

# “Beyond Wave-Pinning; Dynamical Mechanisms for Cell Polarity and Interdigitation.”

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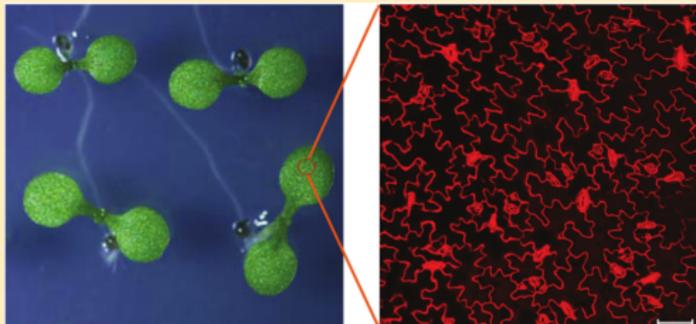


- 1 Introduction (Motivation and quick review of previous works).
- 2 Our Results.
  - Prototype model for cell polarisation.
  - Pavement cells.
- 3 Conclusions and Future Research.



# Pavement cells: Understanding the puzzle.

## Jigsaw-like pattern in pavement cells



Reproduced from [Lin et al. 2014]. Cotyledon of *Arabidopsis thaliana*.  
Scale bar 50[ $\mu m$ ]

## Factors

- Turgor Pressure.
- Pressure of Adjacent cells.
- Concentration of Rho-proteins of Plants (ROPs).



# Cell Polarisation induced by a spatial gradient.

## Cell Polarisation

The ability of a cell to form a front and a back, establishing a polarisation axis.



## Studied in.

- *Budding yeast*
- Amoeba (*Dictyostelium discoideum*)
- Fibroblasts
- white blood cells
- nerve cells.

## Role of Cell Polarisation.

is a primary step in . . .

- Motility.
- Cell Differentiation.

Disruption of cell polarity is a hallmark of cancer



# Modelling: Reaction-Diffusion systems.

## Polarised profile.

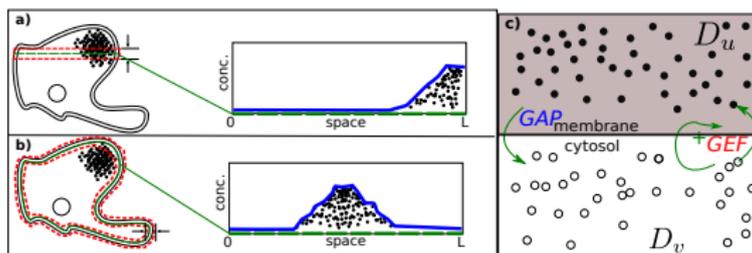
Any non-homogeneous stable spatial concentration profile of proteins and other factors.

## Minimal approach.

- One Rho-Protein.  $u(v)$  active(inactive).
- $D_u \ll D_v$

$$\partial_t u = D_u \partial_{xx} u + f(u, v)$$

$$\partial_t v = D_v \partial_{xx} v + g(u, v)$$



# Modelling: Reaction-Diffusion systems, Wave Mechanism.

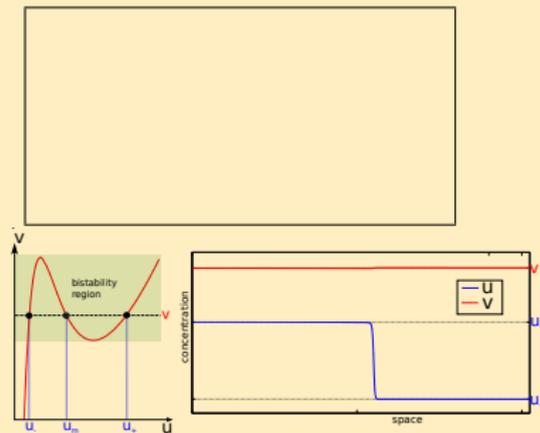
## Wave-Pinning mechanism [Mori et al. 2008].

