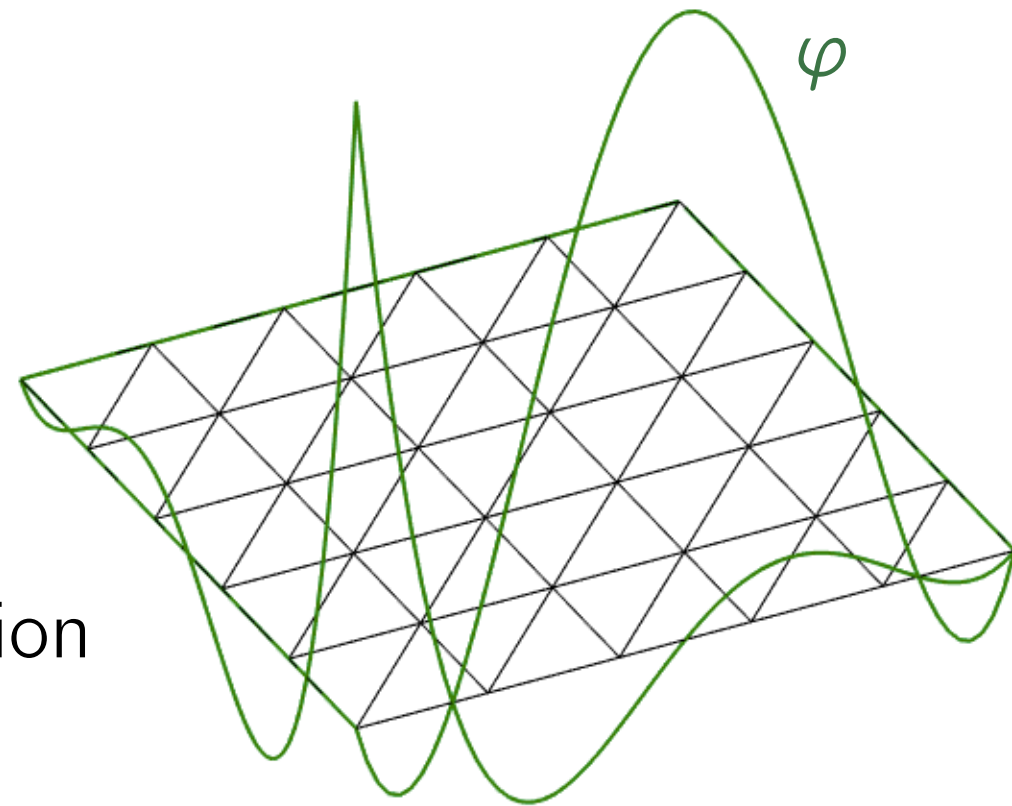
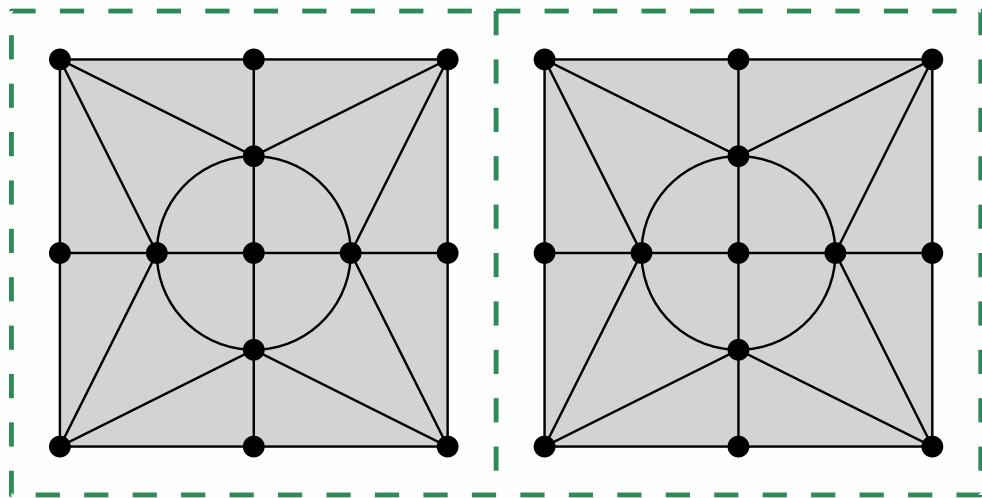


Global problem

Lagrange polynomial for
solution on global faces

Capture frequencies on
large scale

MultiScale CG - Local problem

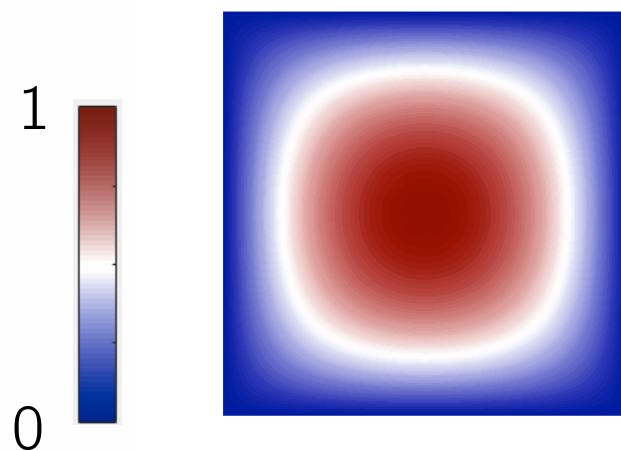


For every subdomain Ω^m , solve Helmholtz equation

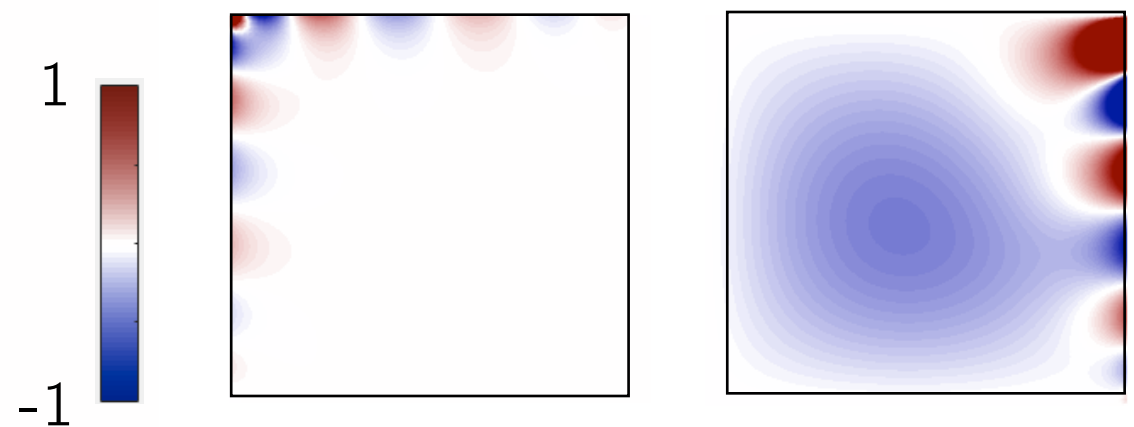
1. Source problem $\longrightarrow \mathbb{A} \mathbf{u}_f = \mathbf{f}$

2. Inhomogeneous Dirichlet given by $\varphi_j, 1 \leq j \leq J \longrightarrow \mathbb{A} \mathbf{u}_{\varphi_j} = \mathbf{d}_{\varphi_j}$

$\mathbf{u}_f$



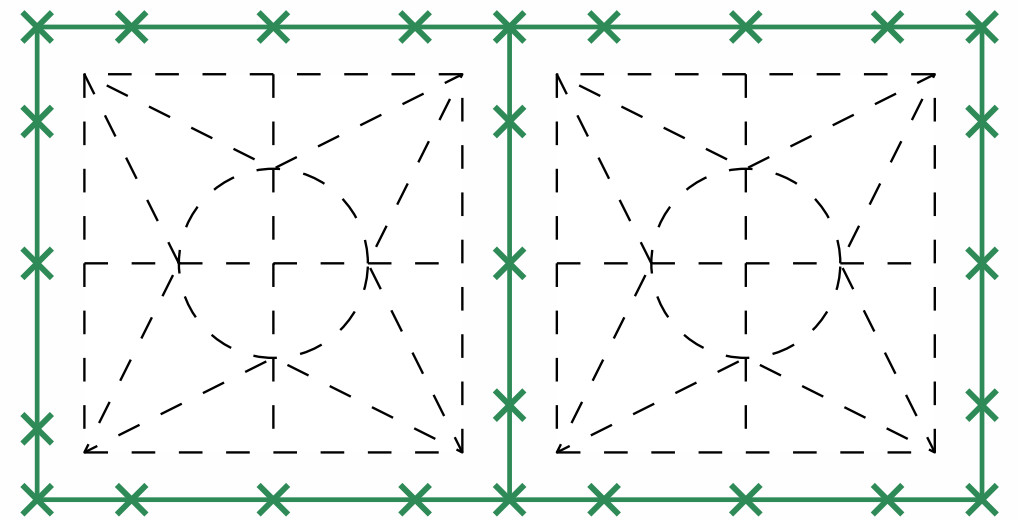
$\mathbf{u}_{\varphi_j}$



MultiScale CG - Global problem

On the subdomain level we apply **linearity** and **superposition**

$$\mathbf{u} = \mathbf{u}_f + \sum_{j=1}^J \lambda_j \mathbf{u}_{\varphi_j}$$



The contribution of each subdomain to the global problem is

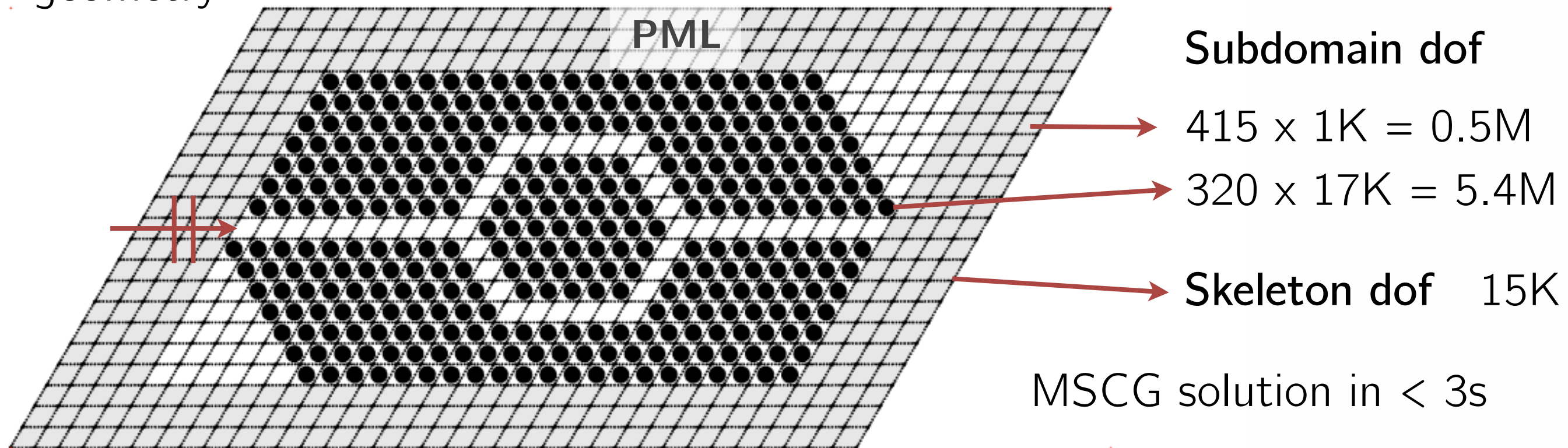
$$\mathbb{K}_{ij} = \mathbf{u}_{\varphi_i}^T \mathbb{A} \mathbf{u}_{\varphi_j}, \quad 1 \leq i, j \leq J$$

$$\mathbf{F}_i = \mathbf{u}_{\varphi_i}^T \mathbf{f}, \quad 1 \leq i \leq J$$

Solve the global problem $\mathbb{K}\mathbf{\Lambda} = \mathbf{F}$

Simulation of waveguide bends

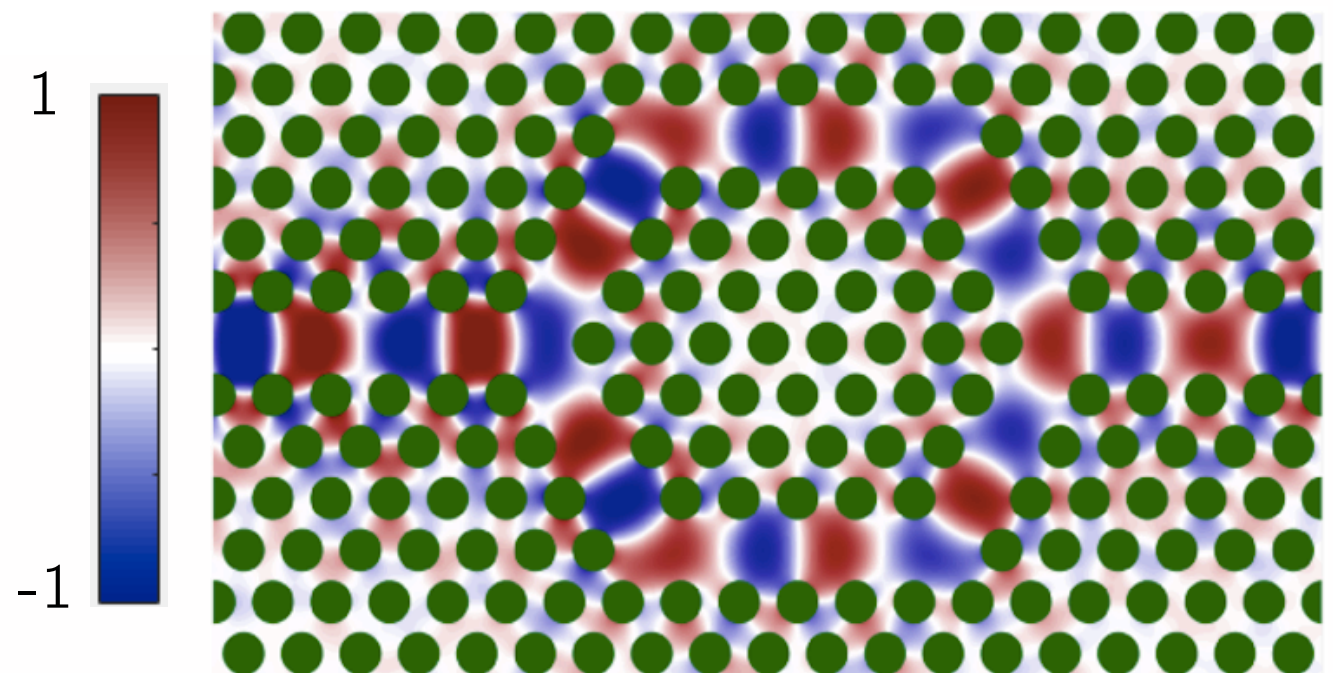
Photonic crystals are expensive to simulate given the complexity of the geometry



Bandgap

$$\frac{\omega a}{2\pi c} \in [0.42, 0.456]$$

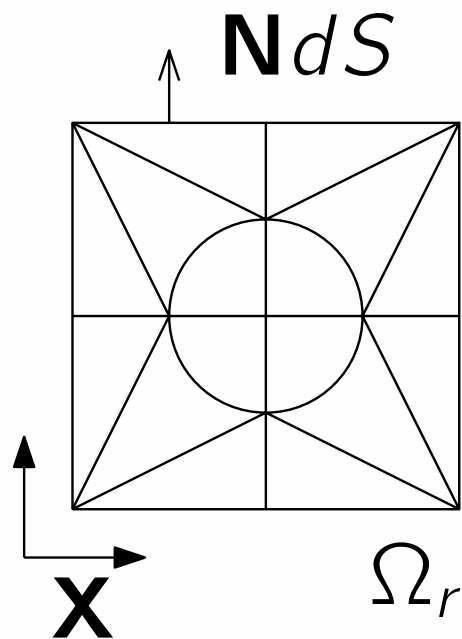
Results for $\frac{\omega a}{2\pi c} = 0.454$



