

Applied Harmonic Analysis Methods in Imaging Science Part I

Demetrio Labate
(University of Houston)

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- 1 Continuous Wavelet Transform
- 2 Continuous Shearlet Transform
 - Shearlet analysis of singularities
- 3 Applications
 - Edge analysis and detection
 - Soma detection in neuronal images
 - Classification with scattering transform



The Continuous Wavelet Transform

The classical continuous wavelet transform on \mathbb{R} is associated with the **affine systems** of functions

$$\{\psi_{a,t}(x) = a^{-\frac{1}{2}}\psi(a^{-1}(x-t)) : a > 0, t \in \mathbb{R}\},$$

where $\psi \in L^2(\mathbb{R})$.



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where $\psi \in L^2(\mathbb{R})$.

Provided that ψ satisfies the **admissibility condition** [Calderón, 1964]

$$\int_{a>0} |\psi(a\xi)|^2 \frac{da}{a} = 1, \quad \text{for a.e. } \xi \in \mathbb{R},$$

the **continuous wavelet transform** of f

$$\mathcal{W}_\psi : f \rightarrow \mathcal{W}_\psi f(a, t) = \langle f, \psi_{a,t} \rangle, \quad \text{for } a > 0, t \in \mathbb{R}^d,$$

is a linear isometry (from $L^2(\mathbb{R})$ to $L^2(\mathbb{A})$).



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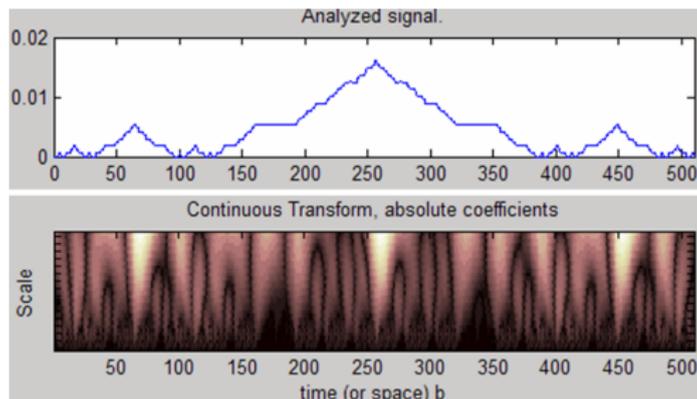
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- $\mathcal{W}_\psi f(a, t)$ measures the content of f at **scale** a and **location** t .



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If f is singular at location t_0 , $\mathcal{W}_\psi f(a, t)$ signals the location t_0 through its asymptotic decay at fine scales, $a \rightarrow 0$.

- This property is a manifestation of the *sparsity and locality* of the wavelet representation and it is critical in multiple signal/image processing applications.



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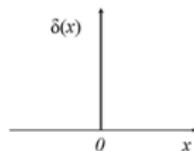
- If $t = 0$, then

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- If $t \neq 0$, then, for each $k \in \mathbb{N}$, there is a constant C_k such that

$$|\mathcal{W}_\psi \delta(a, t)| = |\psi_{a,t}(0)| \leq C_k a^k, \quad a \rightarrow 0.$$



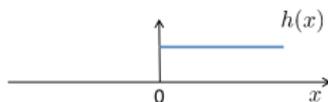
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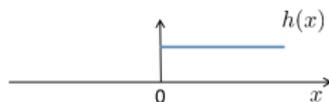
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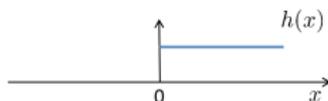
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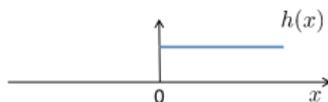
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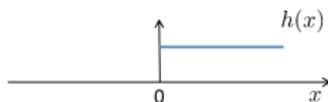
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The continuous wavelet transform resolves the singular support



The Continuous Wavelet Transform

In higher dimensions...



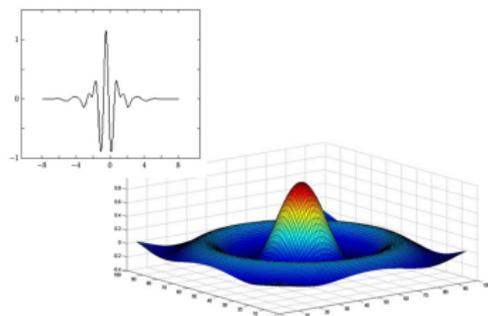
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The simplest way to extend the continuous wavelet transform to \mathbb{R}^d is by considering the affine systems

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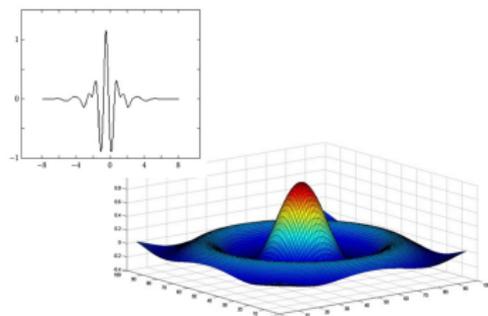
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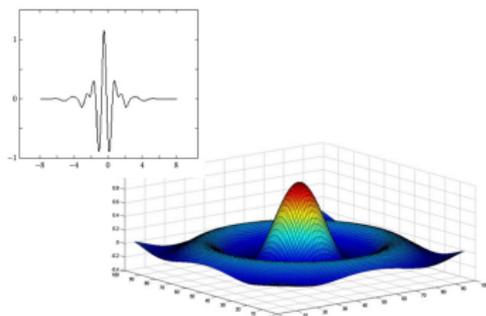
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Similar to the 1D case, it can detect point-singularities and resolve the singular support.

However, it provides very limited information about the geometry of singularities of multivariate functions and distributions.



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The **affine system** generated by $\psi \in L^2(\mathbb{R}^2)$ and \mathbb{A}_G is

$$\{\psi_{M,t}(x) = |\det M|^{-1/2} \psi(M^{-1}(x - t)) : (M, t) \in \mathbb{A}_G\}.$$



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For all $f \in L^2(\mathbb{R}^2)$

$$f(x) = \int_{\mathbb{R}^2} \int_G \langle f, \psi_{M,t} \rangle \psi_{M,t}(x) d\lambda(M) dt,$$

where λ is the left Haar measure on G .



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Admissibility is given by the classical Calderón condition.

This group is associated with the conventional continuous wavelet systems

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A system associated with this group is a **continuous shearlet system**

$$\left\{ \psi_{a,s,t}(x) = a^{-3/4} \psi(M_{as}^{-1}(x-t)) : a \in \mathbb{R}^+, s \in \mathbb{R}, t \in \mathbb{R}^2 \right\}$$



Construction of Continuous Shearlets

There are many admissible shearlets.

