



**Víctor F. Breña-Medina**

Centro de Ciencias Matemáticas, UNAM

Daniele Avitabile

University of Nottingham

Alan R. Champneys & Claire Grierson

University of Bristol

Michael J. Ward

University of British Columbia

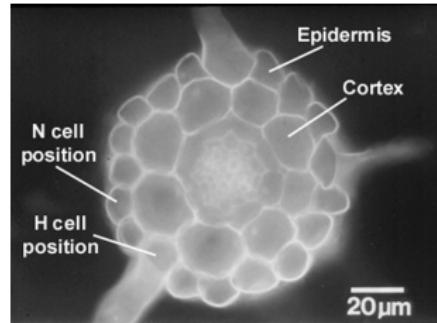
# On How Turing Triggers Biochemical Spot Dynamics in a Plant Root Hair Initiation Model

MS77 COMPUTES SHOOTS AND LEAVES: ALAN TURING,  
PHYLLOTAXIS AND BEYOND - PART I OF II  
SIAM Conference on Applications of Dynamical Systems

May 23, 2017

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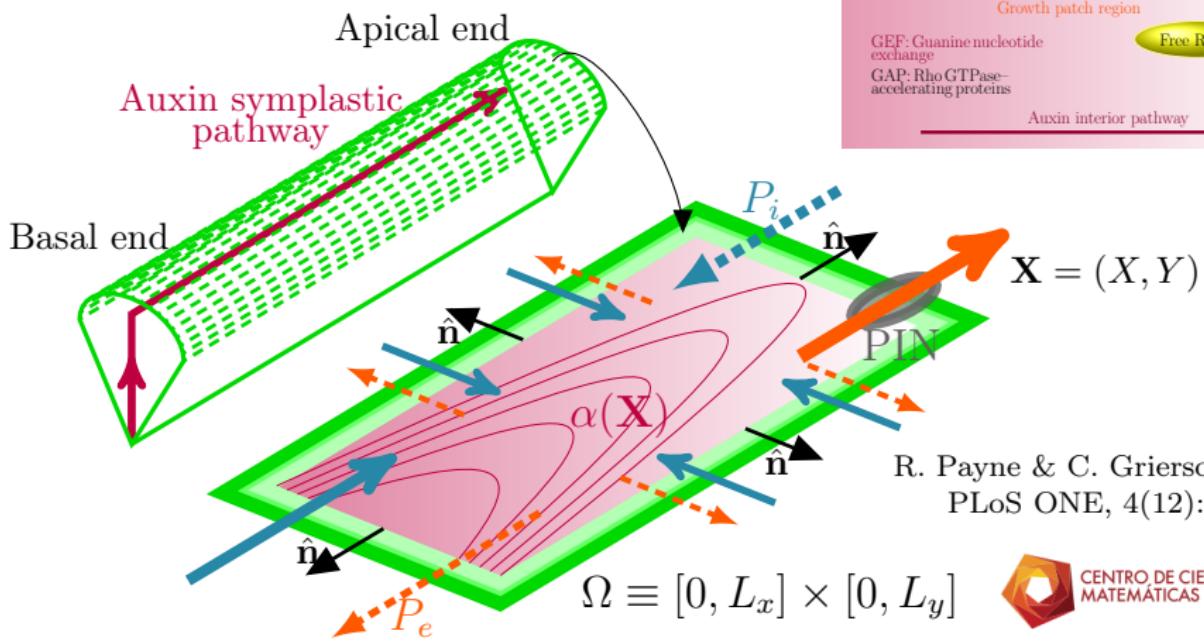
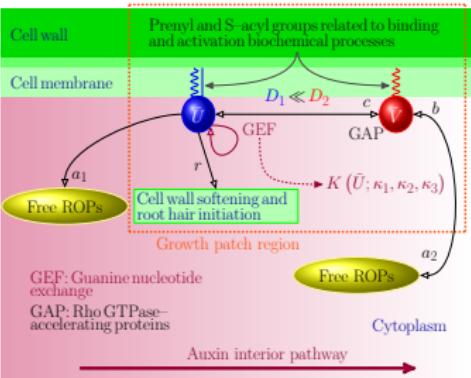
- ① Biochemical patches
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C. Grierson & J. Schiefelbein, 2002

