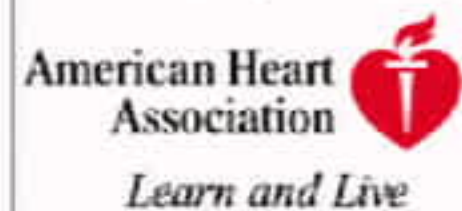
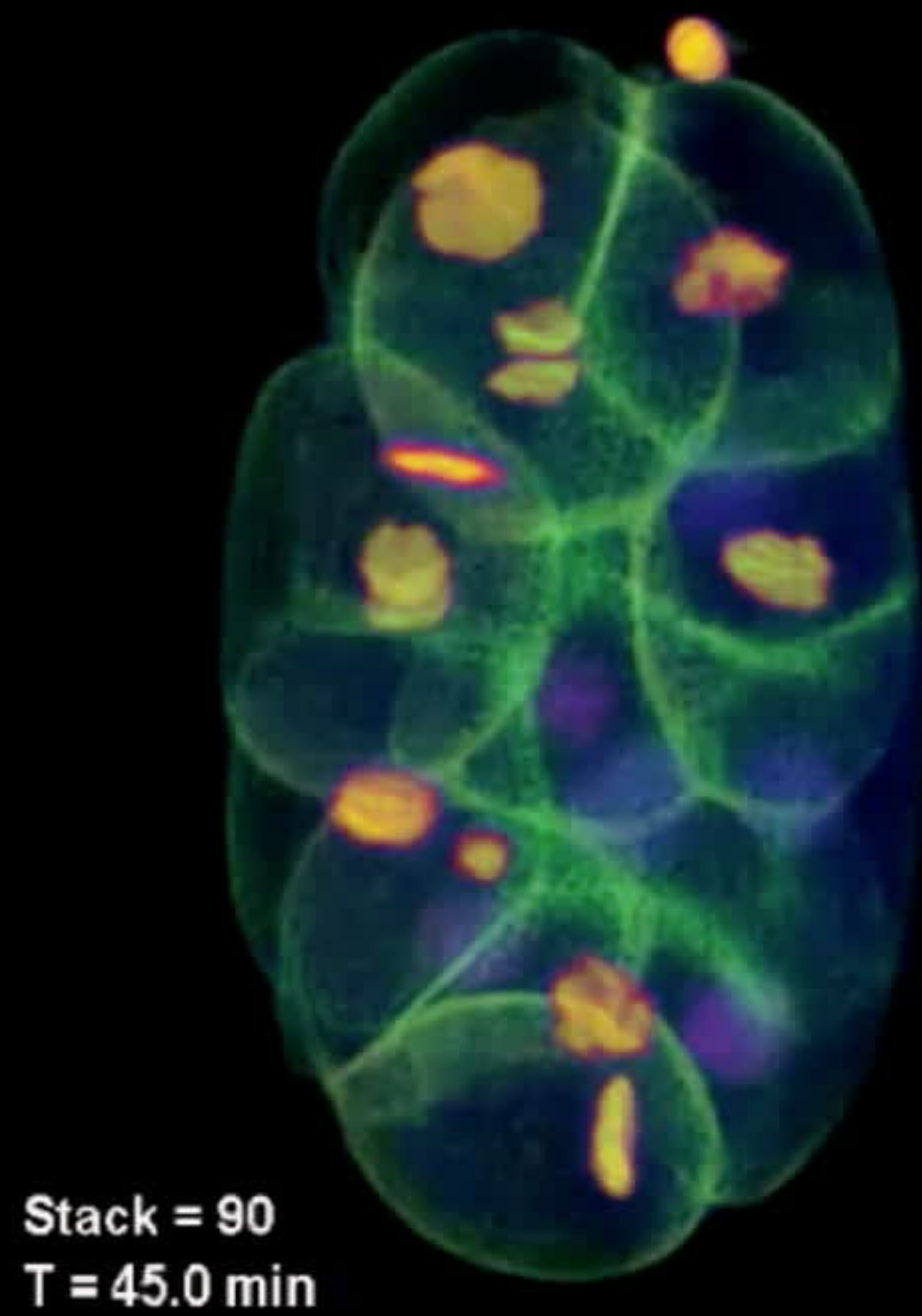


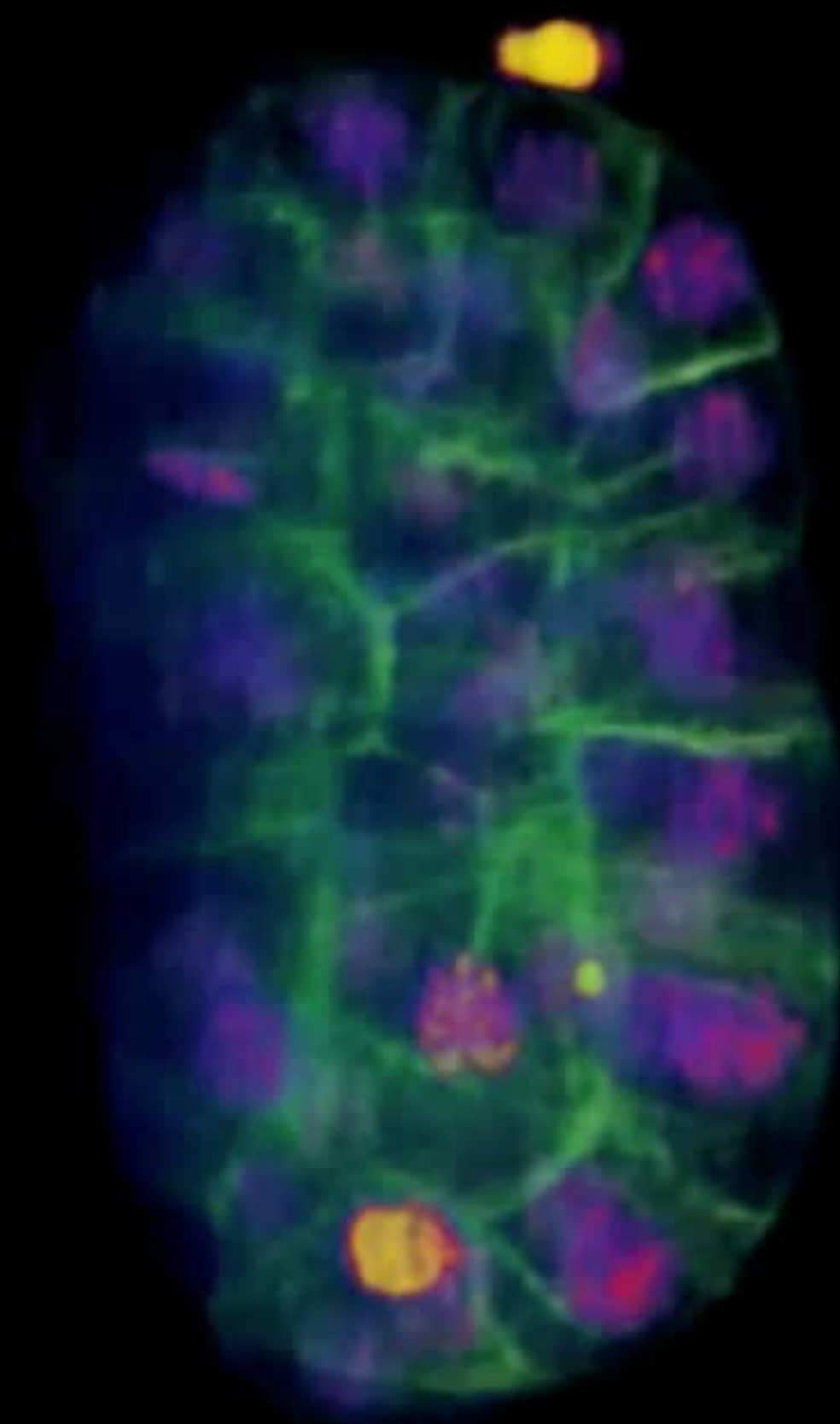
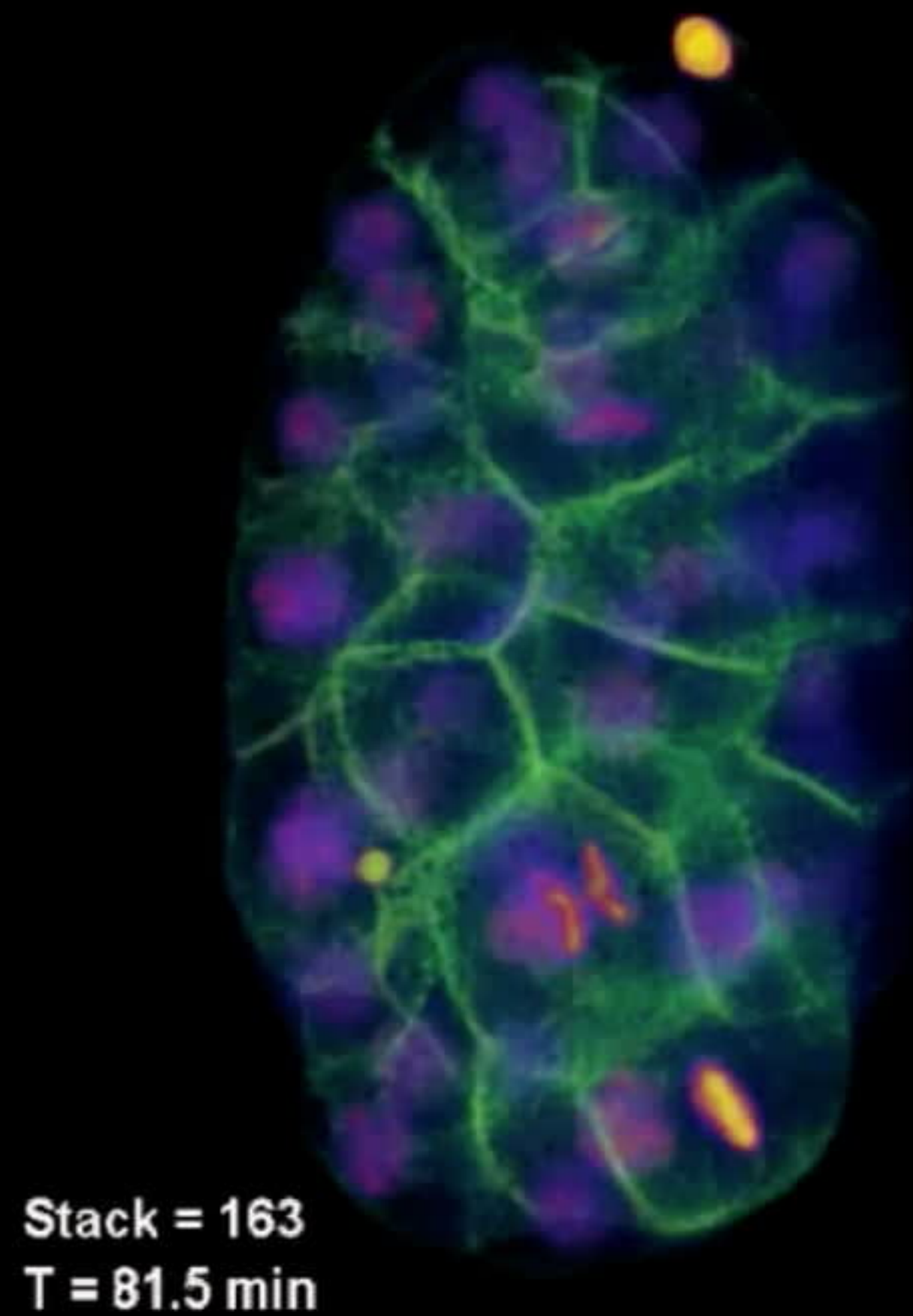
Fluid-Structure Interaction
in Medicine and Biology:
Methods, Models, and Applications

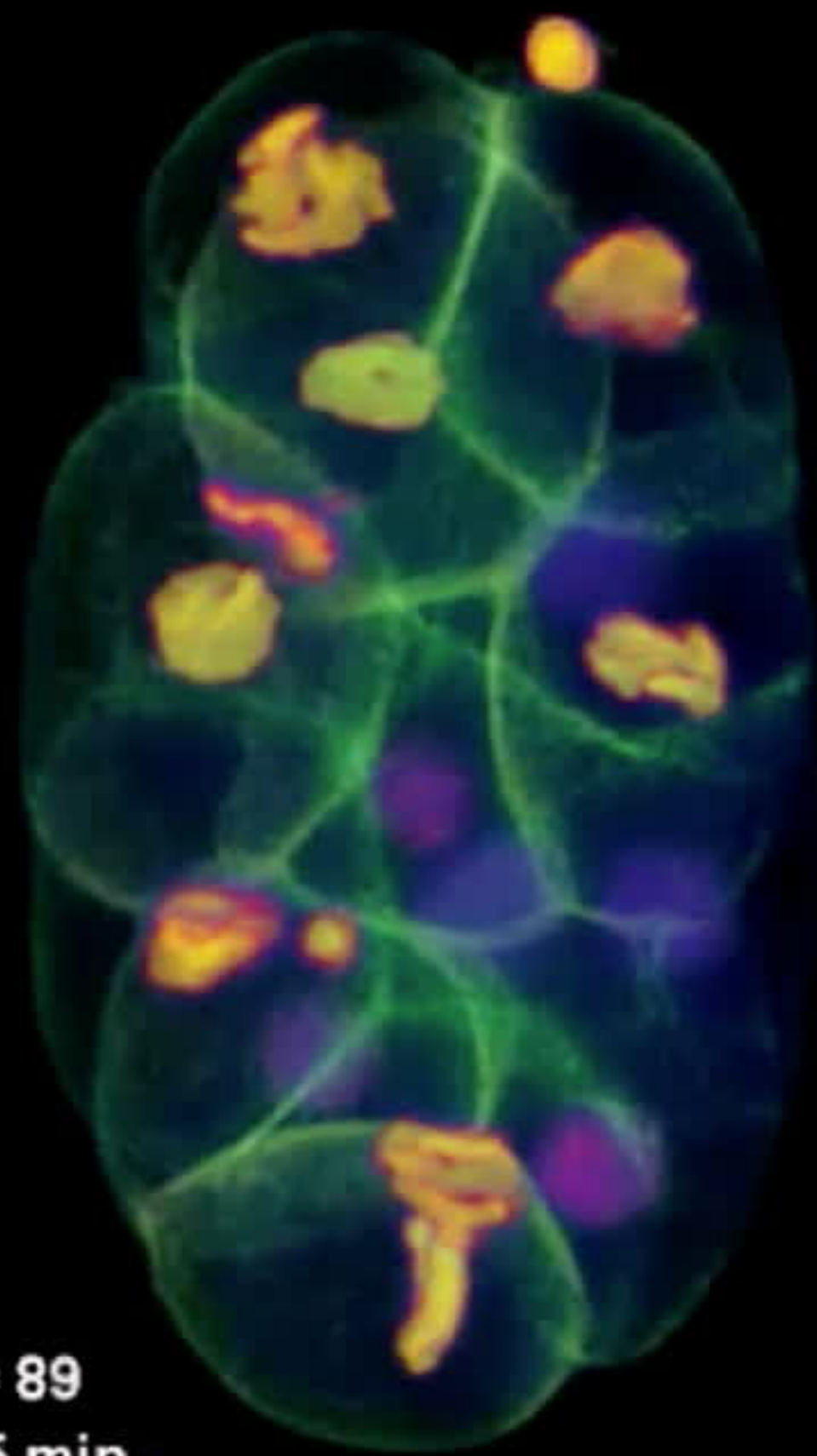
Boyce Griffith
The University of North Carolina at Chapel Hill



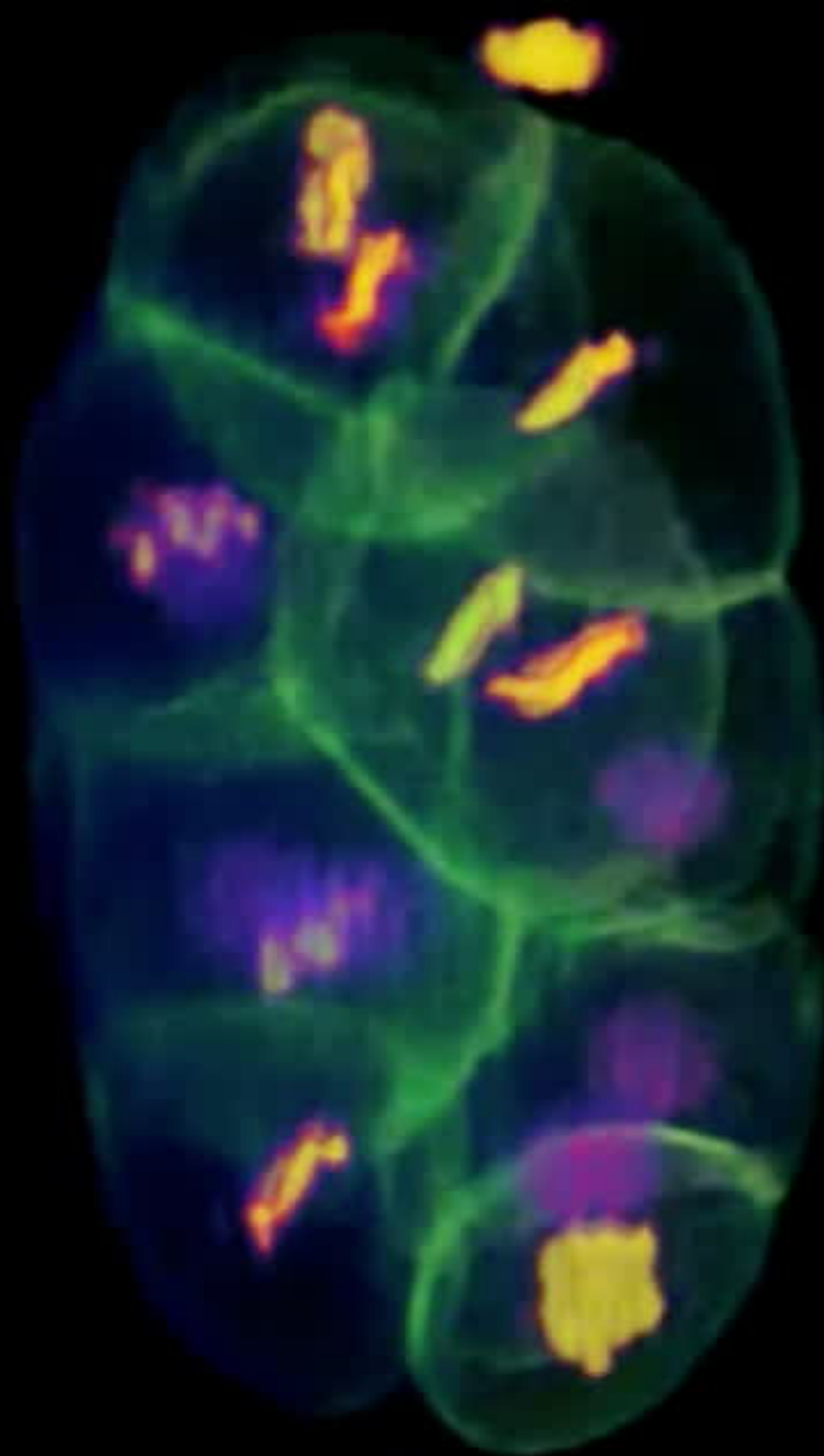
*fluid-structure interaction
occurs at all biological scales*

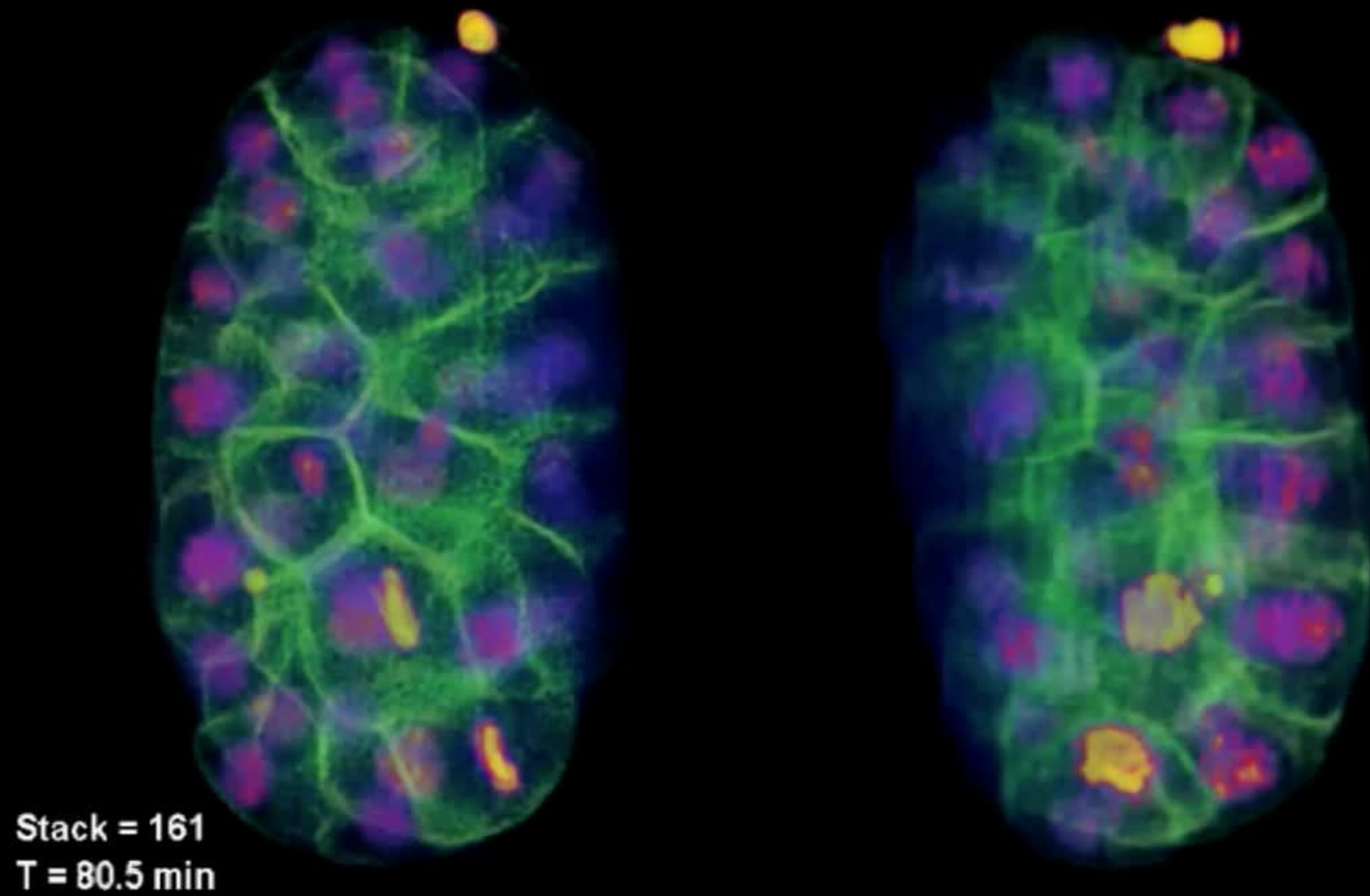


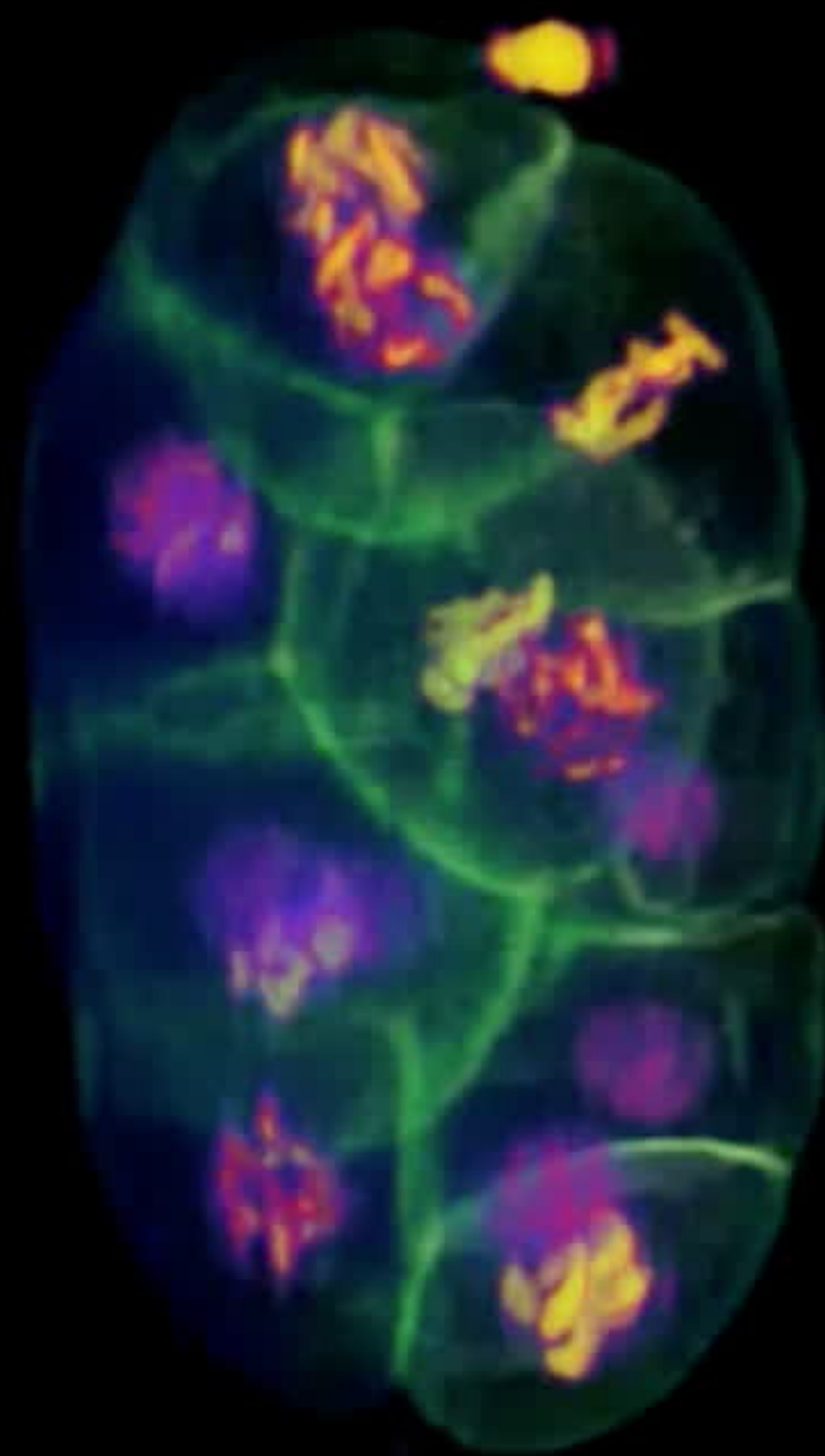
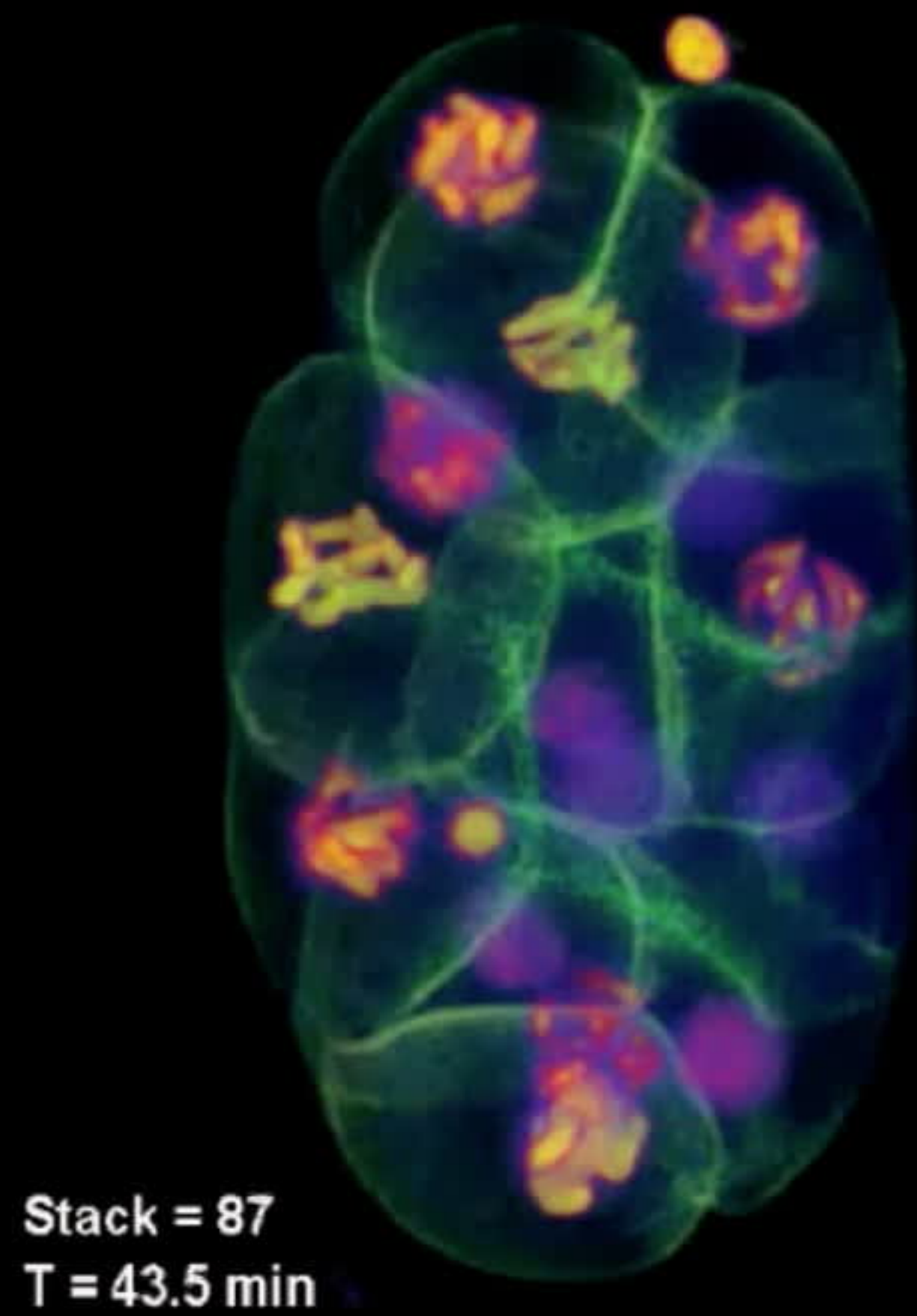


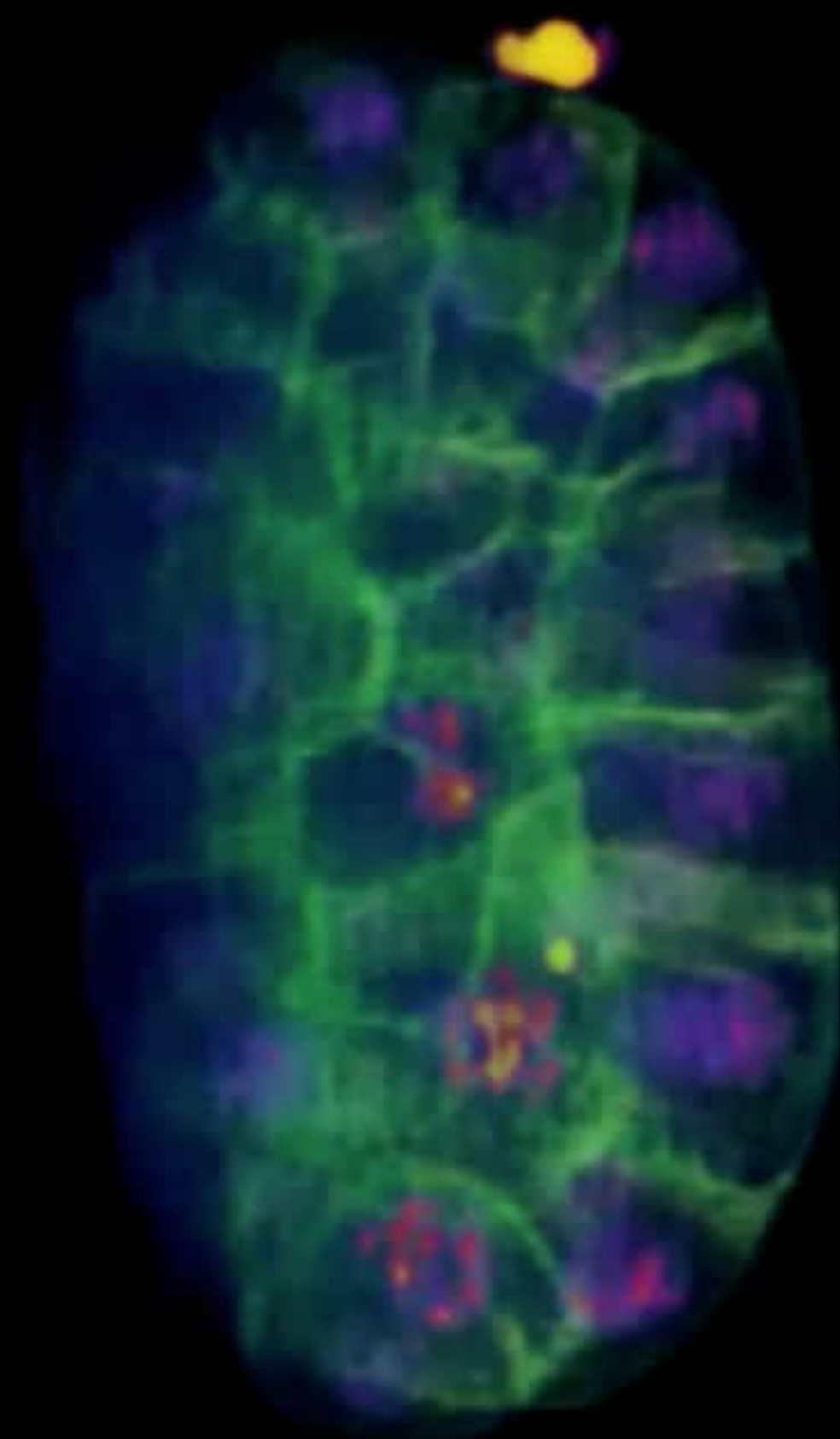
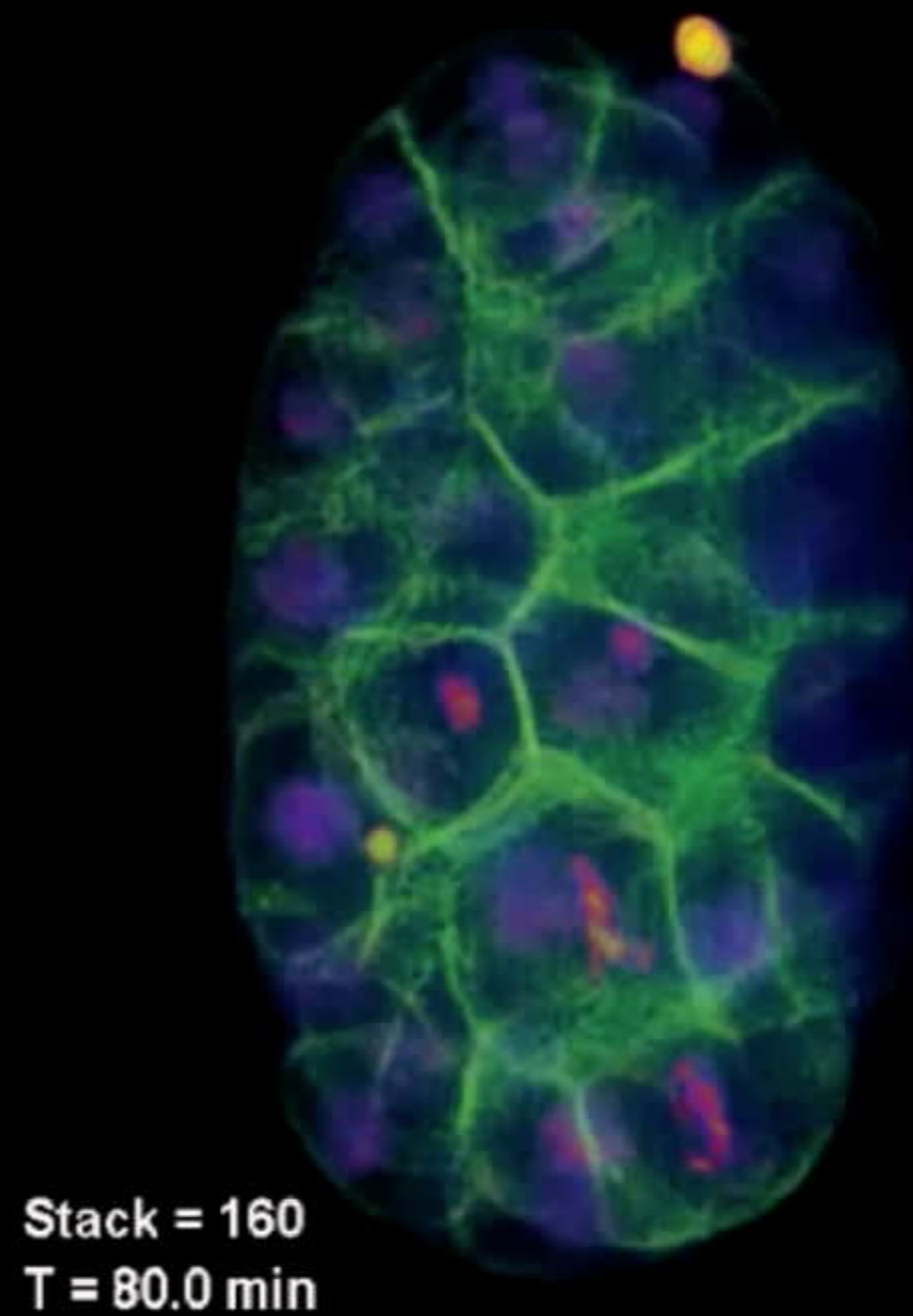


