

SIAM Annual Meeting 2017

# Chaos and learning in spiking neural networks

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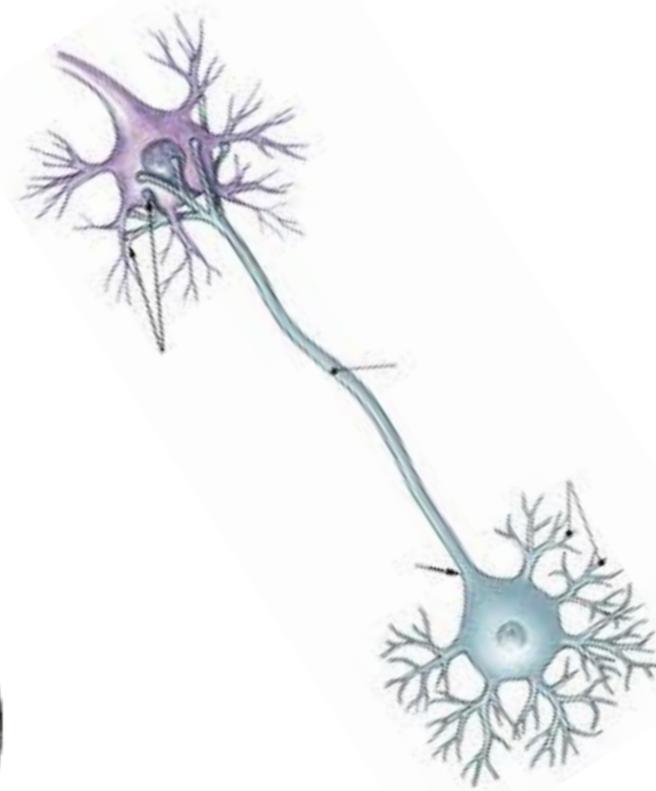
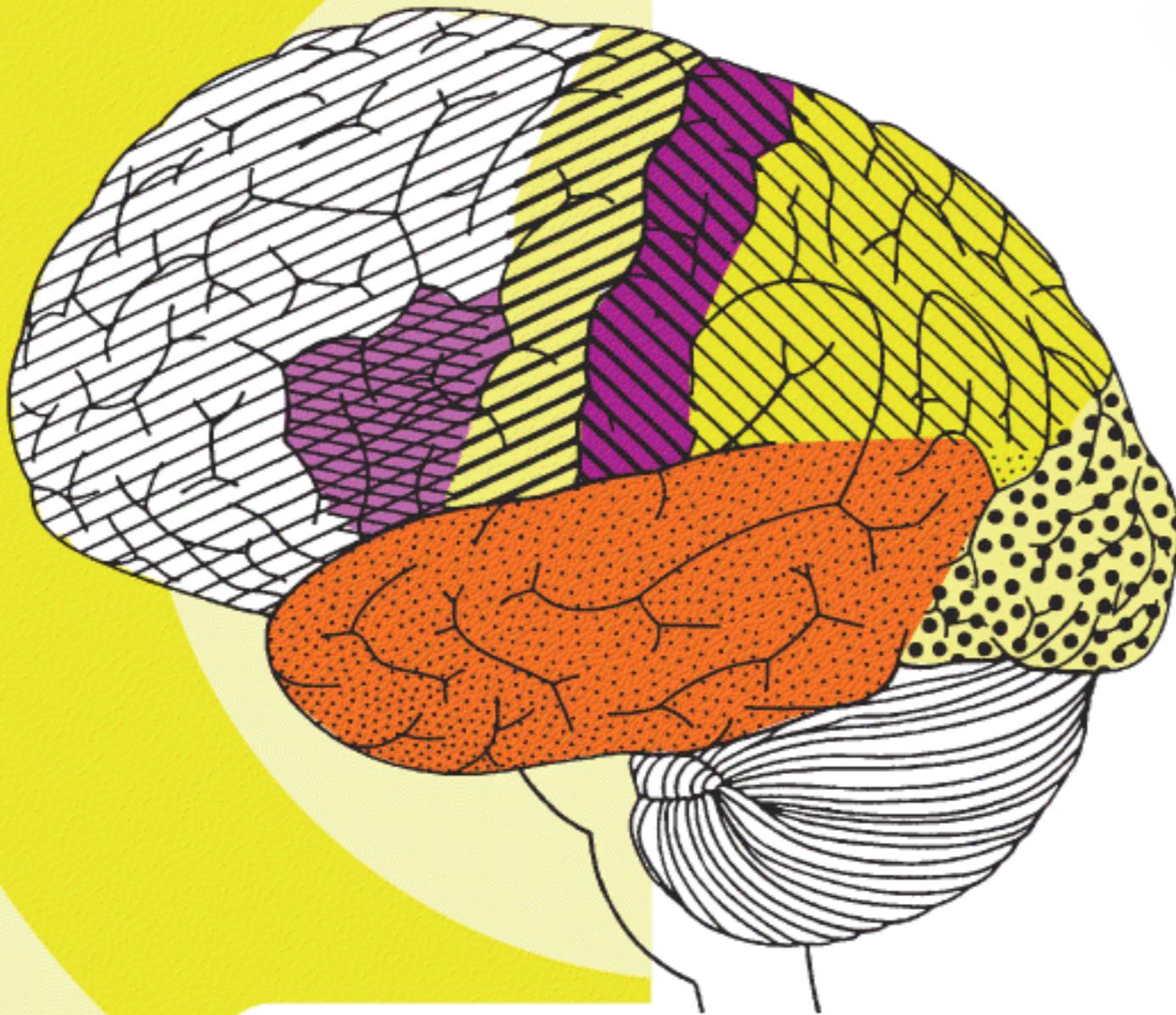


National Institute of  
Diabetes and Digestive  
and Kidney Diseases

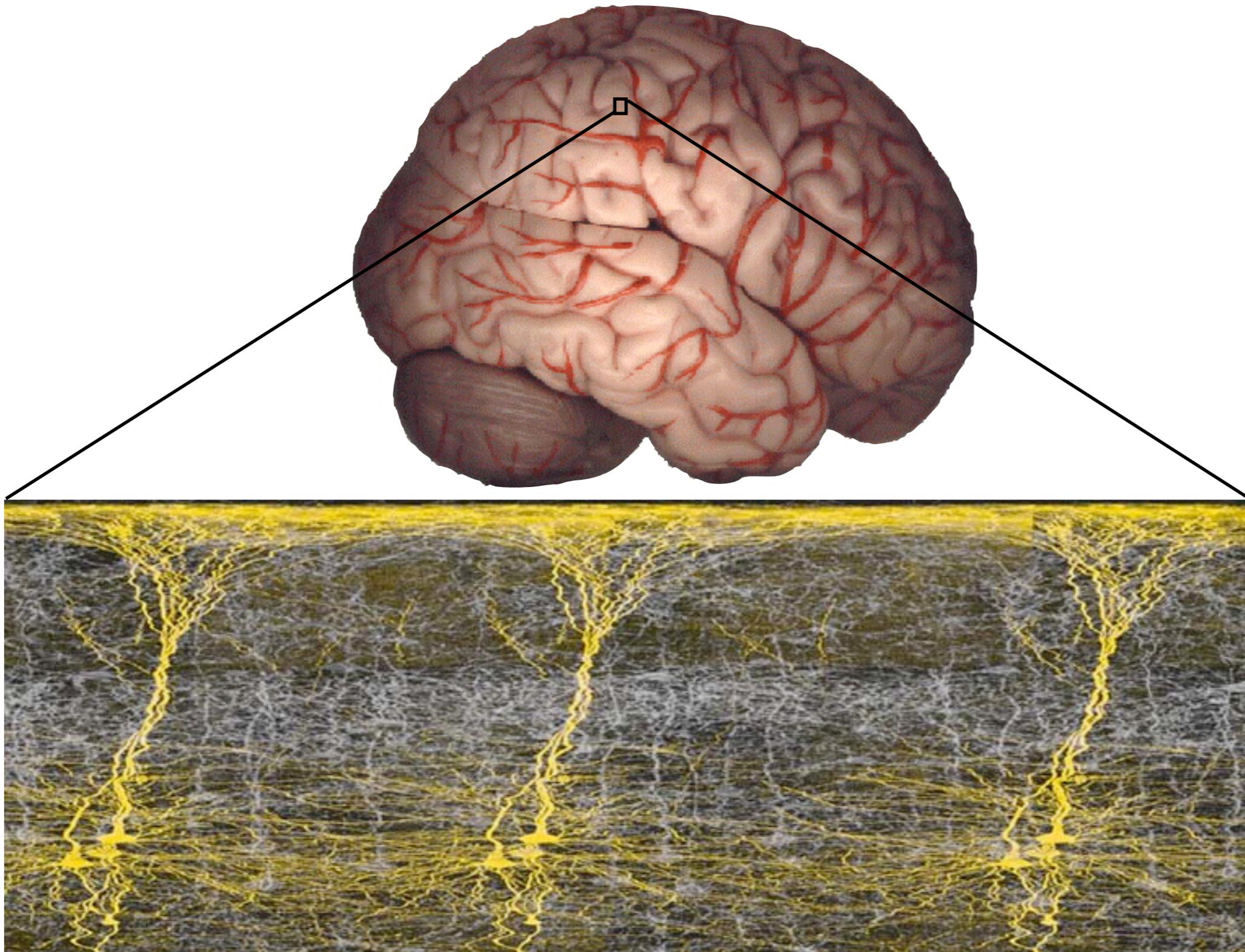


How does brain give rise to complex behavior?

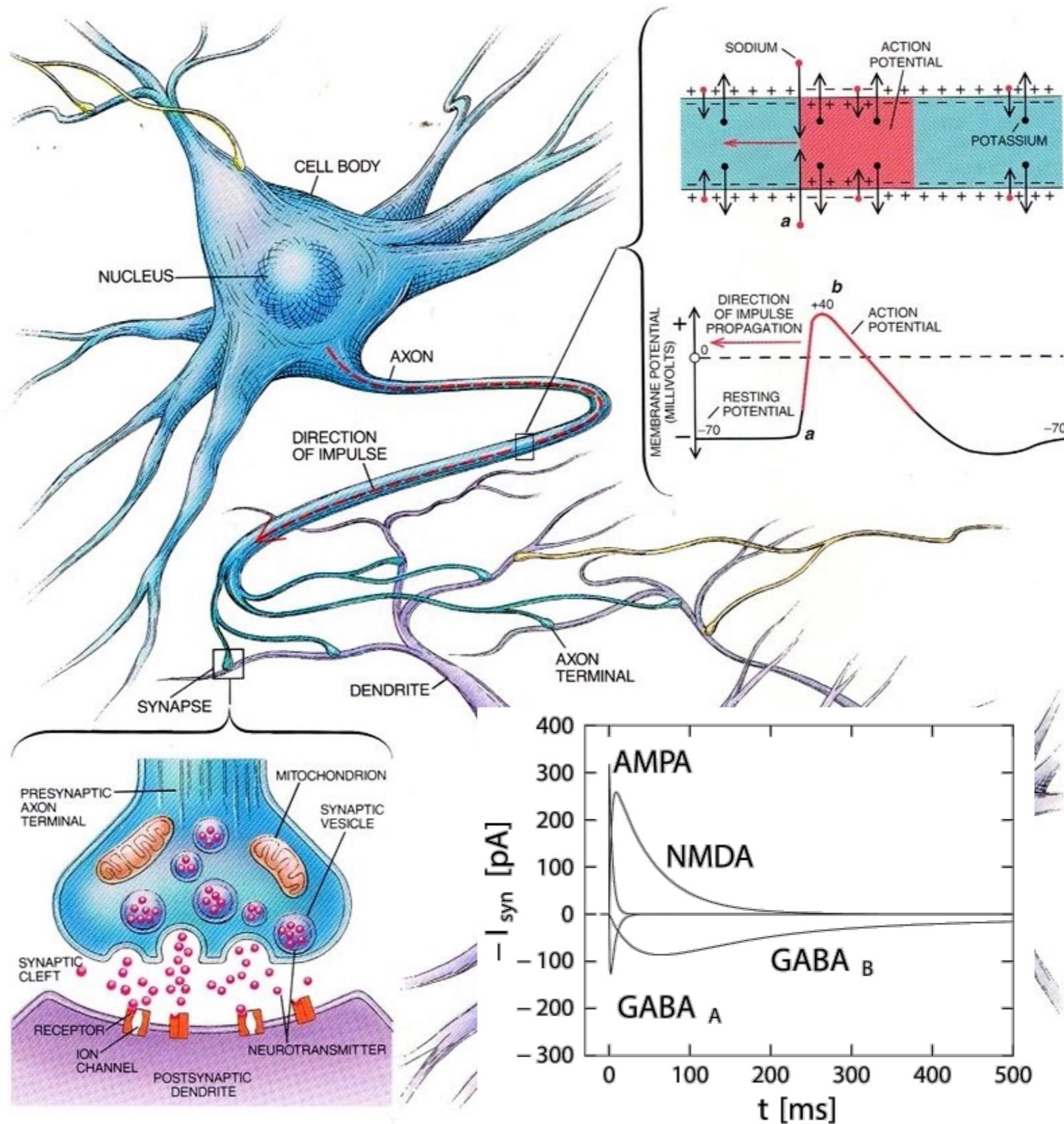
$10^{11}$  neurons



$10^{15}$  connections

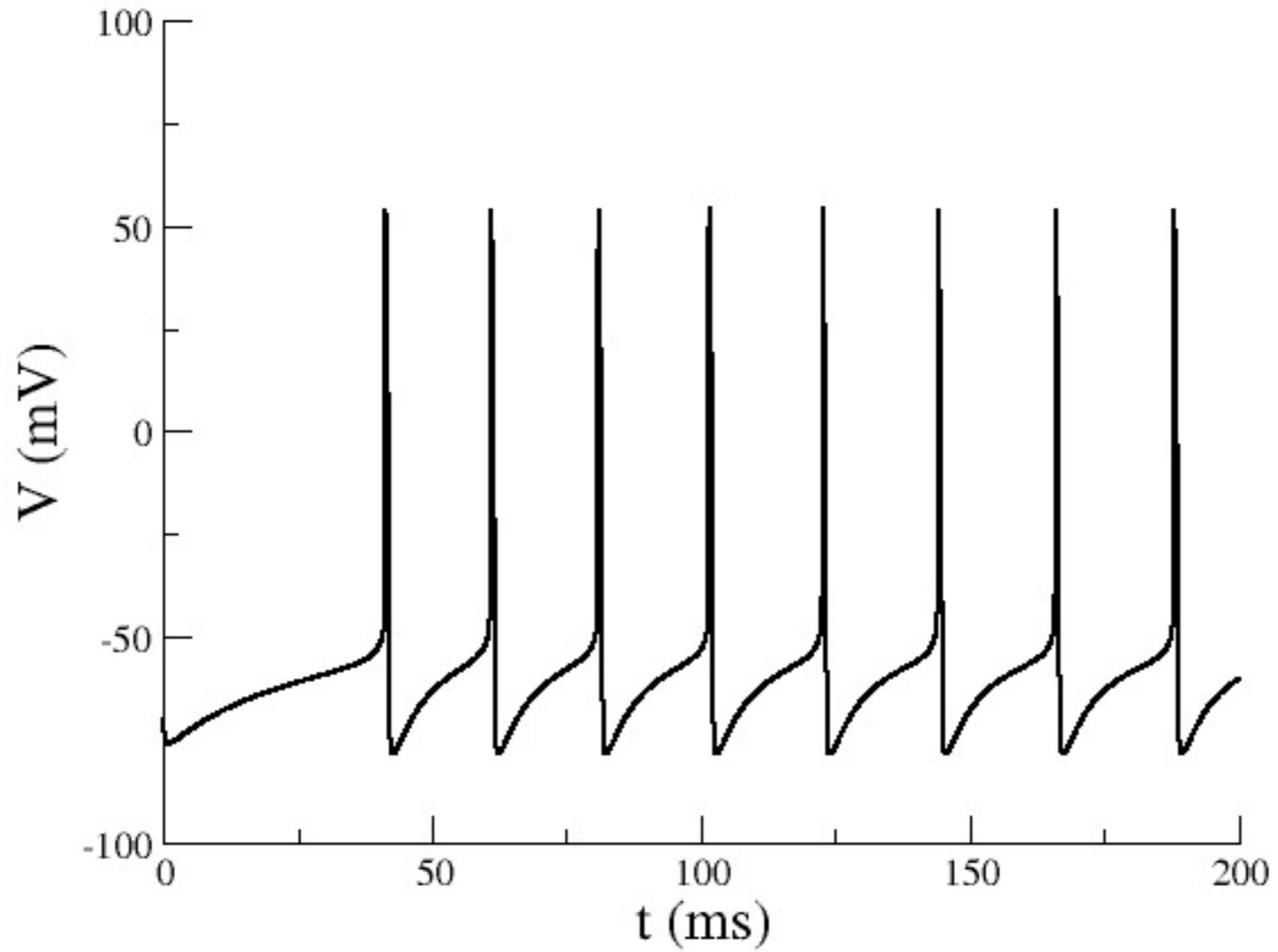


Cortex homogeneous at microscopic level

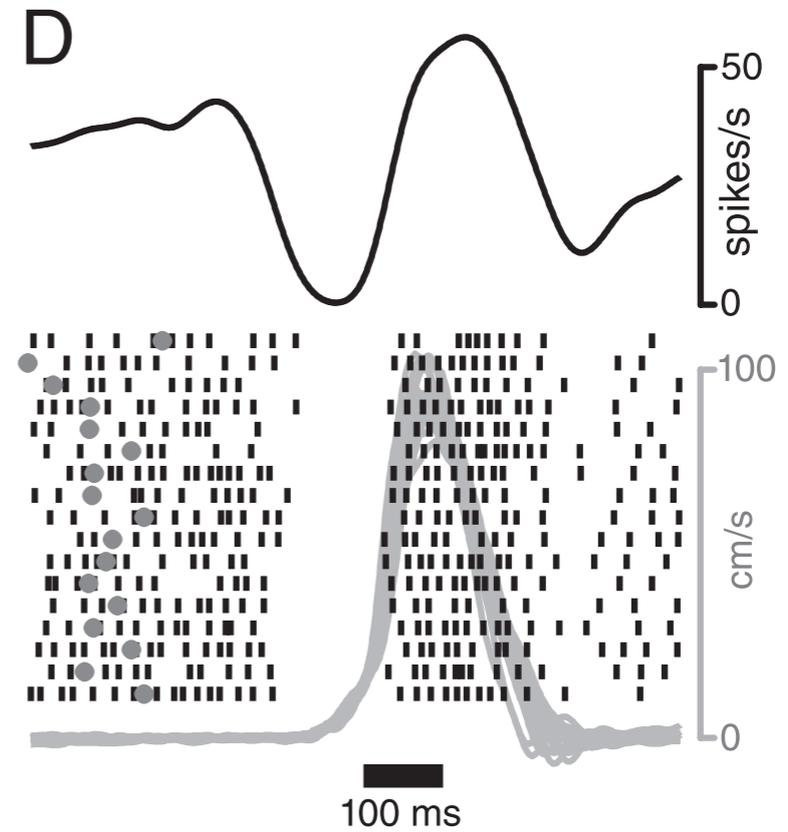
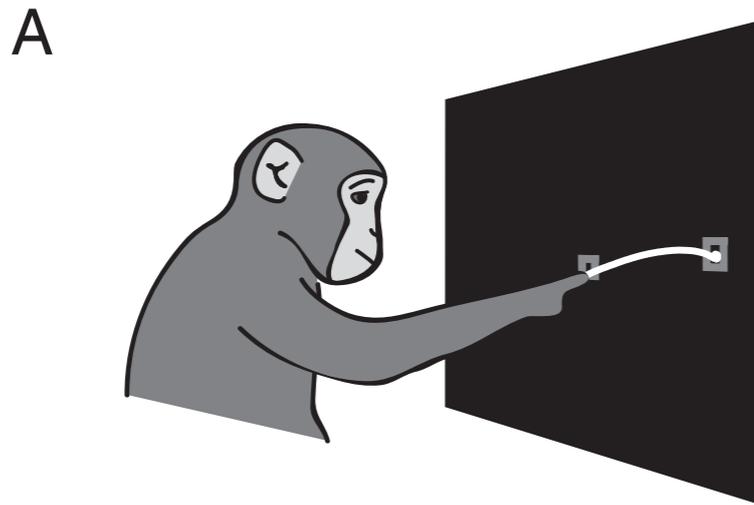