● Generalised Schnakenberg system

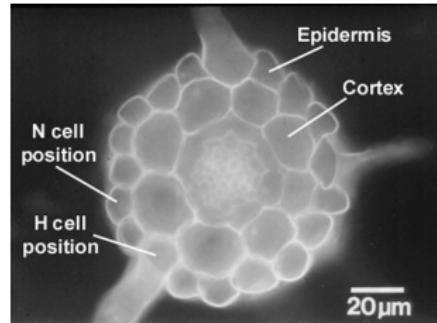
$$\begin{cases} U_t = D_1 \Delta U + k_{20} \alpha(\mathbf{X}) U^2 V - (c + r)U + k_1 V, \\ V_t = D_2 \Delta V - k_{20} \alpha(\mathbf{X}) U^2 V + cU - k_1 V + b. \end{cases}$$



R. Payne & C. Grierson (2009).  
PLoS ONE, 4(12):e8337

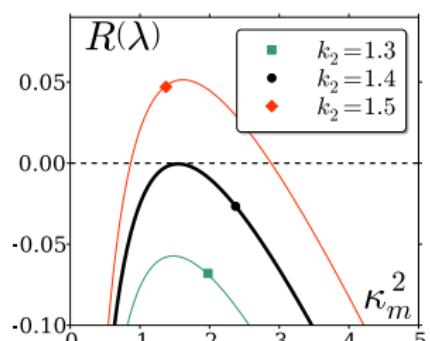
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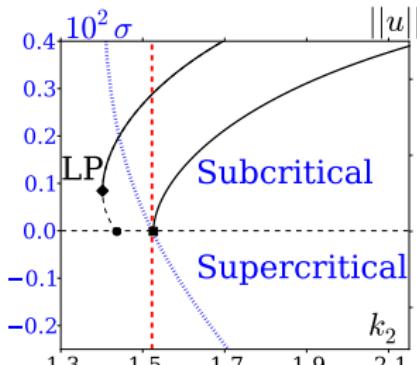


C. Grierson & J. Schiefelbein, 2002

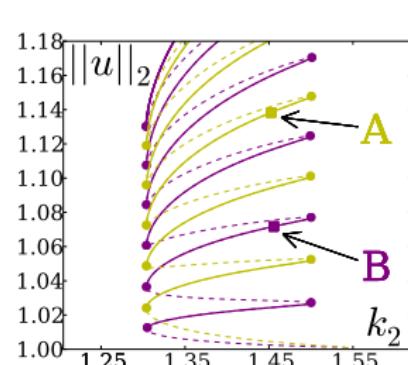
Turing bifurcation to homoclinic snaking



