

Sobol' Indices for Sensitivity Analysis with Dependent Inputs

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1 Sobol' Indices with Independent Variables

2 Sobol' Indices with Dependent Variables

3 Summary and Some Questions

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Formulation

Consider a function,

$$\begin{aligned} f : \mathbb{R}^p &\rightarrow \mathbb{R} \\ \mathbf{x} &\mapsto f(\mathbf{x}) \end{aligned}$$

Assume,

- $\mathbf{x} = (x_1, x_2, \dots, x_p)$ has some known probability distribution
- $f(\mathbf{x})$ is square integrable

Objective: determine the sensitivity of f to \mathbf{x}

Hierarchical Decomposition of f

$f : \mathbb{R}^p \rightarrow \mathbb{R}$ may be decomposed as

$$f(\mathbf{x}) = f_0 + \sum_{i=1}^p f_i(x_i) + \sum_{1 \leq i < j \leq p} f_{i,j}(x_i, x_j) + \cdots + f_{1,2,\dots,p}(x_1, x_2, \dots, x_p)$$

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where

$$f_0 = \mathbb{E}[f(\mathbf{x})]$$

$$f_i(x_i) = \mathbb{E}[f(\mathbf{x})|x_i] - f_0$$

$$f_{i,j}(x_i, x_j) = \mathbb{E}[f(\mathbf{x})|x_i, x_j] - f_i(x_i) - f_j(x_j) - f_0$$

\vdots

ANOVA (Analysis of Variance) Decomposition

$$f(\mathbf{x}) = f_0 + \sum_{k=1}^p \sum_{|u|=k} f_u(\mathbf{x}_u)$$

- this hierarchical decomposition exists $\forall f$ such that $f(\mathbf{x}) \in L^2$

¹Sensitivity estimates for non linear mathematical models. Sobol'. 1993

ANOVA (Analysis of Variance) Decomposition

$$f(\mathbf{x}) = f_0 + \sum_{k=1}^p \sum_{|u|=k} f_u(\mathbf{x}_u)$$

- this hierarchical decomposition exists $\forall f$ such that $f(\mathbf{x}) \in L^2$
- if x_1, x_2, \dots, x_p are statistically independent then ¹

$$\mathbb{E}[f_u(\mathbf{x}_u)f_v(\mathbf{x}_v)] = 0 \quad u \neq v$$

$$\implies \text{Var}(f(\mathbf{x})) = \sum_{k=1}^p \sum_{|u|=k} \text{Var}(f_u(\mathbf{x}_u))$$

¹Sensitivity estimates for non linear mathematical models. Sobol'. 1993

Sobol' Indices with Independent Variables

Using the decomposition of variance

$$\text{Var}(f(\mathbf{x})) = \sum_{k=1}^p \sum_{|u|=k} \text{Var}(f_u(\mathbf{x}_u)),$$

define the Sobol' indices as ²

$$S_u = \frac{\text{Var}(f_u(\mathbf{x}_u))}{\text{Var}(f(\mathbf{x}))}.$$

- S_u measures the relative contribution of \mathbf{x}_u to $\text{Var}(f(\mathbf{x}))$
- there are $2^p - 1$ Sobol' indices

²Sensitivity estimates for non linear mathematical models. Sobol'. 1993

First Order and Total Sobol' Indices

Define the *total Sobol' index* as

$$T_u = \sum_{v \cap u \neq \emptyset} S_v$$

In practice one frequently considers the indices

$$\{S_k, T_k\}_{k=1}^p$$

and refers to them as the first order and total Sobol' indices.