Band-limited shearlets [Guo,Kutyniok,L, 2006]. We choose:

$$\hat{\psi}(\xi) = \hat{\psi}(\xi_1, \xi_2) = \hat{\psi}_1(\xi_1) \hat{\psi}_2\left(\frac{\xi_2}{\xi_1}\right),$$

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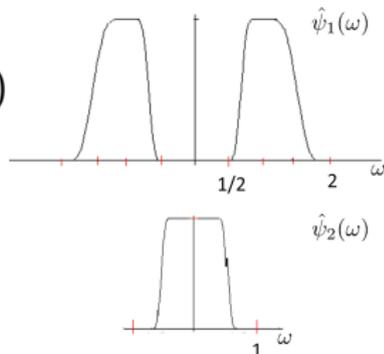
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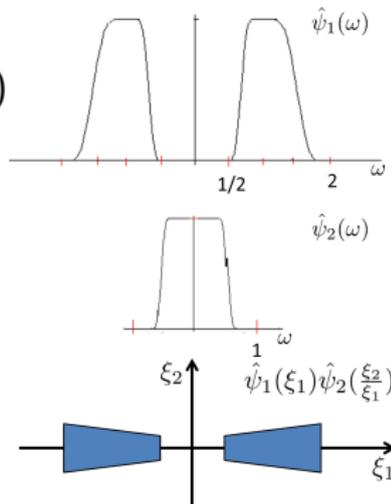
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Hence ψ is a smooth bandlimited function.



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Alternatively...

Compactly supported shearlets

[Lim,Kutyniok,2011] [Kutyniok,Petersen,2015]. We choose:

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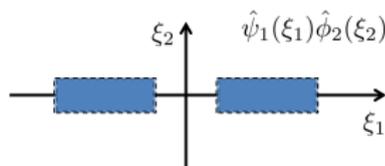
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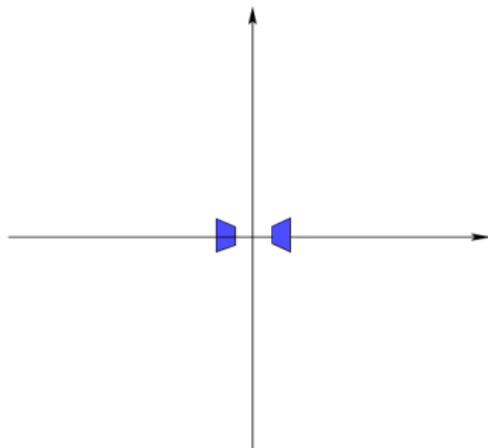
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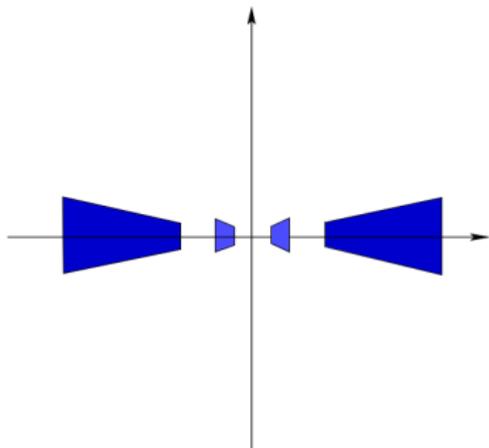
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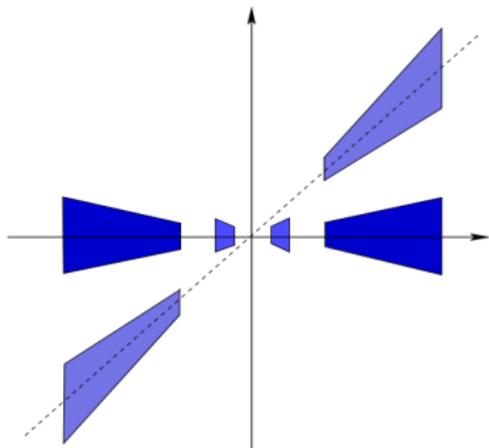
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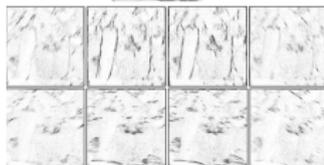
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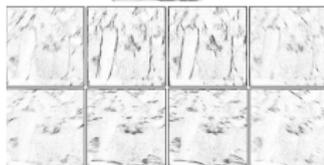
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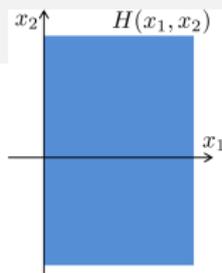


It is able to resolve both the location and orientation of singularities.



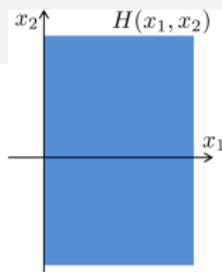
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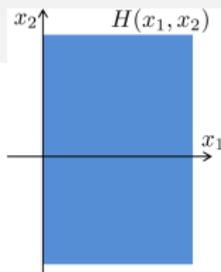
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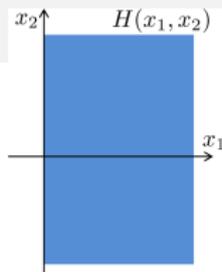
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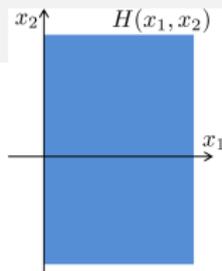
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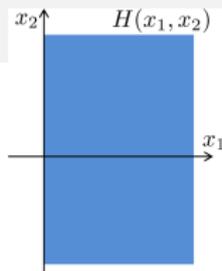
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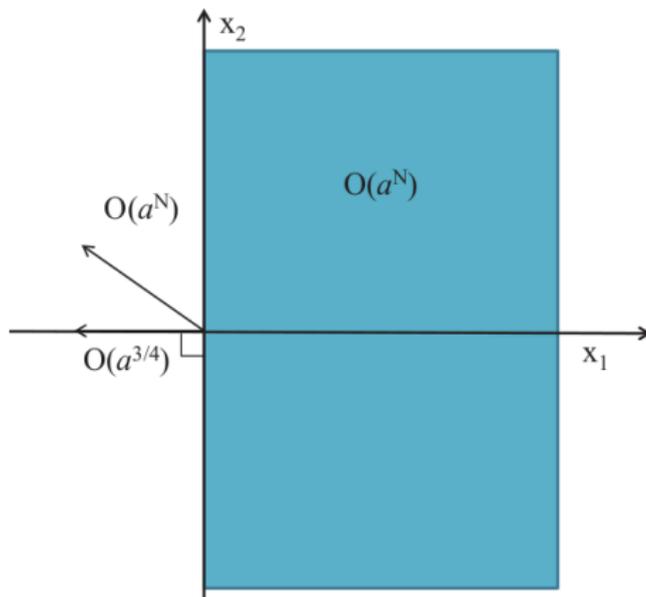
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$$\mathcal{SH}_\psi H(a, 0, (0, t_2)) = O(a^{\frac{3}{4}}).$$



Example: Heaviside function (2D)



$\mathcal{SH}_\psi H(a, s, t)$ decays rapidly for all values of s and $t = (t_1, t_2)$,
except for $s = 0$ and $t_2 = 0$



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- $\mathcal{SH}_\psi f$ provides a precise description of the **geometry** of **piecewise-smooth edges** of f through its asymptotic decay at fine scales [Guo, L, 2008-2015]. This holds also in 3D.