Dispersion relation



Criticality transition

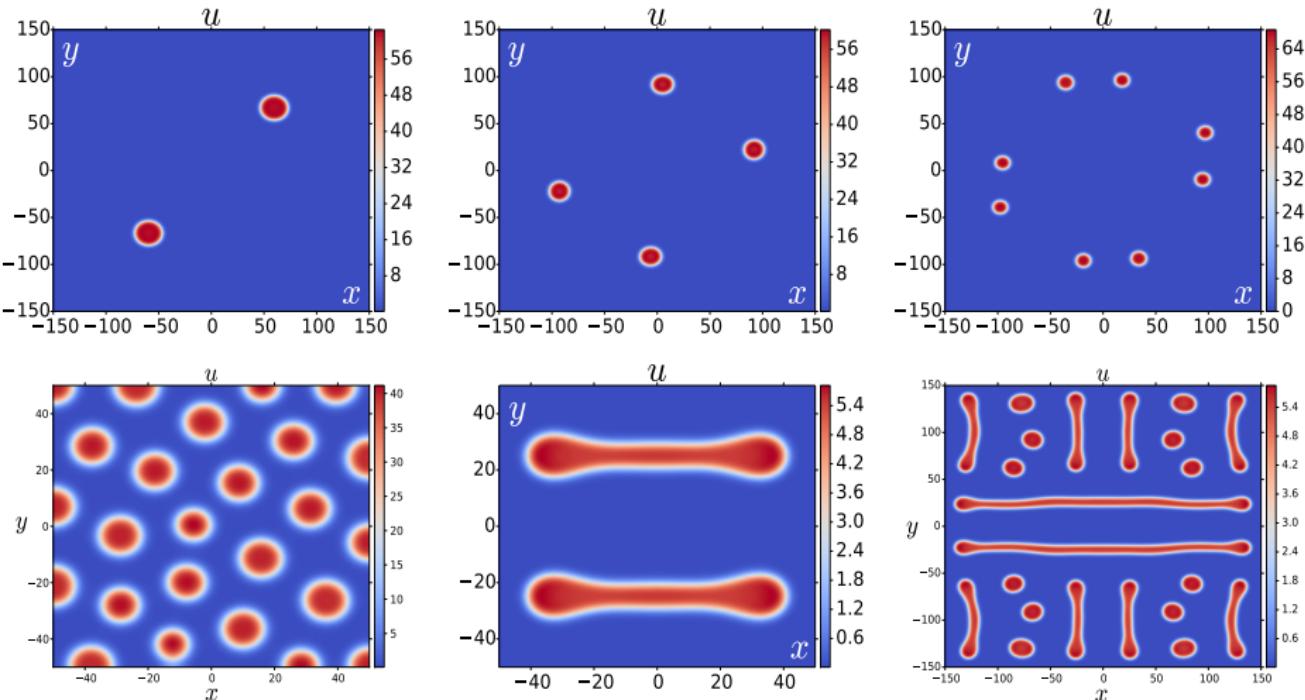


Homoclinic snaking

$$q_1 \underbrace{(k_2 - k_{2c})}_{\mu} z + q_3 z^3 + q_5 z^5 + \text{h.o.t.} = 0, \quad \sigma \equiv q_1 q_3.$$

- 👉 Root of multiplicity two.
- 👉 Long domain.
- 👉 Super- to subcritical transition.
- 👉 Spatial reversibility for steady-states.
- 👉 Turing bifurcation  $\leftrightarrow$  Hamilton–Hopf bifurcation.

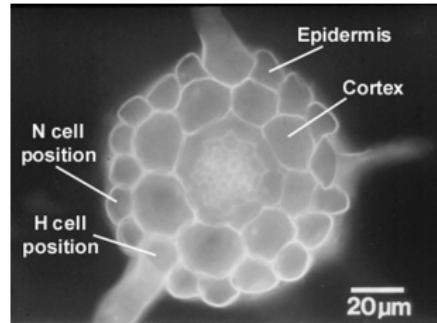
Turing bifurcation to homoclinic snaking



... joint work with A. Champneys  
Phys. Rev. E 90, 032923 (2014).

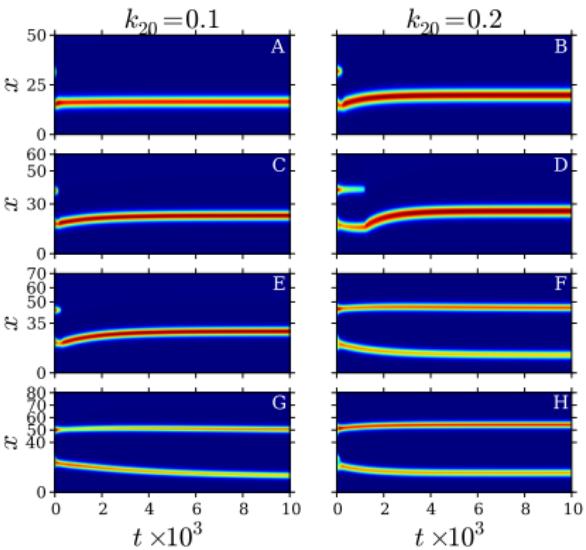
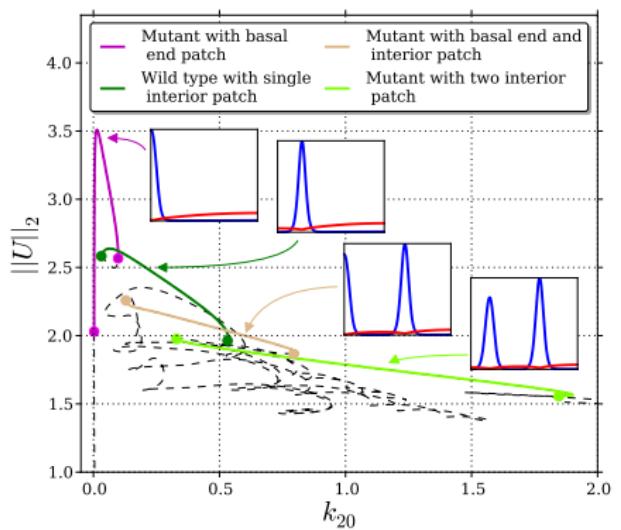
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## Hysteretical structure