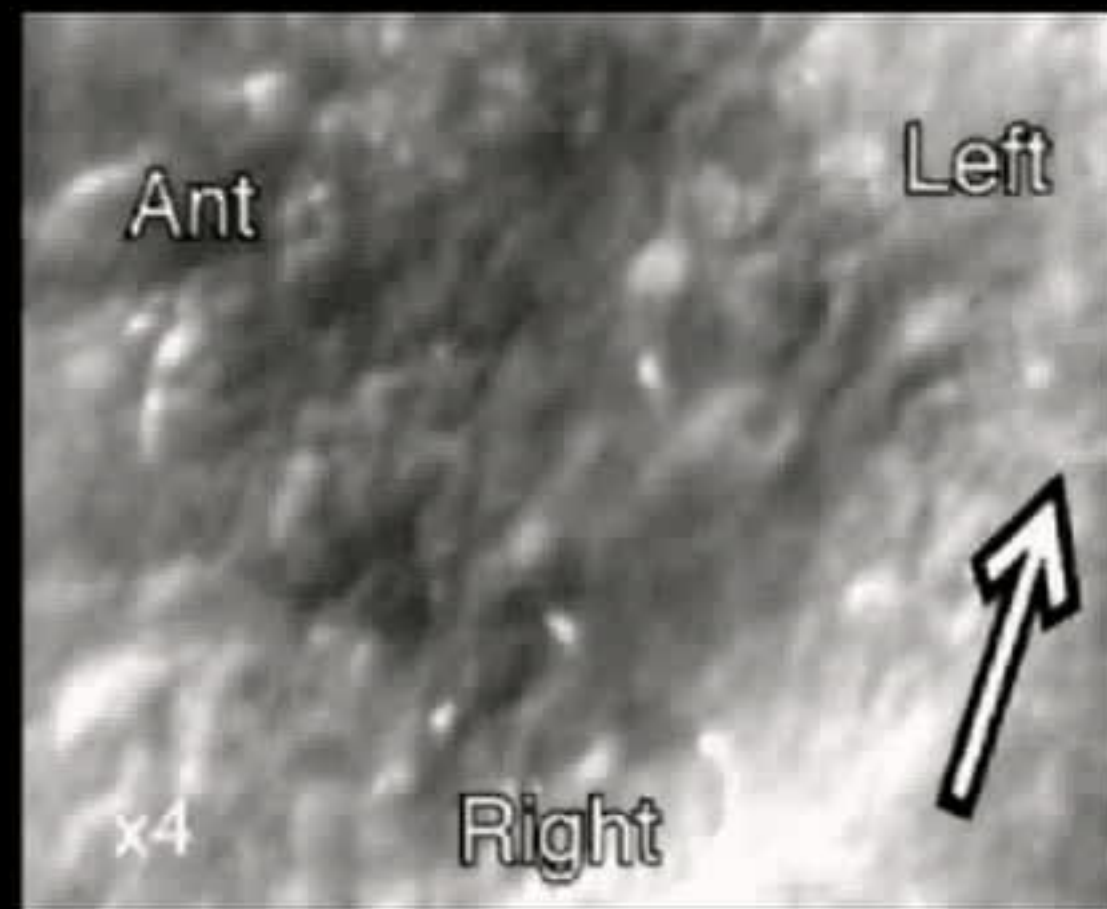
Stack = 89
T = 44.5 min

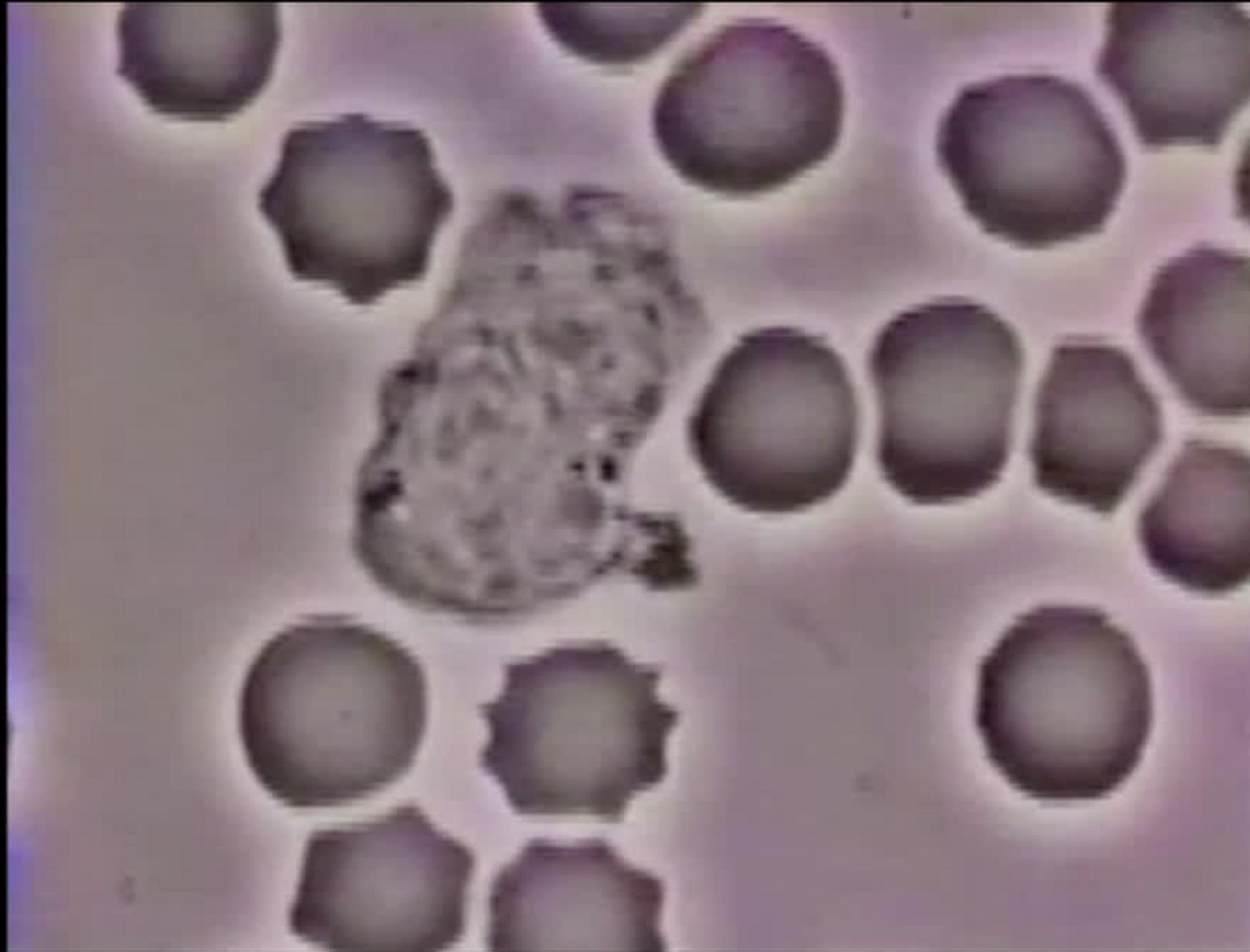




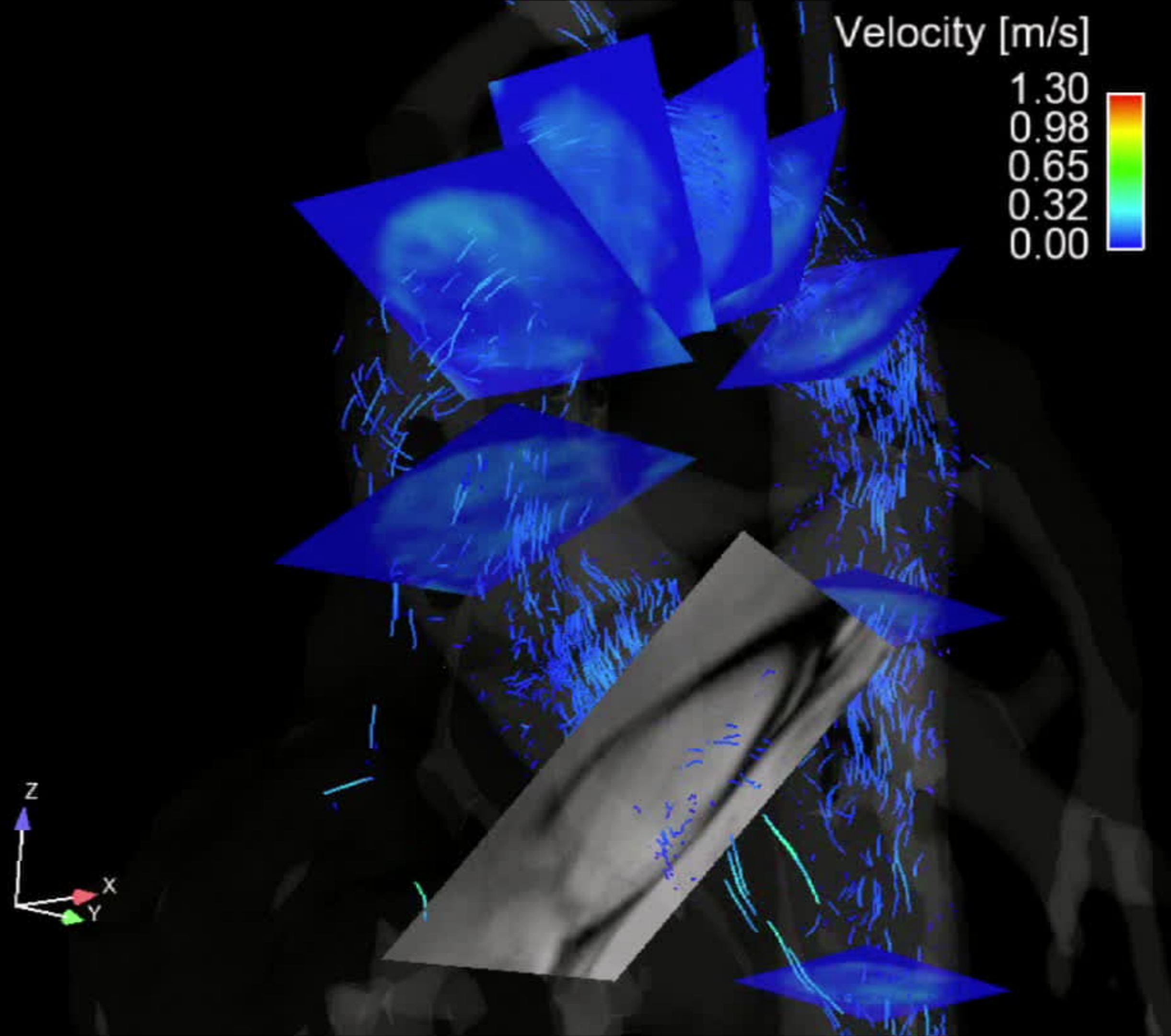








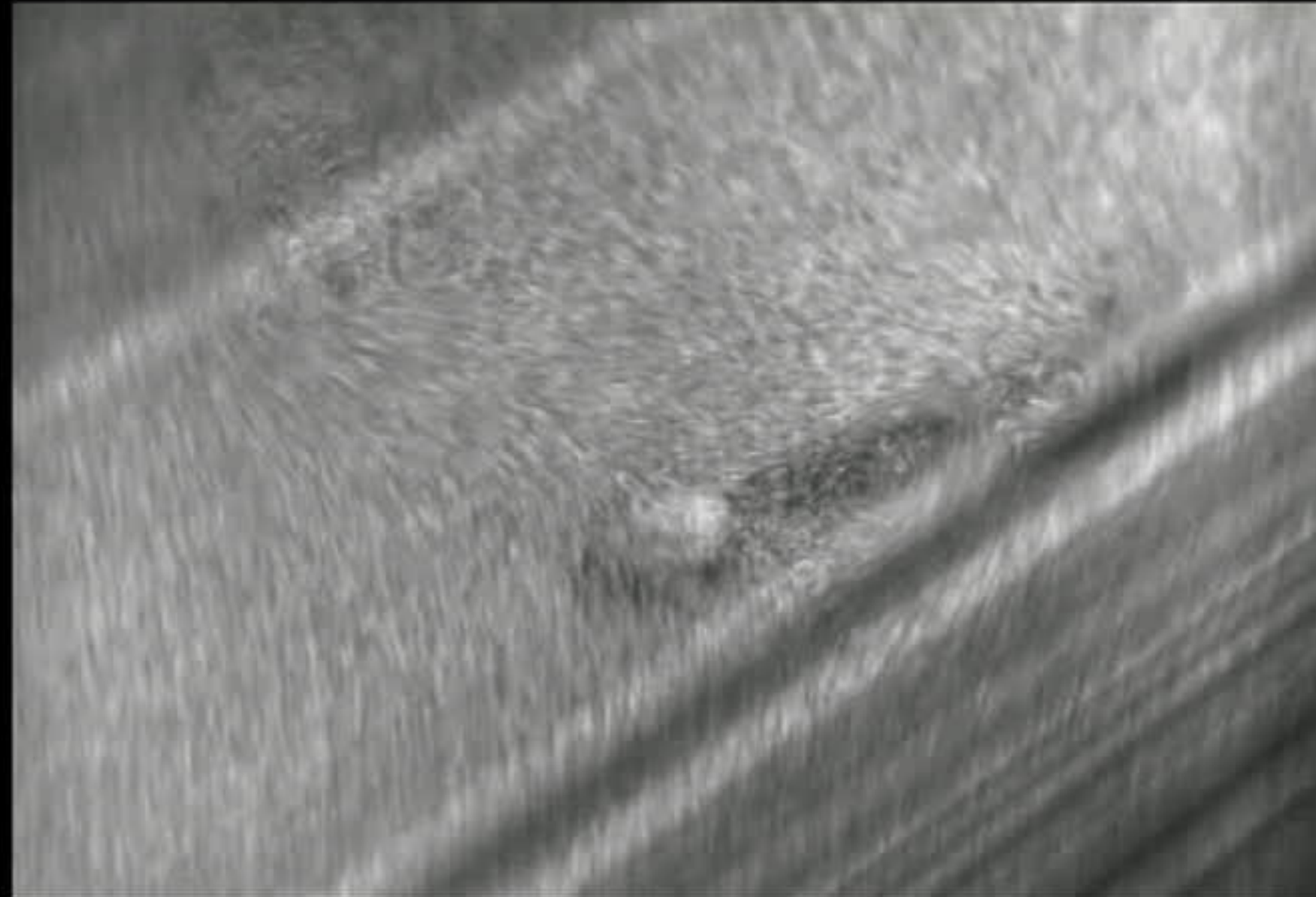
David Rogers, Vanderbilt University, circa 1950





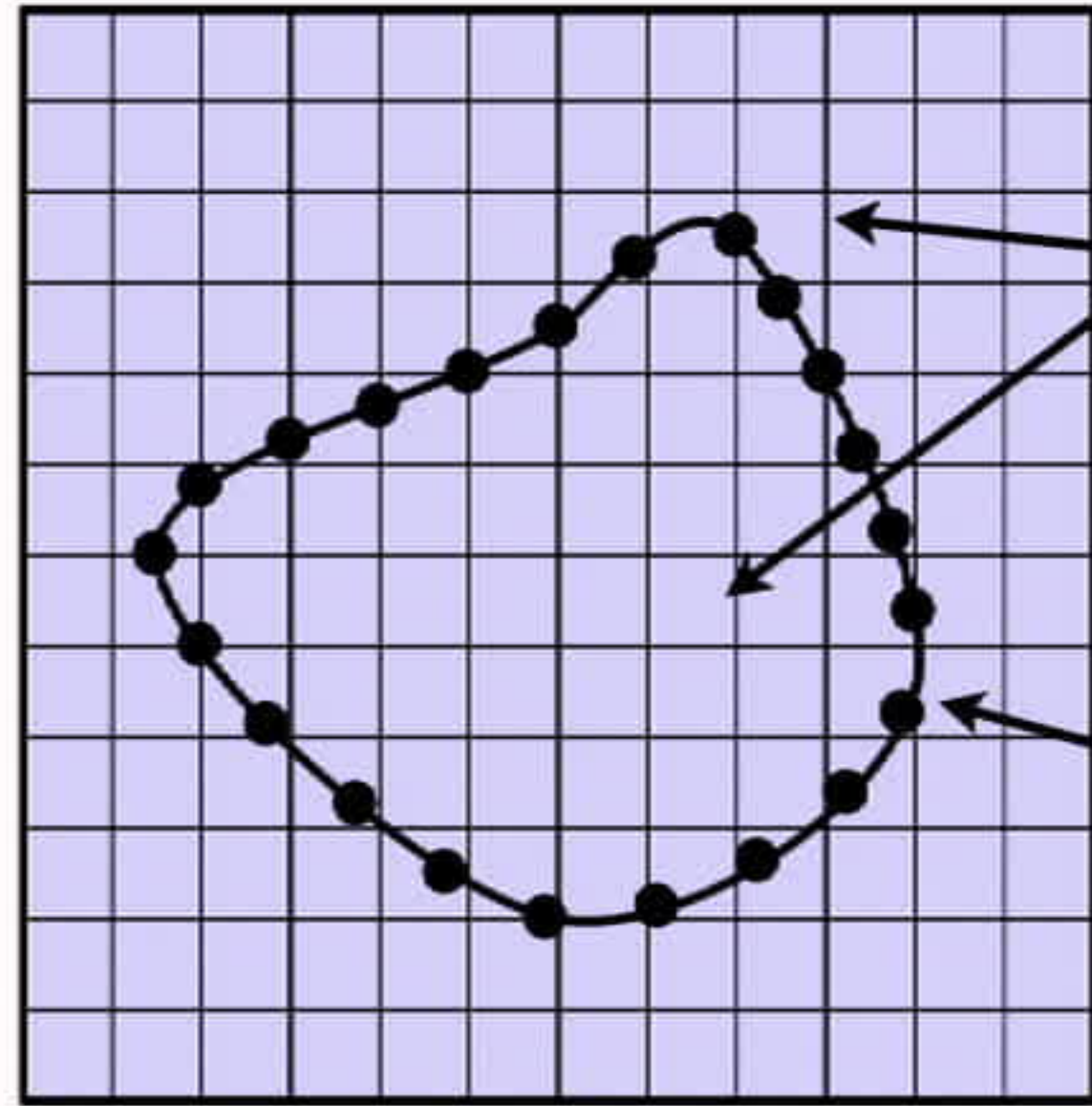
Grace McLaughlin and Laura Miller, UNC-Chapel Hill

Copyright David Lentink | Wageningen University | 2009



Lentink and Dickinson, *Science*, 2009

The immersed boundary method



(i, j, k) labels Cartesian grid cells
 $\mathbf{x}_{i,j,k}$ is the physical position of grid cell (i, j, k)
 $\mathbf{u}_{i,j,k}$ is the Eulerian velocity at grid cell (i, j, k)
 $\mathbf{f}_{i,j,k}$ is the Eulerian force at grid cell (i, j, k)

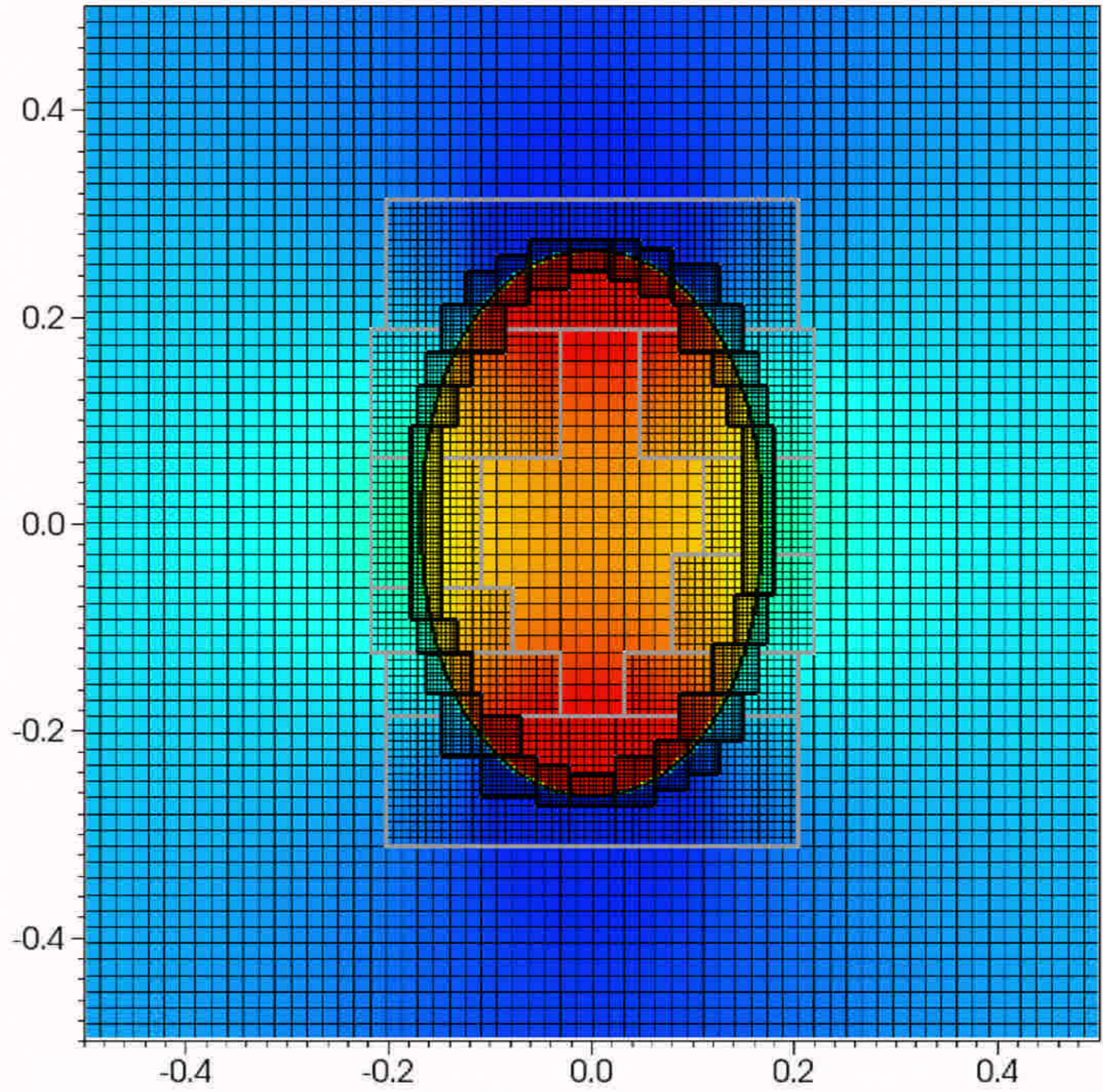
l labels Lagrangian mesh nodes
 \mathbf{x}_l is the physical position of node l
 \mathbf{U}_l is the Lagrangian velocity at node l
 \mathbf{F}_l is the Lagrangian force at node l

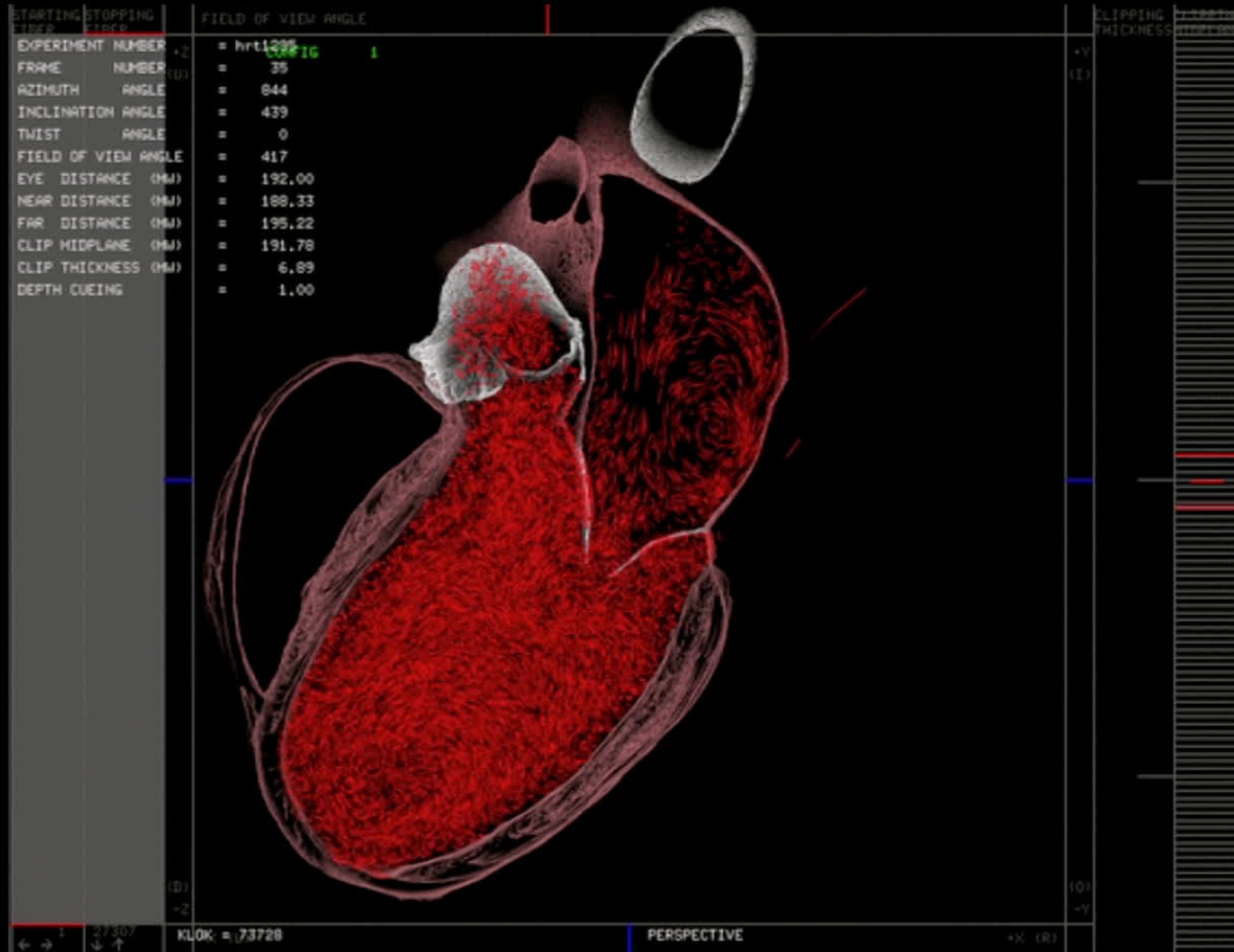
Forces are *spread* from the boundary to nearby Cartesian grid points:

$$\mathbf{f}_{i,j,k} = \sum_l \mathbf{F}_l \delta_h(\mathbf{x}_{i,j,k} - \mathbf{x}_l) \Delta \mathbf{q}$$

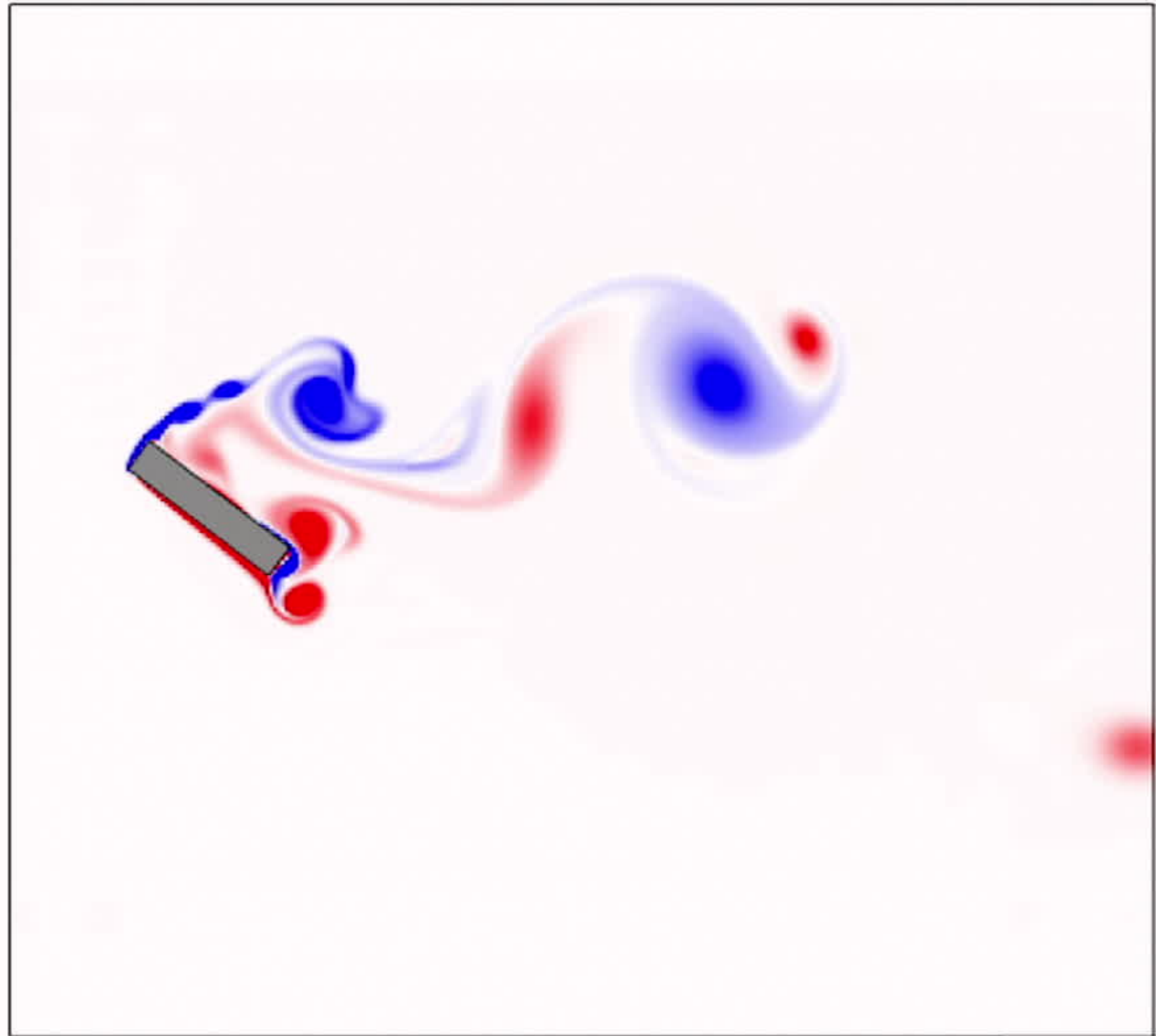
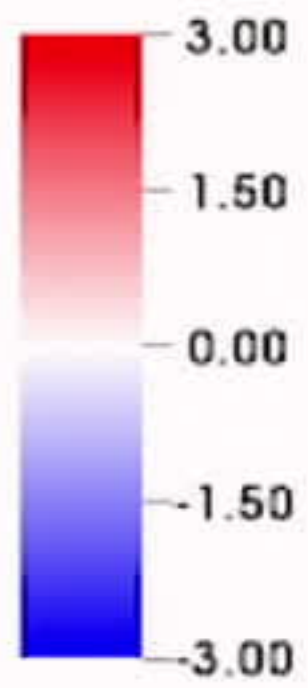
Velocities are *interpolated* to the boundary from nearby Cartesian grid points:

$$\mathbf{U}_l = \sum_{i,j,k} \mathbf{u}_{i,j,k} \delta_h(\mathbf{x}_{i,j,k} - \mathbf{x}_l) \Delta \mathbf{x}$$

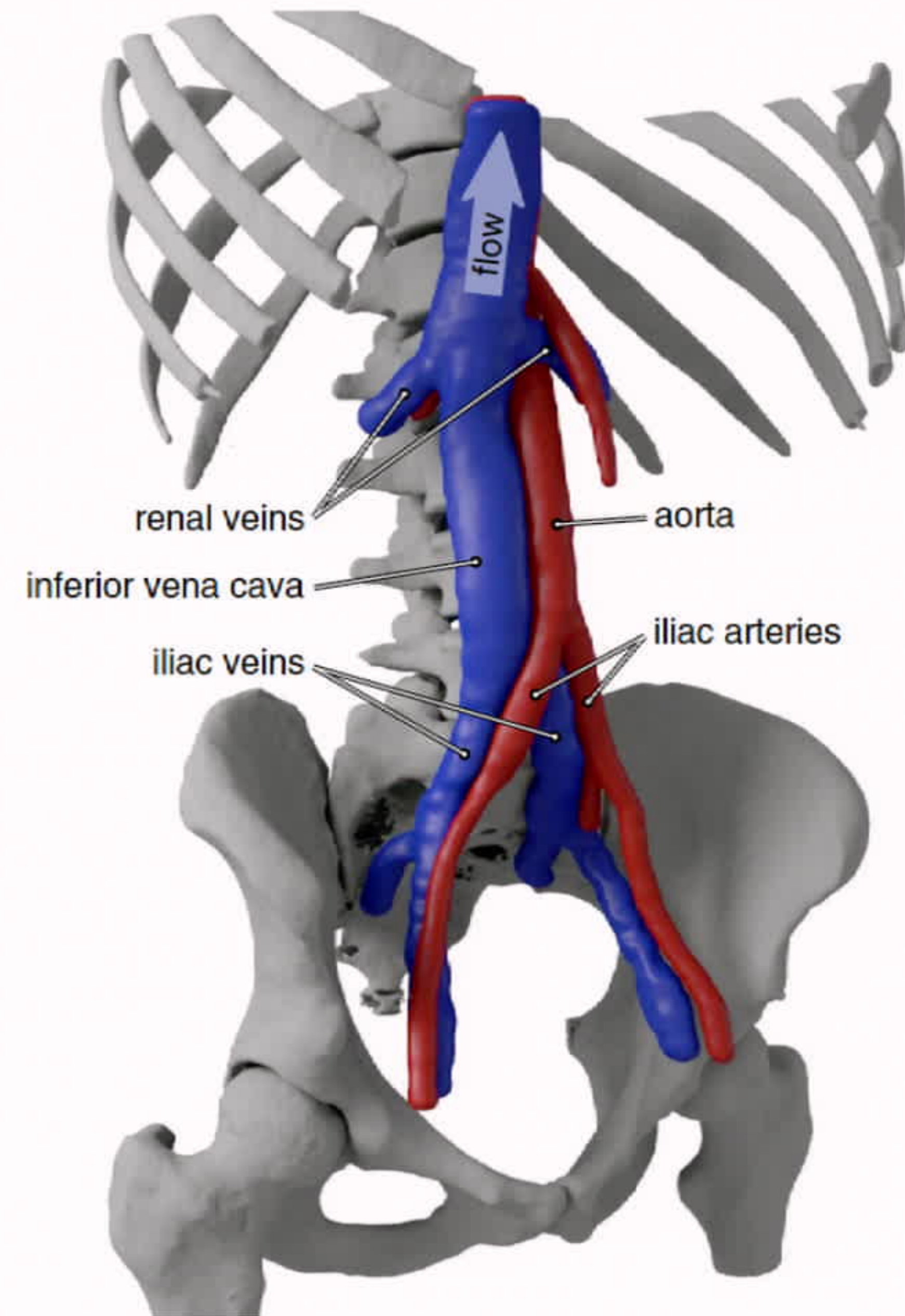




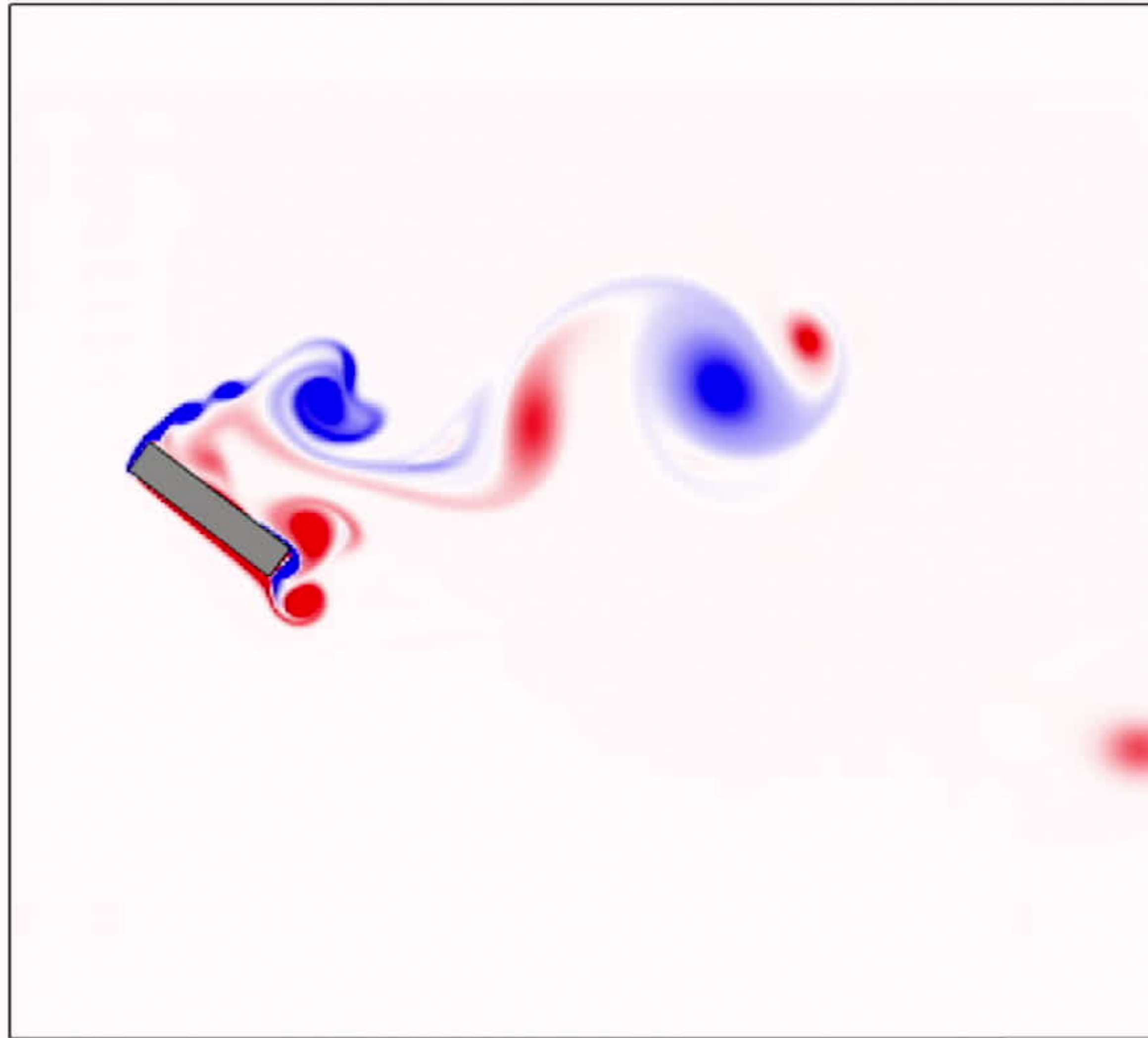
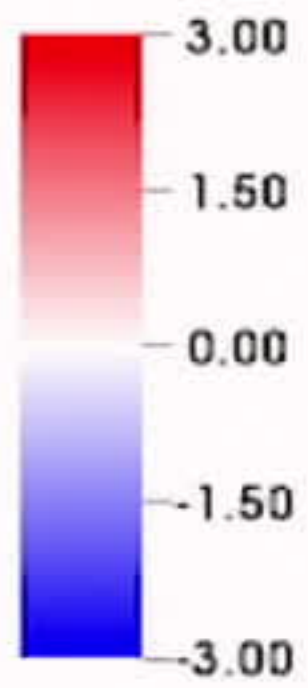
Charles Peskin and David McQueen, NYU



