

The Certified Reduced-Basis Method for Darcy Flows in Porous Media

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Reservoir simulation in petroleum industry

■ Uses :

- well placement, optimization of production scenarios,
- History-matching,
- Sensitivity analysis,
- Quantification of uncertainties.

■ Difficulties :

- Long simulation times (grid's size, time iterations...),
- Simulations should be rerun for different input parameters.

■ A significant part of the simulation time is spent in the resolution of the pressure equation.

- Aim of this study : build a reduced solution for this problem,
- Among all possible methods : **Reduced Basis (RB)**.

Outline

- Two-phase flow model
 - Problem statement
 - Parameterization
 - Finite volume discretization

- Reduced model for the pressure equation
 - Variational RB formulation
 - A posteriori error

- Results
 - First numerical results
 - Reduction of the computational complexity

- Conclusions

Problem statement

- Equations in $\Omega \subset \mathbb{R}^2$

$$\phi \partial_t S + \operatorname{div}(f_w(S)\mathbf{v}) = g, \quad (1)$$

$$\operatorname{div}(\mathbf{v}) = f, \quad (2)$$

$$\mathbf{v} + \lambda_T(S)\mathcal{K}\nabla P = 0, \quad (3)$$

where

$$\lambda_T(S) = \lambda_w(S) + \lambda_o(1 - S),$$

$$\lambda_\alpha(S) = \frac{kr_\alpha(S)}{\mu_\alpha}, \quad \alpha \in \{w, o\},$$

$$kr_w(S) = \left(\frac{S - S_{w,i}}{1 - S_{w,i} - S_{o,r}} \right)^2,$$

$$kr_o(S) = \left(\frac{1 - S - S_{o,r}}{1 - S_{w,i} - S_{o,r}} \right)^2,$$

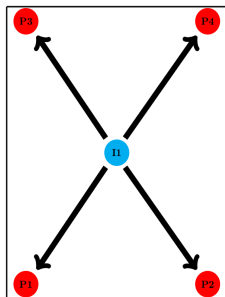
$$f_w(S) = \frac{\lambda_w(S)}{\lambda_T(S)}.$$

- Slip boundary conditions

$$\mathbf{v} \cdot \mathbf{n}|_{\partial\Omega} = 0. \quad (4)$$

- Initial condition

$$S(\cdot, 0) = 0.2 \quad (5)$$



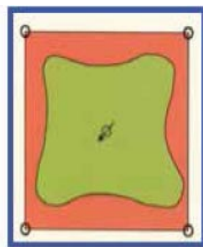
Parameterization

Goal : assess numerically the potential of the enhanced oil recovery by polymer flooding.

Variations of μ_w due to operational conditions $\mu := \mu_w, \mu \in \mathcal{P} = [1, 30]$.



Water flooding



Polymer flooding

IMPIMS scheme and finite volume discretization

- IMPIMS scheme for the time discretization

$$\phi \frac{S_\mu^{n+1} - S_\mu^n}{\Delta t} + \operatorname{div} \left(f_w(S_\mu^{n+1}, \mu) \mathbf{v}_\mu^{n+1} \right) = \mathbf{g}_\mu^{n+1}, \quad (6)$$

$$\operatorname{div}(\mathbf{v}_\mu^{n+1}) = f, \quad (7)$$

$$\mathbf{v}_\mu^{n+1} = -\lambda_T(S_\mu^n, \mu) \mathcal{K} \nabla P_\mu^{n+1}. \quad (8)$$

- A finite volume method for the space discretization (TPFA). For the pressure, one needs to solve a $\mathcal{N} \times \mathcal{N}$ linear system :

$$\mathbb{A}_\mu \mathbf{P}_\mu^{n+1} = \mathbf{f},$$

where

- $(\mathbb{A}_\mu \mathbf{P}_\mu^{n+1})_K = \sum_{\sigma=K|L} a_\sigma^n(\mu) (P_{\mu,K}^{n+1} - P_{\mu,L}^{n+1}),$
- $a_\sigma^n(\mu) =$ harmonic mean of $\lambda_T(S_\mu^n, \mu) \mathcal{K}$ on the edge $\sigma,$
- $\mathbf{f}_K = \int_K f.$