Interpretation of First Order and Total Sobol' Indices

$$\{S_k, T_k\}_{k=1}^p$$

- $S_k, T_k \in [0, 1]$ measure the importance of x_k
- S_k only measures contribution of x_k
- T_k measures the contribution of all interactions involving x_k
- $S_k \leq T_k \forall k \in \{1, 2, \dots, p\}$
- $T_u \leq \sum_{k \in u} T_k \forall u \subset \{1, 2, \dots, p\}$

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Generalization Proposed in the Literature

$$f(\mathbf{x}) = f_0 + \sum_{k=1}^p \sum_{|u|=k} f_u(\mathbf{x}_u)$$

Generalization Proposed in the Literature

Taking the covariance of $f(\mathbf{x})$ with each side of

$$f(\mathbf{x}) = f_0 + \sum_{k=1}^p \sum_{|u|=k} f_u(\mathbf{x}_u)$$

yields

$$\text{Var}(f(\mathbf{x})) = \sum_{k=1}^p \sum_{|u|=k} \text{Cov}(f_u(\mathbf{x}_u), f(\mathbf{x}))$$

and gives Sobol' indices³

$$S_u = \frac{\text{Cov}(f_u(\mathbf{x}_u), f(\mathbf{x}))}{\text{Var}(f(\mathbf{x}))}$$

³Global sensitivity analysis for systems with independent and/or correlated inputs. Rabitz et al. 2010

Generalization Proposed in the Literature

$$S_u = \frac{\text{Cov}(f_u(\mathbf{x}_u), f(\mathbf{x}))}{\text{Var}(f(\mathbf{x}))}$$

The total Sobol' indices may also be generalized,

$$T_u = \sum_{v \cap u \neq \emptyset} S_v$$

Pros

- decomposes $\text{Var}(f(\mathbf{x}))$ as in the case with independence
- relates to the function decomposition

Cons

- S_u may take negative values and is no longer clear to interpret
- $S_k \not\leq T_k$ in general
- $T_u \not\leq \sum_{k \in u} T_k$

Generalization Proposed in the Literature

$$S_u = \frac{\text{Cov}(f_u(\mathbf{x}_u), f(\mathbf{x}))}{\text{Var}(f(\mathbf{x}))}$$

The total Sobol' indices may also be generalized,

$$T_u = \sum_{v \cap u \neq \emptyset} S_v$$

There are other alternative perspectives, see ⁴ ⁵

⁴Estimation of global sensitivity indices for models with dependent variables. Kucherenko et al. 2012.

⁵Non-parametric methods for global sensitivity analysis of model output with dependent inputs. Mara et al. 2015.

A Simple Example to Illustrate

$$f(\mathbf{x}) = 20x_1 + 16x_2 + 12x_3 + 4x_4$$

$$\mathbf{x} \sim \mathcal{N} \left(\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & .5 & .5 & .8 \\ .5 & 1 & 0 & 0 \\ .5 & 0 & 1 & .3 \\ .8 & 0 & .3 & 1 \end{bmatrix} \right)$$

S_1	$S_{1,2}$	$S_{1,3}$	$S_{1,4}$	$S_{1,2,3}$	$S_{1,2,4}$	$S_{1,3,4}$	$S_{1,2,3,4}$	T_1
.903	-.393	-.333	-.295	.030	-.047	.154	-.010	.009

Table: Sobol' indices involving variable x_1 .

A Simple Example to Illustrate

$$f(\mathbf{x}) = 20x_1 + 16x_2 + 12x_3 + 4x_4$$

$$\mathbf{x} \sim \mathcal{N} \left(\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & .5 & .5 & .8 \\ .5 & 1 & 0 & 0 \\ .5 & 0 & 1 & .3 \\ .8 & 0 & .3 & 1 \end{bmatrix} \right)$$

T_1	T_2	$T_{1,2}$
.009	.021	.450

Table: Total Sobol' indices.

$$T_{1,2} \not\approx T_1 + T_2$$

Approximation Theoretic Perspective

- let $f_0 = \mathbb{E}[f(\mathbf{x})]$
- let $u \subset \{1, 2, \dots, p\}$ and $\sim u = \{1, 2, \dots, p\} \setminus u$
- let $\mathcal{P}_{\sim u}f$ be the optimal L^2 approximation of $f - f_0$ in the space of functions which do not depend on \mathbf{x}_u

$$\textbf{Theorem: } T_u = \frac{\|(f-f_0) - \mathcal{P}_{\sim u}f\|_2^2}{\|f-f_0\|_2^2}$$

Interpretation: $T_u \in [0, 1]$ measures the squared relative error of approximating $f - f_0$ by a function which does not depend on \mathbf{x}_u .

