

Error analysis for coupled time-dependent Navier-Stokes and Darcy flows

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SIAM GS

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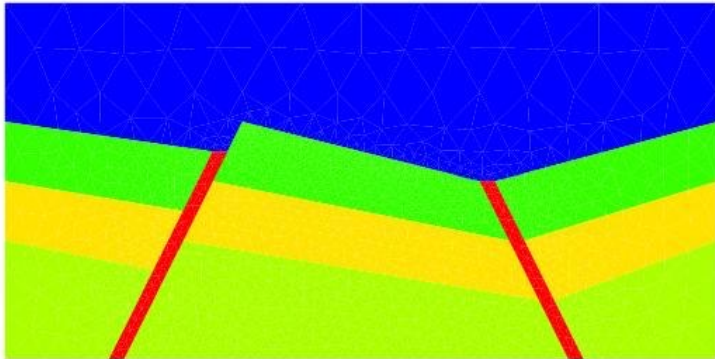


Outline

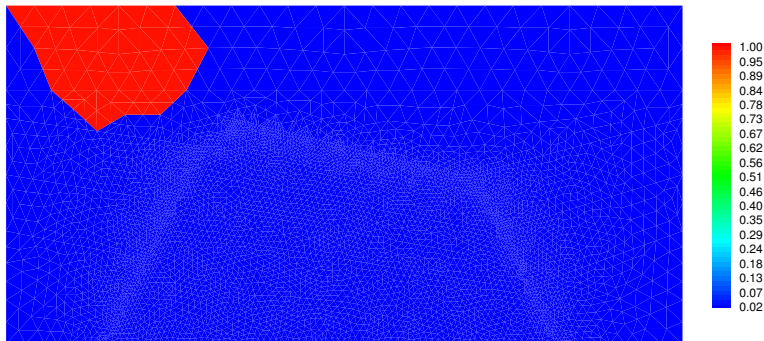
- Coupled Darcy and Navier-Stokes model
- Discontinuous Galerkin scheme
- Analysis and numerical results

A MultiPhysics Problem

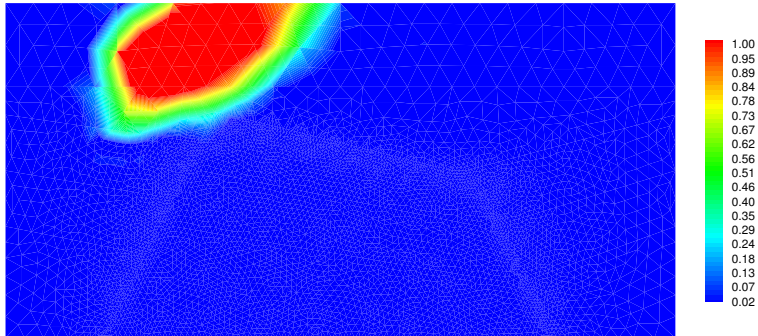
Applications in environment, energy, biomedicine, manufacturing...



