

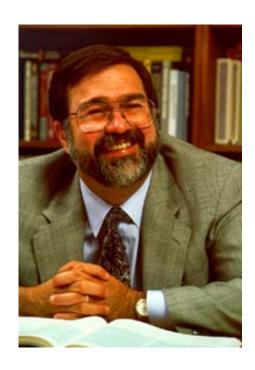


The Moment Problem for Rational Measures: Convexity in the Spirit of Krein

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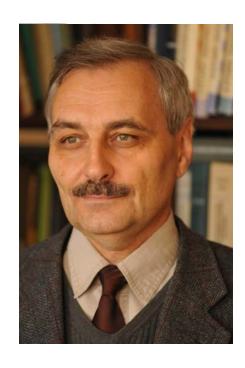
Special recognition



Christopher Byrnes



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C. I. Byrnes and A. Lindquist, The moment problem for rational measures: convexity in the spirit of Krein, in *Modern Analysis and Applications: To the Centenary of Mark Krein*, Vol I, Birkhäuser 2009.

Outline of talk

- The classical theory of moments in the style of Krein
- The moment problem for rational measures
- A Dirichlet principle for the rational moment problem

The generalized moment problem in the spirit of Krein

 \mathfrak{P} finite-dimensional subspace of C[a,b]

$$(u_0, u_1, \ldots, u_n)$$
 basis in \mathfrak{P}

$$p \in \mathfrak{P} \Rightarrow$$

$$p(t) = \sum_{k=0}^{n} p_k u_k(t)$$

Given $c := (c_0, c_1, \dots, c_n) \in \mathbb{C}^{n+1}$,

find positive measure $d\mu$ such that

$$\int_a^b u_k(t) \frac{d\mu}{d\mu} = c_k, \quad k = 0, 1, \dots, n$$



Dual cones

$$p \in \mathfrak{P} \Rightarrow$$

$$p(t) = \sum_{k=0}^{n} p_k u_k(t)$$

$$\mathfrak{P}_+ := \{ p \in \mathfrak{P} \mid P(t) := \operatorname{Re}(p) \ge 0 \quad \forall t \in [a, b] \}$$

closed convex cone

$$\langle c,p
angle := \operatorname{Re}\left\{\sum_{k=0}^n c_k p_k\right\} \quad ext{where } c := (c_0,c_1,\ldots,c_n) \in \mathbb{C}^{n+1}.$$

$$\mathfrak{C}_{+} := \left\{ c \in \mathbb{C}^{n+1} \mid \langle c, p \rangle \ge 0 \quad \forall p \in \mathfrak{P}_{+} \right\}$$

dual cone

closed convex

$$\mathfrak{C}_+=\mathfrak{P}_+^\mathsf{T}$$

 $c \in \mathfrak{C}_+$ positive sequence

Ex 1: Power moment problem

$$u_k(t) = t^k, \quad k = 0, 1, \dots, n$$

Every $p \in \mathfrak{P}$ is a polynomial.

$$c \in \mathfrak{C}_{+}$$

$$(n \text{ even})$$

$$\begin{cases} \begin{bmatrix} c_{j+k} \end{bmatrix}_{j,k=0}^{n/2} \ge 0 \\ \\ (a+b)c_{j+k+1} - abc_{j+k} - c_{j+k+2} \end{bmatrix}_{j,k=0}^{n/2-1} \ge 0 \end{cases}$$

Ex 2: Trigonometric moment problem

$$u_k(t) := e^{ikt}, \quad k = 0, 1, \dots, n \qquad [a, b] = [-\pi, \pi]$$

$$c \in \mathfrak{C}_{+} \qquad \longleftarrow \qquad T_{n} = \begin{bmatrix} c_{0} & c_{1} & \cdots & c_{n} \\ \bar{c}_{1} & c_{0} & \cdots & c_{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ \bar{c}_{n} & \bar{c}_{n-1} & \cdots & c_{0} \end{bmatrix} \geq 0$$

Toeplitz matrix

Ex 3: Nevanlinna-Pick interpolation

$$u_k(t) = \frac{e^{it} + z_k}{e^{it} - z_k}, \quad k = 0, 1, \dots, n$$

For $d\mu = Fdt$, where F = Re(f) with f analytic in \mathbb{D} ,

$$c_k = \int_{-\pi}^{\pi} u_k(t) F(t) dt = f(z_k) \quad k = 0, 1, \dots, n$$

$$c \in \mathfrak{C}_+$$

$$\qquad \qquad P_n = \left[\frac{c_j + \bar{c}_k}{1 - z_j \bar{z}_k}\right]_{j,k=0}^n \ge 0$$