Homogeneous case

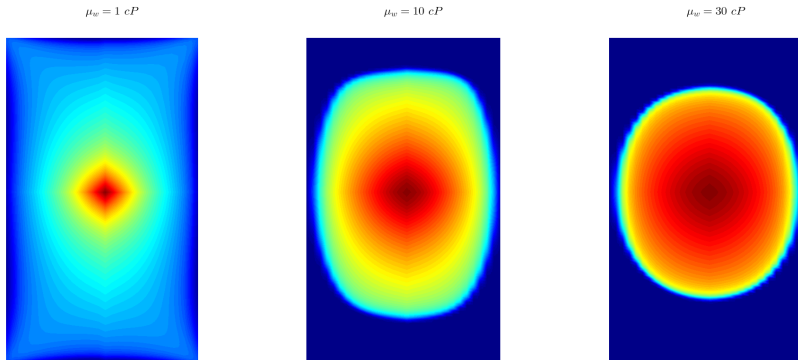
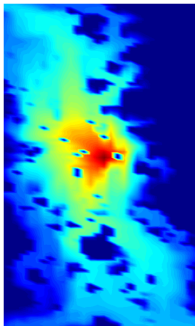


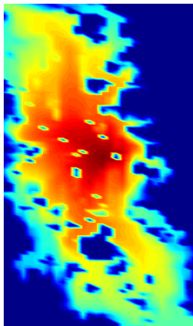
FIGURE: Water saturations for different parameter values at $T = 1,000$ days

SPE10 case¹ (layer 85)

$\mu_w = 1 \text{ cP}$



$\mu_w = 10 \text{ cP}$



$\mu_w = 30 \text{ cP}$

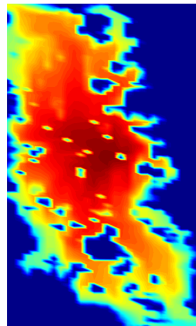


FIGURE: Water saturations for different parameter values at $T = 1,000$ days

1. Tenth SPE comparative solution project : a comparison of upscaling techniques, Christie and Blunt (2001), SPE Reserv. Eval. Eng., 4(4) :308-317.

Reduced model for the pressure equation

The pressure equation reads

$$\left\{ \begin{array}{ll} \operatorname{div} \mathbf{v}_\mu = f, & \text{in } \Omega, \\ \mathbf{v}_\mu = -a(\mu)\nabla P_\mu, & \text{in } \Omega, \\ \mathbf{v}_\mu \cdot \mathbf{n}_\Omega = 0, & \text{on } \partial\Omega, \\ \int_\Omega P_\mu = 0, & \end{array} \right. \quad (9)$$

where $a(\mu) = \lambda_T(S_\mu, \mu)\mathcal{K}$.

Difficulties :

- equation (9) is coupled with a transport equation for S_μ .
- (9) is discretized with a cell-centered finite volume scheme.
- $a(\mu)$ does not fulfill the affine parameter dependence assumption.

Idea 1.

Let us suppose S_μ (and so $a(\mu)$) known for all $\mu \in \mathcal{P}$.

Discrete Galerkin Framework

Idea 2.

Express our finite volume discretization as a variational formulation.