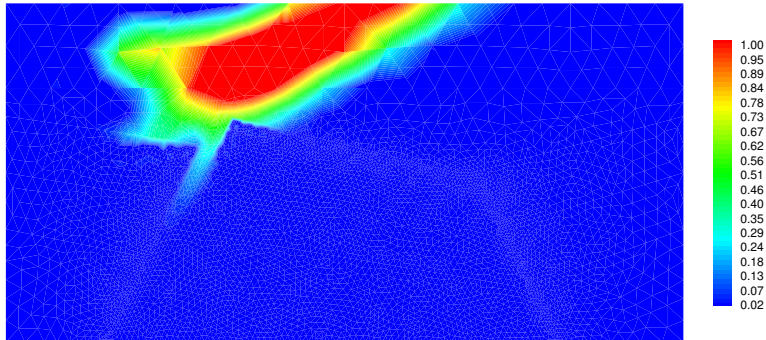
Initial Plume



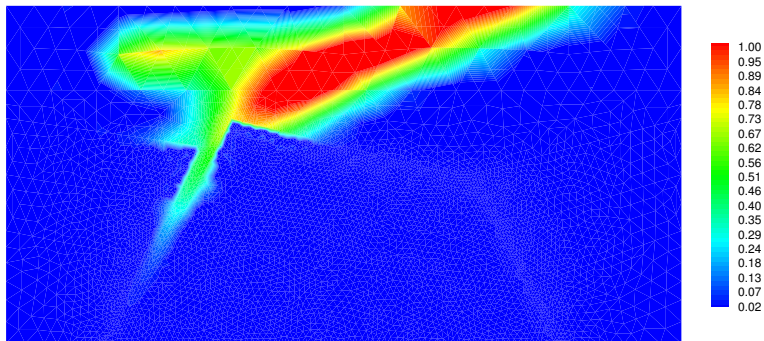
Contamination Simulation



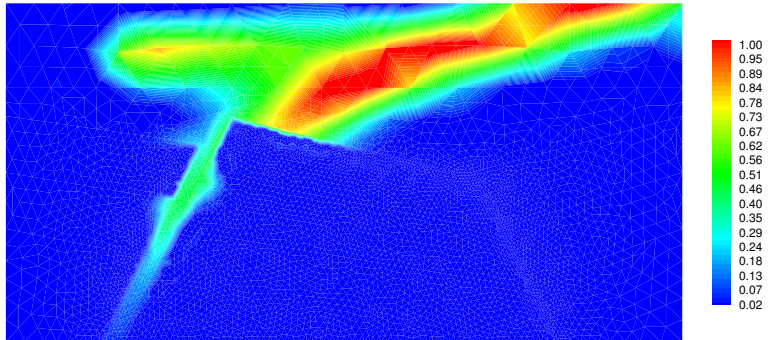
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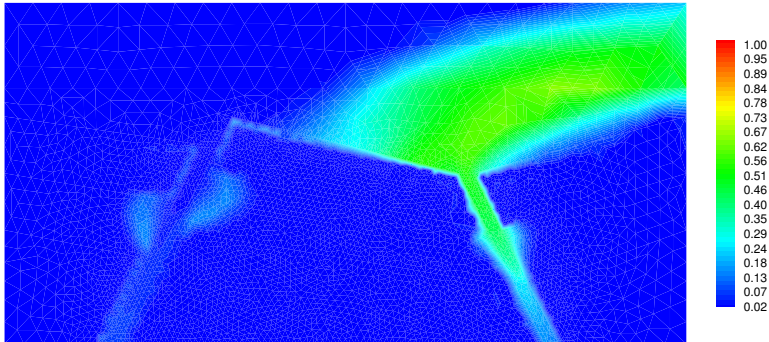
Contamination Simulation



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Contamination Simulation



Navier-Stokes/Darcy

Navier-Stokes in Ω_1 : (surface flow)

$$\begin{aligned} \frac{\partial \mathbf{u}}{\partial t} - \nabla \cdot (2\mu \mathbf{D}(\mathbf{u}) - p_1 \mathbf{I}) + \mathbf{u} \cdot \nabla \mathbf{u} &= \mathbf{f}_1, & \text{in } \Omega_1 \times (0, T) \\ \nabla \cdot \mathbf{u} &= 0, & \text{in } \Omega_1 \times (0, T) \end{aligned}$$

Darcy in Ω_2 : (porous media flow)

$$-\nabla \cdot (\mathbf{K} \nabla p_2) = f_2, \quad \text{in } \Omega_2 \times (0, T)$$

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Interface conditions on interface $\Gamma_{12} = \partial\Omega_1 \cap \partial\Omega_2$

$$\mathbf{u} \cdot \mathbf{n}_{12} = -\mathbf{K} \nabla p_2 \cdot \mathbf{n}_{12}, \quad \text{on } \Gamma_{12} \times (0, T) \quad (1)$$

$$((-2\mu \mathbf{D}(\mathbf{u}) + p_1 \mathbf{I}) \mathbf{n}_{12}) \cdot \mathbf{n}_{12} = p_2, \quad \text{on } \Gamma_{12} \times (0, T) \quad (2)$$

$$\mathbf{u} \cdot \boldsymbol{\tau}_{12}^j = -2\mu G^j (\mathbf{D}(\mathbf{u}) \mathbf{n}_{12}) \cdot \boldsymbol{\tau}_{12}^j, \quad 1 \leq j \leq d-1, \quad \text{on } \Gamma_{12} \times (0, T) \quad (3)$$

where

$$G^j = \frac{\mu \alpha}{(\mathbf{K} \boldsymbol{\tau}_{12}^j, \boldsymbol{\tau}_{12}^j)^{1/2}}$$