Pick matrix

The moment map

$$\mathfrak{M}: C[a,b]^* \to \mathbb{C}^{n+1}, \quad d\mu \mapsto c = \int_a^b u(t)d\mu$$

 $\mathcal{M}_+ \subset C[a,b]^*$ space of positive measures

$$c \in \mathfrak{M}(\mathcal{M}_+)$$

$$P(t) = \operatorname{Re}\{p(t)\}\$$

$$\langle c, p \rangle := \operatorname{Re} \left\{ \sum_{k=0}^{n} c_k p_k \right\} = \int_a^b P(t) d\mu \ge 0 \quad \forall p \in \mathfrak{P}_+$$



$$c\in \mathfrak{C}_+$$

$$\mathfrak{M}(\mathcal{M}_+)\subset \mathfrak{C}_+$$

HYPOTHESIS 1. $\mathring{\mathfrak{P}}_{+} \neq \emptyset$, where $\mathring{\mathfrak{P}}_{+}$ is the interior of \mathfrak{P}_{+} .

THEOREM(Krein-Nudelman). Suppose that Hypothesis 1 holds. Then

$$\mathfrak{M}(\mathcal{M}_+)=\mathfrak{C}_+.$$

In other words, the moment problem is solvable if and only if c is positive.

We have already shown that $\mathfrak{M}(\mathcal{M}_+) \subset \mathfrak{C}_+$ It remains to prove that $\mathfrak{M}(\mathcal{M}_+) \supset \mathfrak{C}_+$ **Proof.** Consider the curve $U = \{u(t); t \in [a, b]\} \subset \mathbb{C}^{n+1}$, where $u(t) = (u_0(t), u_1(t), \dots, u_n(t))$ $a \leq t \leq b$.

For $p \in \mathfrak{P}$,

$$\langle u(t), p \rangle := \operatorname{Re} \left\{ \sum_{k=0}^{n} p_k u_k(t) \right\} = \operatorname{Re} \left\{ p(t) \right\} = P(t)$$

K(U) convex conic hull of U

$$K(U)^{\mathsf{T}} = \{ p \in \mathfrak{P} \mid \langle \phi, p \rangle \ge 0, \ \forall \phi \in K(U) \} = \mathfrak{P}_+$$

$$K(U) = \mathfrak{C}_+$$

 $\mathfrak{M}(\mathcal{M}_+) \subset \mathfrak{C}_+$ is closed, by the Helly selection theorem.

Show that
$$\mathfrak{C}_+ \subset \mathfrak{M}(\mathcal{M}_+)$$
: $\mathfrak{M}(\delta_t) = u(t), \quad a \leq t \leq b$

$$U \subset \mathfrak{M}(\mathcal{M}_{+}) \longrightarrow \underbrace{K(U)}_{\mathfrak{C}_{+}} \subset \mathfrak{M}(\mathcal{M}_{+})$$

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- The moment problem for rational measures
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A motivating example

$$\mathbf{w}(\mathbf{z}) \qquad \mathbf{y} \qquad y(t) = \sum_{k=-\infty}^{t} w_{t-k} u(k)$$

System is finite-dimensional iff $w(z) := \sum_{k=0}^{\infty} w_k z^{-k}$ is rational

white noise
$$\underbrace{ \begin{array}{c} \mathbf{u} \\ \mathbf{w}(\mathbf{z}) \end{array} }$$
 $\underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{array} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \\ \mathbf{w}(\mathbf{t}) \end{aligned} }_{\mathbf{w}(\mathbf{t})} \underbrace{ \begin{array}{c} \mathbf{y} \\ \mathbf{w}(\mathbf{t}) \end{aligned}$

$$\int_{-\pi}^{\pi} e^{ik\theta} \Phi(e^{i\theta}) \frac{d\theta}{2\pi} = c_k := E\{y(t+k)y(t)\} \qquad \qquad \Phi(z) = \frac{P(z)}{Q(z)}$$

\$\mathfrak{P}\$ consists of trigonometric polynomials

$$P(e^{i\theta}) = \text{Re}\{p(e^{i\theta})\}, \quad Q(e^{i\theta}) = \text{Re}\{q(e^{i\theta})\}, \text{ where } p, q \in \mathfrak{P}_+$$

The moment problem for rational measures

DEF.
$$p \in \mathfrak{P}, \quad p = \sum_{k=0}^{n} p_k u_k$$
 polynomial in \mathfrak{P}
$$P = \operatorname{Re}(p)$$

