

Neural Nets as a Filter in Two-Stage Markov Chain Monte Carlo for Velocity Estimation and Uncertainty Quantification

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 - Numerical Experiment

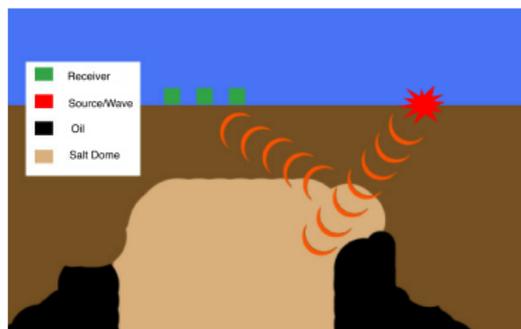


Figure: The reflection seismology process. Waves are generated at the source and reflect off the interfaces between different materials.

- In **exploration seismology**, seismic waves (acoustic or elastic) can be used to image the subsurface of the earth.
- In a typical seismic experiment:
 - ① A source creates a disturbance in the form of a wave.
 - ② This wave travels through the earth and reflects off of material property interfaces.
 - ③ Seismometers on the surface of the earth or in wells record the returning wave.
- This recorded seismic data can be used to image the earth's subsurface.
- In velocity inversion, the result is a map of wavespeed that can be used to determine lithology.

- A **deterministic** approach to waveform inversion results in a single model of the desired parameter. Constructing uncertainty information requires **many assumptions** about a single model, even Bayesian formulations of the inverse problem.
- A **stochastic** approach allows us to characterize and quantify uncertainty with fewer assumptions.
- **Markov Chain Monte Carlo (MCMC)** allows us to sample from the posterior distribution of the model. We examine **tens of thousands** of possible velocity models to construct a picture of the posterior distribution.
- This allows us to **avoid assumptions** when constructing and analyzing the posterior distribution, which means a better characterization of the uncertainty.

- Mosegaard and Tarantola (1995) pioneered the use of Stochastic Bayesian methods in seismic inversion.
- Sambridge and Mosegaard (2002) summarized the use of Monte Carlo and MCMC algorithms in geophysical inverse problems.
- Bayesian methods have been used, for example, in [seismic imaging](#) (e.g., Ely et al. (2018)), [reservoir flow](#) (e.g., Oliver et al. (1997), Ginting et al. (2015), and [hydrology](#) (e.g., Vrugt et al. (1998)).

