





A posteriori error control for the binary Mumford–Shah model

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 u_0



Binary Mumford–Shah model $\theta_1, \theta_2 \in L^1(\Omega)$

$$E[\mathcal{O}] = \int_{\mathcal{O}} \theta_1 \, \mathrm{d}x + \int_{\Omega \setminus \mathcal{O}} \theta_2 \, \mathrm{d}x + \operatorname{Per}[\mathcal{O}]$$





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$$E[\chi] = \int_{\Omega} \theta_1 \chi + \theta_2 (1 - \chi) \,\mathrm{d}x + |\mathrm{D}\chi|(\Omega)$$









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• $\theta_i = \frac{1}{\nu}(c_i - u_0)^2$ (i = 1, 2) for weight parameter $\nu > 0$









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 $\theta_i = \frac{1}{\nu} (c_i - u_0)^2 \ (i = 1, 2) \text{ for weight parameter } \nu > 0$ $c_1 = (\int_\Omega \chi \, \mathrm{d}x)^{-1} \int_\Omega \chi u_0 \, \mathrm{d}x, \ c_2 = (\int_\Omega 1 - \chi \, \mathrm{d}x)^{-1} \int_\Omega (1 - \chi) u_0 \, \mathrm{d}x$

The binary Mumford–Shah model (cont.)



$$E[\chi, c_1, c_2] = \int_{\Omega} \theta_1 \chi + \theta_2 (1 - \chi) \,\mathrm{d}x + |\mathrm{D}\chi|(\Omega)$$

minimize E over the set $\chi \in BV(\Omega, \{0, 1\})$ (c_1, c_2 fixed)

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- thresholding of the relaxed solution and cut out argument

Convex relaxation and thresholding - CEN



Idea Relax range of χ to [0,1]

[Nikolova, Esedoglu, Chan '06]

$$E_{\mathsf{CEN}}[u] = \int_{\Omega} u\theta_1 \, \mathrm{d}x + \int_{\Omega} (1-u) \, \theta_2 \, \mathrm{d}x + |\mathrm{D}u|(\Omega).$$

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Theorem

where [u > s] is the s-superlevel set of u, i.e. $\{x : u(x) > s\}$.

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$$\begin{split} u^* \in \mathop{\mathrm{argmin}}_{u \in BV(\Omega,[0,1])} E_{\mathsf{CEN}}[u] & \Rightarrow \quad [u^* > s] \in \mathop{\mathrm{argmin}}_{\chi \in BV(\Omega,\{0,1\})} E[\chi] \\ & \text{for all a.e. } s \in [0,1], \end{split}$$

where [u > s] is the s-superlevel set of u, i.e. $\{x : u(x) > s\}$.

- ✓ $BV(\Omega, [0, 1])$ convex
- $\pmb{\times}~ E_{\mathsf{CEN}}$ convex, but not uniformly convex in u



Uniformly convex approach

$$E^{\mathsf{rel}}[u] = \int_{\Omega} u^2 \theta_1 \, \mathrm{d}x + \int_{\Omega} (1-u)^2 \, \theta_2 \, \mathrm{d}x + |\mathrm{D}u|(\Omega)$$



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Theorem

[Chambolle/Darbon '08][B. SSVM '09]

Let $\theta_1, \theta_2 \in L^1(\Omega)$, $\theta_1, \theta_2 \ge 0$ a.e.. Then,

- E^{rel} has a unique minimizer on $BV(\Omega)$.
- $u = \underset{v \in BV(\Omega)}{\operatorname{argmin}} E^{\mathsf{rel}}[v] \Rightarrow \chi_{[u>0.5]} \in \underset{\chi \in BV(\Omega, \{0,1\})}{\operatorname{argmin}} E[\chi].$ Moreover, $u(x) \in [0, 1]$ for a.e. $x \in \Omega$.



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- E^{rel} has a unique minimizer on $BV(\Omega)$.
- $\begin{array}{l} \bullet \ u = \mathop{\mathrm{argmin}}_{v \in BV(\Omega)} E^{\mathsf{rel}}[v] \Rightarrow \chi_{[u > 0.5]} \in \mathop{\mathrm{argmin}}_{\chi \in BV(\Omega, \{0,1\})} E[\chi] \,. \\ \\ \text{Moreover, } u(x) \in [0,1] \text{ for a.e. } x \in \Omega. \end{array}$
- ✓ $BV(\Omega)$ convex (even unconstrained)
- \checkmark E_{UC} uniformly convex in u



Proof sketch:

[Chambolle/Darbon '09]

• $E^{\mathsf{rel}}[\min\{\max\{0, v\}, 1\}] \le E^{\mathsf{rel}}[v]$ for any $v \in BV(\Omega)$.