Resolution of edges using the CST ($d = 2$)

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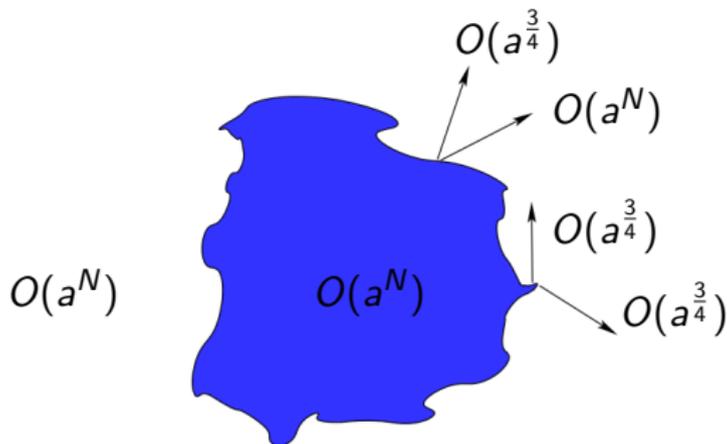
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That is, $\mathcal{SH}_\psi B$ has slow asymptotic decay only at the edge points for normal orientations, where

$$\mathcal{SH}_\psi B(a, s_0, t) = O(a^{\frac{3}{4}}) \quad \text{as } a \rightarrow 0$$



Resolution of Edges (D=2)



At the **regular points** t on an edge, for normal orientation, the shearlet transform decays as $O(a^{3/4})$. For all other values of s , the decay is as fast as $O(a^N)$, for any $N \in \mathbb{N}$.

At the **corner points**, the shearlet transform decays as $O(a^{3/4})$ for both normal orientations.



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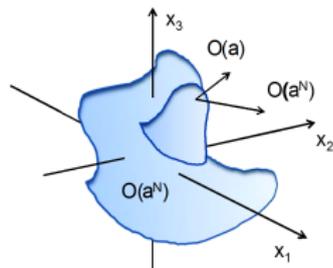
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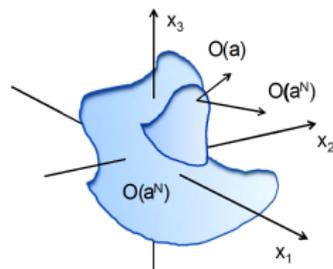
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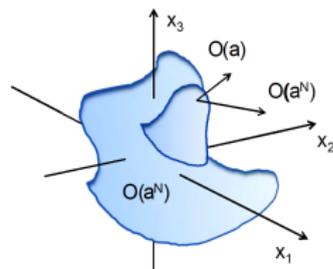
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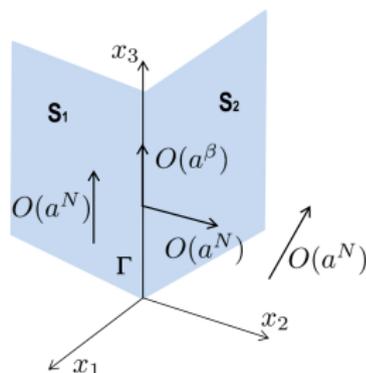
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- Analysis of one-dimensional manifolds, such as the curve of intersection of 2 surfaces. [Houska,L,2015] [Guo,L,2015]



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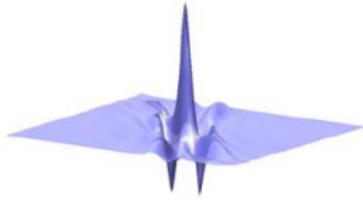
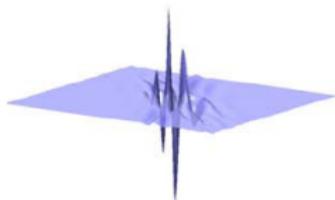
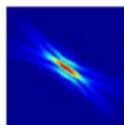
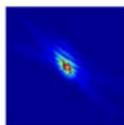
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It is possible to separate, in a precise sense, point and curvilinear singularities in 2D [Donoho, Kutyniok, 2013] or points and piecewise linear singularities (polyhedral singularities) in 3D [Guo & L, 2014].



Applications



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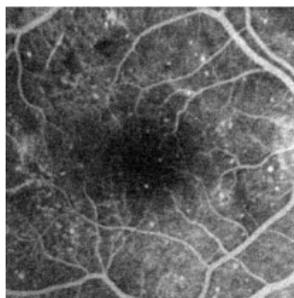
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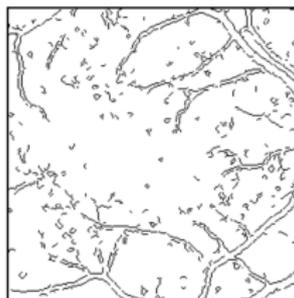


Edge Detection

Shearlet-based **edge detection** on retina images [Easley,L,Yi,2008].



Original retina image



Wavelet/Canny result
FOM=0.27



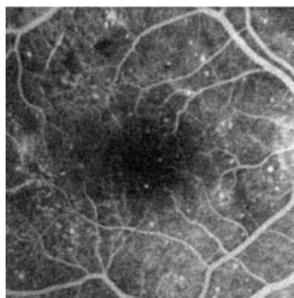
Shearlet result
FOM=0.45

The Figure Of Merit (FOM) measures the closeness of reconstruction to the true edge map (the higher the better).

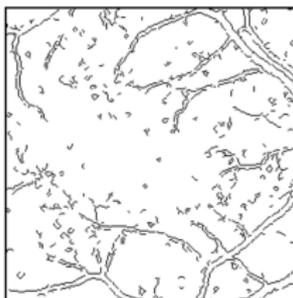


Edge Detection

Shearlet-based **edge detection** on retina images [Easley,L,Yi,2008].