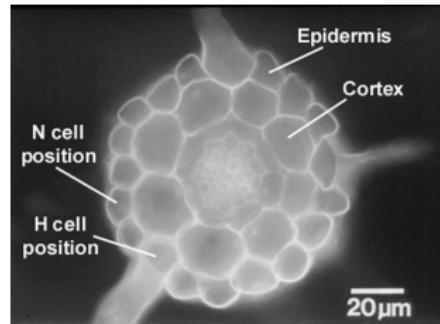


- 👉 Slow drifting spikes.
- 👉 Asymmetric amplitudes.
- 👉 Gradient controls location.
- 👉 Over-crowding instability.
- 👉 Perturbed **subcritical** Turing bifurcation. 🚀

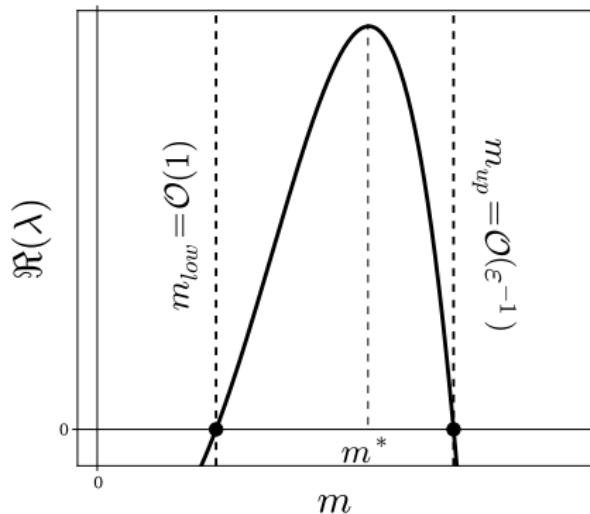
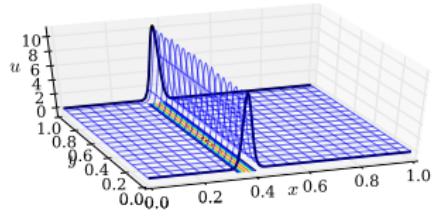
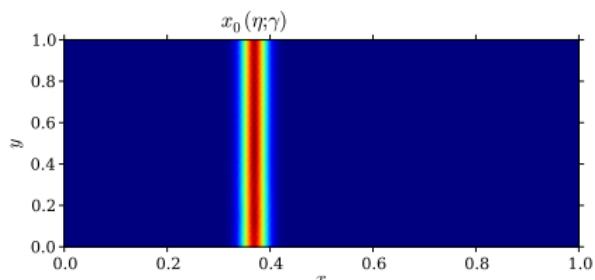
... joint work with A. Champneys, C. Grierson & M. Ward (2014).  
SIAM J. Appl. Dyn. Syst. 13(1), pp. 210–248.

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**Breakup instability**

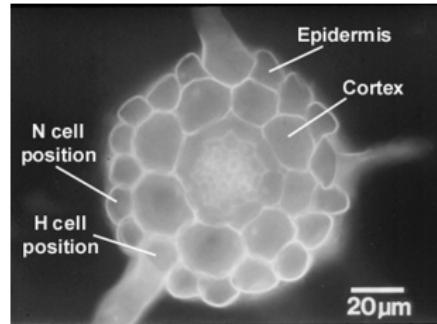
$$\mathcal{L}_0 \Phi_0 - \theta_h(\lambda; m) w^2 \frac{\int_{-\infty}^{\infty} w \Phi_0 \, d\xi}{\int_{-\infty}^{\infty} w^2 \, d\xi} = (\lambda + s \varepsilon^2 m^2) \Phi_0, \quad s = \left( \frac{L_x}{L_y} \right)^2.$$

... joint work with D. Avitabile, A. Champneys, & M. Ward (2015).  
SIAM J. Appl. Math. 75(3), pp. 1090–1119.