How Neurons Communicate

# Neurons “spike”

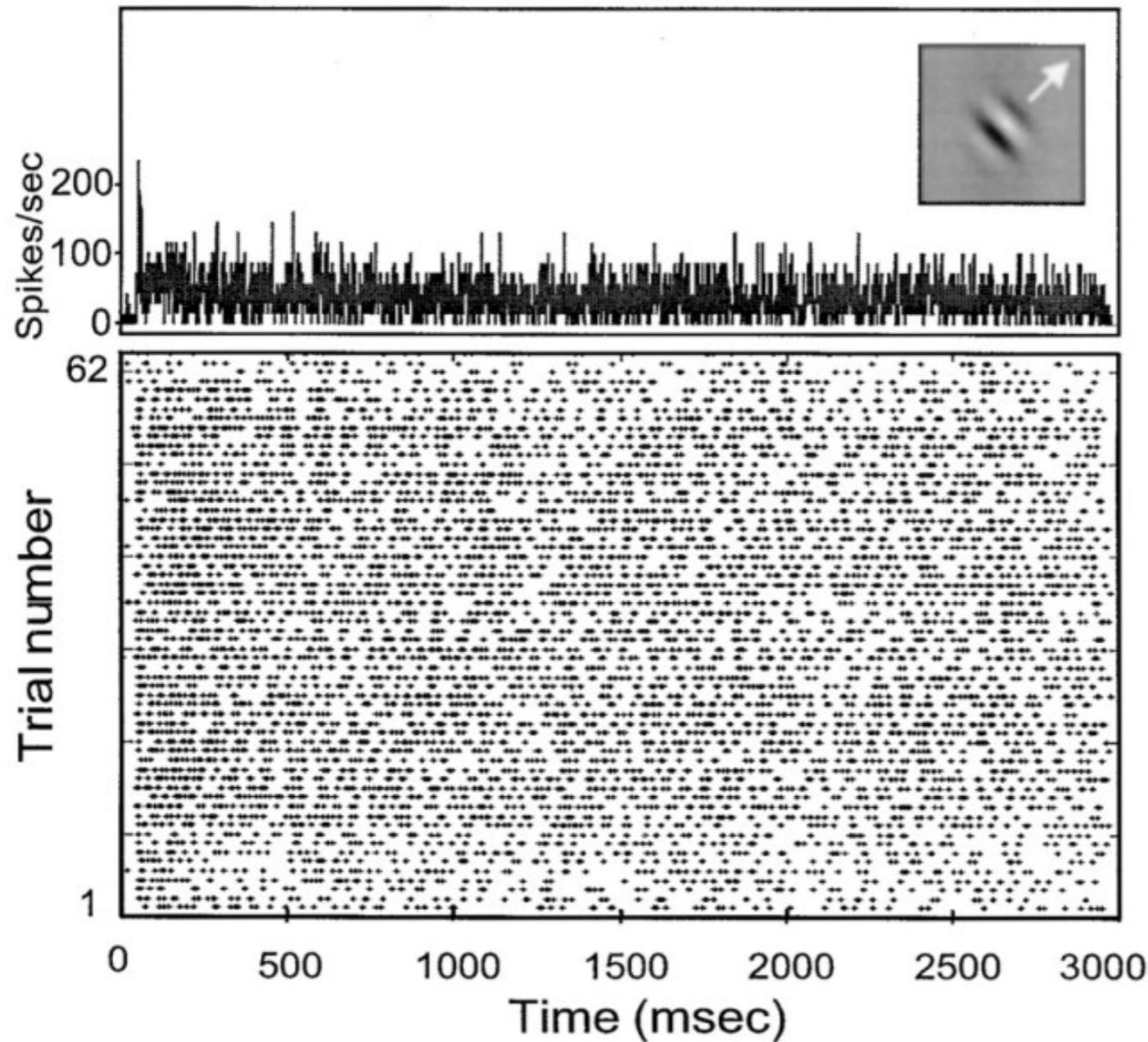


# Spiking correlated to behavior



Churchland and Shenoy, 2007

# Spiking is variable



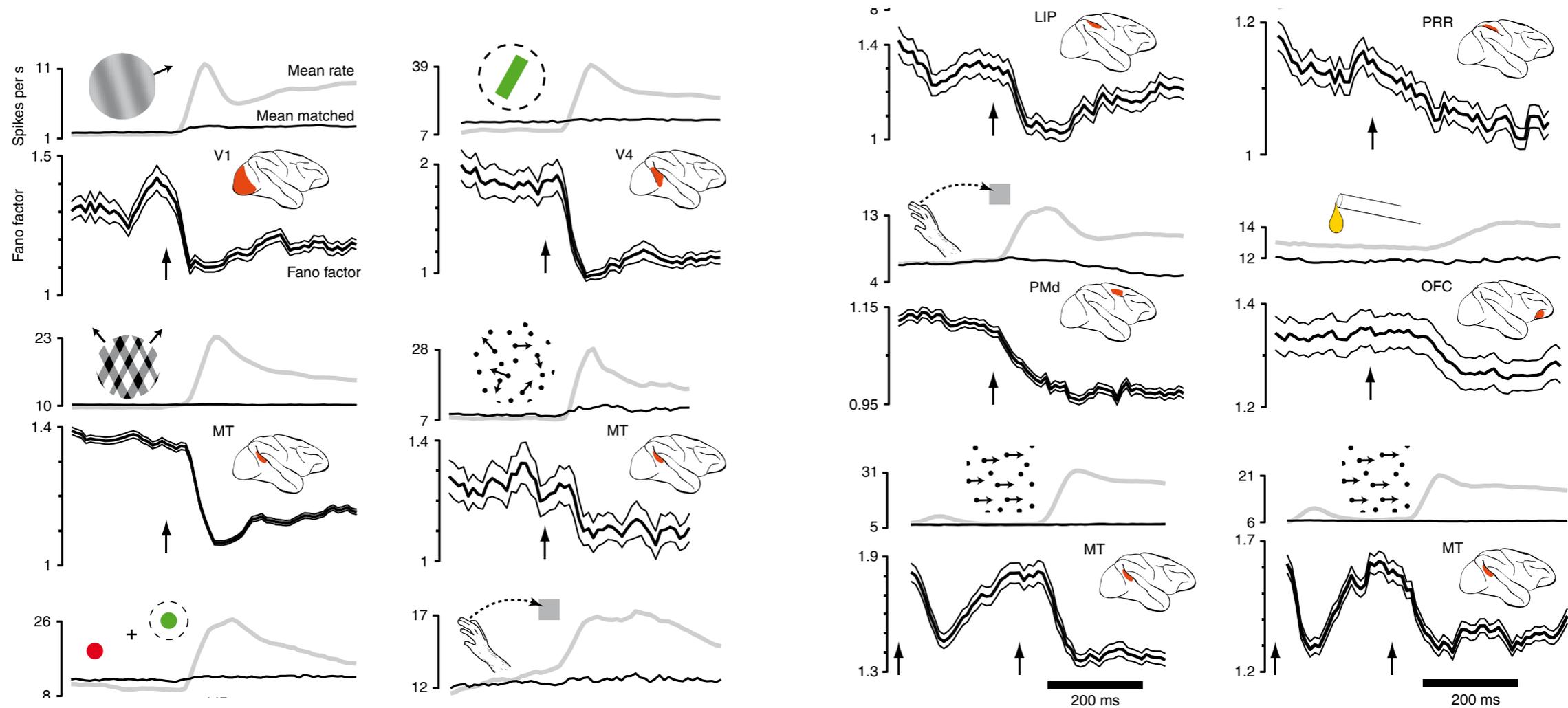
ISI CV  $\sim 1$

Fano Factor  $\sim 1$

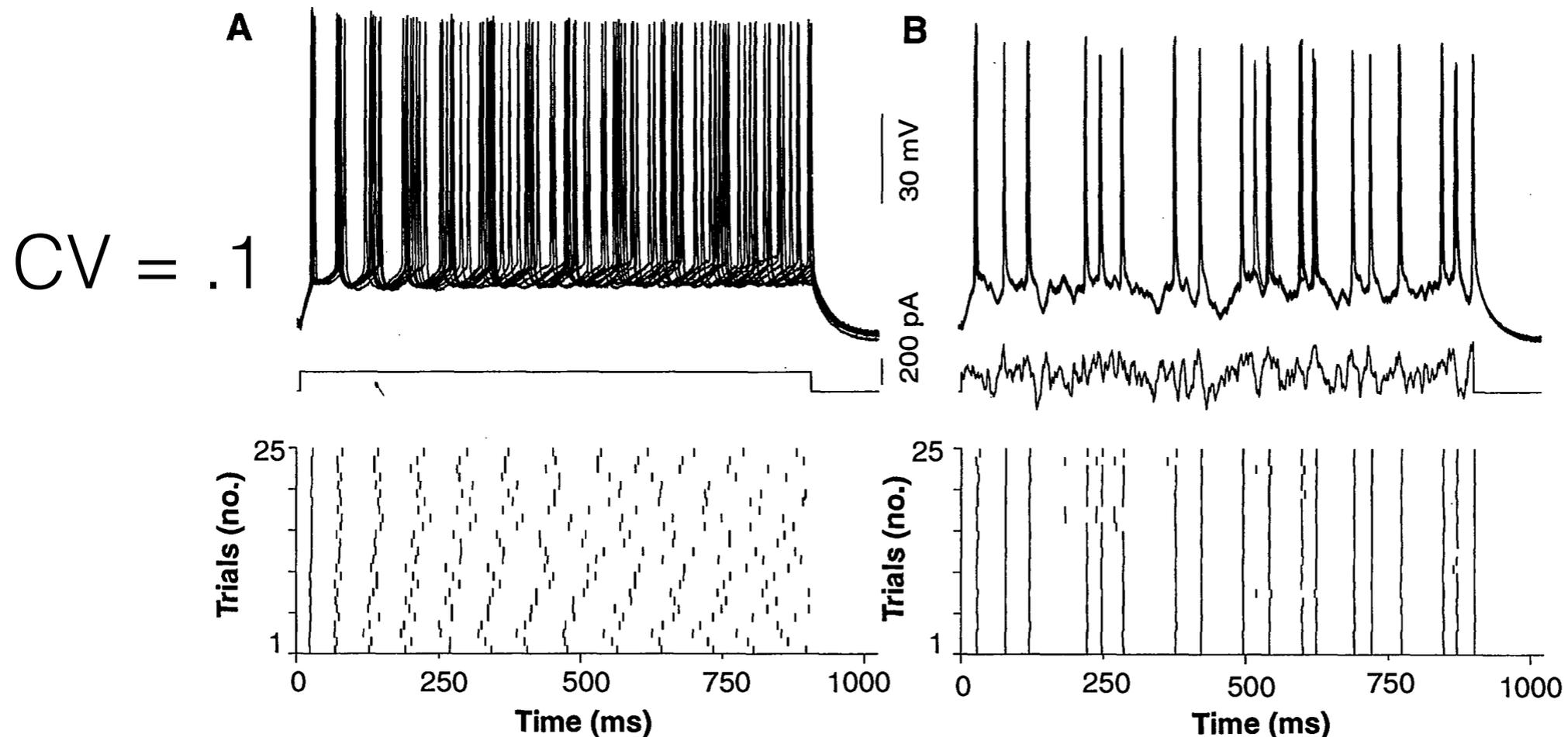
Poisson process

Buracas et al. 1998

# Spiking variability correlated to behavior



# Neurons are reliable



**Fig. 1.** Reliability of firing patterns of cortical neurons evoked by constant and fluctuating current. **(A)** In this example, a superthreshold dc current pulse (150 pA, 900 ms; middle) evoked trains of action potentials (approximately 14 Hz) in a regular-firing layer-5 neuron. Responses are shown superimposed (first 10 trials, top) and as a raster plot of spike times over spike times (25 consecutive trials, bottom). **(B)** The same cell as in (A) was again stimulated repeatedly, but this time with a fluctuating stimulus [Gaussian white noise,  $\mu_s = 150$  pA,  $\sigma_s = 100$  pA,  $\tau_s = 3$  ms; see (14)].

# Softy-Koch “Paradox”, 1993

Spiking variable

Neurons reliable



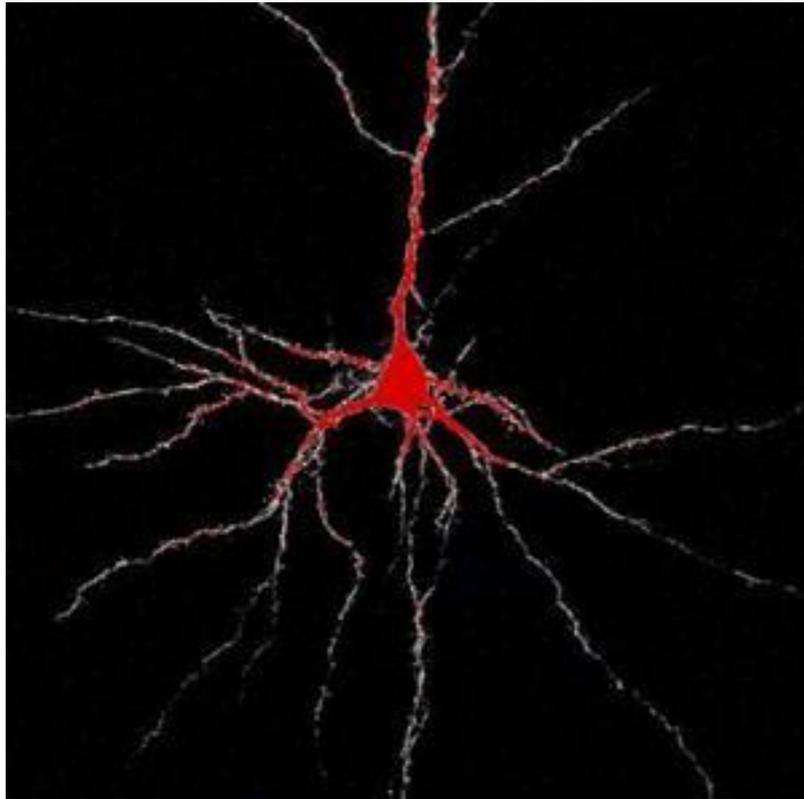
**Open Questions  
Remain**

Answer: Balanced State

Van Vreeswijk and Sompolinsky, 1996 & 1998

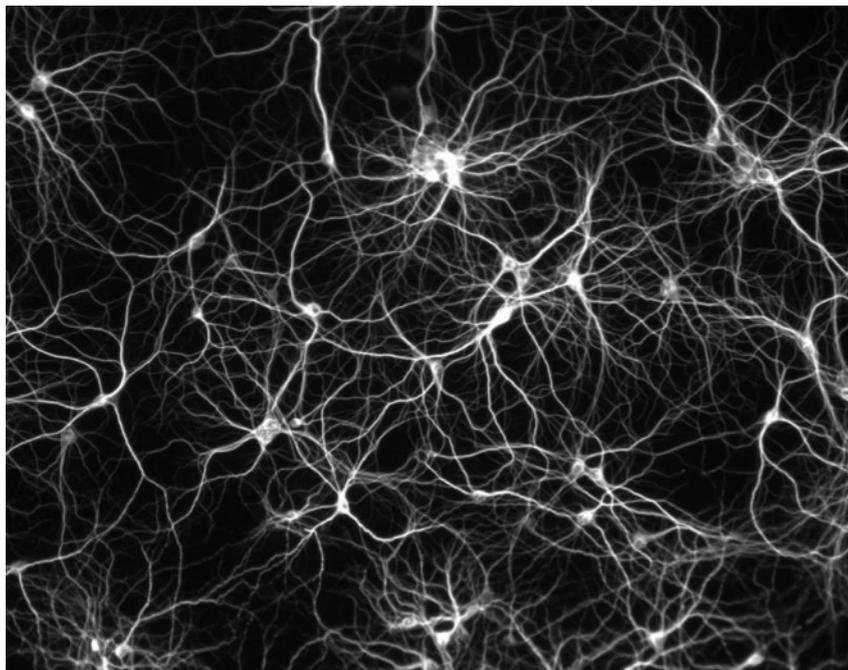
Connections strong and sparse,  
Chaotic state is a fixed point

# Network



$$\frac{dV}{dt} = g(V, I)$$

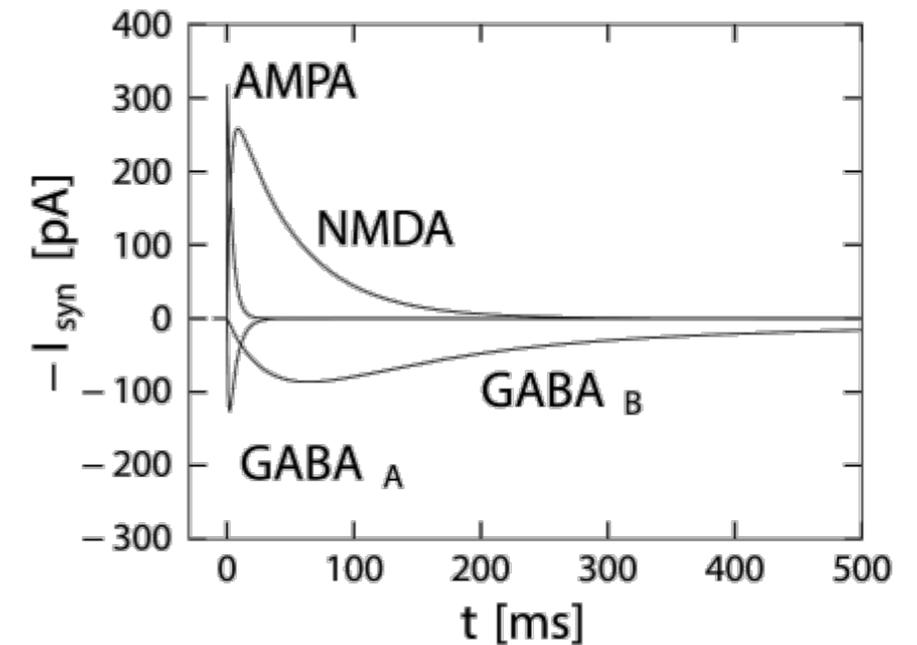
Input



$$\frac{dV_i}{dt} = g \left( V_i, I + \sum_{j=1}^N w_{ij} s(V_j) \right)$$

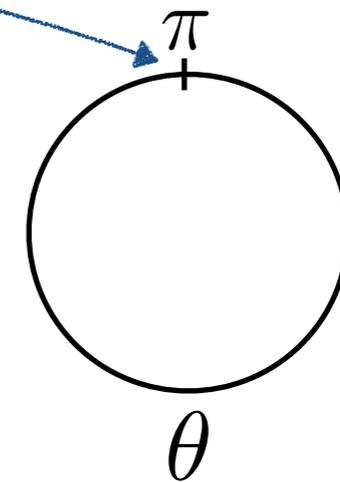
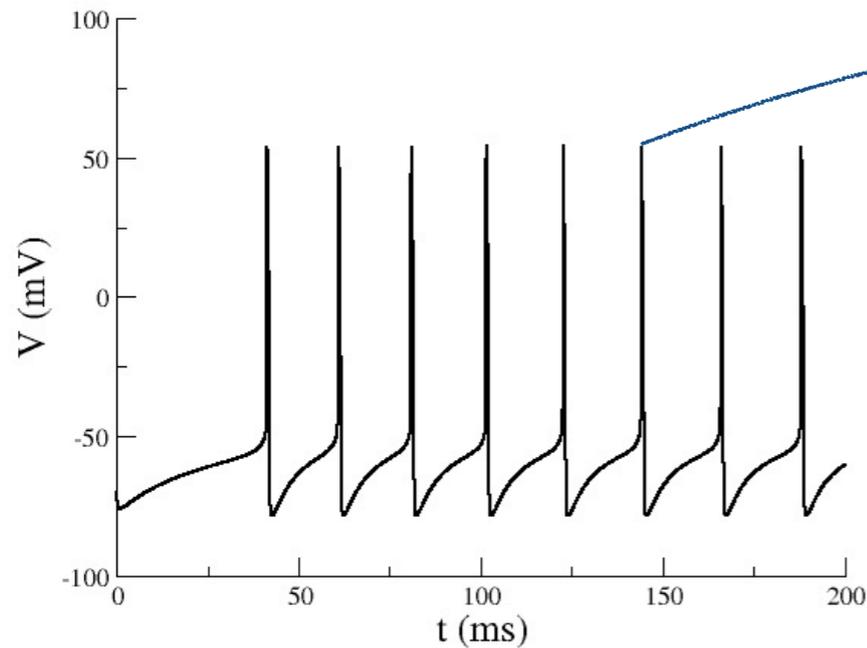
Connection weights

## Synapse



What is the dynamical repertoire of a network of spiking neurons?

# Neuron phase model



$$\frac{d\theta}{dt} = 1 - \cos \theta + I(1 + \cos \theta)$$

Theta neuron

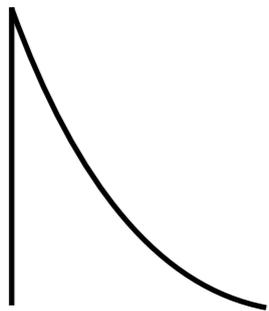
AKA ERMENTROUT-KOPELL CANONICAL MODEL

3 parameters

# Network

$$\dot{\theta}_i = 1 - \cos \theta_i + (I + u_i)(1 + \cos \theta_i)$$

Synapse



$$\dot{u}_i = -\beta u_i + \beta \sum_{j,s} w_{ij} \delta(t - t_j^s(\theta_j))$$

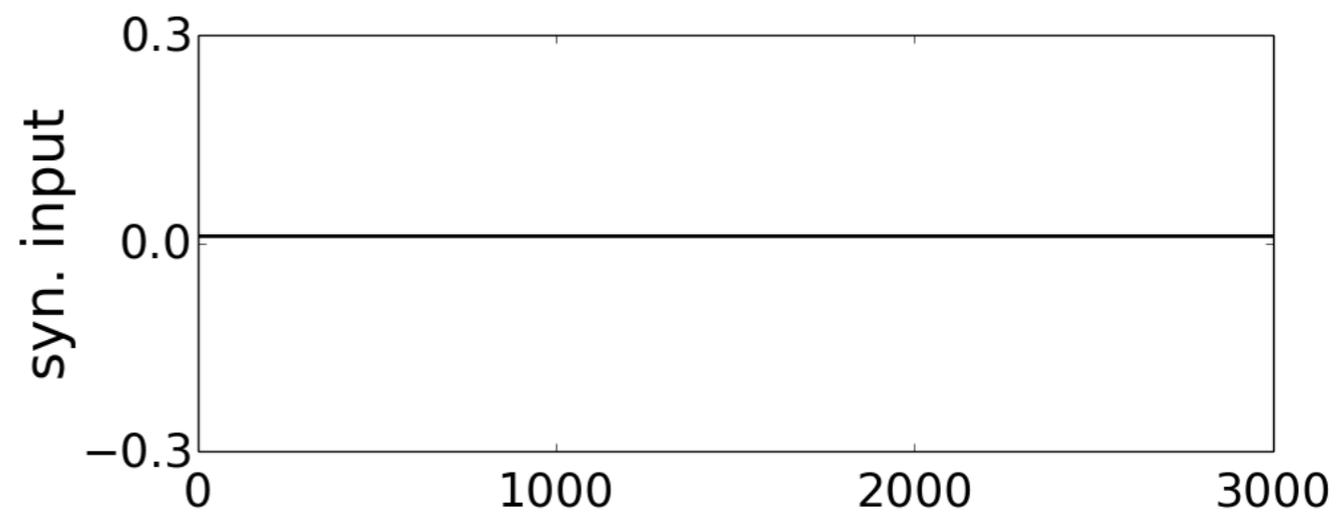
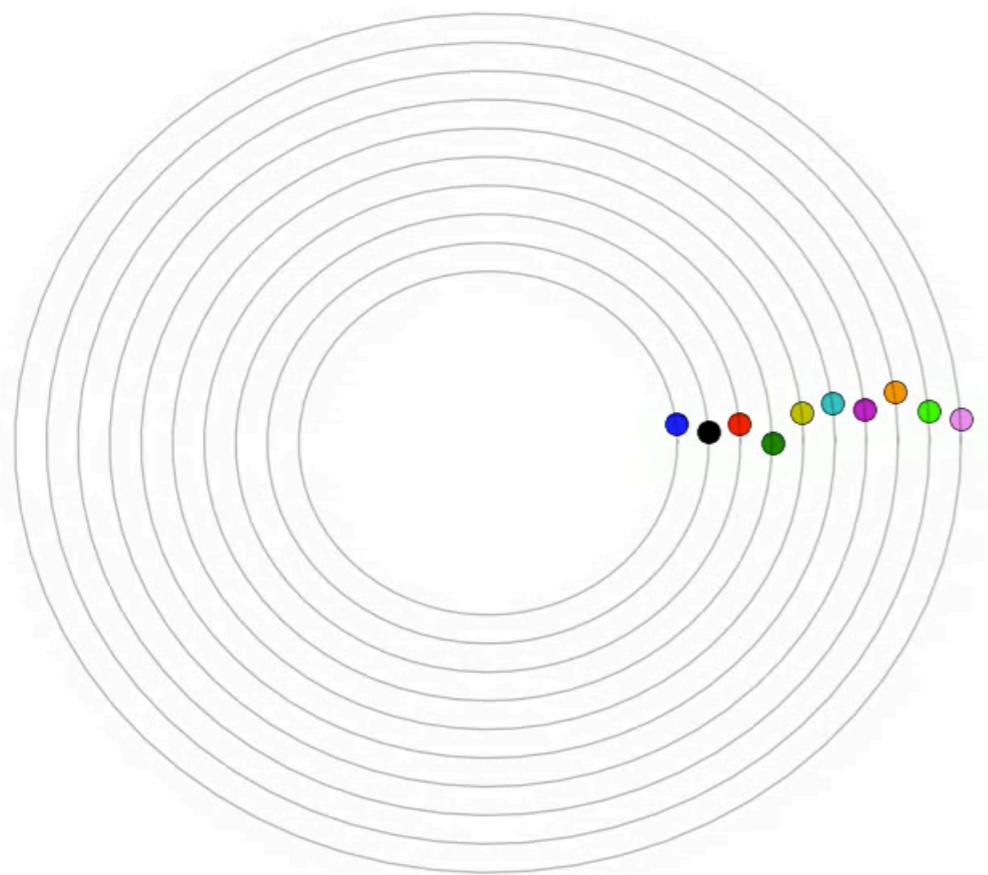
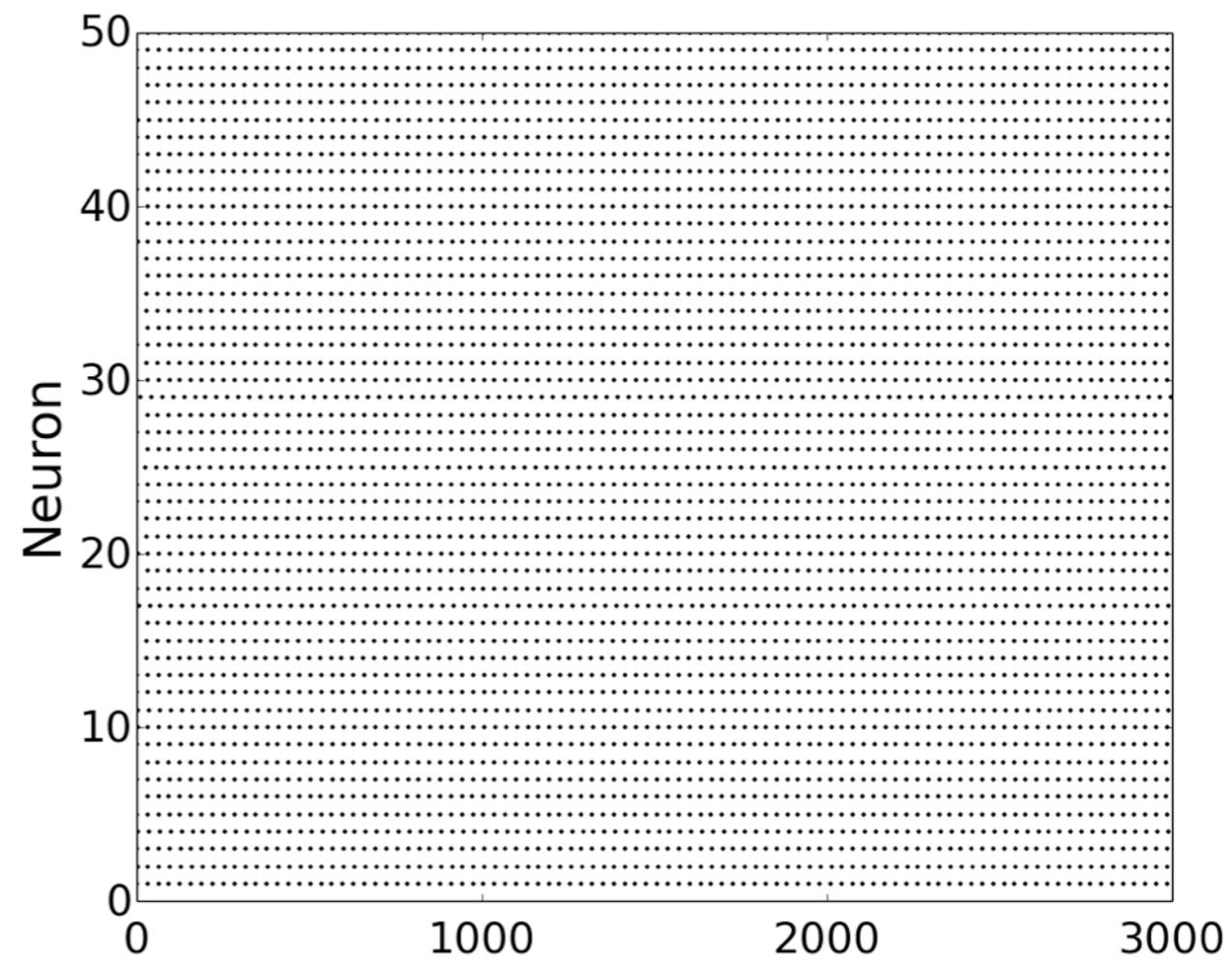
$$t_j^s = \{t \mid \theta_j(t) = \pi, \dot{\theta}_j > 0\}$$

