

Functional maps + products =

Michael Bronstein

USI Lugano / Imperial College / Intel

SIAM AM, Portland, 13 July 2018



>\$10K

2005



\$100

2010



\$20

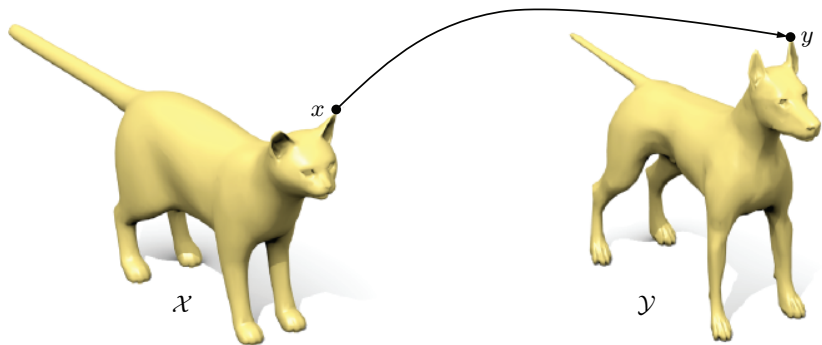
2014



\$17

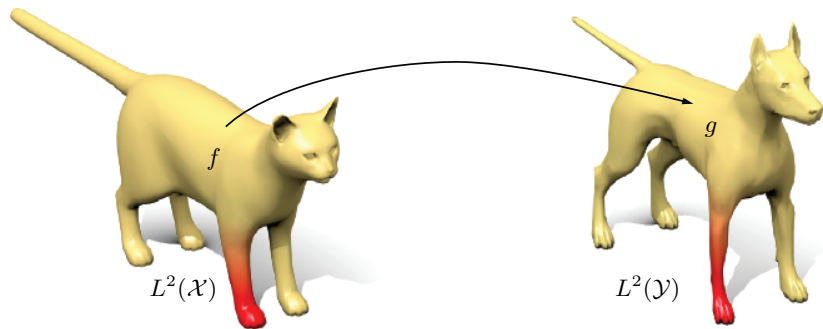
2017

Pointwise correspondence



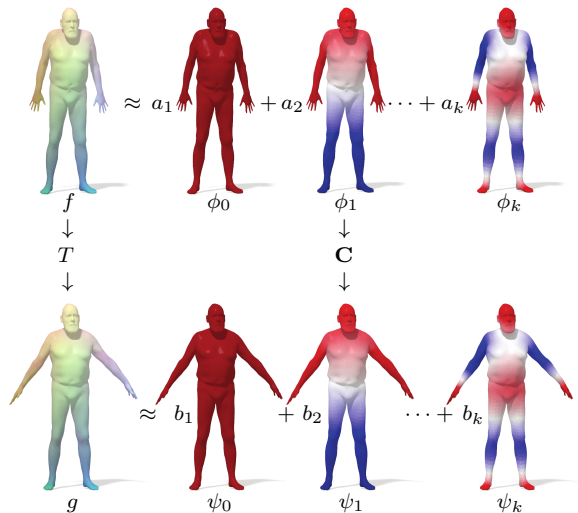
Point-wise map $t: \mathcal{X} \rightarrow \mathcal{Y}$

