



#### BAYESIAN MODEL SELECTION, CALIBRATION AND UNCERTAINTY QUANTIFICATION OF THERMODYNAMIC PROPERTIES

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## MOTIVATION



#### **BACKGROUND BAYESIAN STATISTICS**

- Bayesian statistics provides a framework for model selection, calibration and UQ
- for some model, *M*, Bayes' theorem states:

posterior parameter distribution	data Likelihood	prior parameter distribution
$\Pr(\boldsymbol{\theta} \mathbf{D}, M) =$	$\Pr(\mathbf{D} \boldsymbol{\theta}, M)$	$\Pr(\boldsymbol{\theta} M)$
	$\Pr(\mathbf{D} M)$	
	marginal Likelihood	

$$R = \frac{\Pr(M_A | \mathbf{D})}{\Pr(M_B | \mathbf{D})} = \frac{\Pr(\mathbf{D} | M_A) \Pr(M_A)}{\Pr(\mathbf{D} | M_B) \Pr(M_B)}$$

$$y = w_0 + xw_1$$

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posterior	data	prior
parameter	Likelihood	parameter
distribution		distribution
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Metropolis-Hastings Markov chain Monte Carlo



affine invariant ensemble sampler / kombine



MultiNest





#### **BAYESIAN FRAMEWORK FITTING A MODEL**

Polynomial Model: 
$$M(x, \Theta) = \sum_{i=0}^{N} \Theta_i * x^i$$

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Ex: 
$$C_p^{liq}(T) = c_1 + c_2 T$$

Priors:  $\begin{array}{l} \Pr\left(\Theta_{i}|M\right) = \mathcal{U}\left(\Theta_{i}|-2,2\right)\\ \Pr\left(\varepsilon|M\right) = \mathcal{U}\left(\varepsilon|0,1\right) \end{array}$ 

Likelihood:  $Pr(\mathbf{D}|\boldsymbol{\Theta},\varepsilon,M) = \prod \mathcal{N}(y_j|M(x_j,\boldsymbol{\Theta}),\varepsilon)$ 8 2.2 og marginal likelihood 6 Concernance Announcements of the Announcements of t 2.0 4 1.8  $\geq$ 2 1.6 0 synthetic data 1.4 1.4 kombine true model -2 1.2 prediction MultiNest 1.2 95% CI  $\theta^{\Gamma}$  1.0 0 1 2 3 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0 0.8 polynomial order х 0.6 0.15 0.10 ω 0.05

Paulson 2018



1.2

0.75 1.00 1.25

 $\theta_1$ 

0.0

0.1

ε

1.0

 $\theta_0$ 

0.00



#### **BAYESIAN FRAMEWORK SPECIALIZED METHODS**

Thermodynamic Consistency  $Pr\left(\mathbf{D}|\mathbf{\Theta}, M_{H}, M_{C_{p}}\right) = \prod_{i} \mathcal{N}\left(H_{i}|M_{H}\left(T_{i}, \mathbf{\Theta}\right), \varepsilon_{i}\right) \cdot \prod_{j} \mathcal{N}\left(C_{p_{j}}|M_{C_{p}}\left(T_{j}, \mathbf{\Theta}\right), \varepsilon_{j}\right)$ 

**Rescaling of Errors** 

 $Pr\left(\mathbf{D}|\mathbf{\Theta}, \alpha, M\right) = \prod_{i} \prod_{j} \mathcal{N}\left(y_{j}^{i} | M\left(x_{j}^{i}, \mathbf{\Theta}\right), \varepsilon_{j}^{i} / \alpha^{i}\right)$ 



#### BAYESIAN FRAMEWORK THERMODYNAMIC CONSISTENCY













## CASE STUDY HAFNIUM METAL

- experimental thermodynamic measurements of  $\alpha$ ,  $\beta$  and liquid phase Hf
- 20 total datasets obtained
  - 17 for  $\alpha$ , 9 for  $\beta$ , 10 for liquid
  - 14 for  $C_p$ , 6 for H, 0 for S, 0 for G
- data corrected for temperature scale, Zr content
- reported error bars converted to standard errors (GUM)