$$w_{ij} \sim N(0, \sigma^2/N)$$

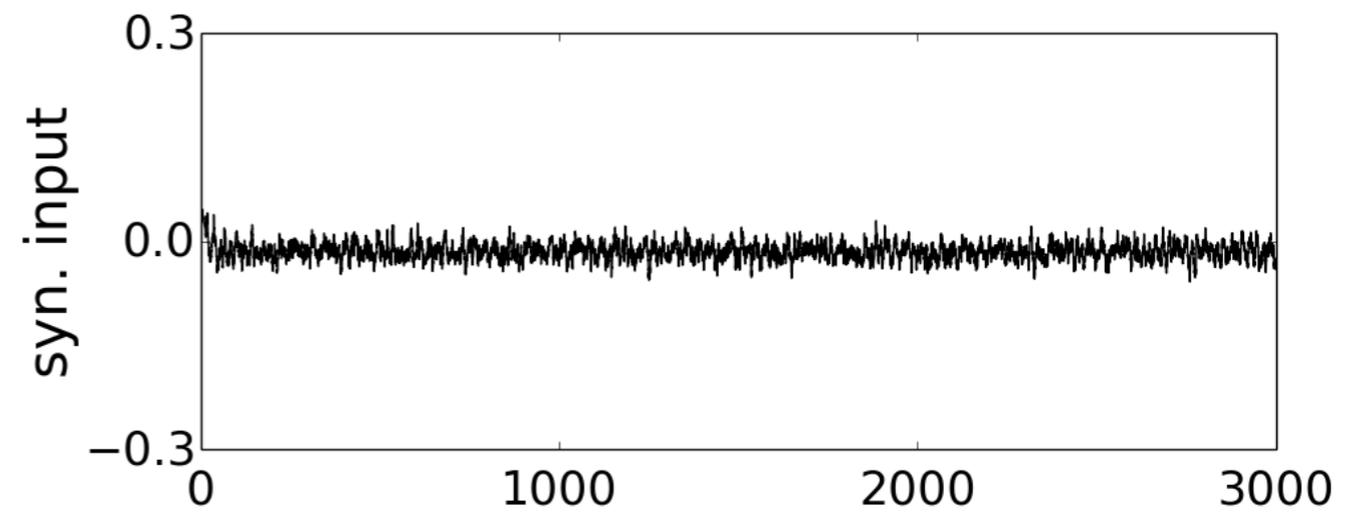
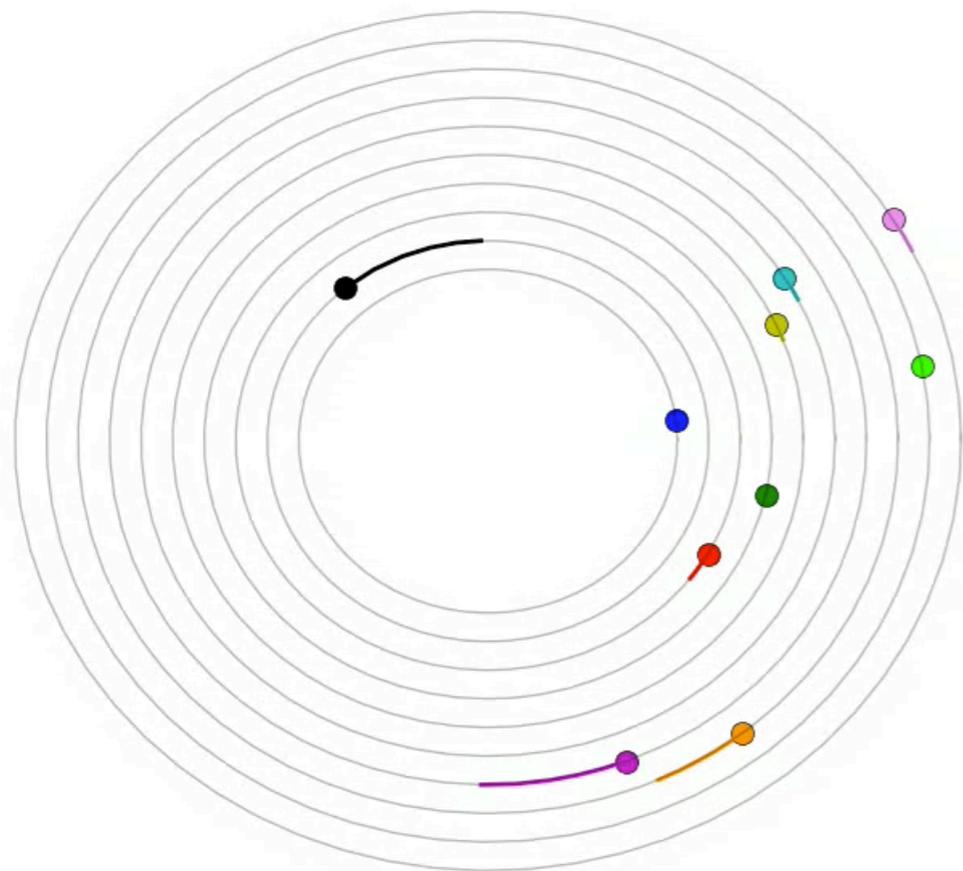
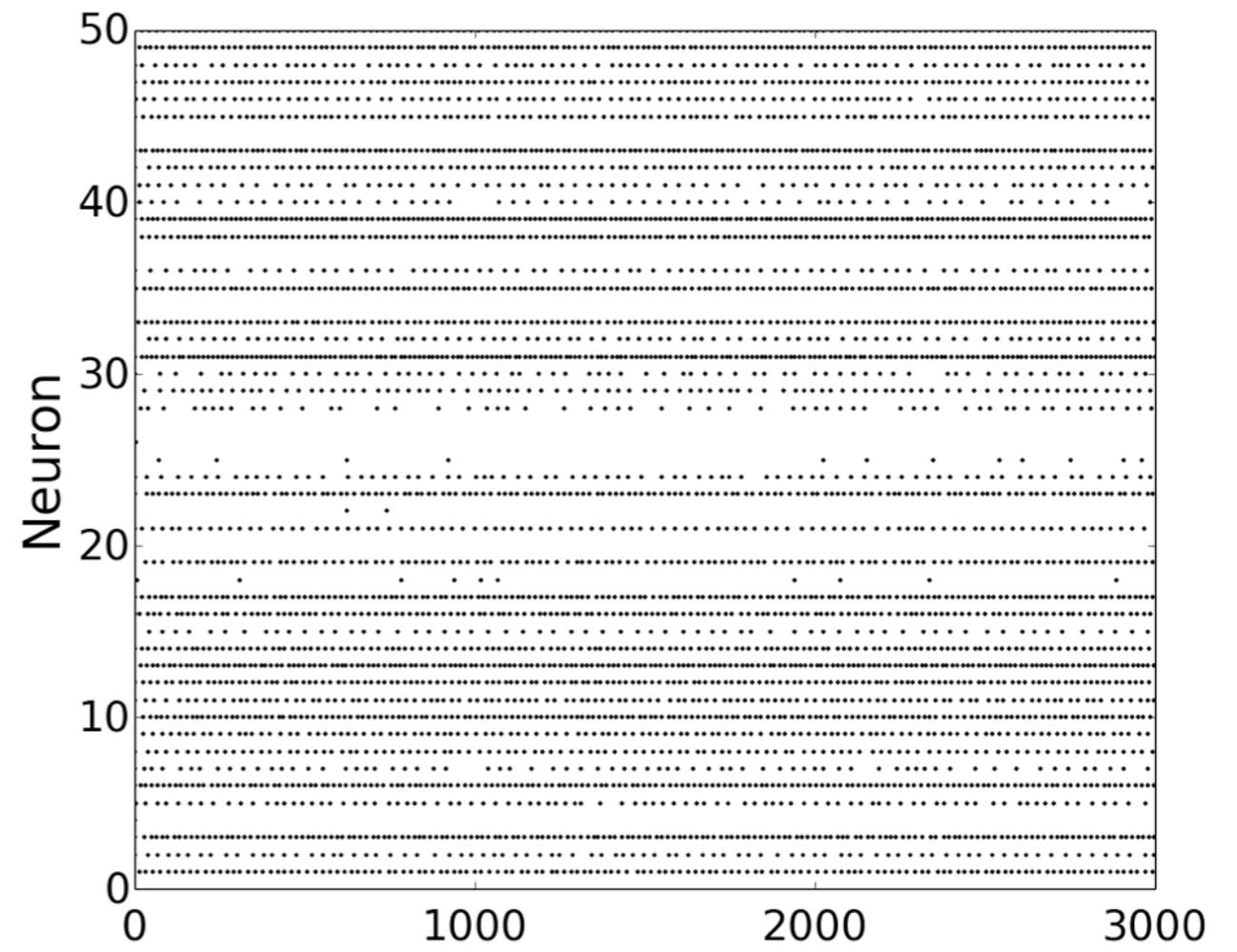
Random coupling

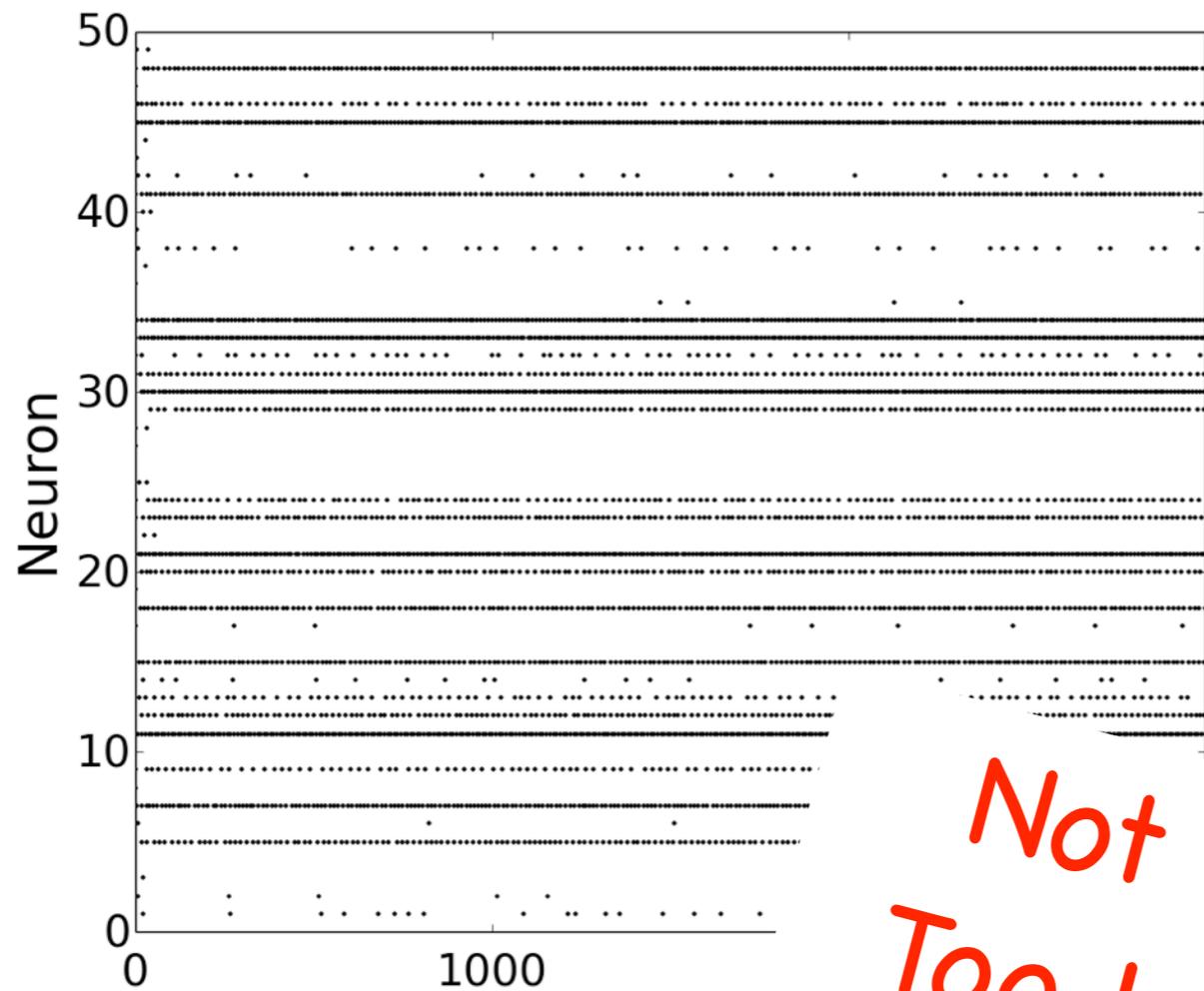
$$\sigma = 0, I = 0.01, \beta = 0.1$$

$$N = 200$$

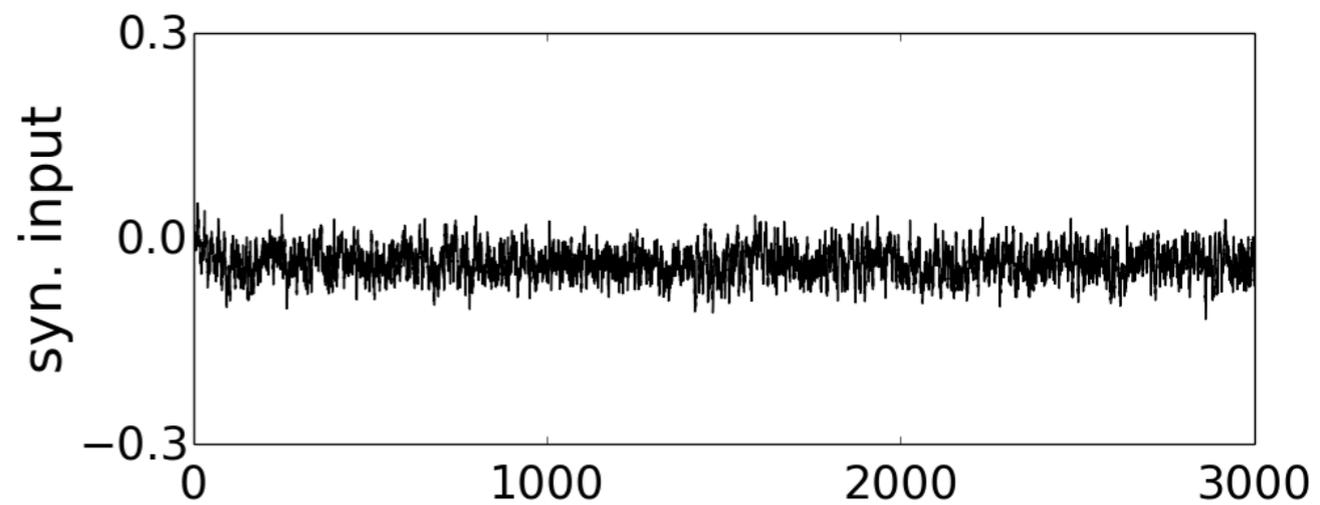


$\sigma = 0.5$



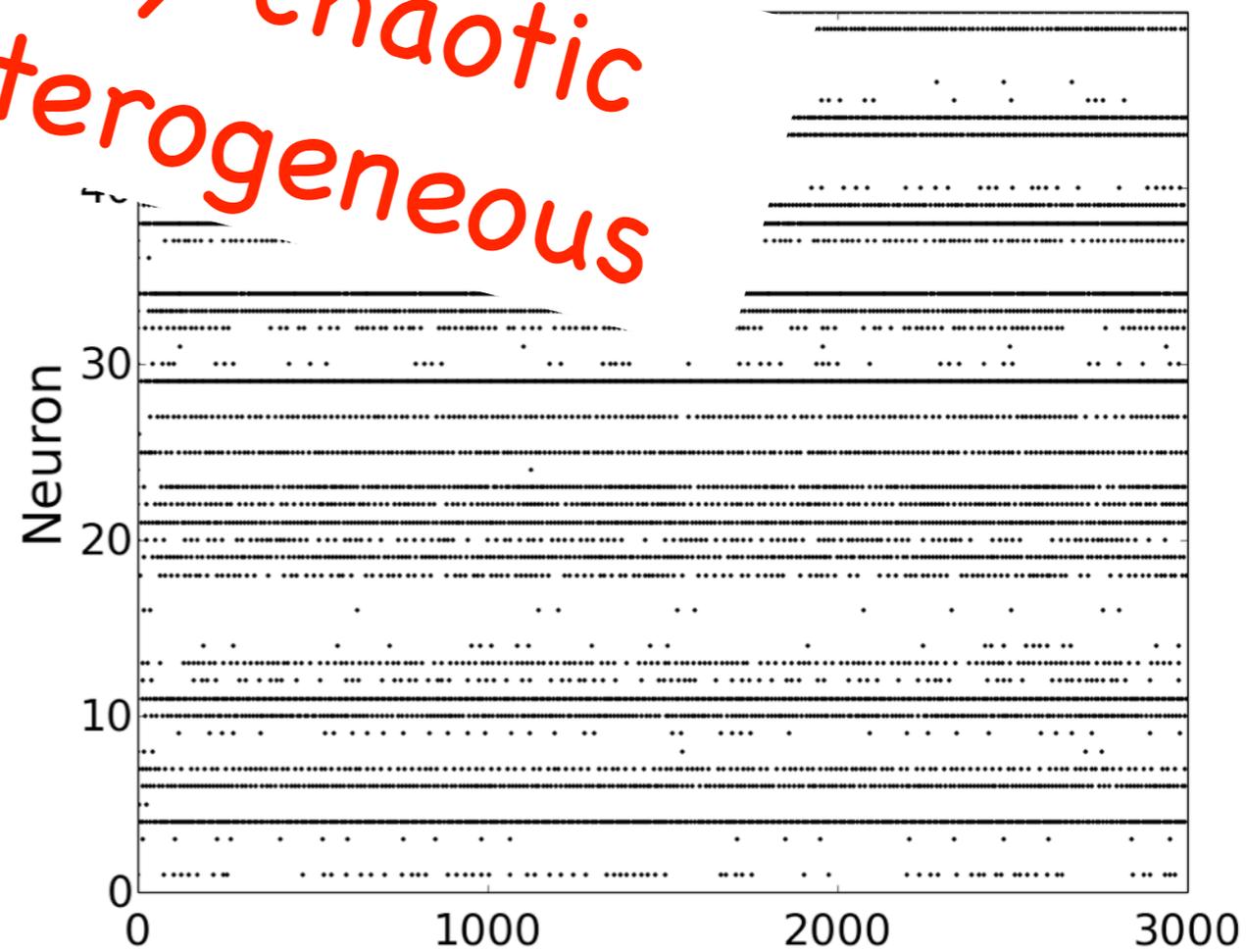
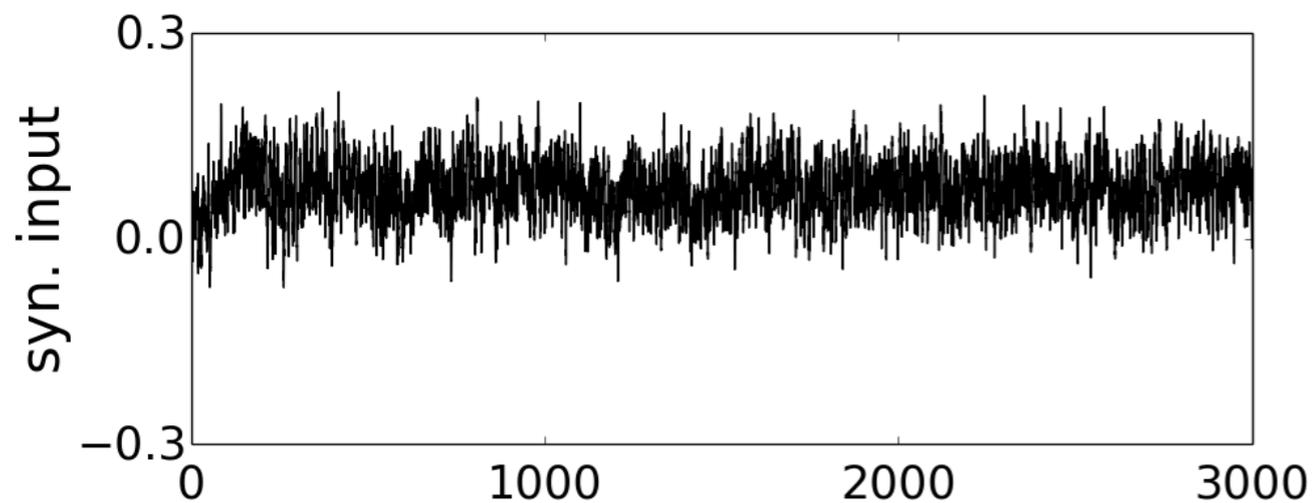