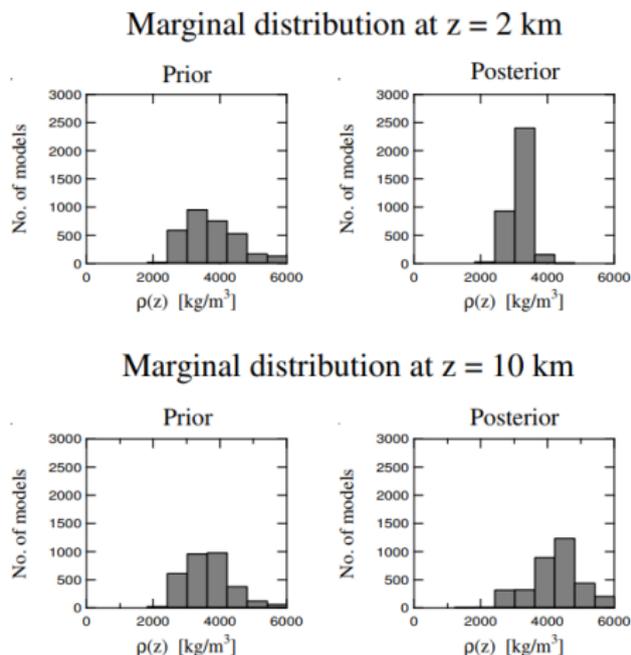


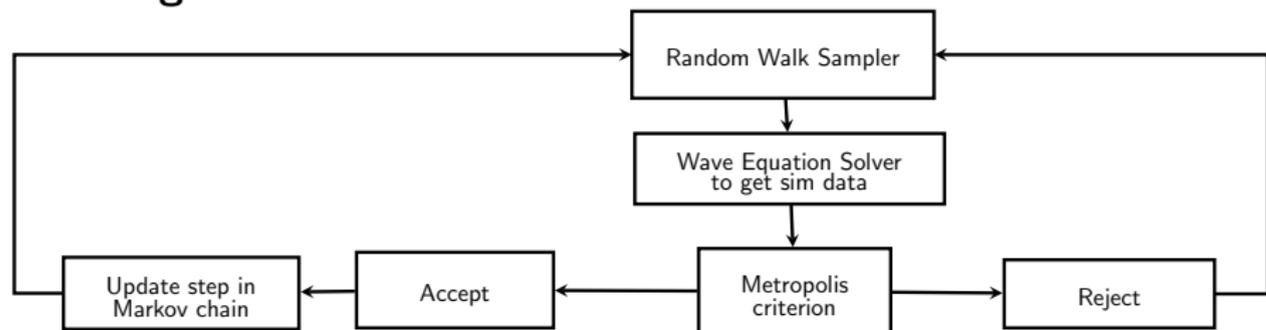
Figure: Prior and posterior distributions of mass density. Mosegaard and Tarantola (1995)



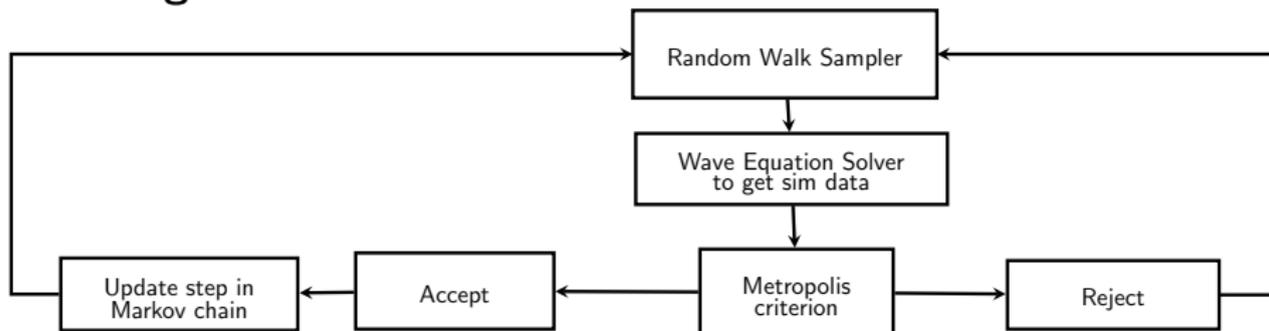
Figure: Rejected velocity models

- Problem: MCMC can take **many models (tens of thousands)** to converge to steady state, and each model must be run through a forward simulator to see if it is acceptable for the characterization of the posterior distribution.
- Often **90%** of samples are rejected!
- Proposed solution: use upscaled solution to **quickly reject samples**, then simulate on the full fine grid if upscaled sample is accepted.
- This technique was first proposed by **Efendiev et al. (2005)** for two-phase flow.