P/Q, where $p, q \in \mathfrak{P}$ real rational function for \mathfrak{P}

$$\mathcal{R}_{+} = \left\{ d\mu \mid d\mu = rac{P(t)}{Q(t)} dt, \; p,q \in \overset{\circ}{\mathfrak{P}}_{+}
ight\} \subset \mathcal{M}_{+}$$

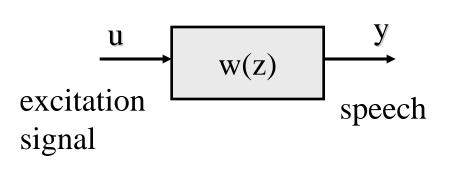
rational positive measure

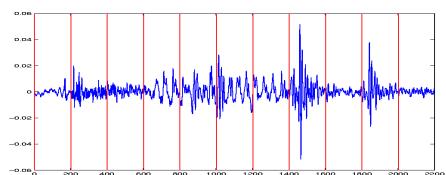
$$\int_{a}^{b} u_k d\mu = c_k, \quad k = 0, 1, \dots, n \quad (\dagger)$$

Find $d\mu \in \mathcal{M}_+$ satisfying (†) linear problem

Find $d\mu \in \mathcal{R}_+$ satisfying (†) nonlinear problem

Ex: Modeling speech





on each (30 ms) subinterval w(z) constant, y stationary

observation: y_0, y_1, \ldots, y_N

 $N \approx 250$

$$\int_{-\pi}^{\pi} e^{ikt} d\mu = c_k := \frac{1}{N+1} \sum_{t=0}^{N-k} y_{t+k} y_t, \quad k = 0, 1, \dots, n \quad \frac{n}{n} = \frac{10}{N+1}$$

$$\mathfrak{P} = \operatorname{span}\{1, e^{it}, e^{2it}, \dots, e^{int}\}\$$

$$d\mu = \left| w(e^{it}) \right|^2 dt \in \mathcal{R}_+$$

Cellular telephone:

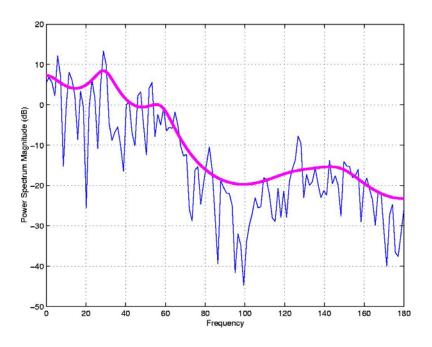
$$d\mu = \frac{\rho_n}{\left|\varphi_n(e^{it})\right|^2} dt$$

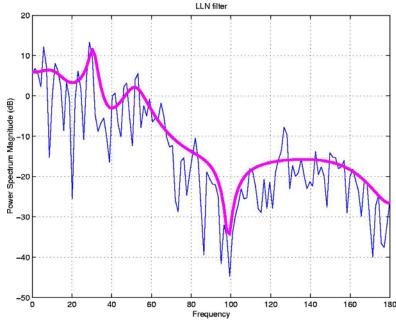
 $\varphi_n(z)$ n:th Szegö polynomial orthogonal on the unit circle

FFT in blue

Another rational positive measure of the same degree







$$\overset{\circ}{\mathfrak{C}_{+}}$$
 interior of \mathfrak{C}_{+}

$$c \in \overset{\circ}{\mathfrak{C}_+}$$
 \longleftrightarrow $\langle c, p \rangle > 0$ $\forall p \in \mathfrak{P}_+ \setminus \{0\}$ strictly positive sequence

HYPOTHESIS 2. The vector space \mathfrak{P} consists of Lipschitz continuous functions.

THEOREM. Suppose that Hypotheses 1 and 2 hold. Then

$$\mathfrak{M}(\mathcal{R}_+) = \overset{\circ}{\mathfrak{C}}_+.$$

In other words, the moment problem for rational measures is solvable if and only if c is strictly positive.

THEOREM. Suppose that Hypotheses 1 and 2 hold. Then

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In other words, the moment problem for rational measures is solvable if and only if c is strictly positive.

THEOREM(Krein-Nudelman). Suppose that Hypothesis 1 holds. Then

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THEOREM. Suppose that Hypotheses 1 and 2 hold. Then

$$\mathfrak{M}(\mathcal{R}_+) = \overset{\circ}{\mathfrak{C}}_+.$$

In other words, the moment problem for rational measures is solvable if and only if c is strictly positive.