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C. Grierson & J. Schiefelbein, 2002

**Asymptotic setting**

Conservation principle

$$\int_{\Omega} U_0 \, d\Omega = \frac{d_y}{\beta\gamma}, \quad d_y \equiv \frac{L_y}{L_x}, \quad \beta\gamma = \frac{(c+r)rk_1}{k_{20}b^2},$$

$$\text{then } U = \varepsilon^{-2} U_j \quad \Rightarrow \quad \sum_{j=1}^N \int_{\mathbb{R}^2} U_j \, d\xi \sim \frac{d_y}{\beta\gamma}, \quad \xi = \varepsilon^{-1}(\mathbf{x} - \mathbf{x}_j).$$

### Asymptotic setting

## 👉 Conservation principle 👈

$$\int_{\Omega} U_0 \, d\Omega = \frac{d_y}{\beta\gamma}, \quad d_y \equiv \frac{L_y}{L_x}, \quad \beta\gamma = \frac{(c+r)rk_1}{k_{20}b^2},$$

then  $U = \varepsilon^{-2}U_j \Rightarrow \sum_{j=1}^N \int_{\mathbb{R}^2} U_j \, d\xi \sim \frac{d_y}{\beta\gamma}, \quad \xi = \varepsilon^{-1}(\mathbf{x} - \mathbf{x}_j).$

## 👉 Re-scaling 👈

$$U = \varepsilon^{-2}u, \quad V = \varepsilon^2v, \quad D = \varepsilon^{-2}D_0,$$

where  $\varepsilon^2 \equiv \frac{D_1}{L_x^2(c+r)}$  and  $D \equiv \frac{D_2}{L_x^2k_1}.$

## 👉 Asymptotic expansion 👈

$$u = \underbrace{u_{0j}(\rho)}_{\text{profile}} + \varepsilon \underbrace{u_{1j}(\rho)}_{\text{location}} \dots, \quad v = \underbrace{v_{0j}(\rho)}_{\text{profile}} + \varepsilon \underbrace{v_{1j}(\rho)}_{\text{location}} \dots.$$



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### Asymptotic setting

## 👉 Conservation principle 👈

$$\int_{\Omega} U_0 \, d\Omega = \frac{d_y}{\beta\gamma}, \quad d_y \equiv \frac{L_y}{L_x}, \quad \beta\gamma = \frac{(c+r)rk_1}{k_{20}b^2},$$

then  $U = \varepsilon^{-2}U_j \Rightarrow \sum_{j=1}^N \int_{\mathbb{R}^2} U_j \, d\xi \sim \frac{d_y}{\beta\gamma}, \quad \xi = \varepsilon^{-1}(\mathbf{x} - \mathbf{x}_j).$

## 👉 Re-scaling 👈

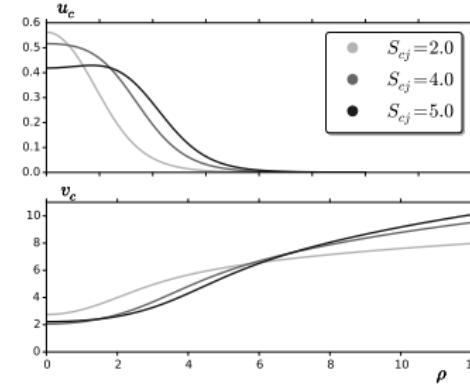
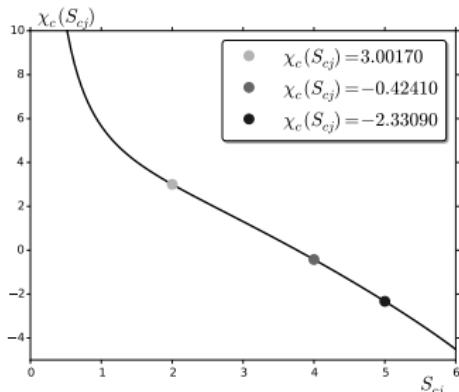
$$U = \varepsilon^{-2}u, \quad V = \varepsilon^2v, \quad D = \varepsilon^{-2}D_0,$$

$$\text{where } \varepsilon^2 \equiv \frac{D_1}{L_x^2(c+r)} \text{ and } D \equiv \frac{D_2}{L_x^2 k_1}.$$

## 👉 Canonical core problem 👈

$$\Delta_\rho u_c + u_c^2 v_c - u_c = 0, \quad \Delta_\rho v_c - \frac{\tau}{\beta} (u_c^2 v_c - u_c) - u_c = 0, \quad \rho = |\xi|,$$

$$u_c \rightarrow 0, \quad v_c \sim S_{cj} \log \rho + \chi_c(S_{cj}), \\ \rho \rightarrow \infty.$$