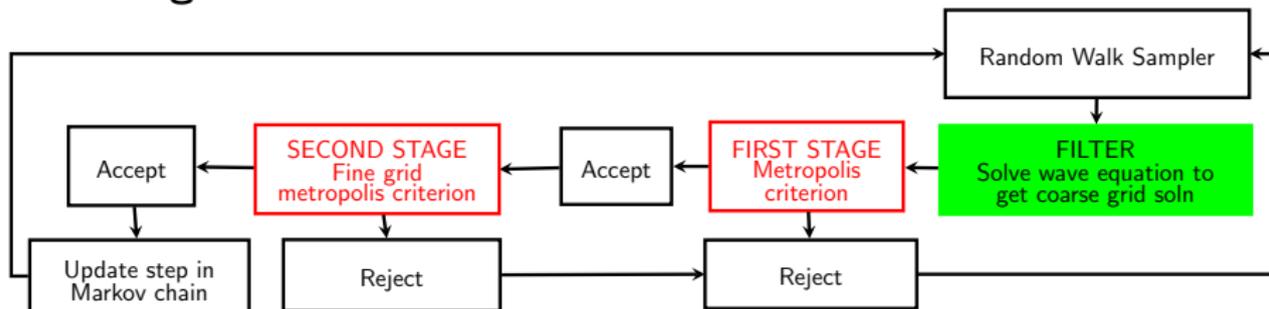
One Stage



One Stage



Two Stage



According to Bayes rule,

$$P(c | \text{data}) \propto P(\text{data} | c) P(c)$$

Posterior distribution:
what we now think
(after simulation)

Likelihood function:
measures the degree of fit between
the measured & simulated data
given the parameters

Prior distribution:
what we used to think
(before simulation)

- We assume the likelihood function has the form:

$$P(d_m | c) = \exp\left(-\frac{\|d_m - d_s\|^2}{\sigma^2}\right).$$

- The prior distribution can take many forms, e.g. uniform or Gaussian.
- However, the **posterior is not necessarily Gaussian**.

After obtaining the simulated receiver data, we decide whether to accept or reject the proposed perturbation with the **Metropolis Criterion**.

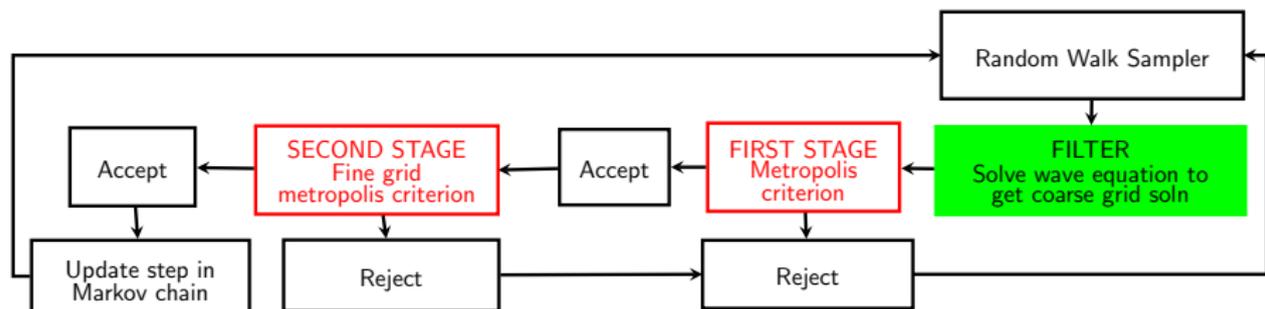
Accept C with probability:

$$\rho(C_n, C) = \min \left\{ 1, \frac{P_F(C|d_m)q(C_n|C)}{P_F(C_n|d_m)q(C|C_n)} \right\}.$$

Where $P_F(C|d_m)$ is the posterior using the filter likelihood, C and C_n are the proposed and last accepted perturbation, $q(C|C_n)$ is the proposal distribution, and d_m is the measured data.

On the filter, we accept C with probability

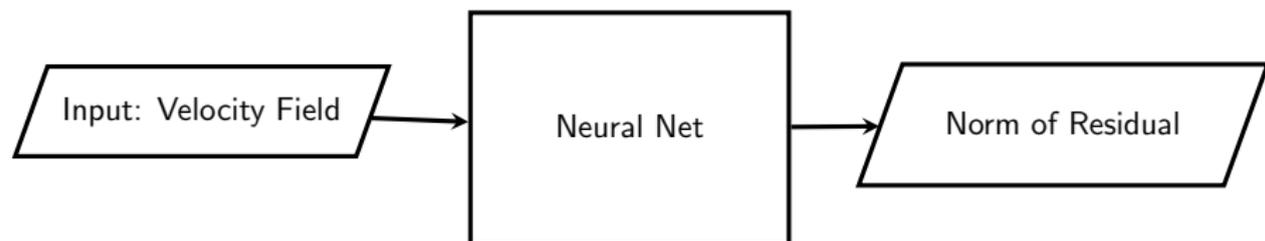
$$\rho(C_n, C) = \min \left\{ 1, \frac{P(C|d_m)}{P(C_n|d_m)} \frac{P_F(C_n|d_m)}{P_F(C|d_m)} \right\}.$$



