A Quasi-Static Projection Method for 3-Dimensional Hypoelastoplasticity

Nicholas Boffi February 27, 2017

SIAM CSE Conference. Harvard University, Department of Applied Mathematics. Rycroft Group. • Solid metal with atoms "frozen" into liquid-like disorder.

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Bulk Metallic Glasses

Lattice

Defect

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Bulk Metallic Glasses

Lattice

Defect

- Solid metal with atoms "frozen" into liquid-like disorder.
- Amorphous structure gives unique properties.
- Catastrophic failure: shear banding.



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- Effective temperature χ quantifies localized "softness".



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Jaumann derivative

$$\frac{\mathcal{D}\sigma}{\mathcal{D}t} \stackrel{\text{Stiffness}}{= \widehat{\mathsf{C}} : \underbrace{\mathsf{D}}^{\text{el}}_{\text{Elastic Part}}}_{\text{Elastic Part}}$$

$$\underbrace{ \frac{\mathcal{D}\sigma}{\mathcal{D}t}}_{\text{Jaumann derivative}} \overset{\text{Stiffness}}{\widehat{\mathsf{C}}: \underbrace{\mathsf{D}^{\text{el}}}_{\text{Elastic Part}} }$$

$$\mathsf{D} = \frac{1}{2} (\nabla \mathsf{u} + (\nabla \mathsf{u})^T)$$







Linear Elasticity $\frac{\mathcal{D}\sigma}{\mathcal{D}t} = \widehat{\mathbf{C}} : \underbrace{\mathbf{D}}_{\text{Elastic Part}}^{\text{Stiffness}}$ laumann derivative $\underbrace{\mathbf{\tilde{D}}}_{\text{Rate of deformation}} = \underbrace{\frac{1}{2} (\nabla \mathbf{u} + (\nabla \mathbf{u})^T)}_{\text{T}}$ Definition $= D^{el} + D^{pl}$ Hypoelastoplastic assumption $\rho \frac{d\mathbf{u}}{dt} = \nabla \cdot \boldsymbol{\sigma}$

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$$\frac{d\chi}{dt} = \frac{D^{pl}\bar{s}}{s_y c_0} \left(\chi_{\infty} - \chi\right)$$



Advective derivative

 $\frac{d\chi}{dt} = \frac{D^{pl}\bar{s}}{s_y c_0} \left(\chi_{\infty} - \chi\right)$











$$\frac{d\chi}{dt}_{\text{dective derivative}} = \underbrace{\frac{D^{pl}\bar{s}}{s_{y}c_{0}}(\chi_{\infty} - \chi)}_{\text{Relaxation to }\chi_{\infty}}$$

$$\bar{s}^{2} = \frac{1}{2}\sigma_{0,ij}\sigma_{0,ij}$$

Linear Elasticity $\frac{\mathcal{D}\sigma}{\mathcal{D}t} = \widehat{\mathbf{C}} : \underbrace{\mathbf{D}^{el}}_{\text{Elastic Part}}$ laumann derivative $\underbrace{\mathbf{\tilde{D}}}_{\text{Rate of deformation}} = \underbrace{\frac{1}{2}(\nabla \mathbf{u} + (\nabla \mathbf{u})^T)}_{\text{Definition}}$ $= D^{el} + D^{pl}$ Hypoelastoplastic assumption $\rho \underbrace{\frac{d\mathbf{u}}{dt}}_{\text{Net force}} = \underbrace{\nabla \cdot \sigma}_{\text{Net force}}$ $m \times a$

Shear Transformation Zone Theory

 $\frac{d\chi}{\underbrace{dt}}_{\text{Advective derivative}} = \underbrace{\frac{D^{pl}\bar{s}}{s_y c_0}}_{\substack{\text{Relax}}}$

$$= \frac{D^{-3}}{\frac{s_y c_0}{\text{Relaxation to } \chi_{\infty}}} (\chi_{\infty} - \chi)$$
$$= \frac{1}{2} \sigma_{0,ij} \sigma_{0,ij}$$