**Source parameter and auxin**

$$u_{0j} \equiv \sqrt{\frac{D_0}{\beta \gamma \alpha(\mathbf{x}_j)}} u_c, \quad v_{0j} \equiv \sqrt{\frac{\beta \gamma}{D_0 \alpha(\mathbf{x}_j)}} v_c, \quad S_j \equiv \sqrt{\frac{\beta \gamma}{D_0 \alpha(\mathbf{x}_j)}} S_{cj}.$$

👉  $S_j = \frac{\beta \gamma}{D_0} \int_0^\infty \left[ \frac{\tau}{\beta} (\alpha(\mathbf{x}_j) u_{0j}^2 v_{0j} - u_{0j}) + u_{0j} \right] \rho d\rho.$  👕

$$\frac{\tau}{\beta} = \frac{c+r}{r}.$$

**Auxin gradient and shape****Proposition**

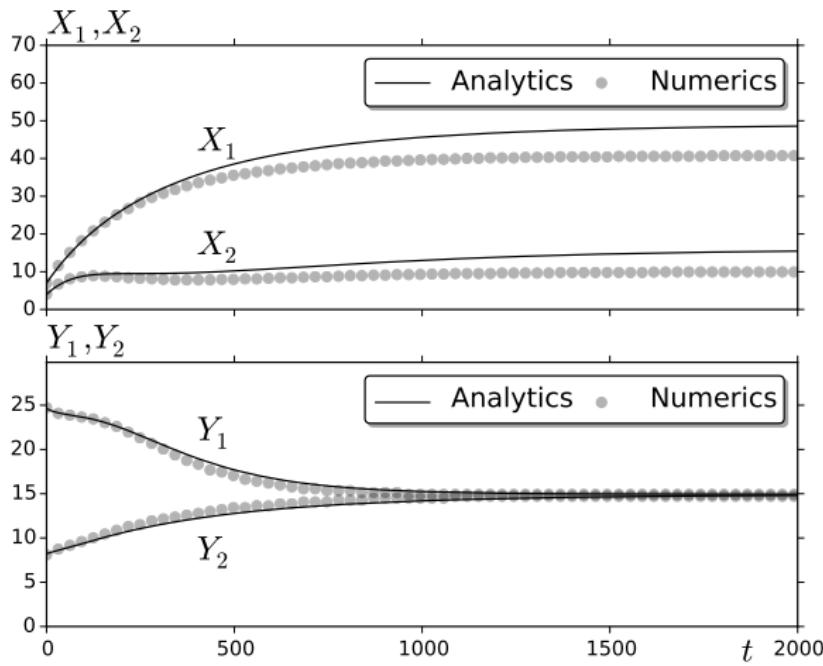
Let be  $\varepsilon \ll 1$ ,  $U = \mathcal{O}(\varepsilon^{-2})$ ,  $V = \mathcal{O}(\varepsilon)$ ,  $D = \mathcal{O}(\varepsilon^{-2})$  and stable  $N$ -spot quasi steady-state solution on an  $\mathcal{O}(1)$  time-scale, the slow dynamics on the long time-scale  $\eta = \varepsilon^2 t$  of this quasi steady-state spot pattern consists of the ODEs

$$\text{→ } \frac{d\mathbf{x}_j}{d\eta} = n_1 \Psi_j + n_2 \frac{\nabla \alpha(\mathbf{x}_j)}{\alpha(\mathbf{x}_j)}, \quad \text{→ } j = 1, \dots, N,$$

where  $n_1$  y  $n_2$  satisfy a nonlinear algebraic system and depend on  $S_{cj}$  and the ratio  $\tau/\beta$ , and the interaction vector is defined by

$$\Psi_j = -2\pi \left( S_{cj} \nabla_{\mathbf{x}} R_j + \sum_{i \neq j}^N S_{ci} \nabla_{\mathbf{x}} G_{ji} \right),$$

where  $R_j = R(\mathbf{x}_j, \mathbf{x}_j)$  and  $G_{ji} = G(\mathbf{x}_j, \mathbf{x}_i)$ .



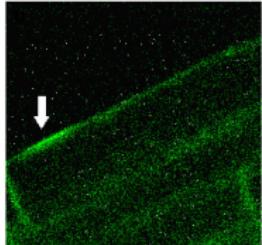
... joint work with D. Avitabile & M. Ward (in review);  
[arXiv:1703.02608](https://arxiv.org/abs/1703.02608) and [bioRxiv:114876](https://www.biorxiv.com/content/early/2017/03/27/114876).