Likelihood function:

$$P(d_m|c) = \exp\left(-\frac{\|d_m - d_s\|^2}{\sigma^2}\right).$$

Idea: replace the expensive evaluation of $\|d_m - d_s\|^2$ with a **neural net**.



Advantages of Neural Nets

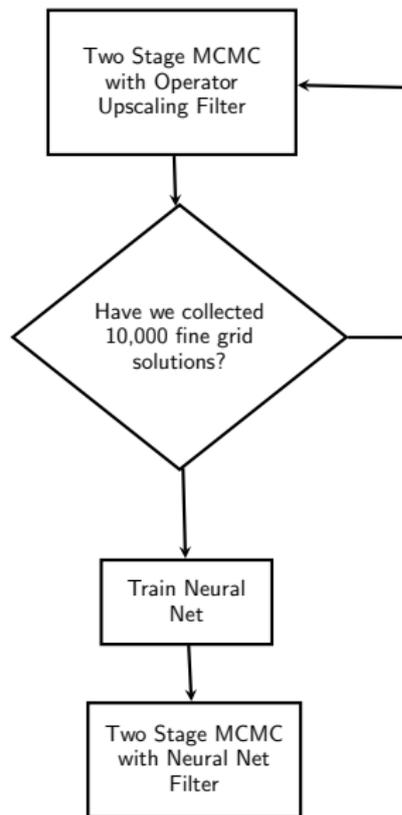
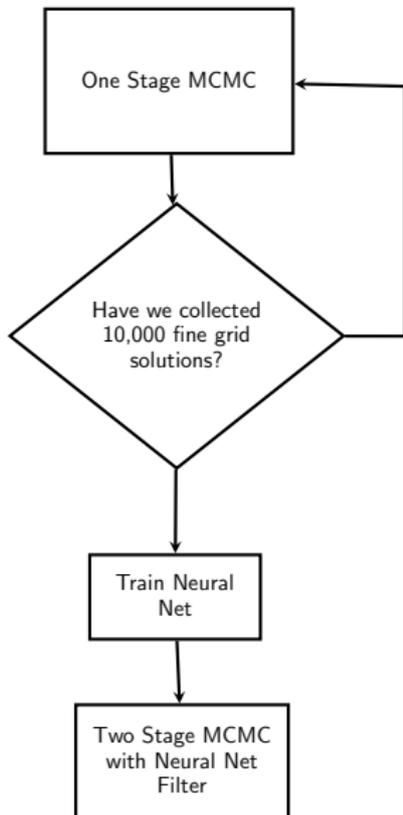
- Once a Neural Net is trained, evaluating a model is extremely fast (milliseconds)
- Neural Nets are capable of approximating very complex relationships
- Data for training can be generated as part of the MCMC process

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Disadvantages of Neural Nets

- Where's the physics?
- Training data is expensive to generate
- Predictions are not always very accurate with very complex relationships
- Many knobs to twist in the Neural Net!