Reference domain formulation

Reformulate governing equations [Persson *et.al.* 09] with deformation mapping parametrized by y

reference

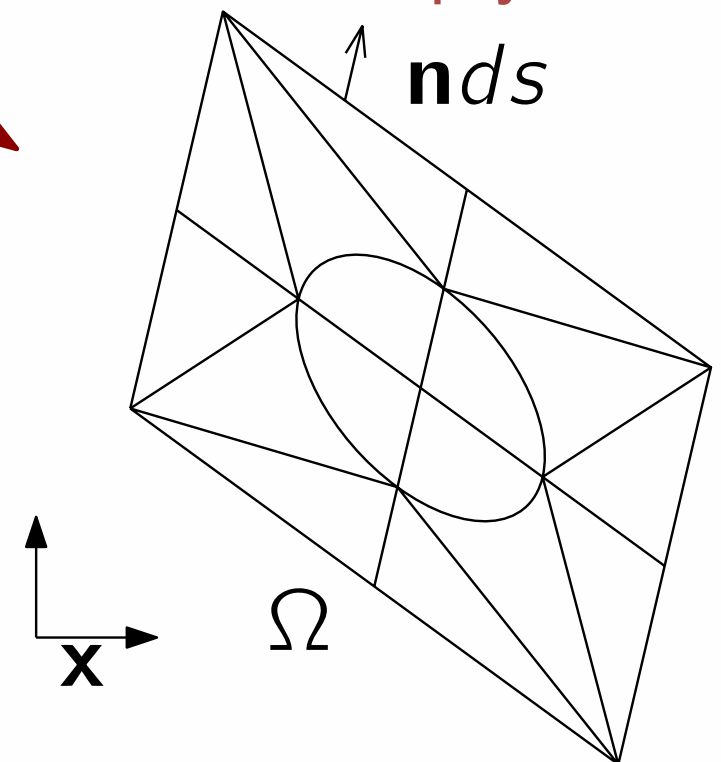


$$\mathbf{x} = \mathcal{G}(\mathbf{X}, y)$$

$$\mathbf{G} = \nabla_r \mathcal{G}$$

$$g = \det \mathbf{G}$$

physical

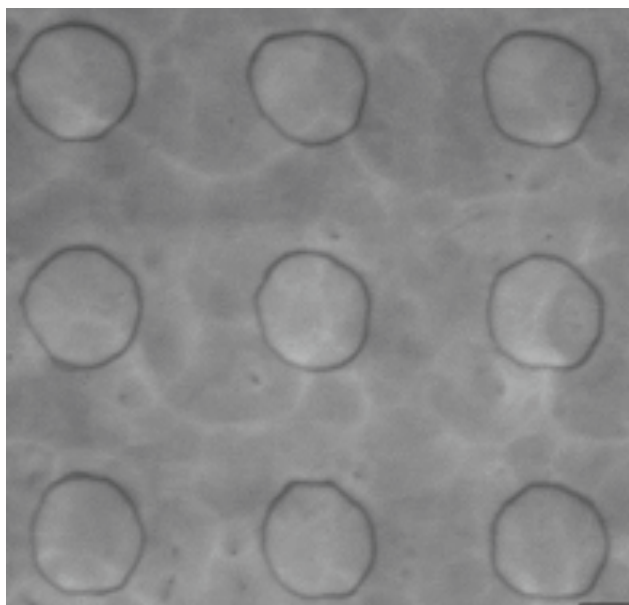
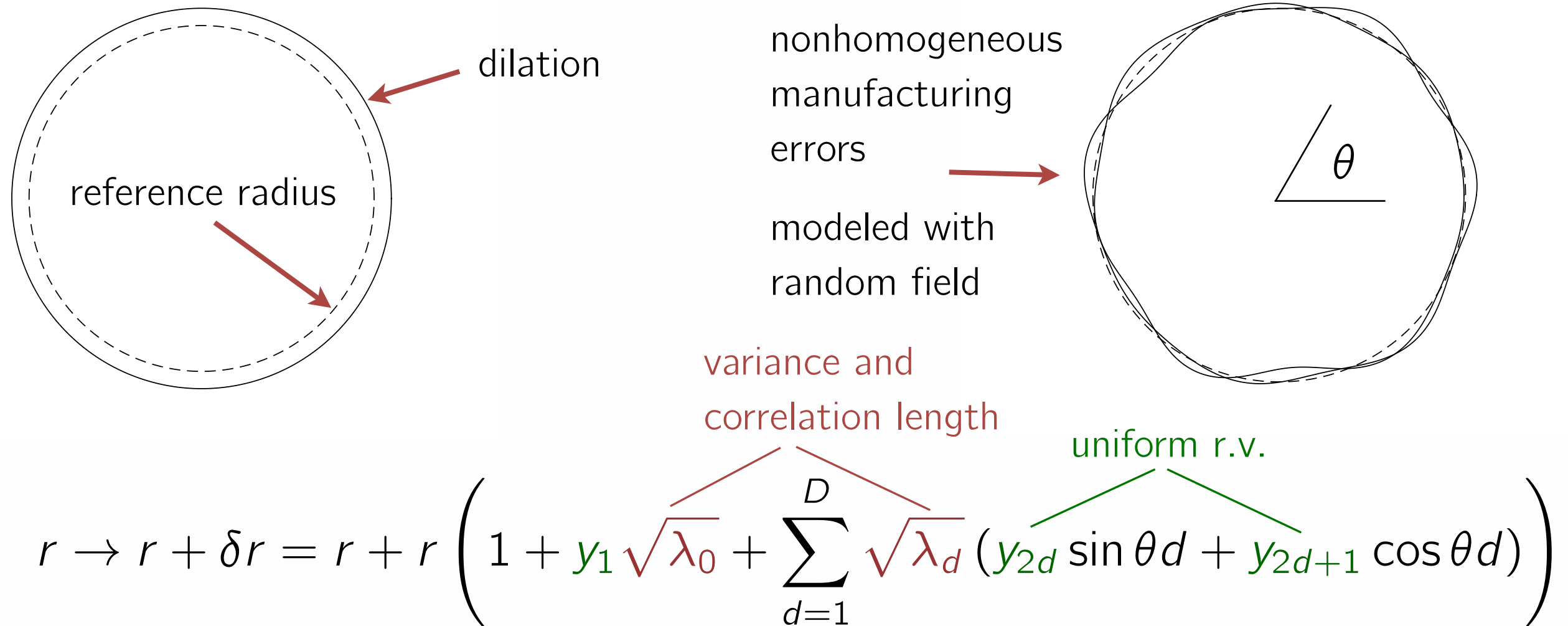


$$\begin{aligned} -\nabla_r \cdot (\rho(\mathbf{X}) g \mathbf{G}^{-1} \mathbf{G}^{-T} \nabla_r u) \\ -k^2(\mathbf{X}) u g = f g \end{aligned}$$

$$-\nabla \cdot (\rho(\mathbf{x}) \nabla u) - k^2(\mathbf{x}) u = f$$

MSCG for geometry variations

Analyze response of a structured medium under geometry variations

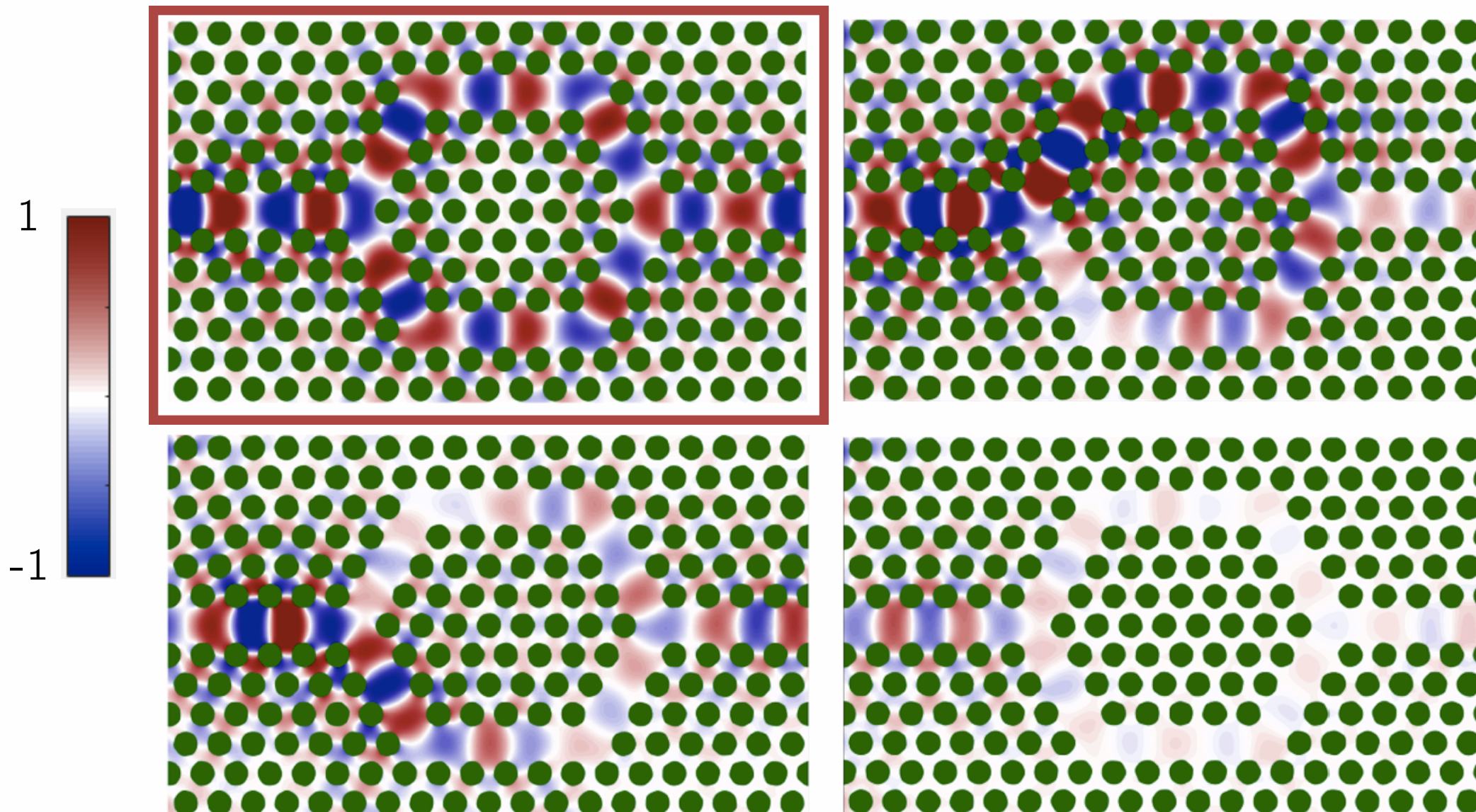


Nanogaps of Al_2O_3 on gold substrate

[Yoo *et al.* 2016]

Stochastic simulation of waveguide

- ✓ Radius of rods modeled with 15 r.v. (90% energy)
 - ✓ Relative radius perturbation $|\delta r|/r < 0.05$
 - ✓ Independent realizations of errors for each rod
- no longer capitalize **repetition** of subdomains



Reduced basis for MSCG (1/2)

Develop an accurate surrogate efficient to evaluate

- Proper orthogonal decomposition [Sirovich 87]
- Reduced basis method [Noor *et al.* 80, Rozza *et al.* 08,...]

Reduced basis for multiscale CG and geometry parameters

- ✓ RB for each type of subdomain [Huynh *et al.* 13]
- ✓ Empirical interpolation [Barrault *et al.* 04] for parameter dependent mapping $\mathcal{G}(y)$

$$\mathbb{A}(y)\mathbf{u}_{\varphi_j} = \mathbf{d}_{\varphi_j}(y)$$



$$\sum_{q=1}^Q \sigma_q(y) \mathbb{A}_q \mathbf{u}_{\varphi_j} = \sum_{q=1}^Q \sigma_q(y) \mathbf{d}_{q,\varphi_j}$$

Reduced basis for MSCG (2/2)

- ✓ For each Dirichlet BC φ_j , compute snapshots sampling y
- ✓ **Single RB** $\mathbf{Z}$ compressing snapshots for all Dirichlet BC $\varphi_j, 1 \leq j \leq J$

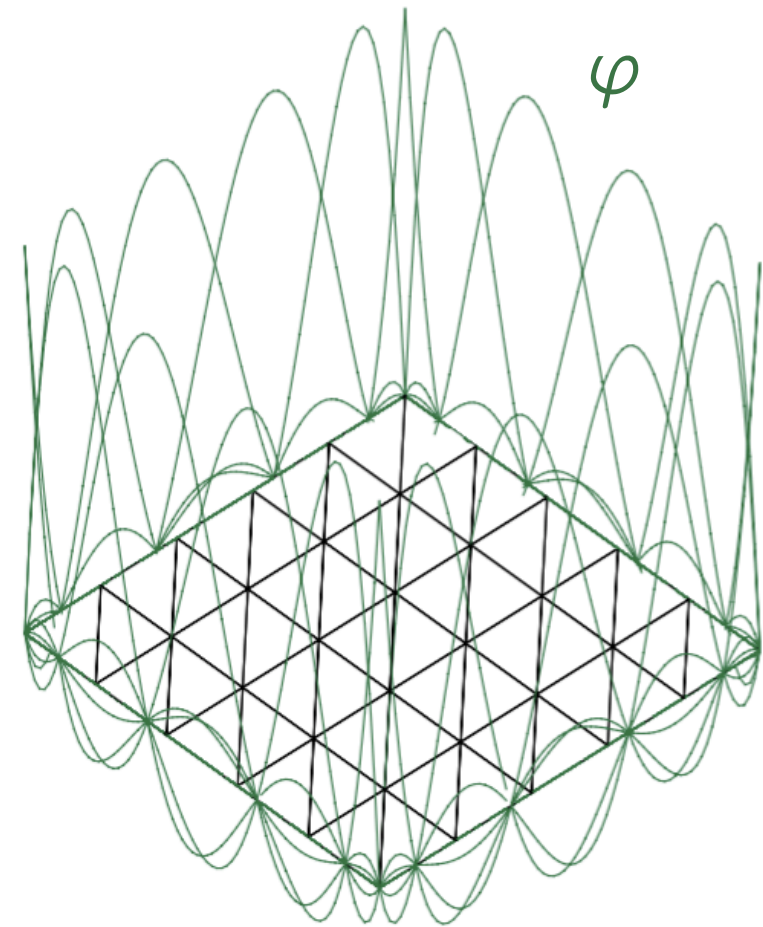
$$\mathbf{u}_{\varphi_j}^N = \mathbf{Z} \mathbf{c}_j$$

- ✓ Linear system with **multiple** RHS

$$\sum_{q=1}^Q \sigma_q(y) \mathbf{Z}^\dagger \mathbf{A}_q \mathbf{Z} \mathbf{c}_j = \sum_{q=1}^Q \sigma_q(y) \mathbf{Z}^\dagger \mathbf{d}_{q,\varphi_j}$$

- ✓ RB approximation to local contribution to stiffness matrix

$$\mathbb{K}_{ij}^N = \sum_{q=1}^Q \sigma_q(y) \mathbf{c}_j^\dagger \mathbf{Z}^\dagger \mathbf{A}_q \mathbf{Z} \mathbf{c}_j, \quad 1 \leq i, j \leq J$$