Functional correspondence

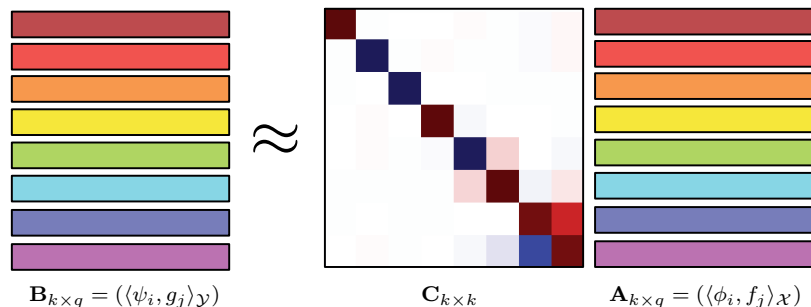


Functional map $T: L^2(\mathcal{X}) \rightarrow L^2(\mathcal{Y})$

Functional maps in spectral domain



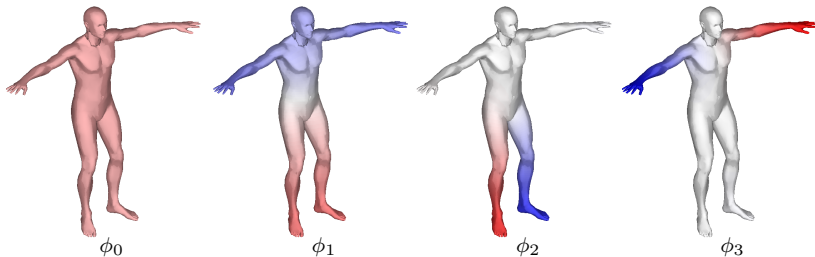
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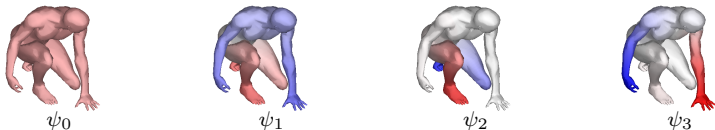
where \mathbf{A} , \mathbf{B} are Fourier coefficients of corresponding ‘probe’ functions

$$g_i \approx T f_i \quad i = 1, \dots, q \geq k$$

Laplacian eigenbasis



For shapes with simple spectrum, Laplacian eigenfunctions are invariant (up to sign) to isometric deformations, $\psi_i = \pm T\phi_i$



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- **Is Laplacian eigenbasis the best way to represent functional maps?**

Pointwise maps = product preserving maps

Theorem Functional map $T : L^2(\mathcal{X}) \rightarrow L^2(\mathcal{Y})$ is a pointwise map iff

$$T(f \cdot h) = (Tf) \cdot (Th)$$

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Functional maps in product bases

Product basis

$$f \approx \sum_{i=0}^k a_i \phi_i$$

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$$f \approx \sum_{i=0}^k a_i \phi_i + \sum_{j=1}^r \tilde{a}_j \prod_{l=1}^{r_j} \phi_{i_{jl}} \quad i_{jl} \in \{1, \dots, k\}$$

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$$\cos(nx) \cdot \cos(mx) = \frac{1}{2}[\cos((n+m)x) + \cos((n-m)x)]$$

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Product basis

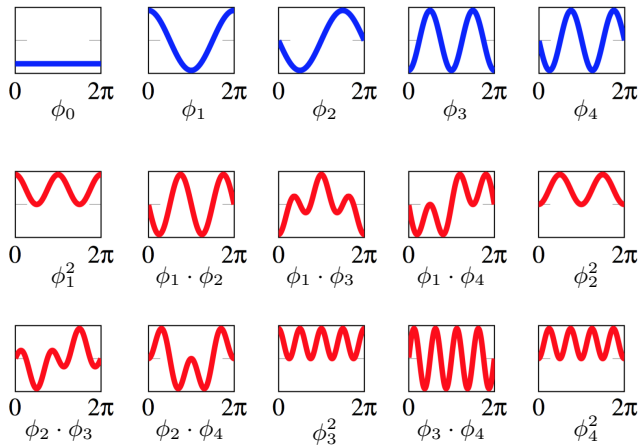
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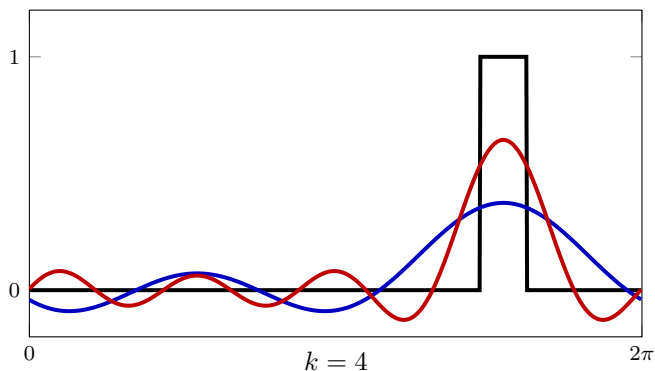
$$\cos(nx) \cdot \cos(mx) = \frac{1}{2}[\cos((n+m)x) + \cos((n-m)x)]$$