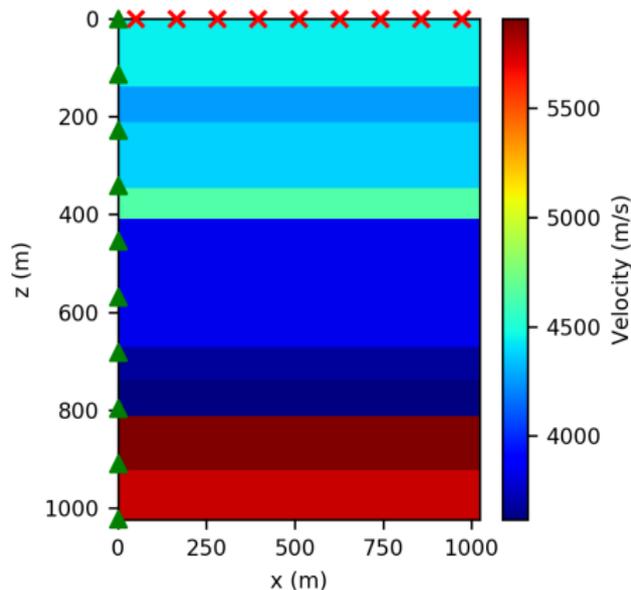
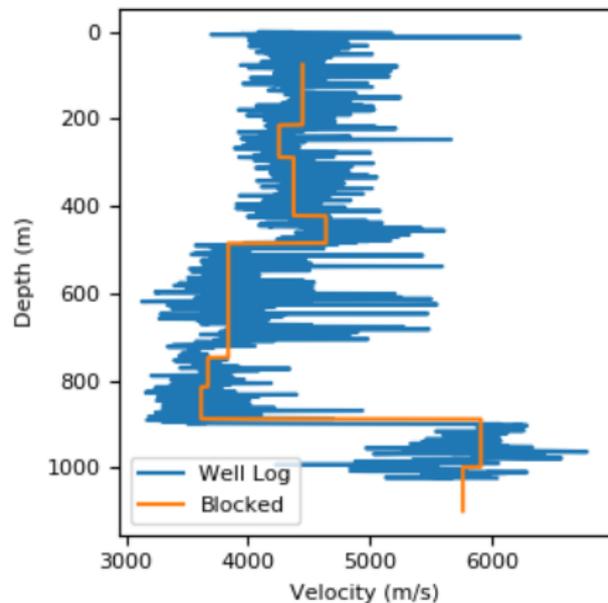


Figure: Flat Layer Experimental Setup

Figure: The well log (blue, courtesy of Pioneer Natural Resources) and 9-layer block (orange).

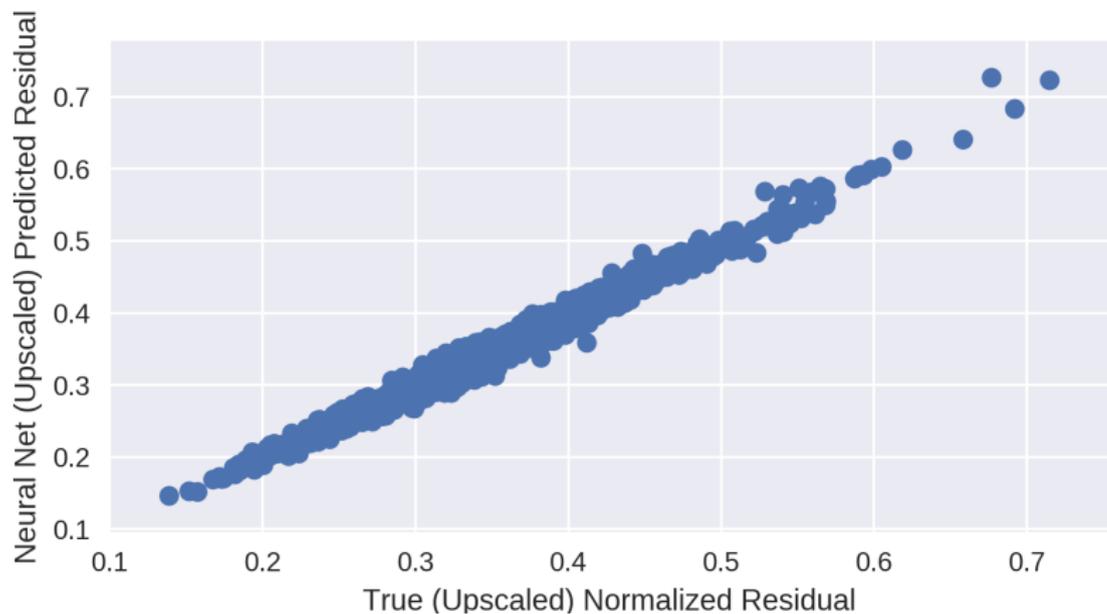


Figure: The fine grid residual norm vs neural net filter residual norm with continuous learning