Let $Q_{\mathcal{N}}$ be the space of piecewise-constant L2-functions subject to zero-mean condition, i.e.,

$$\frac{1}{\mathcal{N}} \sum_K |K| P_K = 0.$$

Given $\mu \in \mathcal{P}$, consider the problem

$$\begin{aligned} \text{Find } P_{\mu}^{\mathcal{N}} \in Q_{\mathcal{N}} \text{ such that} \\ C_{\mathcal{N}}(P_{\mu}^{\mathcal{N}}, q; \mu) = L_f(q), \quad \forall q \in Q_{\mathcal{N}}, \end{aligned} \quad (10)$$

where

$$C_{\mathcal{N}}(P_{\mu}^{\mathcal{N}}, q; \mu) = \sum_{\sigma=K|L} a_{\sigma}(\mu) (P_{\mu,K}^{\mathcal{N}} - P_{\mu,L}^{\mathcal{N}}) (q_K - q_L) \text{ and } L_f(q) = \sum_K f_K q_K.$$

The space $Q_{\mathcal{N}}$ is equipped with the energy norm

$$\| \| p \| \|_{\mathcal{N}, \mu}^2 = C_{\mathcal{N}}(p, p; \mu). \quad (11)$$

The reduced problem reads

$$\begin{aligned} \text{Find } P_\mu^N \in Q_N \text{ such that} \\ C_{\mathcal{N}}(P_\mu^N, q; \mu) = L_f(q), \quad \forall q \in Q_N. \end{aligned} \quad (12)$$

The reduced basis method consists in solving a small $N \times N$ system

$$\mathbb{A}^N(\mu) \mathbf{P}_\mu^N = \mathbf{f}^N, \quad (13)$$

with

- $\mathbf{P}_\mu^N \in \mathbb{R}^N$ such that $P_\mu^N = \sum_{n=1}^N (\mathbf{P}_\mu^N)_n P_{\mu_n}$,
- $\mathbb{A}^N(\mu) \in \mathbb{R}^{N \times N}$, such that $\mathbb{A}_{m,n}^N(\mu) = \sum_{\sigma=K|L} a_\sigma(\mu) (P_{\mu_m, K}^{\mathcal{N}} - P_{\mu_m, L}^{\mathcal{N}}) (P_{\mu_n, K}^{\mathcal{N}} - P_{\mu_n, L}^{\mathcal{N}})$,
- $\mathbf{f}^N \in \mathbb{R}^N$ such that $\mathbf{f}_n^N = \sum_{K \in \mathcal{T}} P_{\mu_n, K}^{\mathcal{N}} \int_K f$.

A posteriori error estimate – first attempt

Definition 1 (Residual and associated norm).

Let $p \in Q_{\mathcal{N}}$. For all $q \in Q_{\mathcal{N}}$, define the residual

$$\langle \mathcal{R}_{\mathcal{N}}(p; \mu), q \rangle = C_{\mathcal{N}}(p, q; \mu) - L_f(q),$$

and the associated (discrete) norm

$$\|\mathcal{R}_{\mathcal{N}}(p; \mu)\|_{\mathcal{N}, *, \mu} = \sup_{q \in Q_{\mathcal{N}}} \frac{\langle \mathcal{R}_{\mathcal{N}}(p; \mu), q \rangle}{\|q\|_{\mathcal{N}, \mu}}.$$

Proposition 1 (Energy estimate).

$$\|P_{\mu}^{\mathcal{N}} - P_{\mu}^N\|_{\mathcal{N}, \mu} \leq \Delta_N^{en}(\mu) := \frac{1}{\alpha_{\mathcal{N}}(\mu)} \|\mathcal{R}_{\mathcal{N}}(P_{\mu}^N; \mu)\|_{\mathcal{N}, *, \mu} \quad (14)$$

with

$$\alpha_{\mathcal{N}}(\mu) = \inf_{q \in Q_{\mathcal{N}} \setminus \{0\}} \frac{C_{\mathcal{N}}(q, q; \mu)}{\|q\|_{\mathcal{N}, \mu}}.$$

