

Policy-Switching Schemes for Power System Protection

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- 1 Motivation
- 2 Background
 - Remedial Action Schemes
 - Automated Planning
- 3 Methodology
 - Policy Switching
 - Implementation
 - Test Case Overview
- 4 Results
 - Case Study
 - Key Takeaways
 - Current & Future Work

Motivation for Automated Contingency Mitigation

- 1 Continued widespread outages that require effective cascading restraint.
- 2 Non-uniform implementation of remedial action schemes (RASs) (SPSs).
- 3 Increased variability in generation (renewables).
- 4 Greater network congestion.
- 5 Malicious attacks (cyber or physical).
- 6 Higher penetration of distributed energy resources (DERs) (energy storage & small-scale distributed generation).



Load Shedding (LS)

CHARACTERISTICS

- Naive and Homogenous:
 - Affects all loads in the network.
 - Usually triggered by under-voltage conditions.
- Adaptive and Dynamic:
 - Ability to select loads based on a rule. (priority, severity, electrical distance, etc.)
 - Usually triggered by multiple conditions (UV, UF, $\frac{dV}{dt}$, $\frac{dF}{dt}$).

LS BENEFITS

- Direct manipulation of generation/load mismatch.
- Can be done in real-time.

LS CHALLENGES

- Direct customer impact.
- Must be done incrementally.

Islanding

CHARACTERISTICS

- Intentional creation of microgrids.
- Typically pre-determined based on common contingencies.
- Usually done based on slow-coherency, electrical distance, active/reactive power balance.

BENEFITS

- Can isolate operational sections from affected sections.
- Can fully utilize DER capability to decrease impact on customers.

CHALLENGES

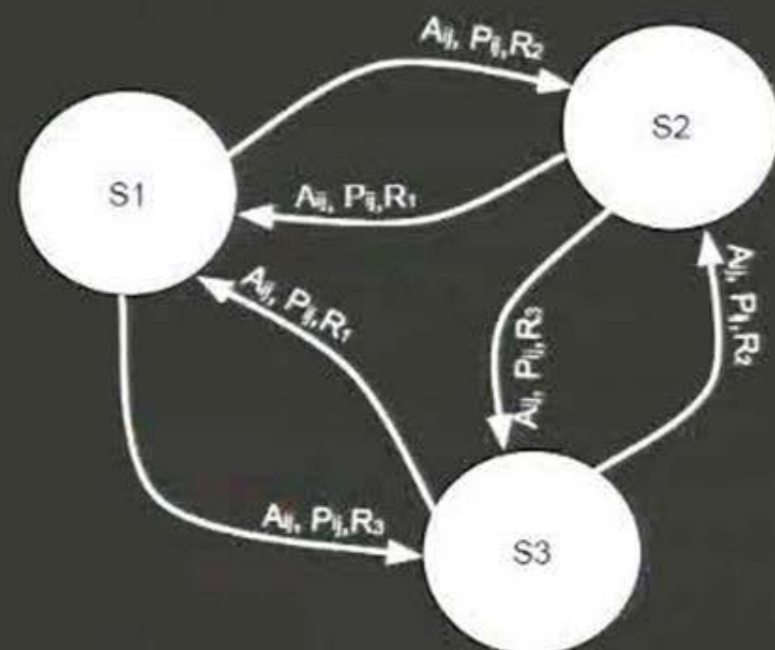
- Slow calculation – usually done offline.
- Can cause portions of the grid to fully collapse.

Markov Decision Processes (MDP)

MDPs provide well-developed theory for computational solutions to controllable and observable systems with stochastic dynamics.

MDP COMPONENTS

- System States (S):
Time Independent
- Control Actions (A):
Stationary or Non-Stationary
- Probabilistic Transition Distributions (P):
Stochastic Movement Between States
- Rewards (R):
Function of Current State



Solutions to MDPs

What is the solution to an MDP?