Model and variance reduction method

Combine **high-fidelity solver** with one (or multiple) **low-fidelity models**

Multilevel MC [Giles 08], Multifidelity MC [Ng *et al.* 12]

RB control variate [Boyaval 12]

Exploit statistical correlation: **reduce variance** in estimates

Use **reduced basis** as low-fidelity model

Model and variance reduction method [Vidal-Codina 15]

Output s as a functional of the solution of stochastic PDE

$$E[s] = E[s - s_N] + E[s_N]$$

The diagram illustrates the decomposition of the expectation formula. A red arrow points from the term $E[s - s_N]$ in the top equation to the corresponding term in the bottom equation. The bottom equation is $E_{M_0, M_1}[s] = E_{M_1}[s - s_N] + E_{M_0}[s_N]$. Two red arrows point from the terms $E_{M_1}[s - s_N]$ and $E_{M_0}[s_N]$ in the bottom equation to the text 'Variance reduction (statistical correlation)' and 'Model reduction (cheaper output evaluation)' respectively.

$$E_{M_0, M_1}[s] = E_{M_1}[s - s_N] + E_{M_0}[s_N]$$

Variance reduction (statistical correlation) + Model reduction (cheaper output evaluation)

Estimate of expectation

Choose $N_1 < N_2 < \dots < N_L$ and define L -MVR estimator

$$E_{M_0, \dots, M_L}[s] = E_{M_0}[s_{N_1}] + \sum_{\ell=1}^{L-1} E_{M_\ell}[s_{N_{\ell+1}} - s_{N_\ell}] + E_{M_L}[s - s_{N_L}]$$

output evaluation complexity →

← # samples M_ℓ

For i.i.d. samples between levels, we apply the central limit theorem

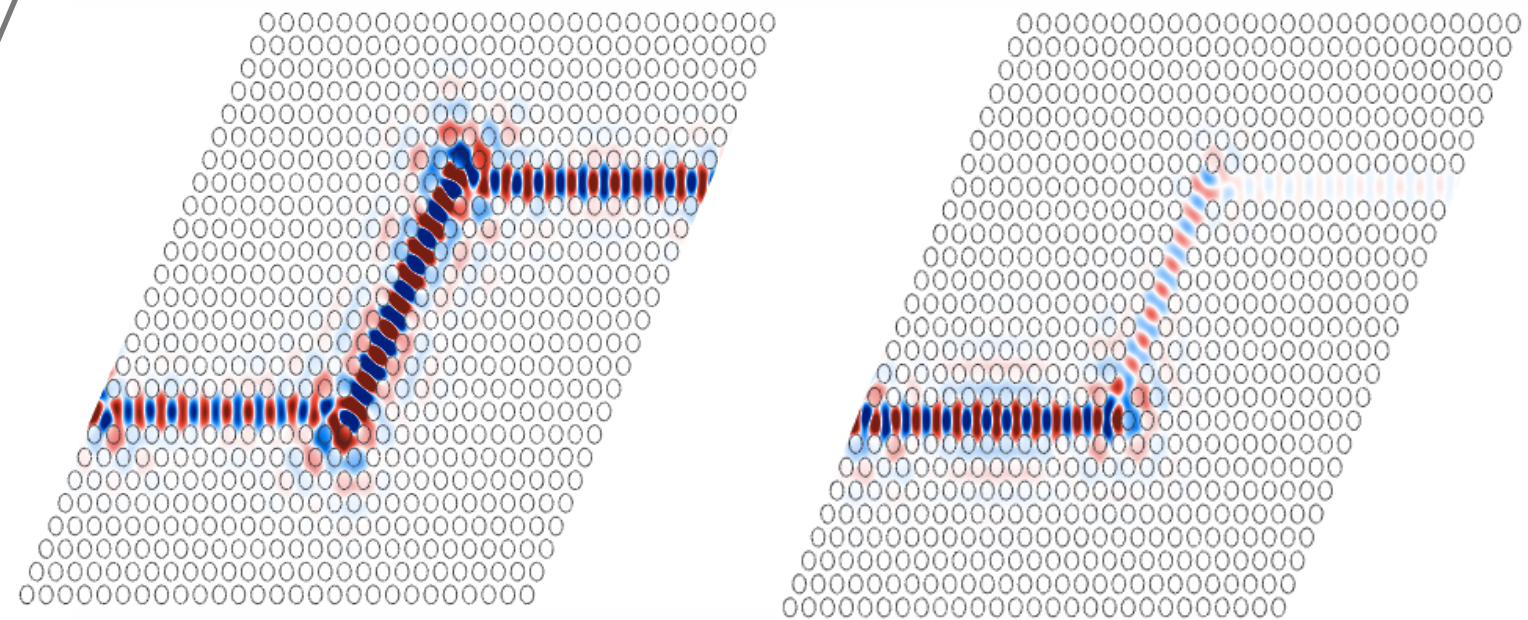
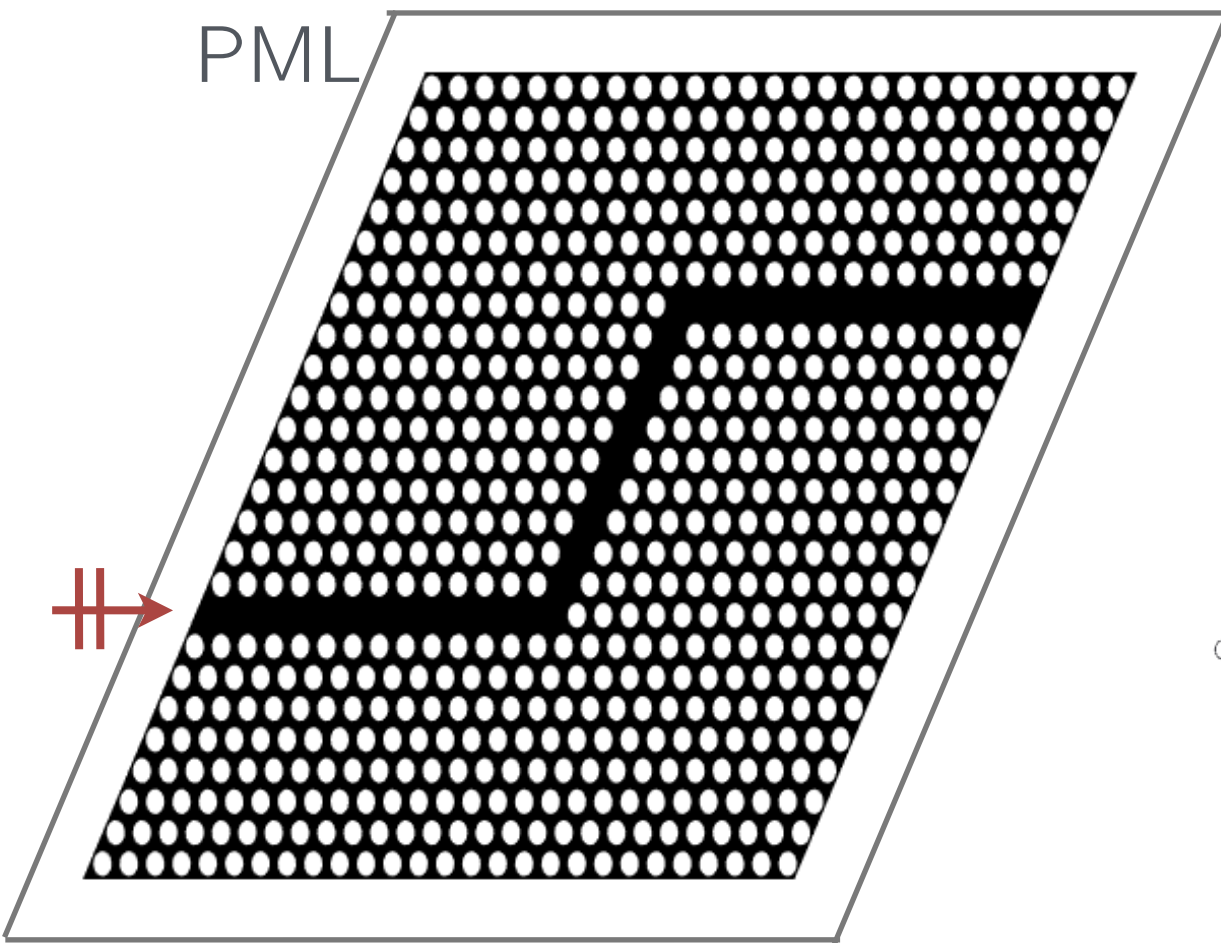
$$\lim_{M_0 \rightarrow \infty} \dots \lim_{M_L \rightarrow \infty} \Pr(|E[s] - E_{M_0, \dots, M_L}[s]| \leq \Delta_E) = \operatorname{erf}\left(\frac{a}{\sqrt{2}}\right), \quad \forall a \geq 0$$

obtain *a posteriori* sampling error estimates

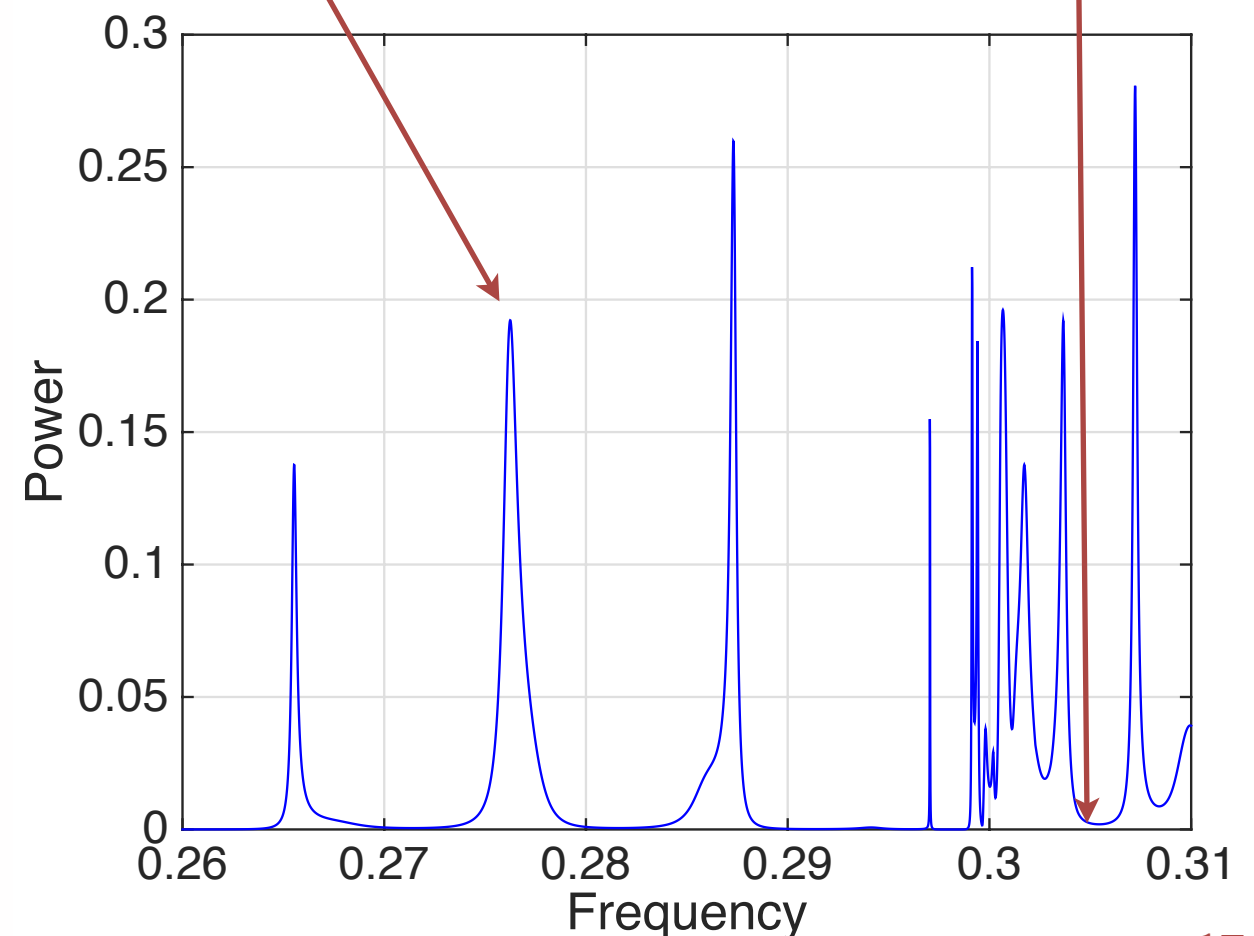
$$\Delta_E = a \sqrt{\frac{V_{M_0}[s_{N_1}]}{M_0} + \sum_{\ell=1}^{L-1} \frac{V_{M_\ell}[s_{N_{\ell+1}} - s_{N_\ell}]}{M_\ell} + \frac{V_{M_L}[s - s_{N_L}]}{M_L}}$$

Similar estimators for the **variance**

Robust design of photonic slab

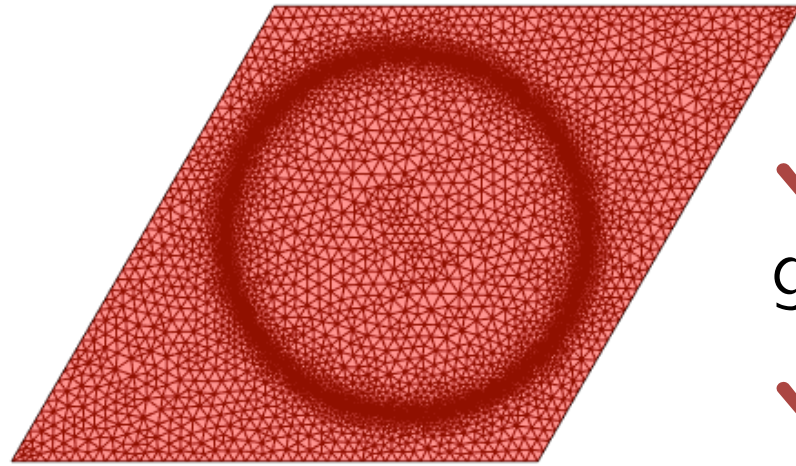


- ✓ Silicon slab on triangular lattice with air holes
- ✓ TE polarization, solve for H_z
- ✓ Output s is optical power at outlet



Computational domain and subproblem selection

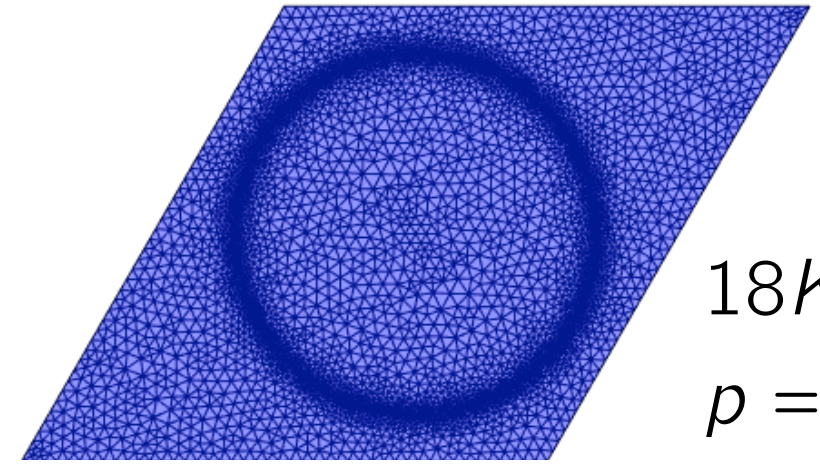
Subdomain #1 (optimization)