Coupling via Bilinear Forms

- Γ_{12} : interface between Ω_1 and Ω_2
- Integrate by parts the divergence operators in momentum and Darcy equations (with test functions \mathbf{v} in Ω_1 and q in Ω_2)

$$T_{12} = - \int_{\Gamma_{12}} (2\mu \mathbf{D}(\mathbf{u}) - p_1 \mathbf{I}) \mathbf{n}_1 \cdot \mathbf{v} - \int_{\Gamma_{12}} \mathbf{K} \nabla p_2 \cdot \mathbf{n}_2 q$$

- Define $\mathbf{n}_{12} = \mathbf{n}_1$ and use interface conditions to rewrite

$$T_{12} = \int_{\Gamma_{12}} p_2 \mathbf{v} \cdot \mathbf{n}_{12} - \int_{\Gamma_{12}} \mathbf{u} \cdot \mathbf{n}_{12} q + \sum_{j=1}^{d-1} \frac{1}{G^j} \int_{\Gamma_{12}} \mathbf{u} \cdot \boldsymbol{\tau}_{12}^j \mathbf{v} \cdot \boldsymbol{\tau}_{12}^j$$

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Variational methods allow for easy handling of interface conditions via traces of functions

Cesmelioglu, Girault, Riviere, ESAIM M2AN, 2013.

Discrete Scheme

Find $(\mathbf{u}_h^{n+1}, p_{1h}^{n+1}, p_{2h}^{n+1}) \in \mathbf{X}^h \times M_1^h \times M_2^h$, for all $0 \leq n \leq N_T$ such that

$$\left(\frac{\mathbf{u}_h^{n+1} - \mathbf{u}_h^n}{\Delta t}, \mathbf{v} \right)_{\Omega_1} + a_S(\mathbf{u}_h^{n+1}, \mathbf{v}) + b_S(\mathbf{v}, p_{1h}^{n+1}) + c_{NS}(\mathbf{u}_h^n, \mathbf{u}_h^n; \mathbf{u}_h^{n+1}, \mathbf{v})$$

$$+ a_D(p_{2h}^{n+1}, q) + (p_{2h}^{n+1}, \mathbf{v} \cdot \mathbf{n}_{12})_{\Gamma_{12}} - (\mathbf{u}_h^{n+1} \cdot \mathbf{n}_{12}, q)_{\Gamma_{12}} + \sum_{j=1}^{d-1} \frac{1}{G^j} (\mathbf{u}_h^{n+1} \cdot \boldsymbol{\tau}_{12}^j, \mathbf{v} \cdot \boldsymbol{\tau}_{12}^j)_{\Gamma_{12}}$$

$$= (\mathbf{f}_1^{n+1}, \mathbf{v})_{\Omega_1} + (f_2^{n+1}, q)_{\Omega_2}, \quad \forall (\mathbf{v}, q) \in \mathbf{X}^h \times M_2^h$$

$$b_S(\mathbf{u}_h^{n+1}, q) = 0, \quad \forall q \in M_1^h.$$

Interior penalty discontinuous Galerkin discretizations

Discontinuous piecewise polynomials of degree k for NSE velocity and Darcy pressure, and $k - 1$ for NSE pressure

Existence and Uniqueness of Solution

- Linear problem: Easy?

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$$\forall \mathbf{u}_h, \mathbf{v}_h \in \mathbf{X}^h, \quad c_{NS}(\mathbf{u}_h, \mathbf{u}_h; \mathbf{v}_h, \mathbf{v}_h) \geq \frac{1}{2}(\mathbf{u}_h \cdot \mathbf{n}_{12}, \mathbf{v}_h \cdot \mathbf{v}_h)_{\Gamma_{12}}.$$

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- To control this term, we need an a priori bound on velocity

$$\|\mathbf{u}_h^n\|_{DG, \Omega_1} \leq \mu C^*, \quad \forall n$$

- Challenge: bound in $L^\infty(0, T; H^1)$ is needed instead of $L^\infty(0, T; L^2)$!