$\sigma = 1.0$



*Not very chaotic  
Too heterogeneous*

$\sigma = 1.5$



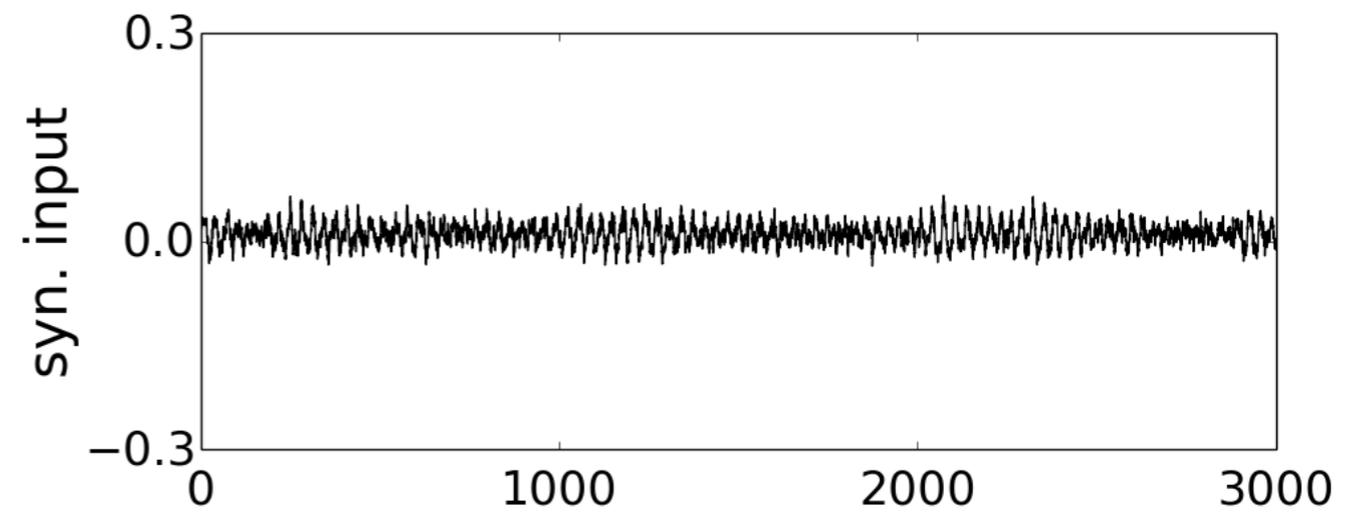
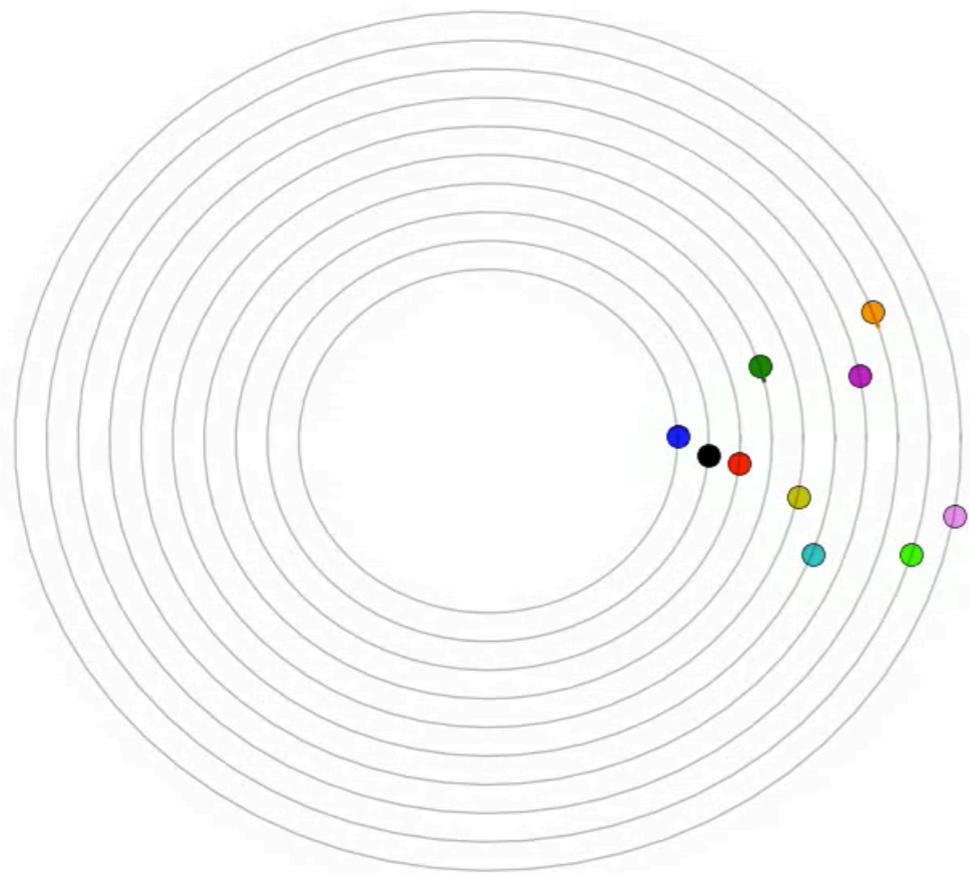
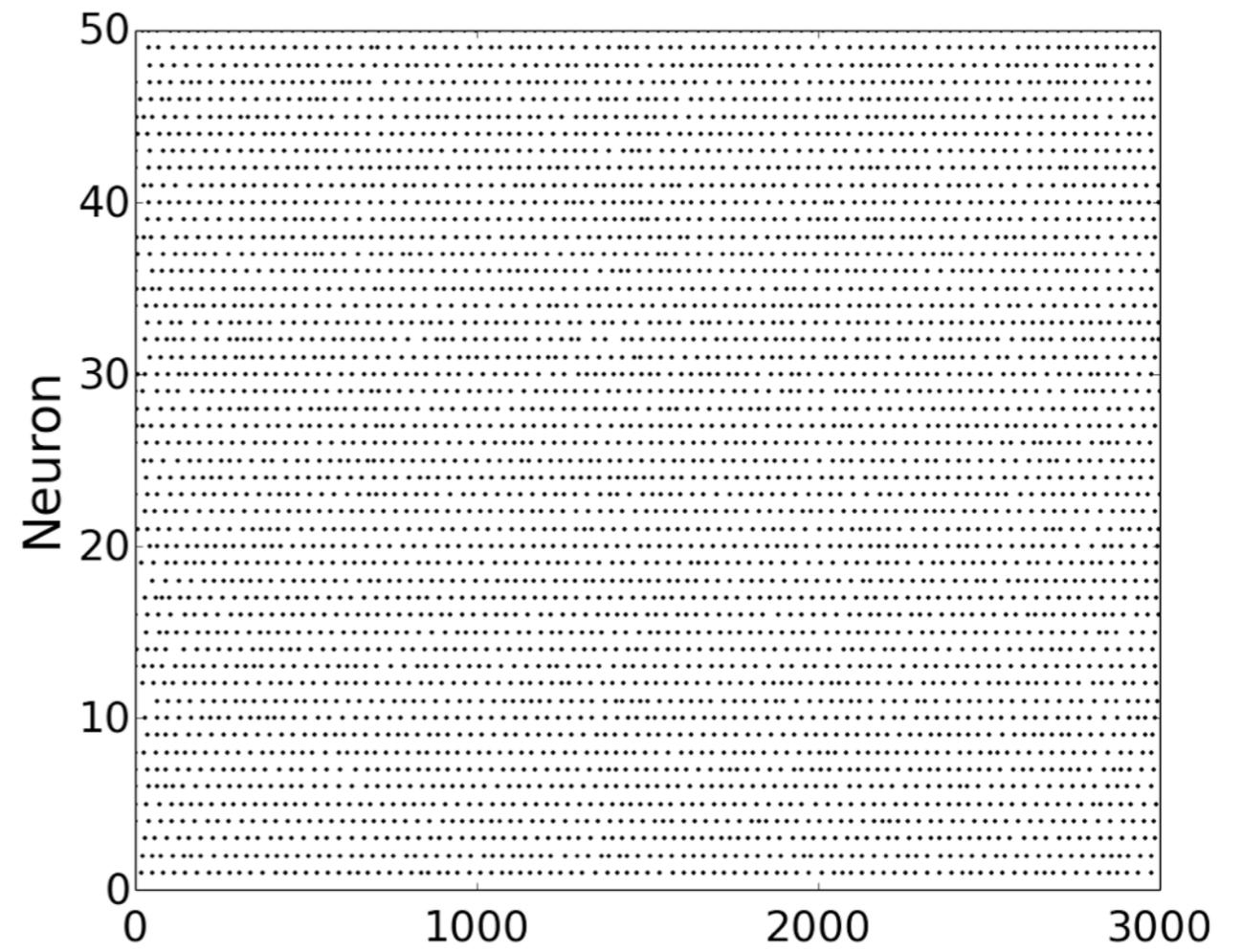
Column sum corrected

# ^ Network model

$$\dot{\theta}_i = 1 - \cos \theta_i + (I + u_i)(1 + \cos \theta_i)$$

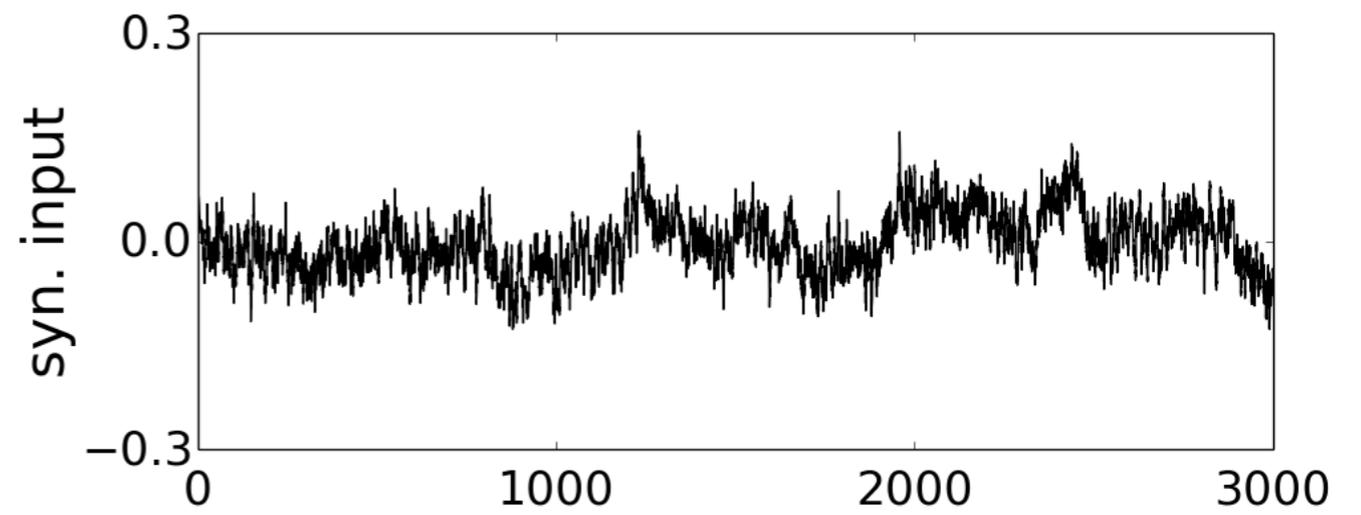
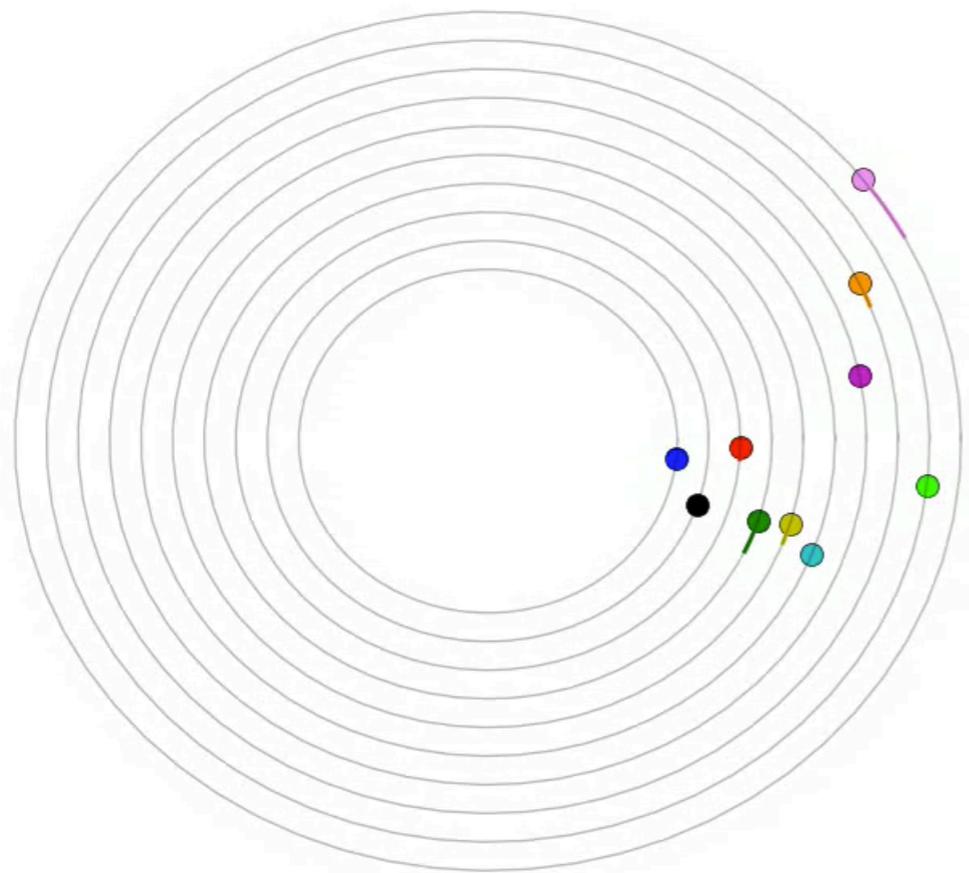
$$\dot{u}_i + \beta u_i = \beta \sum_{j,s} \left( w_{ij} \left( -\frac{1}{N} \sum_k w_{ik} \right) \right) \delta(t - t_j^s(\theta_j))$$

$\sigma = 0.5$



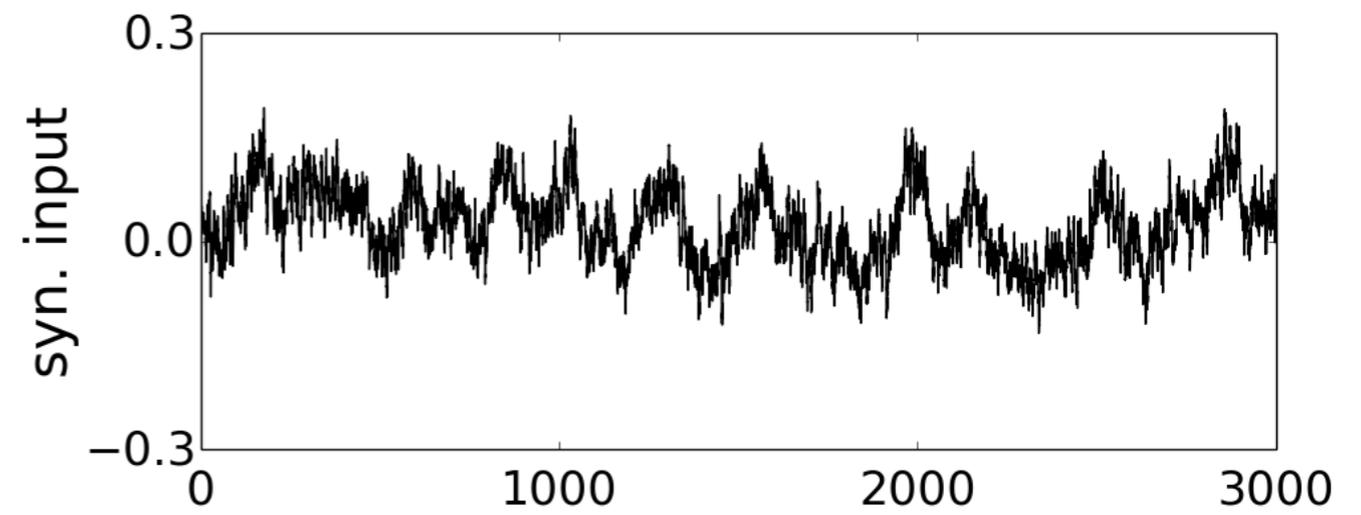
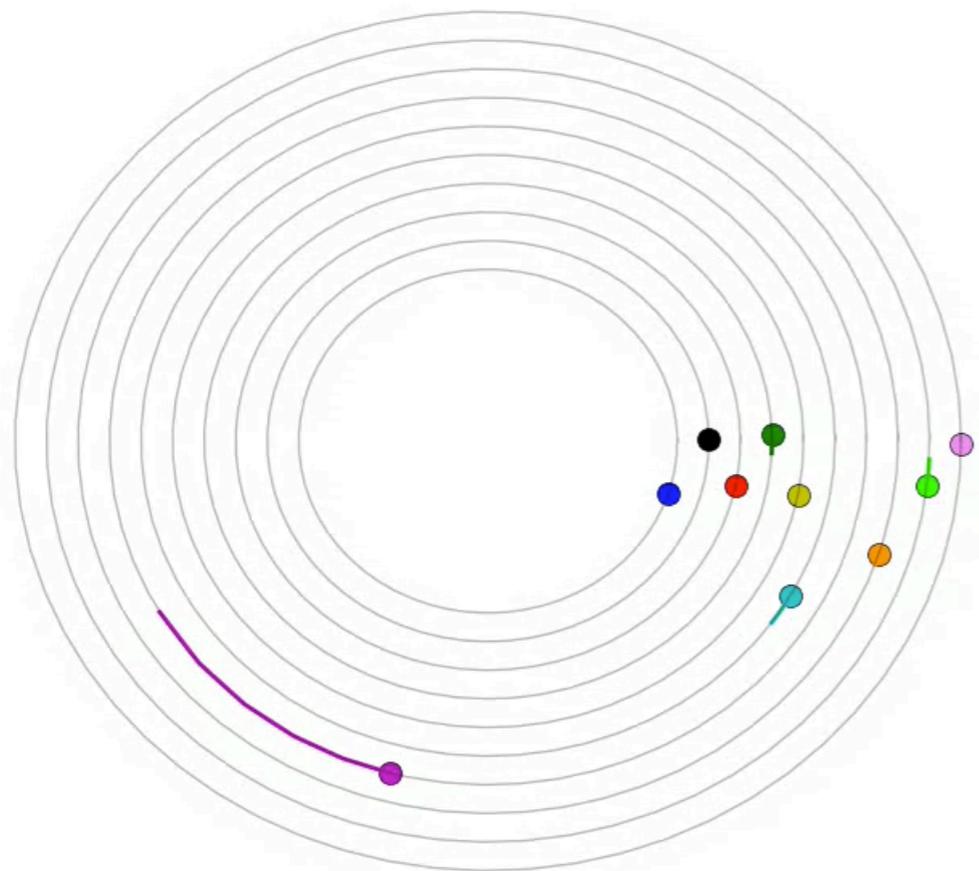
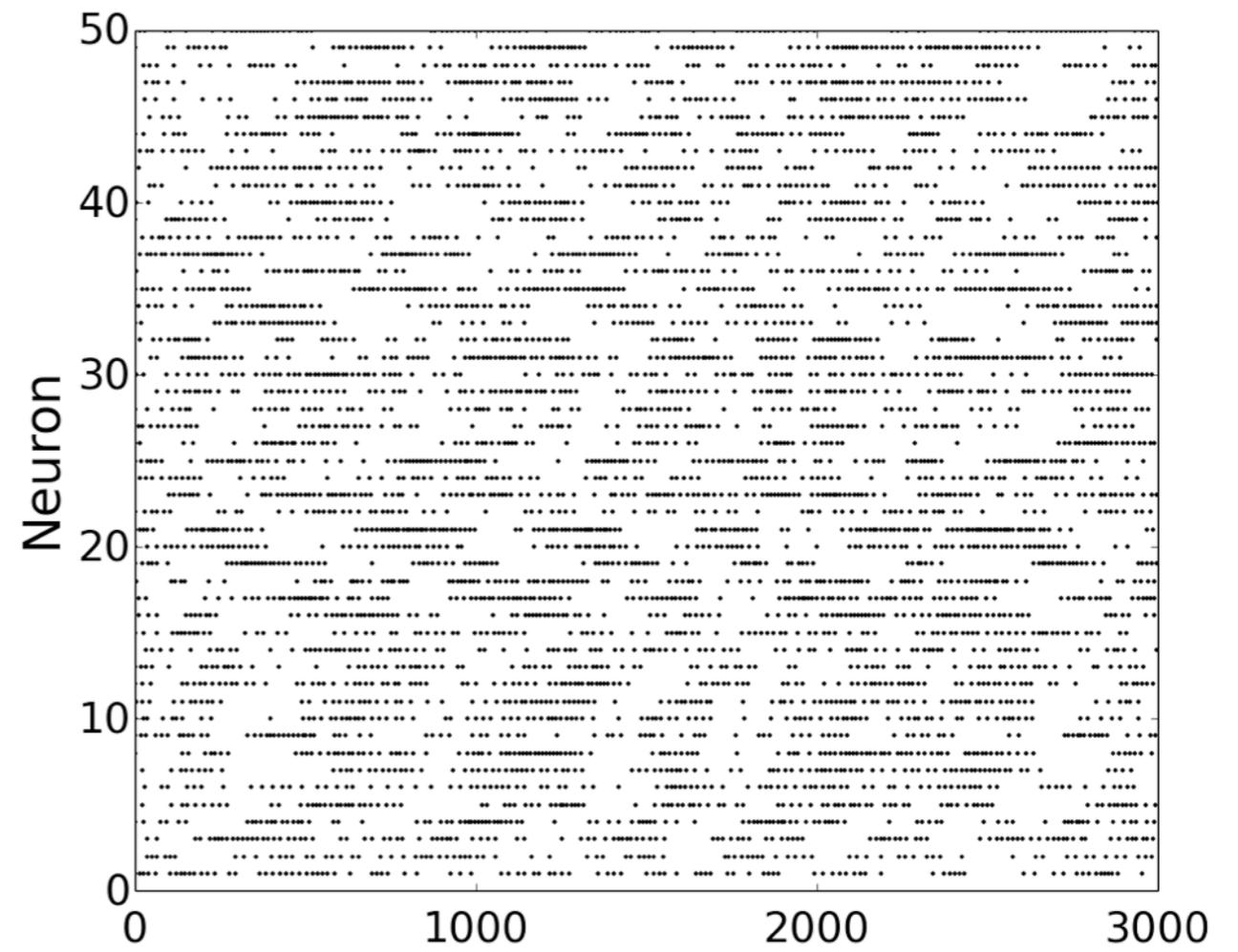
FF < .1