- ✓ Develop RB for geometry and frequency
- ✓ Lagrange polynomial of order 10

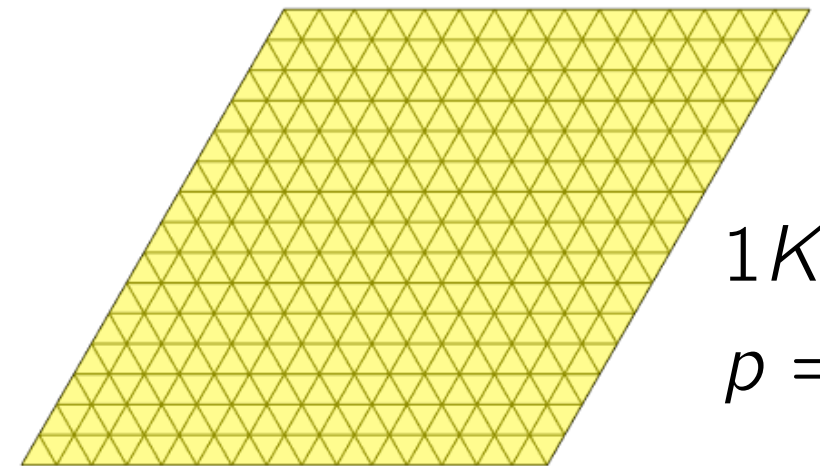
18K dof
 $p = 2$

Subdomain #2



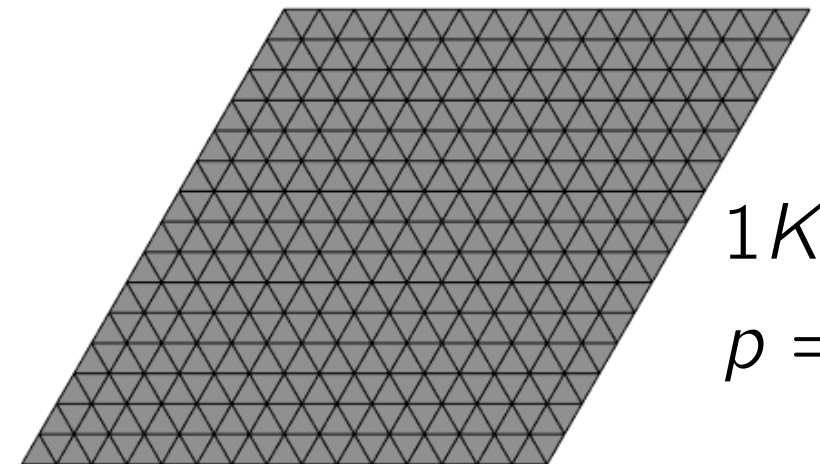
18K dof
 $p = 2$

Subdomain #3

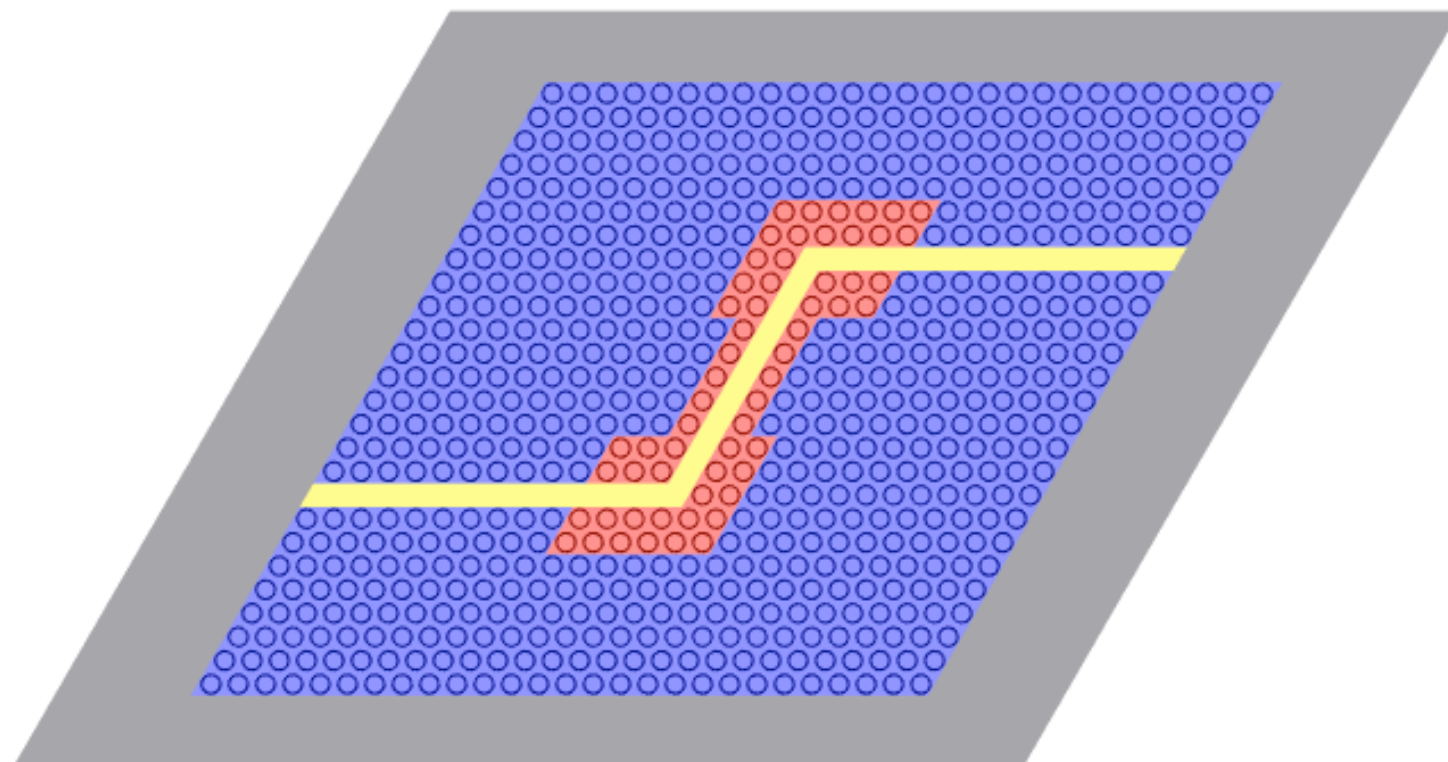


1K dof
 $p = 2$

Subdomain #4



1K dof
 $p = 2$

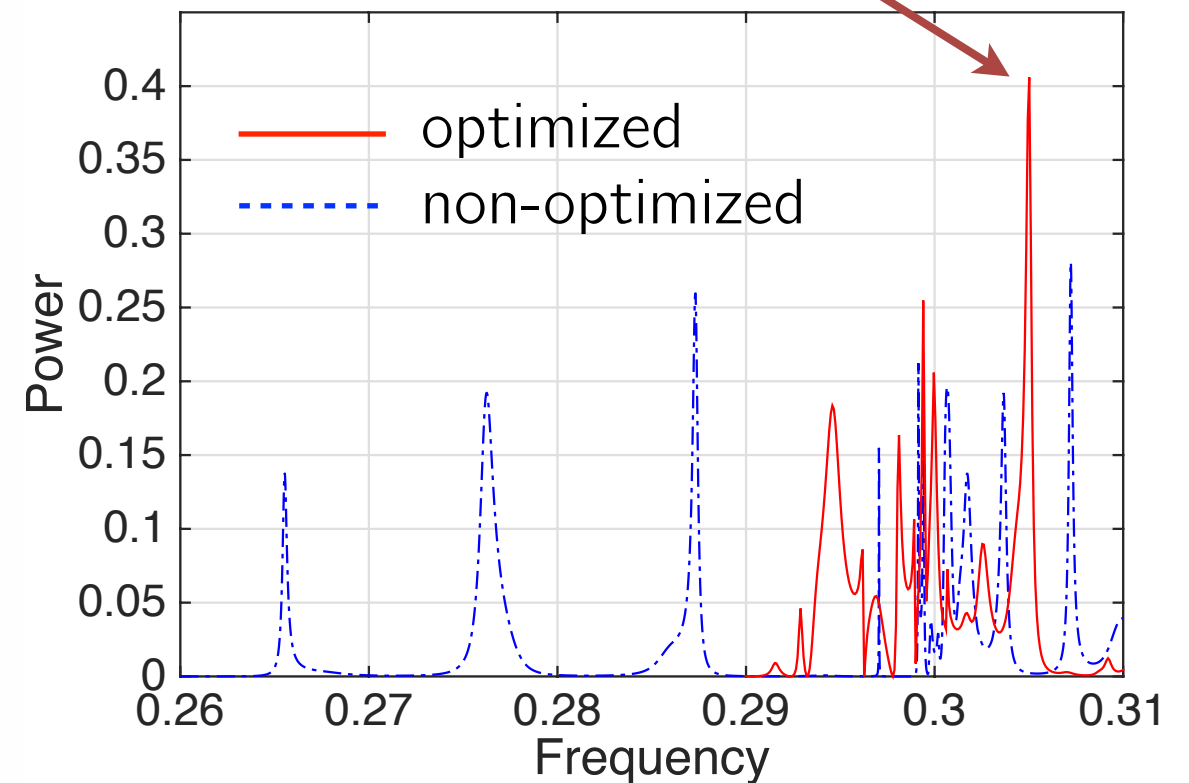
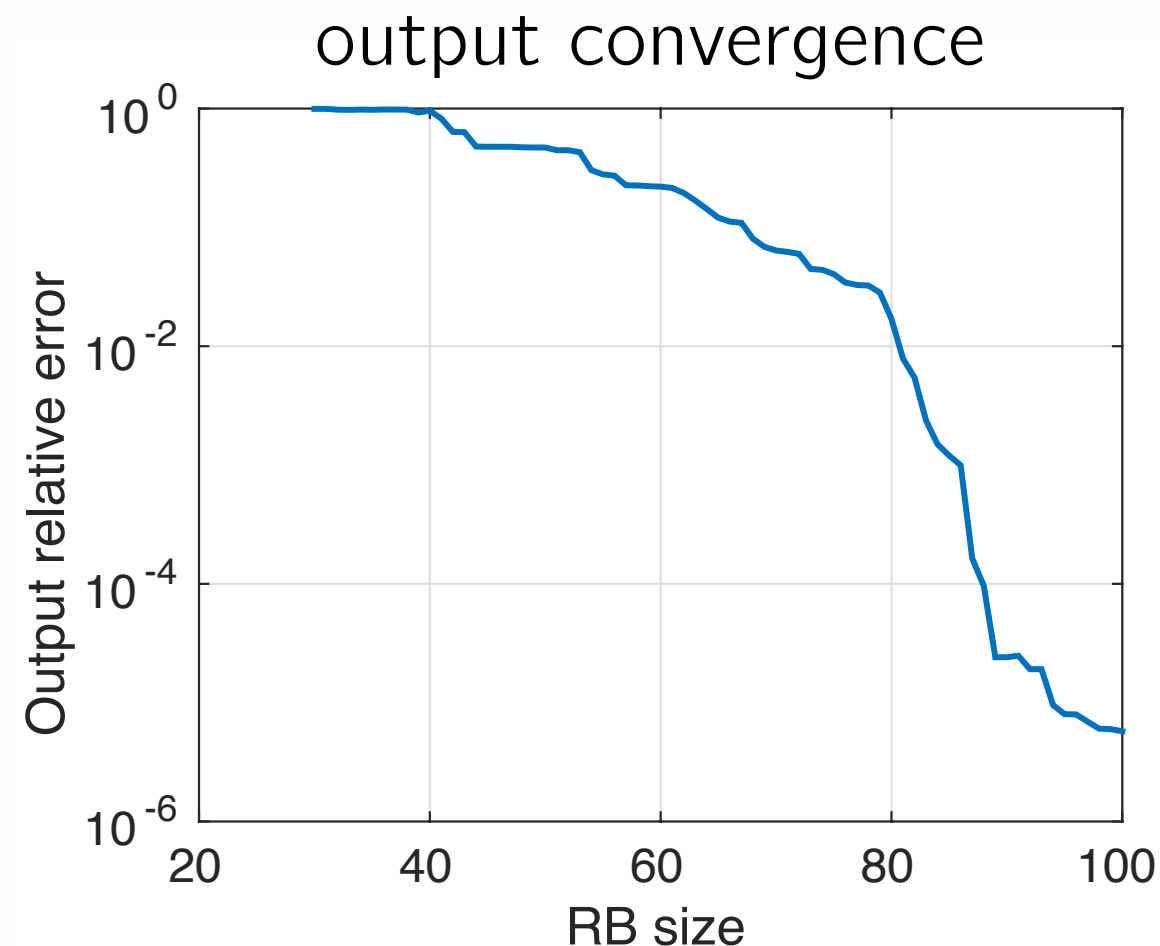
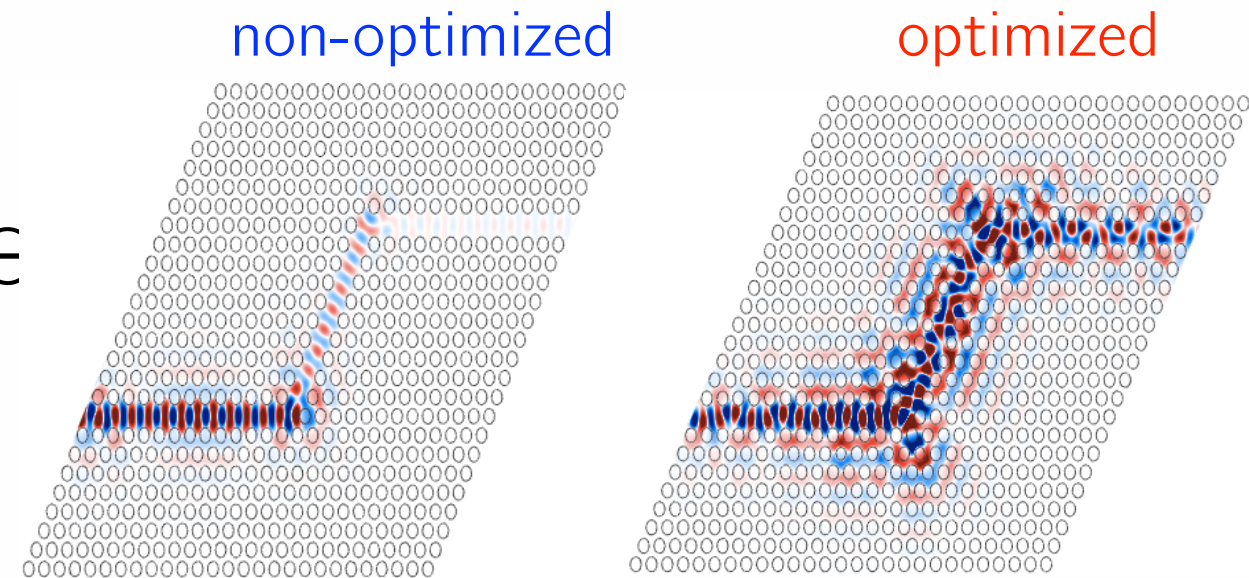