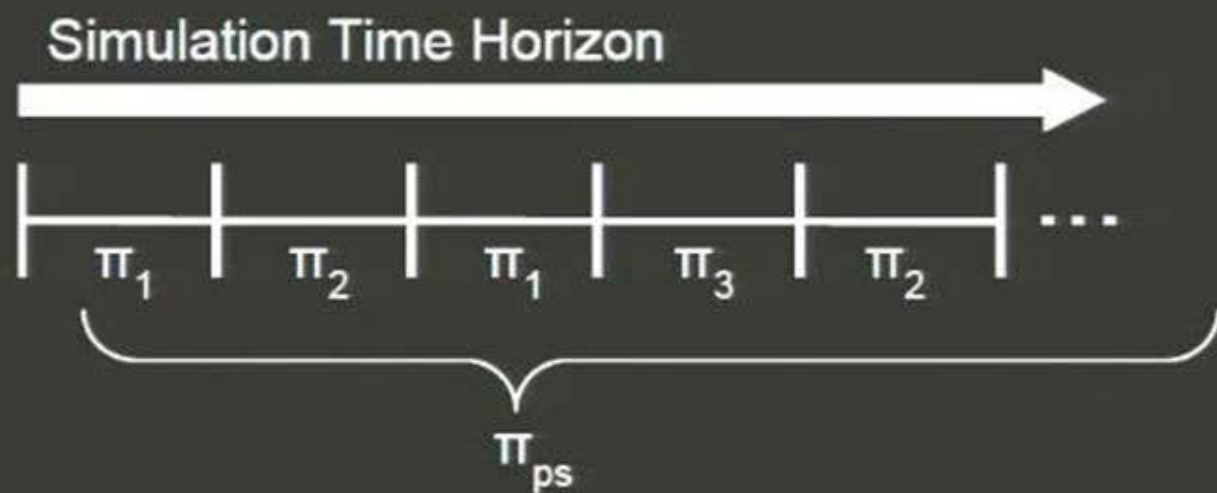
Policy (π) = A mapping of States (s) to Actions (a).

Optimal Policy (π^*) = Policy with max *Value* (V) in any given state (s).

Value:

$$V^\pi(s) = E \left[\sum_{t=0}^{\infty} \beta^t R(s_t) \right]$$

Policy Switching



Formally:

$$\pi_{ps}(s) = \pi_{i^*}(s)$$

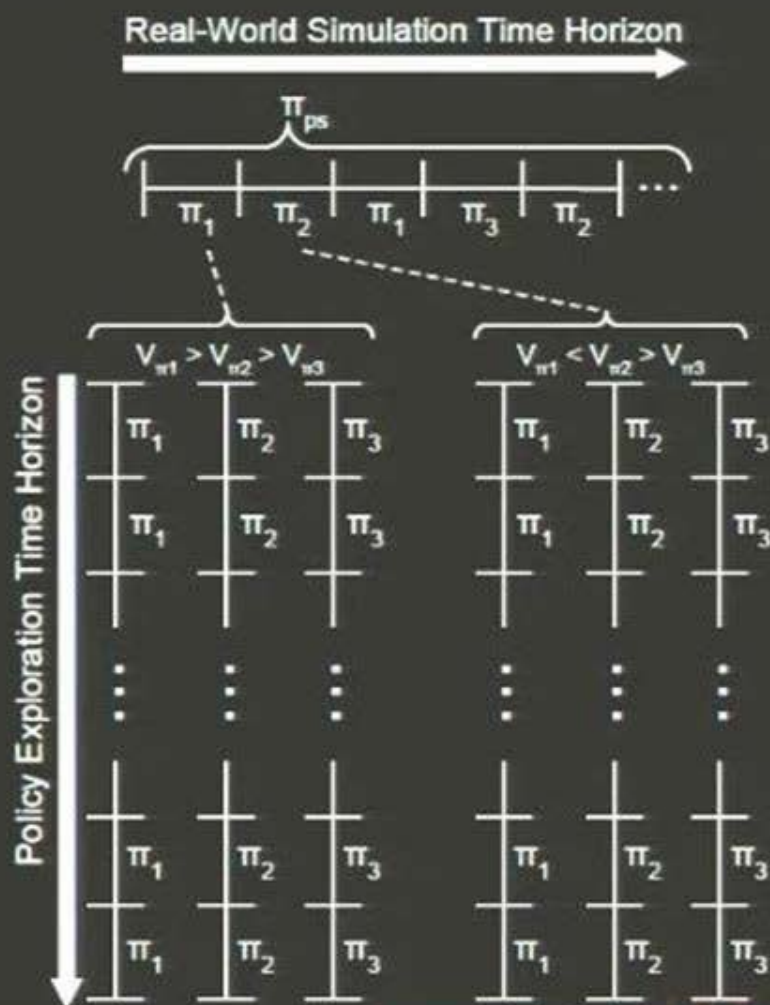
$$i^* = \arg \max_i V_{\pi_i}(s)$$

Policy Switching:

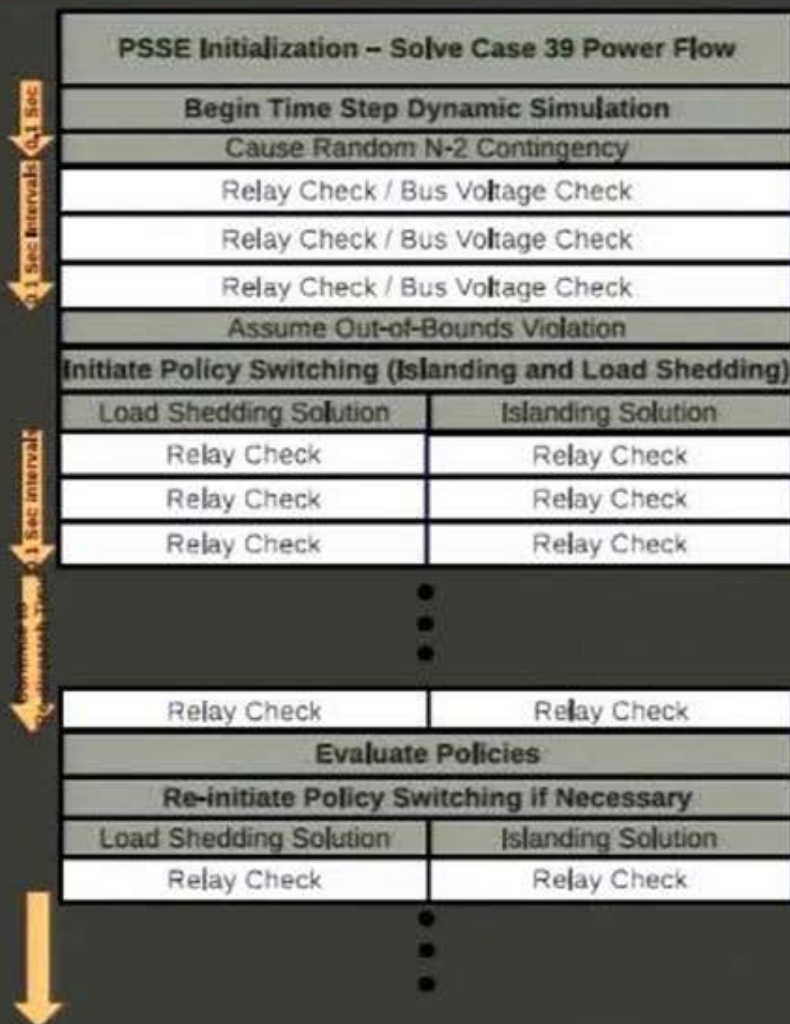
Basic guarantee that

$$V(\pi_{ps}) \geq \max_i V(\pi_i)$$

Policy Switching

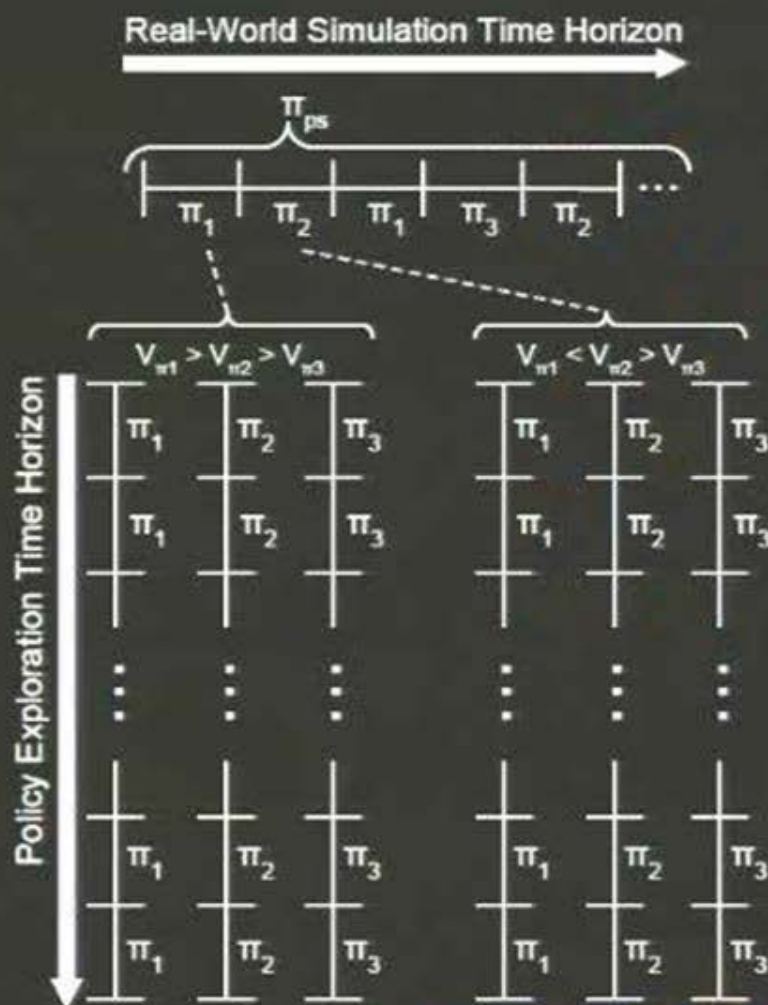


Implementation

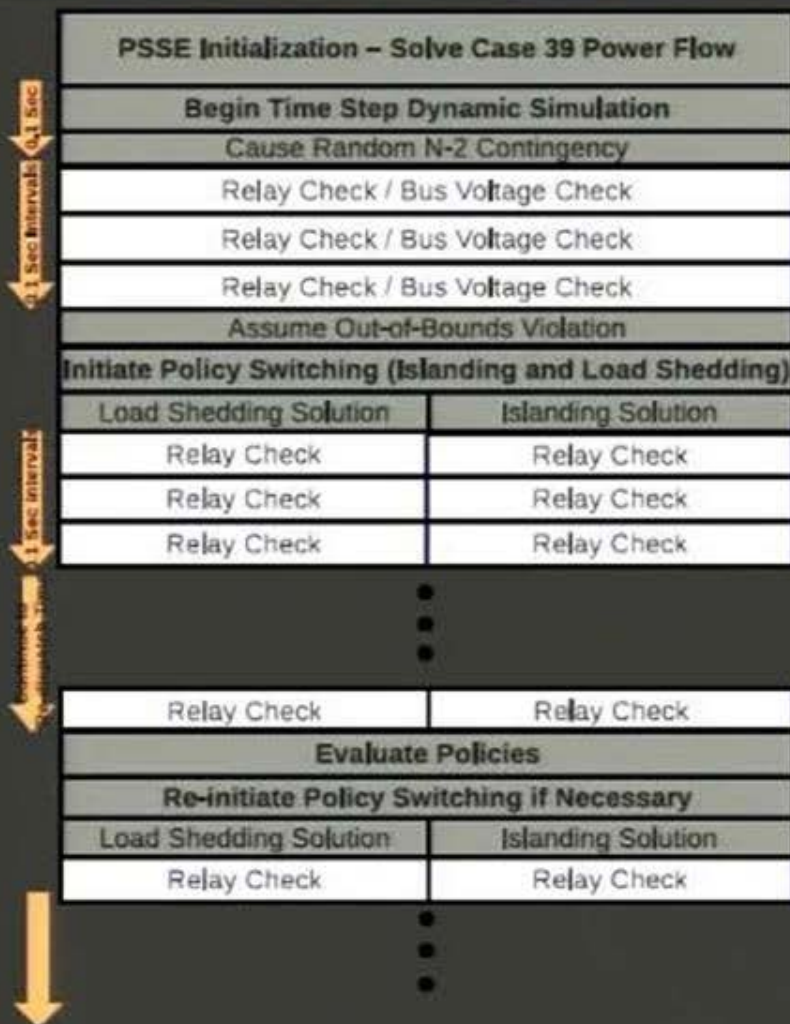


- 1 Python/Siemens PSSe
- 2 Time-Domain Simulation
- 3 3 Different Timescales
 - 1 $\frac{1}{120}$ s – PSSe step
 - 2 $\frac{1}{10}$ s – Grid check
 - 3 5 s – Emgcy. dispatch
- 4 Random N-2 Contingencies
- 5 Parallelization