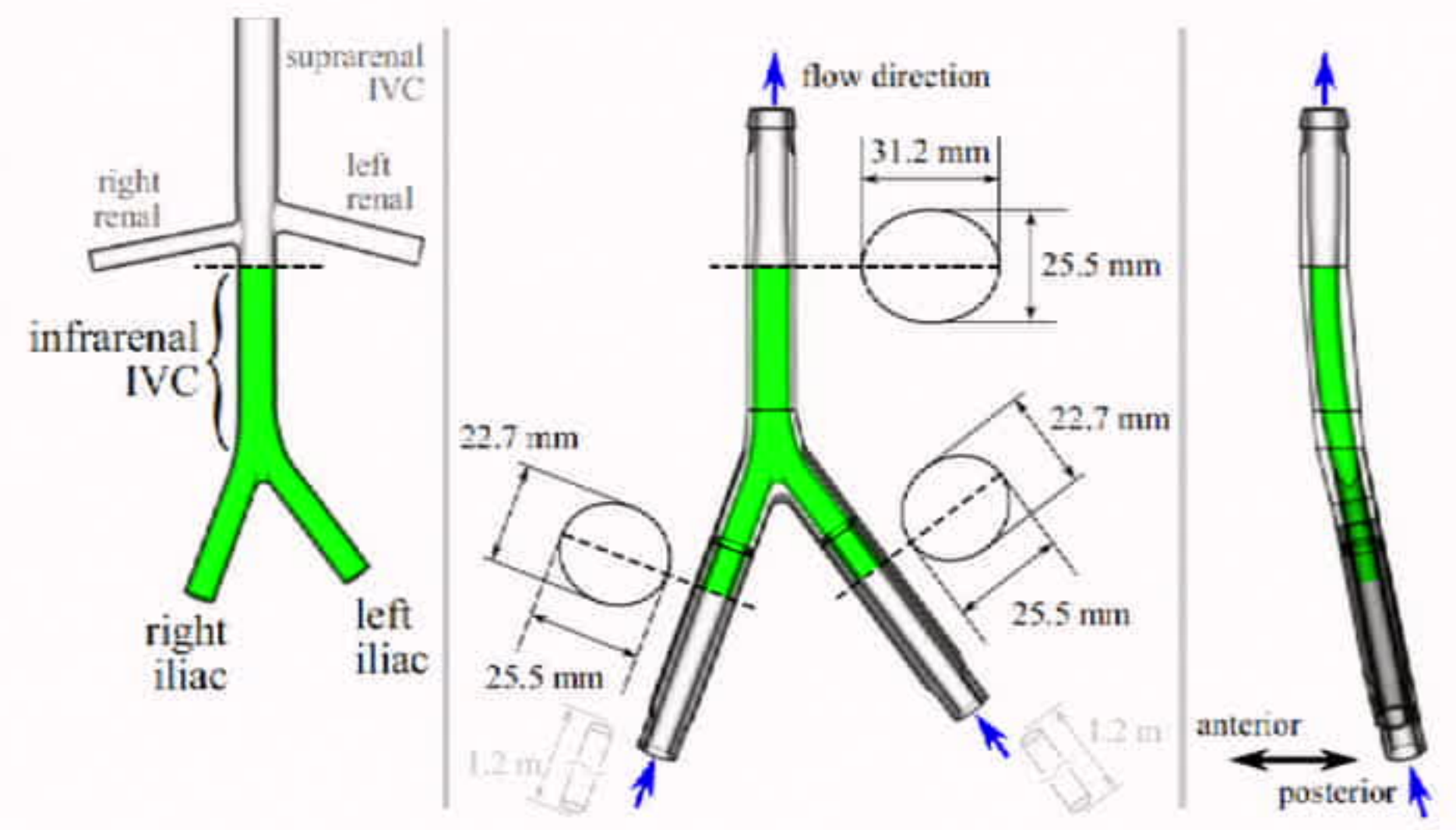
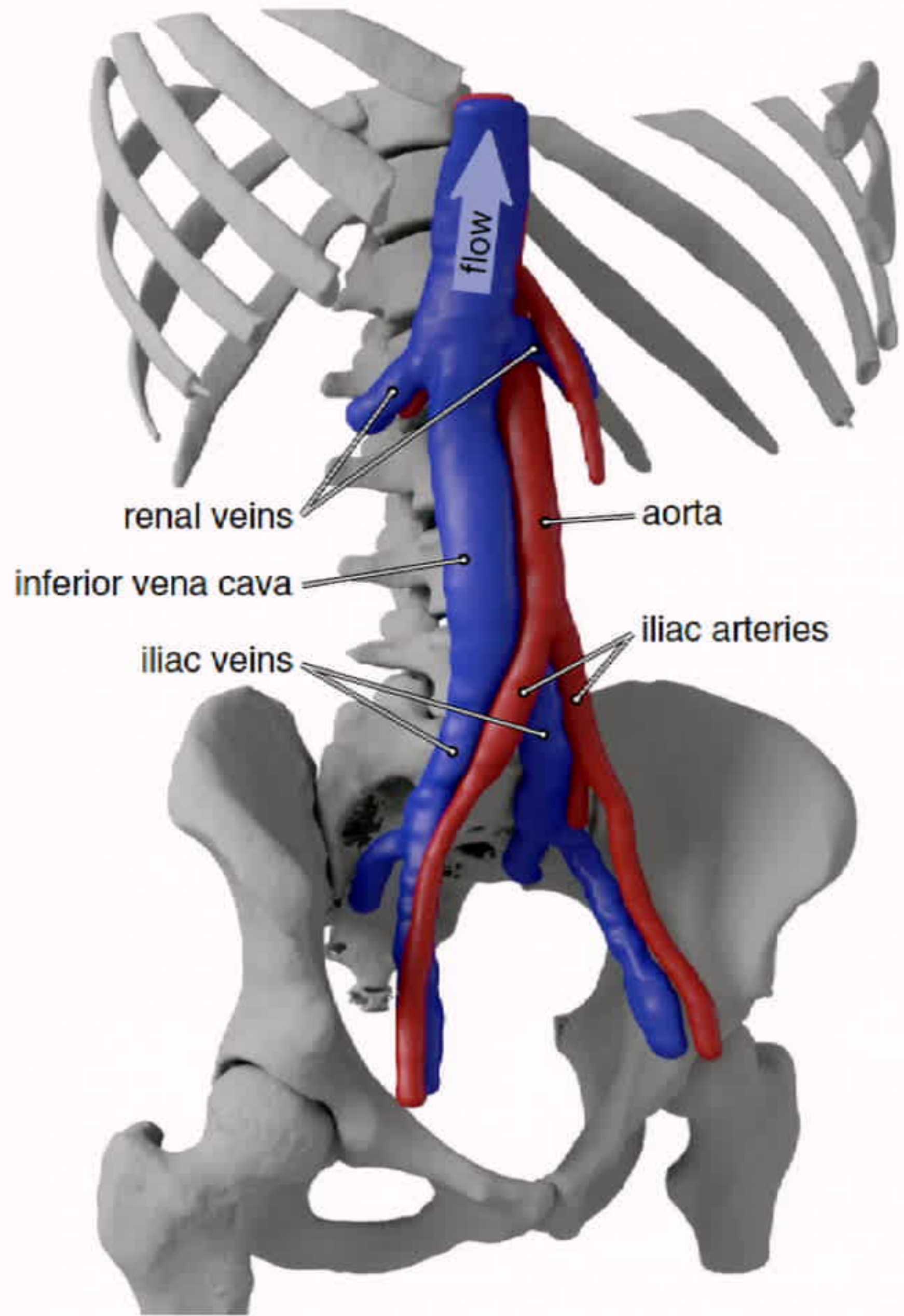
Amin Kolahehdouz (UNC-Chapel Hill & FDA) and Brent Craven (FDA)



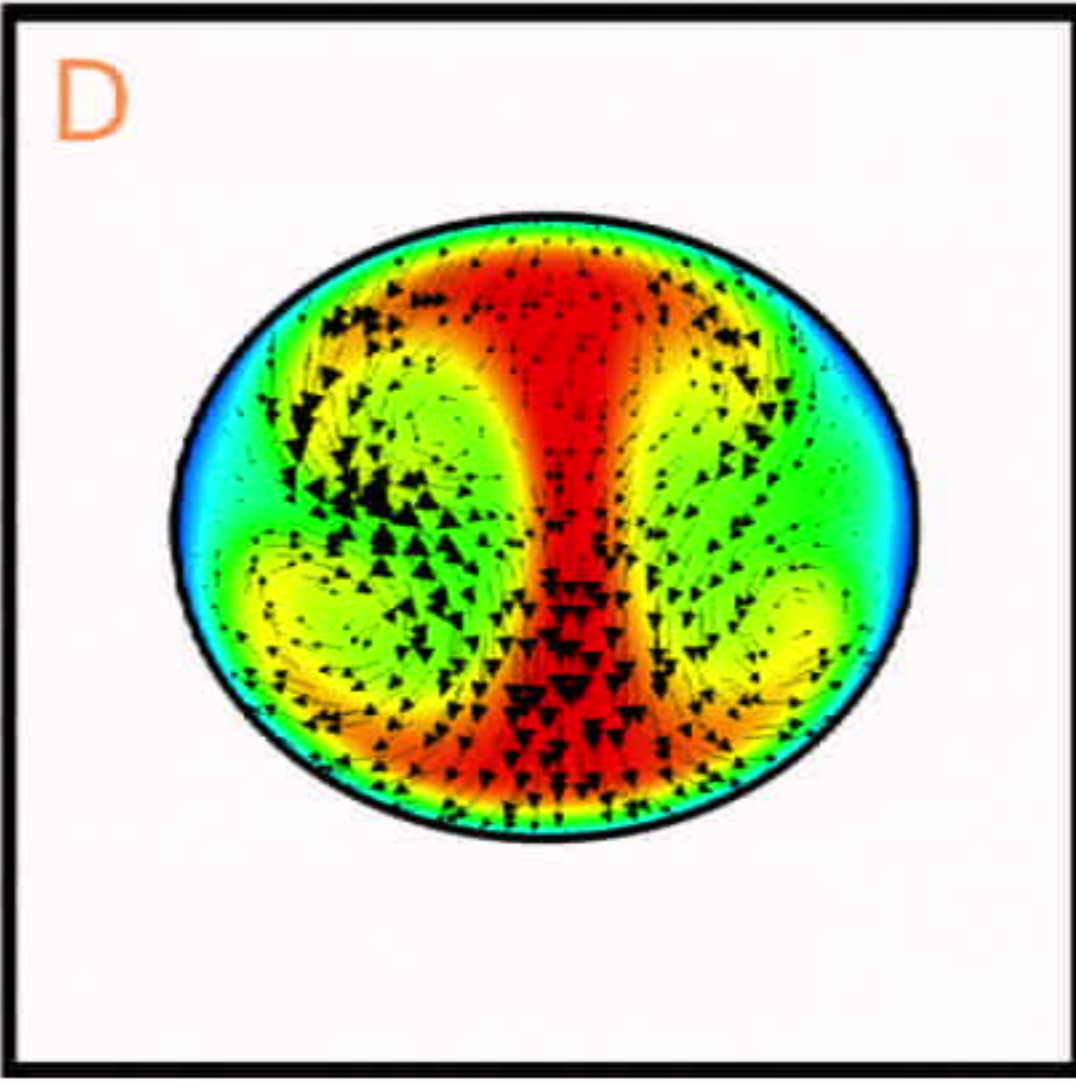
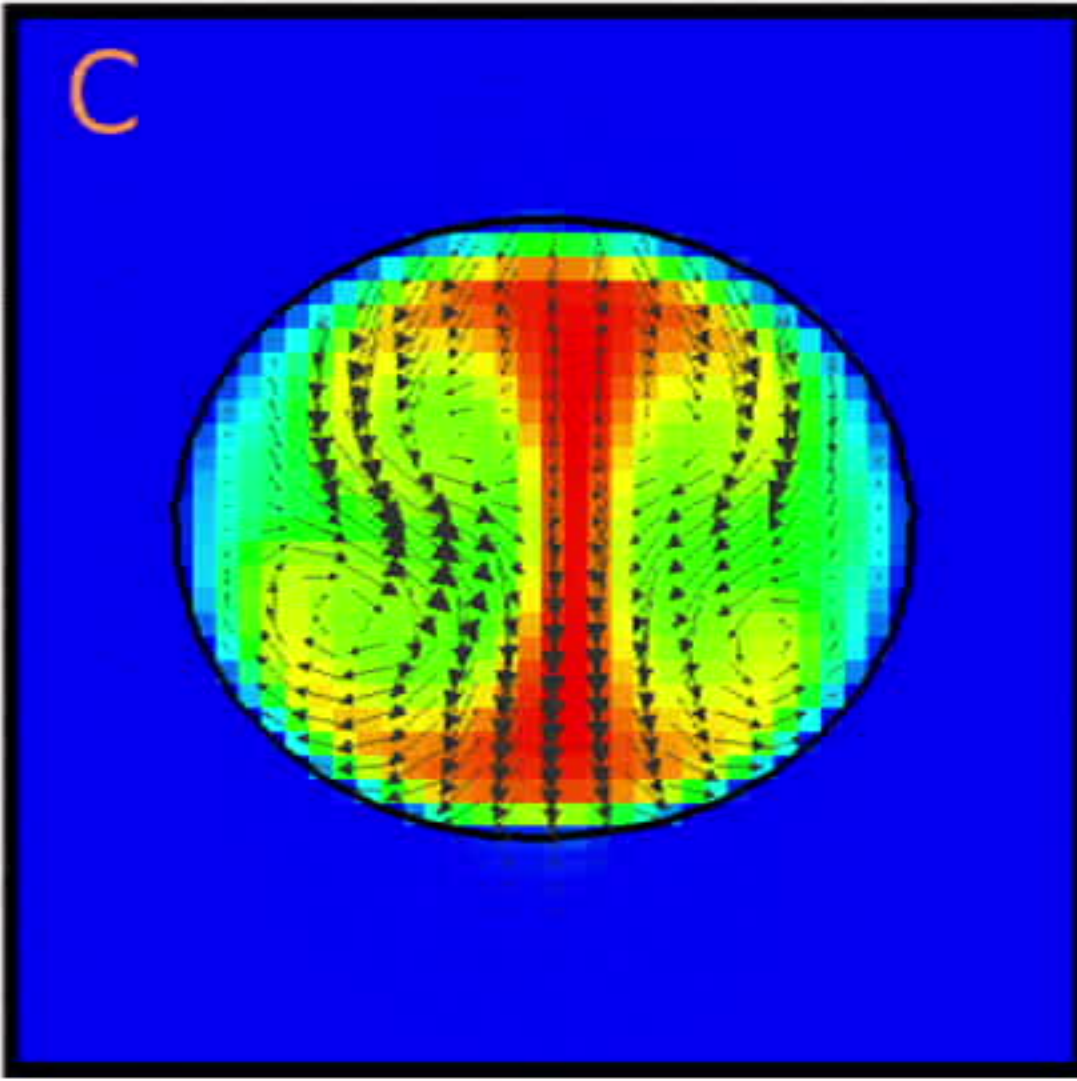
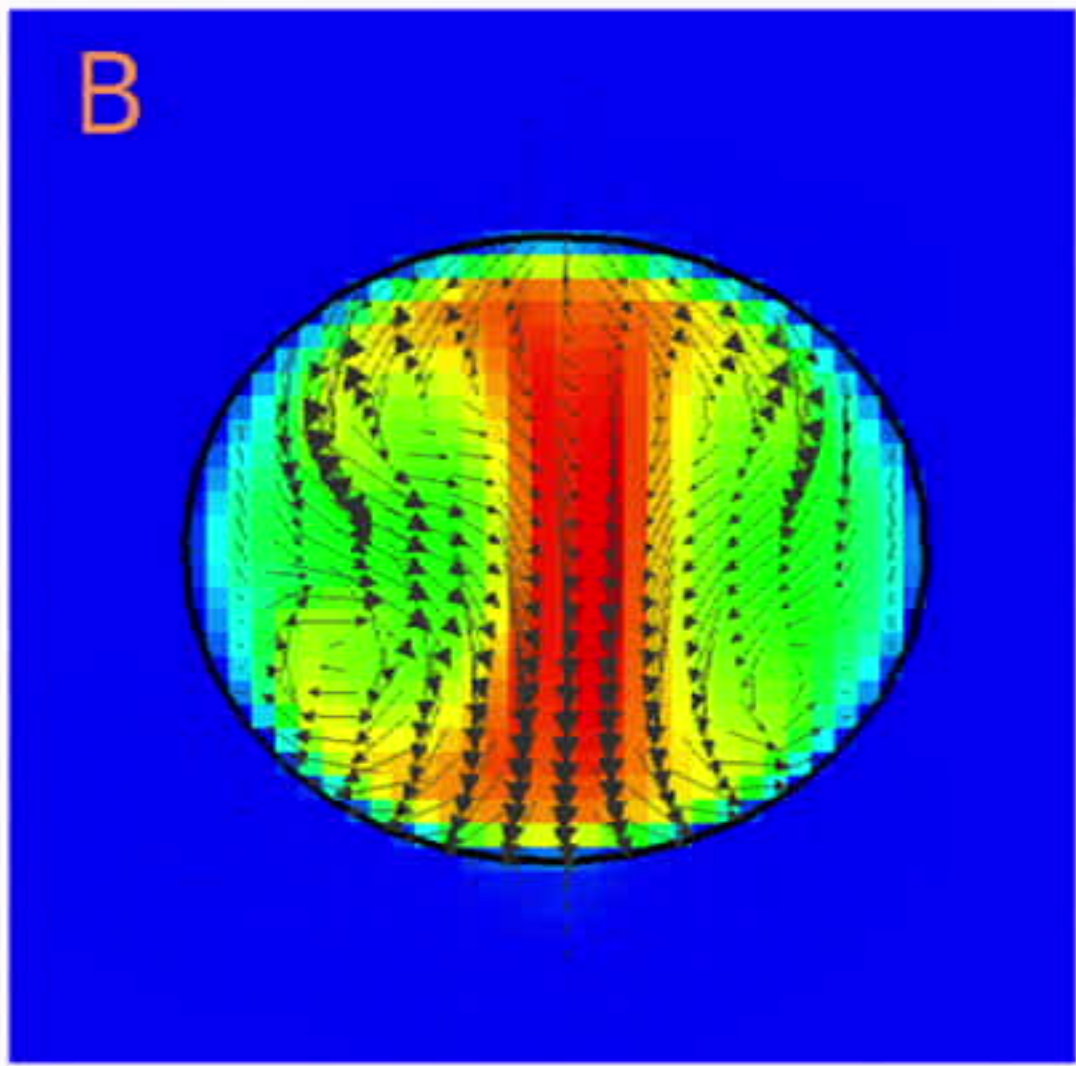
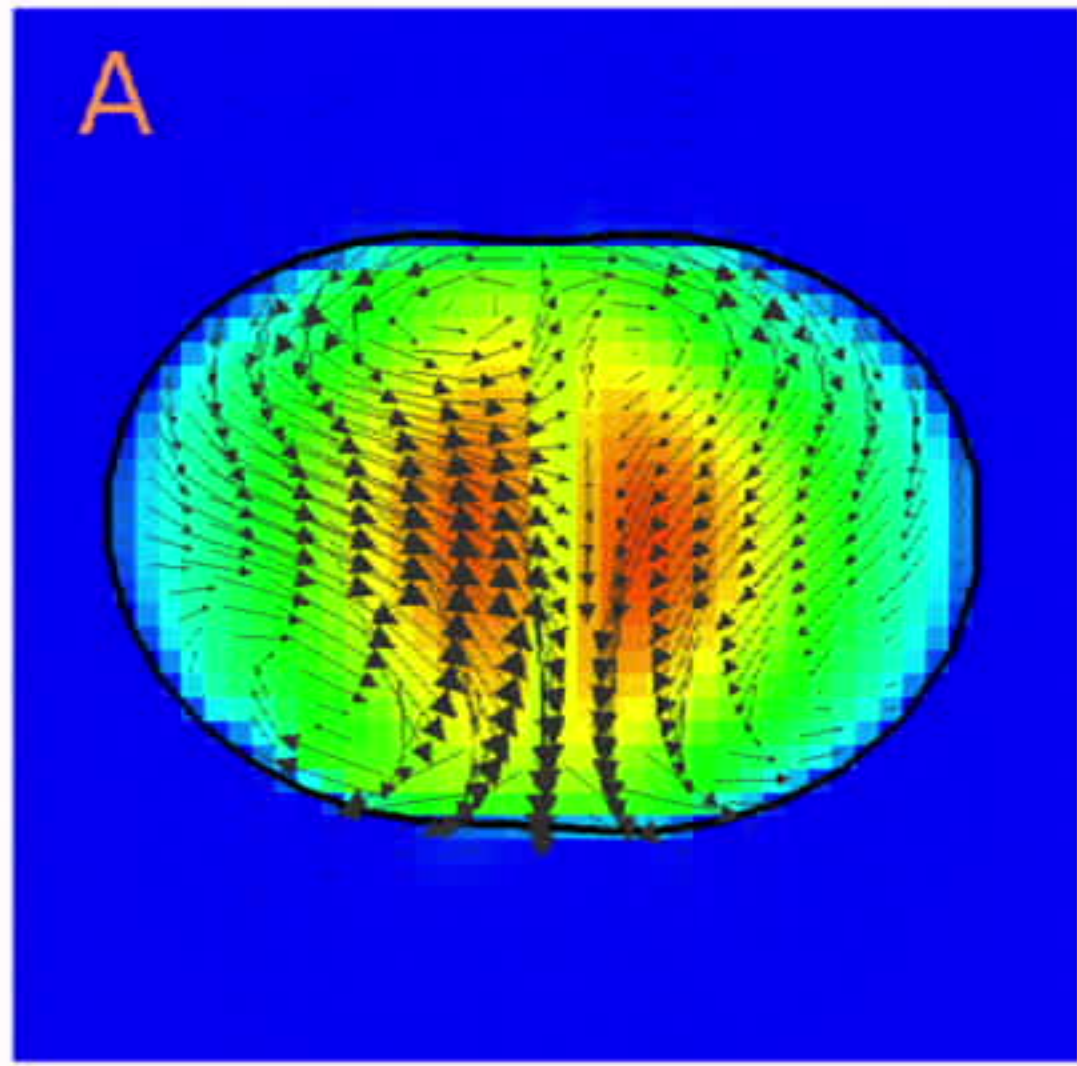
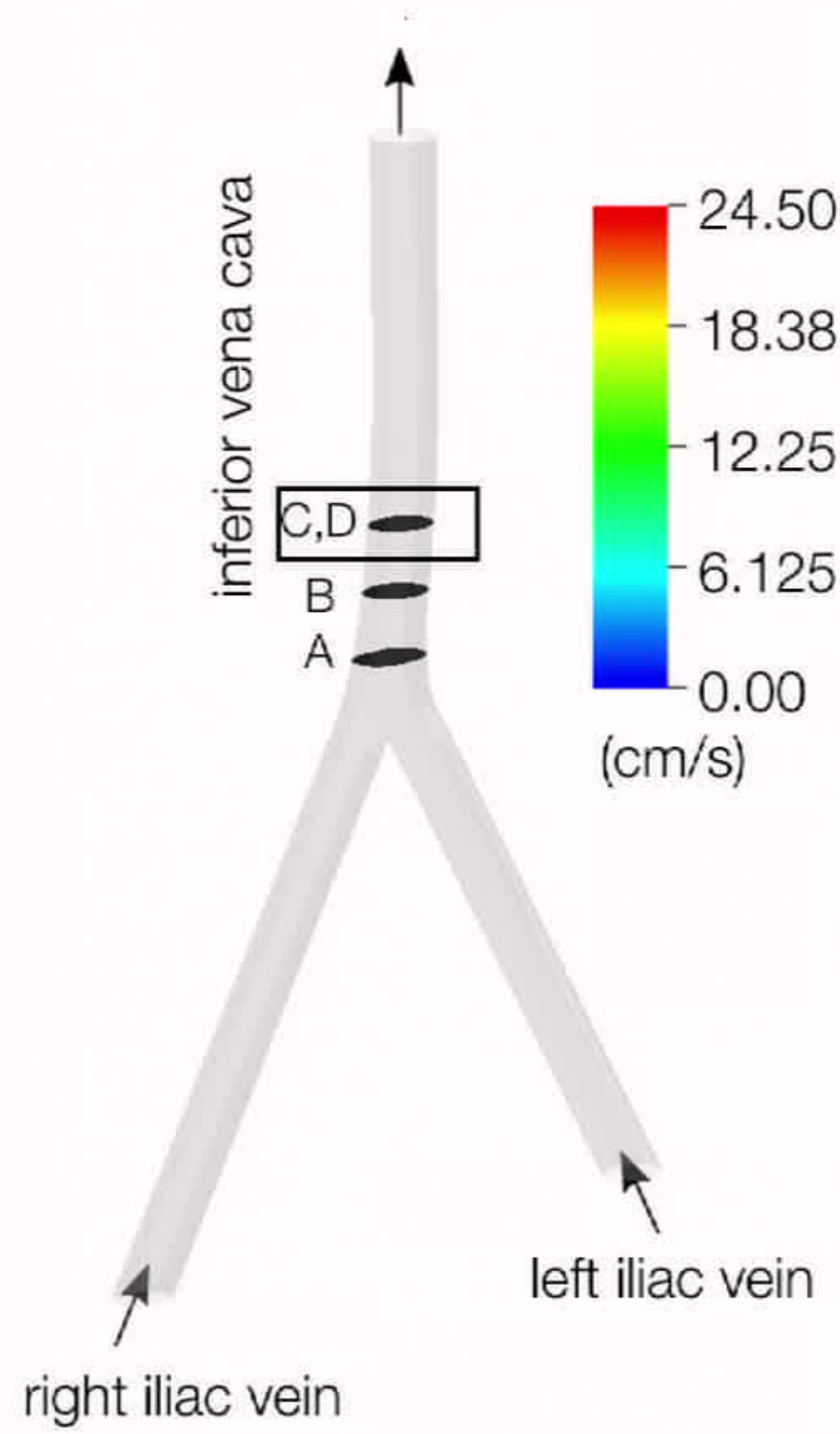
Amin Kolahehdouz (UNC-Chapel Hill & FDA) and Brent Craven (FDA)

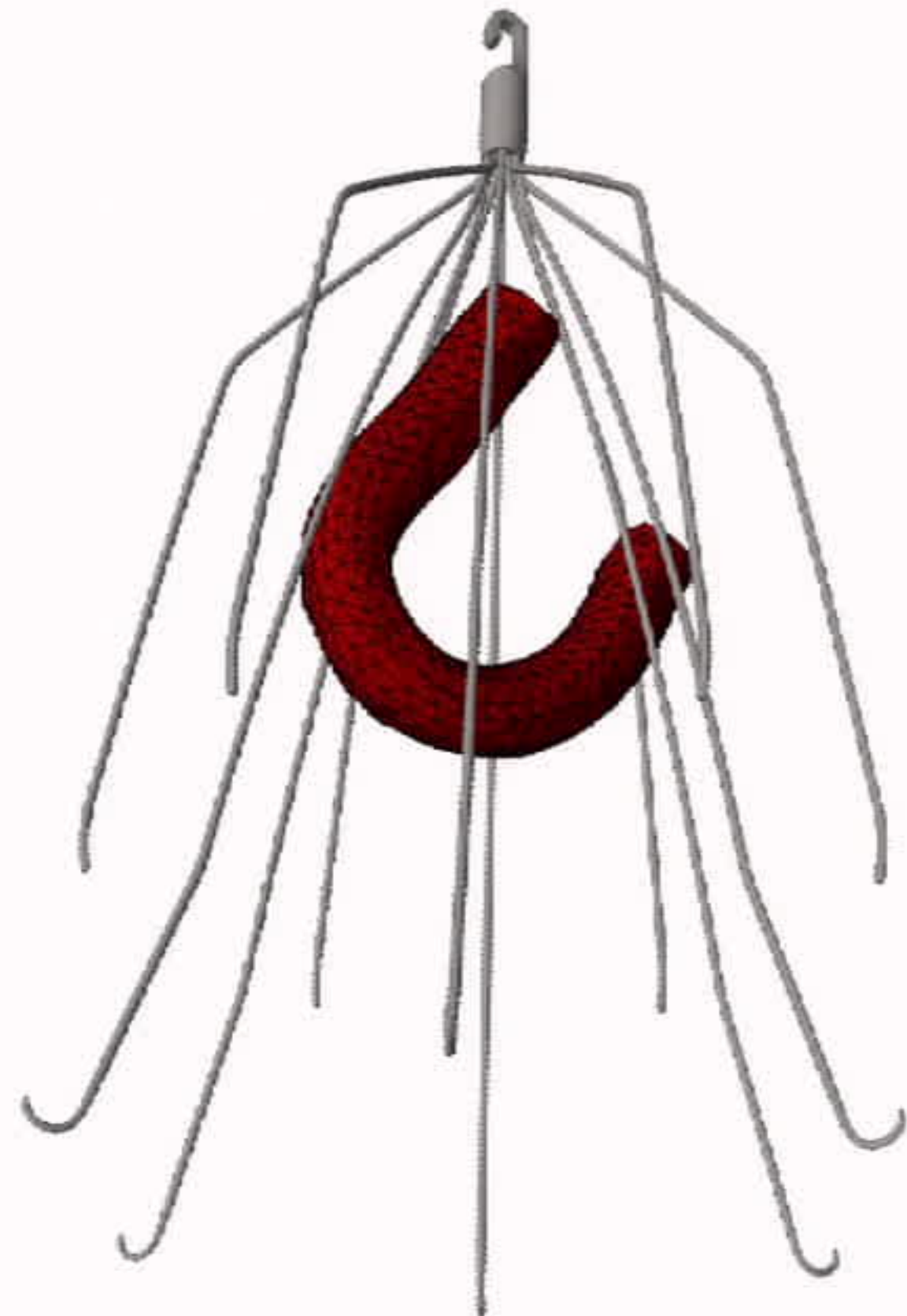
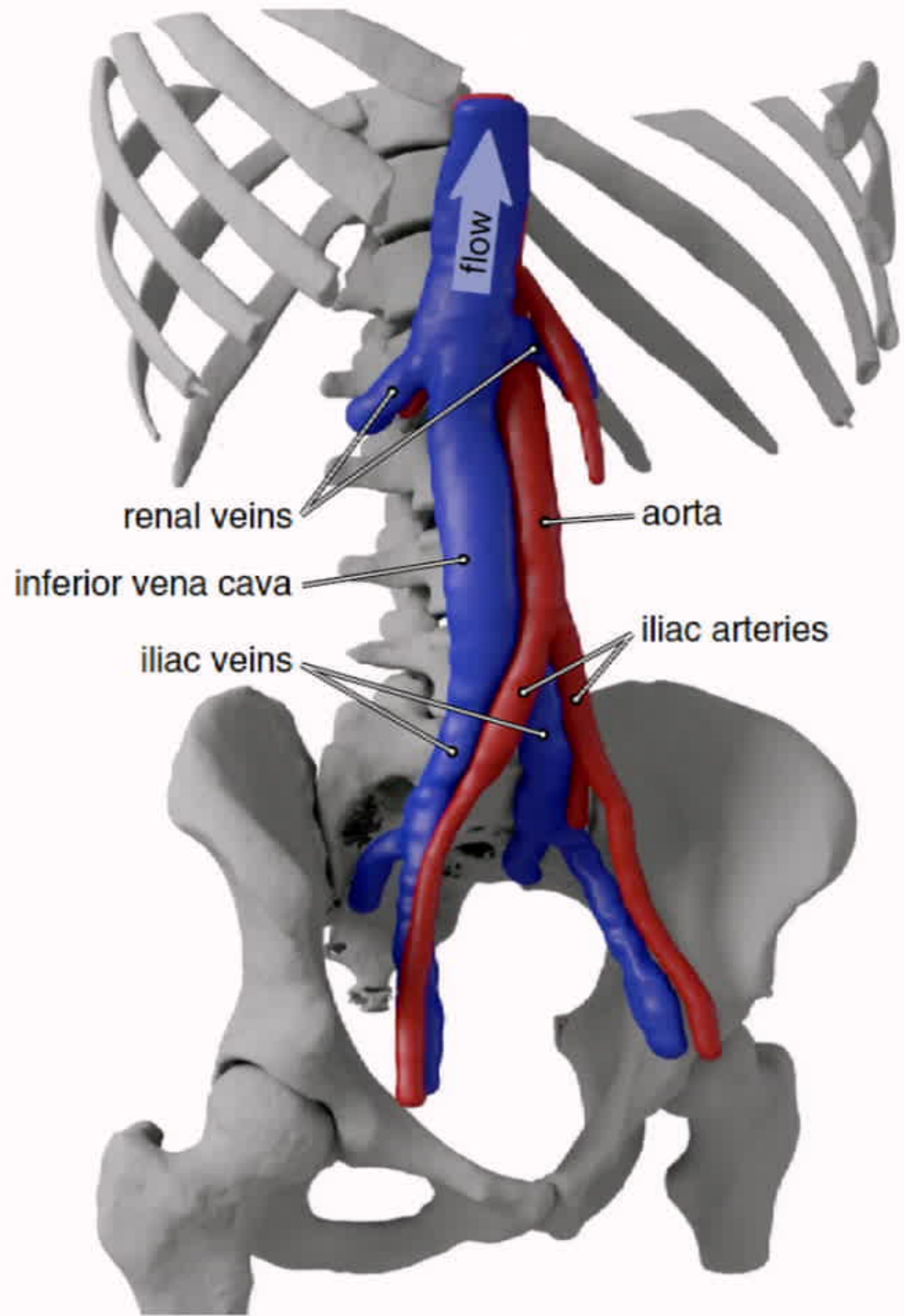


Amin Kolahdouz (UNC-Chapel Hill & FDA) and Brent Craven (FDA)

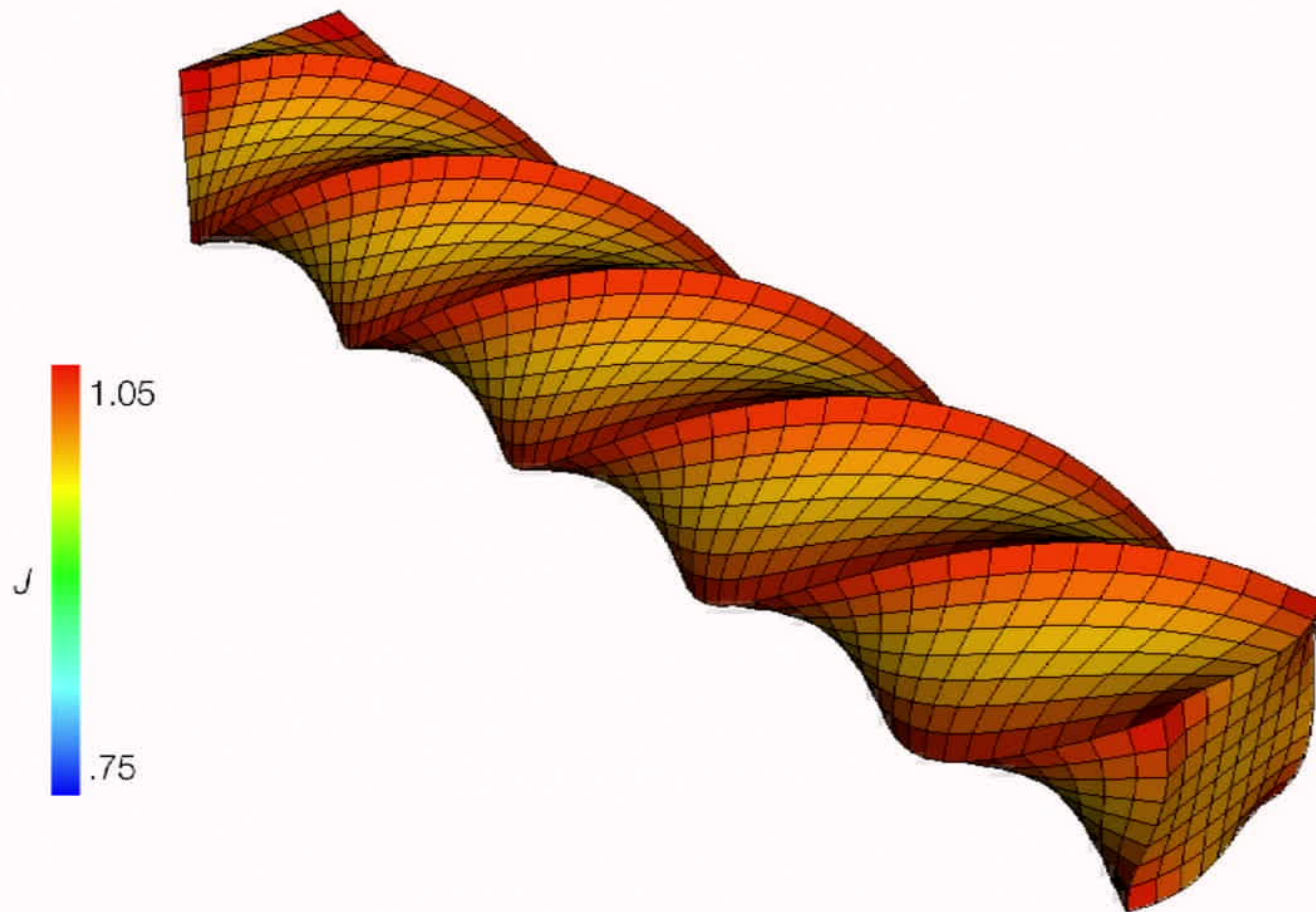


Amin Kolahe Douz (UNC-Chapel Hill & FDA) and Brent Craven (FDA)





With Amin Kolahehdouz (UNC-Chapel Hill & FDA) and Alex Rygg and Brent Craven (FDA)



Hyperelasticity: $\mathbb{P}^s = \frac{\partial W}{\partial \mathbb{F}}$, $\mathbb{F} = \frac{\partial \boldsymbol{\chi}}{\partial \mathbf{X}}$, $J = \det(\mathbb{F})$

Mooney-Rivlin: $W = a(I_1 - 3) + b(I_2 - 3)$, $I_1 = \text{tr}(\mathbb{C})$, $I_2 = \frac{1}{2}(I_1^2 - \text{tr}(\mathbb{C}^2))$, $\mathbb{C} = \mathbb{F}^T \mathbb{F}$

Add a volumetric energy to *stabilize*: $W_{\text{stab}} = W(\mathbb{F}) + \beta_s U(J)$ (incompressible: $J \equiv 1$)

Use *modified* deformation gradient: $\bar{\mathbb{W}}_{\text{stab}} = W(\bar{\mathbb{F}}) + \beta_s U(J)$, $\bar{\mathbb{F}} = J^{-\frac{1}{3}} \mathbb{F}$

These computations use the open-source **IBAMR** software.

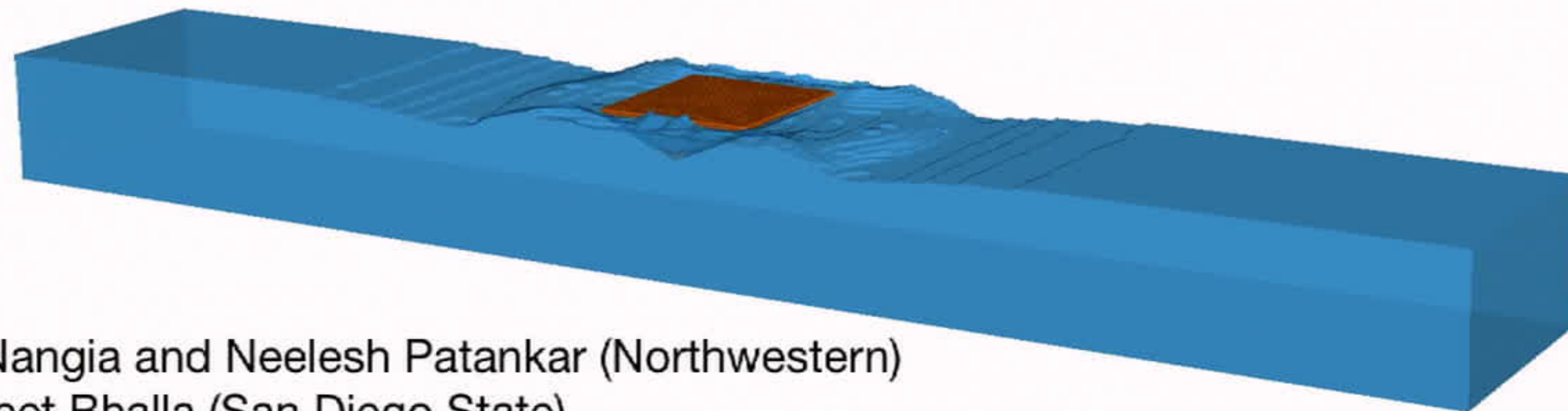
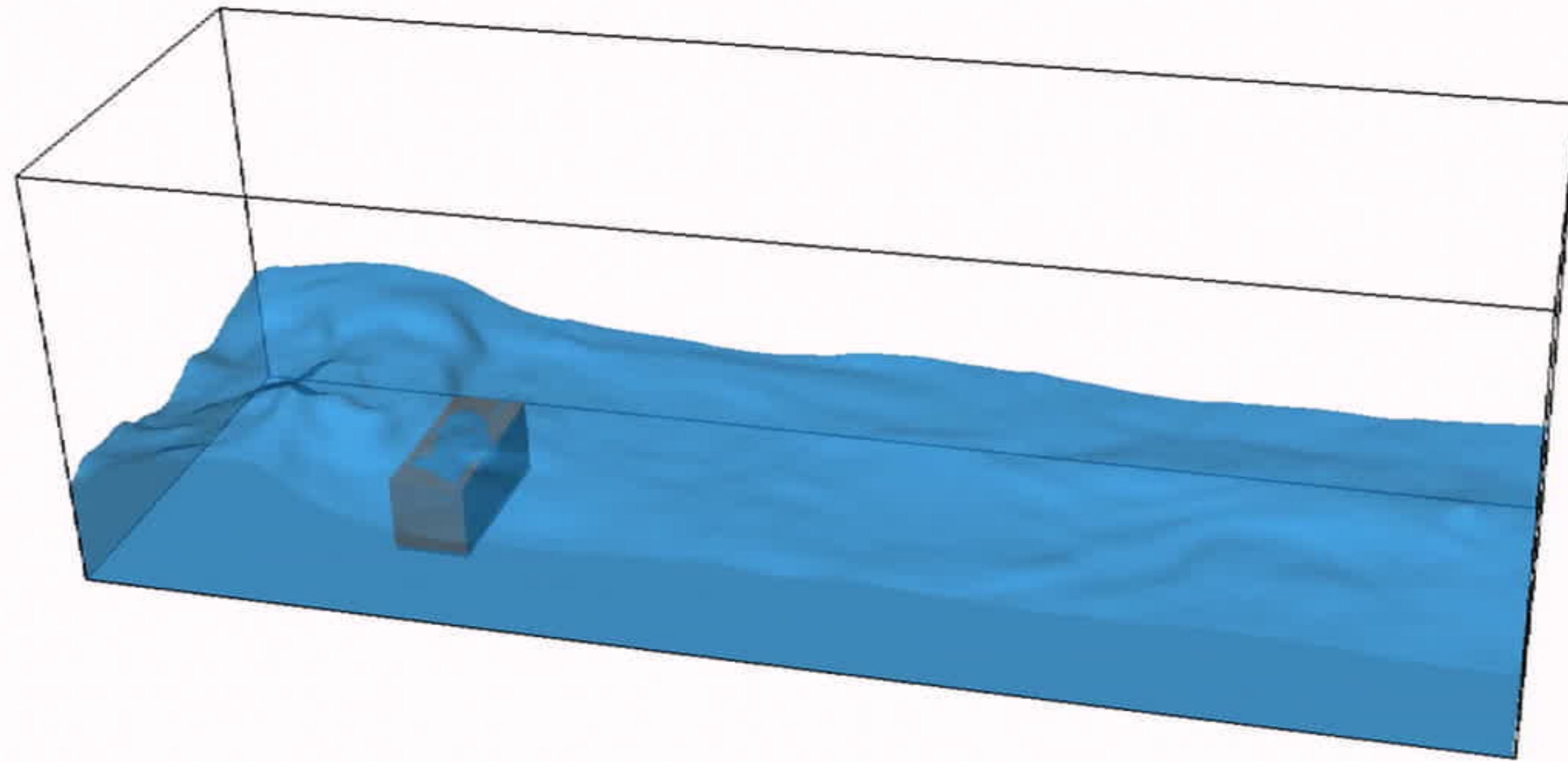
Software infrastructure: IBAMR relies on other open-source software, including PETSc, SAMRAI, and *hypra*. Finite element computations rely on `libMesh`.