Uses of Global Sensitivity Analysis

Global sensitivity analysis may be used to:

- prioritize data acquisition and/or model development
- determine unimportant variables for dimension reduction
 - guide the construction of surrogate models
 - “freezing” variables
- determine and mitigate risk
- gain insight into underlying phenomenon

Uses of Global Sensitivity Analysis

Global sensitivity analysis may be used to:

- prioritize data acquisition and/or model development
- determine unimportant variables for dimension reduction
 - guide the construction of surrogate models
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- determine and mitigate risk
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The remainder of this talk will focus on “freezing” (replacing) unimportant variables to reduce dimensions.

GSA for Dimension Reduction

- If T_u is small and I freeze \mathbf{x}_u , how much error do I incur?
- Results exist when the variables are independent. ⁶
- Dependencies among the variables help.
- Replacing \mathbf{x}_u with $g(\mathbf{x}_{\sim u})$ is superior to freezing.
- T_u is the error when $f(\mathbf{x})$ is projected.
- The approximation theoretic perspective also helps analyze the error from replacing \mathbf{x}_u .

⁶Estimating the approximation error when fixing unessential factors in global sensitivity analysis. Sobol' et al. 2007.

Replacing Unimportant Variables

$$f(\mathbf{x}) = f_0 + \mathcal{P}_{\sim u} f(\mathbf{x}_{\sim u}) + \mathcal{P}_{\sim u}^{\perp} f(\mathbf{x})$$

$$T_u = \frac{\|\mathcal{P}_{\sim u}^{\perp} f(\mathbf{x})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2}$$

$$\begin{aligned}\delta_u &= \frac{\|f(\mathbf{x}) - f(g(\mathbf{x}_{\sim u}), \mathbf{x}_{\sim u})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2} \\ &= \frac{\|\mathcal{P}_{\sim u}^{\perp} f(\mathbf{x}) - \mathcal{P}_{\sim u}^{\perp} f(g(\mathbf{x}_{\sim u}), \mathbf{x}_{\sim u})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2}\end{aligned}$$

Lemma

For any $u \subset \{1, 2, \dots, p\}$ and any g , $\delta_u \geq T_u$

Replacing Unimportant Variables

$$f(\mathbf{x}) = f_0 + \mathcal{P}_{\sim u} f(\mathbf{x}_{\sim u}) + \mathcal{P}_{\sim u}^\perp f(\mathbf{x})$$

$$T_u = \frac{\|\mathcal{P}_{\sim u}^\perp f(\mathbf{x})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2}$$

$$\delta_u = \frac{\|\mathcal{P}_{\sim u}^\perp f(\mathbf{x}) - \mathcal{P}_{\sim u}^\perp f(g(\mathbf{x}_{\sim u}), \mathbf{x}_{\sim u})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2}$$

- $\delta_u \geq T_u$
- Would like to have an upper bound on δ_u
- Difficult to bound tightly in general

Replacing Unimportant Variables

$$f(\mathbf{x}) = f_0 + \mathcal{P}_{\sim u} f(\mathbf{x}_{\sim u}) + \mathcal{P}_{\sim u}^{\perp} f(\mathbf{x})$$

$$T_u = \frac{\|\mathcal{P}_{\sim u}^{\perp} f(\mathbf{x})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2}$$

$$\delta_u = \frac{\|\mathcal{P}_{\sim u}^{\perp} f(\mathbf{x}) - \mathcal{P}_{\sim u}^{\perp} f(g(\mathbf{x}_{\sim u}), \mathbf{x}_{\sim u})\|_2^2}{\|f(\mathbf{x}) - f_0\|_2^2}$$