Policy Switching

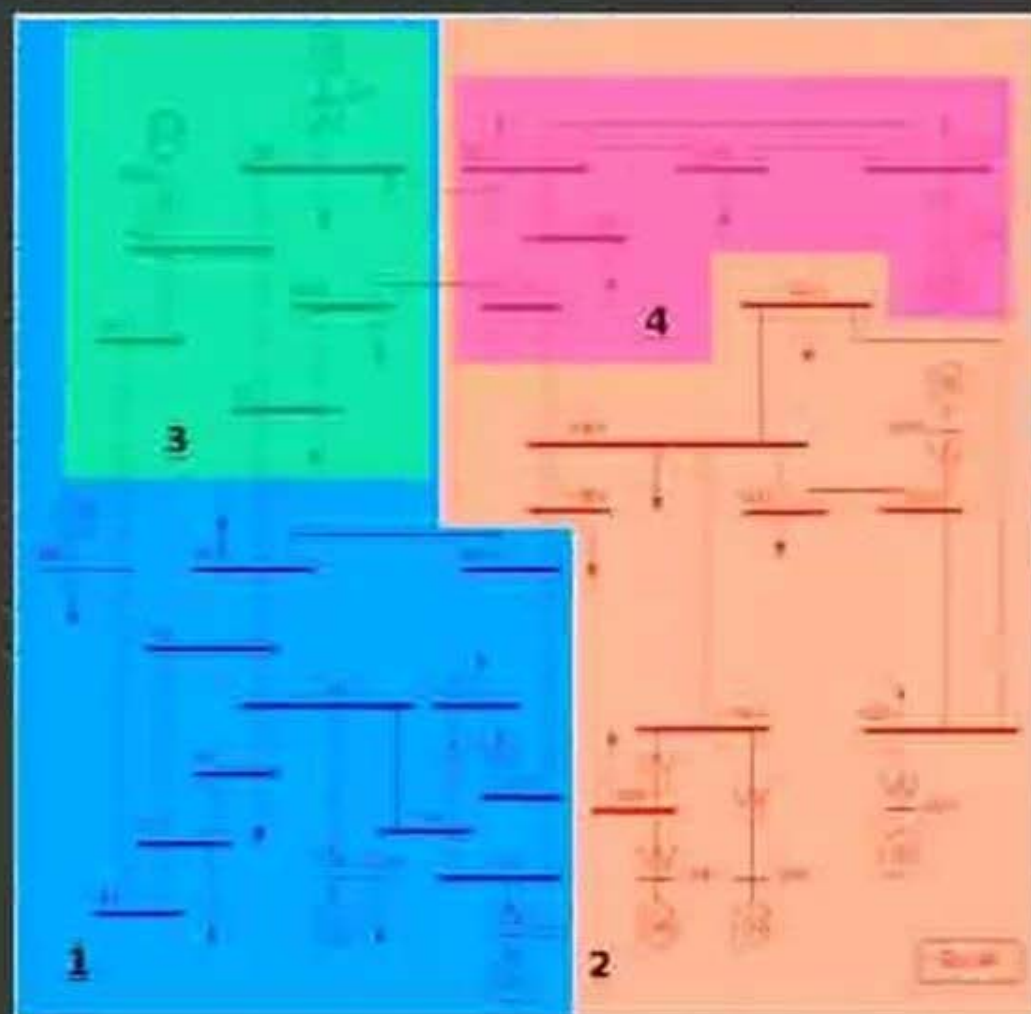


Implementation



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Test Case Overview



- Case Topology
 - 39 Buses
 - 10 Generators
 - 19 Loads
 - 46 Branches

- N-1 Secure
 - Flow Limits
 - Governor Dynamics
 - Exciter Dynamics

Case Study [19-20 and 2-25]