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- $\blacksquare E^{\mathsf{rel}}[\min\{\max\{0,v\},1\}] \le E^{\mathsf{rel}}[v] \text{ for any } v \in BV(\Omega).$
- $\Psi(x,t) := t^2 \theta_1(x) + (1-t)^2 \theta_2(x), \ C_{\Psi} := \int_{\Omega} \Psi(x,0) \, \mathrm{d}x.$

$$\int_{\Omega} \Psi(x, u) \, \mathrm{d}x = \int_{\Omega} \Psi(x, 0) \, \mathrm{d}x + \int_{0}^{1} \int_{\Omega} \partial_{t} \Psi(x, s) \chi_{[u > s]} \, \mathrm{d}x \, \mathrm{d}s$$



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Proof sketch: Chambolle/Darbon '09 • $E^{\mathsf{rel}}[\min\{\max\{0, v\}, 1\}] \leq E^{\mathsf{rel}}[v]$ for any $v \in BV(\Omega)$. • $\Psi(x,t) := t^2 \theta_1(x) + (1-t)^2 \theta_2(x), \ C_{\Psi} := \int_{\Omega} \Psi(x,0) \, \mathrm{d}x.$ $\int_{\Omega} \Psi(x, u) \, \mathrm{d}x = \int_{\Omega} \Psi(x, 0) \, \mathrm{d}x + \int_{\Omega}^{1} \int_{\Omega} \partial_t \Psi(x, s) \chi_{[u>s]} \, \mathrm{d}x \, \mathrm{d}s$ $h_1 \leq h_2 \text{ a.e., } \chi_i \in \operatorname*{argmin}_{\chi \in BV(\Omega, \{0,1\})} \int_{\Omega} h_i \chi \, \mathrm{d}x + |\mathrm{D}\chi|(\Omega) \Rightarrow \chi_1 \geq \chi_2$ • $\chi^s \in \underset{\Omega \in \mathcal{D}V(\Omega, \{\Omega, \})}{\operatorname{argmin}} \left\{ E_s^{\mathsf{rel}}[\chi] := \int_{\Omega} \partial_s \Psi(x, s) \chi \, \mathrm{d}x + |\mathrm{D}\chi|(\Omega) \right\}$ $\gamma \in BV(\Omega, \{0,1\})$ • $\Psi(x, \cdot)$ strictly convex $\Rightarrow \partial_t \Psi(x, \cdot)$ is strictly increasing $\Rightarrow \chi^{s_1} > \chi^{s_2}$ a.e. for $s_1 < s_2$.



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$$\begin{split} F[q] &= I_{\overline{B}_1}[q] = \begin{cases} 0 & \text{if } |q| \le 1 \text{ a.e} \\ +\infty & \text{else} \end{cases} \\ G[v] &= \int_{\Omega} \frac{\frac{1}{4}v^2 + v\theta_2 - \theta_1\theta_2}{\theta_1 + \theta_2} \, \mathrm{d}x \end{split}$$



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- $\Lambda \in \mathcal{L}(Q, \mathcal{V})$, $Q = H_N(\operatorname{div}, \Omega)$ and $\mathcal{V} = L^2(\Omega)$
- $H(\operatorname{div}, \Omega) = \{ q \in L^2(\Omega, \mathbb{R}^n) : \operatorname{div} q \in L^2(\Omega) \} \text{ and } H_N(\operatorname{div}, \Omega) = H(\operatorname{div}, \Omega) \cap \{ q \cdot \nu = 0 \text{ on } \partial \Omega \}$



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- $\Lambda = \operatorname{div}, \, \Lambda^* = \nabla$ holds in the sense

$$\langle \Lambda^* v, q \rangle = (v, \operatorname{div} q)_{L^2(\Omega)} \quad \forall v \in \mathcal{V}, \ q \in \mathcal{Q}$$

Predual functional (cont.)