Impact: 80+ peer-reviewed publications, 15+ PhD theses, many undergraduate theses and conference abstracts

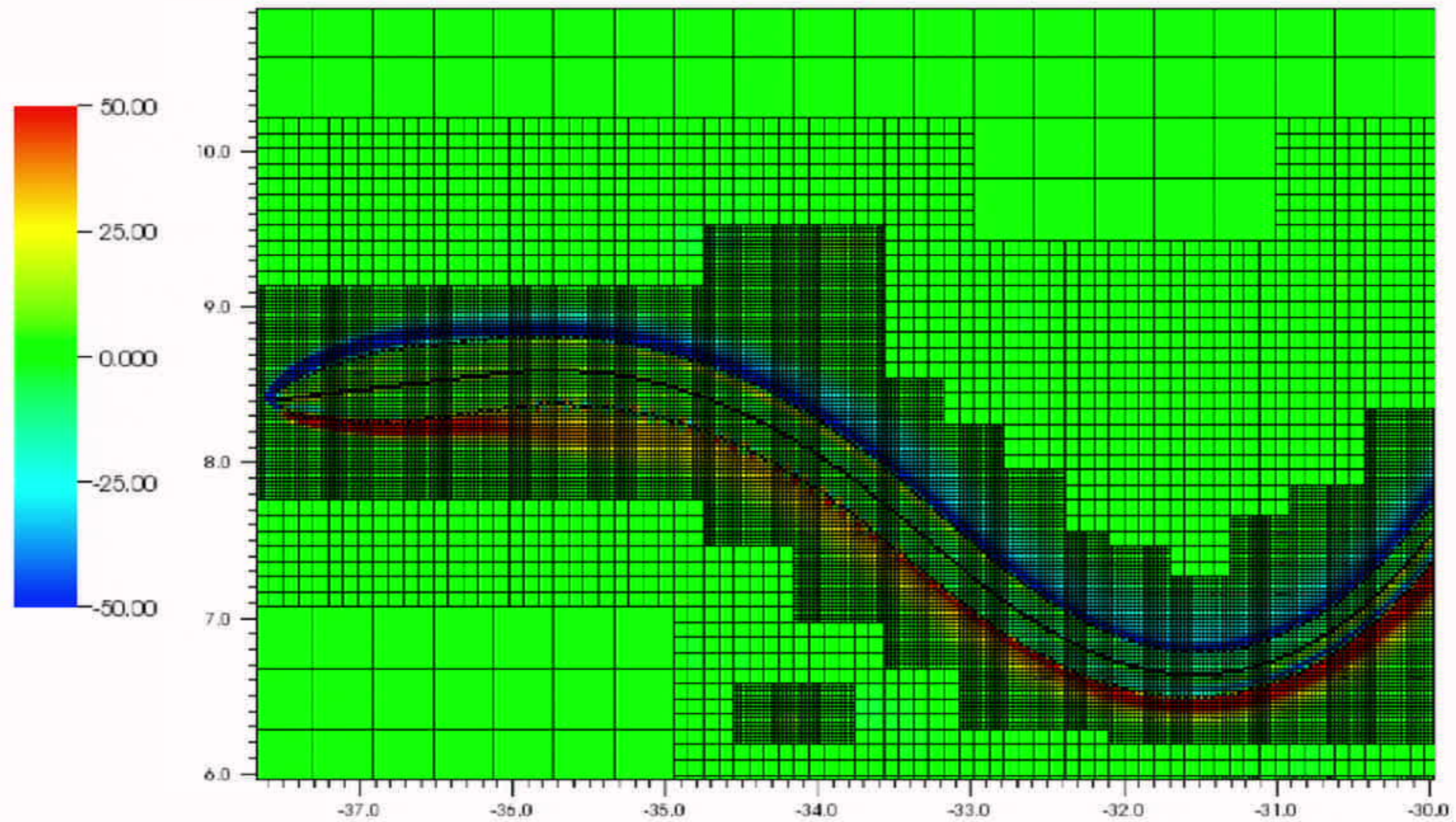
Other modeling approaches provided by IBAMR include:

- *thin rods*, with Sook Lim (Cincinnati)
- *deformational constraints*, with Amneet Bhalla (San Diego State), Aleks Donev (NYU-Courant), and Neelesh Patankar (Northwestern)
- *thermal fluctuations*, with Donev, Patankar, and co-workers
- *complex fluids*, in work by Aaron Barrett (UNC) with Greg Forest (UNC) and Bob Guy and Becca Thomases (UC-Davis)
- *multiphase flows*, in work by Nishant Nangia (Northwestern) with Bhalla and Patankar

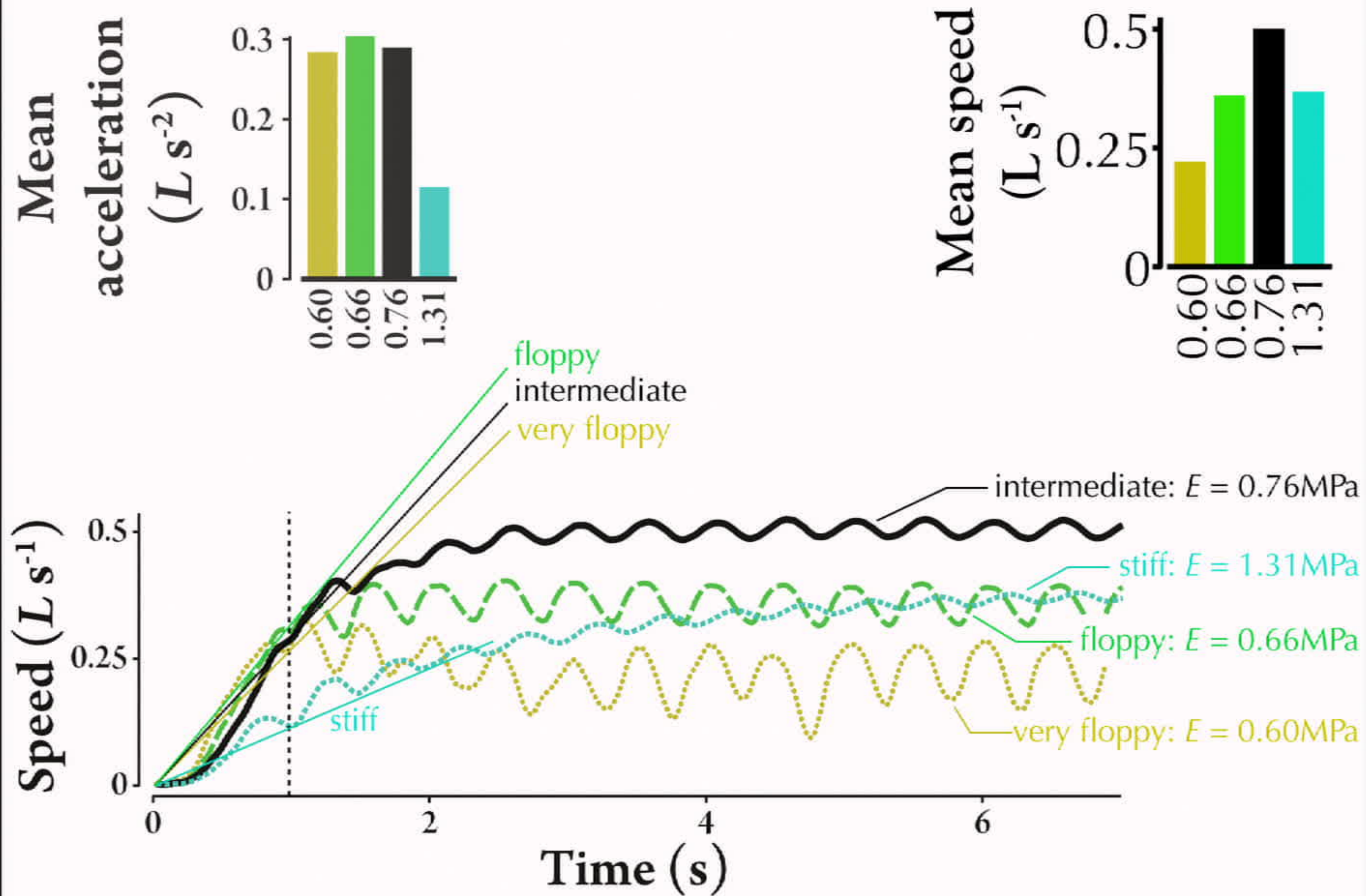
`ibamr.github.io`

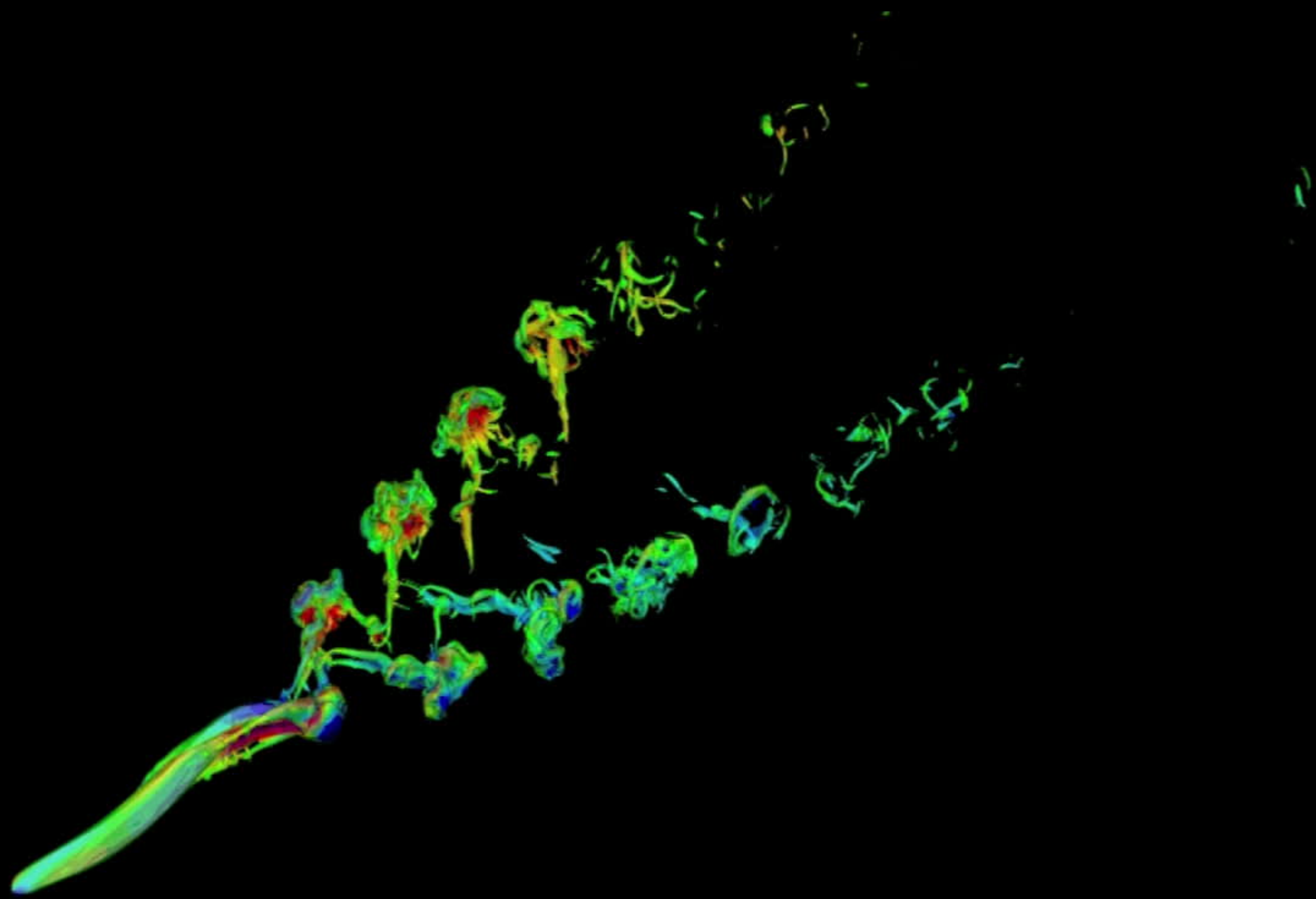


Nishant Nangia and Neelesh Patankar (Northwestern)
and Amneet Bhalla (San Diego State)

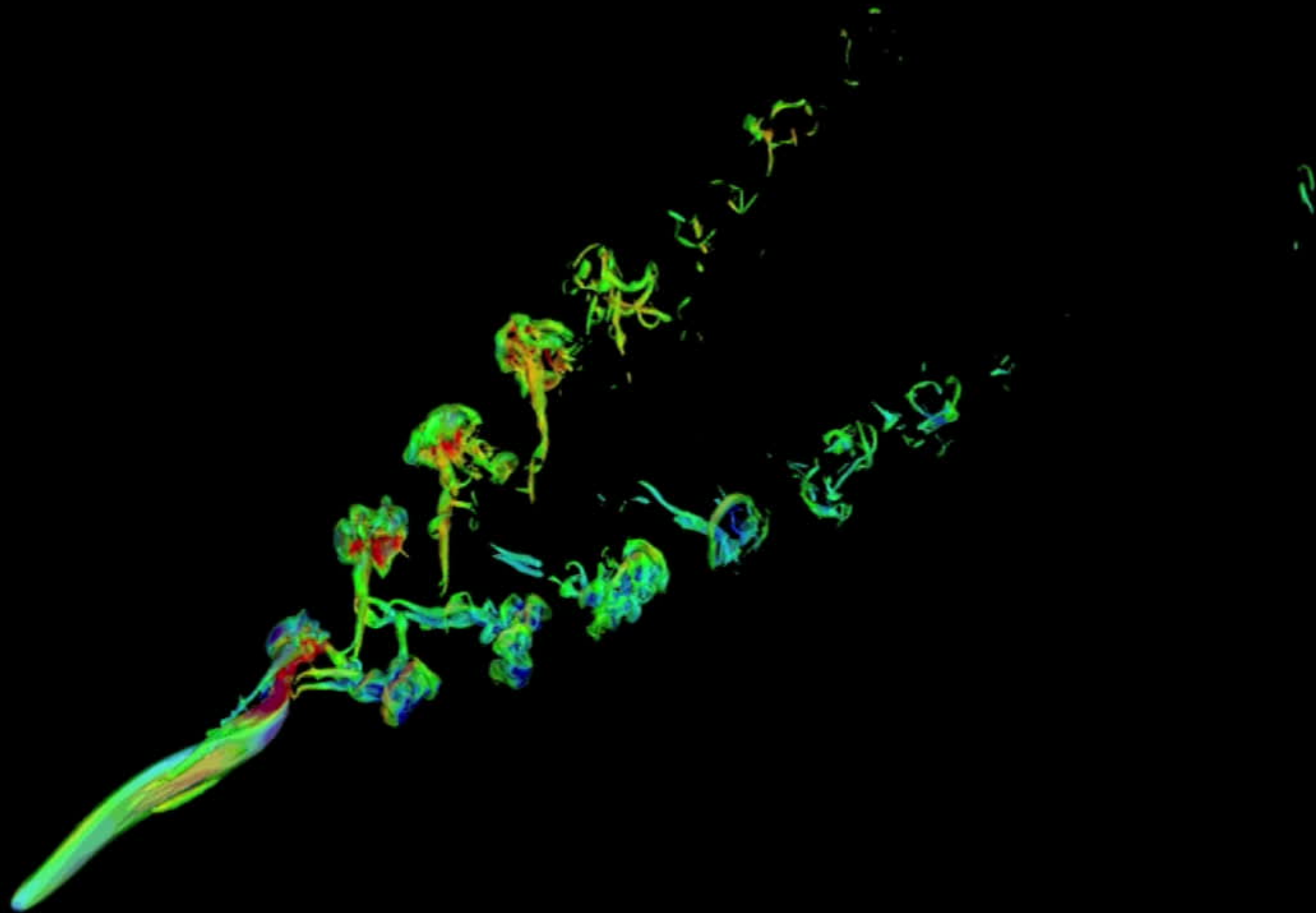


Tytell, Hsu, Williams, Cohen, Fauci, *PNAS* 2010

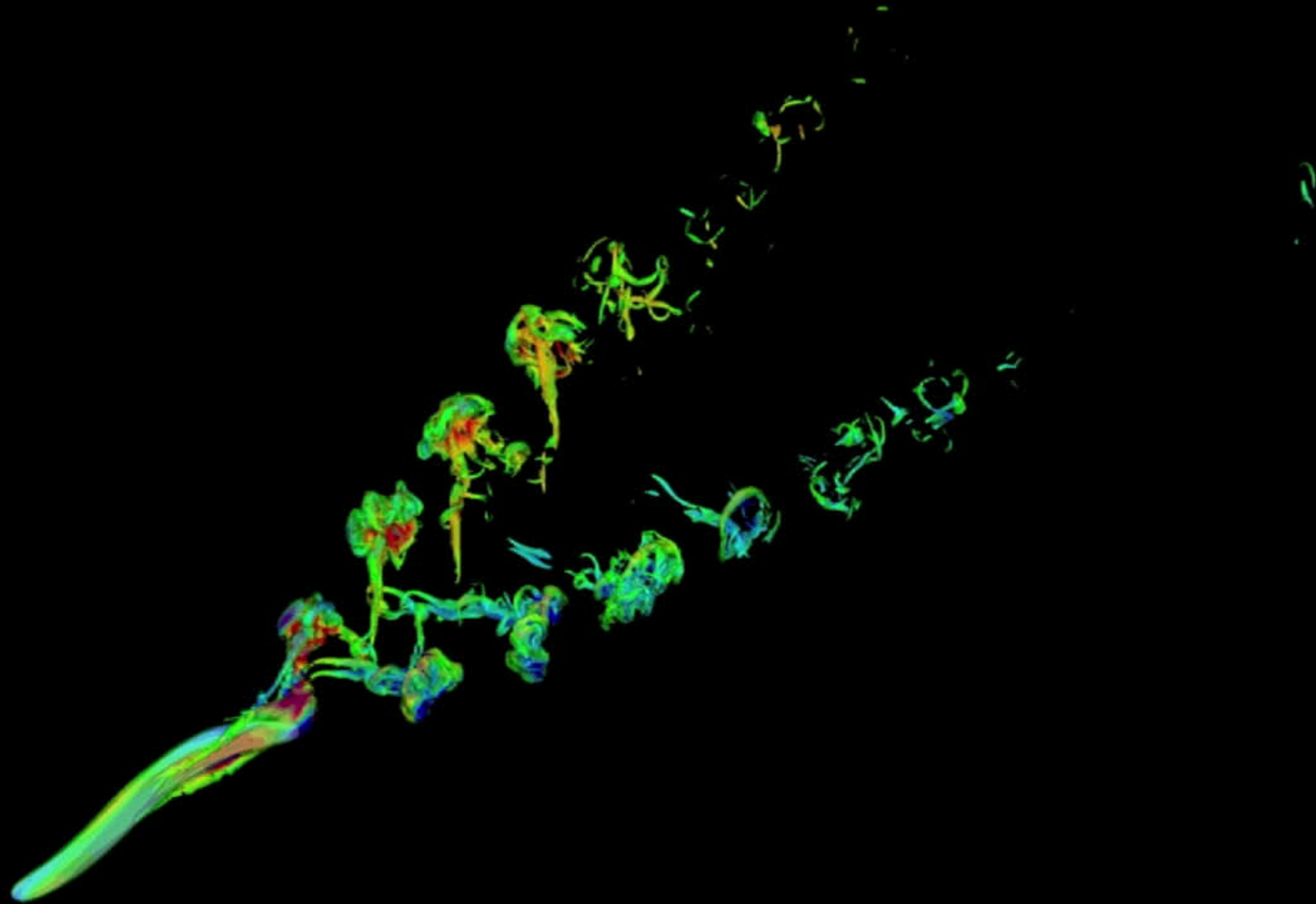




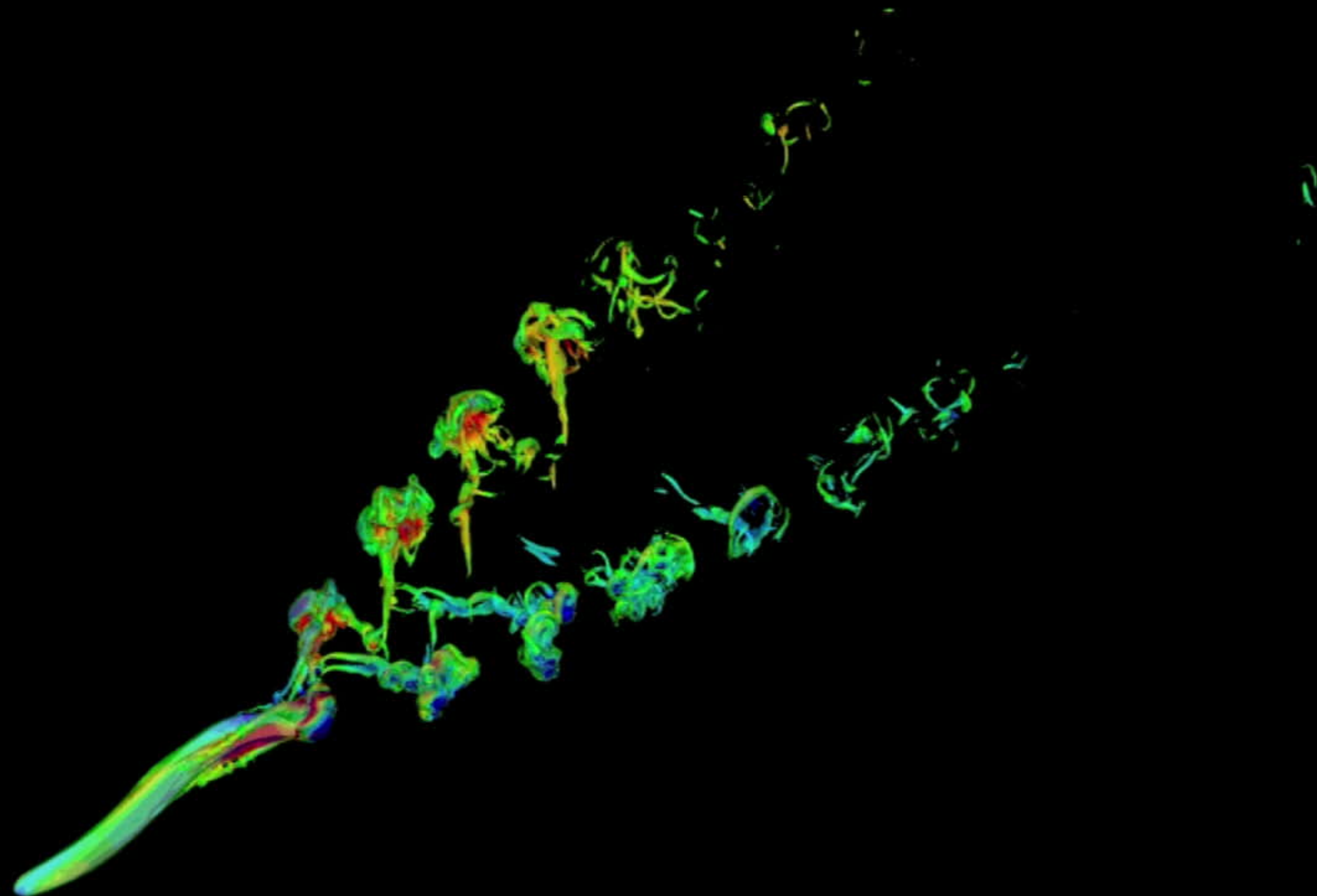
Amneet Bhalla (San Diego State) and Neelesh Patankar (Northwestern)



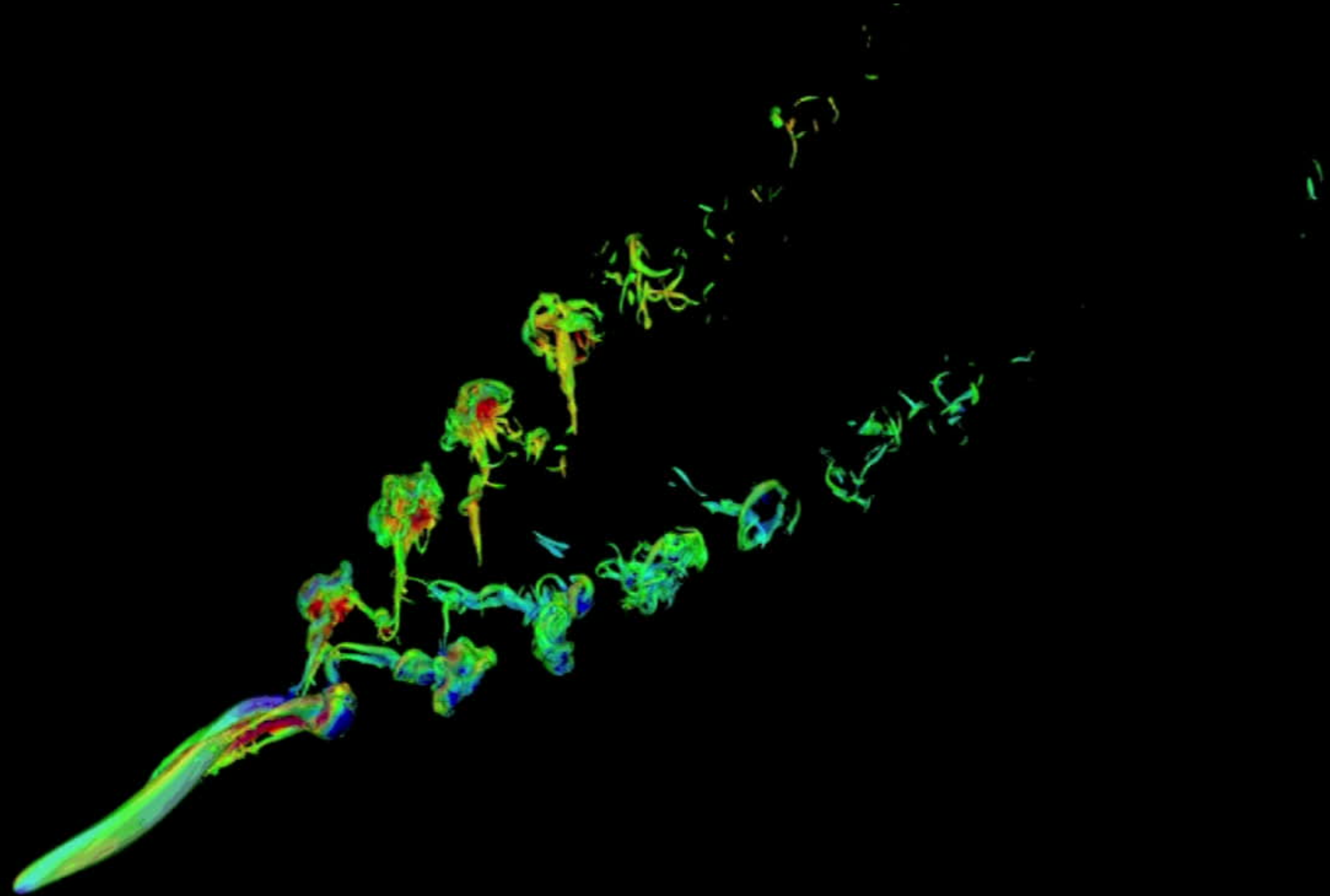
Amneet Bhalla (San Diego State) and Neelesh Patankar (Northwestern)



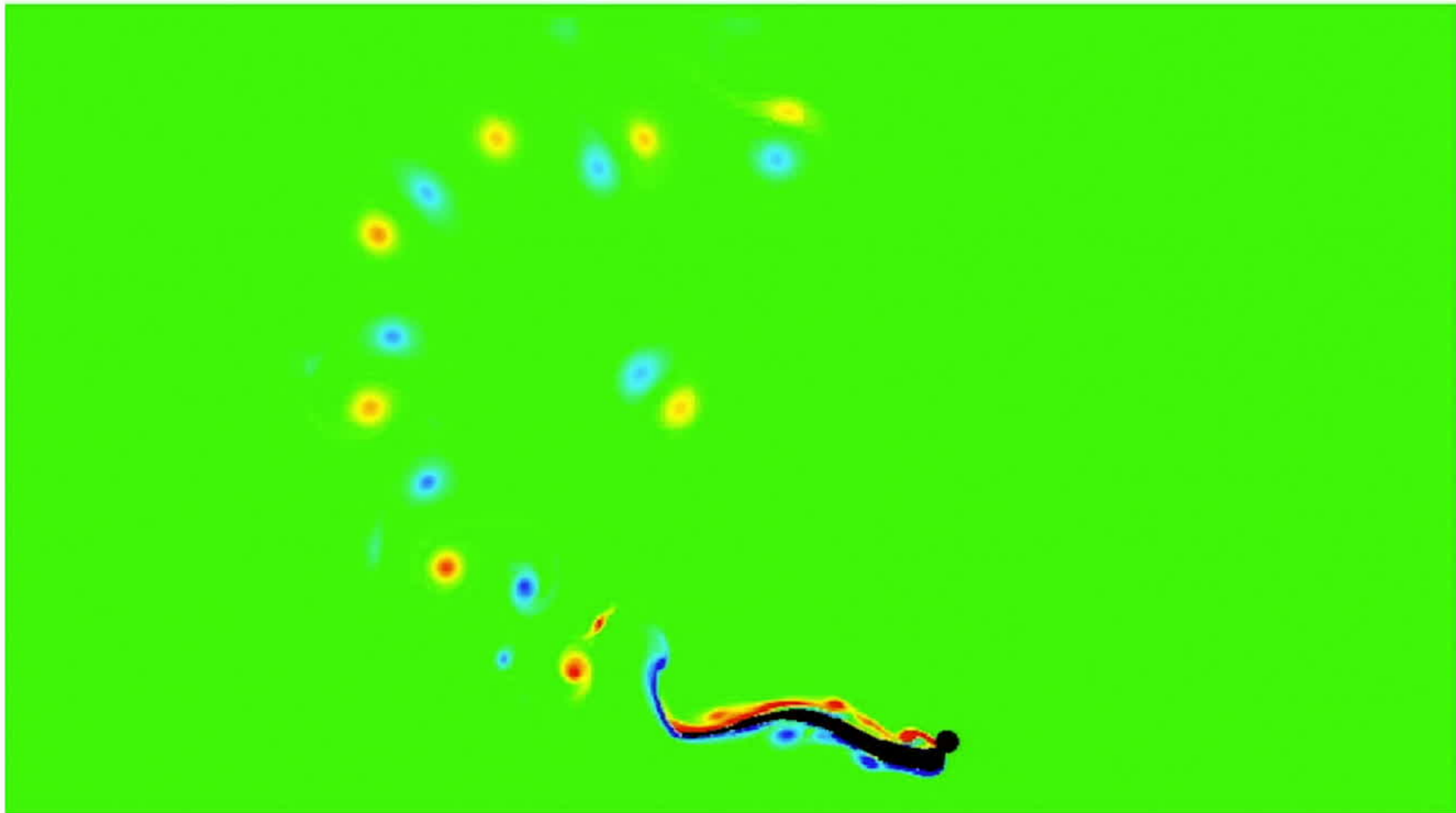
Amneet Bhalla (San Diego State) and Neelesh Patankar (Northwestern)



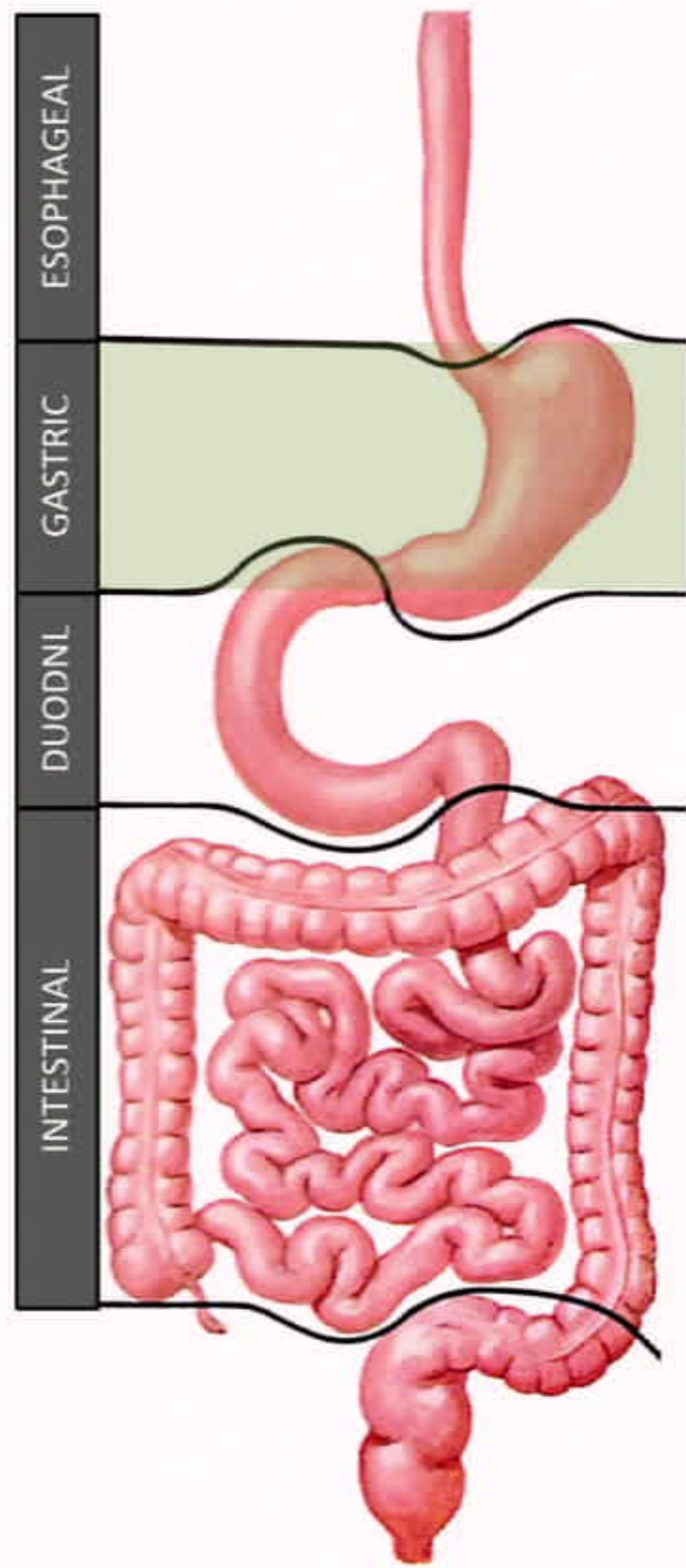
Amneet Bhalla (San Diego State) and Neelesh Patankar (Northwestern)



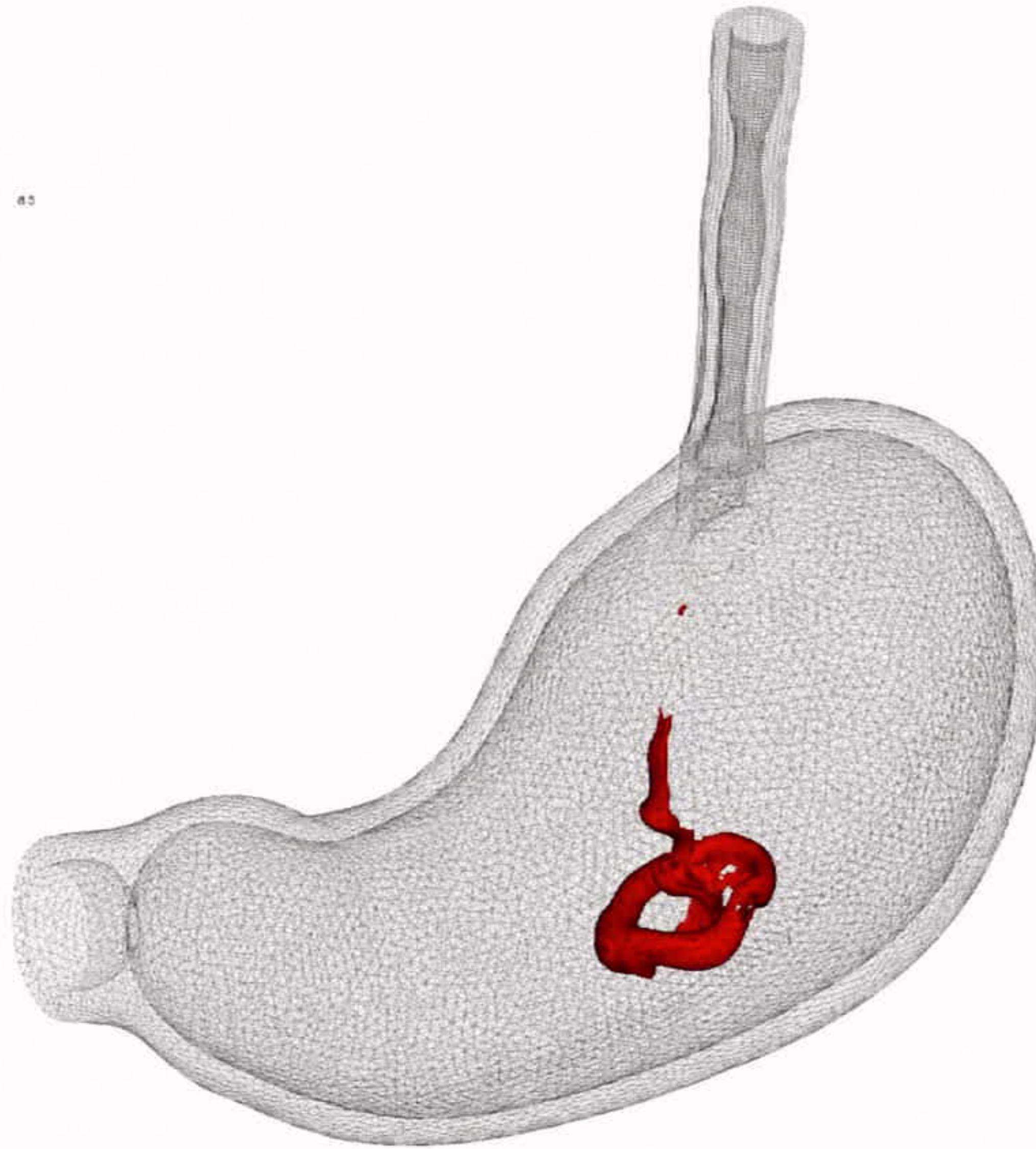
Amneet Bhalla (San Diego State) and Neelesh Patankar (Northwestern)