Policy Available (II):	Islanding (I)		Load Shedding (LS)		Islanding and Load Shedding				
FIRST POLICY	I	LS	I	LS	I	LS	LS	LS	LS
Operational Load (L) [MVA]	4759	5224	4759	4759	4759	5224	5224	5224	5224
System Saved (I)	NO	NO	NO	NO	NO	NO	NO	NO	NO
Reward* (V^*)	(0.366)	(0.401)	(0.366)	(0.366)	(0.366)	(0.401)	(0.401)	(0.401)	(0.401)
# Buses Lost	7	3	7	7	7	3	3	3	3
# Generators Lost	2	2	2	2	2	2	2	2	2
# Full Loads Lost	4	1	4	4	4	1	1	1	1
# Transmission Lines Lost	13	5	13	13	13	6	6	6	6
SECOND POLICY	I	LS	I	LS	LS	LS	I	I	
Operational Load (L) [MVA]	3848	2922	3848	4283	4283	2922	1749	1749	
System Saved (I)	NO	YES	NO	YES	YES	YES	YES	YES	
Reward* (V^*)	(0.296)	(0.725)	(0.296)	(0.829)	(0.829)	(0.725)	(0.865)	(0.865)	
# Buses Lost	14	21	14	7	7	21	5	5	
# Generators Lost	3	5	3	2	2	5	2	2	
# Full Loads Lost	8	9	8	4	4	9	3	3	
# Transmission Lines Lost	21	27	21	13	13	27	9	9	
THIRD POLICY	I	LS**	LS	I	LS**	I	LS**	I	
Operational Load (L) [MVA]	-	-	4453	-	-	-	-	-	
System Saved (I)	-	-	YES	-	-	-	-	-	
Reward* (V^*)	-	-	(0.766)	-	-	-	-	-	
# Buses Lost	-	-	14	-	-	-	-	-	
# Generators Lost	-	-	3	-	-	-	-	-	
# Full Loads Lost	-	-	8	-	-	-	-	-	
# Transmission Lines Lost	-	-	21	-	-	-	-	-	

* Reward calculated based on $V_{max} = 8333$ [MVA]

*No time islanding policy available - Case too small

**Not needed - all service buses within acceptable operating range

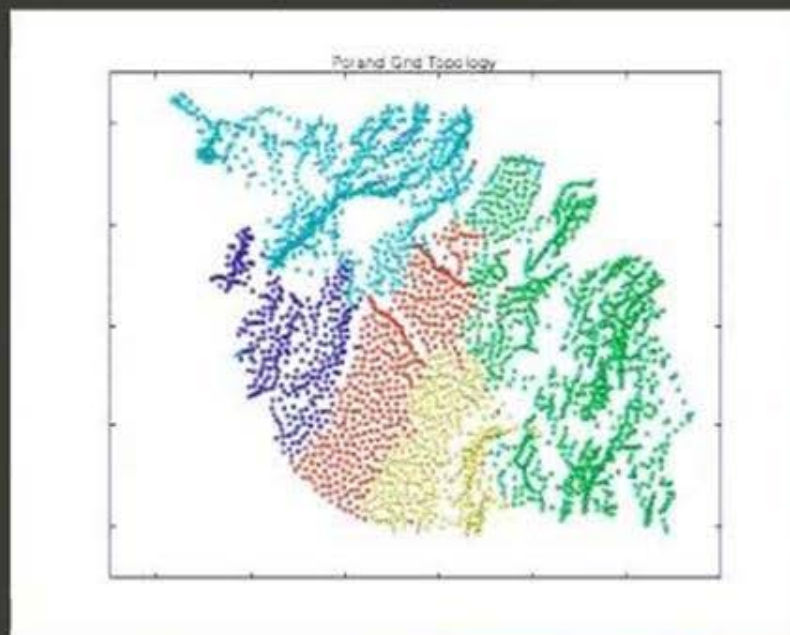
Key Takeaways

- Introduced Policy Switching in the context of Power Systems.
- Quantitative analysis of our methodology – case study on IEEE-39.
- Basic enumeration of each policy's performance.

Experiment	Policies Available (Π)	V^* [s]	Operational Load [MVA]
1	I	0.296	3848
2	LS	0.725	2922
3	I & LS	0.865	4749

Current Work

- Implement on larger grid and with several policies in order to assess scalability.
 - Polish Grid (2383 Bus Winter Peak Model).
 - Improve automation of policy evaluation.
 - Scalability and computation time on different resources: computer, server, supercomputer, etc.



Moving Forward

- Expand Action-space.
- Test with different percentages of variable renewable generation.
- Re-evaluate Reward Scheme
- Compare Results using different simulators.
- Compare Results against various AI schemes.

THANK YOU

QUESTIONS?