From general theory one knows

$$(D^{\mathsf{rel}})^*[v] = F^*[-\Lambda^* v] + G^*[v].$$

$$F[q] = I_{\overline{B}_1}[q], \quad G[v] = \int_{\Omega} \frac{\frac{1}{4}v^2 + v\theta_2 - \theta_1\theta_2}{\theta_1 + \theta_2} \,\mathrm{d}x$$



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The Fenchel conjugates can be computed as follows:

$$F^*[-\Lambda^* v] = \sup_{q \in \mathcal{Q}} (\langle -\Lambda^* v, q \rangle - F[q])$$

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$$= \sup_{q \in \mathcal{Q}, ||q||_{\infty} \le 1} \int_{\Omega} v \operatorname{div} q \, \mathrm{d}x = |\mathrm{D}v|(\Omega)$$
$$G^*[v] = \sup_{w \in L^2(\Omega)} \left((v, w)_{L^2(\Omega)} - G[w] \right) = \int_{\Omega} v^2 \theta_1 + (1-v)^2 \theta_2 \, \mathrm{d}x$$

where last supremum is attained for $w = 2v(\theta_1 + \theta_2) - 2\theta_2$.

$$F[q] = I_{\overline{B}_1}[q], \quad G[v] = \int_{\Omega} \frac{\frac{1}{4}v^2 + v\theta_2 - \theta_1\theta_2}{\theta_1 + \theta_2} \,\mathrm{d}x$$



From general theory one knows

$$(D^{\rm rel})^*[v] = F^*[-\Lambda^* v] + G^*[v].$$

The Fenchel conjugates can be computed as follows:

$$F^*[-\Lambda^* v] = \sup_{q \in \mathcal{Q}} (\langle -\Lambda^* v, q \rangle - F[q]) = \sup_{q \in \mathcal{Q}} \left(-\int_{\Omega} v \operatorname{div} q \, \mathrm{d}x - I_{\overline{B}_1}[q] \right)$$
$$= \sup_{q \in \mathcal{Q}, \|q\|_{\infty} \le 1} \int_{\Omega} v \operatorname{div} q \, \mathrm{d}x = |\mathrm{D}v|(\Omega)$$
$$G^*[v] = \sup_{w \in L^2(\Omega)} \left((v, w)_{L^2(\Omega)} - G[w] \right) = \int_{\Omega} v^2 \theta_1 + (1-v)^2 \theta_2 \, \mathrm{d}x$$
where last summary is attrived for $m = 2v(\theta + \theta_1) = 2\theta$. Thus

where last supremum is attained for $w = 2v(\theta_1 + \theta_2) - 2\theta_2$. Thus,

$$(D^{\mathsf{rel}})^*[v] = F^*[-\Lambda^* v] + G^*[v] = E^{\mathsf{rel}}[v].$$

$$F[q] = I_{\overline{B}_1}[q], \quad G[v] = \int_{\Omega} \frac{\frac{1}{4}v^2 + v\theta_2 - \theta_1\theta_2}{\theta_1 + \theta_2} \,\mathrm{d}x$$





Central insight: Minimizers p of D^{rel} and u of $(D^{rel})^*$ fulfill

 $D^{\mathsf{rel}}[p] = -(D^{\mathsf{rel}})^*[u]$



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$$\begin{split} D^{\mathsf{rel}}[p] &= \inf_{q \in H_N(\operatorname{div},\Omega)} (F[q] + G[\Lambda q]) = \inf_{q \in H_N(\operatorname{div},\Omega)} (F[q] + G^{**}[\Lambda q]) \\ &= \inf_{q \in H_N(\operatorname{div},\Omega)} \sup_{v \in L^2(\Omega)} (F[q] + \langle v, \Lambda q \rangle - G^*[v]) \\ &= \sup_{v \in L^2(\Omega)} \left(-\sup_{q \in H_N(\operatorname{div},\Omega)} (\langle -\Lambda^* v, q \rangle - F[q]) - G^*[v] \right) \\ &= \sup_{v \in L^2(\Omega)} (-F^*[-\Lambda^* v] - G^*[v]) \\ &= \sup_{v \in L^2(\Omega)} (-(D^{\mathsf{rel}})^*[v]) = -\inf_{v \in L^2(\Omega)} (D^{\mathsf{rel}})^*[v] = -(D^{\mathsf{rel}})^*[u] \,. \end{split}$$



Two measures of uniform convexity for $J: X \to \mathbb{R}$



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 $J\left[\frac{x_1+x_2}{2}\right] + \Phi_J(x_2 - x_1) \le \frac{1}{2}(J[x_1] + J[x_2]) \text{ for all } x_1, x_2 \in X$





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$$\langle x', x_2 - x_1 \rangle + \Psi_J(x_2 - x_1) \le J[x_2] - J[x_1]$$
 for all $x' \in \partial J[x_1]$

Theorem [Repin '00]: Let $u \in \operatorname{argmin}_{\tilde{v} \in \mathcal{V}} E^{\operatorname{rel}}[\tilde{v}]$ and $q \in \mathcal{Q}$, $v \in \mathcal{V}' = \mathcal{V} = L^2(\Omega)$. Then,