- Product basis is linearly dependent
- Orthogonality is lost
- Higher orders r become unstable
- Finding optimal approximation that minimizes the number of products used is NP-hard

Example: 1D product basis

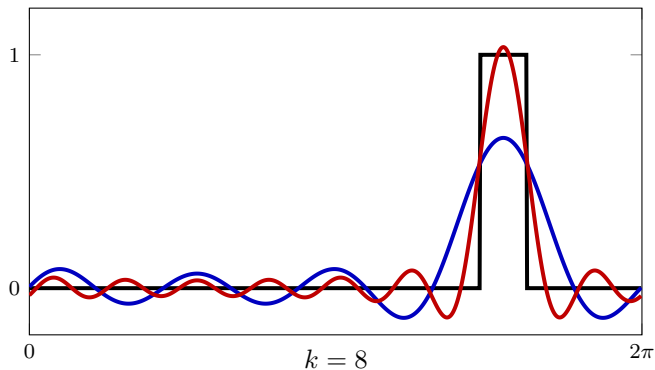


1D function approximation: standard vs product basis



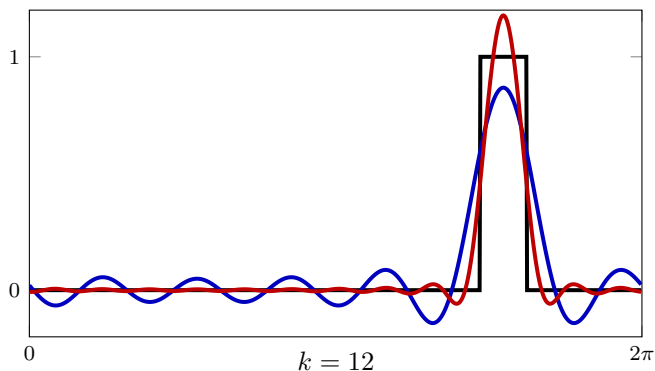
Approximation of a step function (black) using standard (blue) and product (red) bases of order $r = 2$

1D function approximation: standard vs product basis



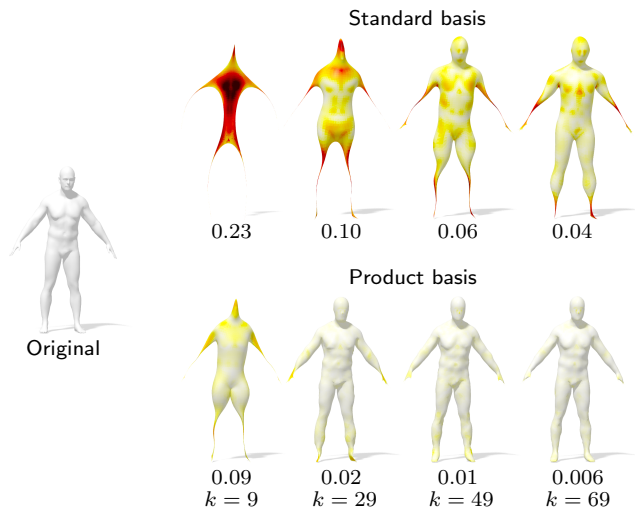
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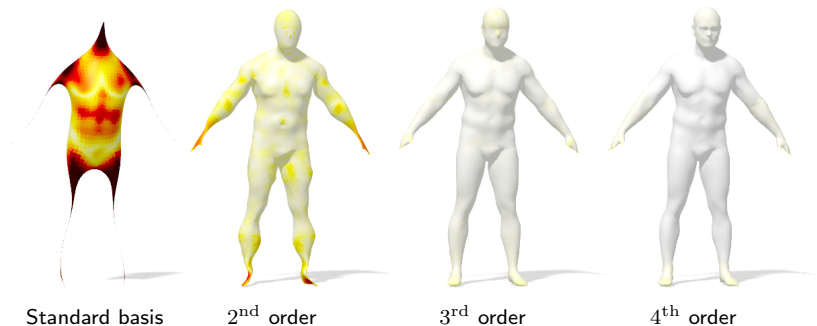
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3D function approximation: standard vs product basis