Original retina image



Wavelet/Canny result
FOM=0.27



Shearlet result
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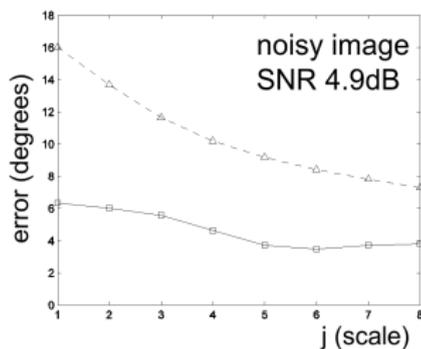
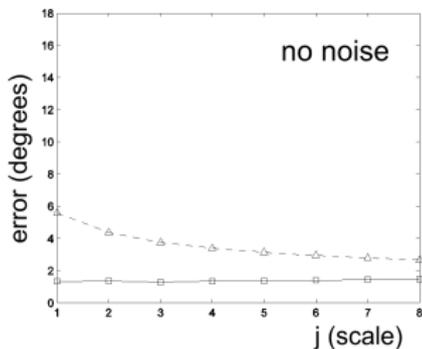
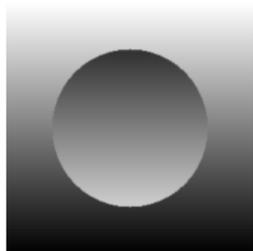
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Shearlet-based methods yield extremely competitive results.



Edge Orientation

With respect to conventional multiscale methods, shearlets enable more accurate and robust estimation of **edge orientation**.



Average error (degrees) in estimating edge orientation using a wavelet method (dashed line) versus a shearlet method (solid line), as a function of the scale 2^{-j} .



Feature Extraction

Multiscale methods can be very useful to extract **features and landmarks** in images. For example:



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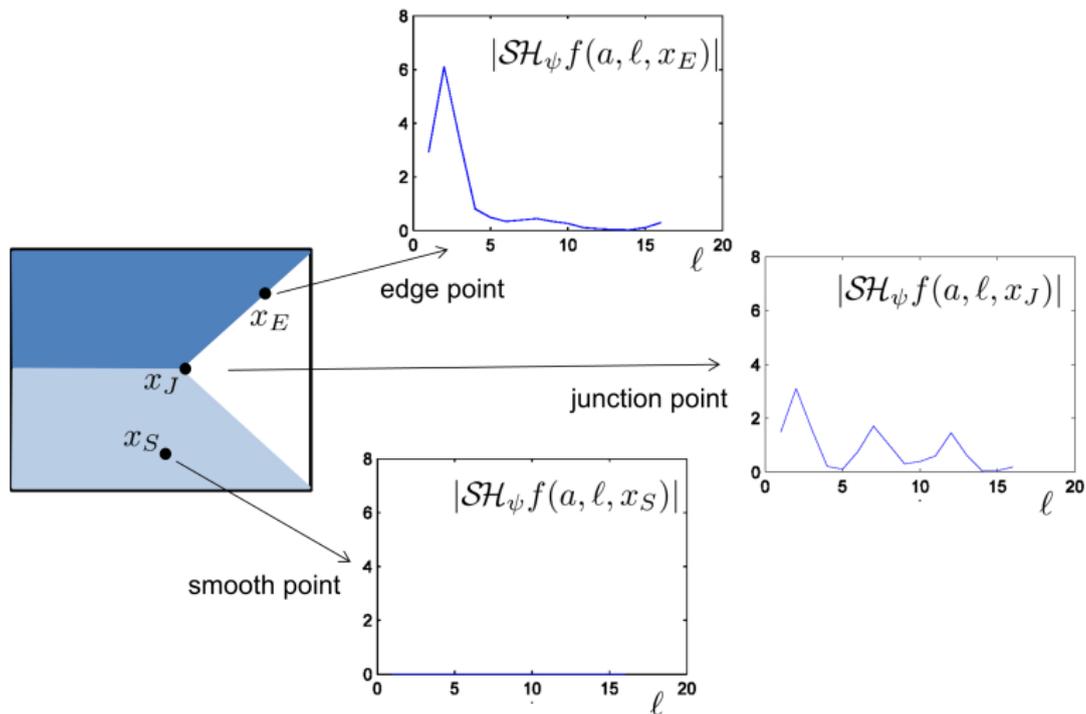
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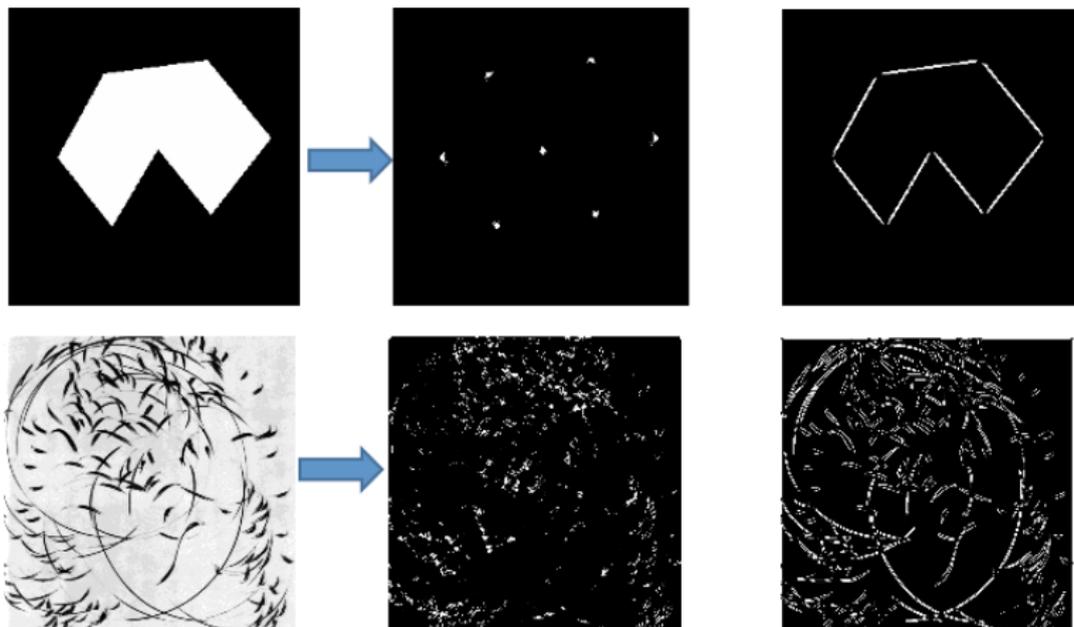
Single-scale shearlet analysis of **corners and junctions**

[Easley, Labate, Yi, 2008]



Feature Extraction

This idea can be used to **classify smooth regions, edges, corner points** [Easley,Labate,Yi,2008].



Feature Extraction

A multiscale variant of this idea can be used to define a **corner detector** that is stable to viewpoint and illumination change, and robust to blur and noise [Duval, Odone, De Vito, 2015].