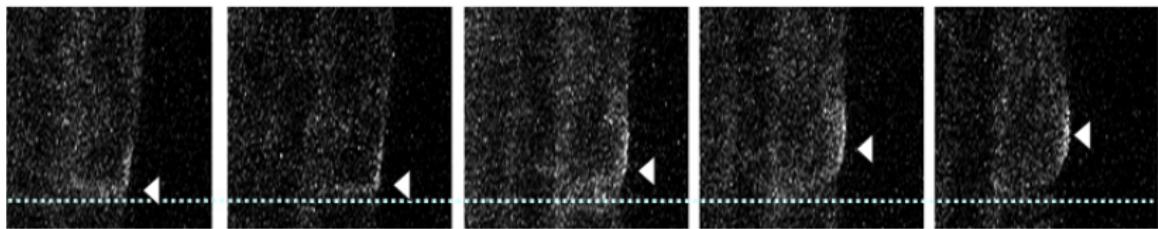
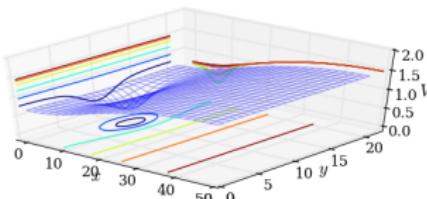
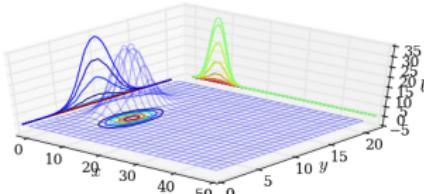
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**Key ROP features**



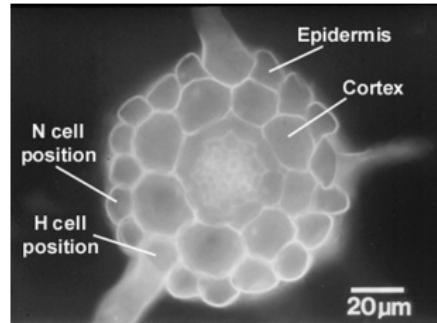
R. Payne & C.  
Grierson, 2009



C. Gierson

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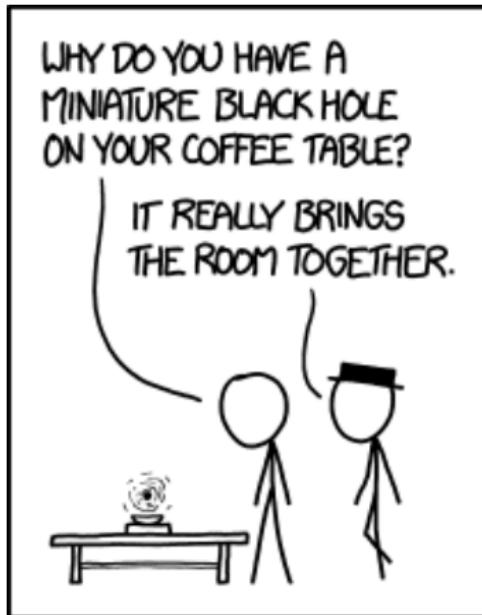
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C. Grierson & J. Schiefelbein, 2002

☞ **Turing bifurcation determines the onset of localised steady-states.**

- ☞ Inverse relationship between the auxin and longitudinal length controls over-crowding instability and give rise to **hysteresis**.
- ☞ ROPs tend to form a **maximal entropy configuration**.
- ☞ Activated ROPs location is directly controlled by auxin gradient and **physical features**.
- ☞ Under-crowding (peanut-splitting) instability is induced as a threshold is overpassed by source parameter  
 $S_c = S_c(k_{20}\alpha(\mathbf{X}_j), L_x)$ ; not shown.
- ☞ More realistic transport processes (hyperbolic diffusion or anomalous diffusion) for auxin or/and ROPs; dynamics upon considering **torsion** and **transversal curvature**; multi-scale interactions between a set of RH cells, non-RH cells and auxin... (R. Plaza, D. Hernández, M. Ward).



“It also brings all the boys, and everything else, to the yard.”  
Randall Munroe

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