Practical computation of error bounds

- Computing the stability factor

$$\alpha_{\mathcal{N}}(\mu) = 1, \quad \forall \mu \in \mathcal{P}$$

- Computing the norm of the residual

$$\begin{aligned} \left\| \mathcal{R}_{\mathcal{N}}(\mathbf{P}_{\mu}^N; \mu) \right\|_{\mathcal{N}, *, \mu}^2 &= (\mathbf{f} - \mathbb{A}_{\mu} \mathbb{P}^N \mathbf{P}_{\mu}^N)^t \mathbb{A}_{\mu}^{\dagger} (\mathbf{f} - \mathbb{A}_{\mu} \mathbb{P}^N \mathbf{P}_{\mu}^N) \\ &= \mathbf{f}^t \mathbb{A}_{\mu}^{\dagger} \mathbf{f} - 2\mathbf{f}^t \mathbb{A}_{\mu}^{\dagger} \mathbb{A}_{\mu} \mathbb{P}^N \mathbf{P}_{\mu}^N + (\mathbb{P}^N \mathbf{P}_{\mu}^N)^t \mathbb{A}_{\mu} \mathbb{P}^N \mathbf{P}_{\mu}^N \end{aligned}$$

Pros & cons 1.

- ✓ trivial computation of $\alpha_{\mathcal{N}}(\mu)$
- ✗ No affine parameter dependence assumption
- ✗ $\mathbb{A}_{\mu}^{\dagger}$ depends on μ

A posteriori error estimate – second attempt

Definition 2 (Norm of the residual).

Let $p \in Q_{\mathcal{N}}$, define a new dual norm as

$$\left\| \mathcal{R}_{\mathcal{N}}(p; \mu) \right\|_{\mathcal{N}, *, \mu_{ref}} = \sup_{q \in Q_{\mathcal{N}}} \frac{\langle \mathcal{R}_{\mathcal{N}}(p; \mu), q \rangle}{\|q\|_{\mathcal{N}, \mu_{ref}}}.$$

Proposition 2 (Energy estimate).

$$\|P_{\mu}^{\mathcal{N}} - P_{\mu}^N\|_{\mathcal{N}, \mu_{ref}} \leq \Delta_N^{en}(\mu) := \frac{1}{\alpha_{\mathcal{N}}(\mu)} \left\| \mathcal{R}_{\mathcal{N}}(P_{\mu}^N; \mu) \right\|_{\mathcal{N}, *, \mu_{ref}} \quad (15)$$

with

$$\alpha_{\mathcal{N}}(\mu) = \inf_{q \in Q_{\mathcal{N}} \setminus \{0\}} \frac{C_{\mathcal{N}}(q, q; \mu)}{\|q\|_{\mathcal{N}, \mu_{ref}}}.$$

Pros & cons 2.

- ✓ A_{μ}^{\dagger} no longer depends on μ
- ✗ complex evaluation of $\alpha_{\mathcal{N}}(\mu)$

Numerical results

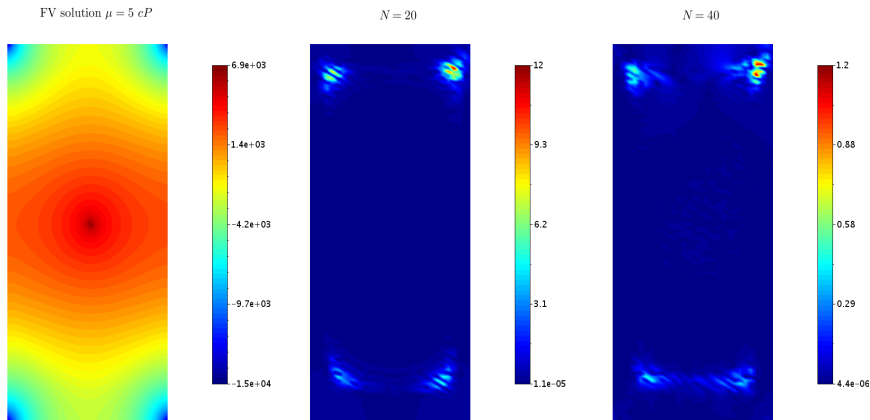
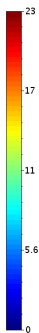
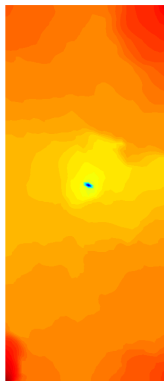
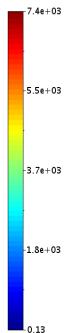


FIGURE: Representative solution and pointwise error for two values of N (homogeneous case).