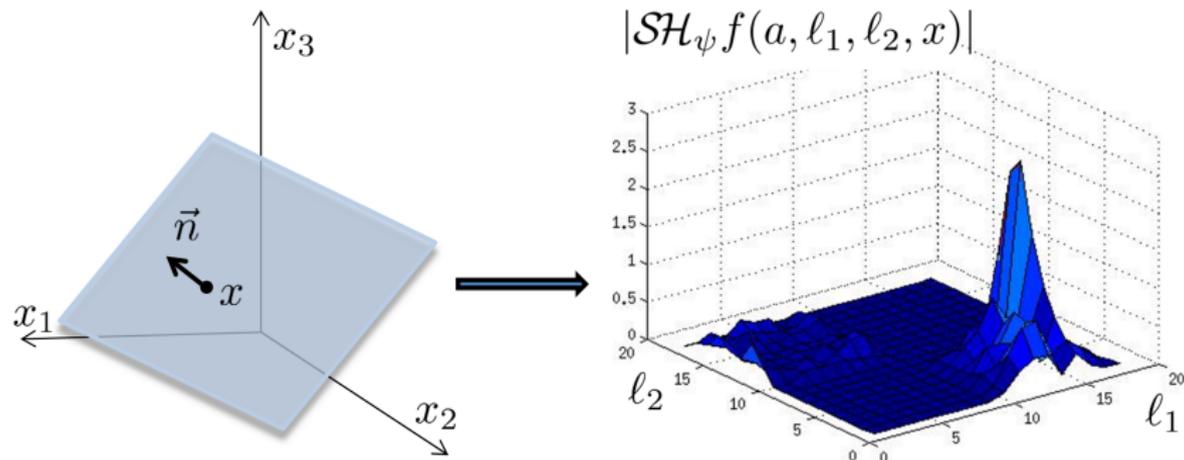


Shearlet multiscale corner detection: $j = 0$ (Blue); $j = 1$ (Green); $j = 2$ (Red); $j = 3$ (Magenta).



Surface Orientation

Same idea extends to 3D. The 3D shearlet transform can be used to estimate the **local surface orientation** [L,Negi,2013].

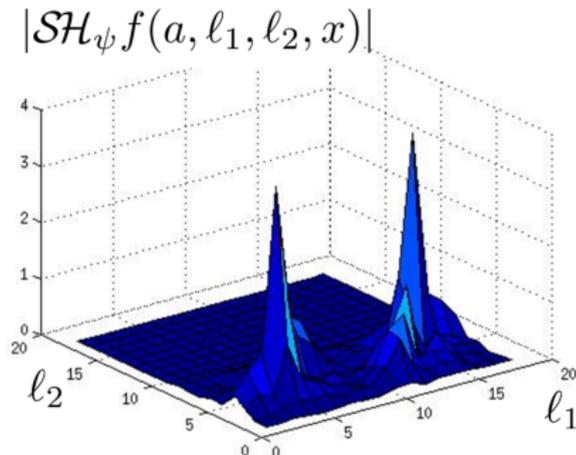
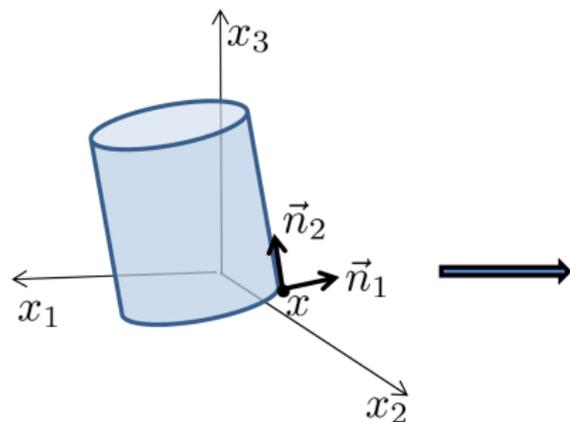


The magnitude of the continuous shearlet transform signals the local orientation of the surface of a solid



Surface Orientation

It can also be useful to detect **wedges and corners**.



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Classification

Due to their ability to capture singularities over multiple scales, multiscale representations are useful to generate highly **informative features** for problems of **classification**.



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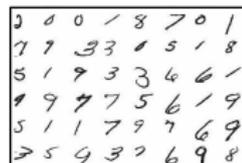
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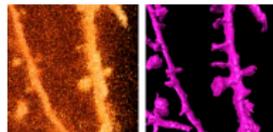
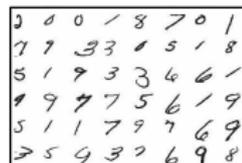
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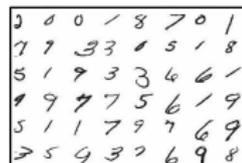
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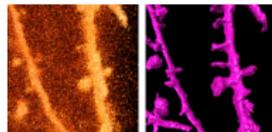
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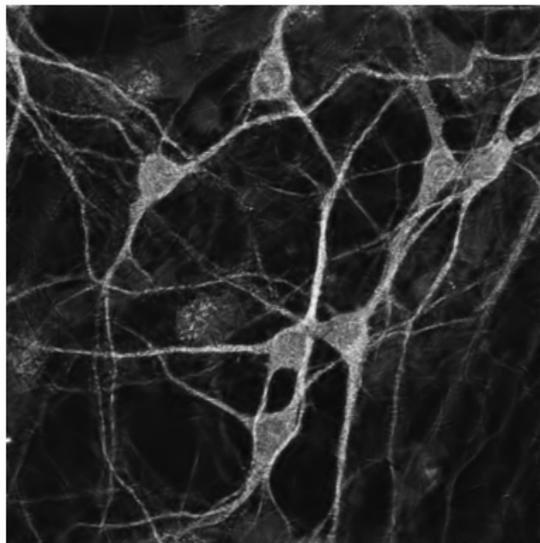


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Problem: Soma Extraction

In neuroscience imaging, it is useful to automatically separate somas from dendrites in fluorescent images of neurons.



It may be challenging to accurately **detect** and **extract** somas due to large variations in size and shape and irregularities of fluorescence intensity.



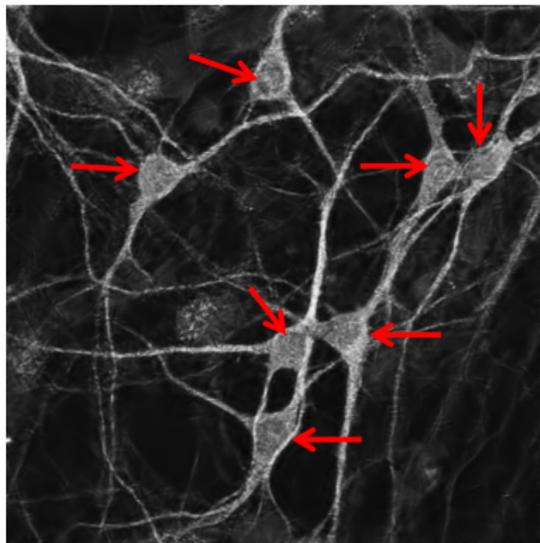
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Confocal image of neuronal culture (maximum projection view)