Alternative to Turing instability

$$\partial_t u = D_u \partial_{xx} u + f(u, v) \quad D_u \ll D_v,$$

$$\partial_t v = D_v \partial_{xx} v - f(u, v), \quad T = \int u + v$$

$$f(u, v) = \gamma \frac{u^2 v}{K^2 + u^2} - \eta u + \delta v$$



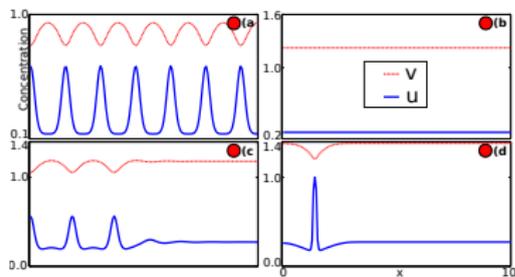
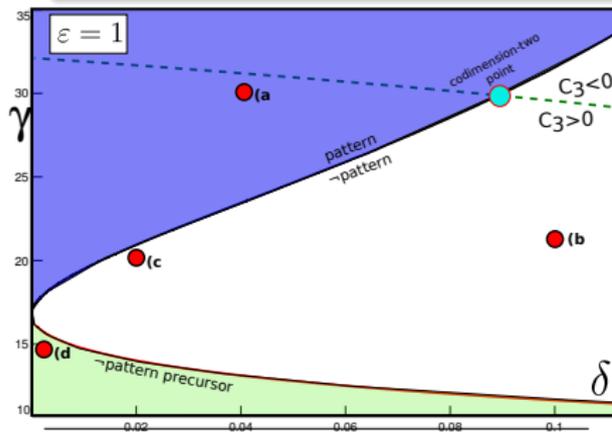
Prototype model for cell polarisation.

# General Model<sup>1</sup>: source and loss terms

$$(1a) \quad \partial_t u = \delta \partial_{xx} u + F(u, v) - \varepsilon \theta u,$$

$$(1b) \quad \partial_t v = \partial_{xx} v - F(u, v) + \varepsilon \alpha,$$

$$F(u, v) = \left( \gamma \frac{u^2 v}{1 + u^2} - \eta u + v \right) \quad x \in [0, \mathcal{L}].$$



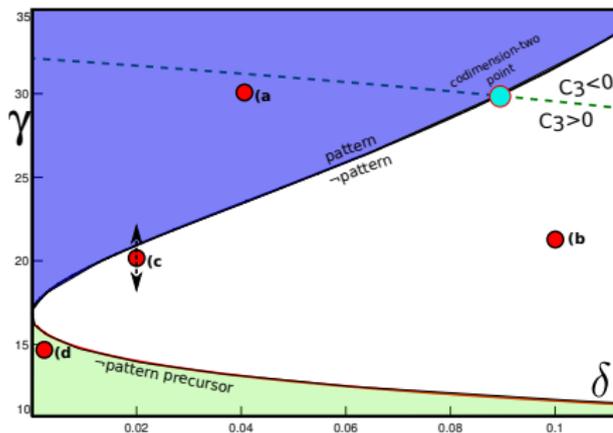
$\delta$	$\gamma$	$\eta$	$\varepsilon$	$\theta$	$\alpha$
[0, 0.2]	[15, 40]	5.2	1	5.5	1.5

<sup>1</sup>Inspired by [Breña-Medina et al PRE 2014]



Prototype model for cell polarisation.

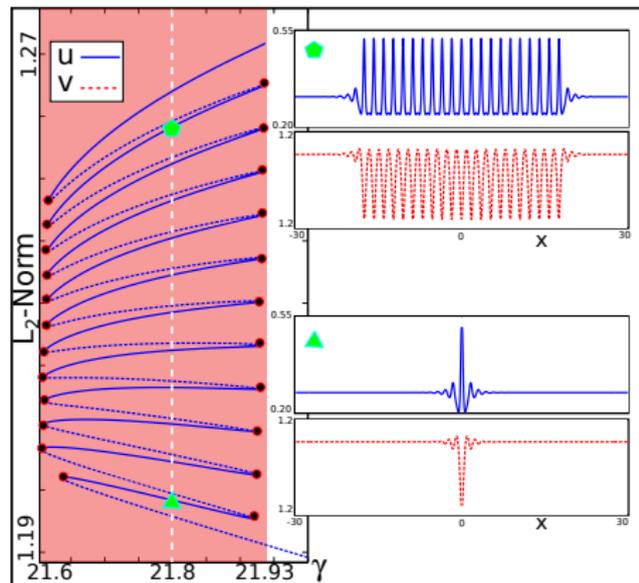
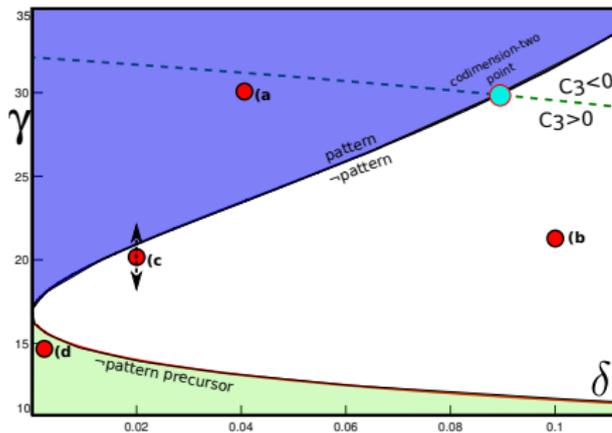
# 1-Parameter continuation of Localised Structures (AUTO) ( $\varepsilon = 1$ ).