Shape optimization at discrete frequencies

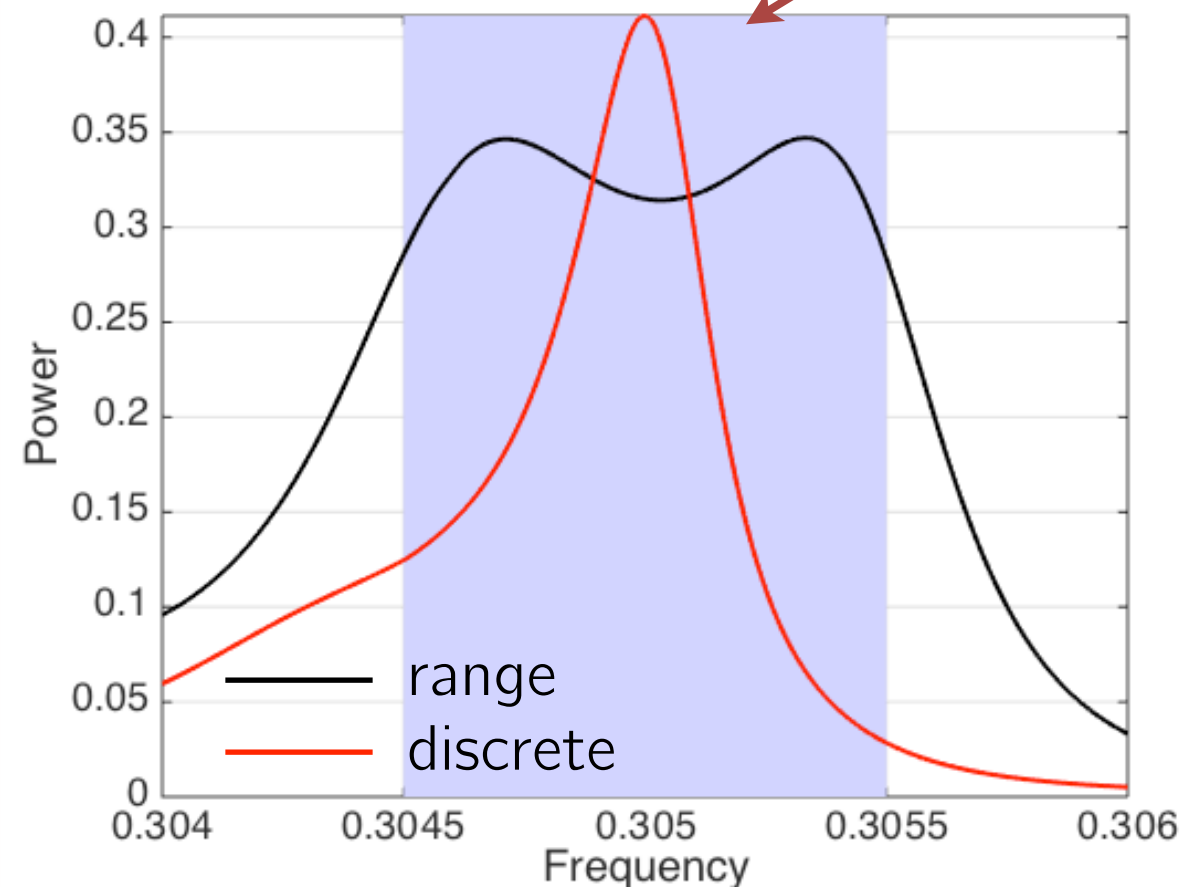
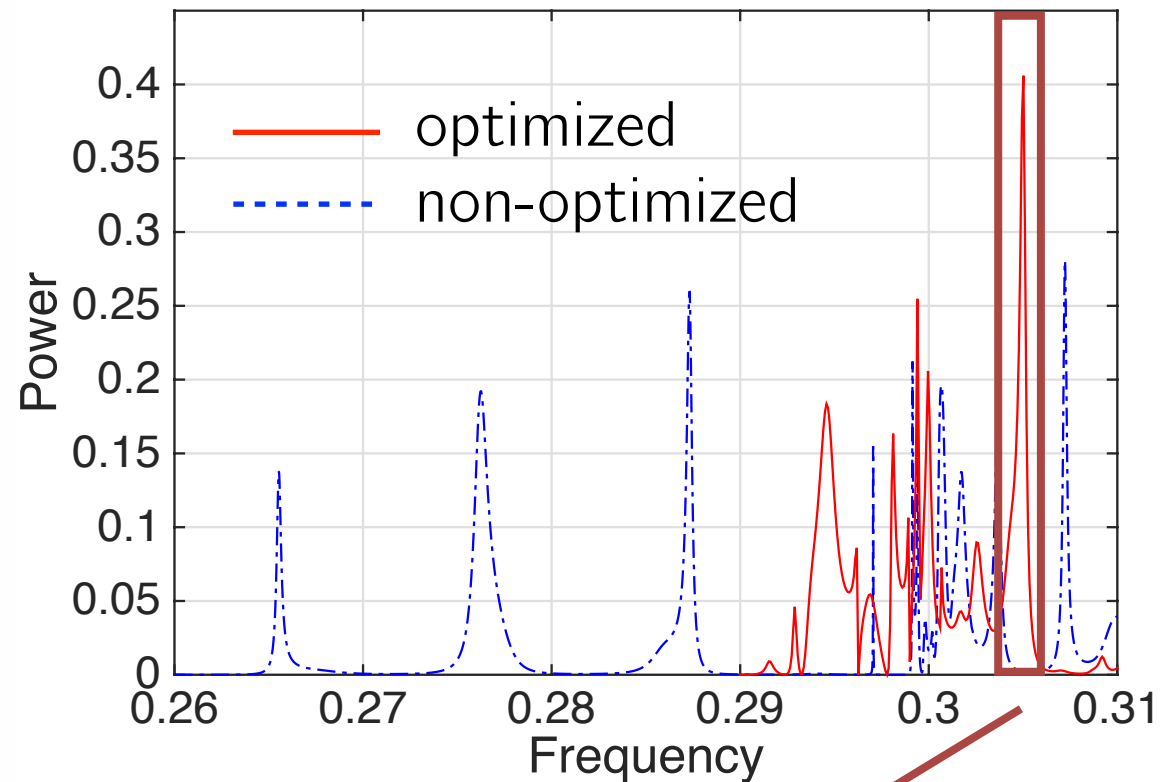
- ✓ Optimize radius of holes to maximize transmission [NLOPT-Johnson 10]

$$\max_{\theta} s \quad \text{where} \quad r_i = r_0(1 + \theta_i), \quad \theta_i \in \mathbb{E}$$

- ✓ Replace CG for RB on optimization subdomains: speedup ~ 150



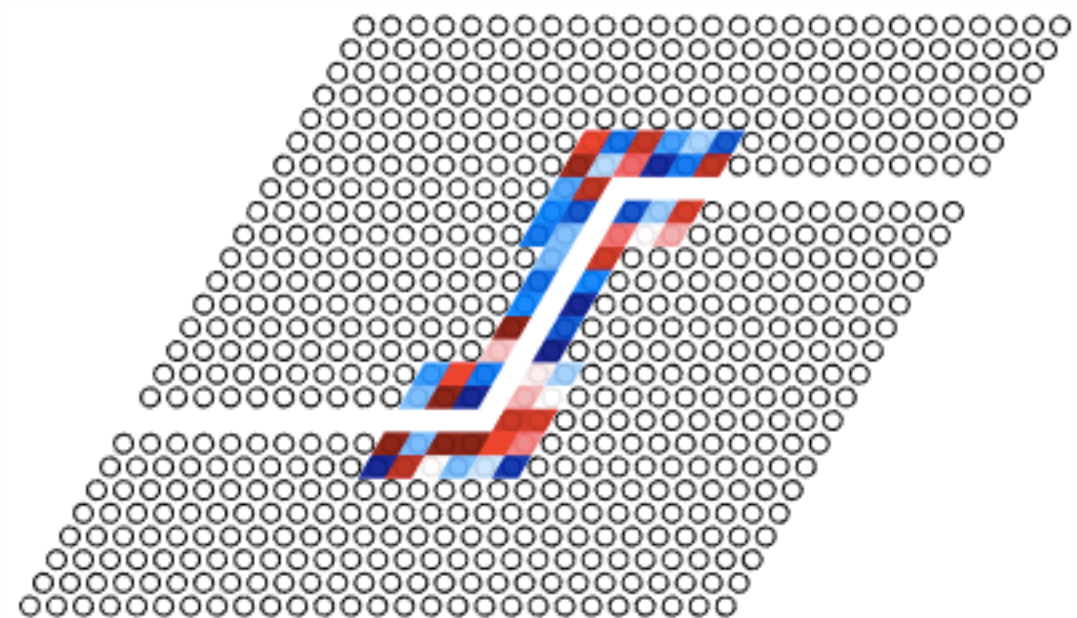
Shape optimization for range of frequencies



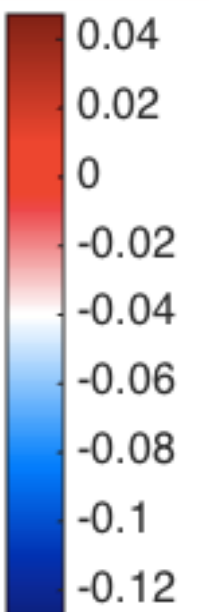
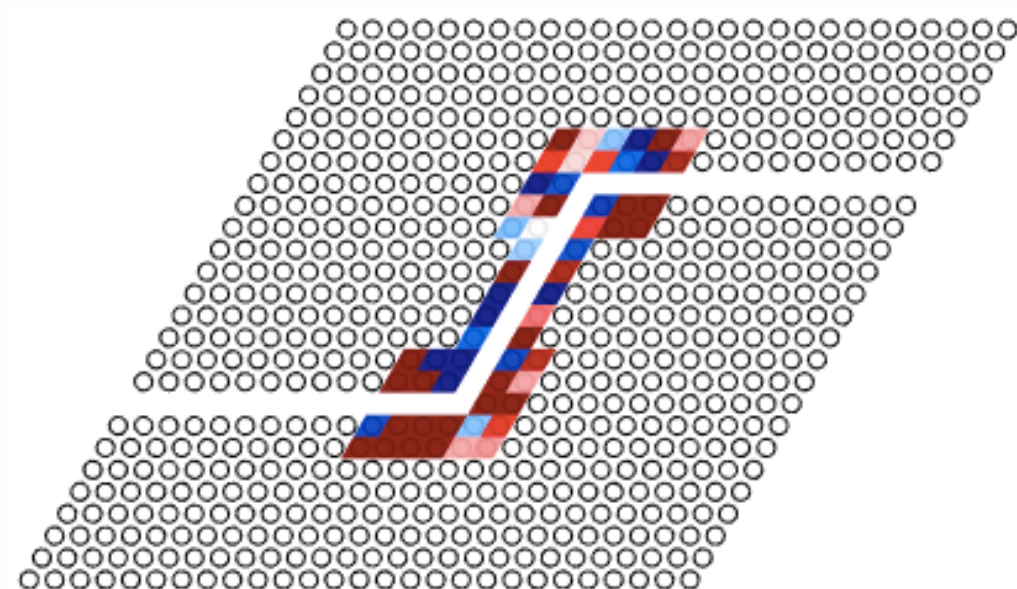
Objective function

