Hierarchical Stochastic Partial Differential Equations for Bayesian Inverse Problems

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Hierarchical models

Results presented are in:

- Lassi Roininen, Mark Girolami, Sari Lasanen and Markku Markkanen, Hyperpriors for Matérn fields with applications in Bayesian inversion, ArXiv 2016
- Karla Monterrubio-Gómez, Lassi Roininen, Sara Wade, Theo Damoulas and Mark Girolami, Posterior Inference for Sparse Hierarchical Non-stationary Models, ArXiv 2018

These studies are closely linked to eg:

- Finn Lindgren, Håvard Rue and Johan Lindström, An explicit link between Gaussian fields and Gaussian Markov random fields: the stochastic partial differential equation approach, J. R. Statist. Soc. B 2011
- Matt Dunlop, Mark Girolami, Andrew Stuart and Aretha Teckentrup, How deep are deep Gaussian processes?, ArXiv 2017

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Plate diagram for a non-stationary hierarchical model

3-level GP model



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Image: A matrix and a matrix

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Hierarchical model

• Hierarchical formulation for a spatial interpolation problem

$$y_{i} \sim \mathcal{N}(z(x_{i}), \sigma_{\varepsilon}^{2}), \quad i = 1, \dots, m,$$

$$z(\cdot) \sim \mathcal{GP}\left(0, C_{\phi}^{\mathsf{NS}}(\cdot, \cdot)\right),$$

$$u(\cdot) := \log \ell(\cdot) \sim \mathcal{GP}\left(0, C_{\varphi}^{\mathsf{S}}(\cdot, \cdot)\right),$$

$$(\tau^{2}, \varphi, \sigma_{\varepsilon}^{2}) \sim \pi(\tau^{2})\pi(\varphi)\pi(\sigma_{\varepsilon}^{2}),$$
(1)

• Performing inference under this model amounts to exploring the posterior

 $\pi(\mathbf{z}, \mathbf{u}, \tau^2, \varphi, \sigma_{\varepsilon}^2 \mid \mathbf{y}) \propto \mathcal{N}(\mathbf{y} \mid \mathbf{z}, \sigma_{\varepsilon}^2 I_m) \mathcal{N}(\mathbf{z} \mid 0, C_{\phi}^{\mathsf{NS}}) \mathcal{N}(\mathbf{u} \mid 0, C_{\phi}^{\mathsf{S}}) \pi(\tau^2) \pi(\varphi) \pi(\sigma_{\varepsilon}^2)$

ullet . . . and using sparse presentations – and fixing τ^2

$$\pi(\mathbf{z}, \mathbf{u}, \lambda, \sigma_{\varepsilon}^{2} \mid \mathbf{y}) \propto \mathcal{N}(\mathbf{y} \mid A\mathbf{z}, \sigma_{\varepsilon}^{2} I_{m}) \mathcal{N}(\mathbf{z} \mid 0, Q_{\mathbf{u}}^{-1}) \mathcal{N}(\mathbf{u} \mid 0, Q_{\lambda}^{-1}) \pi(\lambda) \pi(\sigma_{\varepsilon}^{2}).$$

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Prior: Gaussian Markov random fields

• Matérn fields are often defined as stationary Gaussian random field with a covariance function

$$\operatorname{Cov}(x,x') = \operatorname{Cov}(x-x') = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\frac{|x-x'|}{\ell}\right)^{\nu} K_{\nu}\left(\frac{|x-x'|}{\ell}\right)$$
(2)

where $x, x' \in \mathbb{R}^d$, $\nu > 0$ is the smoothness parameter, and K_{ν} is modified Bessel function of the second kind or order ν .

• The Fourier transform of the covariance function gives a power spectrum

$$\mathcal{S}(\xi) = rac{2^d \pi^{d/2} \Gamma(
u + d/2)}{\Gamma(
u) \ell^{2
u}} \left(rac{1}{\ell^2} + |\xi|^2
ight)^{-(
u+d/2)}$$

 Rozanov 1977: only fields with spectral density given by the reciprocal of a polynomial have a Markov representation.

Prior: Stochastic Partial Differential Equation

- Let w be white noise. We may define the basic Matérn field z via $\hat{z} = \sigma \sqrt{S(\xi)} \hat{w}$ in the sense of distributions.
- By using inverse Fourier transforms, write SPDE

$$\left(1-\ell^2\Delta\right)z=\sigma\sqrt{\ell^d}w.$$

The field z is isotropic.