$\sigma = 1.0$



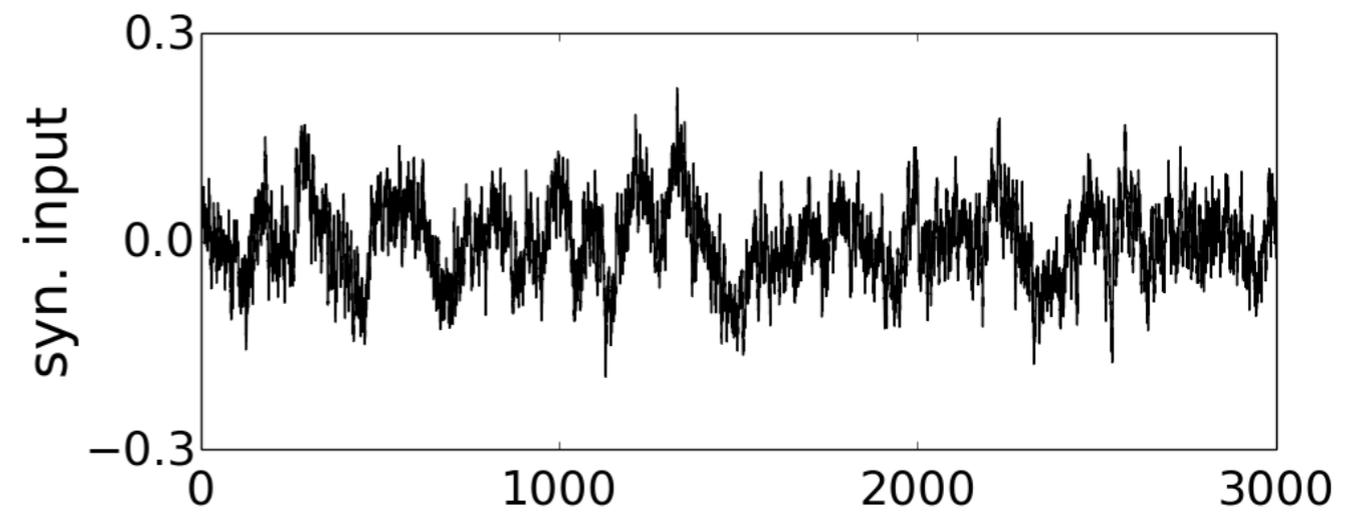
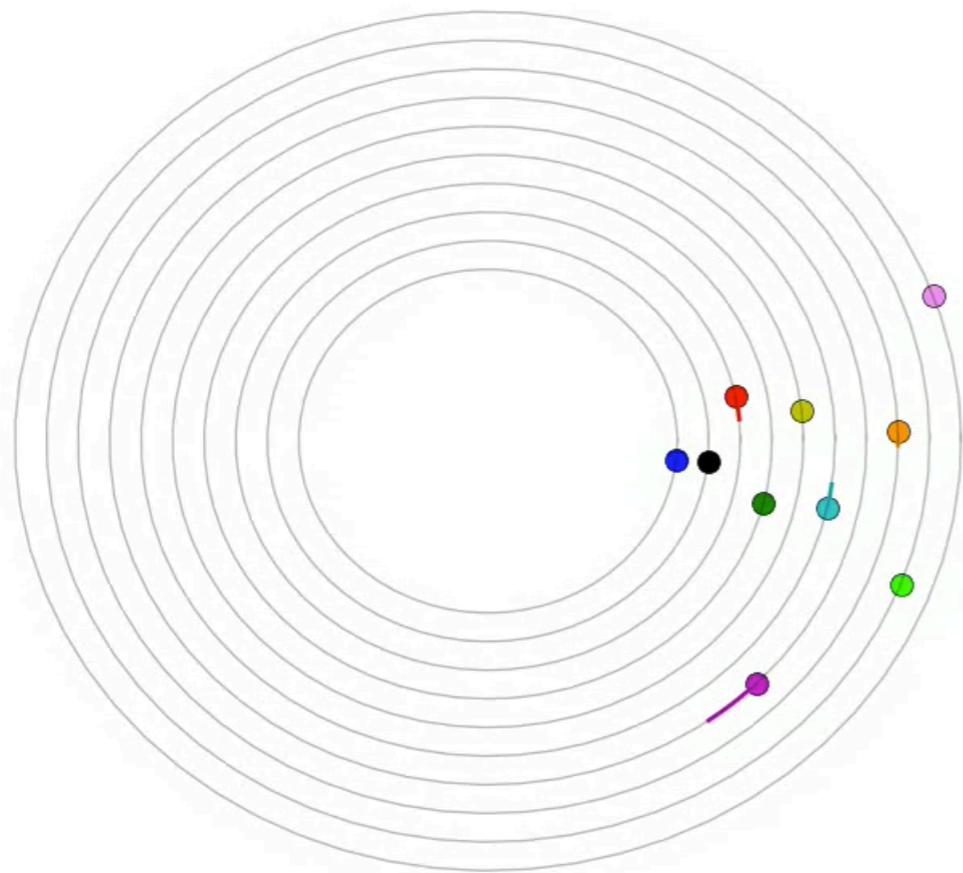
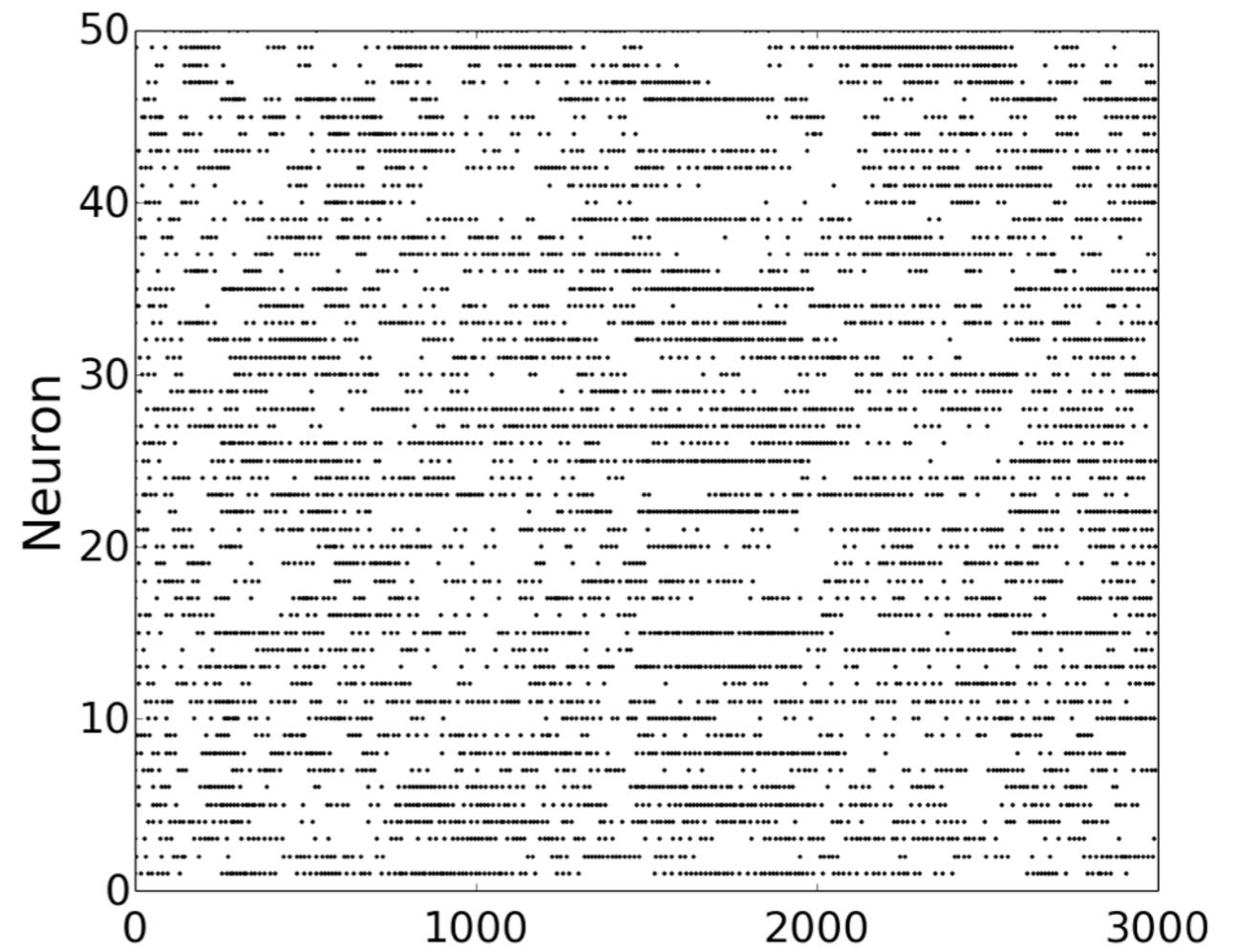
FF = .75

$$\sigma = 1.2$$



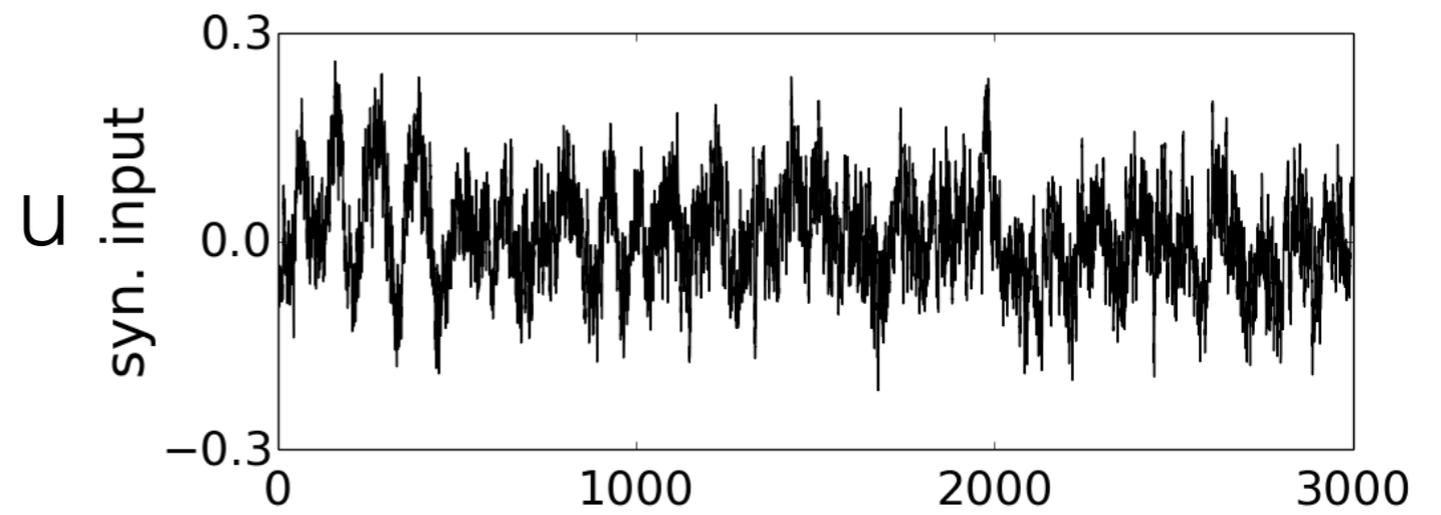
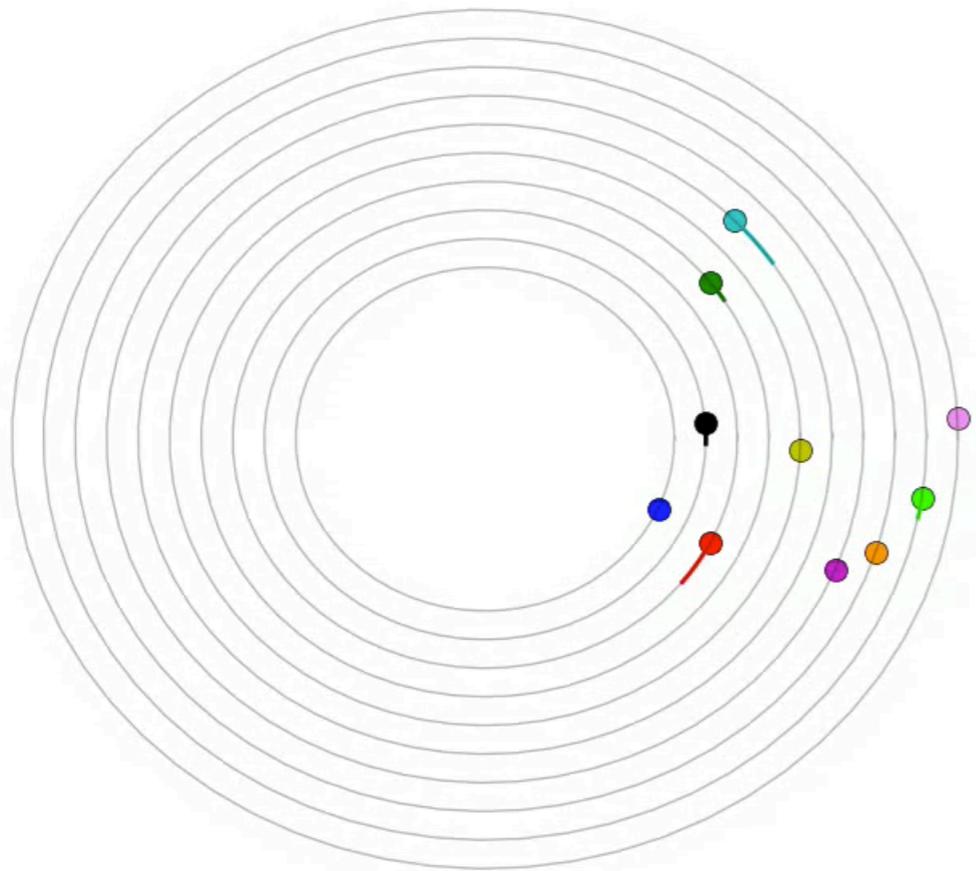
$$FF = 1$$