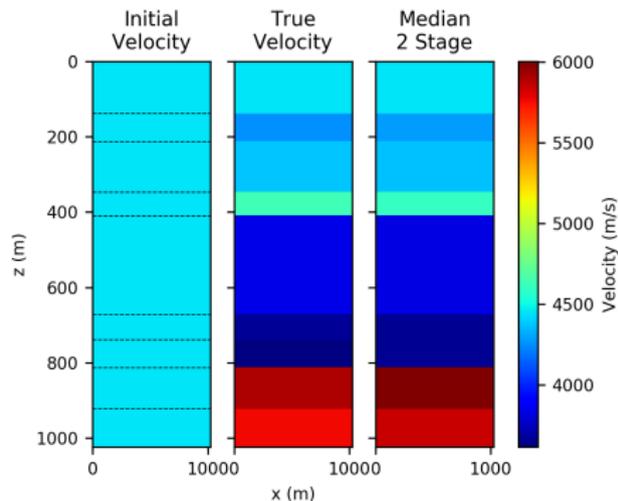


Figure: The initial, true, and median velocity fields for the neural net two stage MCMC. The dashed lines in the initial velocity picture mark the positions of the pre-set interfaces.

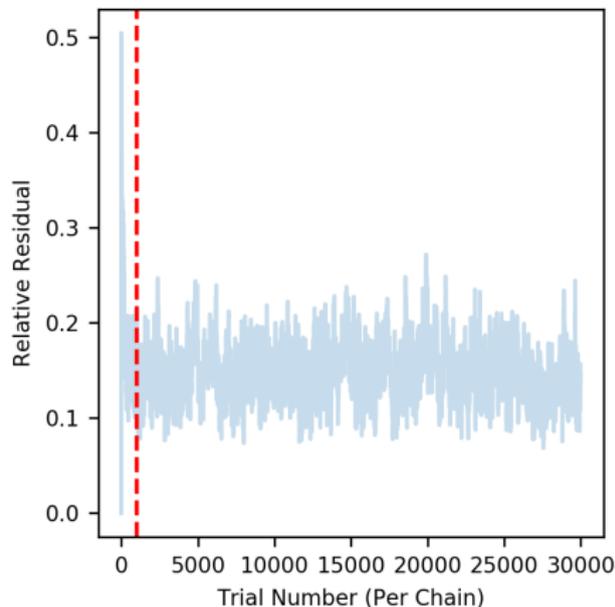


Figure: The relative residuals (blue) and burn-in cutoff (red).