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Due to its *directional sensitivity*, the shearlet transform will exhibit a very different behavior at points of local isotropy (inside soma) vs. points of local anisotropy (inside dendrites)



Directionality Ratio

We define the **directionality ratio** of an image $f \in L^2(\mathbb{R}^2)$ at scale $a > 0$ and location $t \in \mathbb{R}^2$ as the quantity

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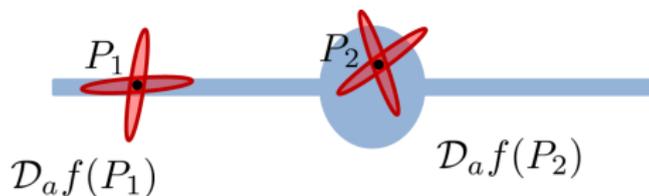
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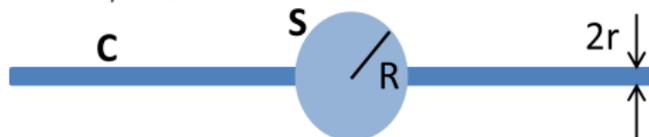
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The directionality ratio $\mathcal{D}_a f(t)$ will be very different depending on t being a point of local isotropy of f or not.



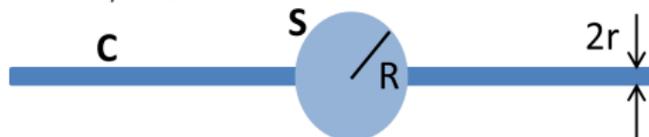
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Theorem [Labate,Negi,Ozcan,Papadakis,2014]: Let $f = \chi_N$, where N is the union of two subsets: a ball S with radius $R > 0$ and a cylinder C of size $2r \times L$, where $r > 0$, $L \gg R$.



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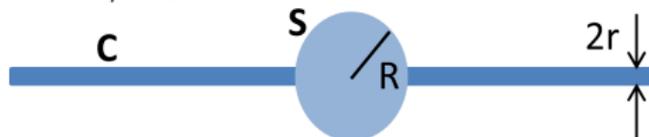


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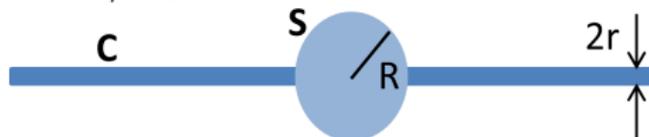
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On the other hand, the directionality ratio of f is **large (close to 1) inside the ball** S .



Soma Extraction. Segmentation

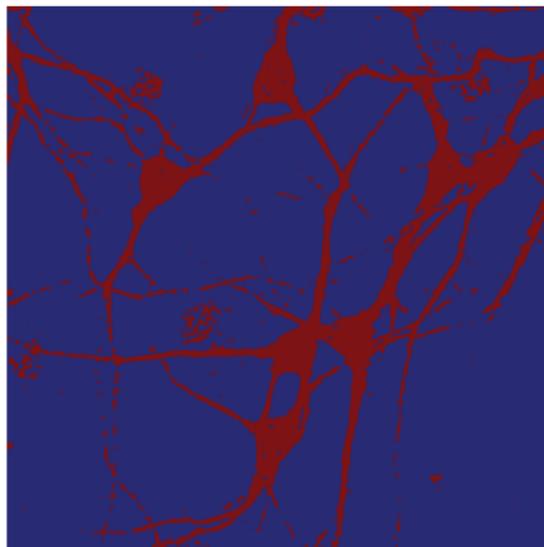
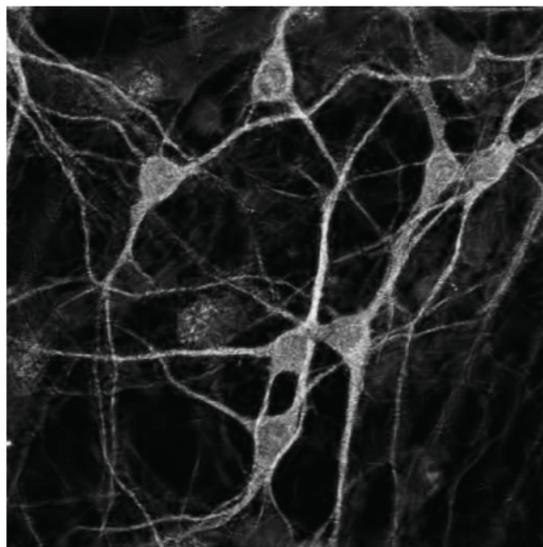
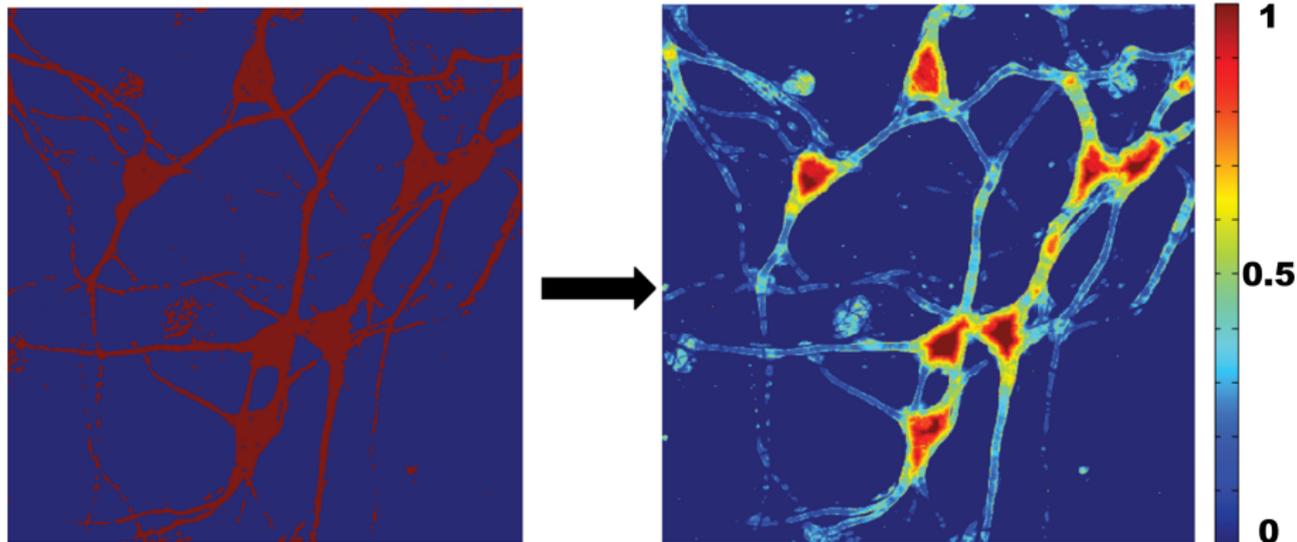


Image segmentation (SVM based)