Proof. As in the classical case:

$$\langle c, p \rangle = \int_a^b P d\mu > 0 \quad \forall p \in \mathfrak{P}_+ \setminus \{0\} \quad \Longrightarrow \quad \mathfrak{M}(\mathcal{R}_+) \subset \mathring{\mathfrak{C}}_+$$

To show that $\mathfrak{M}(\mathcal{R}_+) = \mathring{\mathfrak{C}}_+$ it suffices to show:

PROPOSITION. Suppose that Hypotheses 1 and 2 hold. Then there is a nonempty subset $\mathcal{P}_+ \subset \mathcal{R}_+$ such that $\mathfrak{M}(\mathcal{P}_+)$ is both open and closed in the convex set $\overset{\circ}{\mathfrak{C}}_+$.

$$\mathfrak{M}(\mathcal{P}_+) = \overset{\circ}{\mathfrak{C}}_+ \qquad \mathfrak{M}(\mathcal{R}_+) = \overset{\circ}{\mathfrak{C}}_+$$

PROPOSITION. Suppose that Hypotheses 1 and 2 hold. Then there is a nonempty subset $\mathcal{P}_+ \subset \mathcal{R}_+$ such that $\mathfrak{M}(\mathcal{P}_+)$ is both open and closed in the convex set $\overset{\circ}{\mathfrak{C}}_+$.

For a fixed $p \in \mathring{\mathfrak{P}}_+$, consider the set

$$\mathcal{P}_{+} = \left\{ d\mu \in \mathcal{R}_{+} \mid d\mu = \frac{P}{Q}dt, \ q \in \mathring{\mathfrak{P}}_{+} \right\}$$

and the map $\mathfrak{M}_{|\mathcal{P}_+}:\mathcal{P}_+ \to \mathring{\mathfrak{C}}_+$.

- Jac $\mathfrak{M}_{|\mathcal{P}_+}$ full rank \longrightarrow $\mathfrak{M}(\mathcal{P}_+) \subset \mathring{\mathfrak{C}}_+$ open
- Q Lipschitz $\longrightarrow \mathfrak{M}_{|\mathcal{P}_+}$ proper $\longrightarrow \mathfrak{M}(\mathcal{P}_+) \subset \mathring{\mathfrak{C}}_+$ closed

COROLLARY. Suppose that Hypotheses 1 and 2 hold. Then the moment map $\mathfrak{M}_{|\mathcal{P}_+}: \mathcal{P}_+ \to \mathring{\mathfrak{C}}_+$ is surjective. In other words, for each $c \in \mathring{\mathfrak{C}}_+$, the moment problem

$$\mathfrak{M}(d\mu) = c \quad \text{for } d\mu \in \mathcal{P}_+$$

has a solution.

We want to show that $\mathfrak{M}_{|\mathcal{P}_+}: \mathcal{P}_+ \to \mathring{\mathfrak{C}}_+$ is also injective. In other words, for each $c \in \mathring{\mathfrak{C}}_+$, the moment problem

$$\mathfrak{M}(d\mu) = c \quad \text{for } d\mu \in \mathcal{P}_+$$

has a unique solution.

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- The classical theory of moments in the style of Krein
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A Dirichlet principle

Solving the moment problem

$$\mathfrak{M}(d\mu) = c \quad \text{for } d\mu \in \mathcal{P}_+ \qquad \qquad c \in \overset{\circ}{\mathfrak{C}}_+$$

is equivalent to solving the equations

$$f_k^p(q) := c_k - \int_a^b u_k \frac{P}{Q} dt = 0, \quad k = 0, 1, \dots, n,$$

where $p \in \mathring{\mathfrak{P}}_+$ is fixed.

In this case, the Dirichlet Principle would say that $f_k^p(q) = 0$ should be the critical point equations for some smooth function $\mathbb{J}_p: \mathring{\mathfrak{P}}_+ \to \mathbb{R}$. In fact, a Dirichlet Principle would assert that \mathbb{J}_p should have a unique minimum and no other critical points.