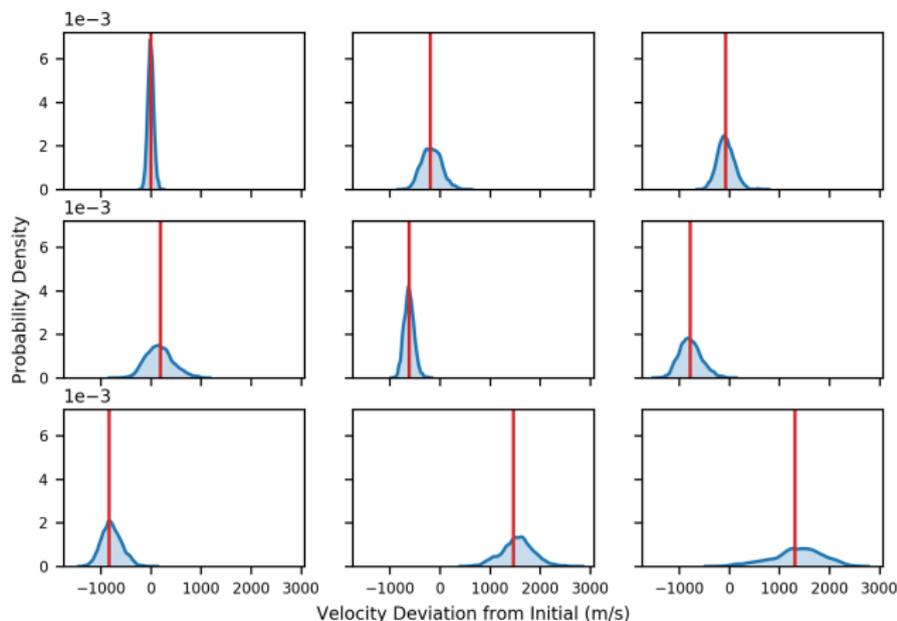


Figure: Kernel Density Estimates of the posterior distributions (blue) with the true value of the velocity (red).

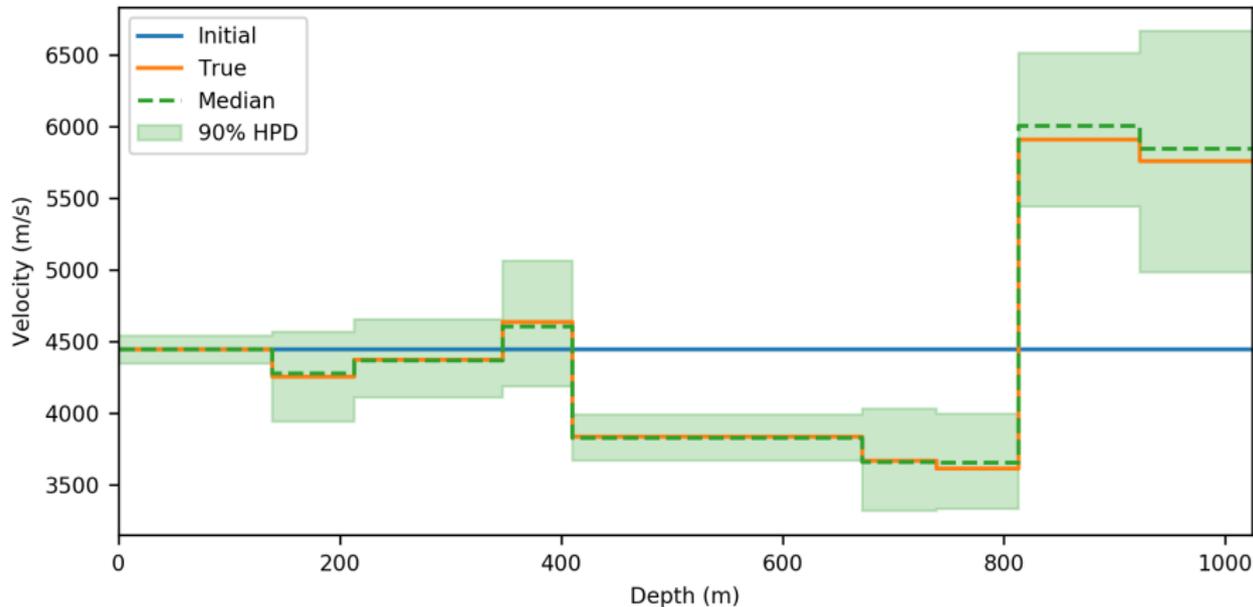


Figure: A one-dimensional slice of the velocity field in depth.

All times include generating training data and training the neural net!

One-Stage MCMC

- Time per trial: 10s
- Time per rejection: 10s
- Acceptance rate: 29%

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Percent Reduction in Time Using Two Stage

- Reduction in time per trial: 65%
- Reduction in time per rejection: 84%

- The two-stage MCMC algorithm is an effective way to quickly reject unacceptable samples and to **reduce runtime of the expensive MCMC procedure**.
- A **neural net** is an extremely inexpensive filter (milliseconds) that can do a good job of approximating the exponent of the likelihood function.
- The **training set** for the neural net can be generated as part of the MCMC process.

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