$\sigma = 1.5$



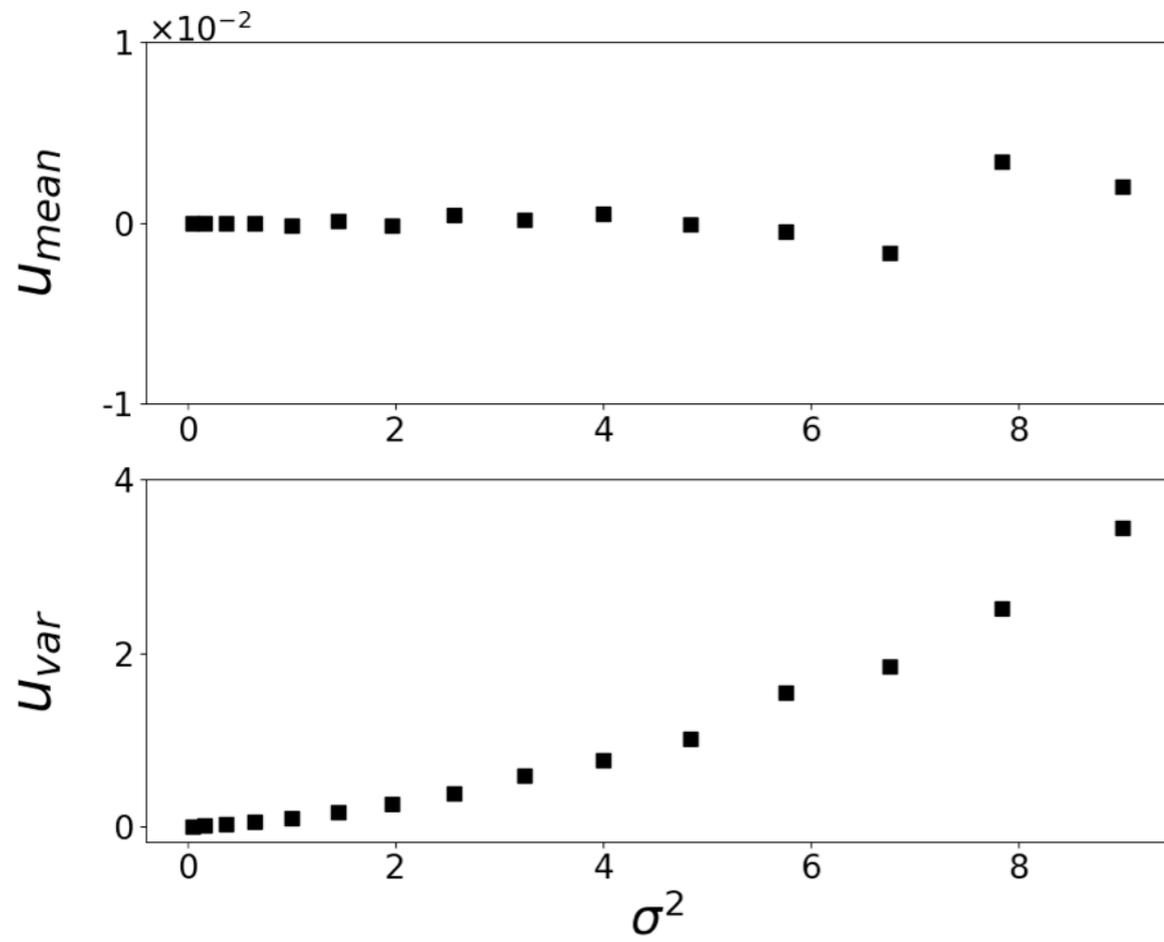
FF 1.4

$\sigma = 2.0$

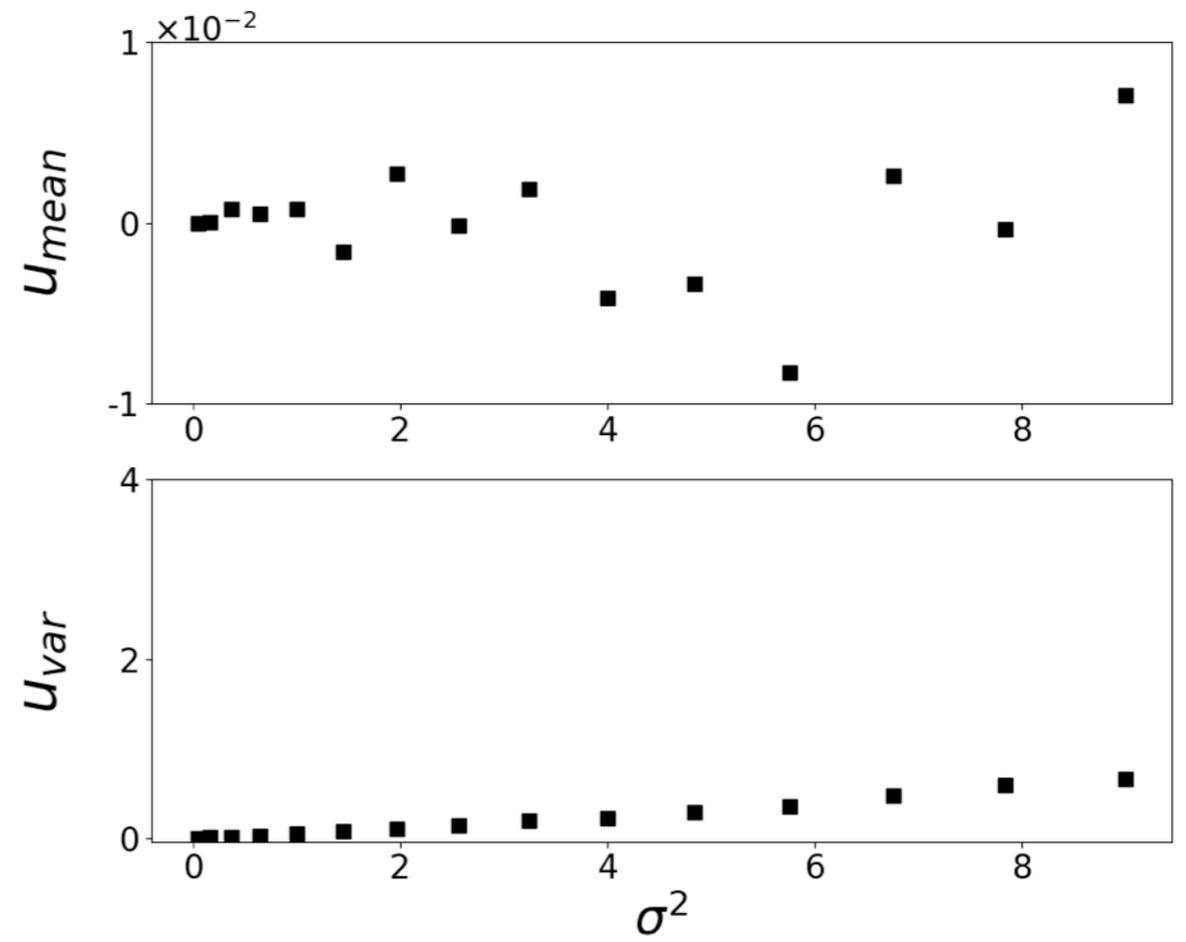


FF 1.7

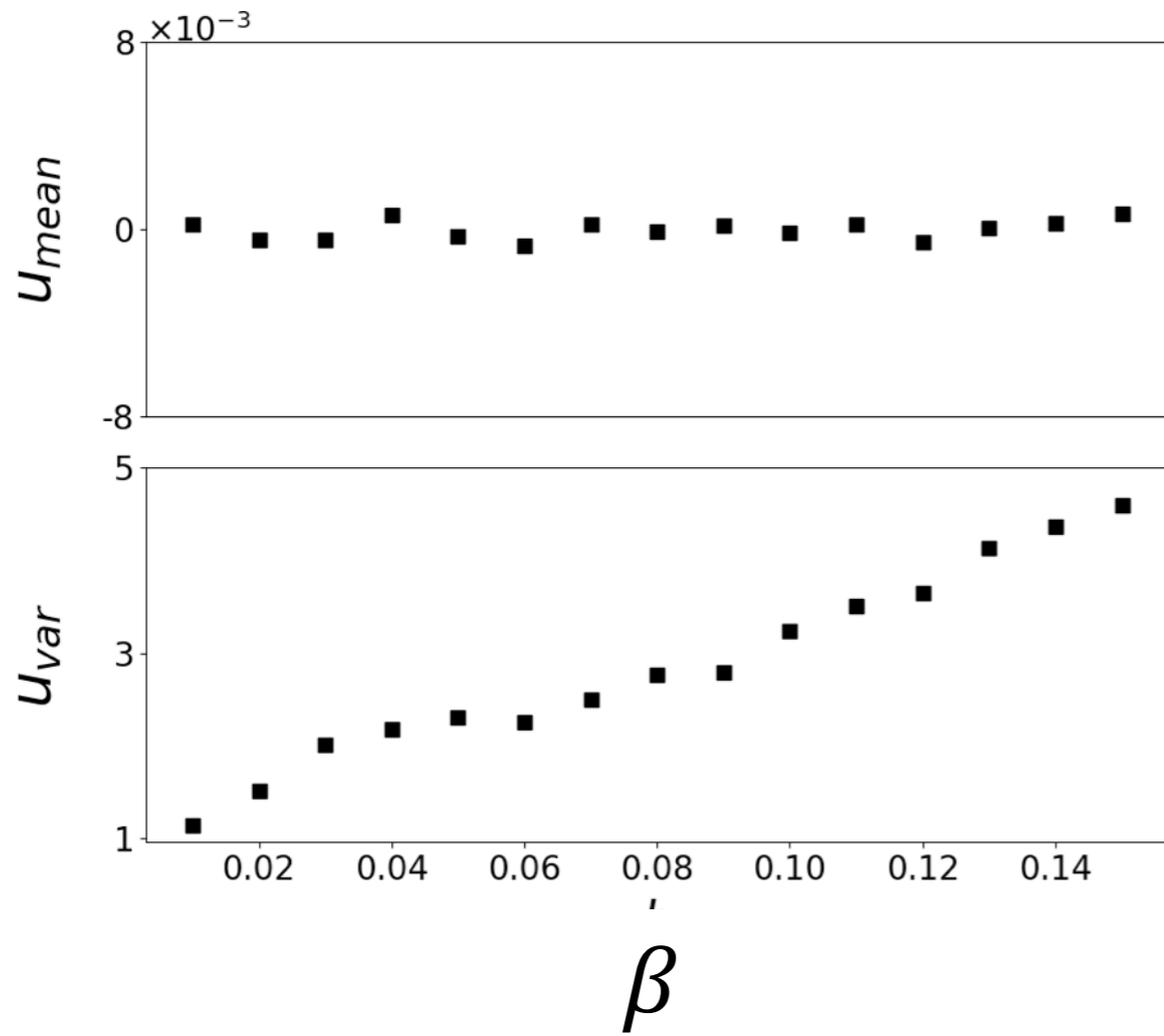
$\lambda=1$



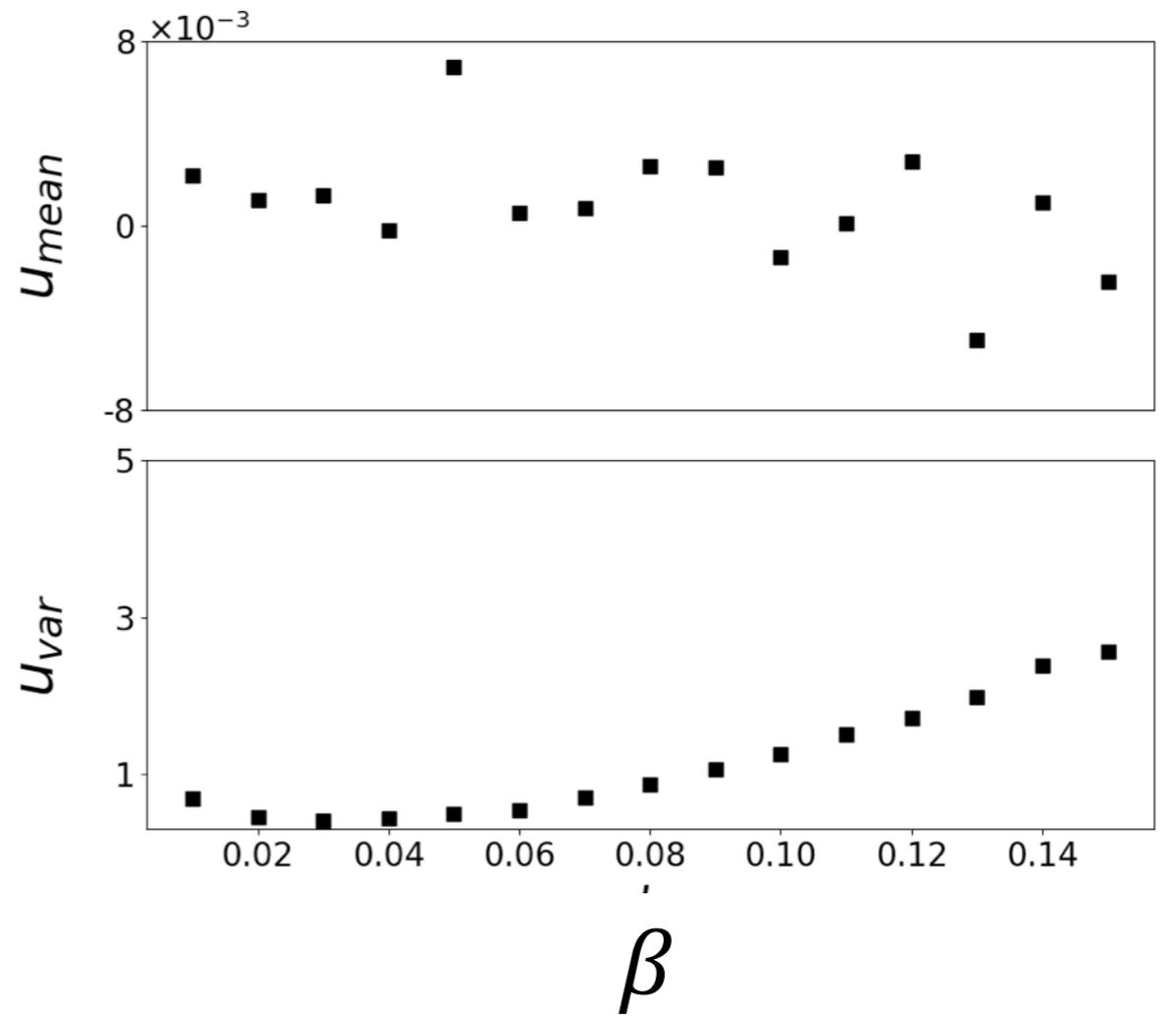
$\lambda=0$



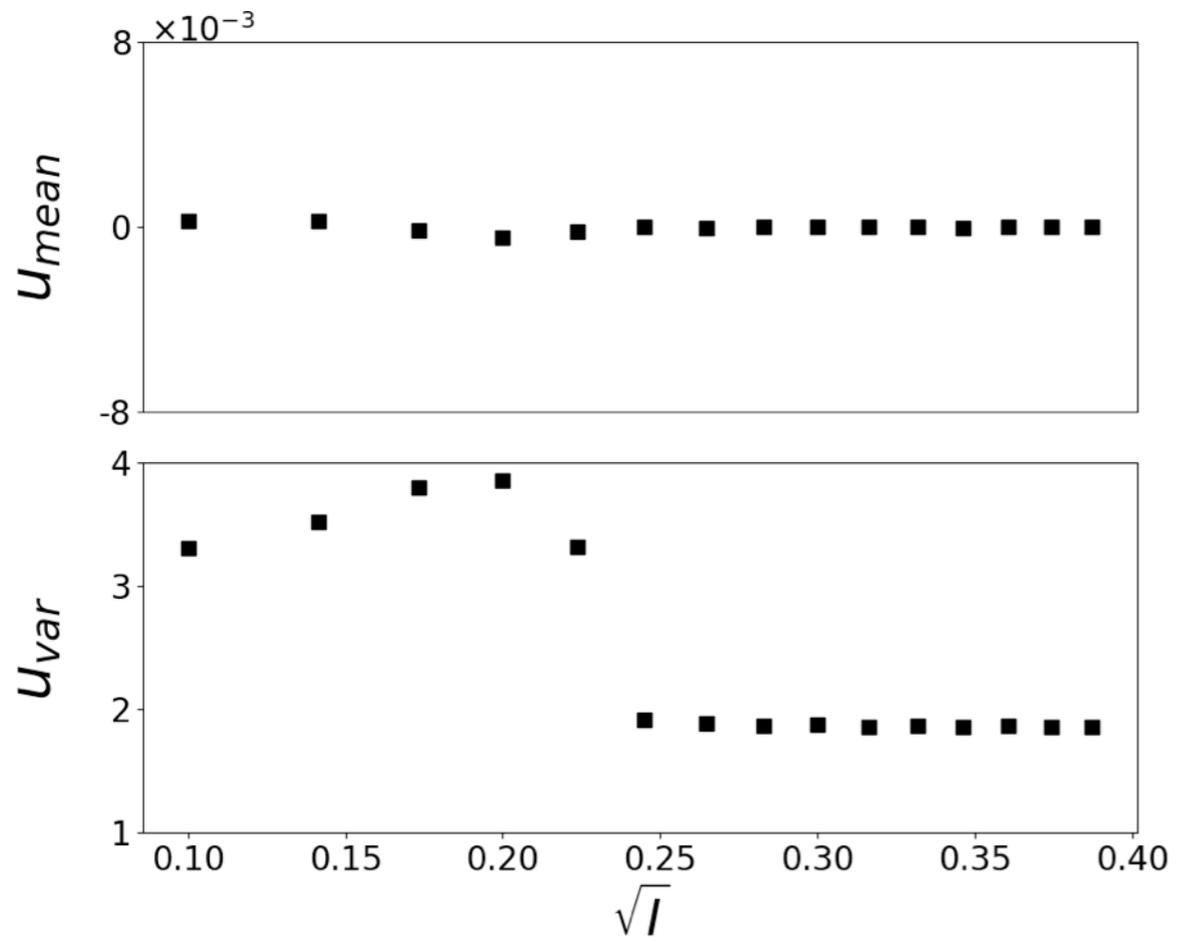
$\lambda=1$



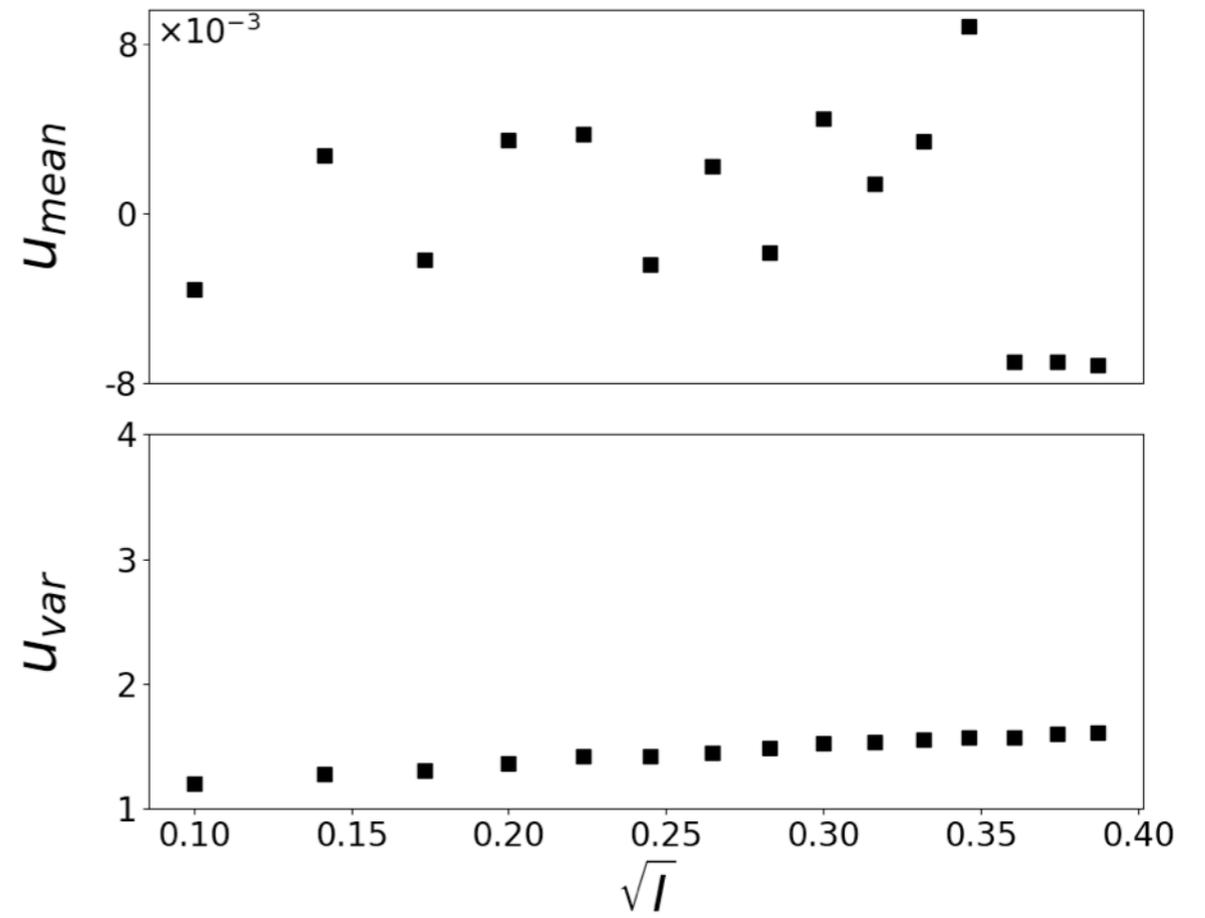
$\lambda=0$



$\lambda=1$



$\lambda=0$



Can also use adaptation instead of sum correction

$$\dot{\theta}_i = 1 - \cos \theta_i + (I + u_i - a_i)(1 + \cos \theta_i)$$

$$\dot{u}_i + \beta u_i = \beta \sum_{j,s} w_{ij} \delta(t - t_j^s(\theta_j))$$

$$\tau \dot{a}_i = u_i - a_i$$

Only needs local information

# Network revisited

$$\dot{\theta}_i = 1 - \cos \theta_i + (I + u_i)(1 + \cos \theta_i)$$

$$\dot{u}_i + \beta u_i = \beta \sum_{j,s} \left( w_{ij} - \frac{\lambda}{N} \sum_k w_{ik} \right) \delta(t - t_j^s(\theta_j))$$

Empirical density

$$\eta_j(\theta, t) = \delta(\theta - \theta_j(t))$$

$$\sum_s \delta(t - t_j^s) = \eta_j(\pi, t) \dot{\theta}_j |_{\theta_j = \pi} = 2\eta_j(\pi, t) \quad \text{Spiking rate}$$

$$\dot{\mathbf{u}}_i(t) = \beta u_i \beta u_i(t) \sum_{j,s} 2 \left( \sum_j w_{ij} \frac{\lambda}{N} \sum_k \eta_j(\pi, t) u_{ik} \right) \delta(t - t_j^s) = \mathbf{0}$$

Network mean

$$\eta(t) = \frac{1}{N} \sum_j \eta_j(t)$$

# Neurons are conserved

Exists in weak sense

$$\partial_t \eta_i(\theta, t) + \partial_\theta F_i(\theta, u_i) \eta_i(\theta, t) = 0$$

$$F_i = 1 - \cos \theta_i + (I + u_i)(1 + \cos \theta_i)$$

Regularize by integrating (averaging)

# Reformulated network

$$\partial_t \eta_i(\theta, t) + \partial_\theta F_i(\theta, u_i) \eta_i(\theta, t) = 0$$

$$\dot{u}_i(t) + \beta u_i(t) - 2\beta \sum_j w_{ij} (\eta_j(\pi, t) - \lambda \eta(\pi, t)) = 0$$

# Disorder to noise

$$\partial_t \eta_i(\theta, t) + \partial_\theta F_i(\theta, u_i) \eta_i(\theta, t) = 0$$

$$\dot{u}_i(t) + \beta u_i(t) = z_i(t)$$

$$z_i(t) = 2\beta \sum_j w_{ij} (\eta_j(\pi, t) - \lambda \eta(\pi, t))$$

$$P[w_{ij}] = \prod_{ij} \sqrt{\frac{N}{2\pi\sigma^2}} e^{-\frac{N w_{ij}^2}{2\sigma^2}} \quad P[w_{ij}] dw_{ij} \rightarrow P[z(t)][dz(t)]$$

# Reformulated network

$$\partial_t \eta_i(\theta, t) + \partial_\theta F_i(\theta, u_i) \eta_i(\theta, t) = 0$$

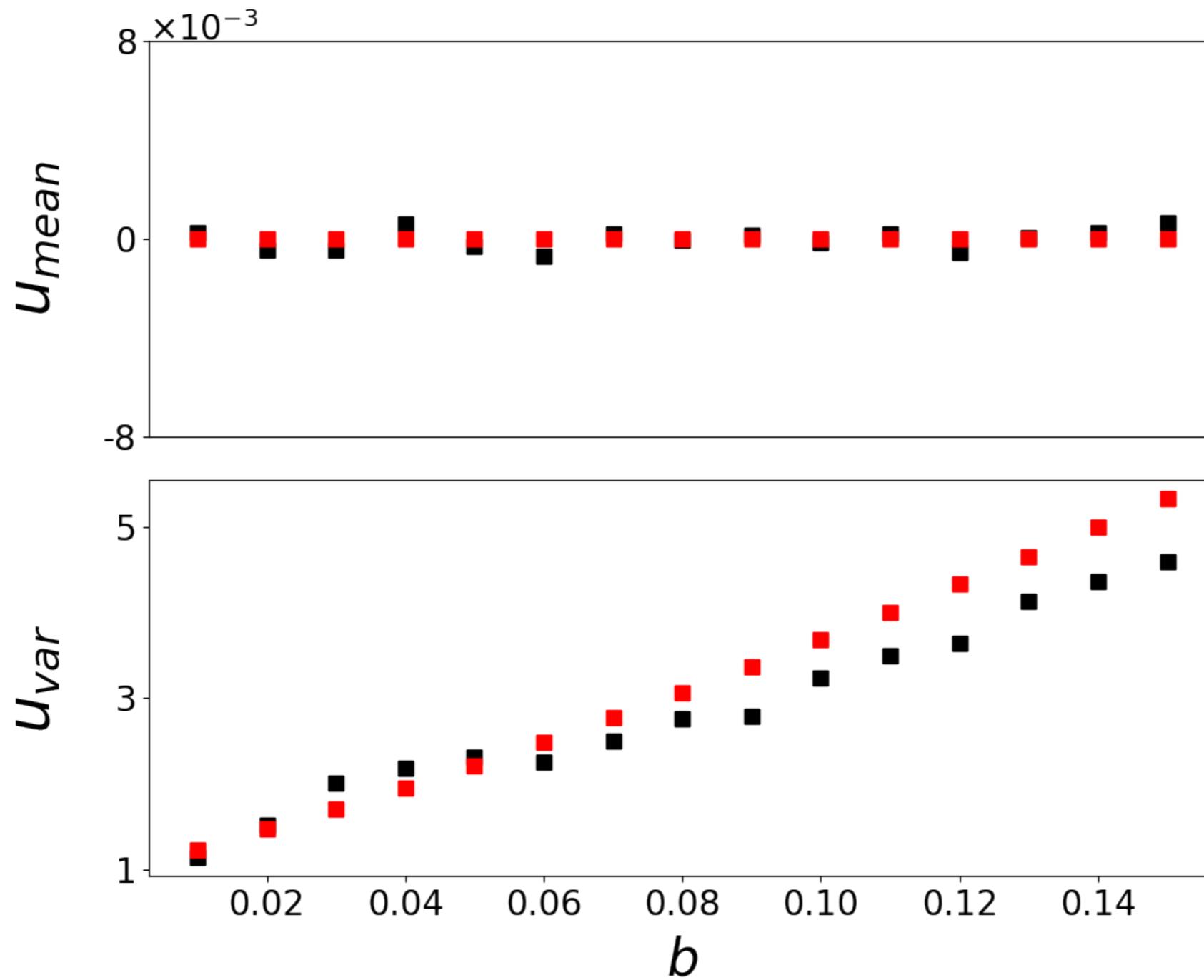
$$\dot{u}_i + \beta u_i = z_i(t)$$

$$E[z_i(t)] = 0$$

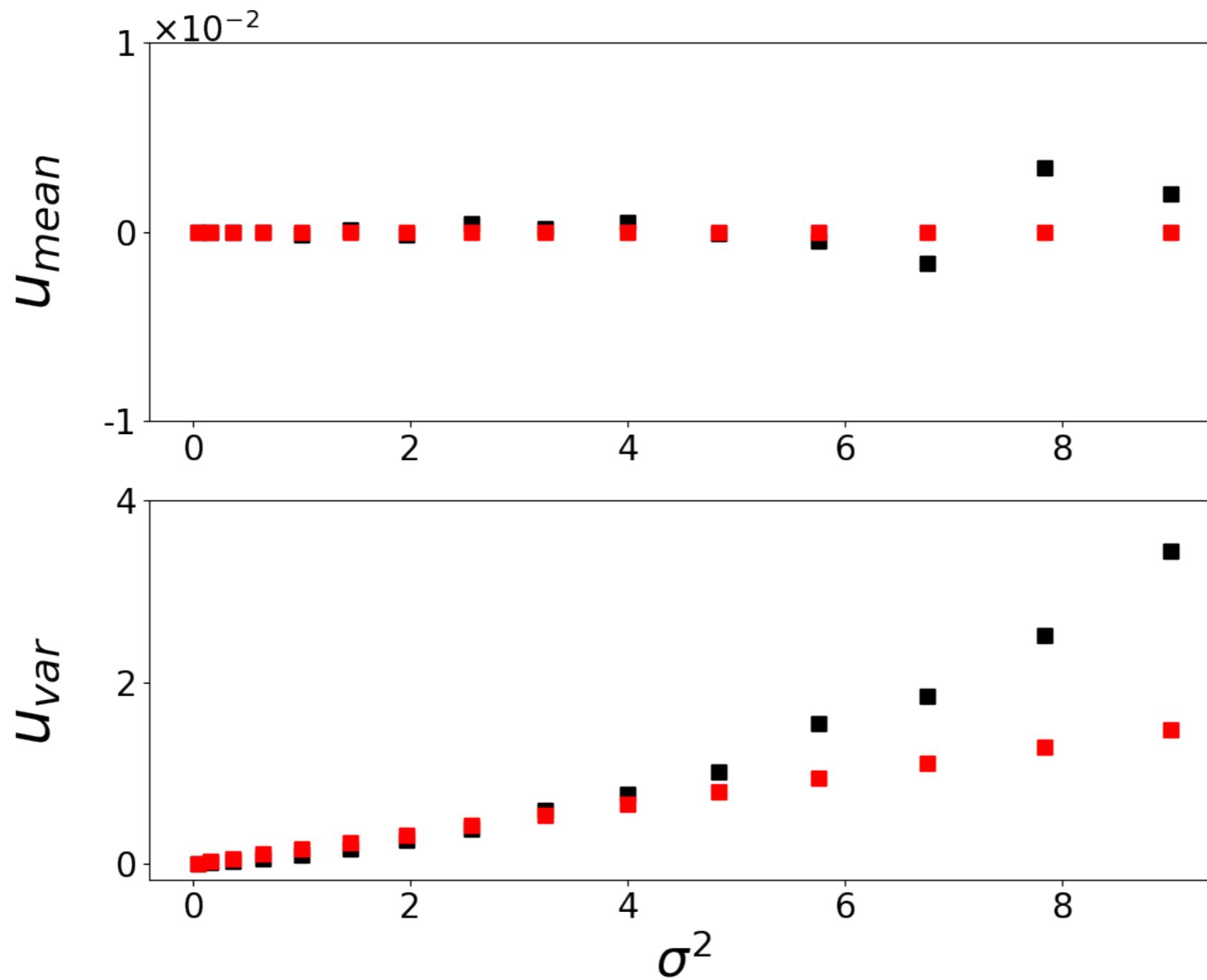
$$\text{Cov}[z_i(t), z_i(s)] = 4\beta^2 \sigma^2 \int dt ds \frac{1}{N} \sum_j \underbrace{[\eta_j(\pi, t) - \lambda \eta(\pi, t)] [\eta_j(\pi, s) - \lambda \eta(\pi, s)]}$$