$$s^* = \max_{\theta} E_{\omega}[s] - \gamma \sqrt{V_{\omega}[s]}$$

Discrete

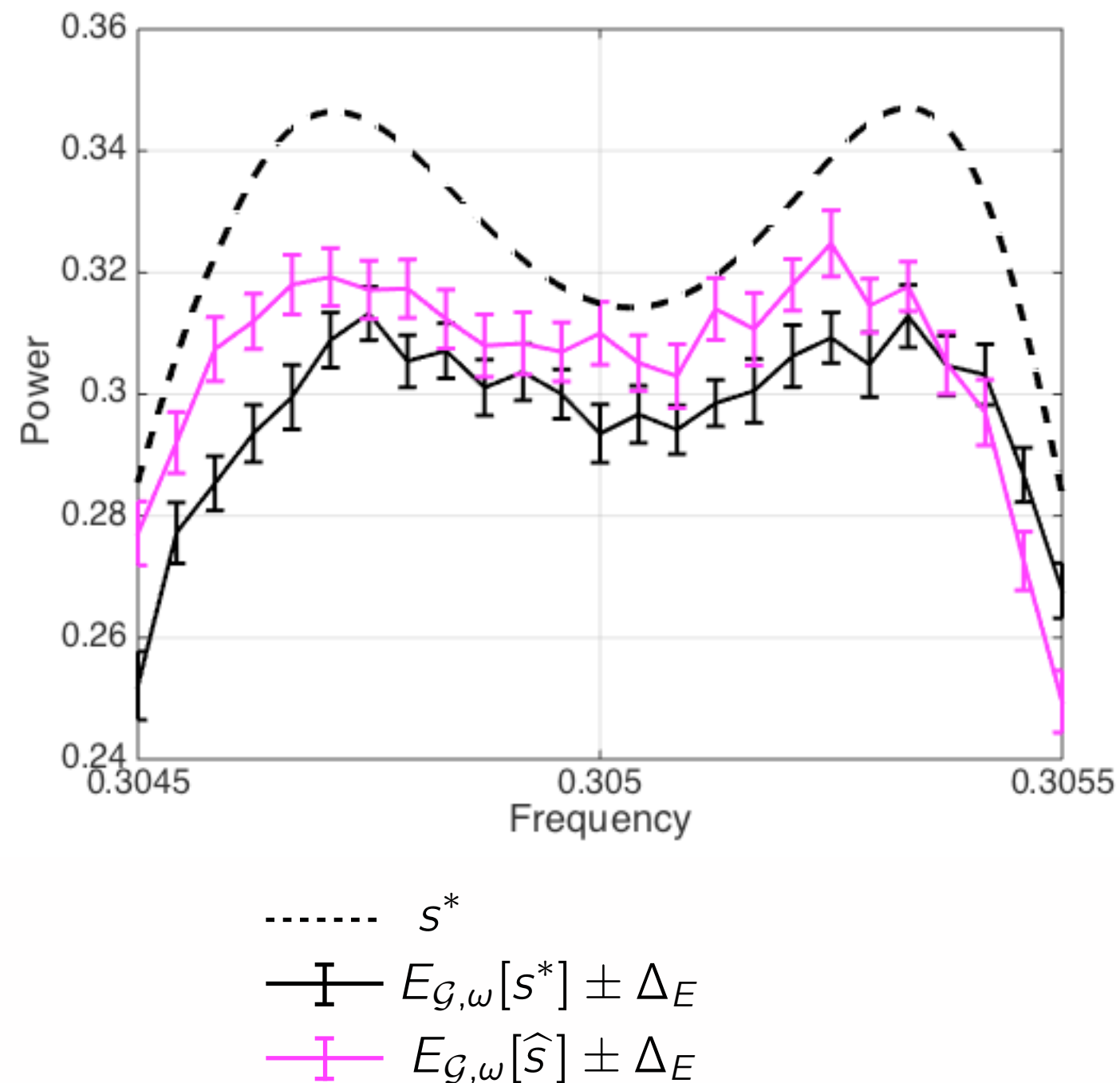


Range

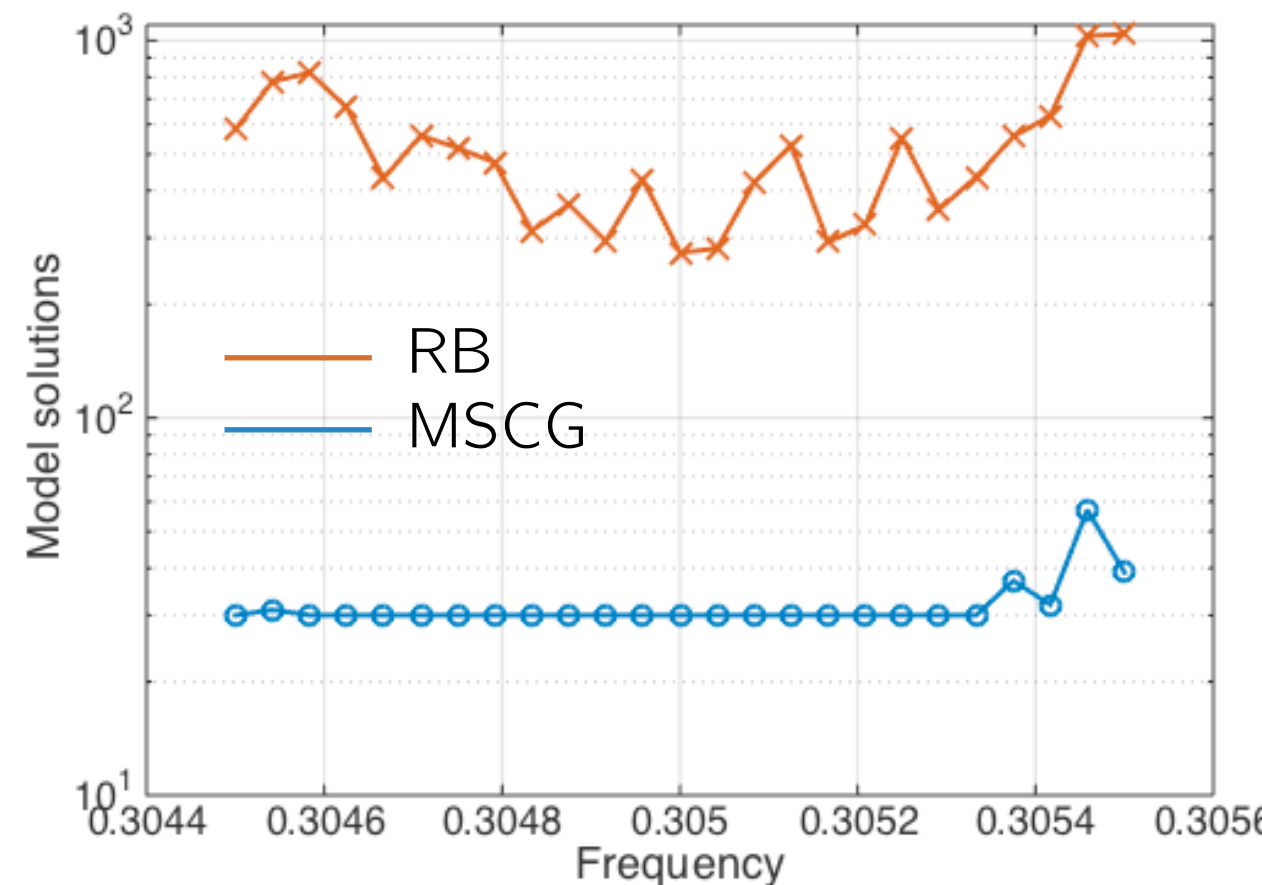


Robust shape optimization for range of frequencies

$$\hat{s} = \max_{\theta} E_{\mathcal{G},\omega}[s] - \gamma \sqrt{V_{\mathcal{G},\omega}[s]} \longrightarrow \text{MVR to approximate statistics}$$



- ✓ Robust design guarantees lower performance degradation
- ✓ MVR replaces expensive MSCG simulations for **cheaper RB** simulations

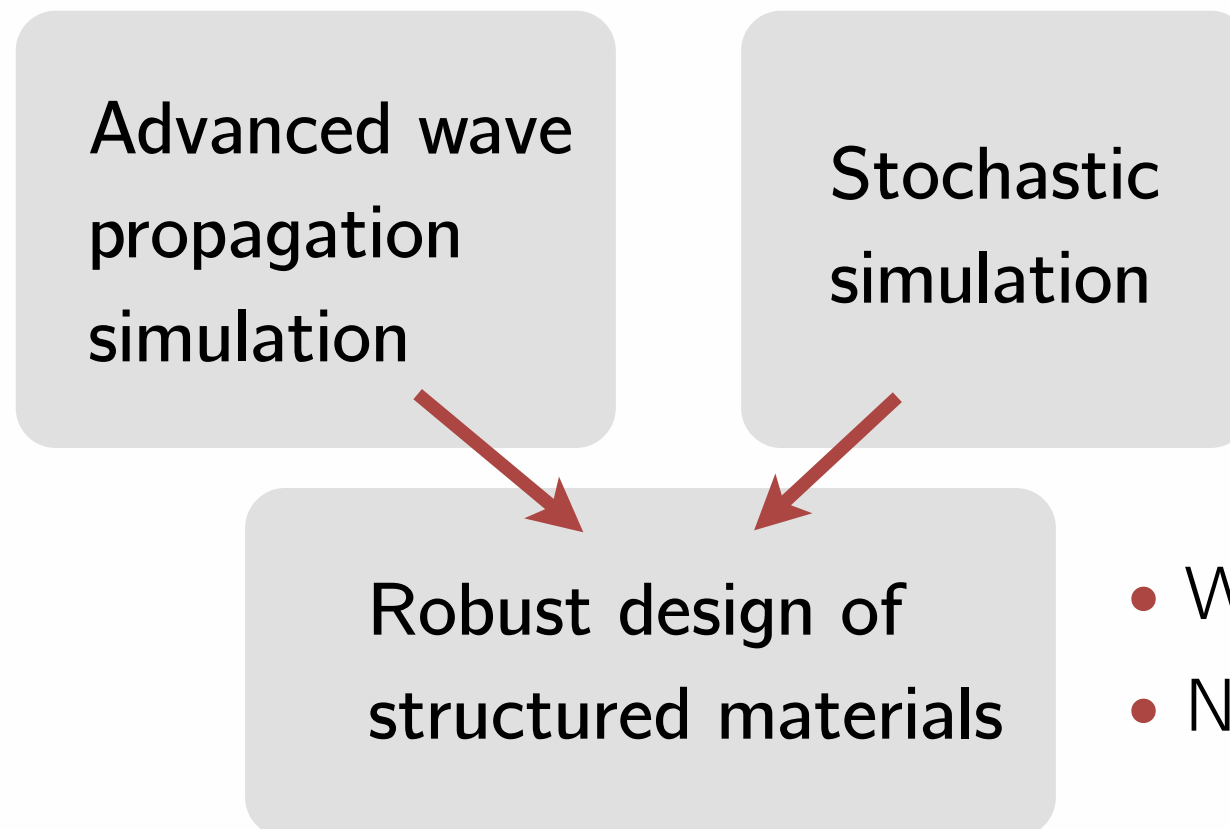


Multiscale model and variance reduction method for wave propagation in heterogeneous materials

- ✓ Multiscale CG exploits repeated patterns in domain
- ✓ Develop RB for geometry variations at the subdomain level
- ✓ Combine MSCG and RB on a multilevel estimator of output statistics
- ✓ Ideal for stochastic simulation and robust design of structured materials

- Multiscale CG method
- Deformable domains
- Helmholtz

- RB for MSCG
- Multilevel variance reduction



- Waveguides, splitters
- Nanogaps



Thanks for your attention

Questions?



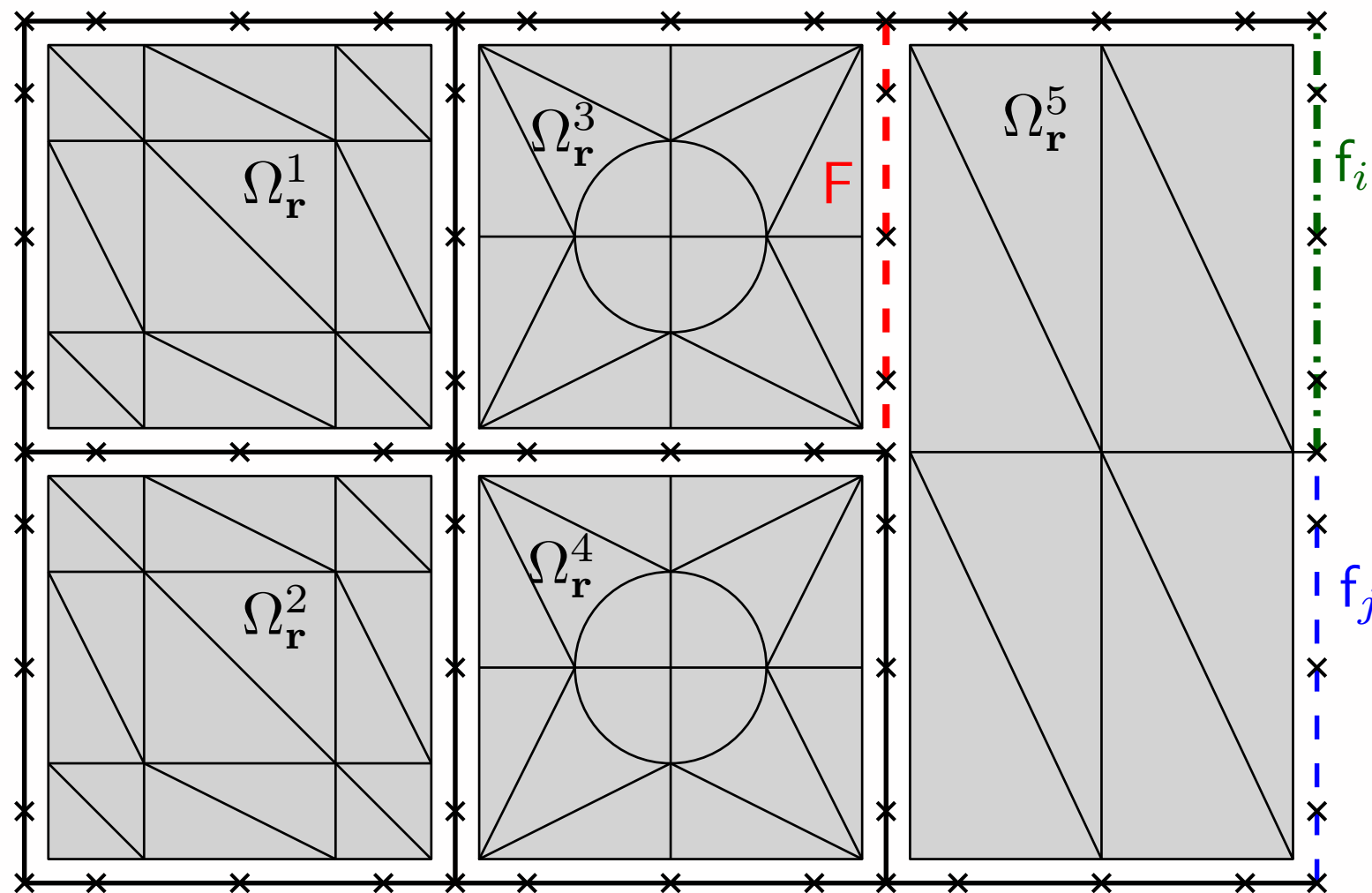
MultiScale CG - Spaces

$$W_h = \{w \in L^2(\Omega) : w \in \mathcal{C}^0(\Omega^m), w|_T \in \mathcal{P}^{p^m}(T), \forall T \in \mathcal{T}_h^m, 1 \leq m \leq M\},$$

$$W_h^m = \{w \in \mathcal{C}^0(\Omega^m), w|_T \in \mathcal{P}^{p^m}(T), \forall T \in \mathcal{T}_h^m\},$$

$$M_h = \{\mu \in L^2(\partial\Omega^m) : \Omega^m \in \mathcal{T}_h) : \mu|_{\partial\Omega^m} = w|_{\partial\Omega^m}, w \in W_h\},$$

$$V_h = \{v \in \mathcal{C}^0(\mathcal{F}_f) : v|_f \in \mathcal{P}^{p^f}(f), \forall f \in \mathcal{F}_f\}$$



$$\mathcal{F}_f = \{f_i, 1 \leq i \leq \sum_{\ell=1}^L N^\ell\}$$

MultiScale CG - Formulation

Introduce auxiliary variable $\mathbf{q}_h$ approximating the flux, with $[\![\mathbf{q}_h \cdot \mathbf{n}]\!]$ the normal component

Seek $(u_h, \lambda_h, \mathbf{q}_h) \in W_h \times V_h(u_D) \times M_h$

$$(\mathbf{q}_h, \nabla w)_\Omega - (k^2 u_h, w)_\Omega - \sum_{m=1}^M \langle \mathbf{q}_h \cdot \mathbf{n}, w \rangle_{\partial\Omega^m} = (f, w)_\Omega$$

$$u_h = P^{W_h^m}(\lambda_h), \quad \text{on } \mathcal{F}_f$$

$$\langle [\![\mathbf{q}_h \cdot \mathbf{n}]\!], v \rangle_{\mathcal{F}_f} = \langle g_N, v \rangle$$

for all $(w, v) \in W_h \times V_h(0)$

- ✓ Enforce continuity of the normal component of the flux across interfaces
- ✓ Uniqueness of solution can be proved

MultiScale CG - Formulation

Seek $(u_h^f|_{\Omega^m}, u_h^\eta|_{\Omega^m}) \in W_h^m(0) \times W_h^m(\eta)$

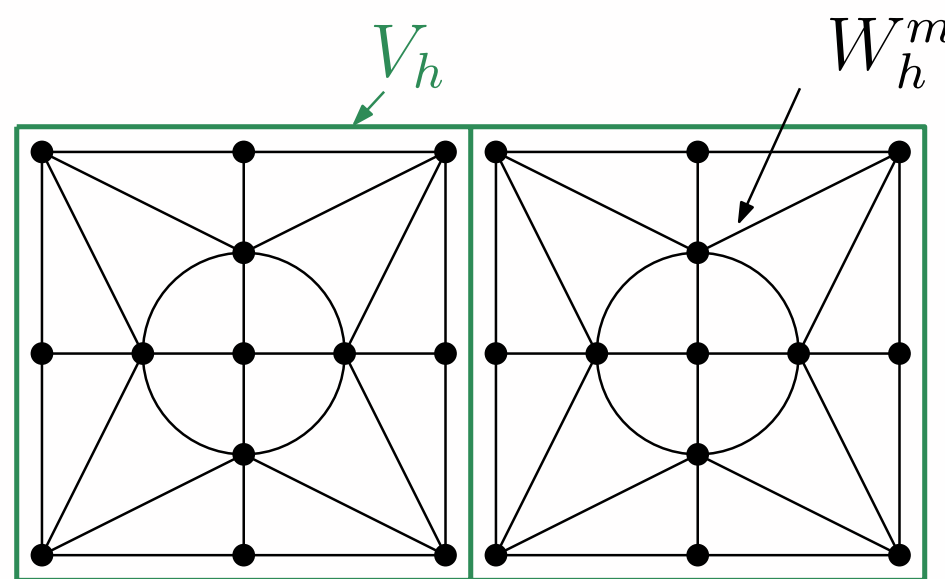
$$(\rho \mathbf{G} \nabla_{\mathbf{x}} u_h^f, \nabla_{\mathbf{x}} w)_{\Omega^m} - (k^2 u_h^f, w g)_{\Omega^m} = (f, w g)_{\Omega^m}, \quad \forall w \in W_h^m(0),$$

$$(\rho \mathbf{G} \nabla_{\mathbf{x}} u_h^\eta, \nabla_{\mathbf{x}} w)_{\Omega^m} - (k^2 u_h^\eta, w g)_{\Omega^m} = 0, \quad \forall w \in W_h^m(0)$$

Applying **linearity** and **superposition** we have $u_h = u_h^f + u_h^{\lambda_h}$

and the Lagrange multipliers $\lambda_h \in V_h(u_D)$ satisfy

$$(\rho \mathbf{G} \nabla_{\mathbf{x}} u_h^{\lambda_h}, \nabla_{\mathbf{x}} u_h^\mu)_{\Omega} - (k^2 u_h^{\lambda_h}, u_h^\mu g)_{\Omega} = (f, u_h^\mu g)_{\Omega} + \langle g_N, \mu \rangle_{\Omega_N}, \quad \forall \mu \in V_h(0)$$