Define a 1-form on
$$\mathring{\mathfrak{P}}_+$$
: $\omega = \operatorname{Re} \left\{ \sum_{k=0}^n f_k^p(q) dq_k \right\}$

$$\omega = \operatorname{Re} \left\{ \sum_{k=0}^{n} c_k dq_k - \int_a^b \sum_{k=0}^{n} u_k dq_k \frac{P}{Q} dt \right\}$$

$$dQ = \operatorname{Re} \sum_{k=0}^{n} u_k dq_k = \operatorname{Re} \sum_{k=0}^{n} c_k dq_k - \int_a^b \frac{P}{Q} dQ dt$$

$$d\omega = \int_{a}^{b} \frac{P}{Q^2} dQ \wedge dQ dt = 0$$
 ω closed

$$\mathring{\mathfrak{P}}_+$$
 convex



 \mathfrak{P}_+ convex $\qquad \qquad \omega$ exact (The Poincaré Lemma)

$$\omega = \operatorname{Re} \sum_{k=0}^{n} c_k dq_k - \int_{a}^{b} \frac{P}{Q} dQ dt$$

By the Poincaré Lemma, we can integrate along any curve:

$$\mathbb{J}_p(q_1) := \int_{q_0}^{q_1} \left(\operatorname{Re} \sum_{k=0}^n c_k dq_k - \int_a^b \frac{P}{Q} dQ dt \right) \qquad \blacksquare$$

$$\mathbb{J}_p(q) = \langle c, q \rangle - \int_a^b P \log Q \, dt \qquad \begin{array}{c} \text{(modulo a constant)} \\ \text{of integration)} \end{array}$$

This is a strictly convex functional

$$\mathbb{J}_p(q) = \langle c, q \rangle - \int_a^b P \log Q \, dt$$

strictly convex function $\mathbb{J}_p: \check{\mathfrak{P}}_+ \to \mathbb{R}$ satisfying

$$\frac{\partial \mathbb{J}_p}{\partial q_k} = c_k - \int_a^b u_k \frac{P}{Q} dt, \quad k = 0, 1, \dots, n \quad (\dagger)$$

- 1. We have already shown that $\mathfrak{M}_{|\mathcal{P}_{+}}$ is surjective so that the moment equations (†) have a solution $\hat{q} \in \mathring{\mathfrak{P}}_{+}$.
- 2. Therefore, since \mathbb{J}_p is strictly convex, \mathbb{J}_p has a unique minimum.
- 3. Hence $\mathfrak{M}_{|\mathcal{P}_+}$ is also injective. In fact, $\mathfrak{M}_{|\mathcal{P}_+}$ is a diffeomorphism.
- 4. Fix $c \in \mathring{\mathfrak{C}}_+$. The map $g^c : \mathring{\mathfrak{P}}_+ \to \mathring{\mathfrak{P}}_+$ that sends p to \hat{q} is a diffeomorphism onto its image. In other words, the solutions to the moment problem with rational positive measures are completely parameterized by $p \in \mathring{\mathfrak{P}}_+$; i.e., the spectral zeros.

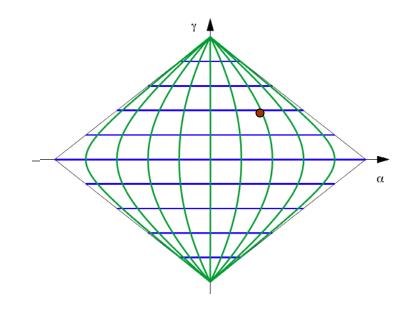
EXAMPLE.
$$\mathfrak{P} = \text{span}\{1, e^{it}, \dots, e^{int}\}$$

The solutions $d\mu \in \mathcal{R}_+$ form a manifold of dimension 2n.

A foliation with one leave for each choice of $p \in \mathring{\mathfrak{P}}_+$ (Kalman filtering)

A foliation with one leave for each choice of $c \in \mathring{\mathfrak{C}}_+$

THEOREM. The two foliations intersect transversely so that each leaf in one meets each leaf in the other in exactly one point.



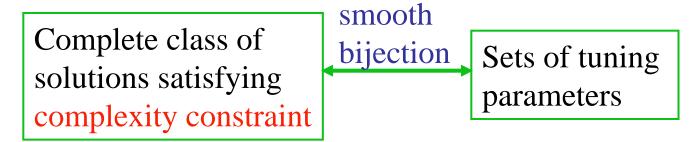
$$\min_{q \in \mathring{\mathfrak{P}}_+} \mathbb{J}(q)$$



unique solution $d\mu = \frac{P}{Q}dt$

Basic paradigm

• Find complete parameterization



- For any choice of tuning parameters, determine the corresponding solution by convex optimization
- Choose a solution that best satisfies additional design specifications (without increasing the complexity)

Conclusions

- The classical moment problem has a solution for each positive sequence.
- Natural constraints in applications, e.g., in systems and control, motivate the moment problems for rational measures.
- The moment problem for rational measures
 - has a solution for each strictly positive sequence
 - is completely parameterized by spectral zeros
 - can be solved by convex optimization