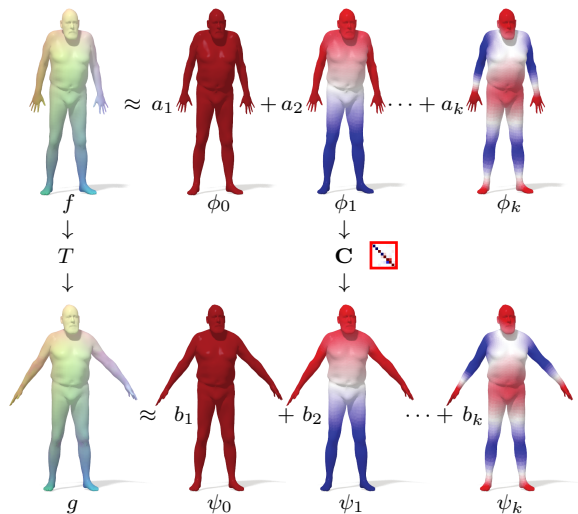
Approximation of the shape 3D coordinates in standard and product bases

3D function approximation: standard vs product basis



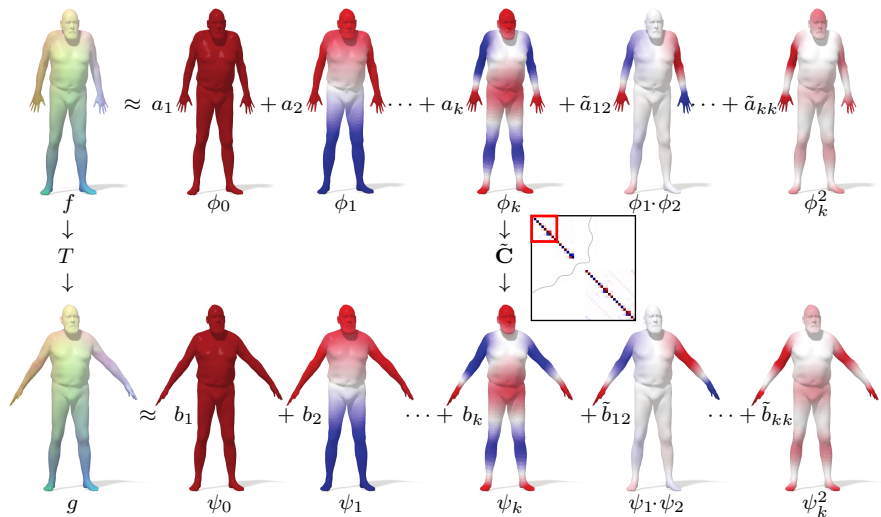
Reconstruction of the shape 3D coordinates using standard and product bases of different order ($k = 20$)

Functional maps in product bases



Nongeng, Melzi, Rodolà, Castellani, B, Ovsjanikov 2018

Functional maps in product bases



Functional maps in product bases

$$f \approx \sum_{i=0}^k a_i \phi_i + \sum_{i,j=1}^k \tilde{a}_{ij} \phi_i \cdot \phi_j$$

Functional maps in product bases

$$Tf \approx T \left(\sum_{i=0}^k a_i \phi_i + \sum_{i,j=1}^k \tilde{a}_{ij} \phi_i \cdot \phi_j \right)$$

Functional maps in product bases

$$Tf \approx \sum_{i=0}^k a_i T\phi_i + \sum_{i,j=1}^k \tilde{a}_{ij} T(\phi_i \cdot \phi_j)$$

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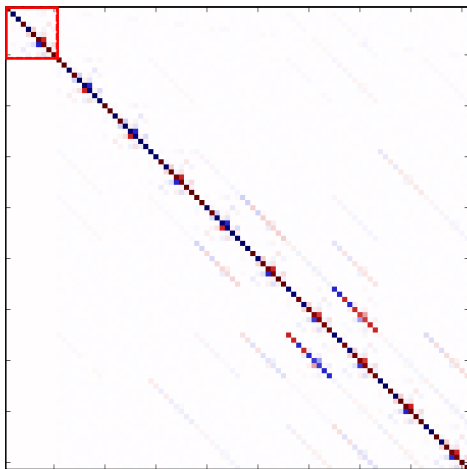
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Structure of matrix \tilde{C}