Total deviatoric stress


Shear Transformation Zone Theory

 $\begin{array}{c} \displaystyle \frac{d\chi}{dt} \\ \displaystyle \text{Advective derivative} \end{array} = \underbrace{\frac{D^{pl}\bar{s}}{s_{y}c_{0}}\left(\chi_{\infty}-\chi\right)}_{\text{Relaxation to }\chi_{\infty}} \\ \displaystyle \frac{\bar{s}^{2}}{\bar{s}^{2}} = \frac{1}{2}\sigma_{0,ij}\sigma_{0,ij} \\ \hline \text{Total deviatoric stress} \end{array}$

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$$\underbrace{\frac{d\chi}{dt}}_{\text{Relaxation to }\chi_{\infty}} = \underbrace{\frac{1}{2}\sigma_{0,ij}\sigma_{0,ij}}_{\text{Frobenius norm}}$$

$$\sigma_0 = \sigma - \frac{1}{3}\text{Tr}(\sigma)\text{I}$$

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 $\frac{d\chi}{dt} = \underbrace{\frac{D^{pl}\bar{s}}{s_{y}c_{0}}(\chi_{\infty}-\chi)}_{\text{Relaxation to }\chi_{\infty}}$ Advective derivative $\frac{\bar{s}_{z}^{2}}{\bar{s}_{z}^{2}} = \underbrace{\frac{1}{2}\sigma_{0,ij}\sigma_{0,ij}}_{\text{Frobenius norm}}$ Total deviatoric stress $\underbrace{\sigma_{0}}_{\text{Deviatoric stress}} = \underbrace{\sigma - \frac{1}{3}\text{Tr}(\sigma)\text{I}}_{\text{Subtract hydrostatic}}$ Deviatoric stress $\underbrace{\mathbf{D}_{z}^{pl}}_{\text{Plastic rate}} = D^{pl}\frac{\sigma_{0}}{\bar{s}}$



Shear Transformation Zone Theory

 $\frac{d\chi}{d\underline{t}} = \underbrace{\frac{D^{pl}\overline{s}}{s_{p}c_{0}}(\chi_{\infty} - \chi)}_{\text{Relaxation to }\chi_{\infty}}$ Advective derivative $\overline{s}_{j}^{2} = \frac{1}{2} \underbrace{\sigma_{0,ij}\sigma_{0,ij}}_{\text{Frobenius norm}}$ Total deviatoric stress $\underbrace{\sigma_{0}}_{\text{Deviatoric stress}} = \underbrace{\sigma_{-}\frac{1}{3}\text{Tr}(\sigma)\text{I}}_{\text{Subtract hydrostatic}}$ Plastic rate $\underbrace{D^{pl}}_{\infty} = \underbrace{D^{pl}\frac{\sigma_{0}}{\overline{s}}}_{\infty \text{ deviatoric}}$



Hypoelastoplastic Long-Time Limit

$$\frac{\mathcal{D}\sigma}{\mathcal{D}t} = \mathsf{C} : \left(\mathsf{D} - \mathsf{D}^{\mathsf{pl}}\right)$$

Incompressible Navier-Stokes

Hypoelastoplastic Long-Time Limit

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Hypoelastoplastic equation

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$$\rho \frac{d\mathbf{u}}{dt} = -\nabla p + \nabla \cdot \mathbf{T}$$

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$$\nabla\cdot\sigma\approx 0$$

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From Navier-Stokes to Hypoelastoplasticity

 $\sigma_{\text{H.E.P.}} \iff \mathbf{u}_{\text{N.S.}}$

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 $\sigma_{\text{H.E.P.}} \iff \mathbf{u}_{\text{N.S.}}$

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· Any algorithm for Navier-Stokes should work for hypoelastoplasticity.

Hypoelastoplastic Long-Time Limit

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Navier-Stokes equation

 $\underbrace{\nabla\cdot\mathbf{u}\approx0}_{\text{Incompressibility constraint}}$



- Any algorithm for Navier-Stokes should work for hypoelastoplasticity.
- This analogy is independent of the plasticity model.