Bounding Velocity in $L^\infty(0, T; H^1(\mathcal{T}_h))$

- We need to bound the time derivative of velocity

$$\left\| \frac{\mathbf{u}_h^{n+1} - \mathbf{u}_h^n}{\Delta t} \right\|_{L^2(\Omega_1)} \leq C$$

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- **Theorem:** There is a constant \tilde{C} , independent of h such that for all $\mathbf{u}_h \in \mathbf{V}^h$ and for all $q_{2h} \in M_2^h$,

$$|(q_{2h}, \mathbf{u}_h \cdot \mathbf{n}_{12})_{\Gamma_{12}}| \leq \tilde{C} \|q_{2h}\|_{\text{DG}, \Omega_2} \|\mathbf{u}_h\|_{L^2(\Omega_1)}$$

Key ingredient: regularization of discrete functions by Scott-Zhang interpolant

Existence and Uniqueness

Theorem:

Assume small data condition that depends on:

$$\mu, \|\mathbf{f}_1\|_{L^\infty(L^2)}, \|\delta_t \mathbf{f}_1\|_{\ell^2(L^2)}, \|\mathbf{f}_2\|_{L^\infty(L^2)}, \|\delta_t \mathbf{f}_2\|_{\ell^2(L^2)}$$

Then there is a unique solution $(\mathbf{u}_h^{n+1}, p_{1h}^{n+1}, p_{2h}^{n+1})$ to the numerical scheme.

Notation:

$$\delta_t g^j = \frac{g^{j+1} - g^j}{\Delta t}$$

Error Estimates

Under the small data assumption, there is a constant C independent of h and Δt such that for all $1 \leq m \leq N_T$, we have,

$$\begin{aligned} & \|\mathbf{u}^m - \mathbf{u}_h^m\|_{L^2(\Omega_1)}^2 + \mu \Delta t \sum_{n=1}^m \|\mathbf{u}^n - \mathbf{u}_h^n\|_{\text{DG}, \Omega_1}^2 + \Delta t \sum_{n=1}^m \|\rho_2^n - \rho_{2h}^n\|_{\text{DG}, \Omega_2}^2 \\ & + \Delta t \sum_{n=1}^m \sum_{j=1}^{d-1} \left\| \frac{1}{\sqrt{G^j}} (\mathbf{u}^n - \mathbf{u}_h^n) \cdot \boldsymbol{\tau}_{12}^j \right\|_{L^2(\Gamma_{12})}^2 \leq C(h^{2k} + \Delta t^2). \end{aligned}$$

This bound is valid if the exact solution satisfies the following regularity assumptions: $\mathbf{u} \in L^\infty(0, T; H^{k_1+1}(\Omega_1)^d)$,

$\frac{\partial \mathbf{u}}{\partial t} \in L^2(0, T; L^\infty(\Omega_1)^d) \cap L^2(0, T; H^{k_1}(\Omega_1)^d)$, $\frac{\partial^2 \mathbf{u}}{\partial t^2} \in L^2((0, T) \times \Omega_1)^d$ and $\rho_2 \in L^\infty(0, T; H^{k_2+1}(\Omega_2))$.

Error Bounds for NSE Pressure

We first need to control the error in the discrete time derivative of velocity in Ω_1 :

$$\|\delta_t(\mathbf{u} - \mathbf{u}_h)\|_{\ell^2(L^2)} \leq C(h^k + \Delta t)$$

This is obtained under the condition:

$$\frac{h^2 + \Delta t^2}{\min_{T \in \mathcal{T}_h^1} h_T} \leq C$$

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Then we can show

$$\|p_1 - p_{1h}\|_{\ell^2(L^2)} \leq C(h^k + \Delta t)$$

Smooth Solutions: $k = 2$

$$\Omega = \Omega_1 \cup \Omega_2, \quad \Omega_1 = (0, 1) \times (0, 1), \quad \Omega_2 = (0, 1) \times (-1, 0)$$