• Inhomogeneous field by allowing a spatially variable length-scaling field $\ell(x)$

$$(1-\ell(x)^2\Delta) z = \sigma\sqrt{\ell(x)^d}w.$$

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Convergence of the discretised prior $h \rightarrow 0$

Theorem

Let z(x; u) satisfy

$$\left(1-\ell(x;u)^2\Delta\right)z=\sigma_0\sqrt{\ell(x;u)^d}w$$
 in D

with the periodic boundary condition where $\ell(x;u) = g(u(x))$ and

$$g(s) = \exp(s)$$

Let $z^N(x; u^N)$ satisfy

$$\left(1-\ell(x;u^N)^2\Delta_N\right)z^N(x;u^N)=\sigma_0\sqrt{\ell(x;u^N)^d}w^N,$$

on $h\mathbb{Z}^d \cap D$, with the periodic boundary. Then $z^N(\cdot; u^N)$ converges to z in $L^2(L^2(D_h), P)$ as $N \to \infty$. (3)

Hyperprior field & parameters and normalisation constants

- Hyperprior fields
 - Matérn covariance
 - Exponential covariance
 - Squared exponential covariance
 - Cauchy walk
- Parameters
 - $\log \sigma_{arepsilon}^2 \sim \mathcal{N}(\cdot, \cdot)$ observation moise
 - $\log\lambda \sim \mathcal{N}(\cdot, \cdot)$ hyperprior length-scaling
- Normalisation constants
 - $\log \det \sigma_{\varepsilon}^2 I \mathsf{Easy}$
 - log det $Q_{\mathbf{u}}^{-1}$ Utilise sparsity of $Q_{\mathbf{u}}$
 - log det Q_{λ}^{-1} Easy for 1D exponential covariance, difficult generally in \mathbf{R}^d

Three MCMC sampling approaches

Implemented:

- Adaptive Metropolis-within-Gibbs MwG: draws samples from the multidimensional vector *u*
- Whitened Elliptical Slice Sampling w-ELL-SS: ancillary augmentation over *z* and *u* and uses elliptical slice sampling
- Marginal Elliptical Slice Sampling m-ELL-SS: integrates out the non-stationary process, resulting in a marginal sampler that draws from u by combining ancillary augmentation and ELL-SS to break the correlation between u and λ .
- Under development:
 - Variational Bayes (due to be submitted by 30 April)

AR(1) hyperpior with the MwG algorithm



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SE hyperpior with the MwG algorithm



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SE hyperpior model with m-ELL-SS algorithm



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AR(1) hyperpior with MWG, w-ELL-SS and m-ELL-SS



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MwG for 2D interpolation



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Non-Gaussian models - Cauchy priors

- Markku Markkanen, Lassi Roininen, Janne M J Huttunen and Sari Lasanen, Cauchy difference priors for edge-preserving Bayesian inversion with an application to X-ray tomography, ArXiv 2016.
- Alberto Mendoza, Lassi Roininen, Mark Girolami, Jere Heikkinen, and Heikki Haario, Statistical methods to enable practical on-site tomographic imaging of whole-core samples, SPWLA 2018.

Stable random walks

Let {X(t), t ∈ I ⊂ ℝ⁺} be a stochastic process. We call it a Lévy α-stable process starting from zero, or simply as stable process, if X(0) = 0, X has independent increments and

$$\mathcal{X}(t) - \mathcal{X}(s) \sim S_{\alpha}\left((t-s)^{1/\alpha}, \beta, 0\right)$$
 (4)

for any $0 \le s < t < \infty$ and for some $0 < \alpha \le 2, -1 \le \beta \le 1$.

• For the continuous limit of the Cauchy walk, we apply independently scattered measures. We obtain random walk approximation

$$X_{t_i} - X_{t_{i-1}} \sim S_{\alpha}(h^{\frac{1}{\alpha}}, \beta, 0)$$

where $t_i - t_{i-1} =: h$. It is easy to see that such random walk approximations converge to the α -stable Lévy motion as $h \to 0$ in distribution on the Skorokhod space of functions that are right-continuous and have left limits.

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Cauchy and Gaussian random walk realisations



Figure 1. Realizations of Cauchy and Gaussian random walks.

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2D Cauchy vs Gaussian priors

$$egin{aligned} X_{j,k} - X_{j-1,k} &\sim ext{Cauchy}(\lambda h_1) \ X_{j,k} - X_{j,k-1} &\sim ext{Cauchy}(\lambda h_2) \end{aligned}$$



$$egin{aligned} X_{j,k} - X_{j-1,k} &\sim \mathcal{N}(0,\sigma^2h_1/h_2) \ X_{j,k} - X_{j,k-1} &\sim \mathcal{N}(0,\sigma^2h_2/h_1) \end{aligned}$$



(a) Realisation of 2D Cauchy field

(b) Realisation of 2D Gaussian field

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Tomographic imaging of whole-core samples

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Sandstone 3D tomography with 10% noise



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Conclusion

- 2–4 layer spatially scalable hierarchical models that can be efficiently handled fully probabilistically.
- Gaussian and non-Gaussian iid random fields.
- This leads to computational advantages and clear statistical interpretation of all the random fields and parameters.

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