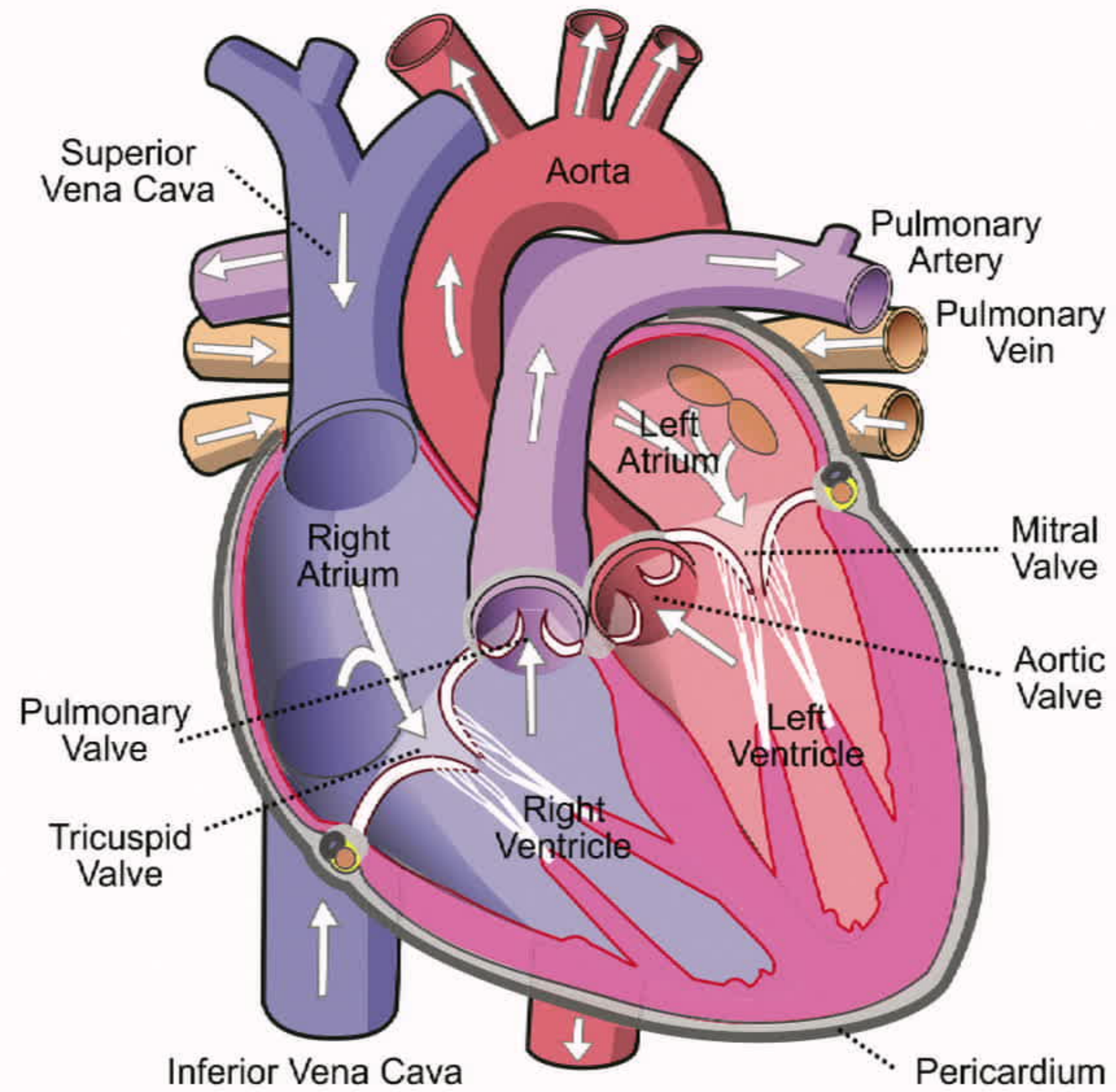
Amneet Bhalla (San Diego State) and Neelesh Patankar (Northwestern)

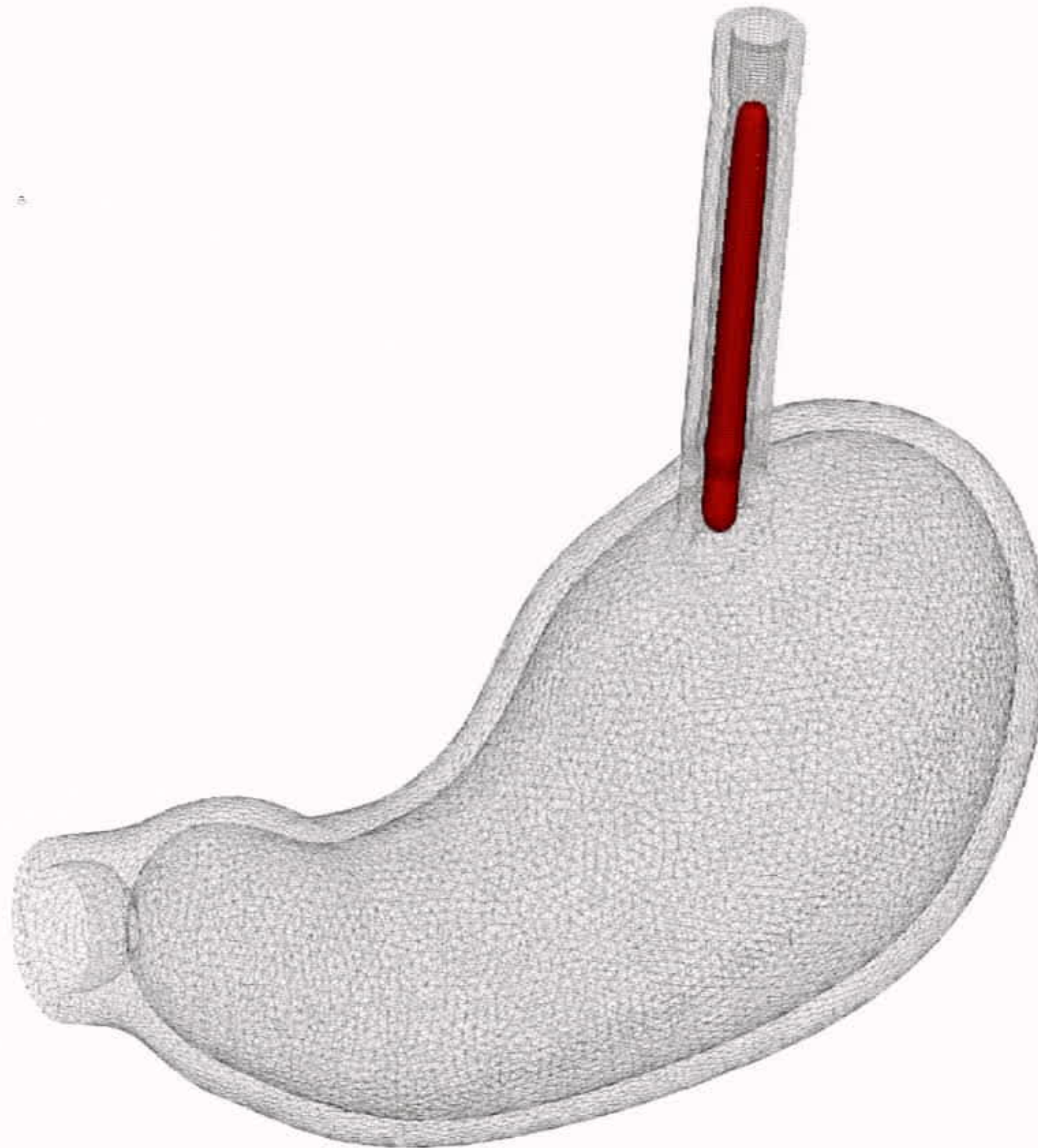
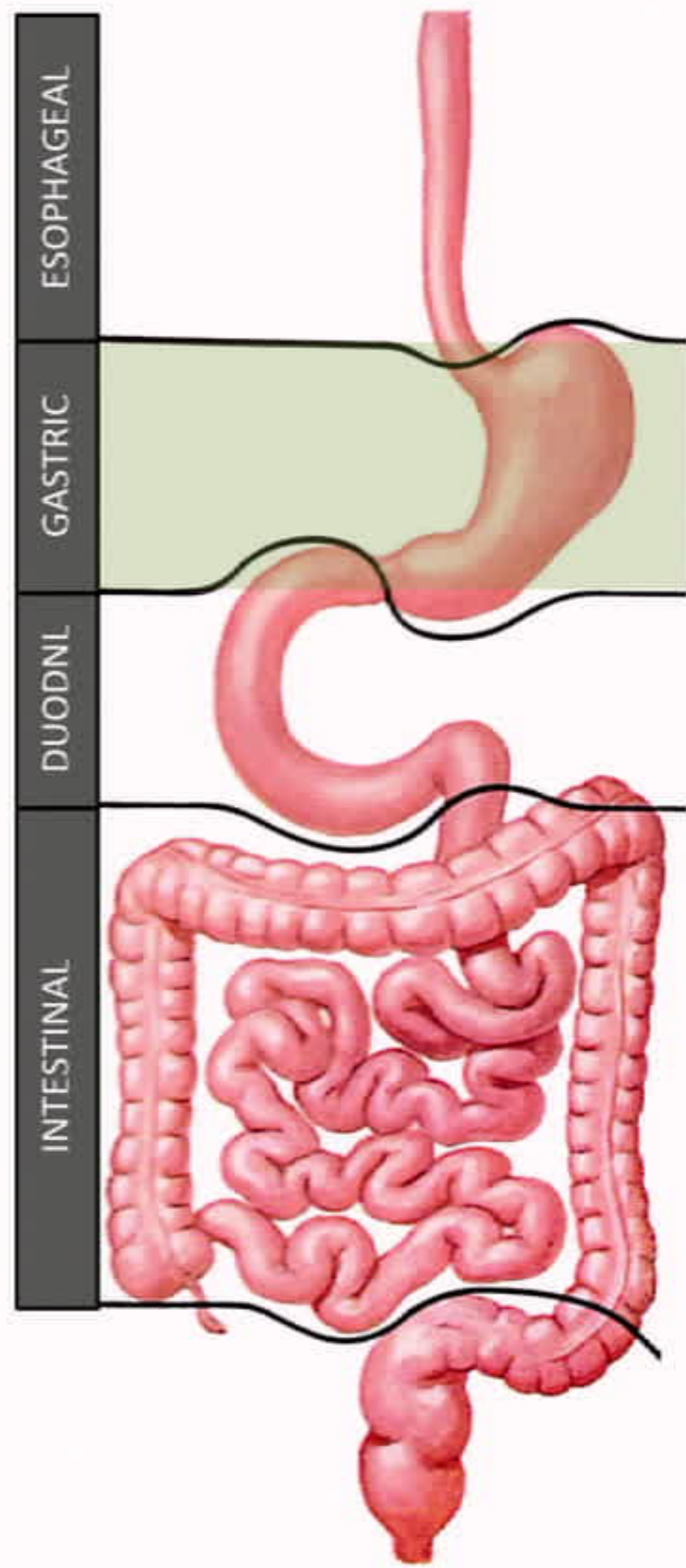


83

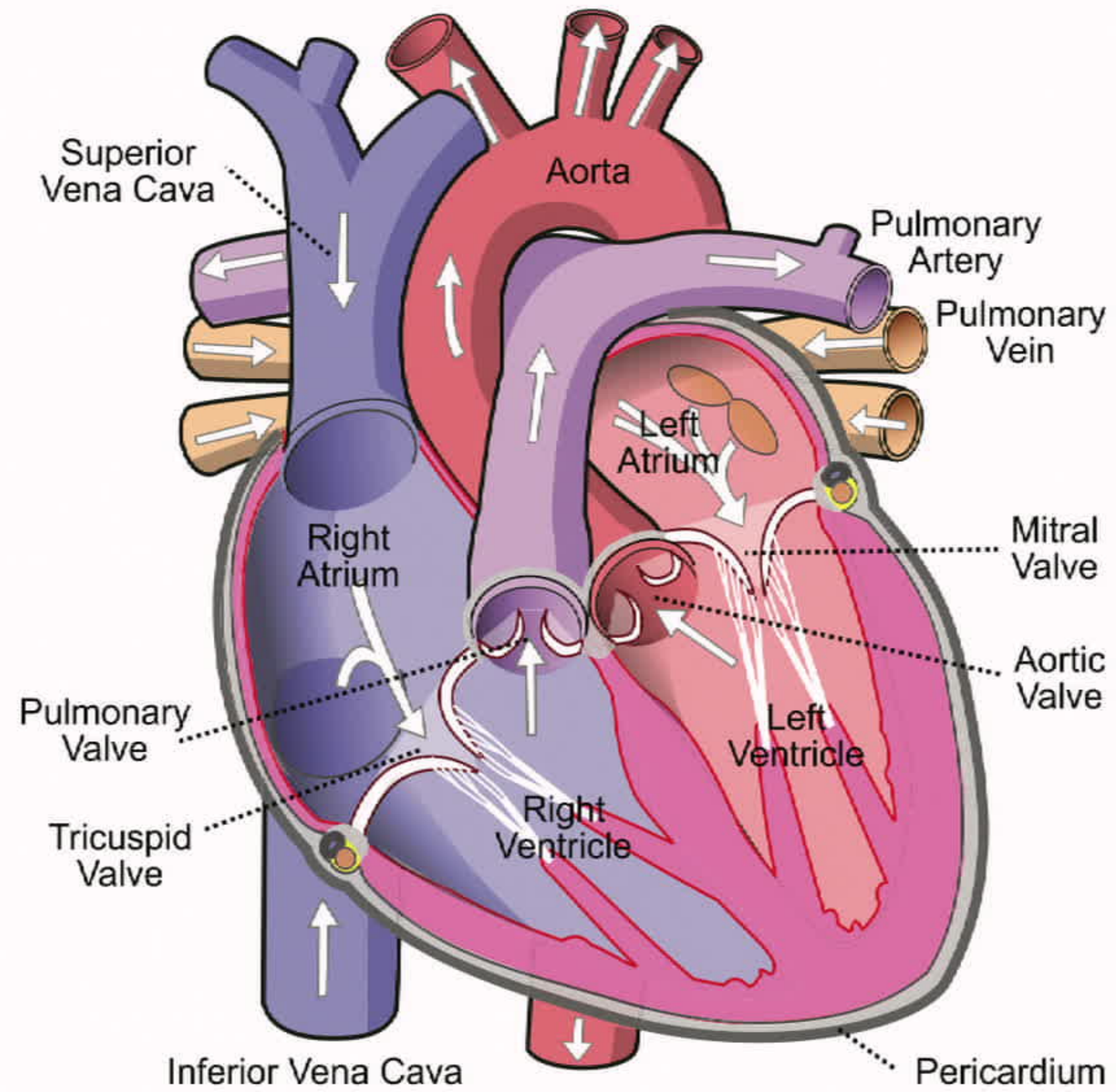


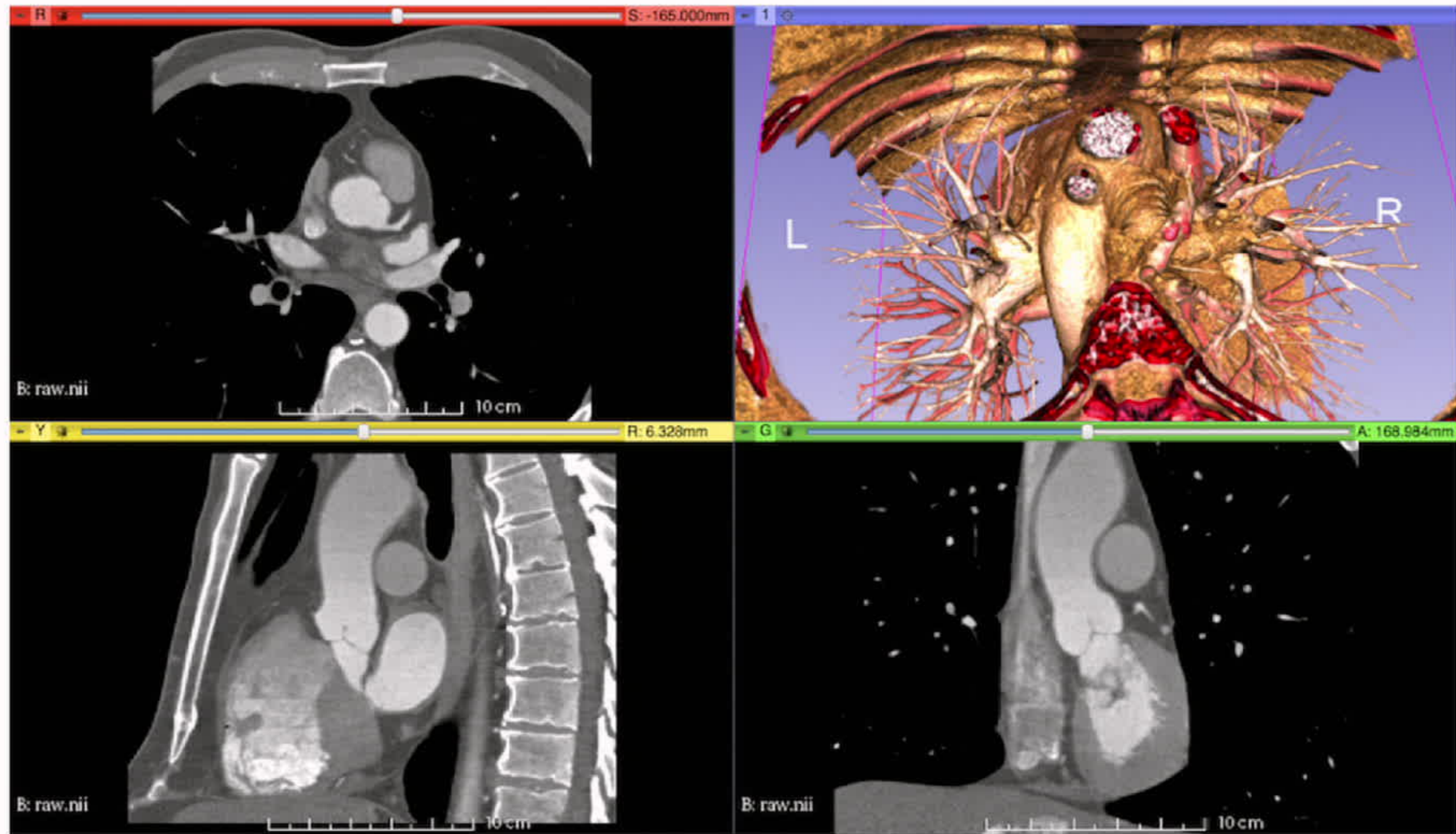
Shashank Acharya, Wenjun Kou, and Neelesh Patankar (Northwestern)



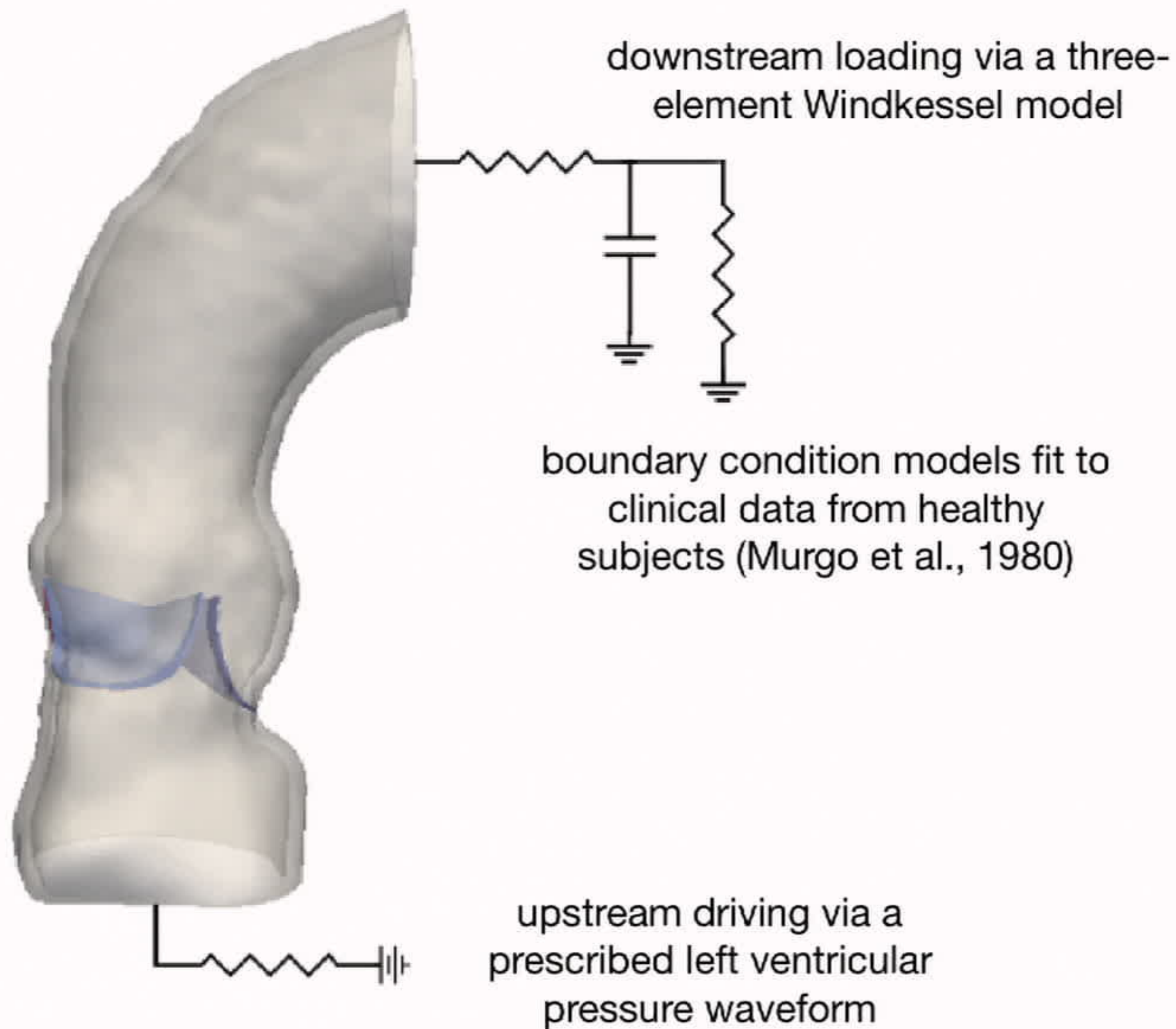


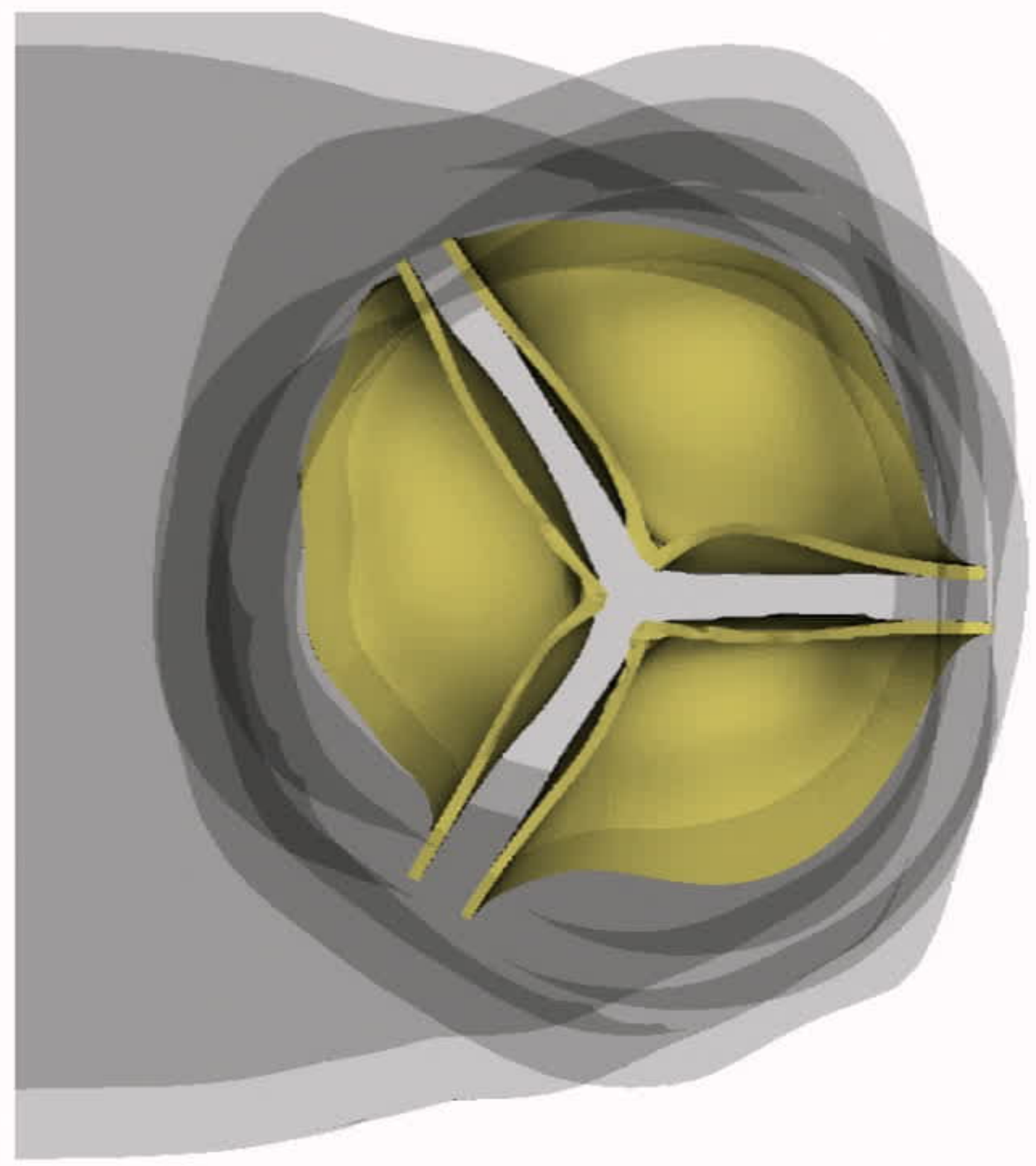
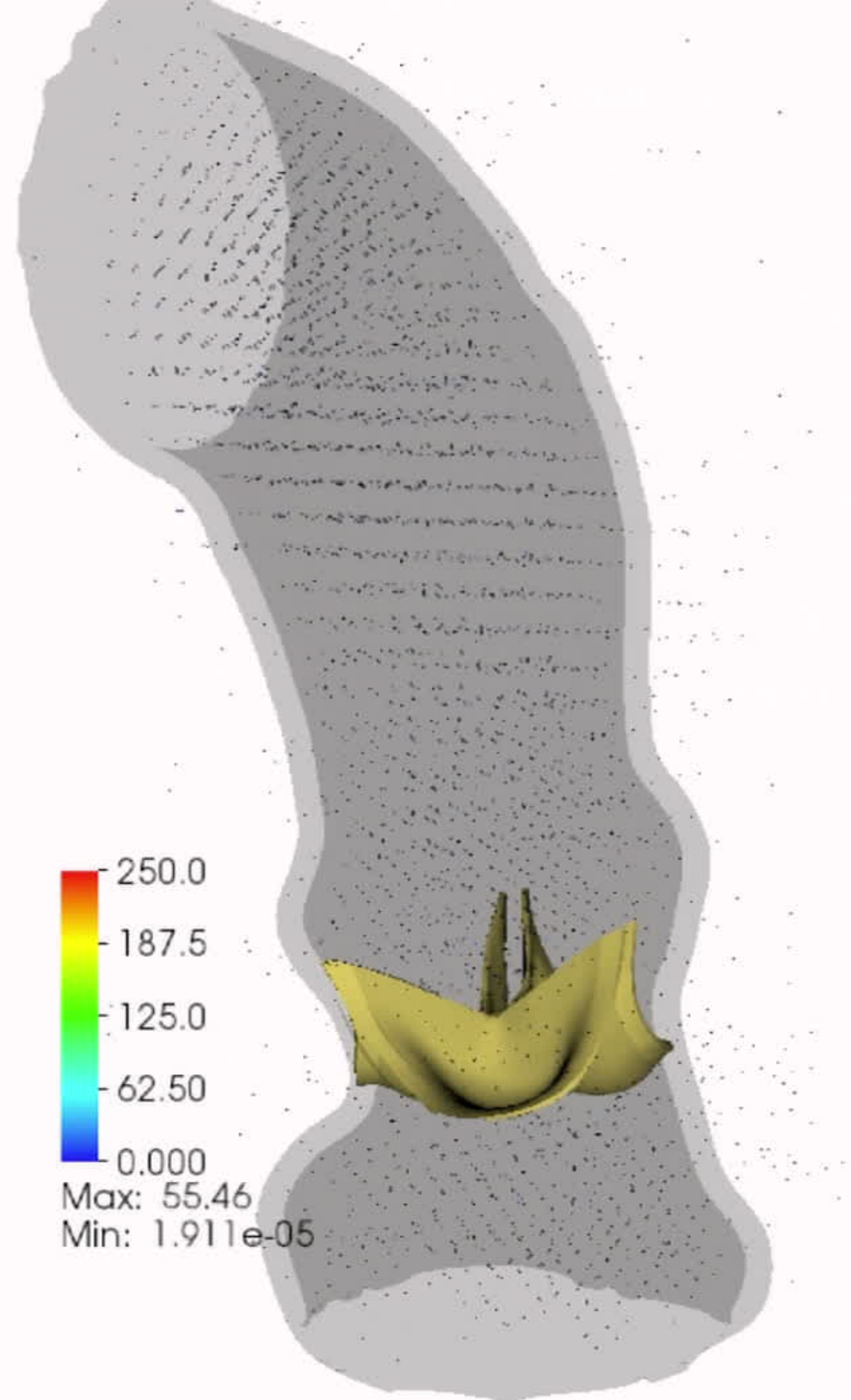
Shashank Achraya, Wenjun Kou, and Neelesh Patankar (Northwestern)

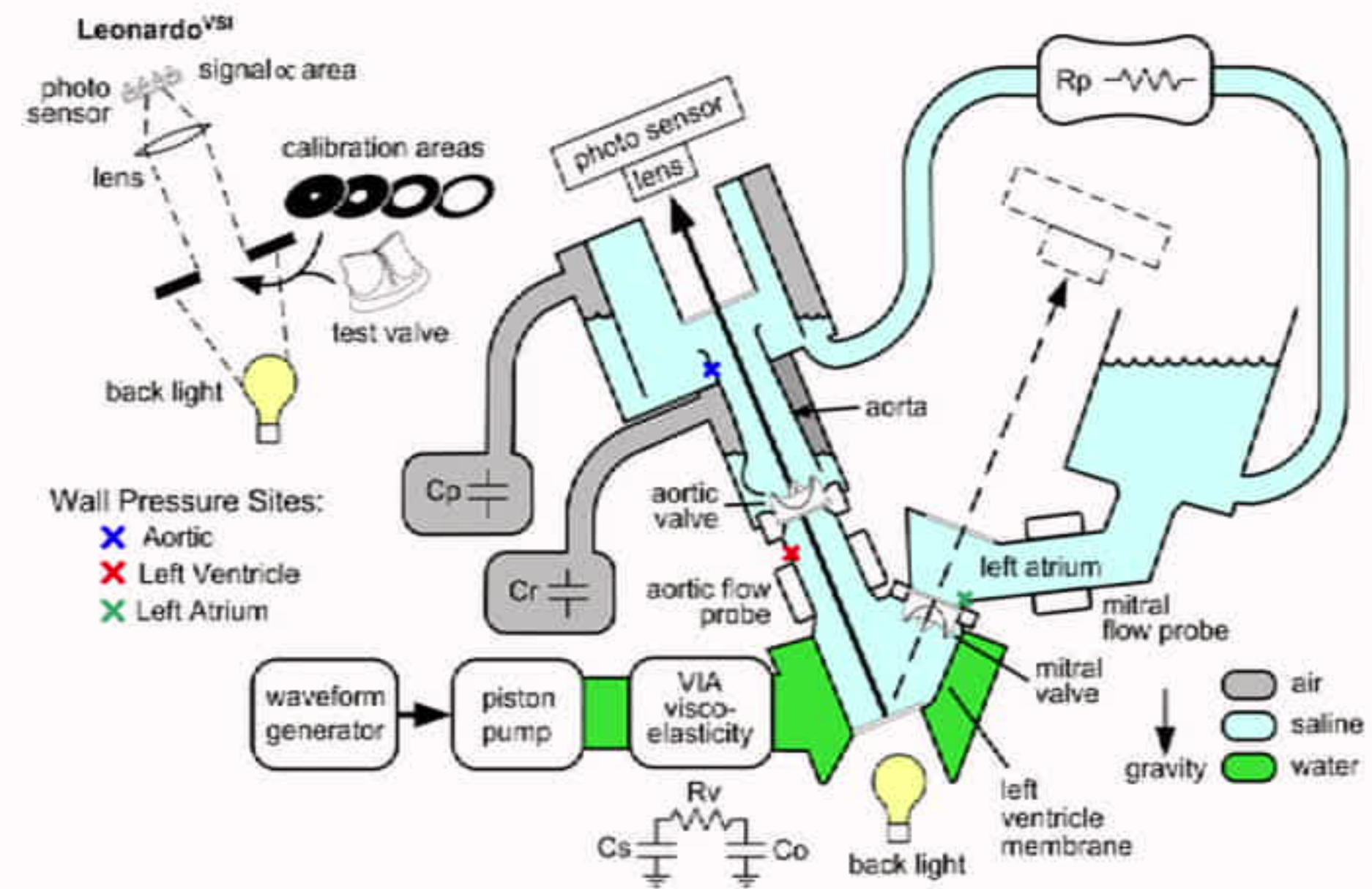




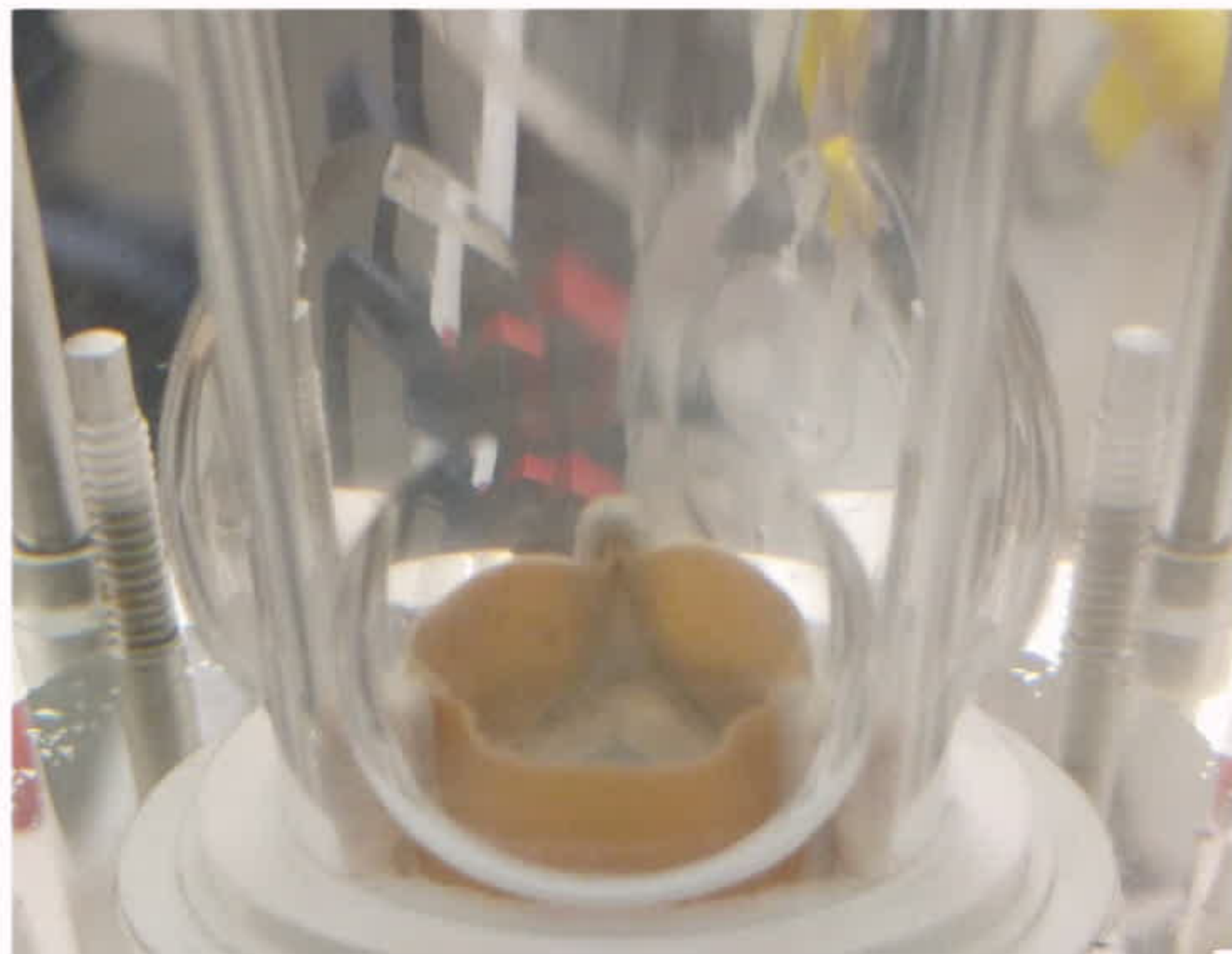
Ali Hasan (UNC-Chapel Hill Undergrad → Duke BME PhD student) and Tommy Caranasos and John Vavalle (UNC School of Medicine)