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The convexity property of Φ_{G^*} and Φ_{F^*} gives:

$$\begin{aligned} \Phi_{G^*}(v-u) + \Phi_{F^*}(-\Lambda^*(v-u)) \\ &\leq \frac{1}{2} \left(F^*[-\Lambda^*v] + G^*[v] + F^*[-\Lambda^*u] + G^*[u] \right) \\ &- \left(F^*[-\Lambda^*\frac{u+v}{2}] + G^*[\frac{u+v}{2}] \right) \end{aligned}$$



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Adding both inequalities gives

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The claim follows using the weak complementarity principle

$$E^{\mathsf{rel}}[u] \ge -D^{\mathsf{rel}}[q].$$



Theorem [Repin '00]: Let $u \in \operatorname{argmin}_{\tilde{v} \in \mathcal{V}} E^{\operatorname{rel}}[\tilde{v}]$ and $q \in \mathcal{Q}$, $v \in \mathcal{V}' = \mathcal{V} = L^2(\Omega)$. Then,

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In our case, one gets

$$\Phi_{F^*} \equiv 0, \ \Phi_{G^*}(v) = \frac{1}{4} \int_{\Omega} v^2(\theta_1 + \theta_2) \,\mathrm{d}x, \ \Psi_{E^{\mathsf{rel}}}(v) = \int_{\Omega} v^2(\theta_1 + \theta_2) \,\mathrm{d}x.$$



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Using $\frac{1}{2\nu}(c_1-c_2)^2 \leq \theta_1+\theta_2$ this leads to:

Theorem [A posteriori error estimate for E^{rel}]: Let $u \in \mathcal{V}$ be the minimizer of E^{rel} . Then, for any $v \in \mathcal{V}$ and $q \in \mathcal{Q}$ it holds that

$$\|u - v\|_{L^{2}(\Omega)}^{2} \leq \operatorname{err}_{u}^{2}[v, q] := \frac{2\nu}{(c_{1} - c_{2})^{2}} \left(E^{\mathsf{rel}}[v] + D^{\mathsf{rel}}[q] \right)$$



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Key observation: solutions of E^{rel} are characterized by steep profiles



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Theorem [A posteriori error estimate for E]: Let $\chi \in BV(\Omega, \{0, 1\})$ be the minimizer of the binary Mumford–Shah functional obtained from E^{rel} . Then for all $v \in \mathcal{V} = L^2(\Omega)$ and $q \in \mathcal{Q} = H_N(\text{div}, \Omega)$ we have

$$\left\|\chi - \chi_{[v > \frac{1}{2}]}\right\|_{L^1(\Omega)} \le \inf_{\eta \in (0, \frac{1}{2})} \left\{ \operatorname{err}_{\chi}[v, q, \eta] = \left(\mathbf{a}[v, \eta] + \frac{1}{\eta^2} \operatorname{err}_u^2[v, q]\right) \right\} \,.$$







Theorem [A posteriori error estimate for *E*]: Let $\chi \in BV(\Omega, \{0, 1\})$ be the minimizer of the binary Mumford–Shah functional obtained from E^{rel} . Then for all $v \in \mathcal{V} = L^2(\Omega)$ and $q \in \mathcal{Q} = H_N(\text{div}, \Omega)$ we have $\|\chi - \chi_{[v > \frac{1}{2}]}\|_{L^1(\Omega)} \leq \inf_{\eta \in (0, \frac{1}{2})} \left\{ \text{err}_{\chi}[v, q, \eta] = \left(a[v, \eta] + \frac{1}{\eta^2} \text{err}_u^2[v, q]\right) \right\}$. **Proof:** $[u > \frac{1}{2}] \Delta [v > \frac{1}{2}] \subseteq [\frac{1}{2} - \eta \leq v \leq \frac{1}{2} + \eta] \cup [|u - v| > \eta]$ Using the estimate for $||u - v||^2$, we get

Using the estimate for $\|u-v\|^2_{L^2(\Omega)}$, we get

$$\mathcal{L}^{n}([|u-v| > \eta]) \le \int_{\{|u-v| > \eta\}} \frac{1}{\eta^{2}} |u-v|^{2} \, \mathrm{d}x \le \frac{1}{\eta^{2}} \mathrm{err}_{u}^{2}[v,q].$$

The above holds for any $\eta \in (0, \frac{1}{2})$, so also for $\inf_{\eta \in (0, \frac{1}{2})}$.