C



\tilde{C}

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$$\tilde{\mathbf{C}}(\mathbf{C}) = \begin{bmatrix} \mathbf{C} & \phi_{00} \mathbf{c}_0^\top \otimes \mathbf{C}_{01} + \phi_{00} \begin{bmatrix} \mathbf{0} \\ \mathbf{C}_{11} \end{bmatrix} \otimes \mathbf{c}_0^\top \\ & \mathbf{C}_{11} \otimes \mathbf{C}_{11} \end{bmatrix}$$

is matrix of size $(k^2 + k + 1) \times (k^2 + k + 1)$ expressed in terms of \mathbf{C} , and

$$\mathbf{C}_{11} = \begin{bmatrix} c_{11} & \dots & c_{1k} \\ \vdots & \vdots & \vdots \\ c_{k1} & \dots & c_{kk} \end{bmatrix} \quad \mathbf{C}_{01} = \begin{bmatrix} c_{01} & \dots & c_{0k} \\ \vdots & \vdots & \vdots \\ c_{k1} & \dots & c_{kk} \end{bmatrix} \quad \mathbf{c}_0^\top = [c_{00} \quad \dots \quad c_{0k}]$$

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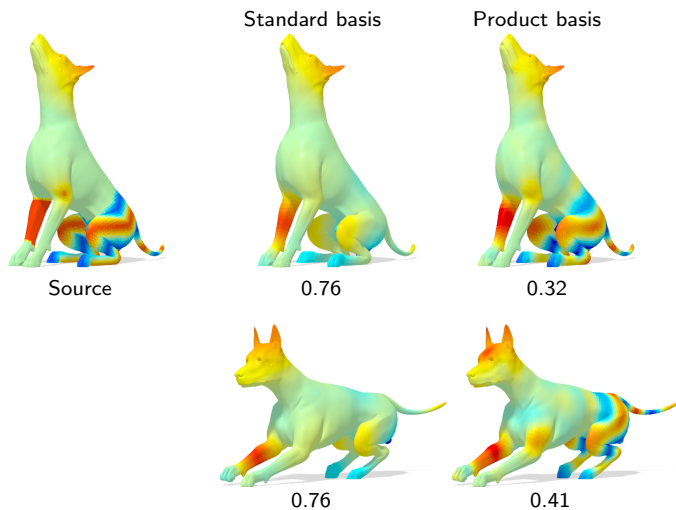
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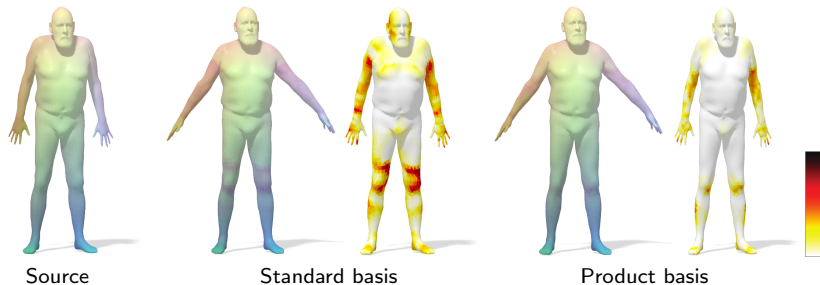
$\Rightarrow (k^2 + k + 1)^2$ coefficients, but only $(k + 1)^2$ degrees of freedom!