MultiScale CG - Implementation

For each subdomain $\mathbb{A}^m \mathbf{u}_f^m = \mathbf{f}^m$ for BC $\varphi = \{\varphi_i\}_{i=1}^{N_m}$
 $\mathbb{A}^m \mathbf{u}_{\varphi_i}^m = \mathbb{A}_{\varphi_i}^m$

Assemble the elementary global matrices

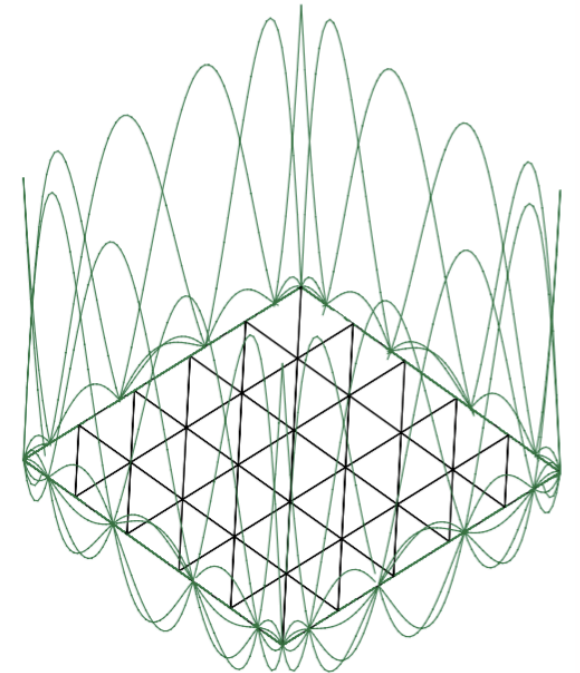
$$\mathbb{K}_{ij}^m = (\mathbf{u}_{\varphi_i}^m)^T \mathbb{A}^m \mathbf{u}_{\varphi_j}^m, \quad 1 \leq i, j \leq N_m$$

$$\mathbb{F}_i^m = (\mathbf{u}_{\varphi_i}^m)^T \mathbf{f}^m + \mathbf{g}_i^m, \quad 1 \leq i \leq N_m$$

Solve the global problem $\mathbb{K}\boldsymbol{\Lambda} = \mathbb{F}$ where $\boldsymbol{\lambda}_h = \sum_{i=1}^N \Lambda_i \varphi_i$

Recover the solution at each subdomain

$$\mathbf{u}^m = \mathbf{u}_f^m + \sum_{i=1}^{N_m} \Lambda_i \mathbf{u}_{\varphi_i}^m$$



MultiScale CG - Reduced basis and DEIM

Weak formulation for the Dirichlet problem

$$(\rho \mathbf{G} \nabla_{\mathbf{x}} u_h^\eta, \nabla_{\mathbf{x}} w)_{\Omega^m} - (k^2 u_h^\eta, w \mathbf{g})_{\Omega^m} = 0, \quad \forall w \in W_h^m(0)$$

Approximate geometry quantities using DEIM

$$\sum_{q=1}^Q \sigma_q(y) (\phi_q^G \rho \nabla_{\mathbf{x}} u_h^\eta, \nabla_{\mathbf{x}} w)_{\Omega^m} - \sum_{q=1}^{Q'} \sigma'_q(y) (k^2 u_h^\eta, w \phi_q^g)_{\Omega^m} = 0, \quad \forall w \in W_h^m(0)$$

Develop a single RB with POD for all possible BC. The RB solution is

$$\sum_{q=1}^Q \sigma_q(y) (\phi_q^G \rho \nabla_{\mathbf{x}} u_N^{\varphi_i}, \nabla_{\mathbf{x}} w)_{\Omega^m} - \sum_{q=1}^{Q'} \sigma'_q(y) (k^2 u_N^{\varphi_i}, w \phi_q^g)_{\Omega^m} = 0, \quad \forall w \in W_N^m(0)$$

Approximate the elementary global matrix

$$\mathbb{K}_{ij}^m \approx \sum_{q=1}^Q \sigma_q(y) (\phi_q^G \rho \nabla_{\mathbf{x}} u_N^{\varphi_j}, \nabla_{\mathbf{x}} u_N^{\varphi_i})_{\Omega^m} - \sum_{q=1}^{Q'} \sigma'_q(y) (k^2 u_N^{\varphi_j}, u_N^{\varphi_i} \phi_q^g)_{\Omega^m}$$

MultiScale CG - Reduced basis implementation

Empirical interpolation of mapping

$$\sum_{q=1}^Q \sigma_q(y) \mathbb{A}_q^m \mathbf{u}_{\varphi_i}^m = \boldsymbol{\varphi}_i$$

POD basis with all possible Dirichlet BC $\Phi = \{\zeta_1, \dots, \zeta_N\} \longrightarrow \mathbf{u}_{\varphi_i}^m = \Phi \mathbf{c}_i$

Galerkin projection to compute coefficients

$$\sum_{q=1}^Q \sigma_q(y) \Phi^T \mathbb{A}_q^m \Phi \mathbf{c}_i = \Phi^T \boldsymbol{\varphi}_i$$

Approximate global elementary matrix

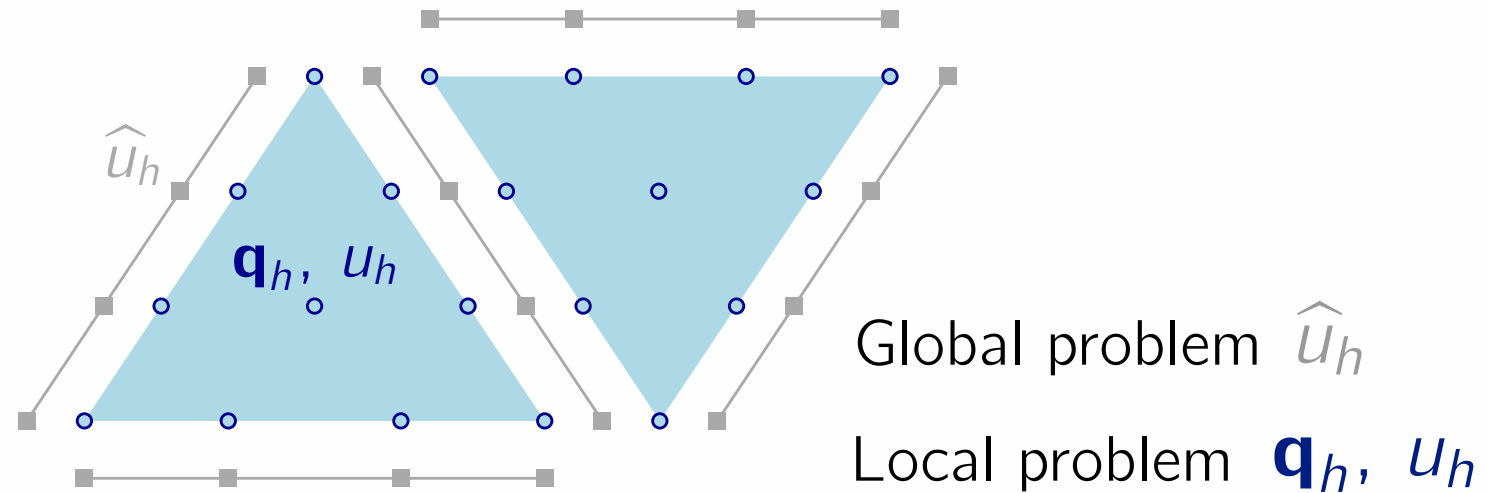
$$\mathbb{K}_{ij}^m \approx \sum_{q=1}^Q \sigma_q(y) \mathbf{c}_i^T \Phi^T \mathbb{A}_q^m \Phi \mathbf{c}_j, \quad 1 \leq i, j \leq N_m$$

$$\mathbb{F}_i^m \approx \mathbf{c}_i^T \Phi^T \mathbf{f}^m + \mathbf{g}_i^m, \quad 1 \leq i \leq N_m$$

Contribution #2: Reduced basis for HDG

Reduced basis for hybridizable discontinuous Galerkin method

$$\begin{aligned} \mathbf{q} - \nabla u &= 0 & \mathbf{x} \in \Omega \\ -\nabla \cdot (\rho \mathbf{q}) + k^2 u &= f & \mathbf{x} \in \Omega \\ \rho \mathbf{q} \cdot \mathbf{n} + \nu u &= g & \mathbf{x} \in \partial\Omega \end{aligned}$$



In [158] we propose a new weak formulation

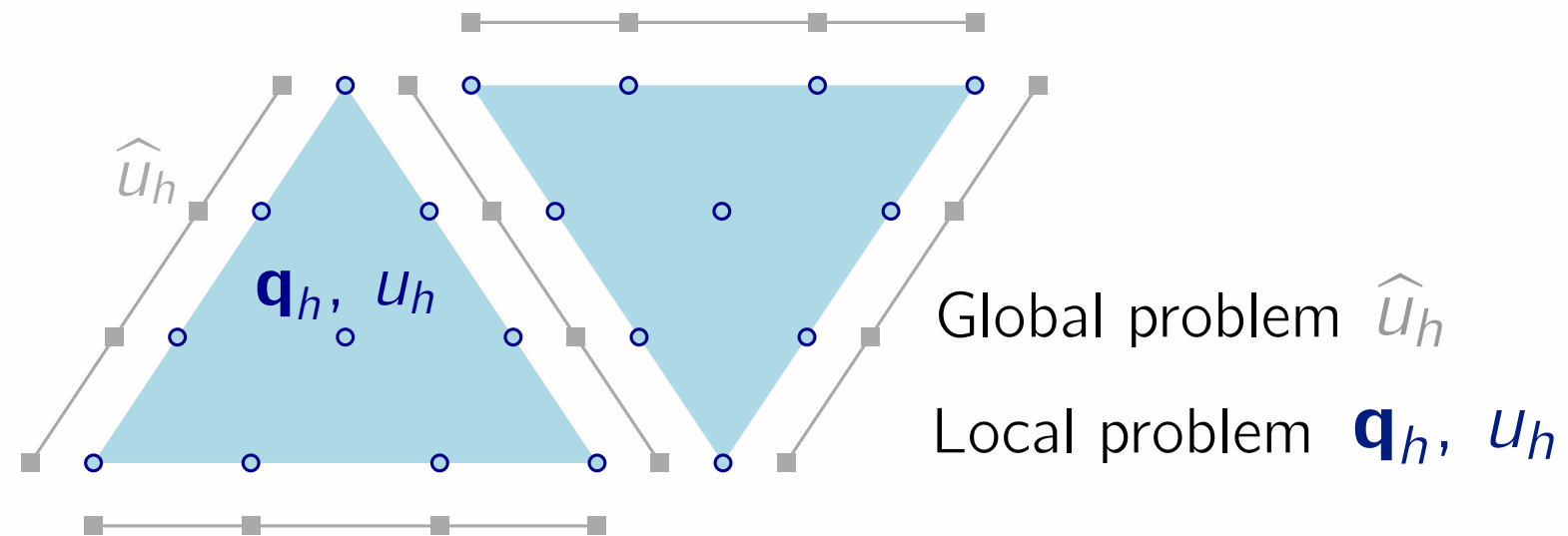
- ✓ Approximate only $u_h, \hat{u}_h$ by setting $\mathbf{q}_h(u_h, \hat{u}_h) \longrightarrow$ RB projection
- ✓ Retain affine parametric dependence of ρ, k^2, ν
- ✓ Solve a system with global variables $\hat{u}_h$ only

Wave Propagation - HDG formulation

Hybridizable Discontinuous Galerkin (HDG) method

Helmholtz equation

$$\begin{aligned} \mathbf{q} - \nabla u &= 0 & \mathbf{x} \in \Omega \\ -\nabla \cdot (\rho \mathbf{q}) + k^2 u &= f & \mathbf{x} \in \Omega \\ \rho \mathbf{q} \cdot \mathbf{n} + \nu u &= g & \mathbf{x} \in \partial\Omega \end{aligned}$$



Why HDG?

- High order approximations
- Low dispersion (irregular grids)
- Solve for reduced DOF problem

HDG solution

$$\begin{array}{c} \text{block diagonal} \\ \uparrow \\ \left[\begin{array}{cc|c} \mathbf{A} & \mathbf{B} & -\mathbf{C} \\ \mathbf{W} & \mathbf{D} & -\mathbf{E} \\ \mathbf{N} & -\mathbf{E}^* & \mathbf{M} \end{array} \right] \begin{bmatrix} \mathbf{Q} \\ \mathbf{U} \\ \hat{\mathbf{U}} \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{F} \\ \mathbf{G} \end{bmatrix} \end{array}$$

- Solve for global DOF $\mathbf{T}\hat{\mathbf{U}} = \mathbf{R}$ (Schur complement)
- Recover local DOF $\mathbf{Q}, \mathbf{U}$ element-wise

Projection for RB with HDG

$$\begin{aligned}
 \mathbf{q} - \nabla u &= 0 & \mathbf{x} \in \Omega \\
 -\nabla \cdot (\rho \mathbf{q}) + k^2 u &= f & \mathbf{x} \in \Omega \\
 \rho \mathbf{q} \cdot \mathbf{n} + \nu u &= g & \mathbf{x} \in \partial\Omega
 \end{aligned}
 \longrightarrow
 \begin{bmatrix} \mathbf{A} & \mathbf{B} & -\mathbf{C} \\ \mathbf{W} & \mathbf{D} & -\mathbf{E} \\ \mathbf{N} & -\mathbf{E}^* & \mathbf{M} \end{bmatrix}
 \begin{bmatrix} \mathbf{Q} \\ \mathbf{U} \\ \hat{\mathbf{U}} \end{bmatrix}
 =
 \begin{bmatrix} \mathbf{0} \\ \mathbf{F} \\ \mathbf{G} \end{bmatrix}$$

Which DOF should we use to parametrize snapshot ζ ?