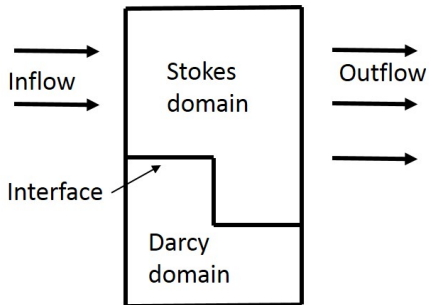
Velocity and pressure in NSE subdomain:

| h | $\ \mathbf{u} - \mathbf{u}_h\ _{L^2(\Omega_1)}$ | CR | $\ \nabla_h(\mathbf{u} - \mathbf{u}_h)\ _{L^2(\Omega_1)}$ | CR | $\ p_1 - p_{1h}\ _{L^2(\Omega_1)}$ | CR |
|------|---|------|---|------|------------------------------------|------|
| 1/2 | 2.694e-02 | | 4.383e-01 | | 4.974e-01 | |
| 1/4 | 4.300e-03 | 2.65 | 1.151e-01 | 1.93 | 1.608e-01 | 1.63 |
| 1/8 | 5.813e-04 | 2.89 | 2.871e-02 | 2.00 | 4.685e-02 | 1.78 |
| 1/16 | 7.385e-05 | 2.98 | 7.051e-03 | 2.03 | 1.263e-02 | 1.89 |
| 1/32 | 1.024e-05 | 2.85 | 1.738e-03 | 2.02 | 3.282e-03 | 1.94 |

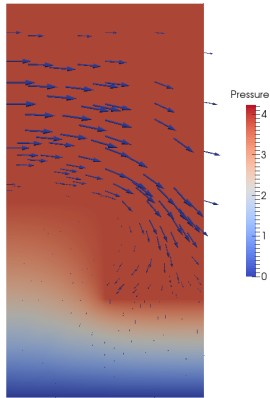
Pressure in Darcy subdomain:

| h | $\ p_2 - p_{2h}\ _{L^2(\Omega_2)}$ | Conv. | $\ \nabla_h(p_2 - p_{2h})\ _{L^2(\Omega_2)}$ | Conv. |
|------|------------------------------------|-------|--|-------|
| 1/2 | 3.1803e-03 | | 5.4874e-02 | |
| 1/4 | 4.9972e-04 | 2.67 | 1.4217e-02 | 1.95 |
| 1/8 | 6.8328e-05 | 2.87 | 3.6107e-03 | 1.98 |
| 1/16 | 8.8834e-06 | 2.94 | 9.0948e-04 | 1.99 |
| 1/32 | 1.1711e-06 | 2.92 | 2.2822e-04 | 1.99 |

Polygonal Interface: Set-up



Polygonal Interface: Pressure and Streamlines



Interface Conditions

Define errors in imposing interface conditions in L^2 norm:

$$E_7 = \|\mathbf{u} \cdot \mathbf{n}_{12} + \mathbf{K} \nabla p_2 \cdot \mathbf{n}_{12}\|_{L^2(\Gamma_{12})}$$

$$E_8 = \|p_2 - ((-2\mu \mathbf{D}(\mathbf{u}) + p_1 \mathbf{I}) \mathbf{n}_{12}) \cdot \mathbf{n}_{12}\|_{L^2(\Gamma_{12})}$$

$$E_9 = \|\mathbf{u} \cdot \boldsymbol{\tau}_{12} + 2\mu G^1(\mathbf{D}(\mathbf{u}) \mathbf{n}_{12}) \cdot \boldsymbol{\tau}_{12}\|_{L^2(\Gamma_{12})}$$

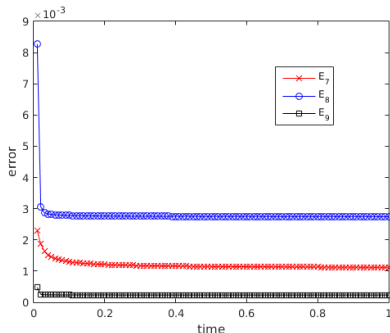
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Conclusions

- DG scheme for coupling time-dependent NSE and Darcy
- Convergence analysis for any polynomial degree
- Interface curve or surface does not have to be smooth
- Acknowledgement: NSF

Chaabane, Girault, Puelz, Riviere. Journal of Computational and Applied Mathematics, 2017.