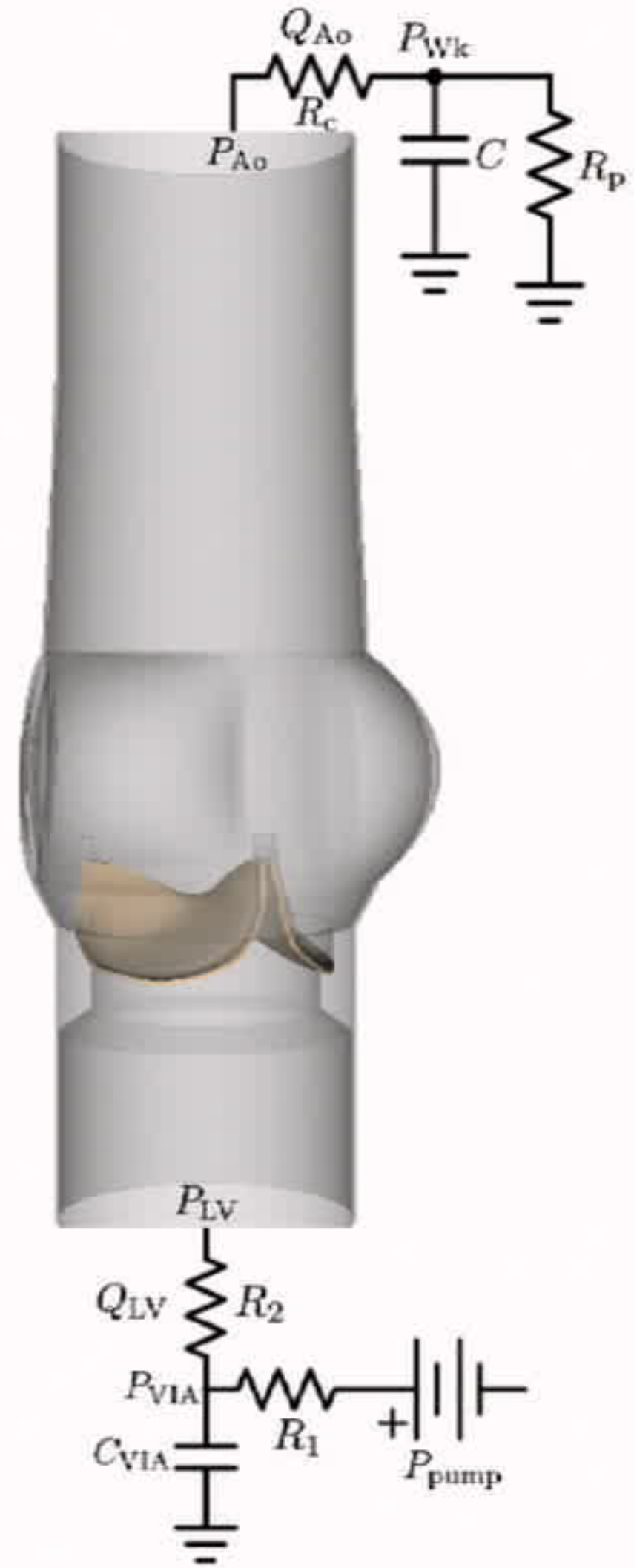




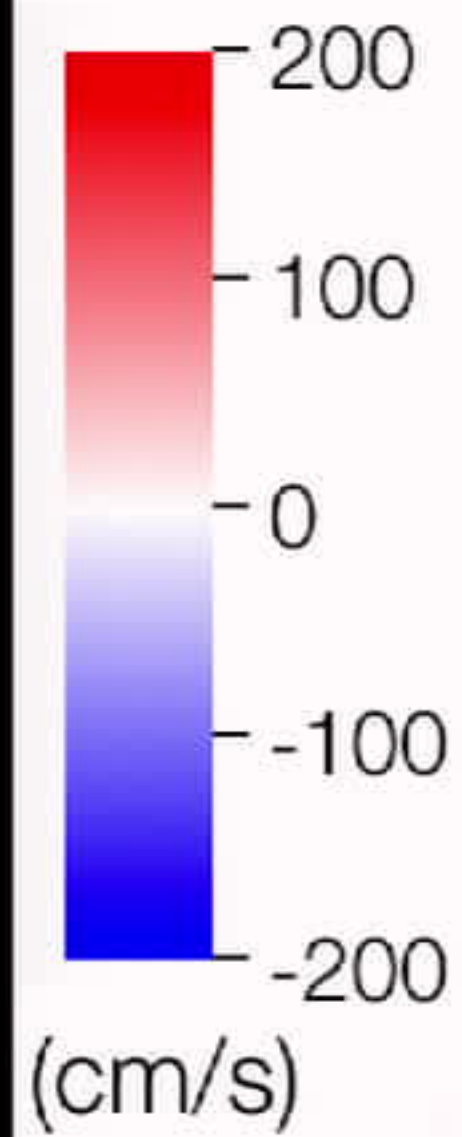
bileaflet mechanical
valve (St. Jude)



porcine bioprosthetic
valve

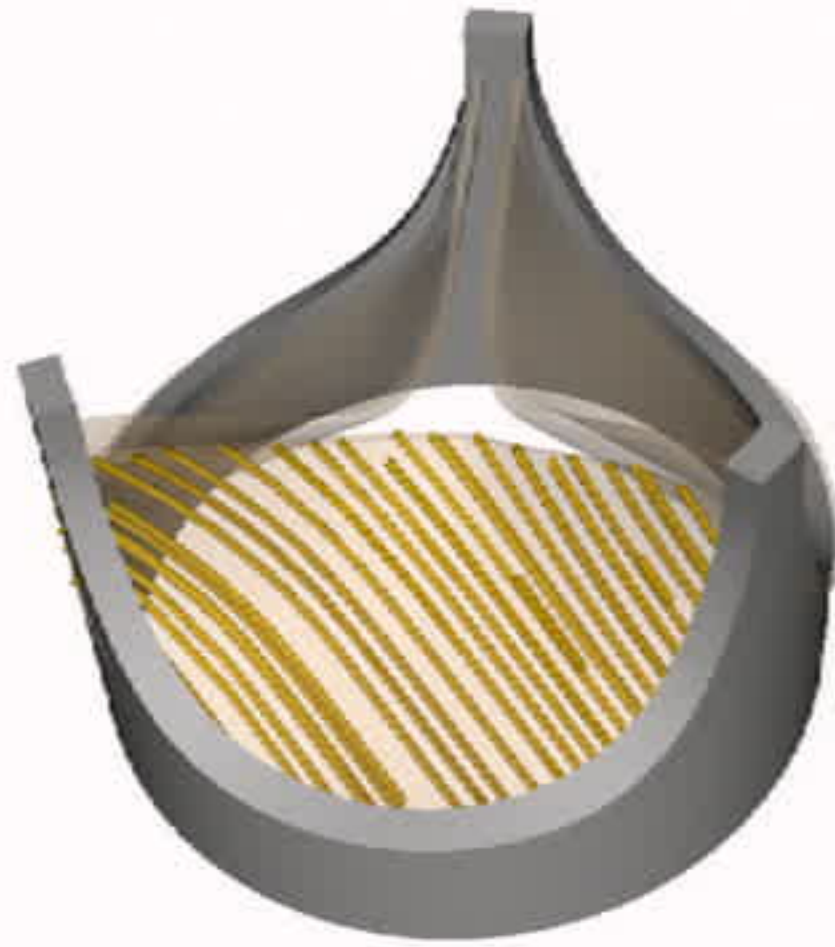


bioprosthetic valve
in aortic test section

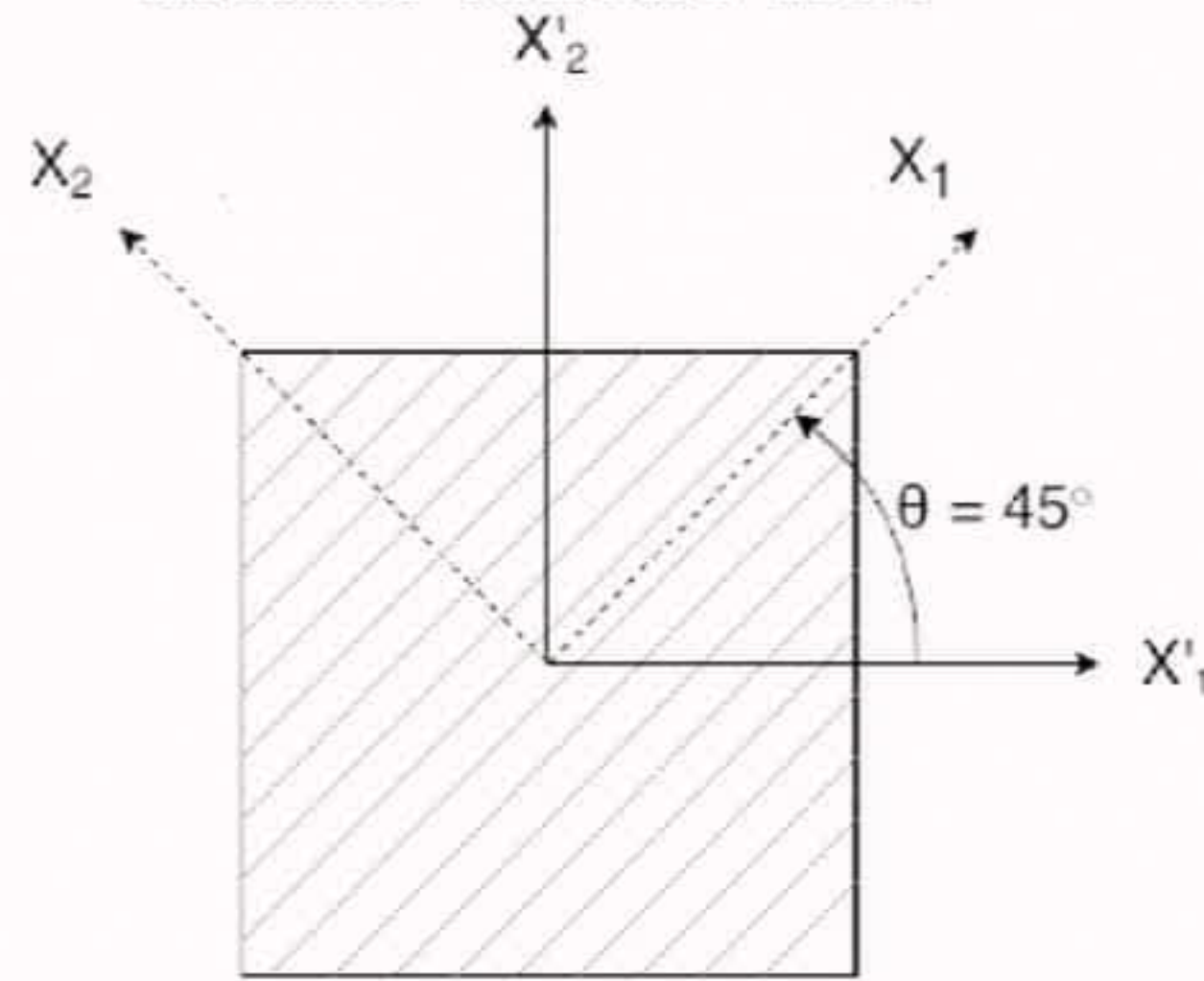


Larry Scotten (LNS Consulting), Mike Lee and Robert Hunt (UNC-Chapel Hill), Amin Kolahehdouz (UNC-Chapel Hill and FDA), and Brent Craven (FDA) and co-workers

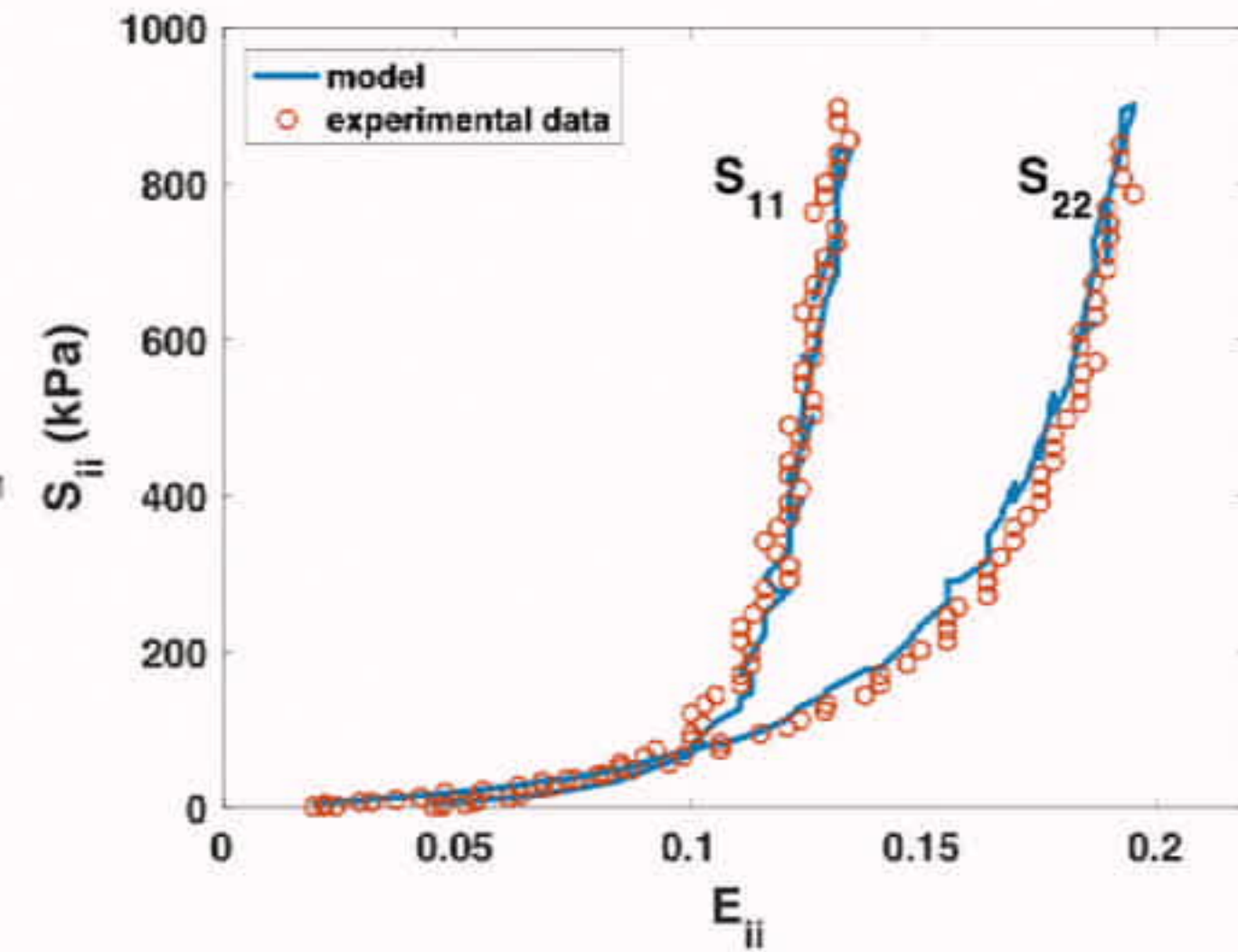
bovine pericardial
bioprosthesis valve



biaxial tensile test



model fit



Data by Duraiswamy from
Kim et al., *Ann Biomed Eng*, 2007

Constitutive model:

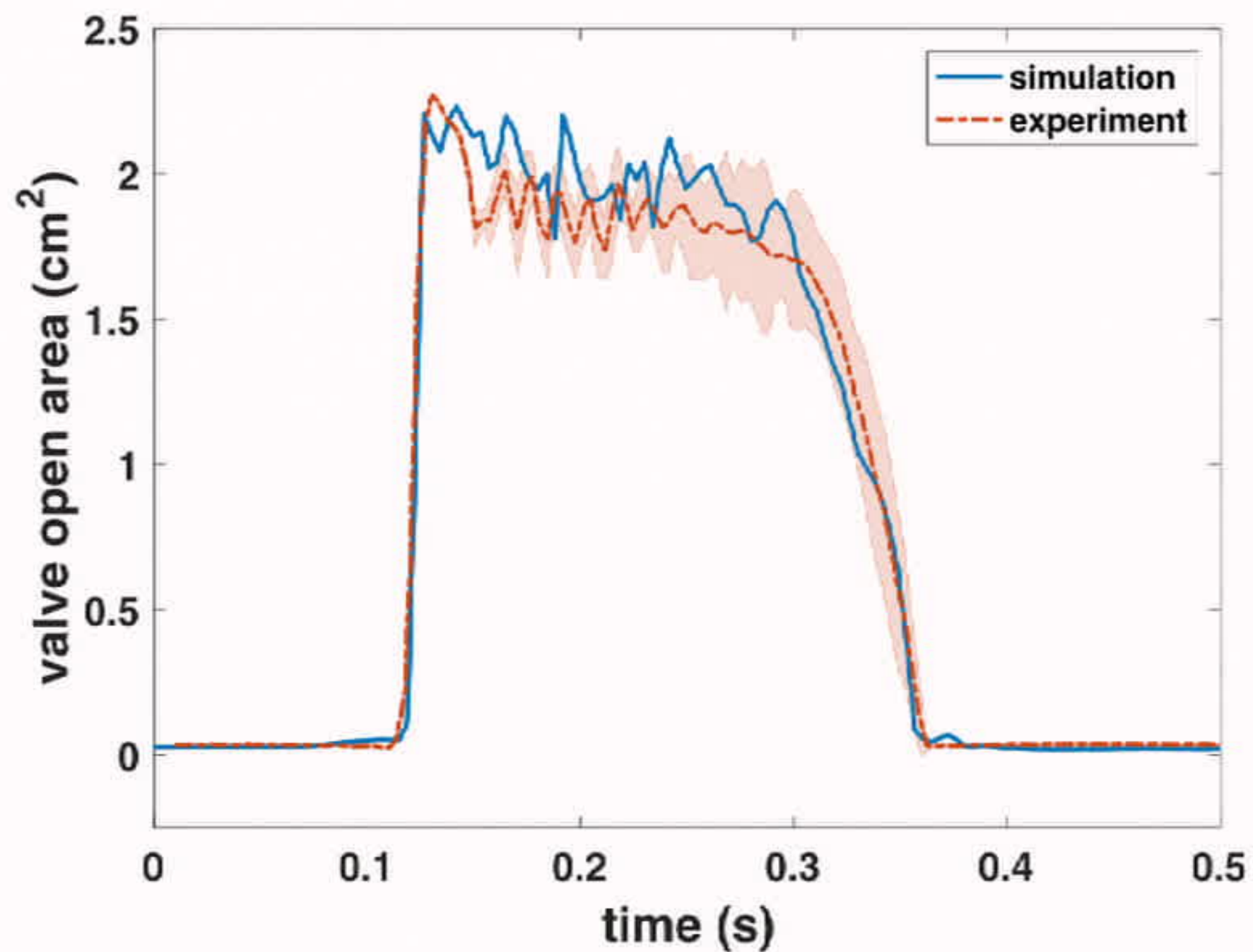
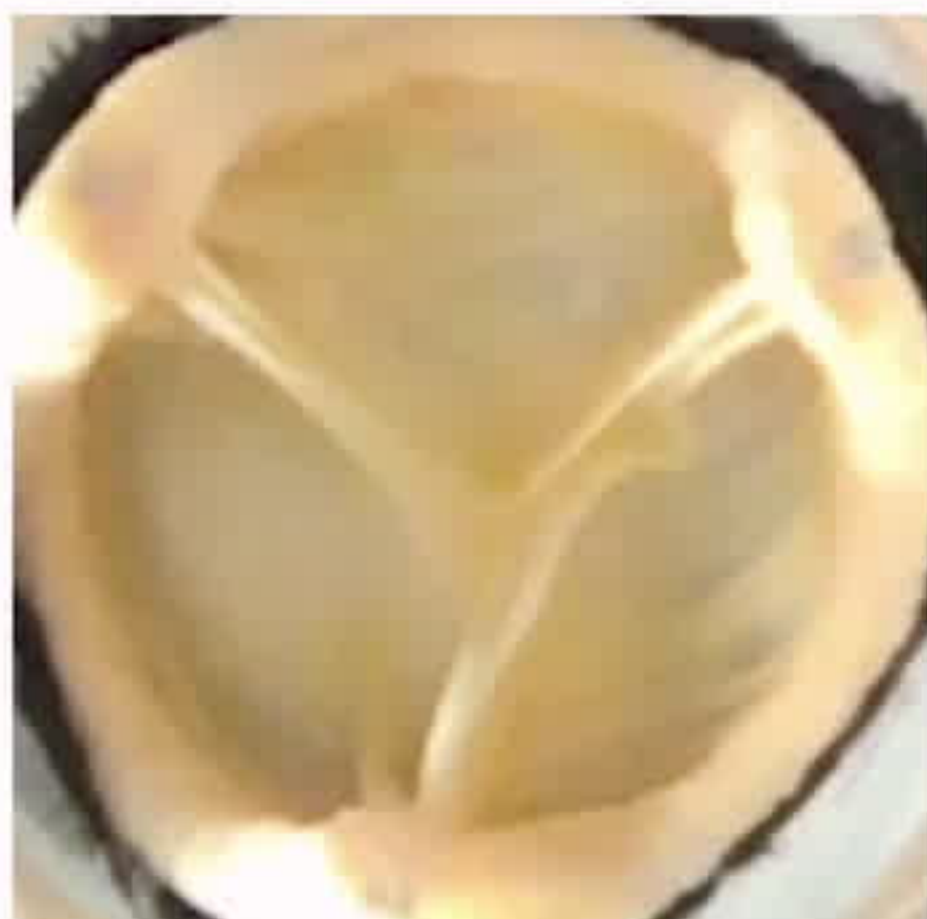
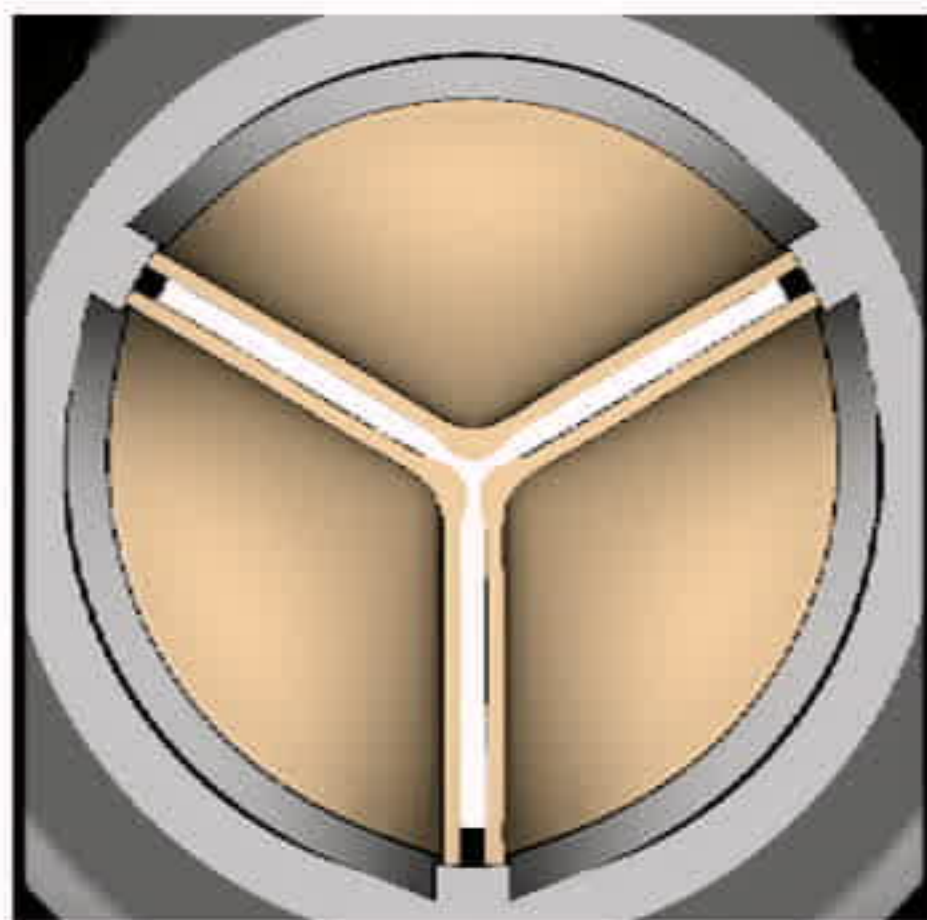
$$W = W_{\text{matrix}} + W_{\text{fiber}}$$

$$W_{\text{matrix}} = \frac{a}{2b} \{ \exp[b(I_1 - 3)] - 1 \}$$

$$W_{\text{fiber}} = \frac{c}{2d} \{ \exp[d(\kappa I_1 + (1 - 3\kappa)I_4 - 1)^2] - 1 \}$$

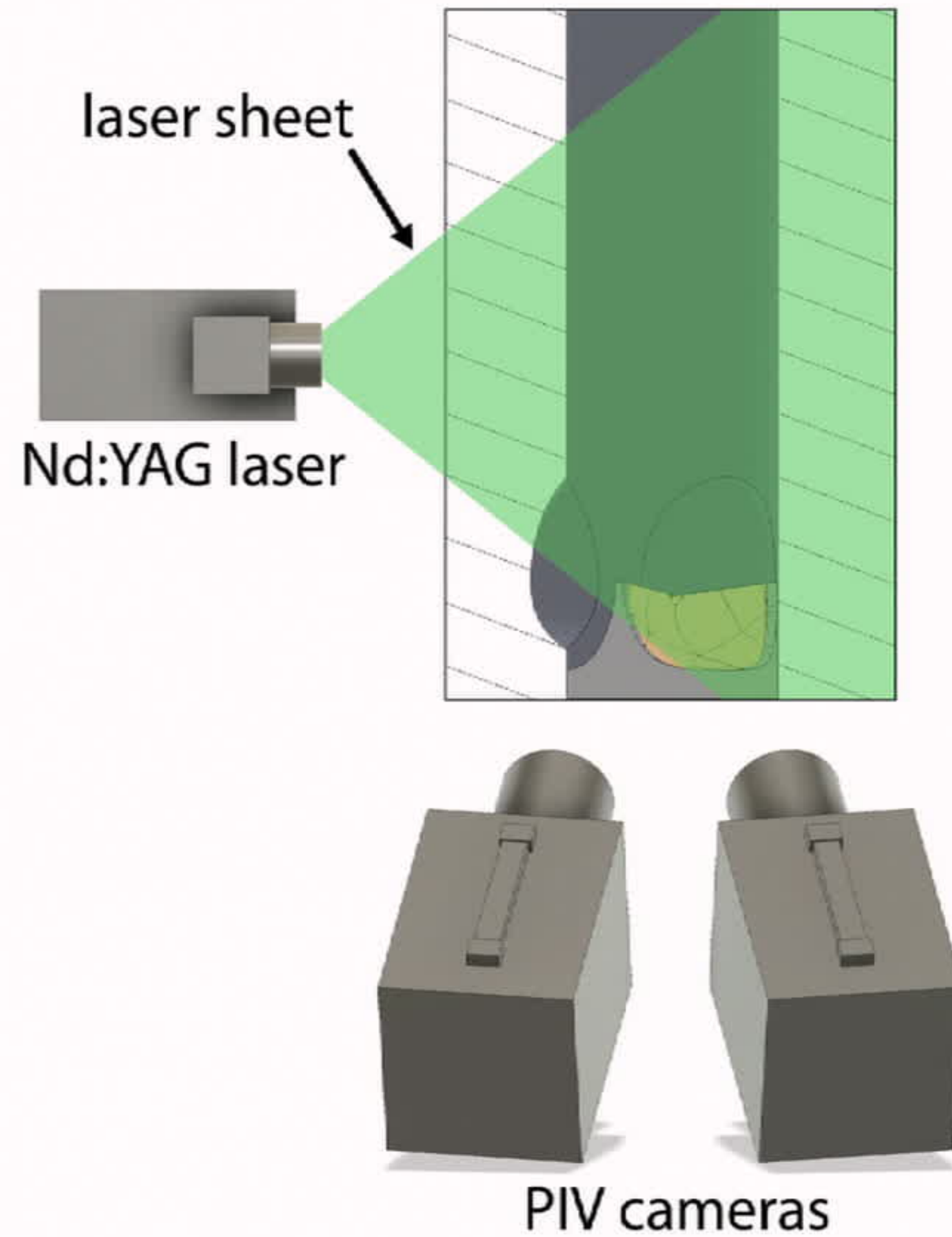
- $I_1 = \text{tr}(\mathbb{F}^T \mathbb{F})$
- $I_4 = \lambda_f^2$ is squared fiber stretch
- κ describes fiber dispersion

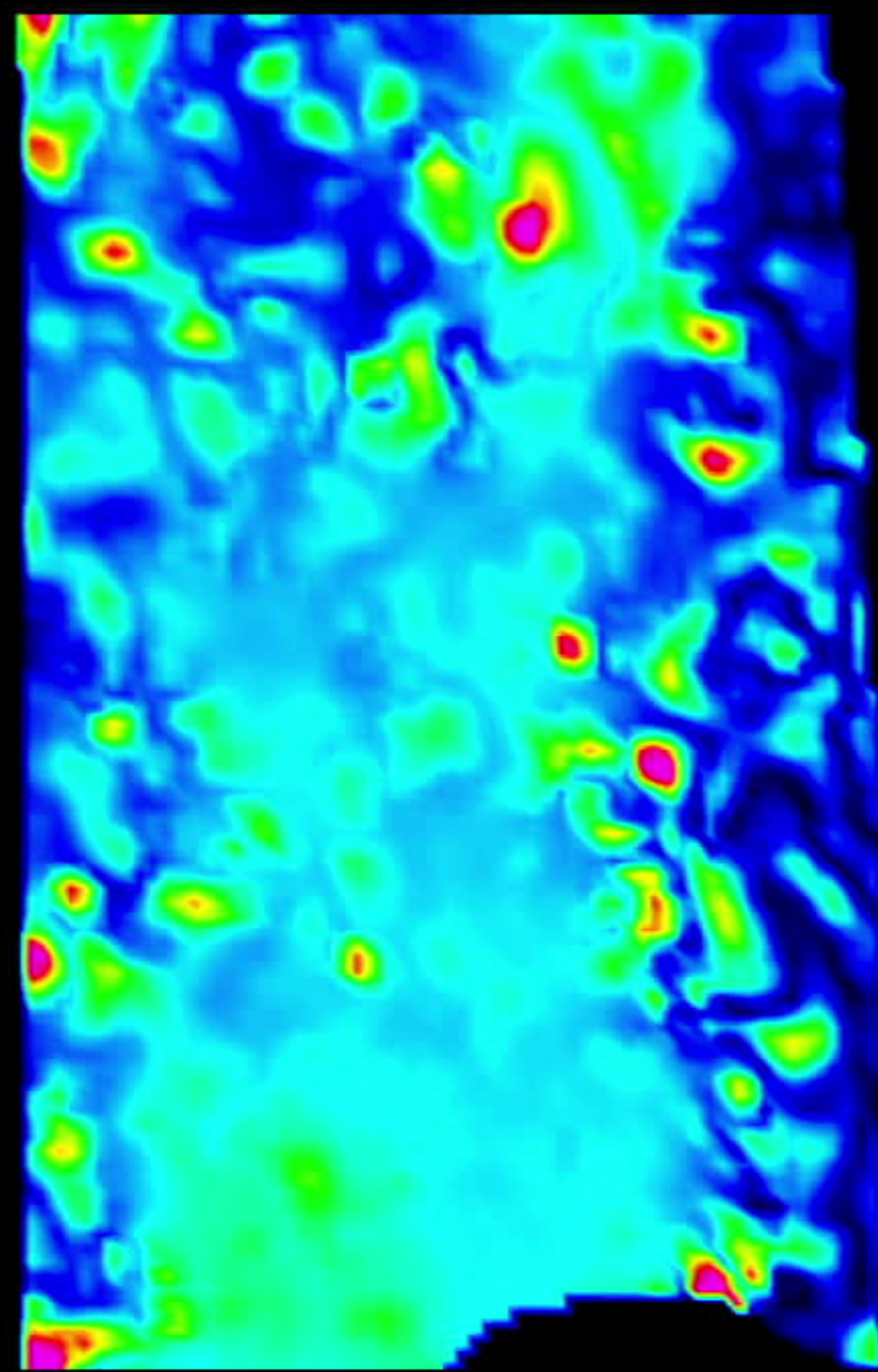
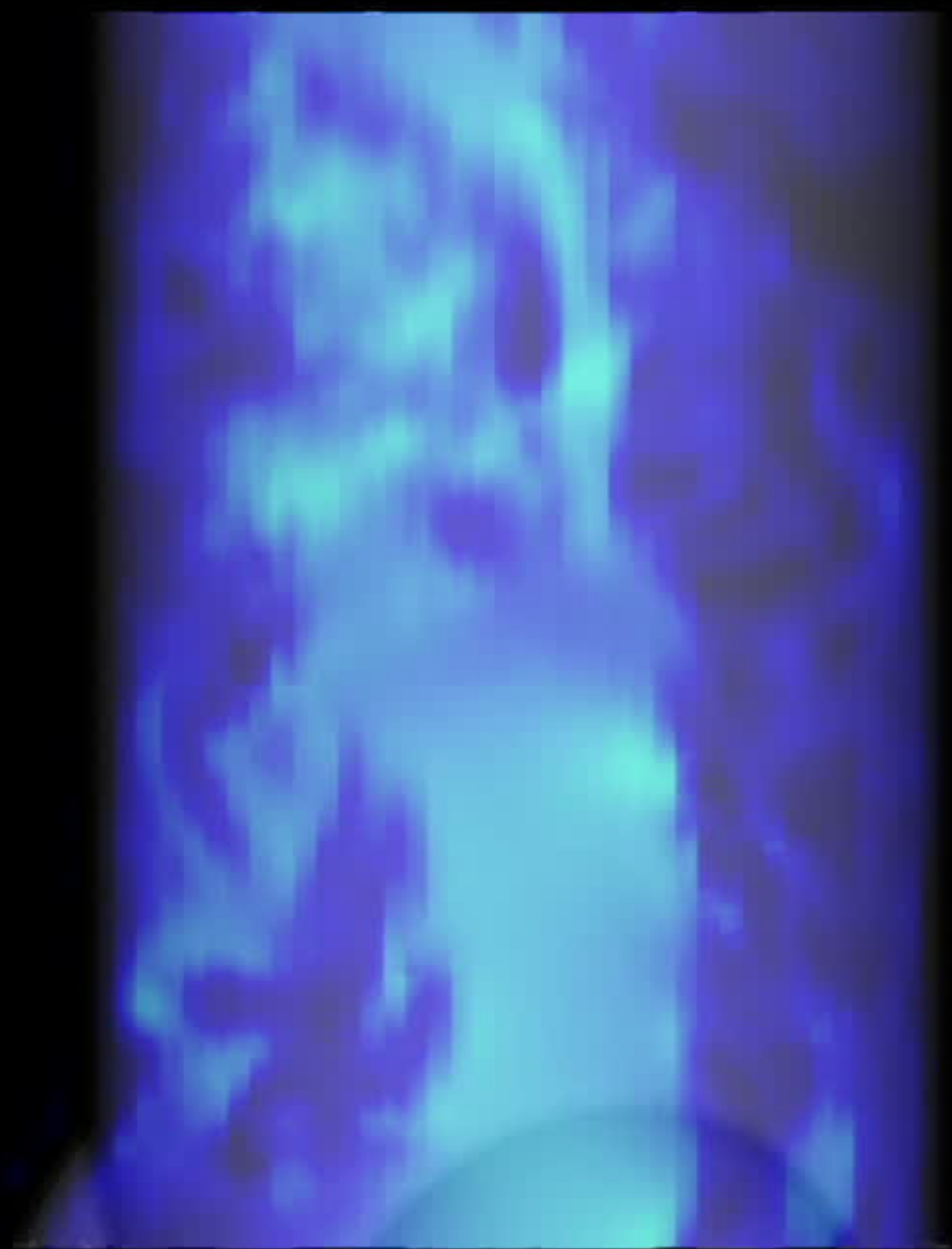
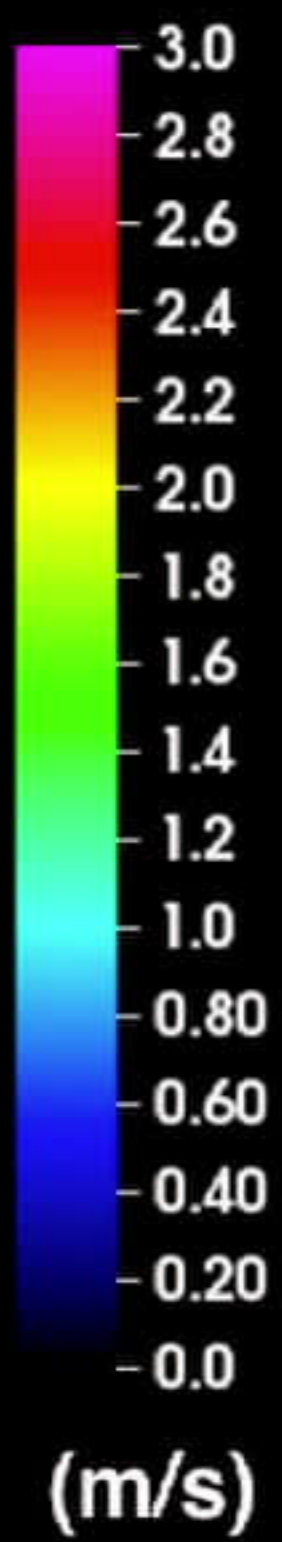
Porcine bioprosthetic valve: Comparing computational and experimental dynamics