Soma Extraction. Directionality ratio



Computation of directionality ratio



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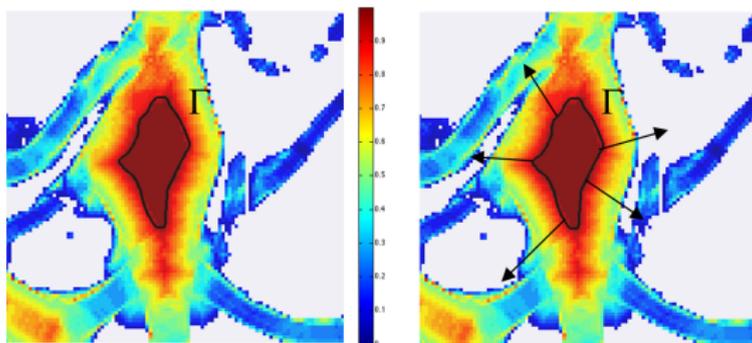


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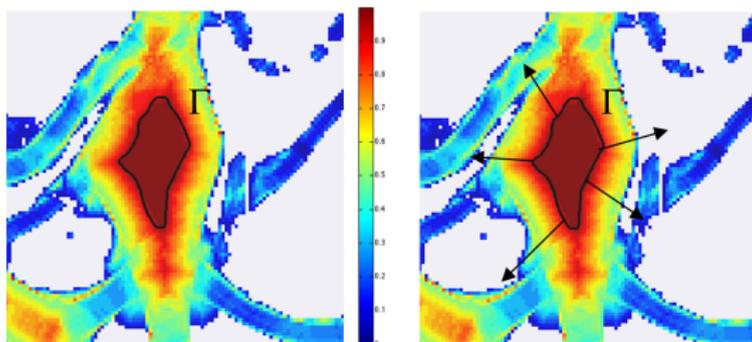


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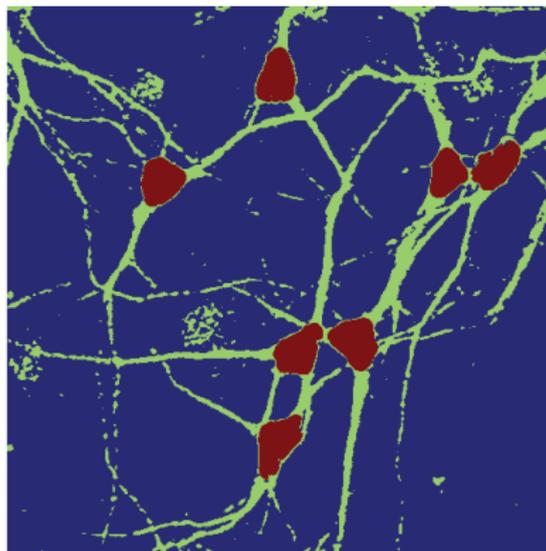
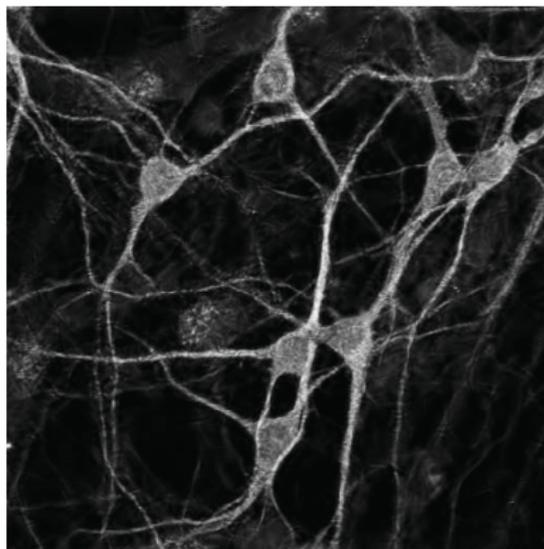
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We also use this method to separate clustered somas.