 ${\mathscr T}$ adaptive simplicial mesh

 \mathcal{V}_h^0 space of piecewise constant finite element functions on \mathscr{T}

 $\mathcal{V}_h^{\widehat{1}}$ space of continuous and affine finite element functions on \mathscr{T}



 ${\mathscr T}$ adaptive simplicial mesh

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$$G_{h}[v_{h}] = \int_{\Omega} \frac{\frac{1}{4}v_{h}^{2} + v_{h} - \theta_{1,h}\theta_{2,h}}{\theta_{1,h} + \theta_{2,h}} \, \mathrm{d}x \,, \quad F_{h}[q_{h}] = I_{\bar{B}_{1}}[q_{h}] \,,$$
$$G_{h}^{*}[v_{h}] = \int_{\Omega} v_{h}^{2}\theta_{1,h} + (1 - v_{h})^{2}\theta_{2,h} \, \mathrm{d}x \,, \quad F_{h}^{*}[q_{h}] = \int_{\Omega} \mathcal{I}_{h}(|q_{h}|) \, \mathrm{d}x \,,$$

for $\theta_{i,h} = \mathcal{I}_h(\frac{1}{\nu}(c_i - u_0)^2)$ for i = 1, 2, \mathcal{I}_h Lagrange interpolation



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$$\begin{aligned} G_h[v_h] &= \int_{\Omega} \frac{\frac{1}{4}v_h^2 + v_h - \theta_{1,h}\theta_{2,h}}{\theta_{1,h} + \theta_{2,h}} \,\mathrm{d}x\,, \quad F_h[q_h] = I_{\bar{B}_1}[q_h]\,, \\ G_h^*[v_h] &= \int_{\Omega} v_h^2 \theta_{1,h} + (1 - v_h)^2 \theta_{2,h} \,\mathrm{d}x\,, \quad F_h^*[q_h] = \int_{\Omega} \mathcal{I}_h(|q_h|) \,\mathrm{d}x\,, \\ \text{for } \theta_{i,h} &= \mathcal{I}_h(\frac{1}{\nu}(c_i - u_0)^2) \text{ for } i = 1, 2, \mathcal{I}_h \text{ Lagrange interpolation} \\ \text{(FE) discretization } \mathcal{V}_h &= \mathcal{V}_h^1 \text{ with } L^2 \text{-scalar product and } \mathcal{Q}_h = (\mathcal{V}_h^1)^2 \\ \text{with lumped mass scalar product,} \\ -\Lambda_h^* : \mathcal{V}_h \to \mathcal{Q}_h \text{ implicitly defined via (cf. [Bartels '14])} \\ \int_{\Omega} \mathcal{I}_h(-\Lambda_h^* v_h \cdot q_h) \,\mathrm{d}x = \int_{\Omega} v_h \mathcal{P}_h \,\mathrm{div} \,q_h \,\mathrm{d}x \quad \forall q_h \in \mathcal{Q}_h, v_h \in \mathcal{V}_h \end{aligned}$$

 $\mathcal{P}_h: L^2(\Omega) \to \mathcal{V}_h$ denotes L^2 -projection



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Primal-dual algorithm

[Chambolle, Pock '11]



Primal-dual algorithm

Chambolle, Pock '11

end

• The resolvent $(\mathrm{Id} + \sigma \partial F_h)^{-1}$ for F_h is well known.


Primal-dual algorithm

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can be computed in a straightforwardly, but involves mass matrices.



Chambolle, Pock '11

Primal-dual algorithm

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can be computed in a straightforwardly, but involves mass matrices.

 \blacksquare The operator norm of Λ can be estimated as follows

•
$$\|\Lambda_h\|^2 \le 48(3+2\sqrt{2})h_{\min}^{-2}$$
 for (FE') and $n=2$

•
$$\|\Lambda_h\|^2 \le 96(3+2\sqrt{2})h_{\min}^{-2}$$
 for (FE)

Numerical results - "Flower"













Numerical results - "Flower"





Numerical results - "Flower" (cont.)





Numerical results - "Cameraman"









Image source: MATLAB

Numerical results - "Cameraman"





Numerical results - "Cameraman" (cont.)





Numerical results - "Gaussians" using (FE')





Numerical results - "Gaussians" using (FE')





Numerical results - "Gaussians" using (FE')







Summary

A posteriori error estimates for the binary Mumford-Shah model



- A posteriori error estimates for the binary Mumford-Shah model
- Natural error quantity: area of the non-properly segmented region

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Outlook

Transfer the approach to more general computer vision problems

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Outlook

- Transfer the approach to more general computer vision problems
- Develop/use minimization algorithms that are tailored to the adaptive structure

References



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Thank you for your attention!

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