Prototype model for cell polarisation.

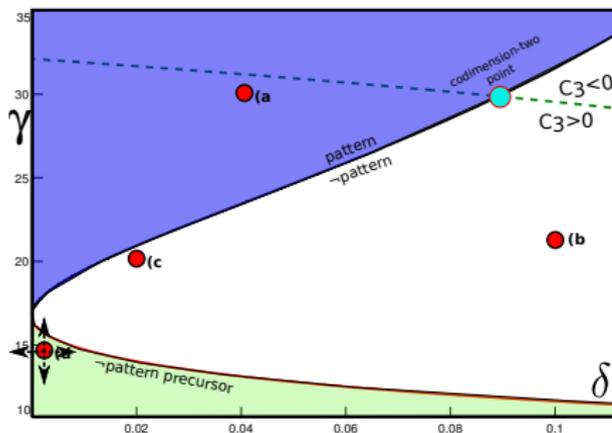
# 1-Parameter continuation of Localised Structures (AUTO)

( $\varepsilon = 1$ ).



Prototype model for cell polarisation.

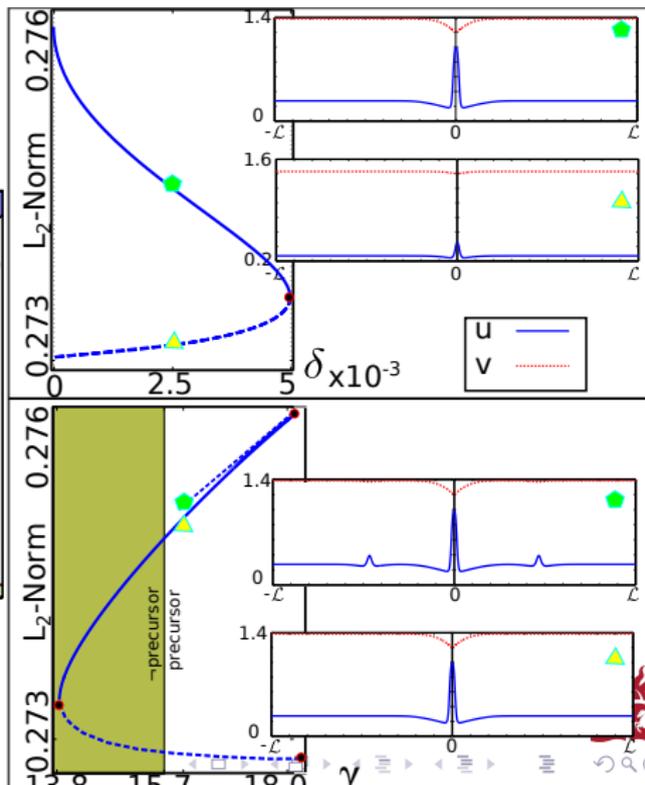
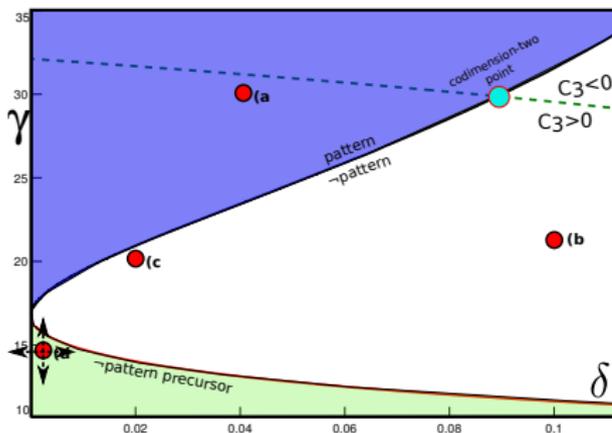
# 1-Parameter continuation of Localised Structures (AUTO) ( $\varepsilon = 1$ ).