Standard vs product bases



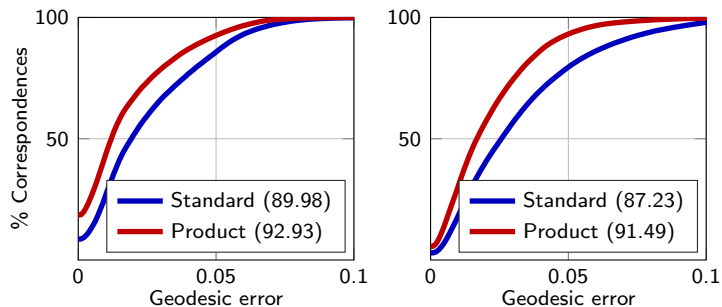
Function approximation and transfer error using standard and product bases

Example of correspondence on FAUST dataset



Correspondence (shown with matching colors) and correspondence error on SCAPE shapes using standard and product bases

Correspondence quality



Quality of functional maps computed with standard and product bases on FAUST (left) and TOSCA (right) shapes

Future directions

- Instead of improving a given functional map, finding pointwise functional maps by solving the non-linear problem

$$\min_{\mathbf{C} \in \mathbb{R}^{k \times k}} \|\mathbf{B} - \tilde{\mathbf{C}}(\mathbf{C})\mathbf{A}\|_{\mathbf{F}}^2$$

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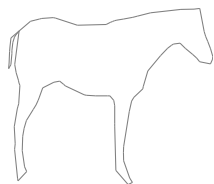
- More general definition of products (potentially combined with learning)

Issues with functional maps

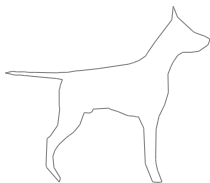
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Functional maps in product spaces

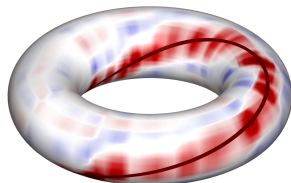
Correspondence in the product space



Source



Target



Product manifold

Functional map $T_\mu : \mathcal{F}(\mathcal{M}) \rightarrow \mathcal{F}(\mathcal{N})$ associated with a **density** $\mu \in L^1(\mathcal{M} \times \mathcal{N})$ on the product manifold $(\mathcal{M} \times \mathcal{N}, g_{\mathcal{M}} \oplus g_{\mathcal{N}})$

$$T_\mu(g)(x) = \int_{\mathcal{N}} g(y) \mu(x, y) dy$$

Laplacian eigenbasis on product manifold

Theorem Let $\mathcal{M} \times \mathcal{N}$ be a product manifold and let

$$\Delta_{\mathcal{M} \times \mathcal{N}} \xi = \gamma \xi$$

Then, there exist ϕ, ψ and α, β s.t. $\Delta_{\mathcal{M}} \phi = \alpha \phi$ and $\Delta_{\mathcal{N}} \psi = \beta \psi$ and

$$\gamma = \alpha + \beta \quad \xi = \phi \wedge \psi$$

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$\phi_0 \wedge \psi_0$



$\phi_1 \wedge \psi_0$



$\phi_0 \wedge \psi_1$



$\phi_2 \wedge \psi_0$



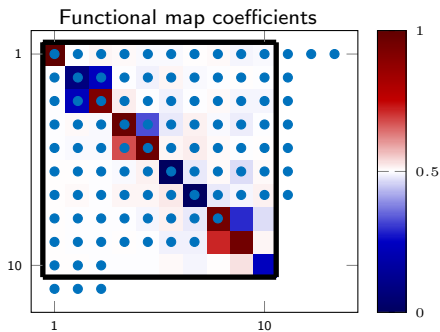
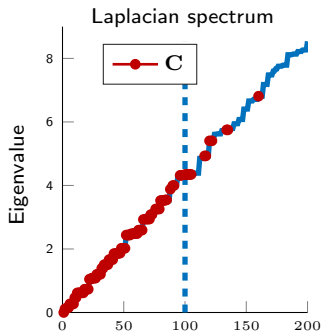
$\phi_3 \wedge \psi_0$

Representation equivalence

Theorem Let $c_{ij} = \langle \phi_i, T_\mu(\psi_j) \rangle_{\mathcal{M}}$ be the representation of T_μ in orthogonal bases $\{\phi_i\}_{i \geq 1}$, $\{\psi_i\}_{i \geq 1}$ and let $p_{ij} = \langle \phi_i \wedge \psi_j, \mu \rangle_{\mathcal{M} \times \mathcal{N}}$ such that $\mu = \sum_{i,j} (\phi_i \wedge \psi_j) p_{ij}$. Then $c_{ij} = p_{ij}$ for all i, j .