Goldberg 1992, GUM 1995, Arblaster 2013, Arblaster 2014, Paulson 2018



#### CASE STUDY MODEL SELECTION

Model	Log Marginal Likelihood	Bayes' Factor
α phase		
Einstein	-1744.2	~0
Debye	-1262.9	~0
Debye + Linear	-1072.6	~0
Debye + Quadratic	-813.2	~0
Debye + Cubic	-640.2	~0
Debye + Quartic	-623.1	1
Debye + Quintic	-627.4	$1.4 \times 10^{-2}$
Debye + SR	-629.7	$1.4 \times 10^{-3}$
β phase		
Constant	-534.2	~0
Linear	-511.1	$3.0 \times 10^{-3}$
Quadratic	-505.3	1
Cubic	-518.5	$1.9 \times 10^{-6}$
Liquid Phase		
Constant	-491.4	~0
Linear	-471.0	1
Quadratic	-476.0	$6.7 \times 10^{-3}$

$$C_p^{Deb}(T,\theta_D) = 9R\left(\frac{T}{\theta_D}\right)^3 \int_0^{\theta_D/T} \frac{x^4 e^x}{(e^x - 1)^2} dx$$

$$C_p^{\alpha}(T) = C_p^{Deb}(T, \theta_D) + a_2 T + a_3 T^2 + a_4 T^3 + a_5 T^4$$

$$H^{\alpha}(T) - H^{\alpha}(298.15\text{K}) = \int_{0}^{T} C_{p}^{Deb}(\tilde{T}, \theta_{D}) d\tilde{T}$$
$$+a_{2}\frac{T^{2}}{2} + a_{3}\frac{T^{3}}{3} + a_{4}\frac{T^{4}}{4} + a_{5}\frac{T^{5}}{5}$$

$$C_p^{\beta}(T) = b_1 + b_2 T + b_3 T^2$$
$$H^{\beta}(T) = b_0 + b_1 T + b_2 \frac{T^2}{2} + b_3 \frac{T^3}{3}$$

$$C_p^{liq}(T) = c_1 + c_2 T$$
$$H^{liq}(T) = c_0 + c_1 T + c_2 \frac{T^2}{2}$$

Roslyakova 2016, Paulson 2018



# CASE STUDY FINAL MODEL



Arblaster 2014, Paulson 2018

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## CASE STUDY FINAL MODEL

Investigate effect of removing individual datasets in Bayesian analysis:



Paulson 2018



# CONCLUSIONS

- Comprehensive framework for model selection, calibration and UQ for thermodynamic property models
- Intuitive modifications address common issues
  - ensuring thermodynamic consistency
  - automated weighting of data sets
- Framework demonstrated in construction of models for  $C_p$ , H, S and G of Hf metal for  $\alpha$ ,  $\beta$  and liquid phases



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## ABSTRACT

Models of the thermodynamic properties of materials form the basis for technological applications including the calculation of phase diagrams and simulation of microstructure evolution during processing – both of which play an important role in the design of materials for improved performance. Currently, the weighting of datasets, removal of outliers and the selection of model forms rely on expert judgements and do not provide uncertainty intervals. In this work we present a Bayesian framework for the selection, calibration and uncertainty quantification of thermodynamic property models. The framework is enabled by recent advances in numerical sampling methods. In addition, we present intuitive modifications that automatically weight datasets, improve robustness of outlier treatments, and ensure consistency of thermodynamically related models. We demonstrate the power of the approach through the construction of models for the specific heat, enthalpy, entropy and Gibbs free energy of Hafnium metal for the alpha, beta and liquid phases at temperatures ranging between 0 and 4900K.



## BAYESIAN FRAMEWORK FITTING A MODEL





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1.0

prediction

95% CI

0.9

0.8

0.7

Х

0.6



1.2

0.3

0.4

0.5

#### **BAYESIAN FRAMEWORK ROBUSTNESS TO OUTLIERS**



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1.0

synthetic data true model

synthetic data true model

prediction 95% CI

0.9

1.0

prediction 95% CI

0.9

0.8

0.8

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#### **BAYESIAN FRAMEWORK DATA WEIGHTING**







#### BAYESIAN FRAMEWORK THERMODYNAMIC CONSISTENCY

Models:

$$C_p(T) = \frac{d}{dT}H(T) = 3R(\theta/T)^2 \frac{e^{\theta/T}}{(\theta/T-1)^2} + aT + bT^2$$

$$H(T) - H(298.15K) = \frac{3R\theta}{e^{\theta}/T - 1} + a\frac{T^2}{2} + b\frac{T^3}{3}$$

Priors:

 $Pr(\theta|M) = \mathcal{U}(\theta|145, 155) \quad Pr(a|M) = \mathcal{U}(a|0.003, 0.009) \quad Pr(b|M) = \mathcal{U}(b|-5 \cdot 10^{-6}, 5 \cdot 10^{-6})$ 

Likelihood: 
$$Pr\left(\mathbf{D}|\boldsymbol{\Theta}, M_{H}, M_{C_{p}}\right) = \prod_{i} \mathcal{N}\left(H_{i}|M_{H}\left(T_{i}, \boldsymbol{\Theta}\right), \varepsilon_{i}\right) \cdot \prod_{j} \mathcal{N}\left(C_{p_{j}}|M_{C_{p}}\left(T_{j}, \boldsymbol{\Theta}\right), \varepsilon_{j}\right)$$

Chen 2001



#### BAYESIAN FRAMEWORK THERMODYNAMIC CONSISTENCY







#### BAYESIAN FRAMEWORK THERMODYNAMIC CONSISTENCY





## CASE STUDY COMPUTATIONAL METHODOLOGY

#### Sampling:

pymultinest with 800 live points

#### Likelihood:

- Student's t-distribution for robustness to outliers
- hyperparameters to rescale reported errors
- simultaneous regression for H and  $C_p$

#### Prior Definition:

- Stage A: define broad uniform priors
- Stage B: narrow priors to 5-sigma Stage A – posterior

#### Model Selection:

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marginal Likelihood

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## CASE STUDY FINAL MODEL





Arblaster 2014, Paulson 2018





## **CASE STUDY FINAL MODEL**



Paulson 2018



# **GENERAL BAYESIAN REGRESSION**

- Analytic Bayesian methods are difficult for non-linear models and nonconjugate priors
- Markov chain Monte Carlo (MCMC) methods can accurately sample posterior
- Simplest algorithm: Metropolis-Hastings (M-H) (1953).

Propose random step in parameter space from  $z^{(\tau)}$  to  $z^*$  according to proposal distribution  $q_k(z|z^{(\tau)})$ 

$$\begin{split} & \text{If } A_k \big( \mathbf{z}^*, \mathbf{z}^{(\tau)} \big) > \text{U}[0, 1] \text{ then } \mathbf{z}^{(\tau+1)} = \mathbf{z}^*, \\ & \text{else } \mathbf{z}^{(\tau+1)} = \mathbf{z}^{(\tau)} \end{split} \quad A_k \big( \mathbf{z}^*, \mathbf{z}^{(\tau)} \big) = \frac{\widetilde{p}(\mathbf{z}^*)}{\widetilde{p}(\mathbf{z}^{(\tau)})} \end{split}$$

Interactive visualization: <u>https://chi-feng.github.io/mcmc-demo/app.html#RandomWalkMH,standard</u>



## MCMC IN PYTHON: EMCEE

- Python implementation of *Affine Invariant Ensemble Sampler* (Goodman, 2010).
- Affine Invariant: addresses inefficiencies in MCMC sampling of posteriors with large covariances
- Ensemble Sampler: large set of walkers simultaneously explore posterior
  - Positions of other walkers make proposal distribution





#### BACKGROUND LINEAR REGRESSION

Equation for linear model :

$$y(\mathbf{x}, \mathbf{w}) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})$$

*x*: feature vector of interest *w*: vector of weights controlling form of model  $\phi(x)$ : vector of basis functions, may include polynomial, harmonic, sigmoidal, Gaussian functions



#### LINEAR REGRESSION FREQUENTIST APPROACH

target variable:  $t = y(\mathbf{x}, \mathbf{w}) + \varepsilon$ 

likelihood function:  $p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{n=1}^{N} N(t_n | \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n), \beta^{-1})$ 

 $x_n, t_n$ : input vector, response for data point nt: vector of responses for all data points X: array of input vectors as follows;  $X \equiv [x_1 ... x_n ... x_N]$ 

maximum likelihood estimate:  $\mathbf{w}_{ML} = (\mathbf{\Phi}^T \mathbf{\Phi})^{-1} \mathbf{\Phi}^T$ 

$$\Phi: \text{ data matrix} \qquad \Phi = \begin{pmatrix} \phi_0(\mathbf{x}_1) & \cdots & \phi_{M-1}(\mathbf{x}_1) \\ \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}_N) & \cdots & \phi_{M-1}(\mathbf{x}_N) \end{pmatrix}$$

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