Network covariance

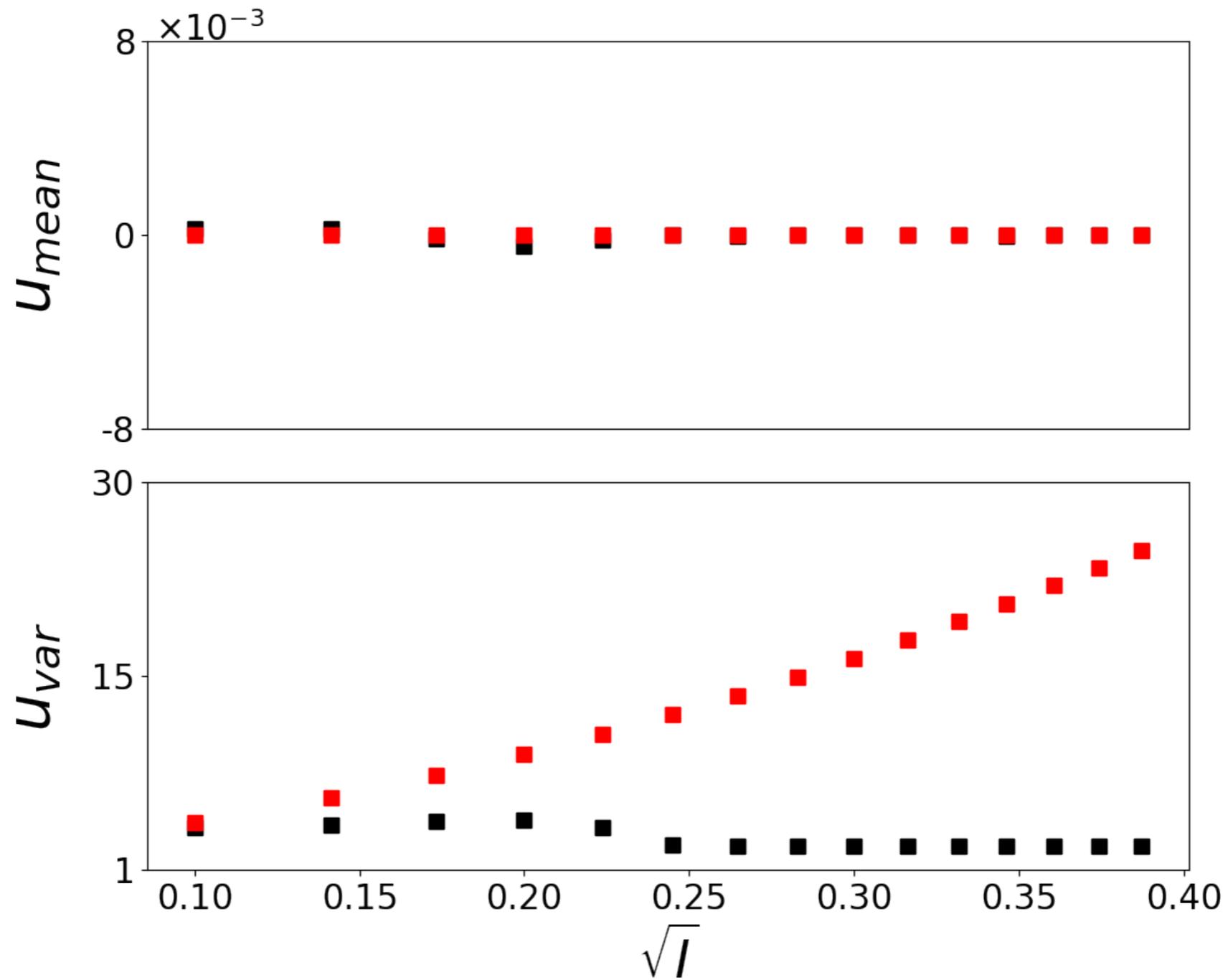
# 1st order expansion



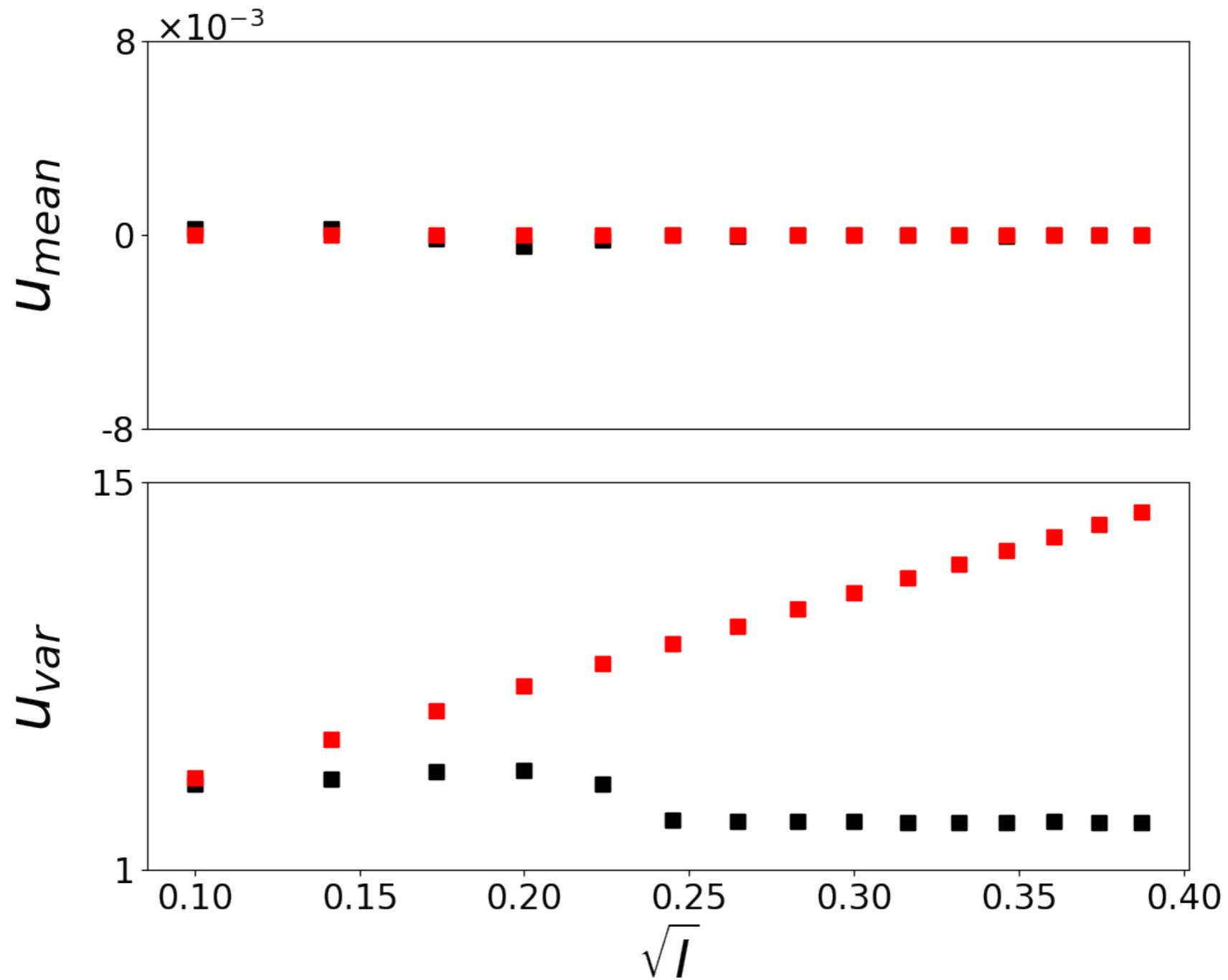
# 1st order expansion



# 1st order expansion



# OU approximation



Can we train  $w_{ij}$  so network  
does what we want?

# Network

$$\dot{\theta}_i = 1 - \cos \theta_i + (I + u_i)(1 + \cos \theta_i)$$

$$\dot{u}_i = \sum_j \beta w_{ij} r_j - \beta \sum_{j,s} w_{ij} \delta(t - t_j^s(\theta_j))$$

$$\dot{r}_j = -\beta r_j + \beta \sum_s \delta(t - t_j^s(\theta_j))$$

Goal: Train  $w_{ij}$  so  $u$  and  $r$  follow targets

# Learning

Minimize over  $w$

$$C_u(\mathbf{w}) = (\hat{\mathbf{u}} - \mathbf{u}(\mathbf{w}))^2$$

$$C_r(\mathbf{w}) = (\hat{\mathbf{r}} - \mathbf{r}(\mathbf{w}))^2$$

↑  
Targets

Super hard in general

since  $\mathbf{u}(\mathbf{w}) = \mathbf{w}\mathbf{r}$

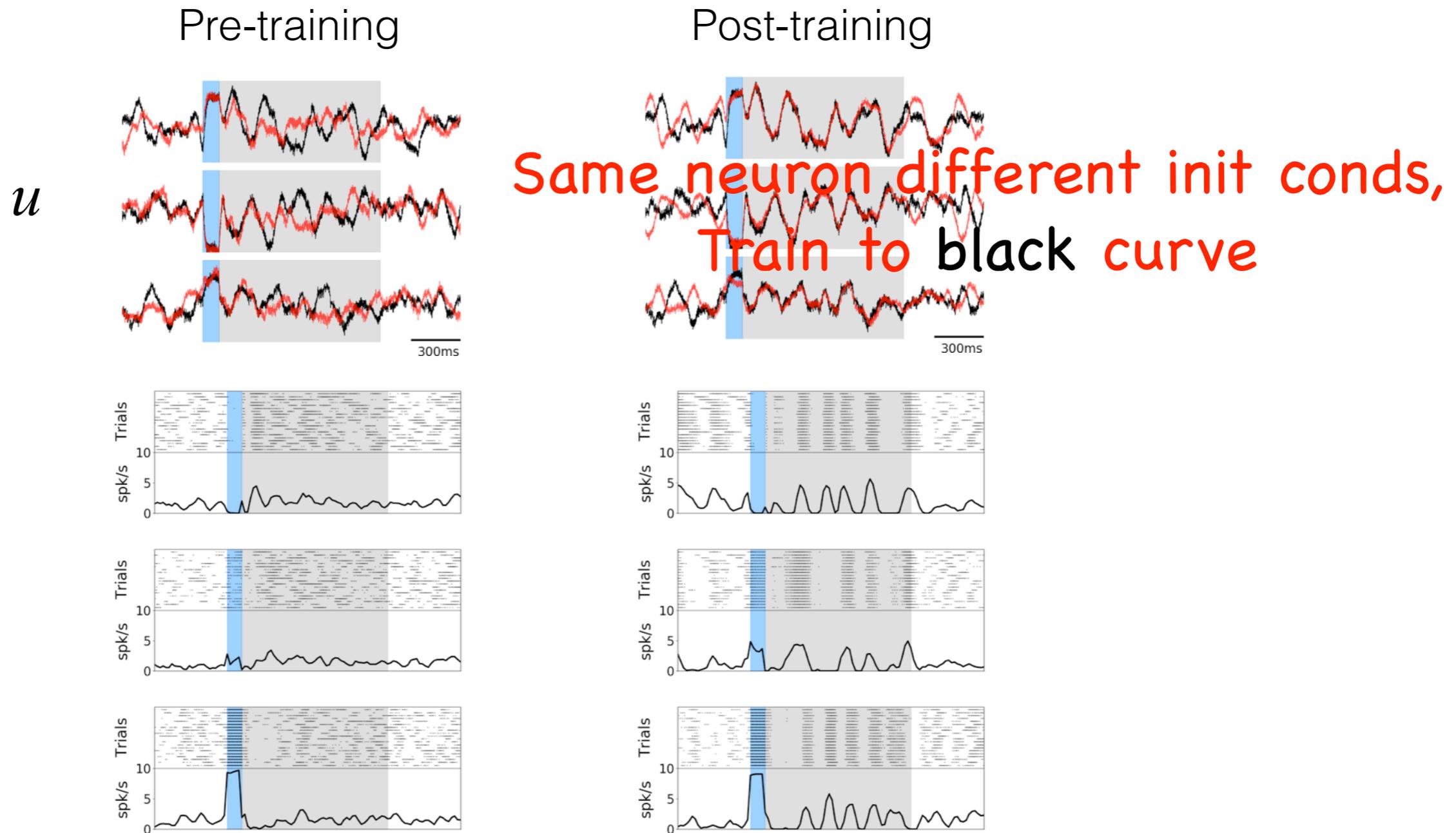
Linear in  $w$

and  $\mathbf{r}(\mathbf{w}) \approx \frac{1}{\pi} \sqrt{\mathbf{w}\mathbf{r}}$

Quasi-static approx

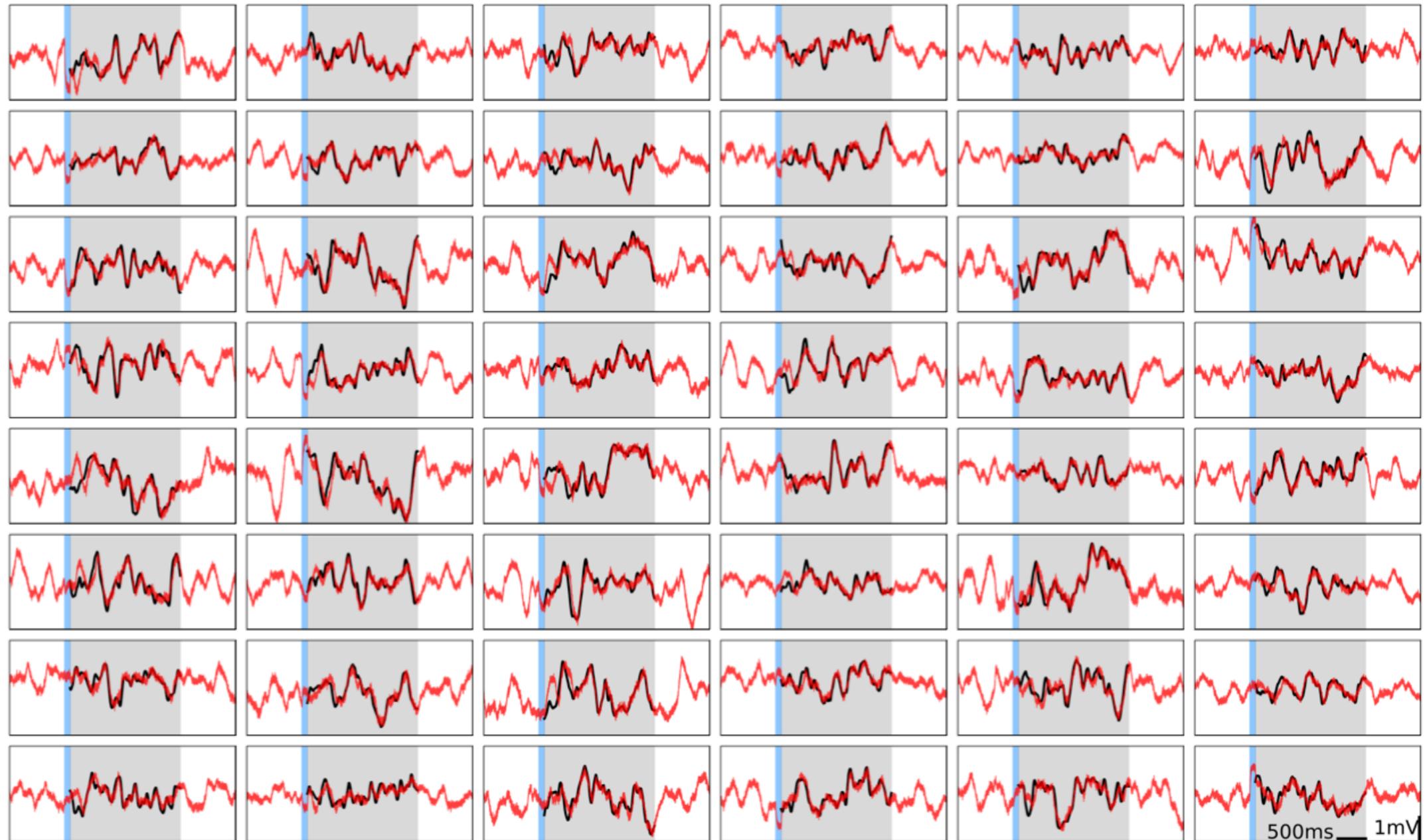
Recursive least squares or FORCE learning

# Learning innate trajectories

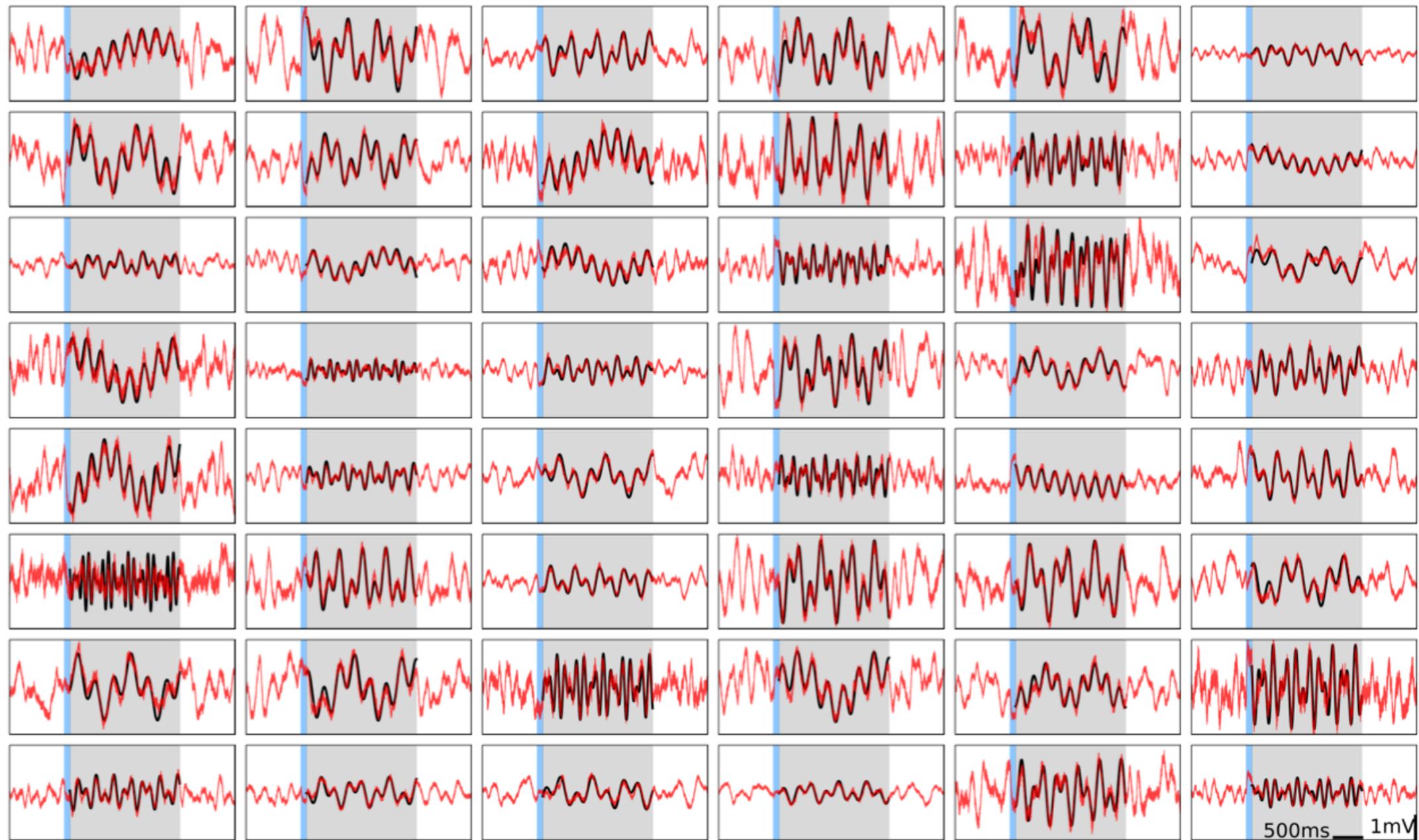


Extends Laje and Buonomano (2013) to spiking networks

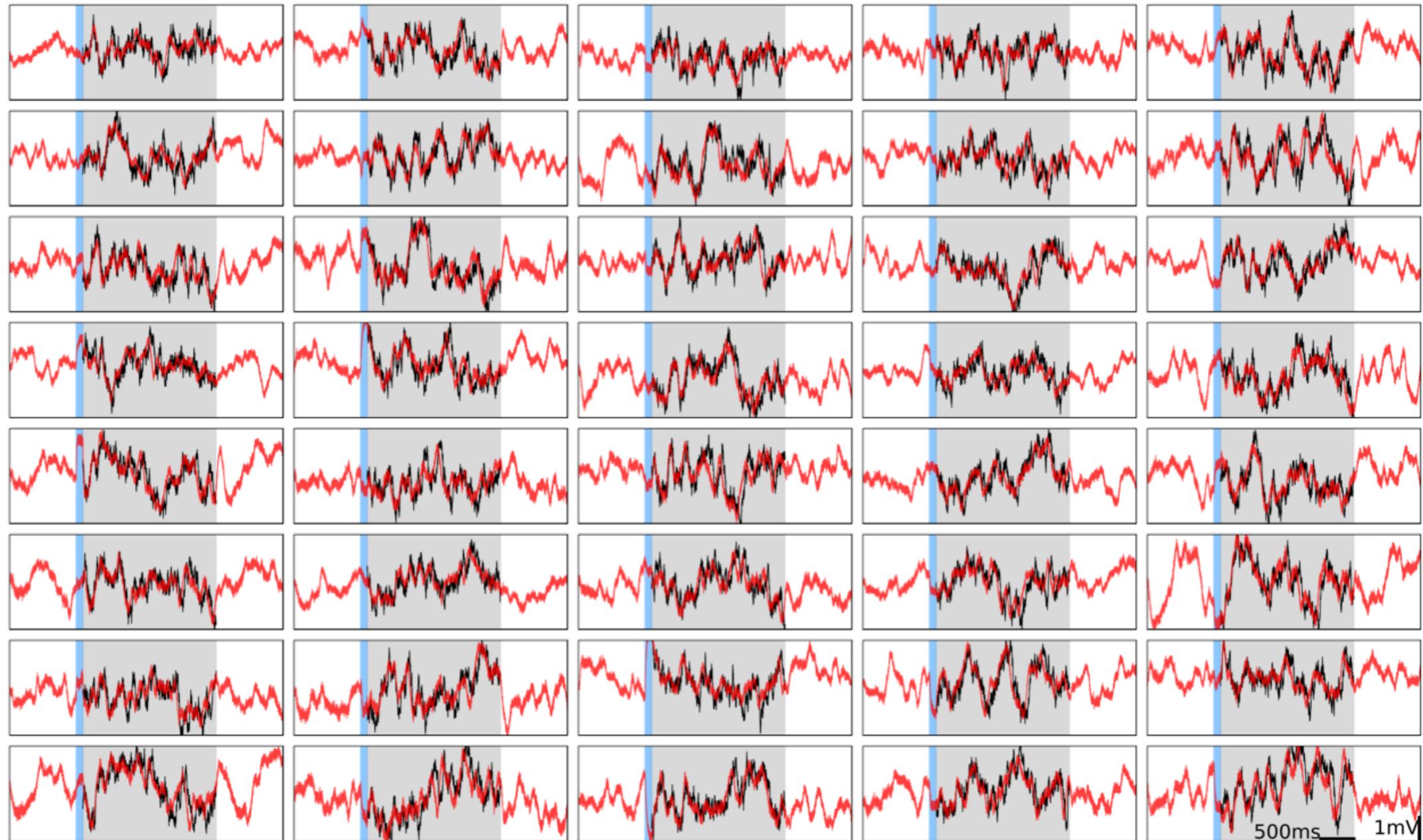
# Chaotic trajectories from another system



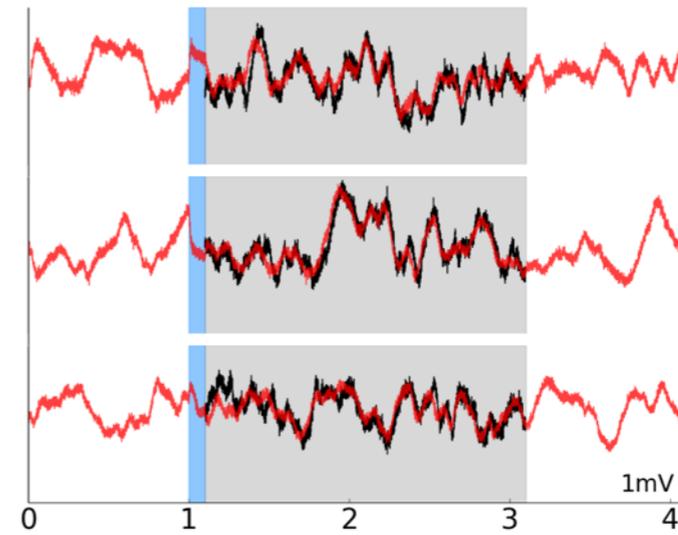
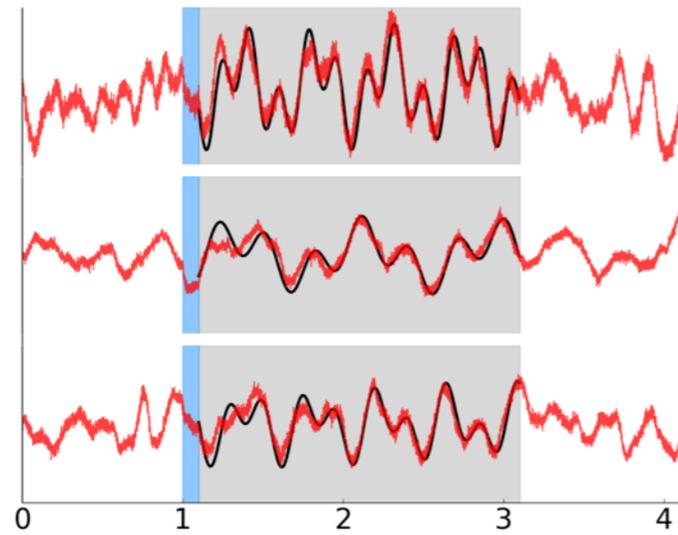
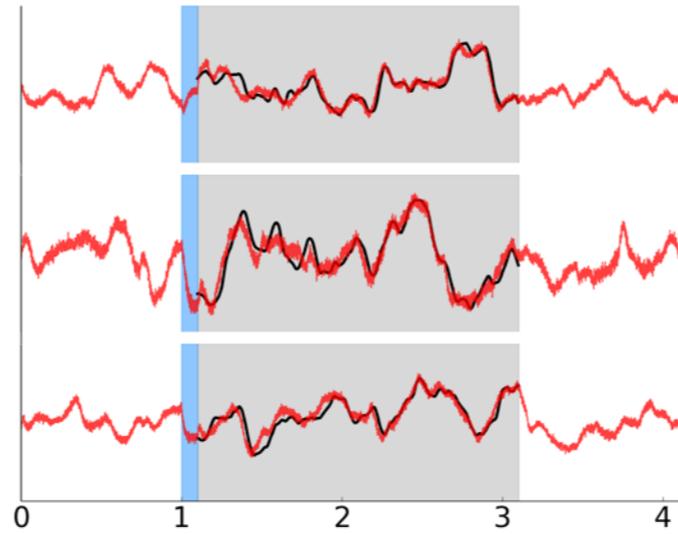
# Periodic functions