FV solution $\mu = 5 \text{ cP}$



$N = 20$



$N = 40$

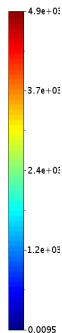
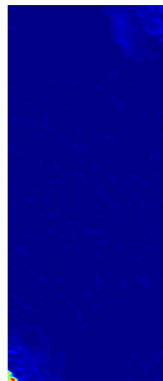
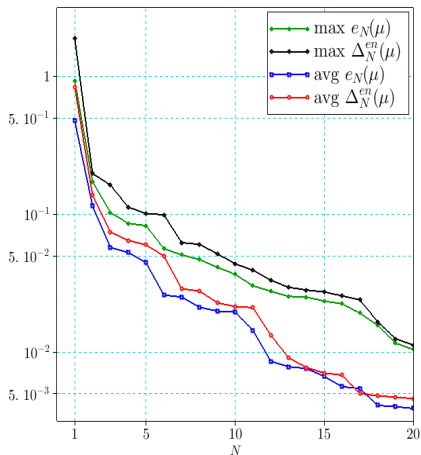


FIGURE: Representative solution and pointwise error for two values of N (SPE10 case).

Homogeneous



SPE10 – layer 85

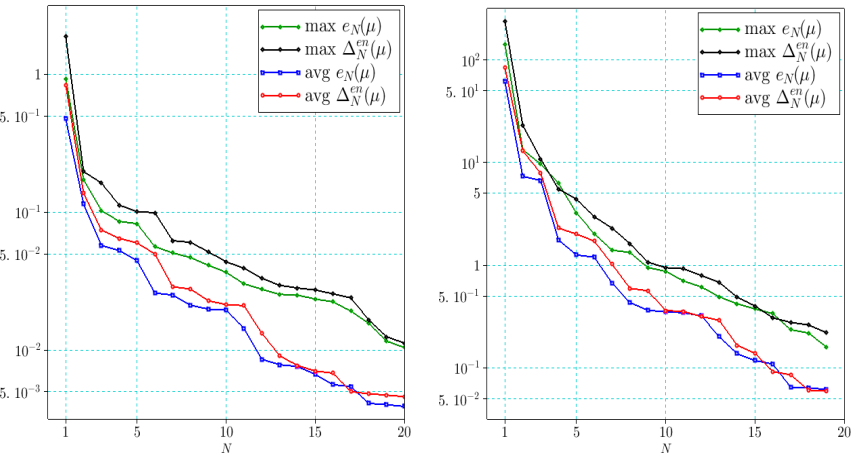


FIGURE: A posteriori error bound. Comparison of the maximum and average exact error $\|P_\mu^{\mathcal{N}} - P_\mu^N\|_\mu$ and the estimator $\Delta_N^{en}(\mu)$ ($\#\Xi_{train} \approx 300$).

Reduction of the computational complexity

To solve

$$\mathbb{A}^N(\mu)\mathbf{P}_\mu^N = \mathbf{f}^N, \quad \forall \mu \in \mathcal{D},$$

one needs to build \mathbb{A}^N whose coefficients are

$$\mathbb{A}_{m,n}^N(\mu) = \sum_{\sigma=K|L} a_\sigma(\mu) (P_{\mu_m,K}^{\mathcal{N}} - P_{\mu_m,L}^{\mathcal{N}}) (P_{\mu_n,K}^{\mathcal{N}} - P_{\mu_n,L}^{\mathcal{N}}).$$

Idea 3.