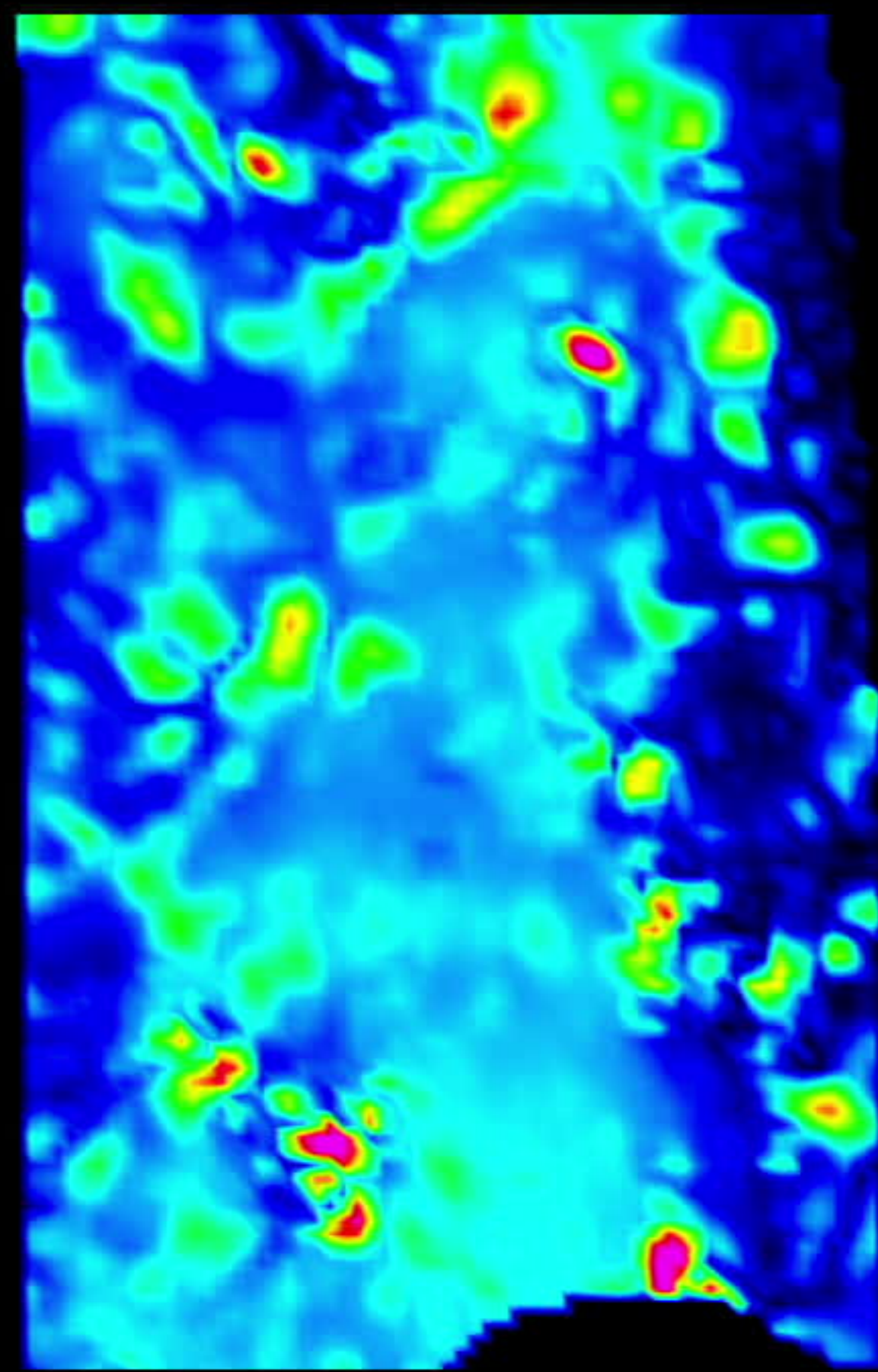
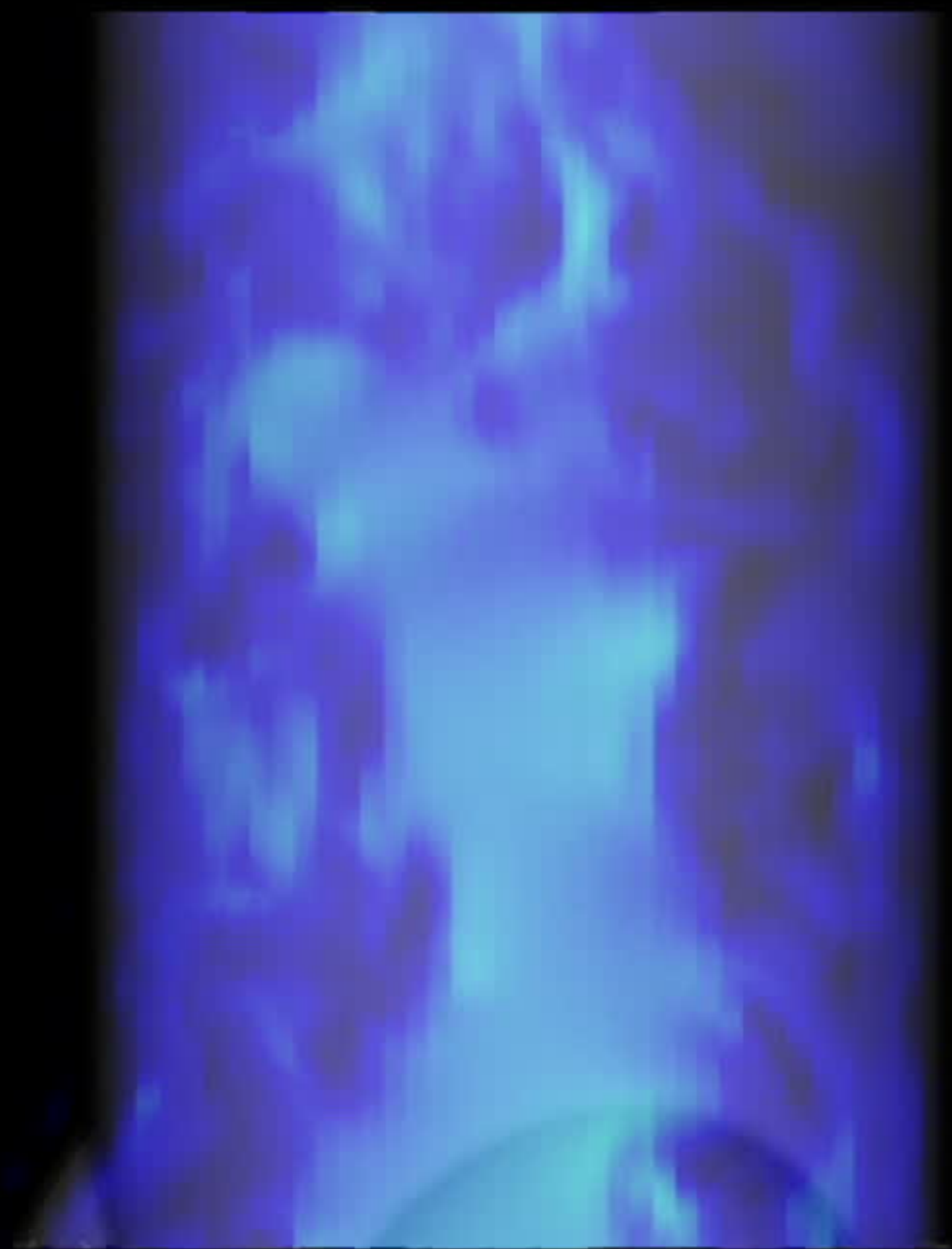
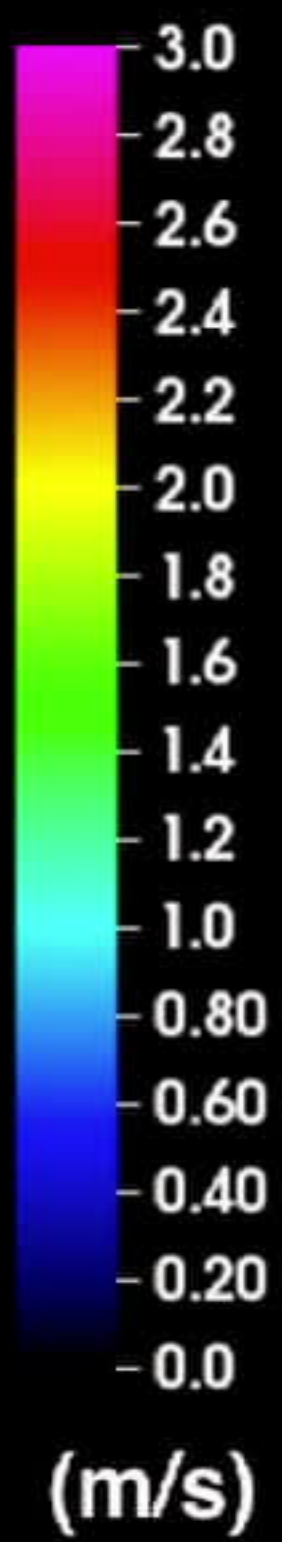


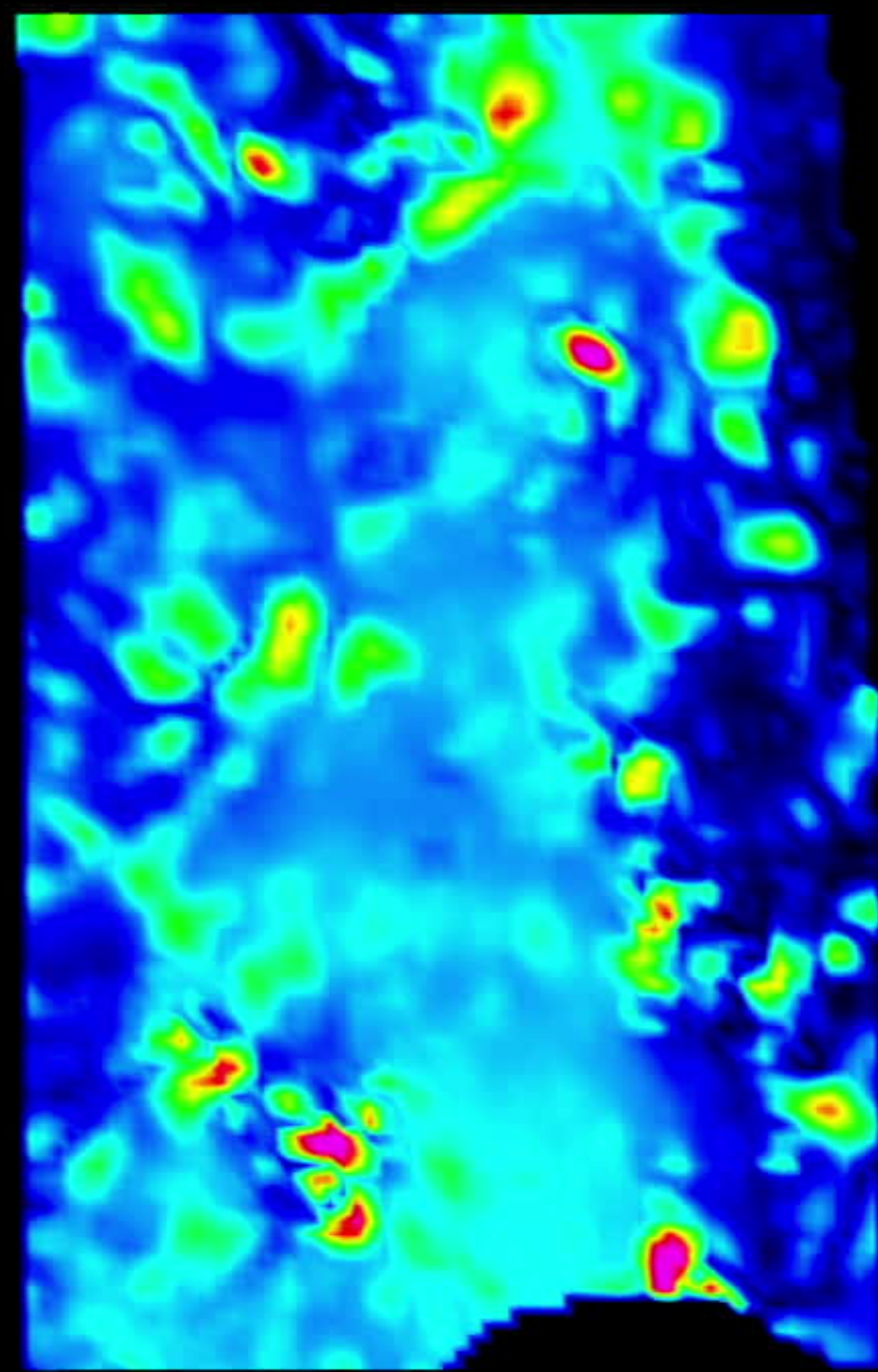
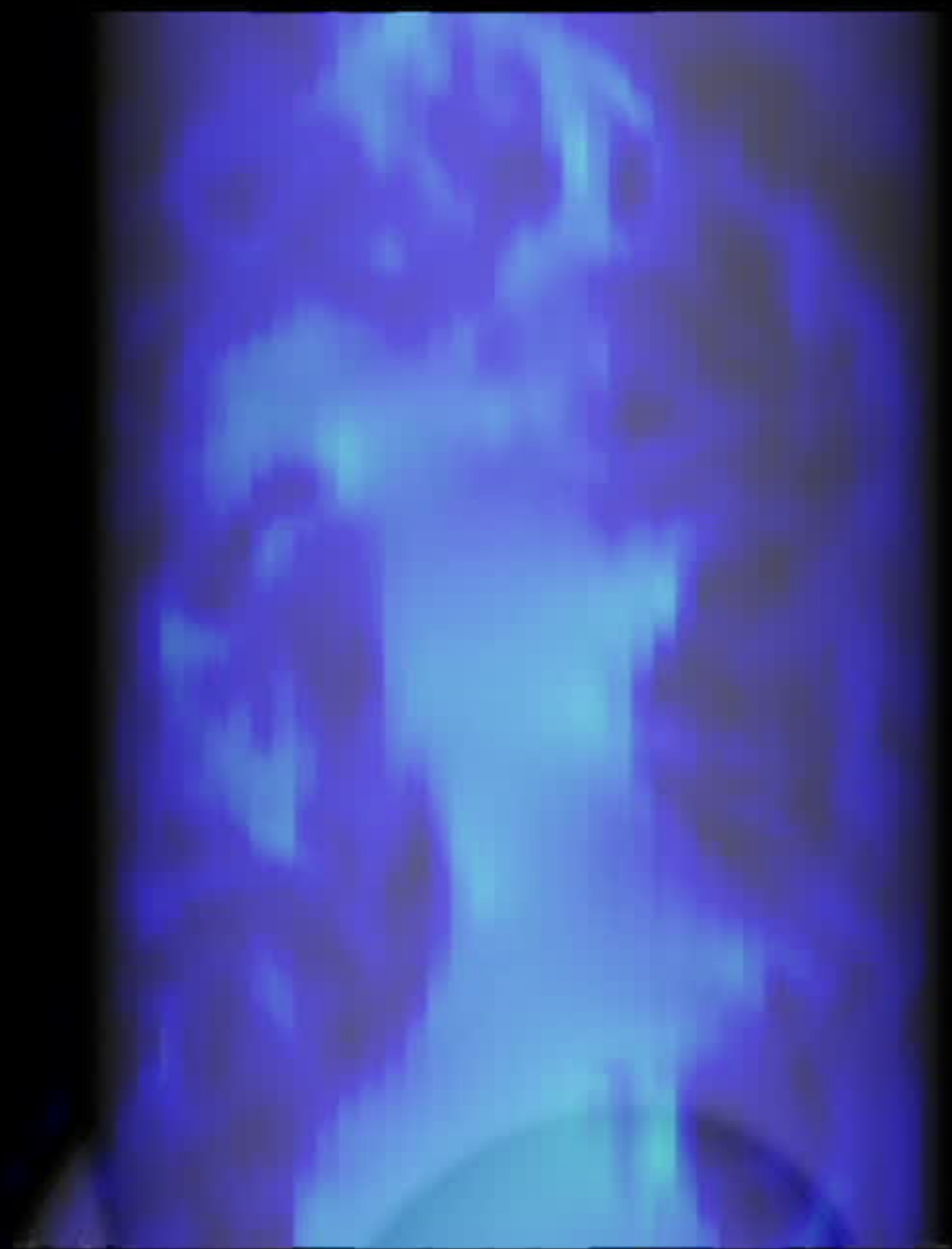
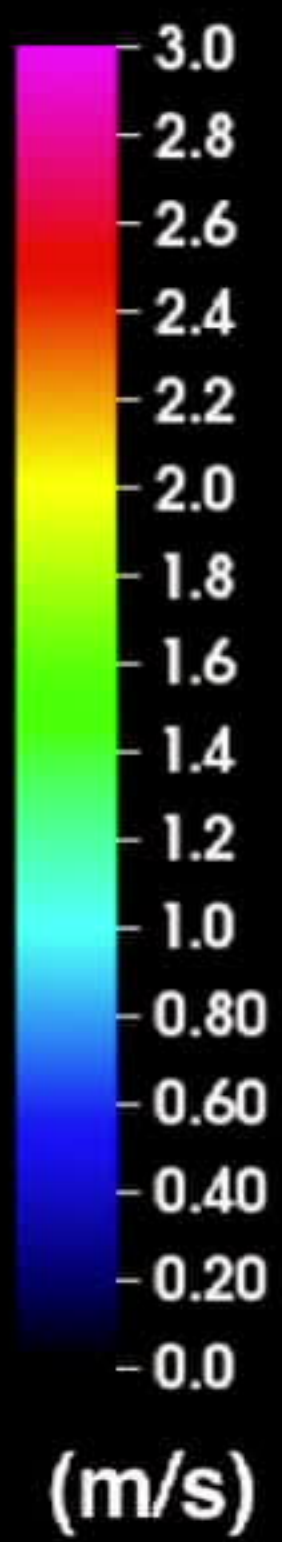
Scatter in leaflet kinematic quantification reflects complex flow dynamics.

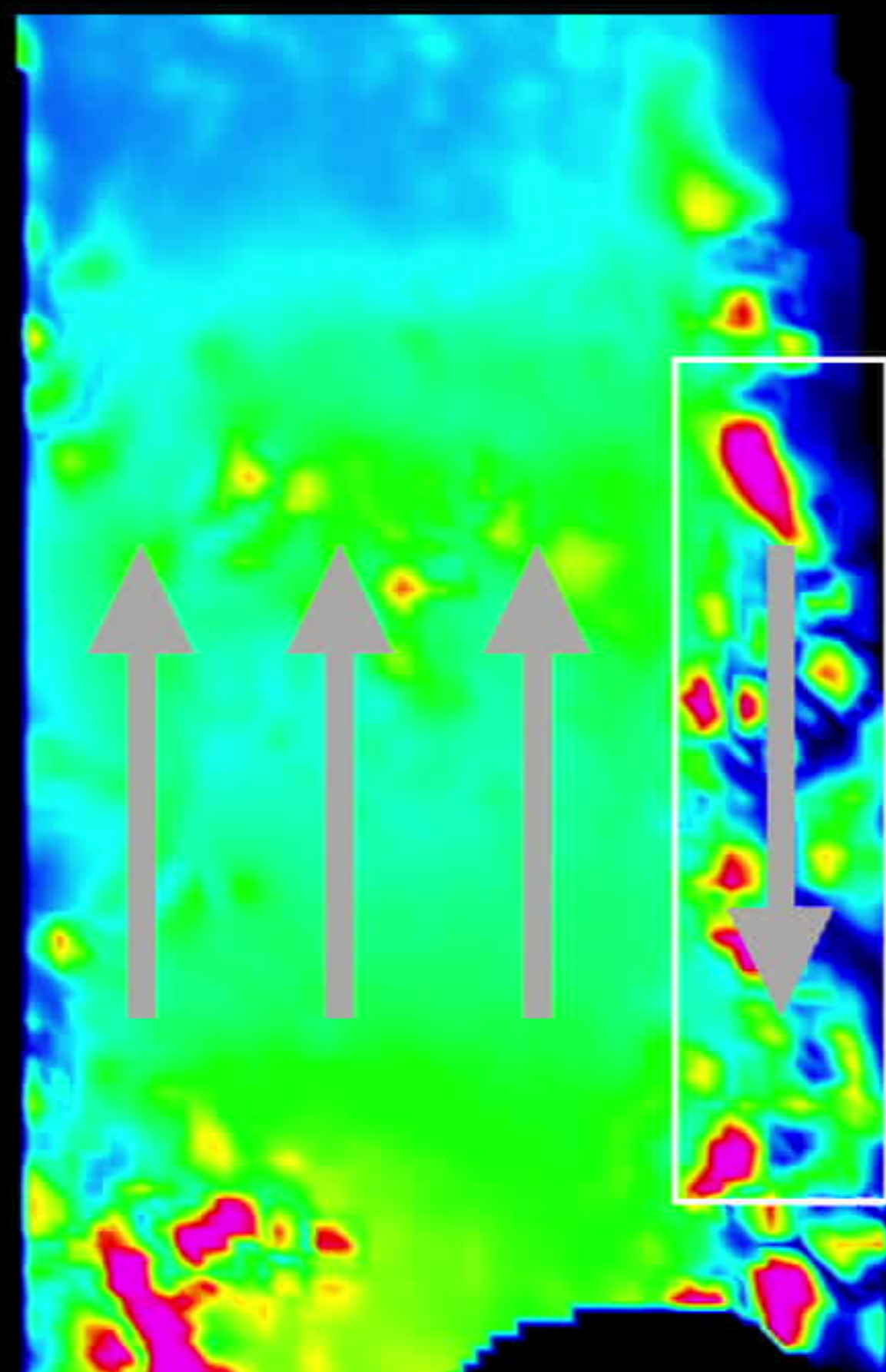
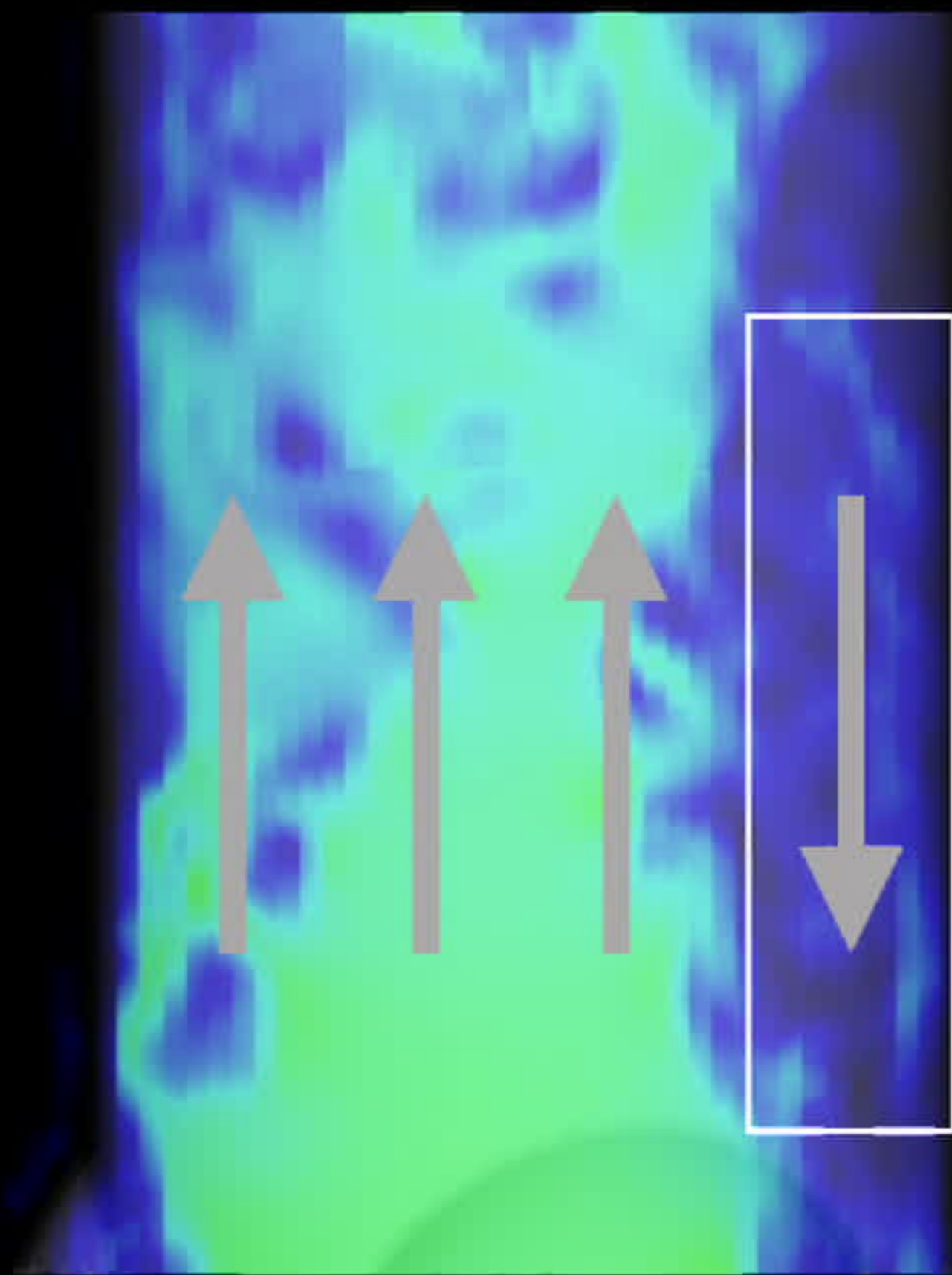
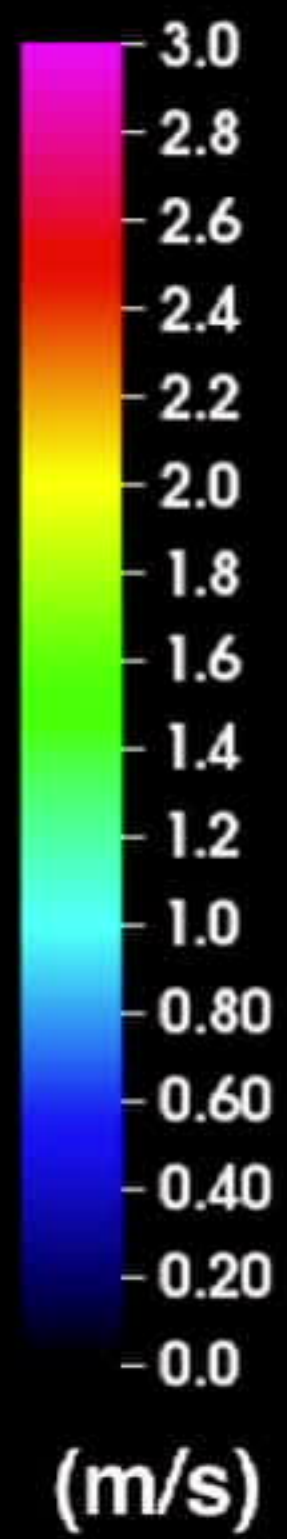
Particle Image Velocimetry (PIV)

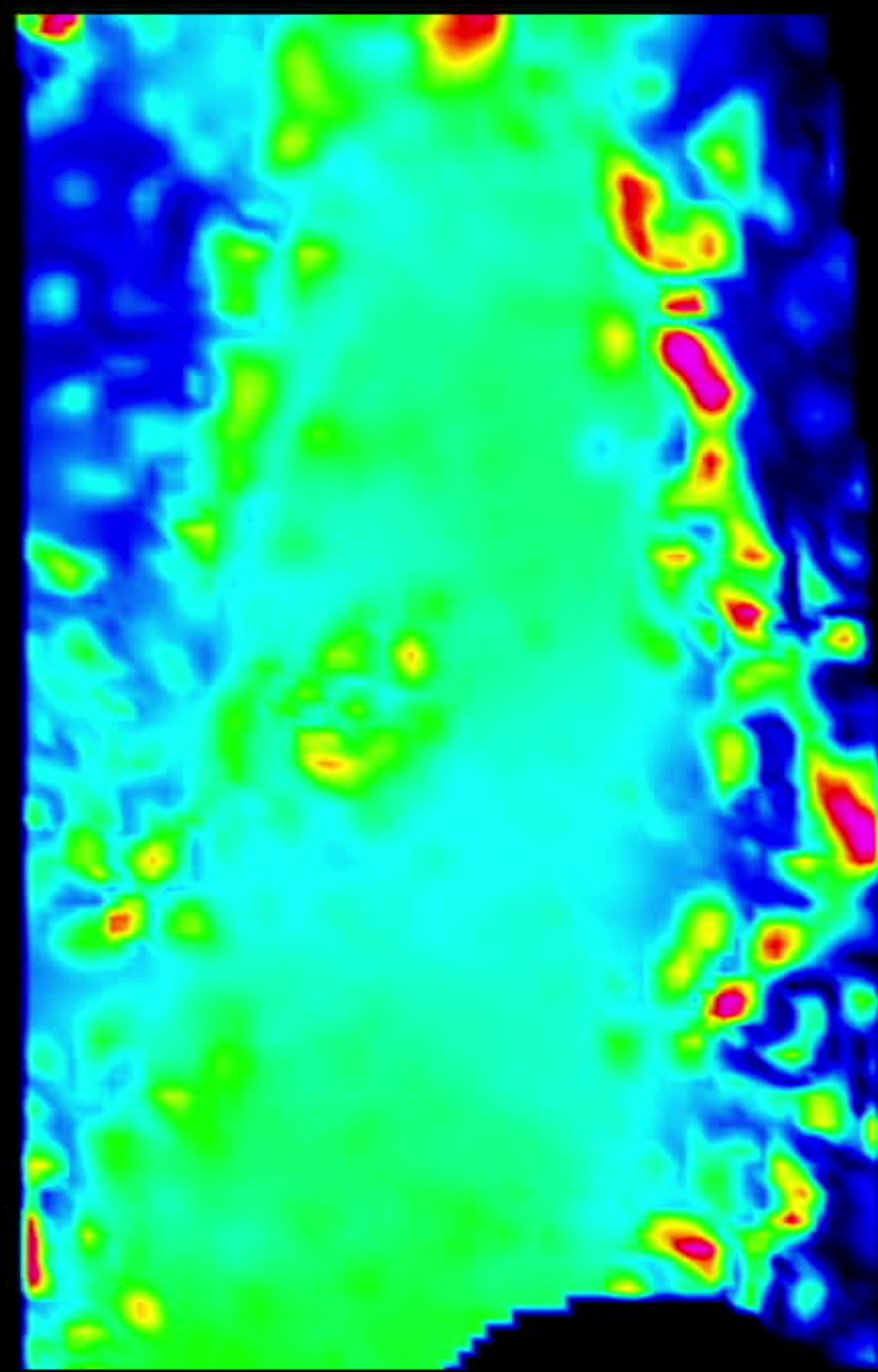
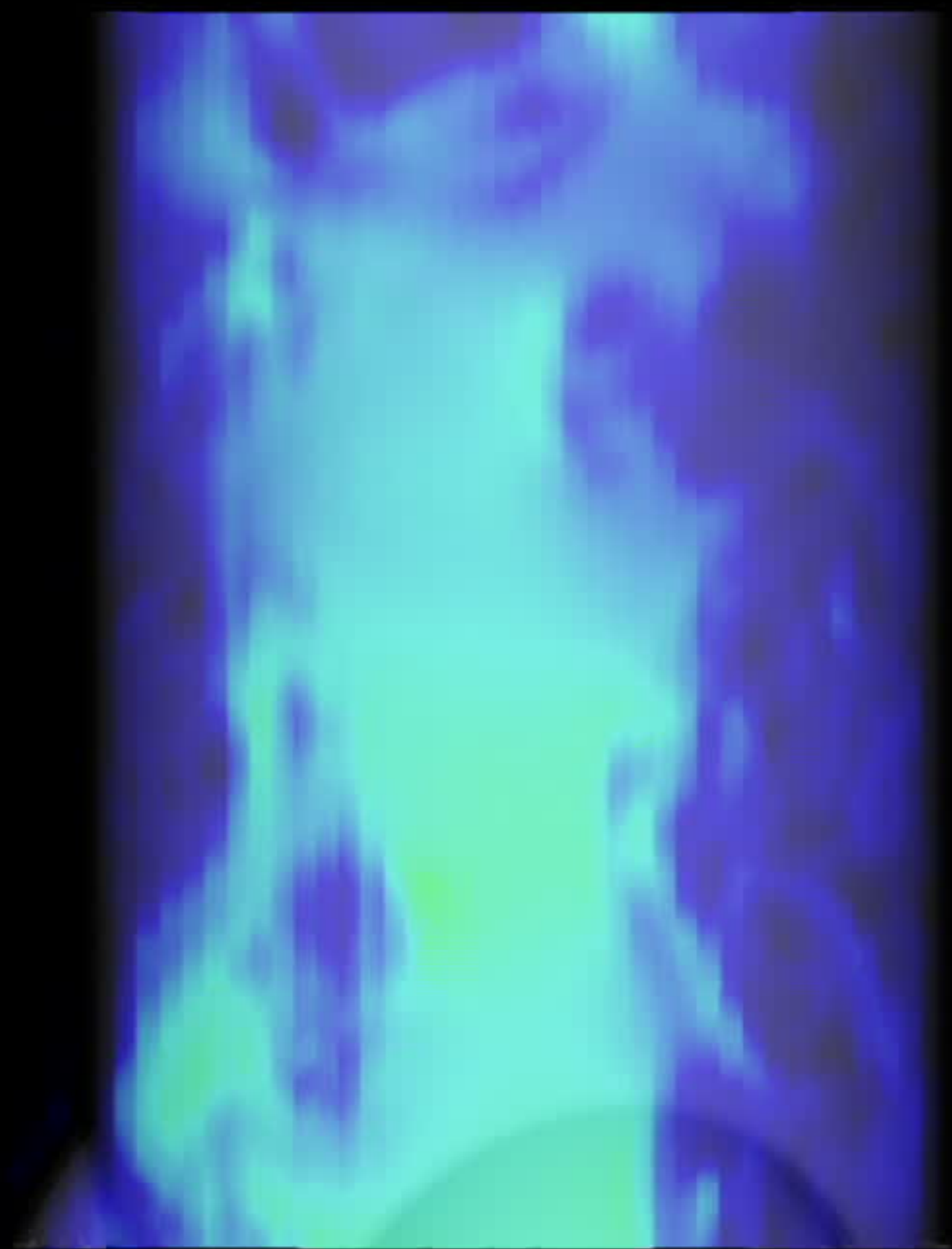
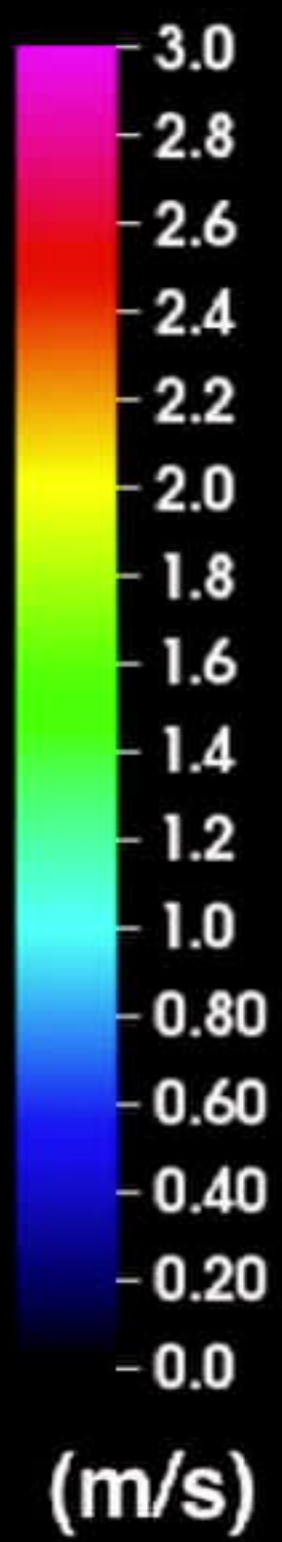


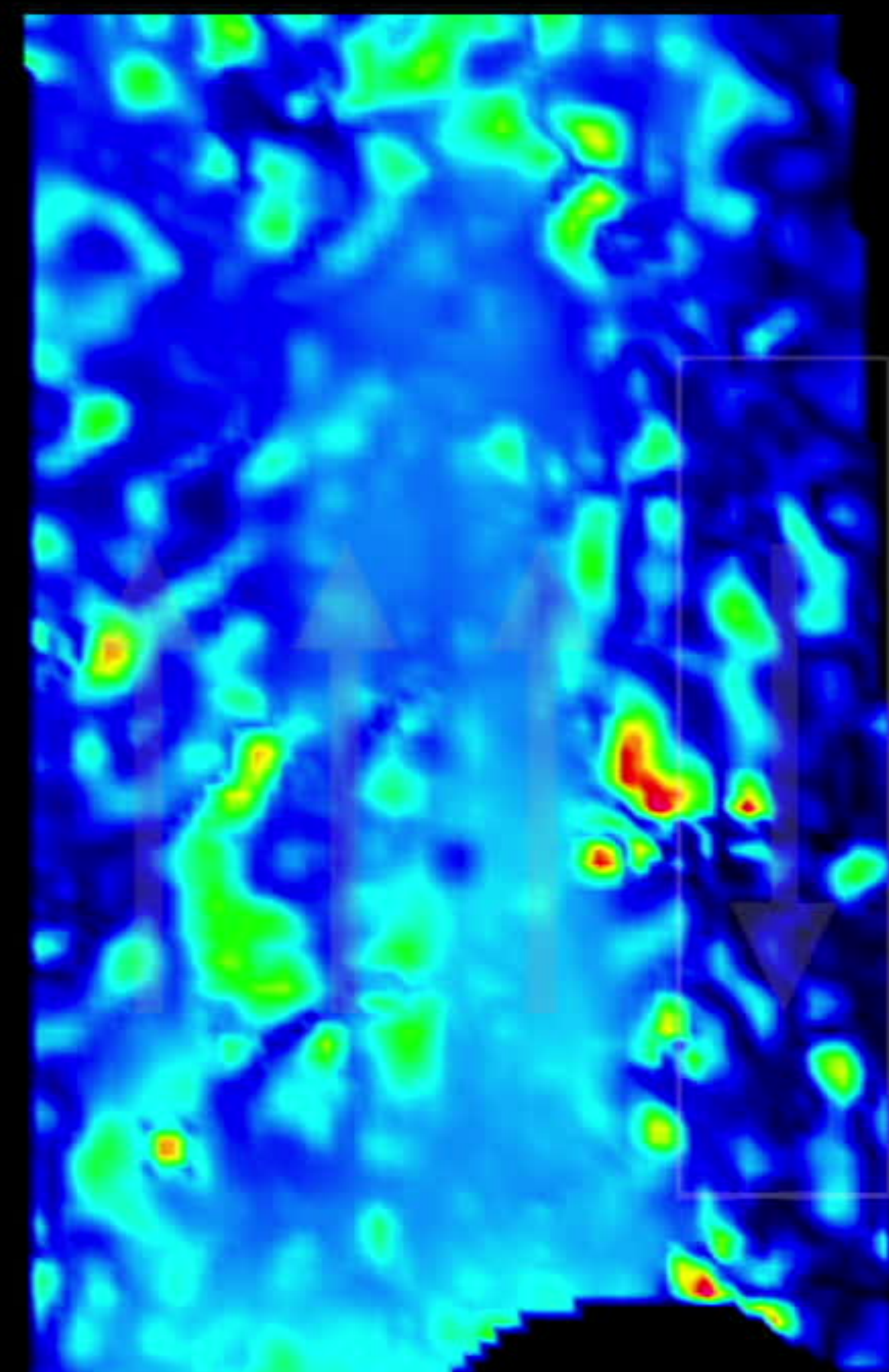
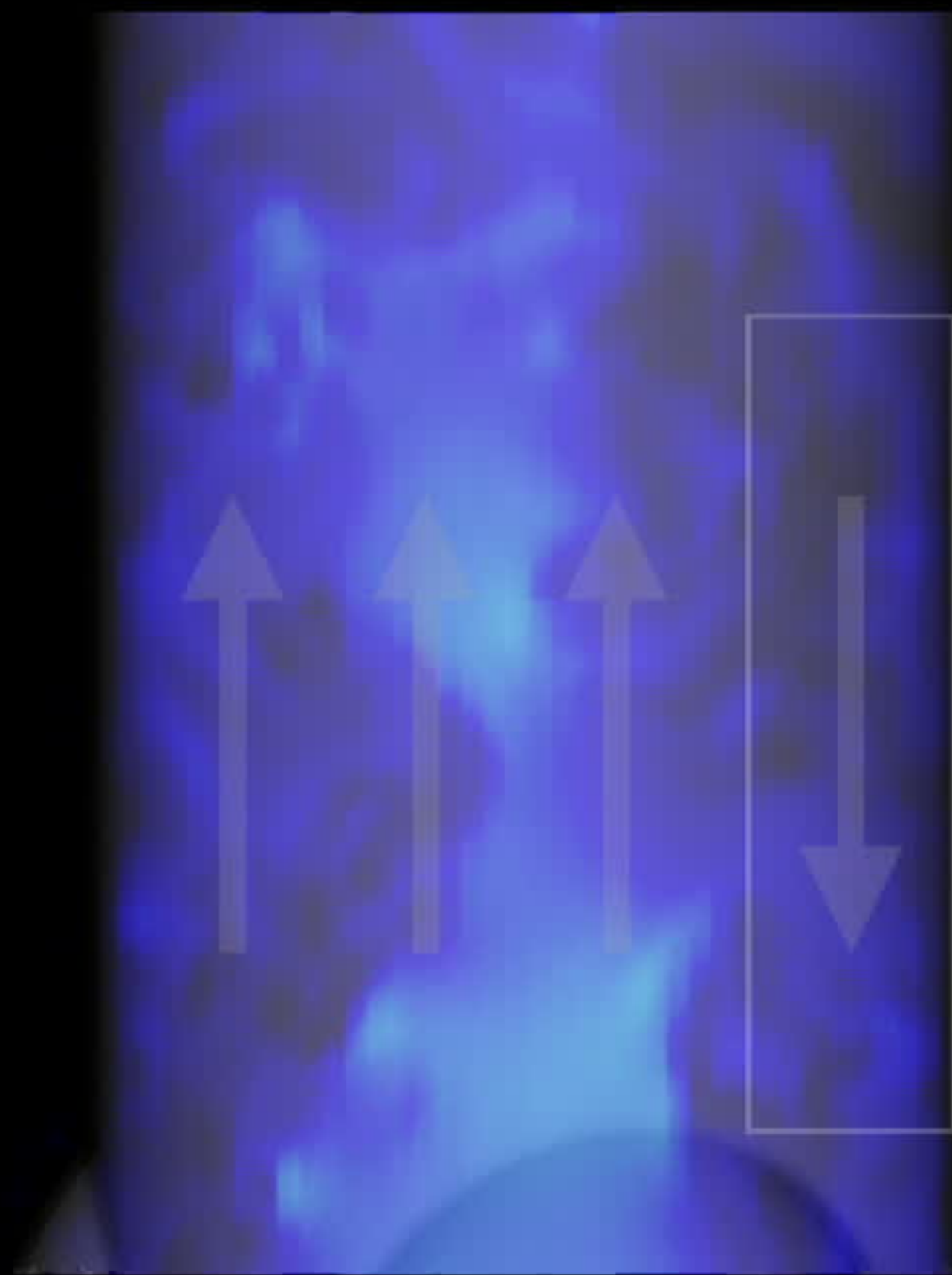
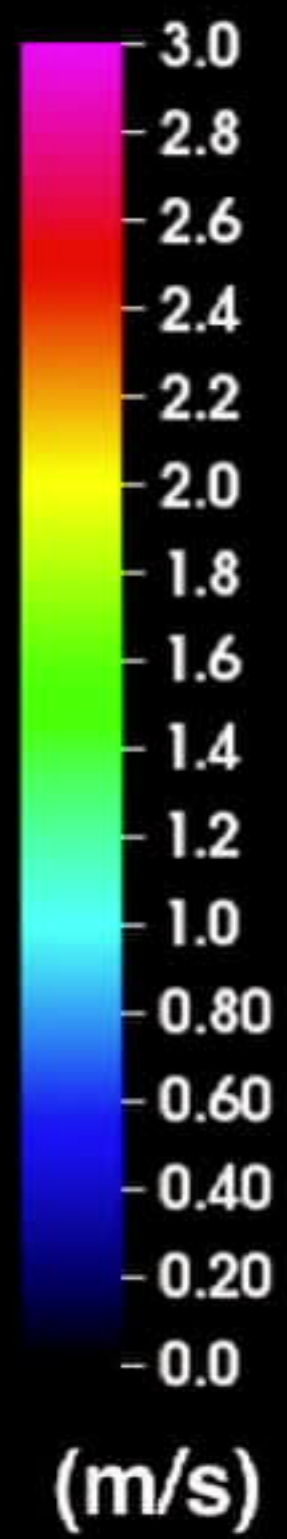