Prototype model for cell polarisation.

# 1-Parameter continuation of Localised Structures (AUTO)

( $\varepsilon = 1$ ).

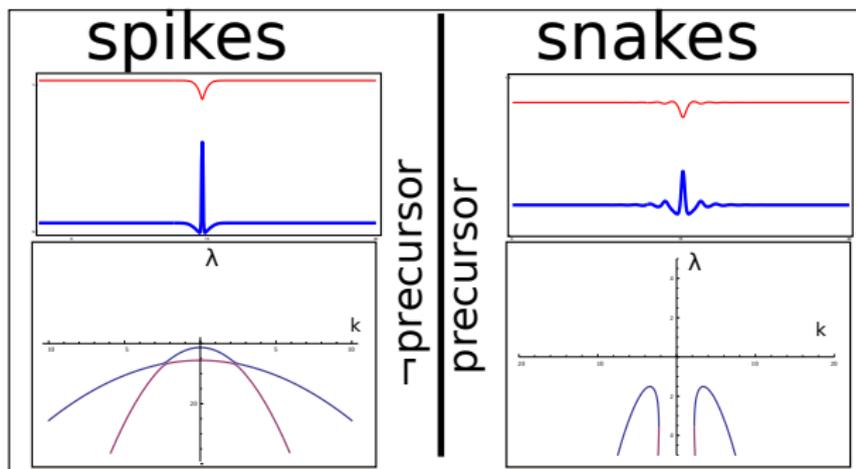


Prototype model for cell polarisation.

## First Result.

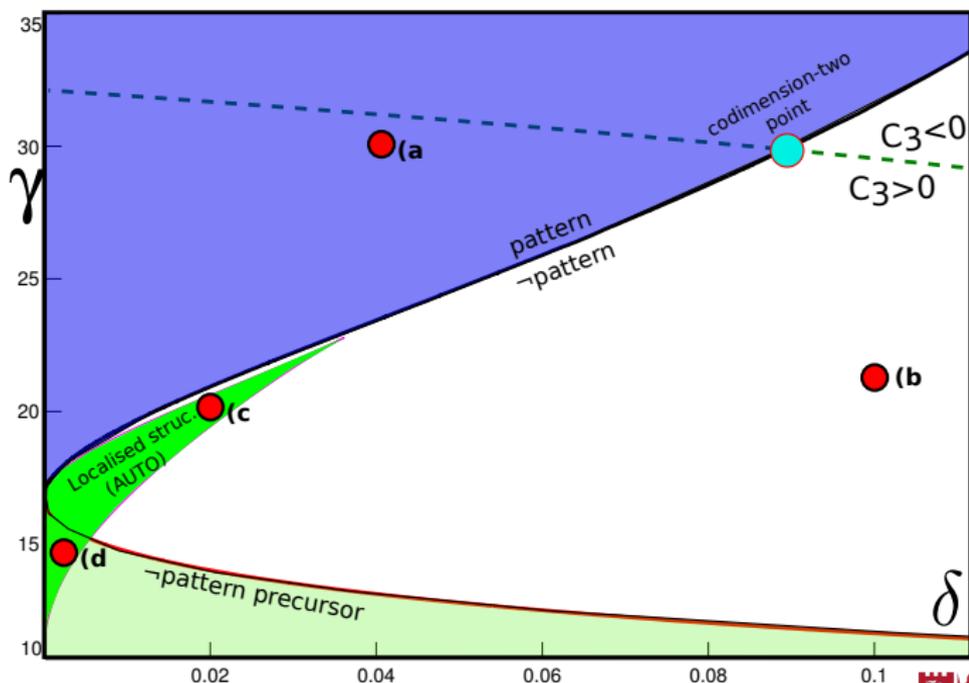
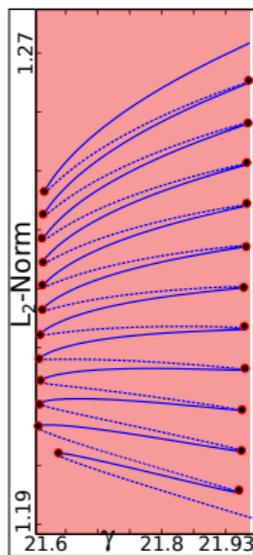
Numerically we have found a transition between the two localised structures ubiquitous in P.D.E.