✗ Projection using all degrees of freedom $\zeta = \begin{bmatrix} \mathbf{Q} \\ \mathbf{U} \\ \hat{\mathbf{U}} \end{bmatrix} \longrightarrow$ Large offline computational cost

✗ Projection using numerical traces $\zeta = [\hat{\mathbf{U}}] \longrightarrow$ Lose affine dependency

$$\mathbf{T}\hat{\mathbf{U}} = \mathbf{R}$$

$$\mathbf{T} = \mathbf{M} + [\mathbf{N} \quad -\mathbf{E}^*] \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{W} & \mathbf{D} \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{C} \\ \mathbf{E} \end{bmatrix}
 \qquad
 \mathbf{R} = \mathbf{G} - [\mathbf{N} \quad -\mathbf{E}^*] \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{W} & \mathbf{D} \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{0} \\ \mathbf{F} \end{bmatrix}$$

✓ Projection using $\zeta = \begin{bmatrix} \mathbf{U} \\ \hat{\mathbf{U}} \end{bmatrix} \longrightarrow$ HDG natural norm, retain affine dependency

$$\mathbf{Q} = \mathbf{A}^{-1} (\mathbf{C}\hat{\mathbf{U}} - \mathbf{B}\mathbf{U}) \longrightarrow
 \begin{bmatrix} \mathbf{D} - \mathbf{W}\mathbf{A}^{-1}\mathbf{B} & \mathbf{W}\mathbf{A}^{-1}\mathbf{C} - \mathbf{E} \\ -\mathbf{E}^* - \mathbf{N}\mathbf{A}^{-1}\mathbf{B} & \mathbf{M} + \mathbf{N}\mathbf{A}^{-1}\mathbf{C} \end{bmatrix}
 \begin{bmatrix} \mathbf{U} \\ \hat{\mathbf{U}} \end{bmatrix}
 =
 \begin{bmatrix} \mathbf{F} \\ \mathbf{G} \end{bmatrix}$$

Eliminate $\mathbf{Q}$ with first equation

HDG formulation

- Approximation spaces

$$W_h^p = \{w \in L^2(D) : w|_K \in \mathcal{P}^p(K), \forall K \in \mathcal{T}_h\}$$

$$\mathbf{V}_h^p = \{\mathbf{v} \in [L^2(D)]^d : \mathbf{v}|_K \in [\mathcal{P}^p(K)]^d, \forall K \in \mathcal{T}_h\}$$

$$M_h^p = \{\mu \in L^2(\mathcal{E}_h) : \mu|_F \in \mathcal{P}^p(F), \forall F \in \mathcal{E}_h\}$$

- Define numerical traces

$$\hat{\mathbf{q}}_h = \mathbf{q}_h - \tau(u_h - \hat{u}_h)\mathbf{n}, \text{ on } \partial K$$

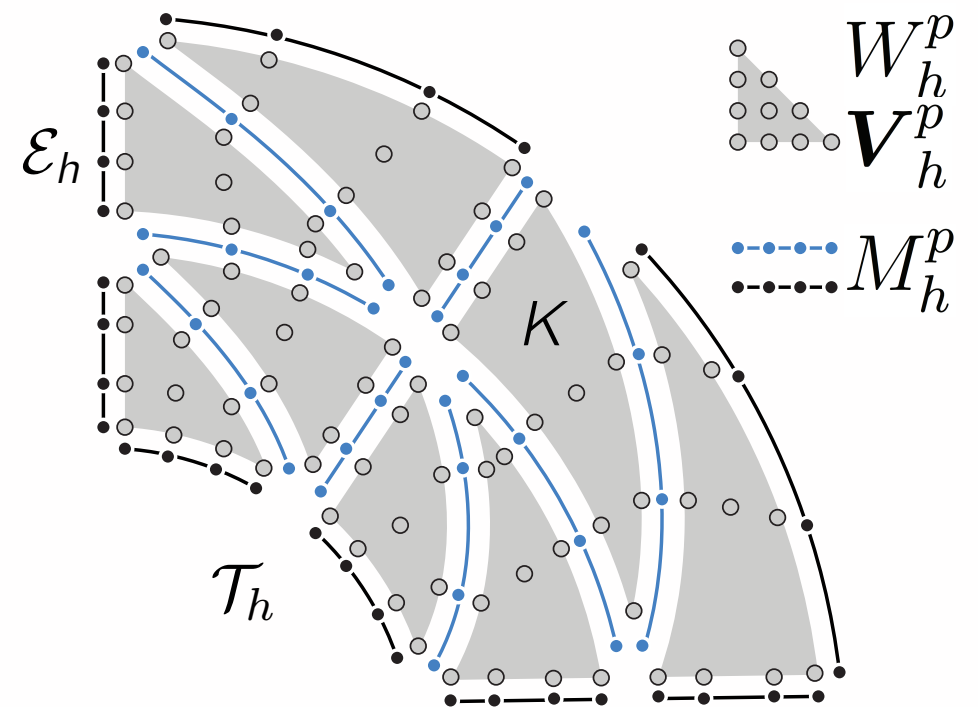
- Find $(\mathbf{q}_h, u_h, \hat{u}_h) \in \mathbf{V}_h^p \times W_h^p \times M_h^p$ such that $\forall (\mathbf{v}, w, \mu) \in \mathbf{V}_h^p \times W_h^p \times M_h^p$

$$(\mathbf{q}_h, \mathbf{v})_{\mathcal{T}_h} + (u_h, \nabla \cdot \mathbf{v})_{\mathcal{T}_h} - \langle \hat{u}_h, \mathbf{v} \cdot \mathbf{n} \rangle_{\partial \mathcal{T}_h} = 0,$$

$$(\rho \mathbf{q}_h, \nabla w)_{\mathcal{T}_h} - \langle \rho \mathbf{q}_h \cdot \mathbf{n}, w \rangle_{\partial \mathcal{T}_h} - (k^2 u_h, w)_{\mathcal{T}_h} + \langle \rho \tau(u_h - \hat{u}_h), w \rangle_{\partial \mathcal{T}_h} = (f, w)_{\mathcal{T}_h}$$

$$\langle \rho \mathbf{q}_h \cdot \mathbf{n}, \mu \rangle_{\partial \mathcal{T}_h} - \langle \rho \tau u_h, \mu \rangle_{\partial \mathcal{T}_h} + \langle \rho \tau \hat{u}_h, \mu \rangle_{\partial \mathcal{T}_h} + \langle \nu \hat{u}_h, \mu \rangle_{\partial \mathcal{D}} = (g, w)_{\partial \mathcal{D}}$$

Local
Global



$$\begin{bmatrix} \mathbf{A} & \mathbf{B} & -\mathbf{C} \\ \mathbf{W} & \mathbf{D} & -\mathbf{E} \\ \mathbf{N} & -\mathbf{E}^* & \mathbf{M} \end{bmatrix} \begin{bmatrix} \mathbf{Q} \\ \mathbf{U} \\ \hat{\mathbf{U}} \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{F} \\ \mathbf{G} \end{bmatrix}$$

Solve for global dof $\mathbf{T}\hat{\mathbf{U}} = \mathbf{R}$

Recover local dof $\mathbf{Q}, \mathbf{U}$

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{W} & \mathbf{D} \end{bmatrix} \text{ Block-diagonal and invertible}$$

A *posteriori* error estimate for expectation

Control variates $\longrightarrow E[s] = E[s - s_{N_1}] + E[s_{N_1}]$

MVR estimator $\longrightarrow E_{M_0, M_1}[s] = E_{M_0}[s - s_{N_1}] + E_{M_1}[s_{N_1}]$

i.i.d samples

$$Z_0 = E[s - s_{N_1}] - E_{M_0}[s - s_{N_1}] \sim N\left(0; \frac{V[s - s_{N_1}]}{M_0}\right)$$

$$Z_1 = E[s_{N_1}] - E_{M_1}[s_{N_1}] \sim N\left(0; \frac{V[s_{N_1}]}{M_1}\right)$$

$$Z_0 + Z_1 = E[s] - E_{M_0, M_1}[s] \sim N\left(0; \underbrace{\frac{V[s - s_{N_1}]}{M_0} + \frac{V[s_{N_1}]}{M_1}}_{\sigma_{MVR}^2}\right)$$

Central limit theorem to establish confidence bounds

$$\lim_{M_0 \rightarrow \infty} \lim_{M_1 \rightarrow \infty} \Pr(|E[s] - E_{M_0, M_1}[s]| \leq a \sigma_{MVR}) = \operatorname{erf}\left(\frac{a}{\sqrt{2}}\right), \quad \forall a \geq 0$$

Optimal weights (I)

- ✓ Precompute MSCG-RB outputs $s, s_{N_\ell}, 1 \leq N_\ell \leq N_{\max}$ for M samples
- ✓ Approximate $V_{M_\ell}[s_{N_\ell} - s_{N_{\ell+1}}]$ (*a posteriori*) with $V_M[s_{N_\ell} - s_{N_{\ell+1}}]$ (*a priori*)
- ✓ Surrogate online cost can be expressed as

$$\hat{C}_{L-MVR} = \sum_{\ell=0}^L \frac{\hat{C}^\ell}{w_\ell} = \frac{a^2}{\Delta_E^2} \left[(t_s + t_{N_1}) \frac{V_M[s - s_{N_1}]}{w_0} + t_{N_L} \frac{V_M[s_{N_L}]}{w_L} + \sum_{\ell=1}^{L-1} (t_{N_\ell} + t_{N_{\ell+1}}) \frac{V_M[s_{N_\ell} - s_{N_{\ell+1}}]}{w_\ell} \right]$$

Optimal weights (II)

✓ Fix level sizes $(\bar{N}_1, \dots, \bar{N}_L) \longrightarrow$ optimize over weights

$$(w_0^*, w_1^*, \dots, w_L^*) = \arg \min \hat{C}_{L-MVR}(\bar{N}_1, \dots, \bar{N}_L)$$
$$\text{s.t.} \quad \sum_{\ell=0}^L w_\ell = 1, \quad w_\ell \geq 0$$

✓ Optimal weights have closed formula

$$w_\ell^* = \frac{\sqrt{\hat{C}^\ell / \hat{C}^0}}{\sum_{\ell'=0}^L \sqrt{\hat{C}^{\ell'} / \hat{C}^0}}, \quad \ell = 0, \dots, L.$$

✓ Exhaustive search $\longrightarrow$ select $(L, N, \mathbf{w})$ with lowest $\hat{C}_{L-EIMVR}$

Empirical interpolation applied to MVR

Choose $N_1 > N_2 > \dots > N_L$ and define L -EIMVR estimator

$$E_{M_0, \dots, \hat{M}_L}[s] = E_{M_0}[s - s_{N_1}] + \sum_{\ell=1}^{L-1} E_{M_\ell}[s_{N_\ell} - s_{N_{\ell+1}}] + E_{M_L}[s_{N_L} - \hat{s}_{N_L}] + E_{\hat{M}_L}[\hat{s}_{N_L}]$$

$\xrightarrow{\text{\# samples } M_\ell}$
 $\xleftarrow{\text{output evaluation complexity}}$

For i.i.d. samples between levels, we apply the central limit theorem

$$\lim_{M_0 \rightarrow \infty} \dots \lim_{\hat{M}_L \rightarrow \infty} \Pr \left(|E[s] - E_{M_0, \dots, \hat{M}_L}[s]| \leq \Delta_{\hat{E}} \right) = \text{erf} \left(\frac{a}{\sqrt{2}} \right), \quad \forall a \geq 0$$

and obtain the *a posteriori* error bound

$$\Delta_{\hat{E}} = a \sqrt{\frac{V_{M_0}[s - s_{N_1}]}{M_0} + \sum_{\ell=1}^{L-1} \frac{V_{M_\ell}[s_{N_\ell} - s_{N_{\ell+1}}]}{M_\ell} + \frac{V_{M_L}[s_{N_L} - \hat{s}_{N_L}]}{M_L} + \frac{V_{\hat{M}_L}[\hat{s}_{N_L}]}{\hat{M}_L}}$$

Empirical interpolation applied to MVR

Estimator for variance

Define $\zeta = \left(s - E_{M_0, M_1, \hat{M}_1}[s]\right)^2$, $\zeta_N = \left(s_N - E_{M_0, M_1, \hat{M}_1}[s]\right)^2$

$$\hat{\zeta}_N = \left(\hat{s}_N - E_{M_0, M_1, \hat{M}_1}[s]\right)^2$$

and reuse multilevel expression

$$V_{M_0, M_1, \hat{M}_1}[s] = E_{M_0}[\zeta - \zeta_N] + E_{M_1}[\zeta_N - \hat{\zeta}_N] + E_{\hat{M}_1}[\hat{\zeta}_N]$$

+ error bounds

Estimator for gradient

$$E_{M_0, M_1, \hat{M}_1}[\nabla s] = E_{M_0}[\nabla s - \nabla s_N] + E_{M_1}[\nabla s_N - \nabla \hat{s}_N] + E_{\hat{M}_1}[\nabla \hat{s}_N]$$

+ error bounds

Extension to arbitrary number of levels is straightforward

Error and cost equation

For a prescribed tolerance Δ

$$\Delta^2 = \underbrace{a^2 \frac{V_{M_0}[s - s_{N_1}]}{M_0}}_{= w_0 \Delta^2} + \sum_{\ell=1}^{L-1} \underbrace{a^2 \frac{V_{M_\ell}[s_{N_\ell} - s_{N_{\ell+1}}]}{M_\ell}}_{= w_\ell \Delta^2} + \underbrace{a^2 \frac{V_{M_L}[s_{N_L} - \hat{s}_{N_L}]}{M_L}}_{= w_L \Delta^2} + \underbrace{a^2 \frac{V_{\hat{M}_L}[\hat{s}_{N_L}]}{\hat{M}_L}}_{= \hat{w}_L \Delta^2}$$

Termination condition MC

Cost of L -MVR estimator

$$C_{L-EIMVR} = (t_s + t_{N_1}) M_0 + t_{N_L} M_L + \sum_{\ell=1}^{L-1} (t_{N_\ell} + t_{N_{\ell+1}}) M_\ell \quad \text{alternatively...}$$

$$C_{L-EIMVR} = \frac{a^2}{\epsilon_{\text{tol}}^2} \left[(t_s + t_{N_1}) \frac{V_{M_0}[s - s_{N_1}]}{w_0} + t_{N_L} \frac{V_{M_L}[s_{N_L} - \hat{s}_{N_L}]}{w_L} + \sum_{\ell=1}^{L-1} (t_{N_\ell} + t_{N_{\ell+1}}) \frac{V_{M_\ell}[s_{N_\ell} - s_{N_{\ell+1}}]}{w_\ell} \right]$$

Optimal weights (I)

- ✓ Fix N_L and precompute EI output at $M_L + \hat{M}_L$ samples
- ✓ Precompute HDG-RB outputs s, s_{N_ℓ} , $N_L \leq N_\ell \leq N_{\max}$ for M samples
- ✓ Approximate $V_{M_\ell}[s_{N_\ell} - s_{N_{\ell+1}}]$ (*a posteriori*) with $V_M[s_{N_\ell} - s_{N_{\ell+1}}]$ (*a priori*)
- ✓ Surrogate online cost can be expressed as

$$\hat{C}_{L-EIMVR} = \sum_{\ell=0}^L \frac{\hat{C}^\ell}{w_\ell} = \frac{a^2}{\Delta^2} \left[(t_s + t_{N_1}) \frac{V_M[s - s_{N_1}]}{w_0} + t_{N_L} \frac{V_M[s_{N_L} - \hat{s}_{N_L}]}{w_L} + \sum_{\ell=1}^{L-1} (t_{N_\ell} + t_{N_{\ell+1}}) \frac{V_M[s_{N_\ell} - s_{N_{\ell+1}}]}{w_\ell} \right]$$

Optimal weights (II)

✓ Compute weight for EI level $\hat{w}_L = \frac{a^2}{\Delta^2} \frac{V_{\hat{M}_L}[\hat{s}_{N_L}]}{\hat{M}_L}$

✓ Fix level sizes $(\bar{N}_1, \dots, \bar{N}_L) \longrightarrow$ optimize over weights

$$(w_0^*, w_1^*, \dots, w_L^*) = \arg \min \hat{C}_{L-EIMVR}(\bar{N}_1, \dots, \bar{N}_L)$$

$$\text{s.t.} \quad \sum_{\ell=0}^L w_\ell = 1 - \hat{w}_L, \quad w_\ell \geq 0$$

✓ Optimal weights have closed formula

$$w_\ell^* = \frac{\sqrt{\hat{C}^\ell / \hat{C}^0}}{\sum_{\ell'=0}^L \sqrt{\hat{C}^{\ell'} / \hat{C}^0}}, \quad \ell = 0, \dots, L.$$

✓ Exhaustive search $\longrightarrow$ select (L, N, w) with lowest $\hat{C}_{L-EIMVR}$

Stochastic simulation: 1d numerical verification

$$\begin{aligned}
 -\nabla \cdot (\rho \nabla u) &= f & x \in \Omega \\
 \rho \nabla u &= 0 & x = 1 \\
 u &= 0 & x = 0
 \end{aligned}
 \quad
 \rho = \sum_{q=1}^{10} y_q \mathbf{1}_{\Omega_q}$$

Compare MC with MVR given by

$$E_{M/10,M}[s] = E_{M/10}[s - s_5] + E_M[s_5]$$