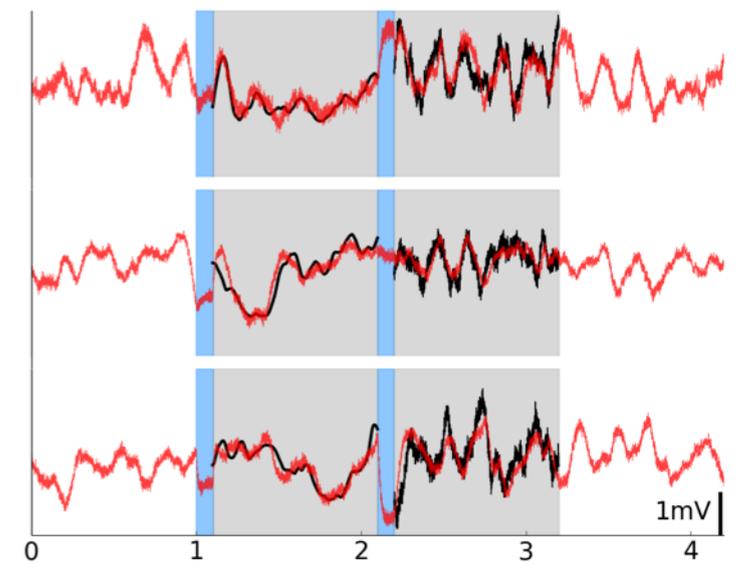
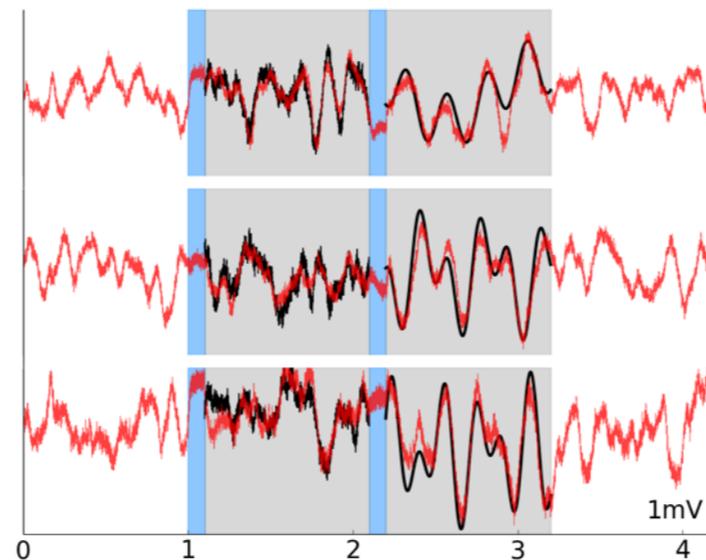
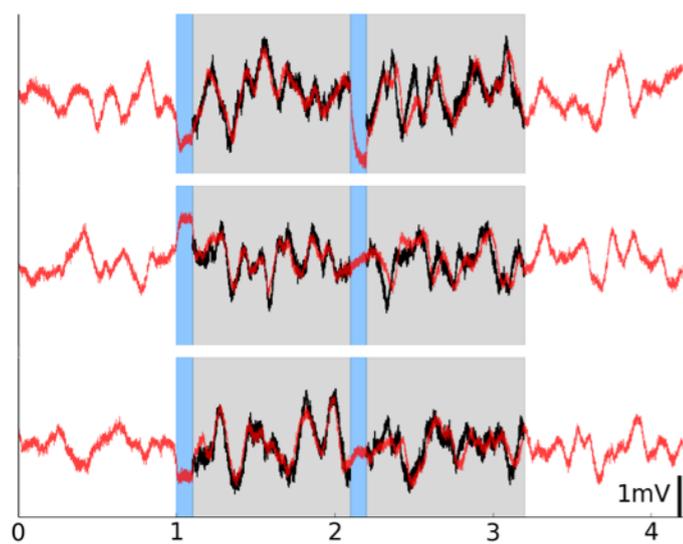
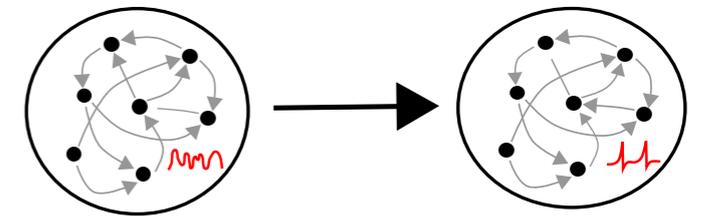
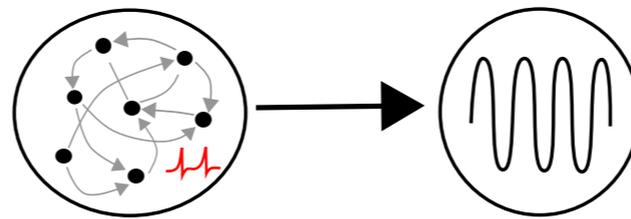
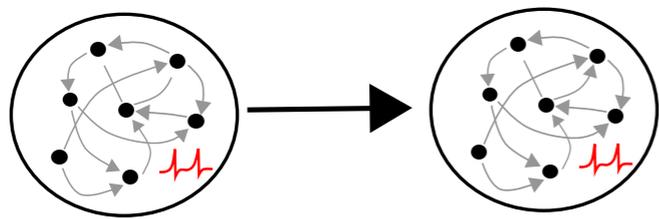
# Stochastic OU process



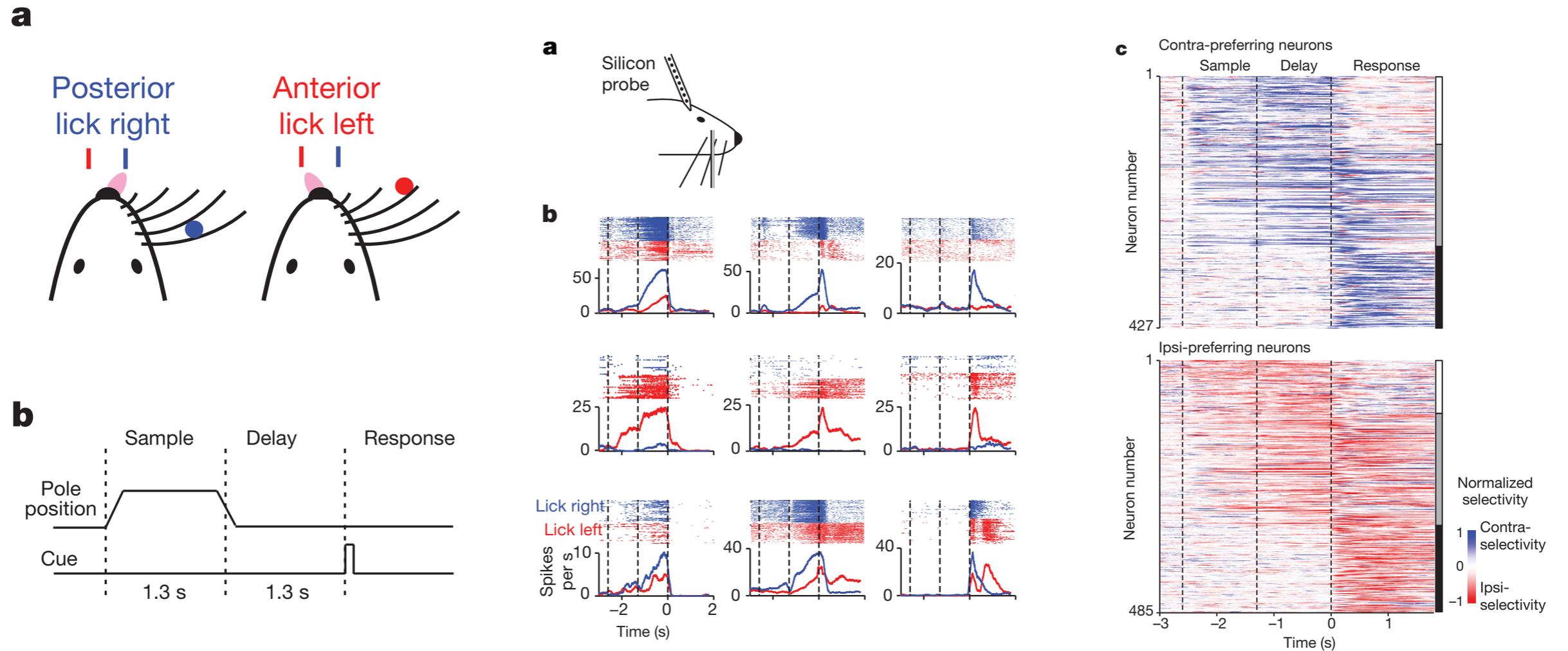
# Arbitrary combinations



# Multiple targets in one network

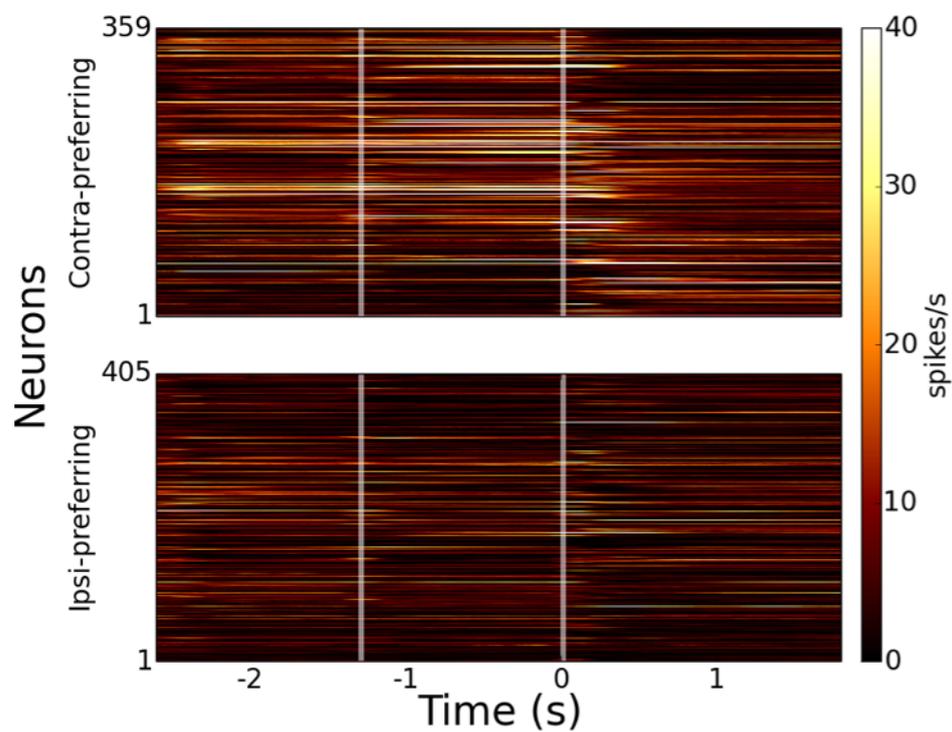


# Real cortical neurons

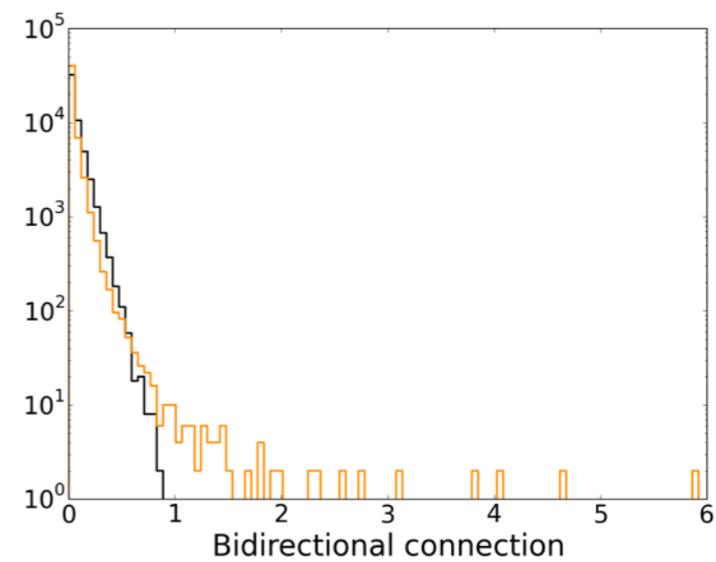
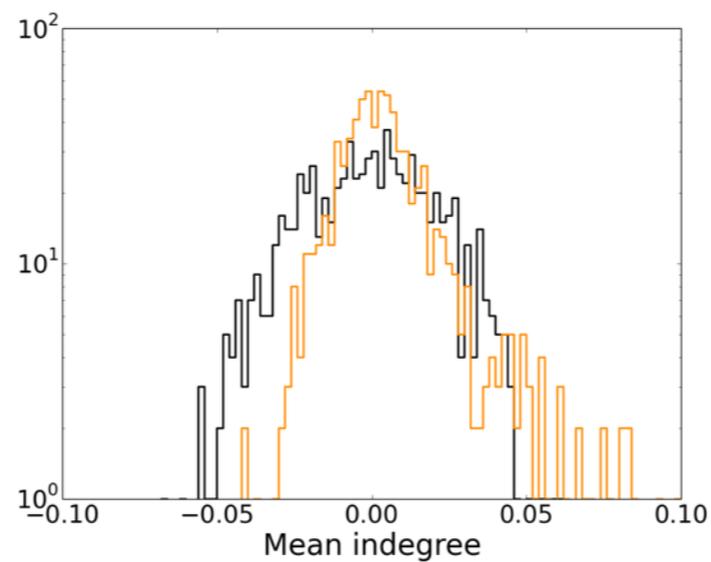
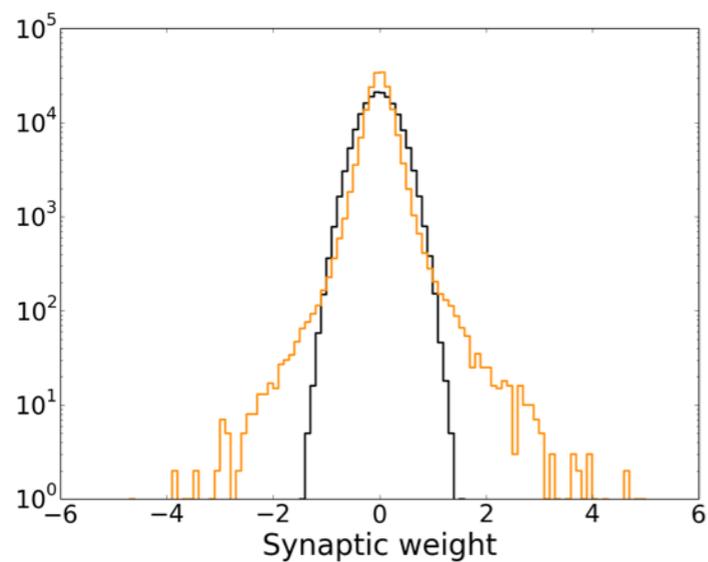
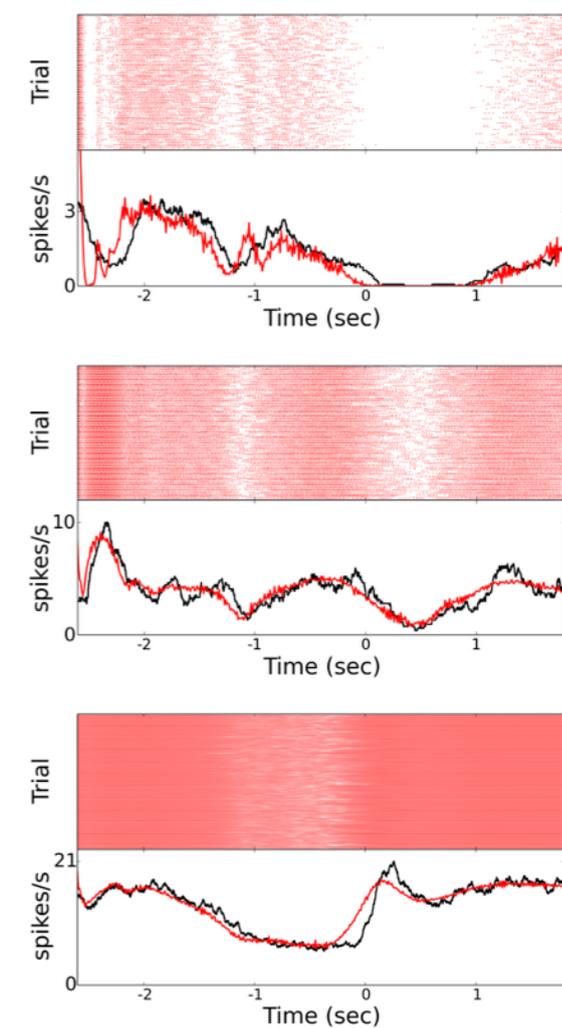
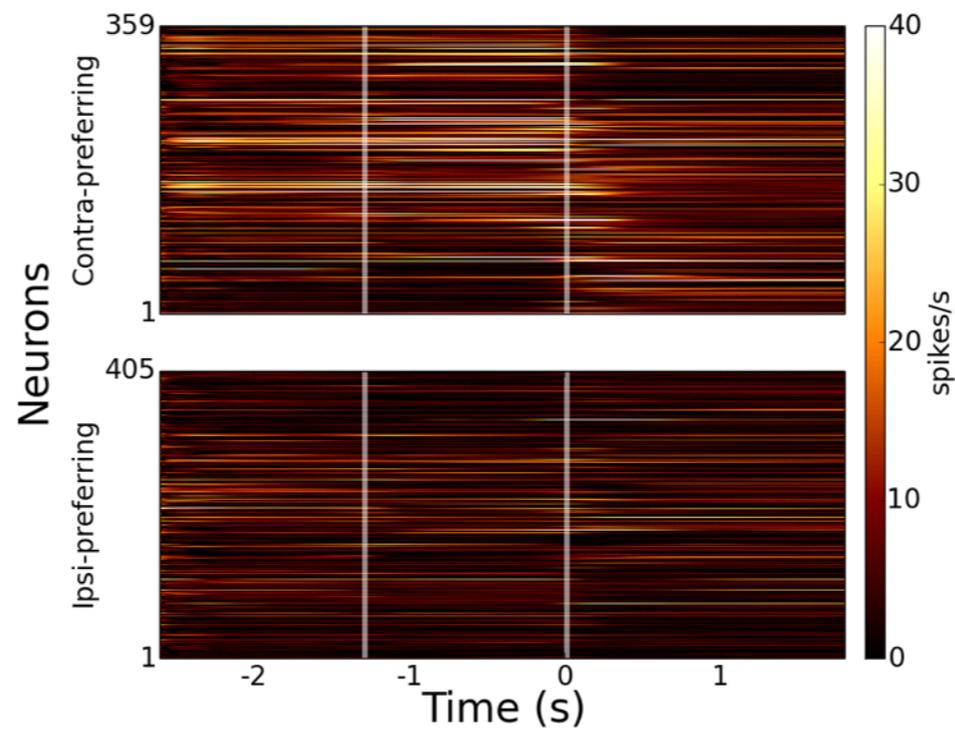


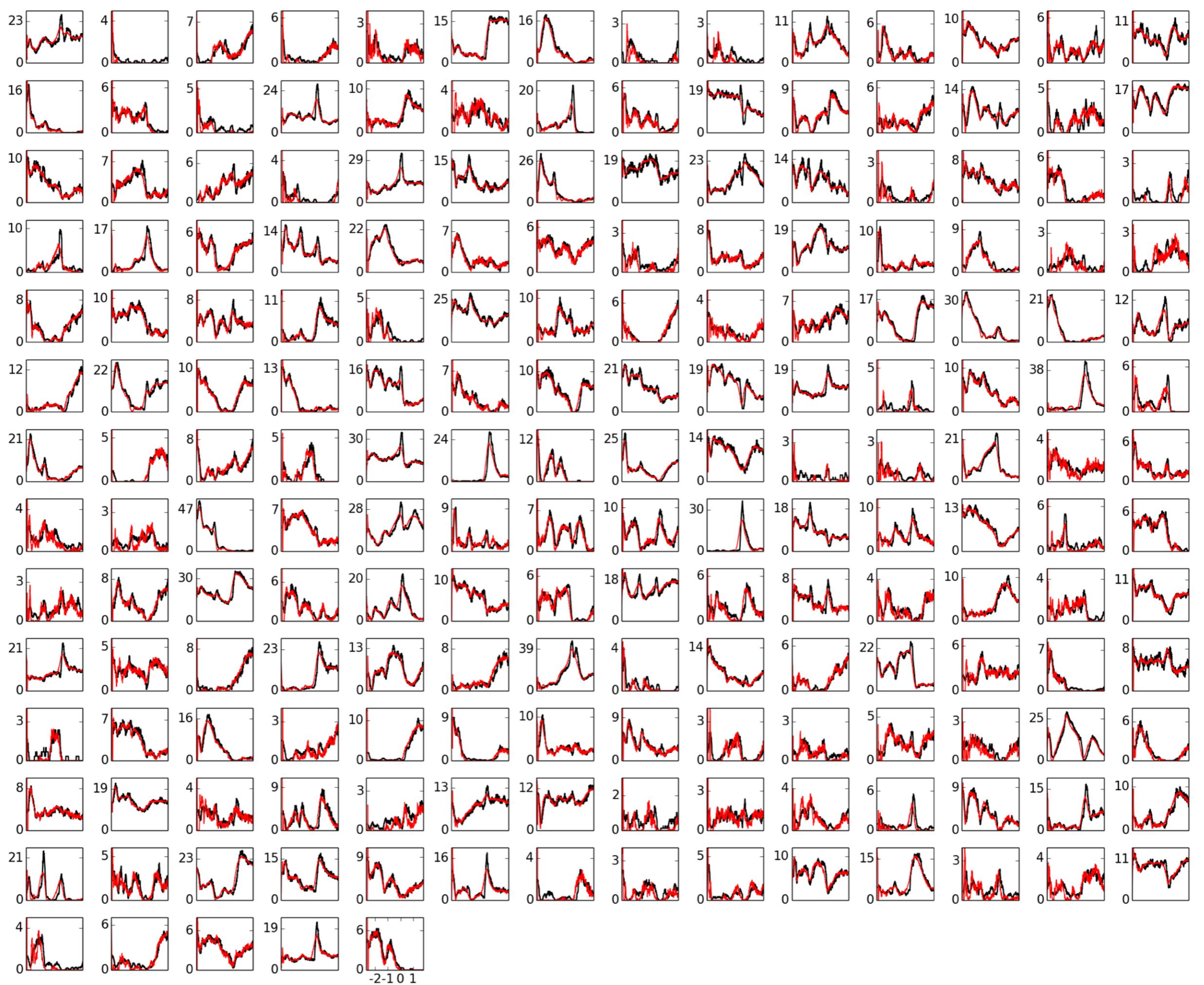
Li et al. 2015

*in-vivo* data



network model





# Universal Dynamical System?

$$\partial_t \eta_i(\theta, t) + \partial_\theta F_i(\theta, u_i) \eta_i(\theta, t) = 0$$

$$\dot{u}_i(t) + \beta u_i(t) - 2\beta \sum_j w_{ij} \eta_j(\pi, t) = 0$$

$$\mathbf{u}(t) = \mathbf{w} \varphi(u(t))$$

Conjecture: network can approximate an arbitrary set of continuous functions\*

\*under a mild set of conditions

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[Slides to appear on sciencehouse.wordpress.com](http://sciencehouse.wordpress.com)