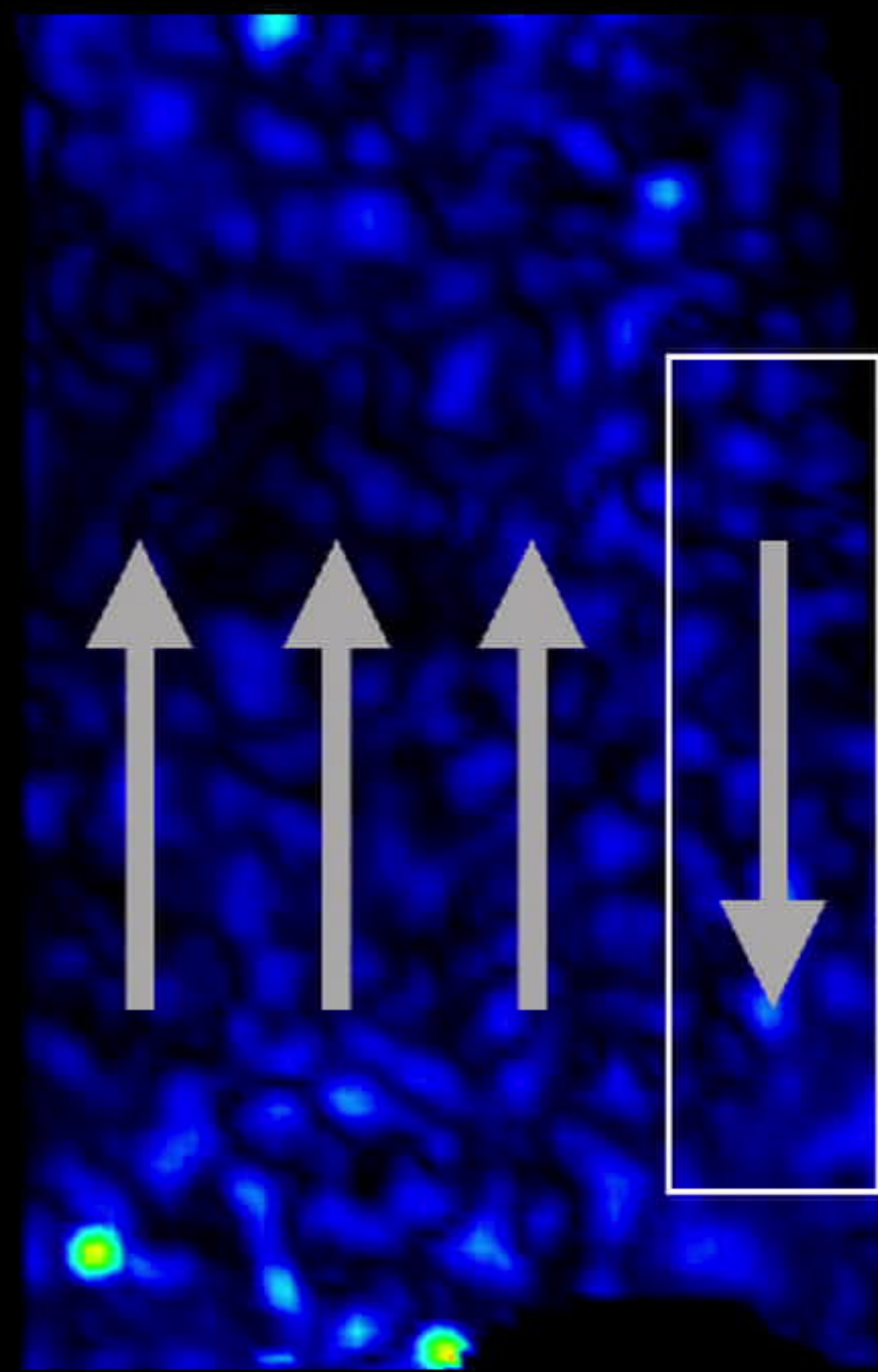
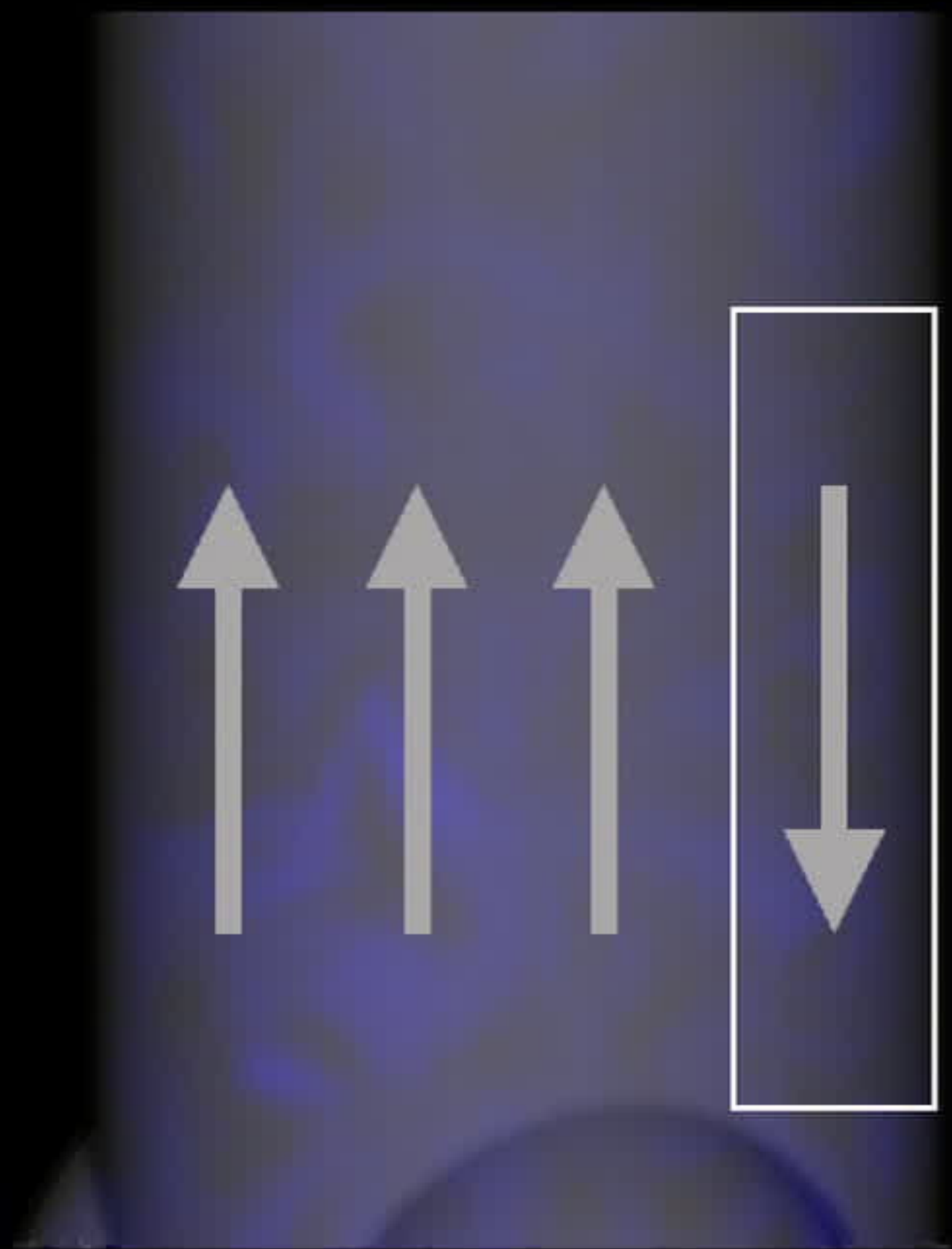
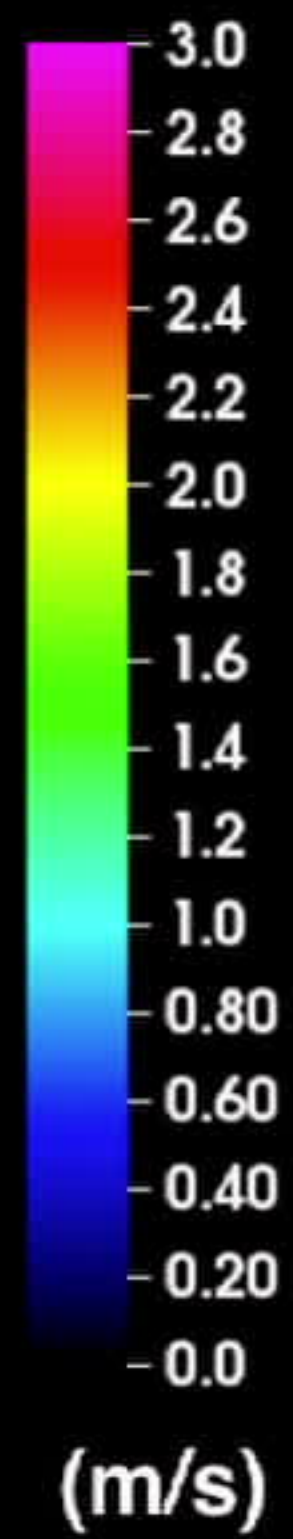


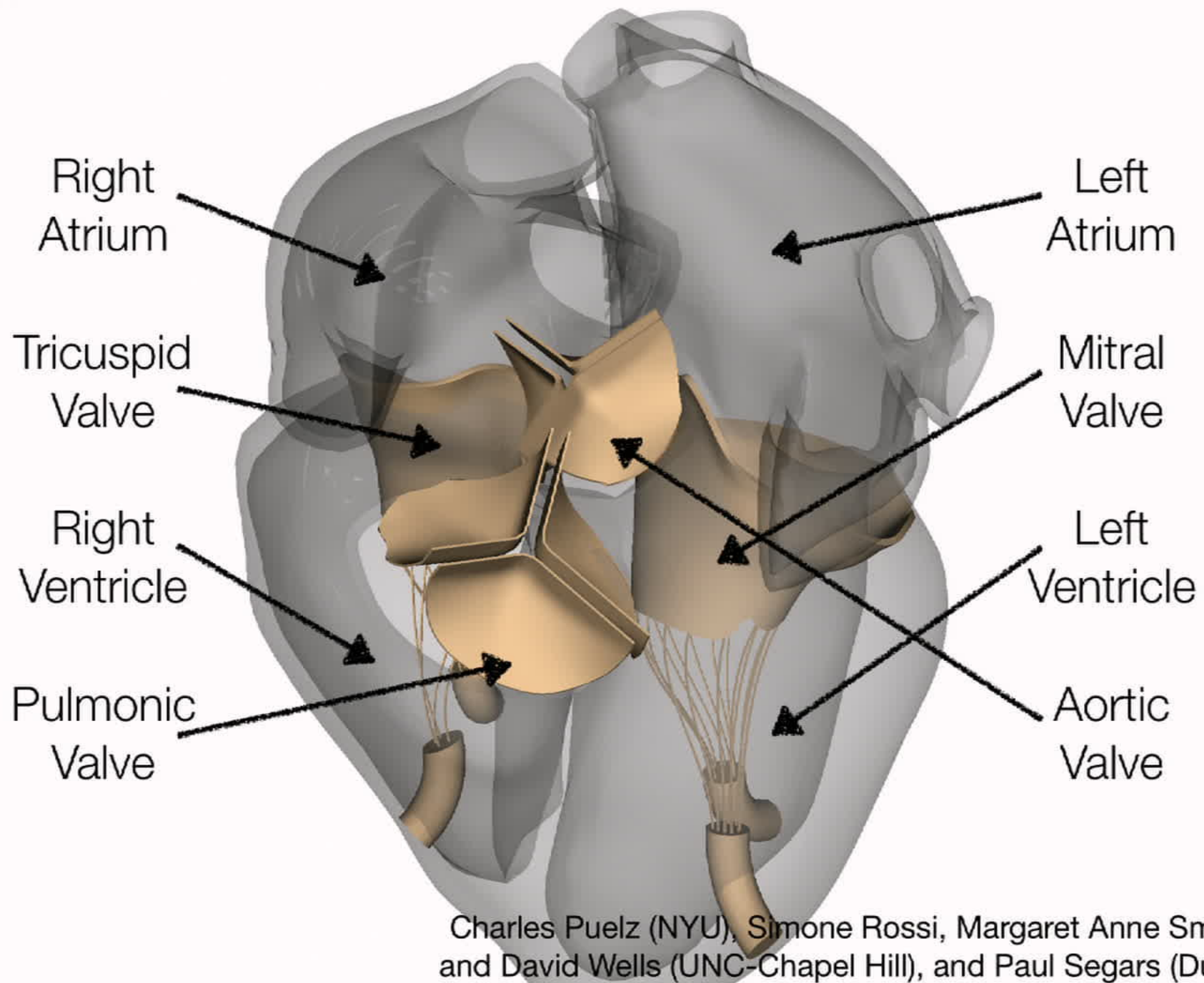






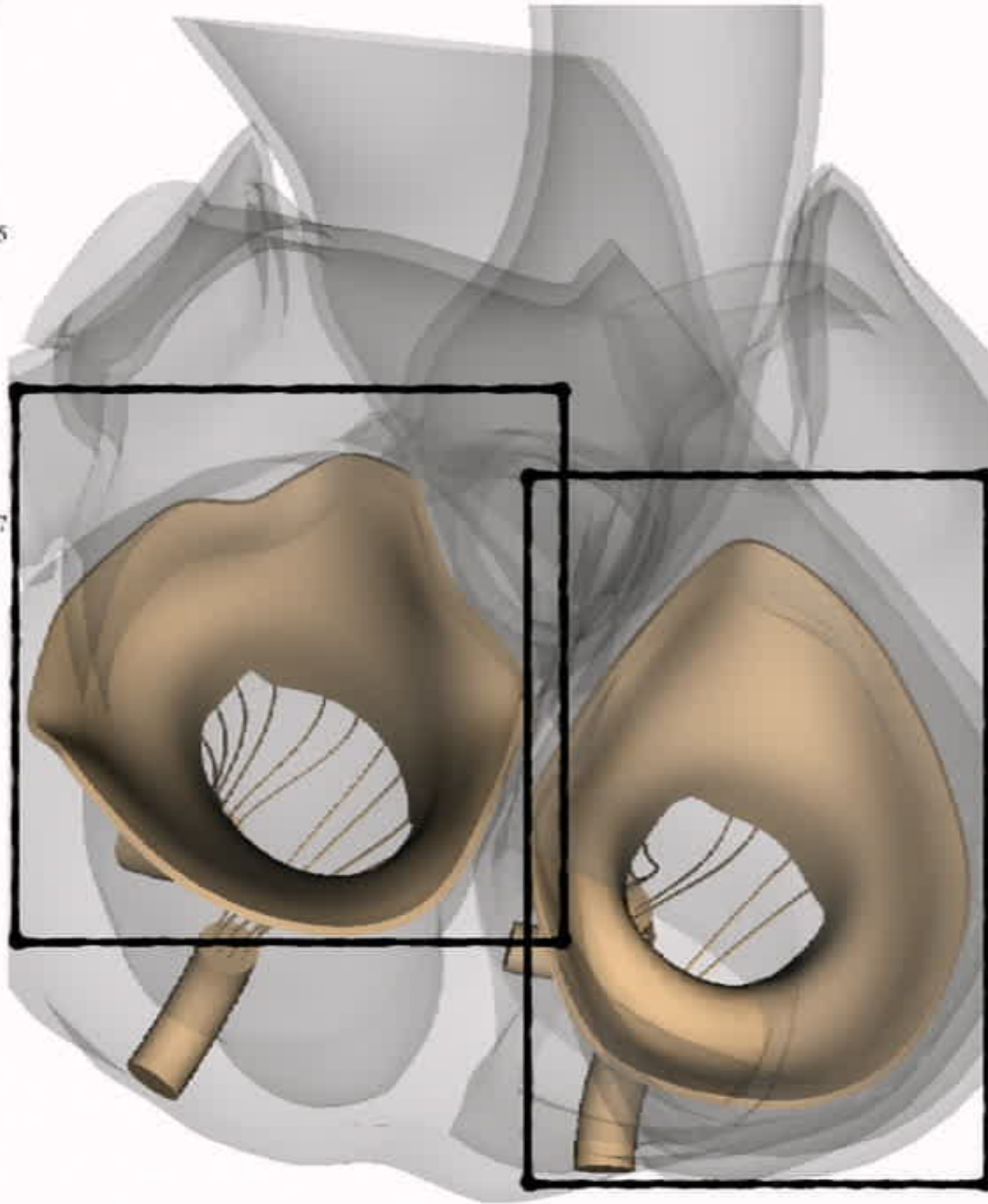
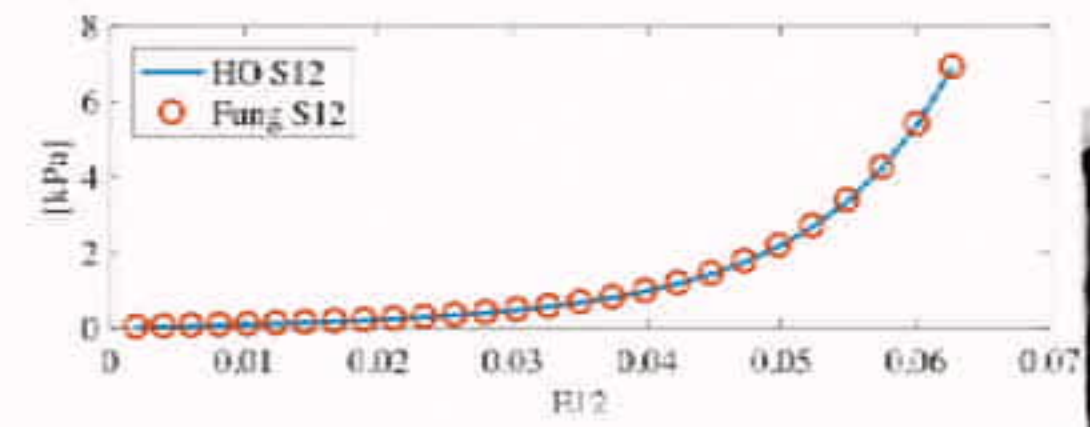
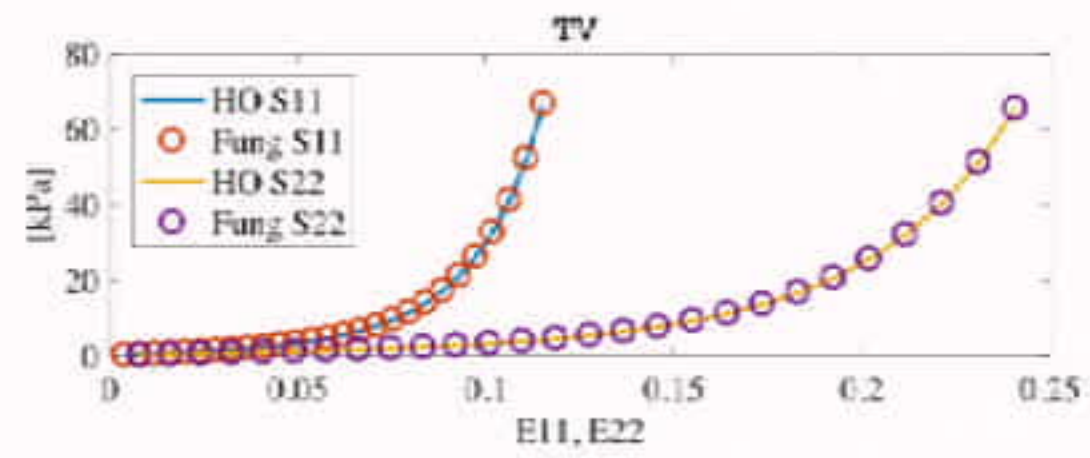




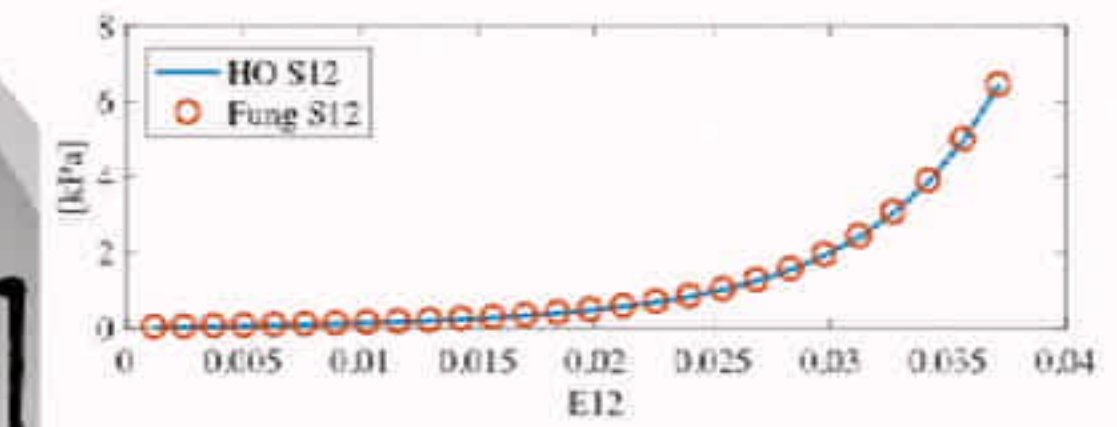
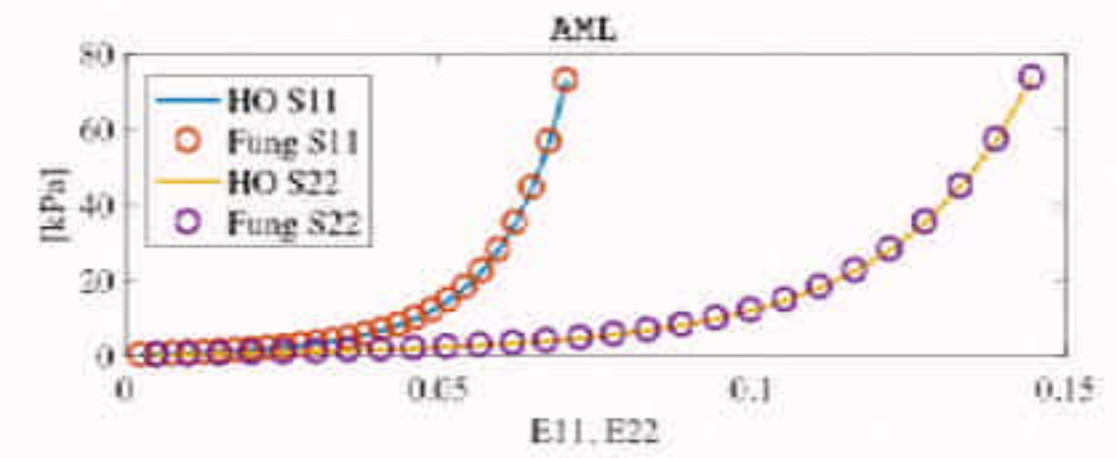


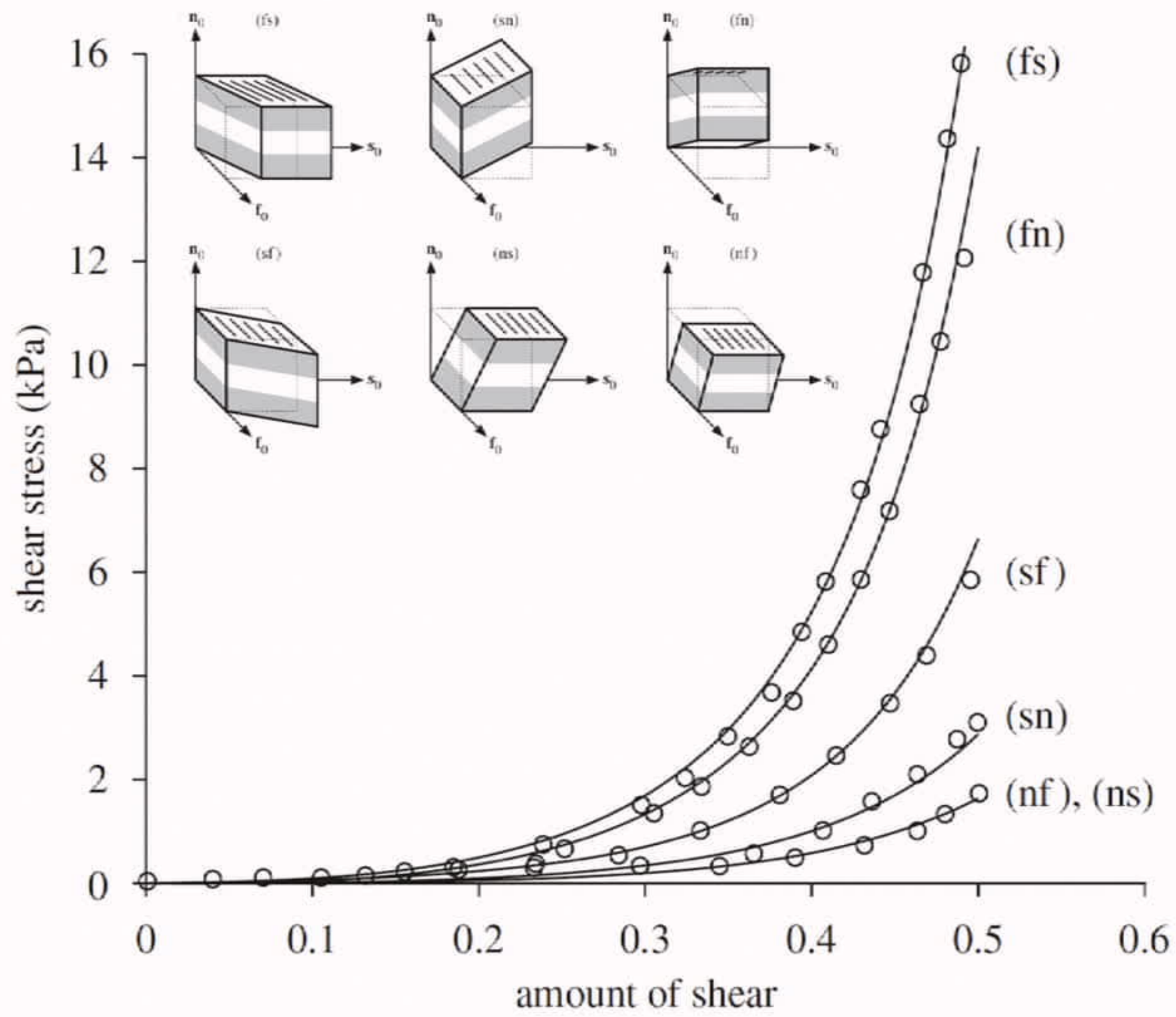
Charles Puelz (NYU), Simone Rossi, Margaret Anne Smith, and David Wells (UNC-Chapel Hill), and Paul Segars (Duke)

Tricuspid

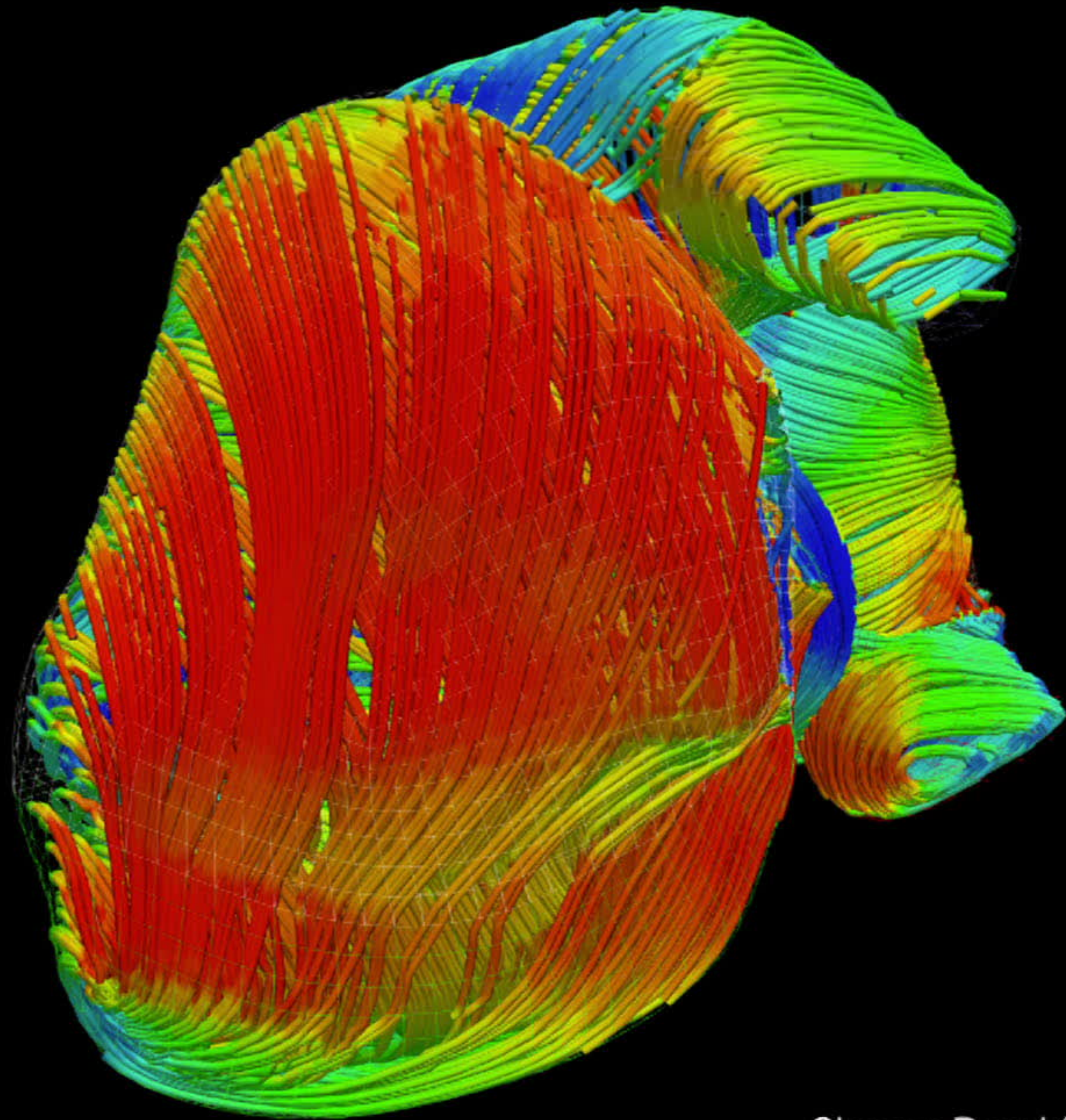


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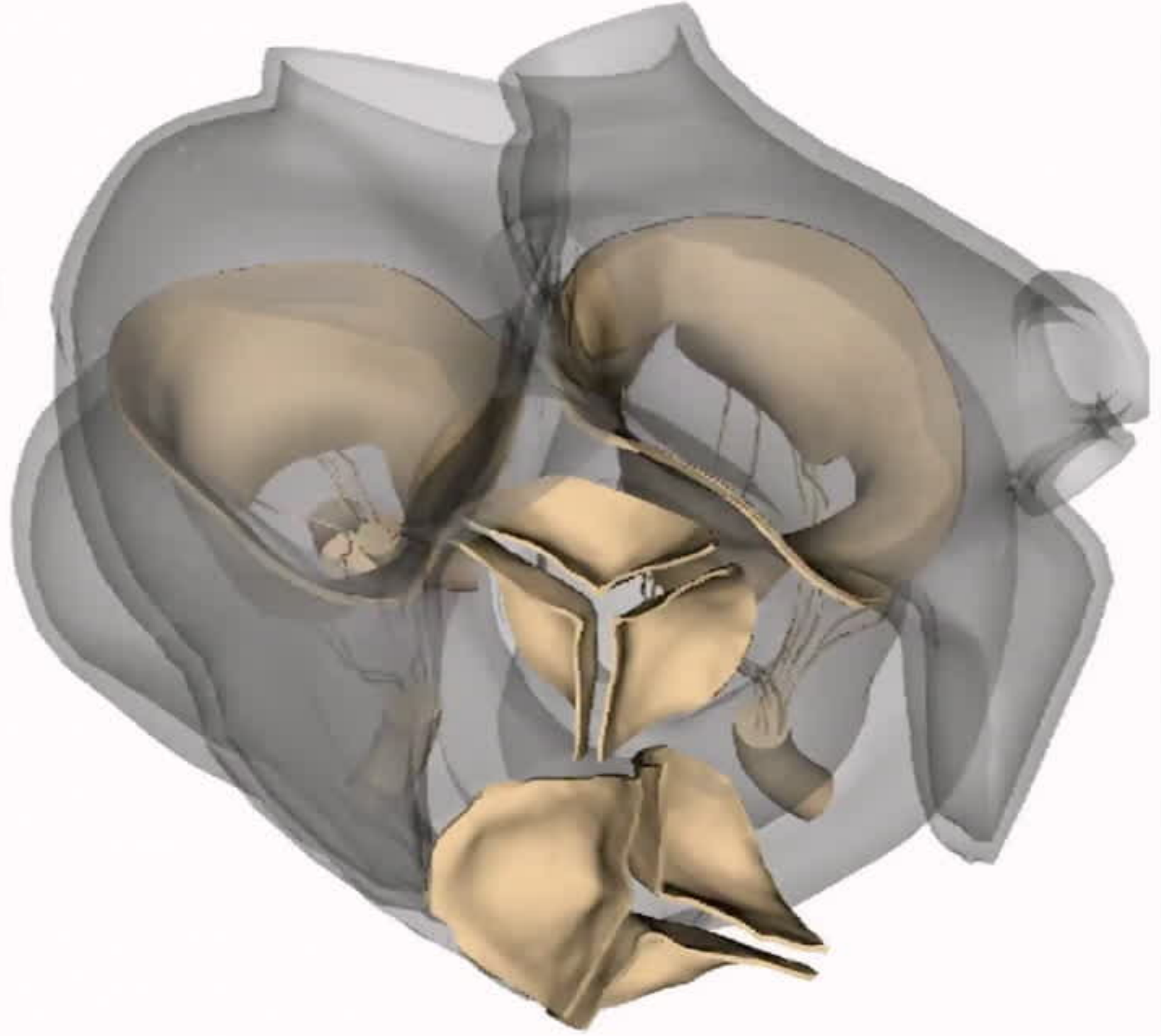
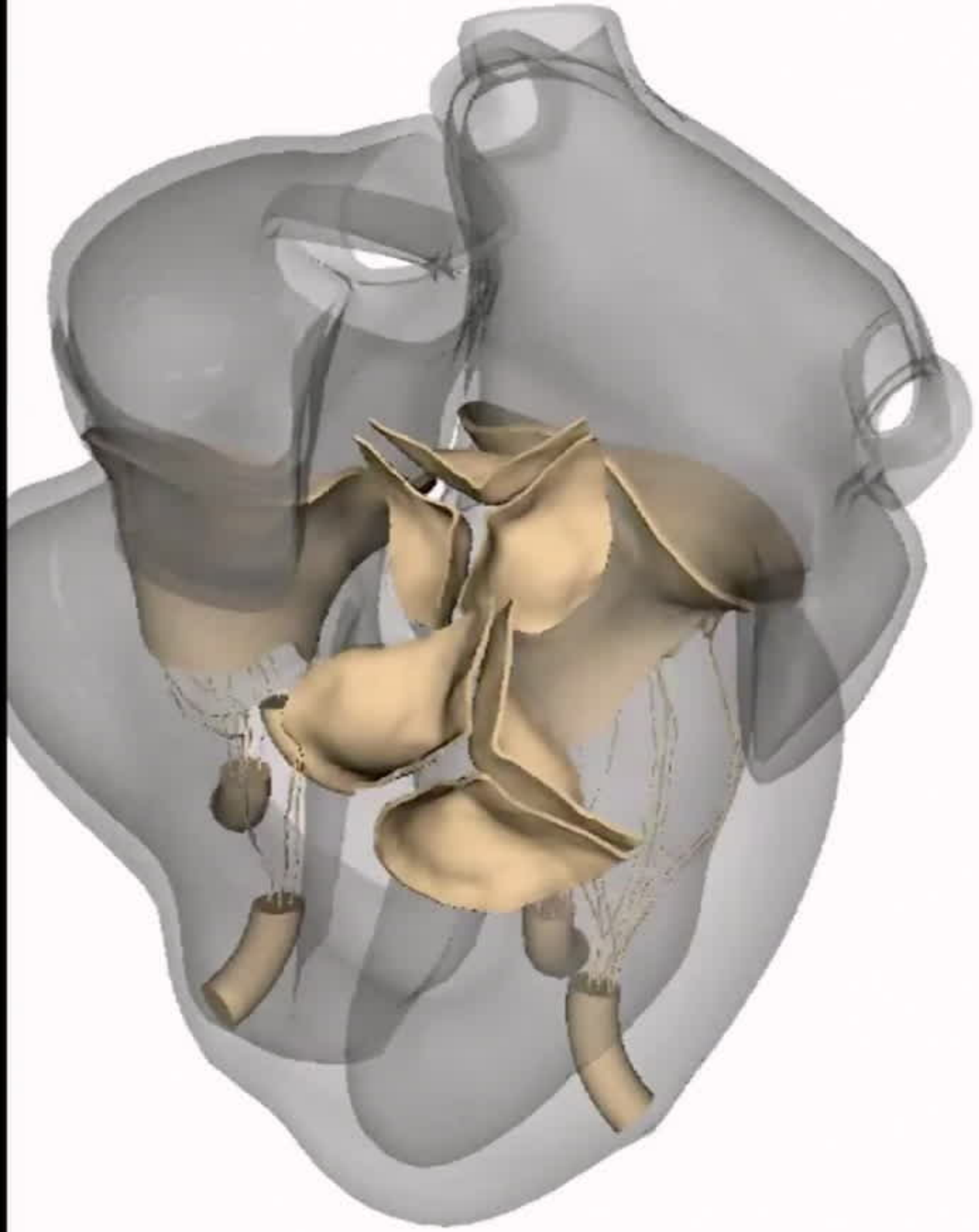




From Holzapfel and Ogden, *Phil Trans R Soc A*, 2009



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