- δ_u will be small when

$$\|\mathcal{P}_{\sim u}^{\perp} f(g(\mathbf{x}_{\sim u}), \mathbf{x}_{\sim u})\|_2 \approx \|\mathcal{P}_{\sim u}^{\perp} f(\mathbf{x})\|_2$$

- δ_u is small if T_u is robust to changes in the distribution of \mathbf{x}

The g-function

$$f(\mathbf{x}) = \prod_{k=1}^{10} \frac{|4x_k - 2| + a_k}{1 + a_k}$$

where $\mathbf{x} \sim \mathcal{N}(\mu, \Sigma)$, i.e. is normally distributed

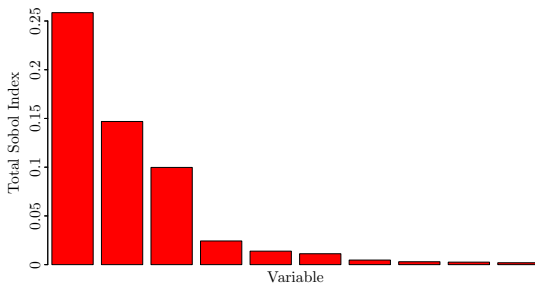
$$\mu_i = \frac{1}{2} \quad i = 1, 2, \dots, 10$$

$$\Sigma_{i,i} = \frac{1}{6} \quad i = 1, 2, \dots, 10$$

$$\Sigma_{i,j} = \frac{\rho}{6|i-j+1|^{\frac{1}{\gamma}}} \quad i \neq j$$

- larger $\rho \implies$ stronger correlations
- larger $\gamma \implies$ “dense” covariance matrix

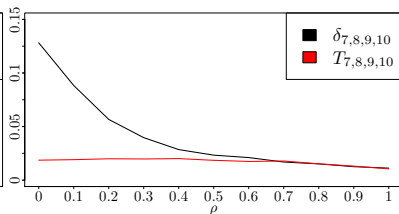
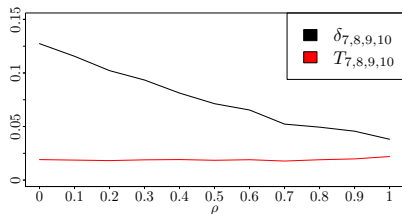
Total Sobol' Indices with $\rho = \frac{1}{2}$ and $\gamma = 6$



Approximation Errors as ρ Varies ($g(\mathbf{x}_{\sim u}) = \mathbb{E}[\mathbf{x}_u | \mathbf{x}_{\sim u}]$)

$\gamma = 1$

$\gamma = 6$



- stronger correlations $\implies \delta_u$ decreases
- $\delta_u \rightarrow T_u$ faster when the correlations are “dense”

Summary

- Reinterpreted the total Sobol' index T_u in terms of approximation error instead of variance analysis.
- Gives T_u a clear interpretation in terms of optimal approximation errors.
- Provides a framework to analyze the error when replacing unimportant variables.
- Argue that dependencies can help reduce error.

Some Questions

- Test for the robustness of T_u with respect to changes in the distribution of \mathbf{x} ? Bound δ_u using this?
- Approaches for constructing $g(\mathbf{x}_{\sim u})$ when \mathbf{x}_u and $\mathbf{x}_{\sim u}$ have nonlinear dependencies? How does this relate to robustness of the Sobol' indices?
- Other characterizations of Sobol' indices which are more useful for other applications of global sensitivity analysis? Maybe involving other methods (moment-independent importance measures, Shapley values, derivative-based global sensitivity measures).

Questions?

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J. Hart and P.A. Gremaud. An approximation theoretic perspective of Sobol' indices with dependent variables.

<https://arxiv.org/pdf/1801.01359v2.pdf>

J. Hart and P.A. Gremaud. Robustness of the Sobol' indices to distributional uncertainty.

<https://arxiv.org/pdf/1803.11249.pdf>