This transition seems to be characterised by the transition in the eigenvalues of the homogeneous state



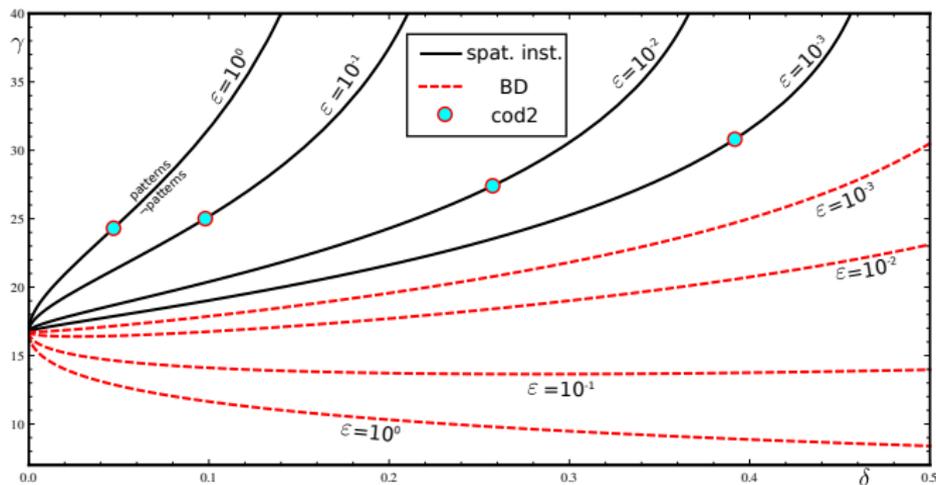
Prototype model for cell polarisation.

## 2-Parameter continuation of Localised Structures.



Prototype model for cell polarisation.

# Limit $\varepsilon \rightarrow 0$ : From localised structures to fronts.

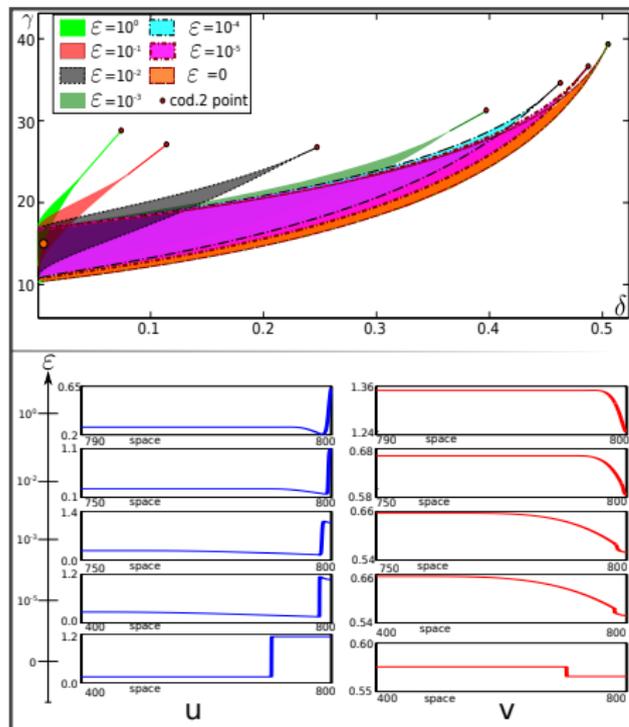


The equivalent to the front is the spike solution.



Prototype model for cell polarisation.

# Limit $\varepsilon \rightarrow 0$ , 2-Parameter continuation of Localised Structures.



Front region( $\varepsilon = 0$ )

$$(2) \quad 0 = \delta \partial_{xx} u + f(u, v)$$

$$(3) \quad 0 = \partial_{xx} v - f(u, v)$$

$$(2)+(3), (2)-(3)$$

$$R = \delta u + v, \quad S = \delta u - v.$$

B.V.P.