Replace $a(\mu)$ with a collateral affine expansion $a_M(\mu) = \sum_{m=1}^M \Theta_m(\mu) \zeta_m$ using the Empirical Interpolation Method^a to obtain

$$\mathbb{A}_{m,n}^{N,M}(\mu) = \sum_{m=1}^M \left(\sum_{\sigma=K|L} \zeta_{m,\sigma} (P_{\mu_m,K}^{\mathcal{N}} - P_{\mu_m,L}^{\mathcal{N}}) (P_{\mu_n,K}^{\mathcal{N}} - P_{\mu_n,L}^{\mathcal{N}}) \right) \Theta_m(\mu). \quad (16)$$

a. An 'empirical interpolation' method : application to efficient reduced-basis discretization of partial differential equations, Barrault, Maday, Nguyen and Patera (2004), C. R. Acad. Sci. Paris, Ser. I, 339(9) :667-672.

EIM-RB a posteriori error estimate

Define the residual

$$\left\langle \mathcal{R}_M(P_\mu^{N,M}; \mu), q \right\rangle = C_{\mathcal{N}}(P_\mu^{N,M}, q; a_M(\mu)) + L_f(q), \quad \forall q \in Q_{\mathcal{N}}.$$

Proposition 3.

The following a posteriori error estimate holds

$$\|P_\mu^{\mathcal{N}} - P_\mu^{N,M}\|_{\mathcal{N}, \mu_{ref}} \leq \frac{1}{\alpha_{\mathcal{N}}(\mu)} \left(\|\mathcal{R}_M(P_\mu^{N,M}; \mu)\|_{\mathcal{N}, *, \mu_{ref}} + \gamma(\mu) \delta_a(\mu) \right) \quad (17)$$

where

$$\delta_a(\mu) = \|a(\mu) - a_M(\mu)\|_{L^\infty(\Omega)}, \quad \gamma(\mu) = \sup_{q \in Q_{\mathcal{N}}} \frac{C_{\mathcal{N}}(P_\mu^{N,M}, q; 1)}{\|q\|_{\mathcal{N}, \mu_{ref}}}$$

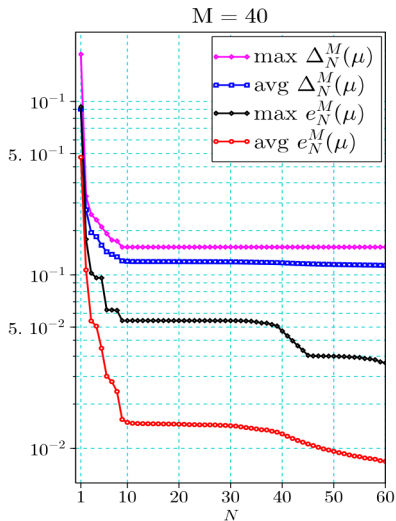
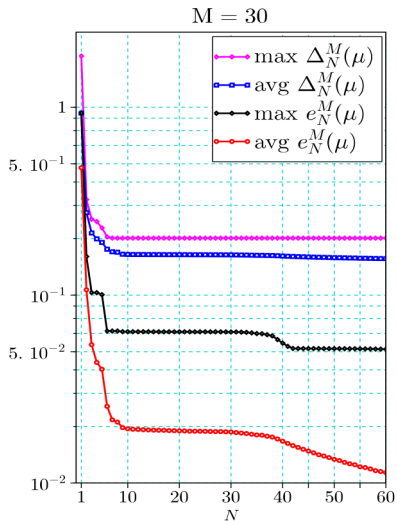


FIGURE: Convergence of the collateral reduced-basis approximation for the homogeneous example.

Conclusions and future works

■ Results

- Reduction of the pressure problem (elliptic) with non-affine dependence in the parameter.
- Certification of the RB model (a posteriori error estimate in energy norm).
- Efficient implementation of the RB method, i.e. the reduced problems can be constructed in complexity independent of \mathcal{N} .
- Certification of the RB-EIM model.

■ Future works

- Improvement of the efficiency of the a posteriori error estimate for the highly heterogenous case.
- Adapt this procedure to reduce the collection of all pressure equations.
- Consider more complex parameterizations (multi-dimensional parameter).

Thank you for your attention
Any questions?