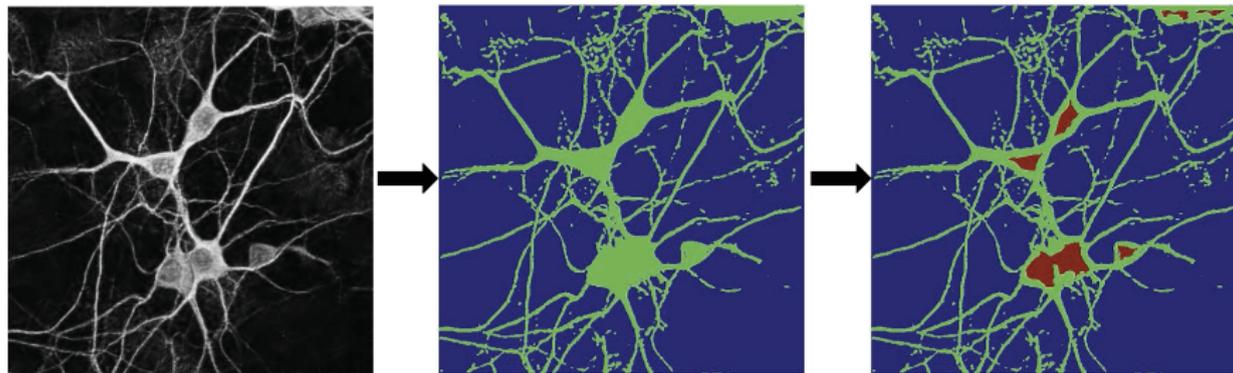


Soma Extraction



Directionality ratio + level set: soma detection

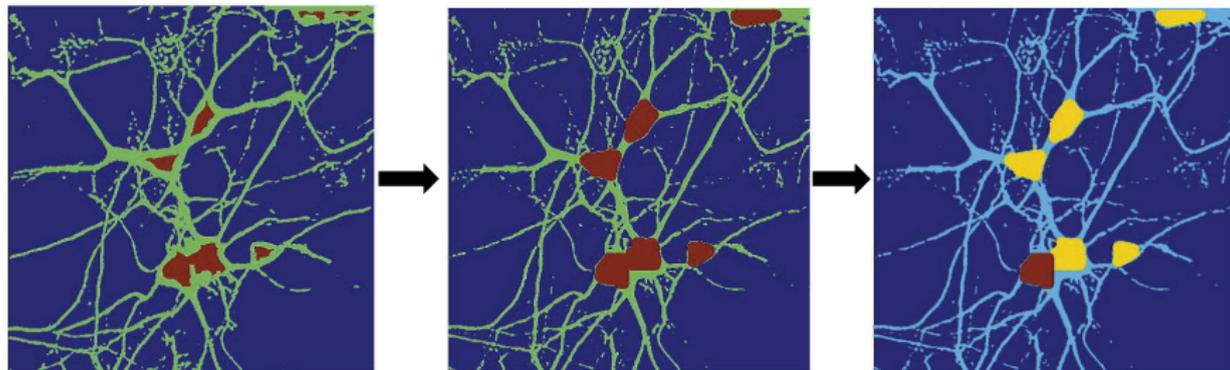
Soma Extraction. Another example



Identification of somas



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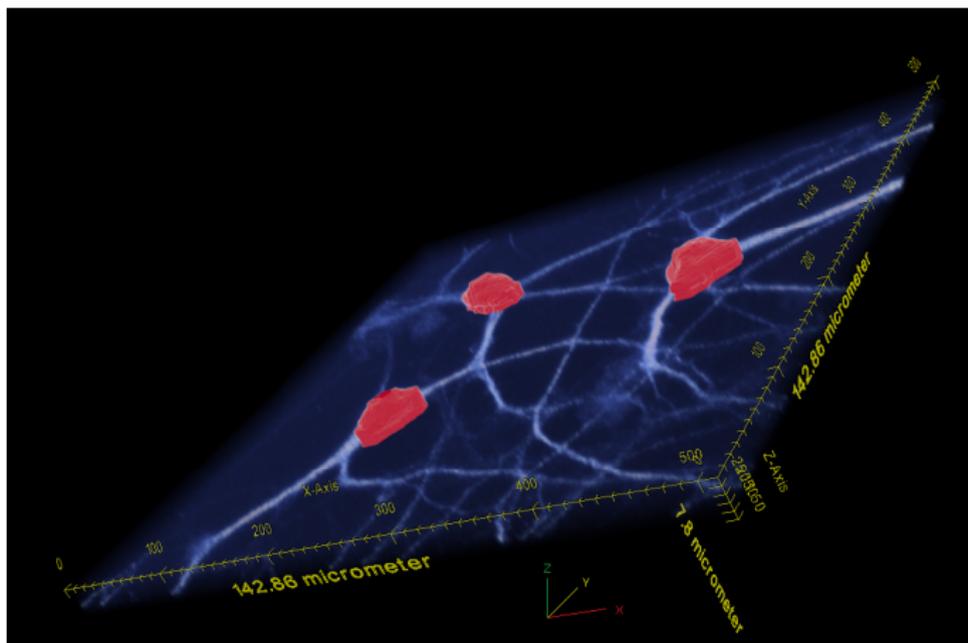


Identification of somas and separation of clustered ones



Soma Extraction (3D)

Method extends to 3D where soma detection can be combined with the extraction of soma morphology [Bozcan,L,Laezza,Negi,Papadakis,2014]



Scattering Transform

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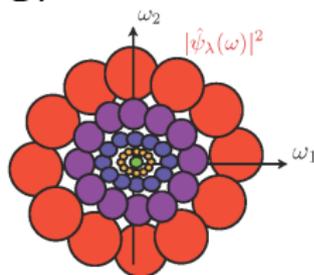
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Dilated wavelets are also rotated with elements $r \in G$:

$$\psi_\lambda(x) = a^{-1}\psi(a^{-1}rx)$$

with $\lambda = (a, r)$, $a > 0, r \in G$.

$$\mathcal{W}_\psi : f \mapsto \mathcal{W}_\psi f(a, t) = f * \psi_\lambda(t)$$



Scattering Transform

By taking the magnitude and then averaging with a low-pass function ϕ , one defines **locally translation invariant** coefficients

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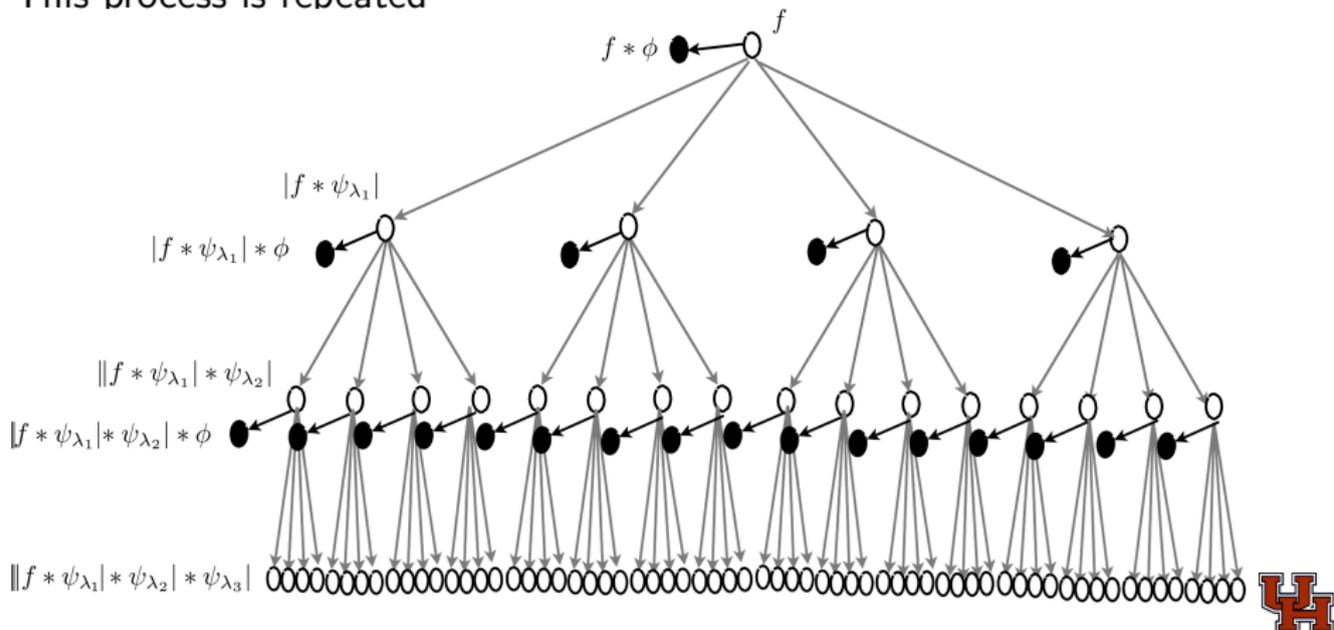


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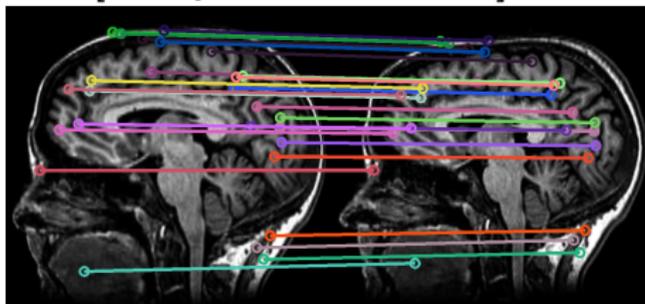
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 - ▶ soma detection, texture classification, . . .





References + codes at:

www.math.uh.edu/~dlabate

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