$$\partial_{xx} R = 0$$

$$\partial_{xx} S = -2f(S, R_0)$$

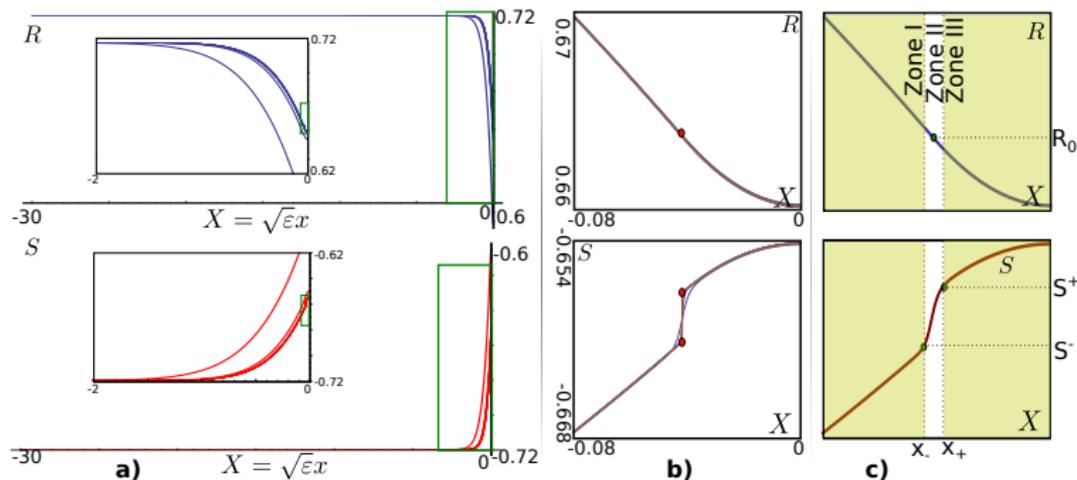


Prototype model for cell polarisation.

## Matched Asymptotics.

Introducing the change of variables:

$$u = \frac{(R+S)}{2\delta}, v = \frac{R-S}{2} + \varepsilon\beta_1, X = \sqrt{\varepsilon}x, \quad \left( \beta_1 = \frac{\alpha(\theta^2 + \alpha^2)}{\theta^2 + \alpha^2(1+\gamma)} \right).$$



Prototype model for cell polarisation.

## Matched Asymptotics: Outer region

$$(R_0, S^\pm, X_+ = X_- = X^*)$$

•  $O(1)$

$$0 = F(R, S)$$

•  $O(\varepsilon)$

$$\frac{d^2 R}{dX^2} = \frac{\theta}{2\delta}(R + S) - \alpha,$$

$$\frac{d^2 S}{dX^2} = \frac{\theta}{2\delta}(R + S) + \alpha - 2\beta_1\psi + \chi(R, S)$$

Where:

$$\chi(R, S) \sim O(\varepsilon), \quad \psi(u^2) = \frac{\gamma u^2}{1 + u^2} + 1$$



Prototype model for cell polarisation.

## Matched Asymptotics: Outer region

$$(R_0, S^\pm, X_+ = X_- = X^*)$$

•  $O(1)$

$$0 = F(R, S) \rightarrow S(R, \hat{u}) = \varphi_1(\hat{u})R + \varphi_0(\hat{u}).$$

•  $O(\varepsilon)$

$$\frac{d^2 R}{dX^2} = \frac{\theta}{2\delta}(R + S) - \alpha,$$

$$\frac{d^2 S}{dX^2} = \frac{\theta}{2\delta}(R + S) + \alpha - 2\beta_1\psi + \chi(R, S)$$

Where:

$$\chi(R, S) \sim O(\varepsilon), \quad \psi(u^2) = \frac{\gamma u^2}{1 + u^2} + 1$$

Choosing:

$$\hat{u} = \begin{cases} u_0 = \alpha/\theta & X \in [-\mathcal{L}, X^*], \\ u_+ = (R_0 + S_+)/ (2\delta) & X \in [X^*, 0] \end{cases}$$



Prototype model for cell polarisation.