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• Neglect **D** term (advection step):

• Hypoelastoplastic equation:

$$\frac{\mathcal{D}\sigma}{\mathcal{D}t} = \mathsf{C} : \left(\mathsf{D} - \mathsf{D}^{\mathsf{pl}}\right).$$

• Neglect D term (advection step):

$$\frac{\sigma^* - \sigma^n}{\Delta t} = -\sigma^n \cdot \omega^n + \omega^n \cdot \sigma^n - (\mathbf{u}^n \cdot \nabla)\sigma^n - \mathbf{C}: \ \left[\mathbf{D}^{\mathrm{pl}}\right]^n$$

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superscript indicates timestep

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Forward-Euler intermediate step

• Hypoelastoplastic equation:

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superscript indicates timestep

$$\underbrace{\frac{\sigma^* - \sigma^n}{\Delta t}}_{\text{Jaumann spin terms}} = \underbrace{-\sigma^n \cdot \omega^n + \omega^n \cdot \sigma^n}_{\text{Jaumann spin terms}} - (\mathbf{u}^n \cdot \nabla)\sigma^n - \mathbf{C}: \quad \overline{[\mathbf{D}^{\text{pl}}]^n}$$

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For

• Hypoelastoplastic equation:

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• Correction term (projection step):

• Hypoelastoplastic equation:

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• Correction term (projection step):

$$\frac{\sigma^{n+1} - \sigma^*}{\Delta t} = \mathsf{C} : \mathsf{D}^{n+1}$$

• Hypoelastoplastic equation:

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• Correction term (projection step):

$$\frac{\sigma^{n+1} - \sigma^*}{\Delta t} = \underbrace{\mathsf{C}: \mathsf{D}^{n+1}}_{\text{complete the Euler step}}$$

• Hypoelastoplastic equation:

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Correction term (projection step):

$$rac{\sigma^{n+1}-\sigma^*}{\Delta t} = \underbrace{\mathsf{C}:\mathsf{D}^{n+1}}_{\mathsf{complete the Euler step}}$$

• Take divergence and enforce $\nabla \cdot \sigma^{n+1} = 0$:

• Hypoelastoplastic equation:

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$$\nabla \cdot \sigma^* \ = \ - \Delta t \nabla \cdot (\mathsf{C} : \mathsf{D}^{n+1})$$
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$$\underbrace{\nabla\cdot\sigma^*}_{\text{source term based on }\sigma^*} = \ -\Delta t\nabla\cdot(\mathsf{C}:\mathsf{D}^{n+1})$$

F

• Hypoelastoplastic equation:

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$$\underbrace{\nabla \cdot \sigma^*}_{\text{source term based on } \sigma^*} = \underbrace{-\Delta t \nabla \cdot (\mathbf{C} : \mathbf{D}^{n+1})}_{\text{linear system for } \mathbf{u}^{n+1}}$$

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• Hypoelastoplastic equation:

$$\frac{\mathcal{D}\sigma}{\mathcal{D}t} = \mathsf{C} : \left(\mathsf{D} - \mathsf{D}^{\mathsf{pl}}\right).$$

• Neglect **D** term (advection step):

$$\underbrace{\frac{\sigma^* - \sigma^n}{\Delta t}}_{\text{prward-Euler intermediate step}} = \underbrace{-\sigma^n \cdot \omega^n + \omega^n \cdot \sigma^n}_{\text{Jaumann spin terms}} - \underbrace{(\mathbf{u}^n \cdot \nabla)\sigma^n - \mathbf{C}}_{\text{advective derivative}} \cdot \underbrace{[\mathsf{D}^{\mathsf{pl}}]^n}_{\text{advective derivative}}$$

Correction term (projection step):

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• Same software for both quasi-static and explicit method.

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• Need to solve complex linear system with mixed spatial derivatives for velocity update.

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- **mg3d**: custom parallel geometric multigrid solver written in C⁺⁺ and MPI.
- C⁺⁺ templates to solve for arbitrary datatypes (*n*-dimensional vectors, complex numbers, etc.) at each point.





 Restriction and interpolation operators: R_i, T_i.

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grid i-1 grid i

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1D Example

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1D Example

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	14		

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Quasi-Static Results

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Conclusions, Future Directions, and Acknowledgments

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