## Matched Asymptotics: Outer region

$$(R_0, S^\pm, X_+ = X_- = X^*)$$

$$R(X) = \begin{cases} R_1(X) = \zeta(u_0) + (R_0 - \zeta(u_0)) \frac{\cosh(\sigma(u_0)(X+\mathcal{L}))}{\cosh(\sigma(u_0)(X^*+\mathcal{L}))} & X \in [-\mathcal{L}, X^*], \\ R_3(X) = \zeta(u_+) + (R_0 - \zeta(u_+)) \frac{\cosh(\sigma(u_+)X)}{\cosh(\sigma(u_+)X^*)} & X \in [X^*, 0] \end{cases}$$

and

$$S(X) = \begin{cases} \varphi_1(u_0)R_1(X) + \varphi_0(u_0) & X \in [-\mathcal{L}, X^*], \\ \varphi_1(u_+)R_3(X) + \varphi_0(u_+) & X \in [X^*, 0]. \end{cases}$$

Where

$$\zeta(u) = v(u) + \frac{\alpha\delta}{\theta} + v'(u) \left( \frac{\alpha}{\theta} - u \right), \quad \sigma(u) = \sqrt{\frac{\theta}{\delta + v'(u)}}.$$

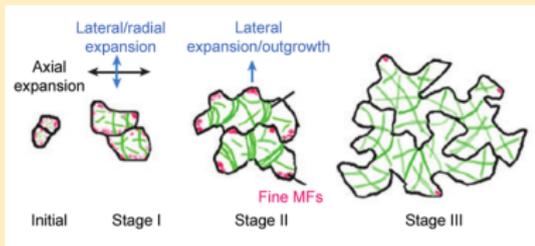




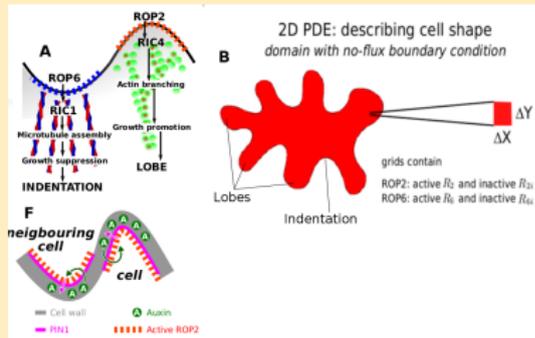
Pavement cells.

## Pavement cells (Preliminary).

## Experimental observations



Reproduced from [Lin et al. 2014]. Cotyledon of



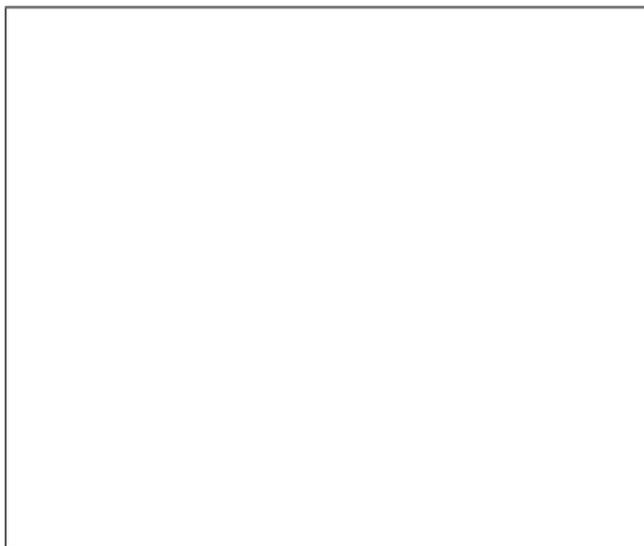
Reproduced from [Grieneisen et al. 2012]



## Pavement cells.

## Pavement cells (preliminary).

$$\partial_t \vec{c} = \underbrace{\partial_{\gamma\gamma} \vec{c}}_{\text{curve shortening}} + \underbrace{\vec{c}_\theta}_{\text{opposite curvature}} + \underbrace{(\vec{c}_\theta - \vec{c})}_{\text{stationary shape}} + \underbrace{\eta(\gamma) \hat{n}}_{\text{anisotropy}}$$



# Conclusions and Future Research.

## Conclusions.

- ➊ **Adding source and loss terms to the wave pinning model** we found
  - 2 types of localised structures: spikes and snakes.
  - Transition between spikes and snakes, BD point.
  - Limit  $\varepsilon \rightarrow 0$  connects spikes with fronts.
  - Match Asymptotics in the limit  $\varepsilon \rightarrow 0$  in terms of  $R_0$ .
- ➋ **Pavement cells (Preliminary)** A generalised version of the curve-shortening flow problem, is proposed to describe the dynamics in the membrane.



# Conclusions and Future Research.

## Future Research.

- 1 **Matching Asymptotics:** Find Analytically  $R_0$  from an additional matching condition.
- 2 **Pavement cells:** Refine the model for pavement cells (e.g. consider more than one cell, couple the model with the *ROPs* model.).