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Representation efficiency

$$\mu = \sum_{\ell=0}^k p_{\ell} \xi_{\ell}$$



$\phi_0 \wedge \psi_0$



$\phi_1 \wedge \psi_0$



$\phi_0 \wedge \psi_1$



$\phi_2 \wedge \psi_0$



$\phi_3 \wedge \psi_0$

Separable basis

Representation efficiency

$$\mu = \sum_{\ell=0}^k p_{\ell} \xi_{\ell}$$



ξ_0



ξ_2



ξ_3



ξ_4



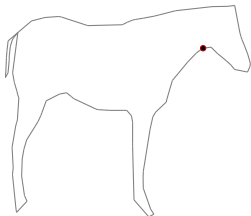
ξ_5

Non-separable localized basis

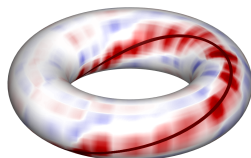
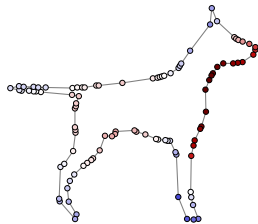
Eigenfunctions of the **Hamiltonian operator** $H = \Delta_{\mathcal{M} \times \mathcal{N}} + V$, where V is the localization potential

Rodolà, Löhner, BB, Solomon 2018; Choukroun et al. 2017; Melzi, Rodolà, Castellani, B 2017

Example: 1D correspondence

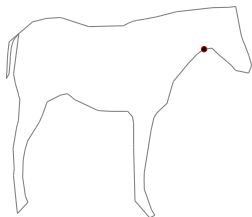


Source

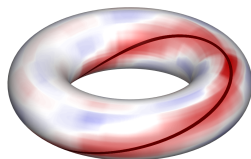
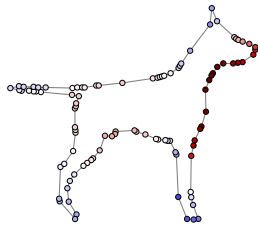


Delta function transfer using functional map on the product space computed in **separable basis**. Groundtruth correspondence shown in black.

Example: 1D correspondence

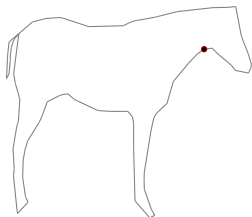


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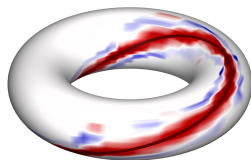
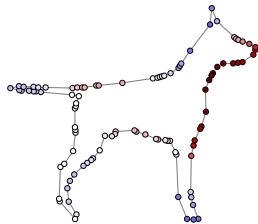


Delta function transfer using functional map on the product space computed in **localized basis (90% area)**. Groundtruth correspondence shown in black.

Example: 1D correspondence

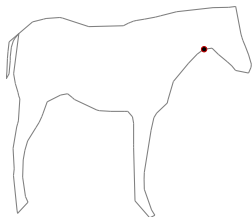


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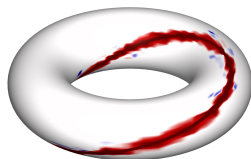
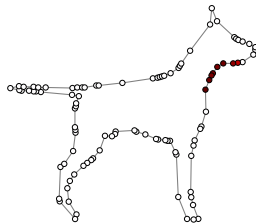


Delta function transfer using functional map on the product space computed in **localized basis (25% area)**. Groundtruth correspondence shown in black.

Example: 1D correspondence

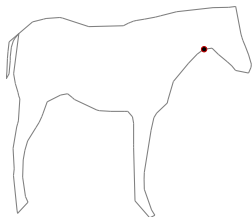


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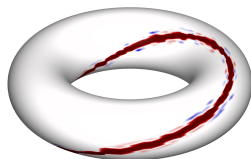
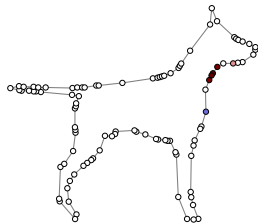


Delta function transfer using functional map on the product space computed in **localized basis (5% area)**. Groundtruth correspondence shown in black.

Example: 1D correspondence

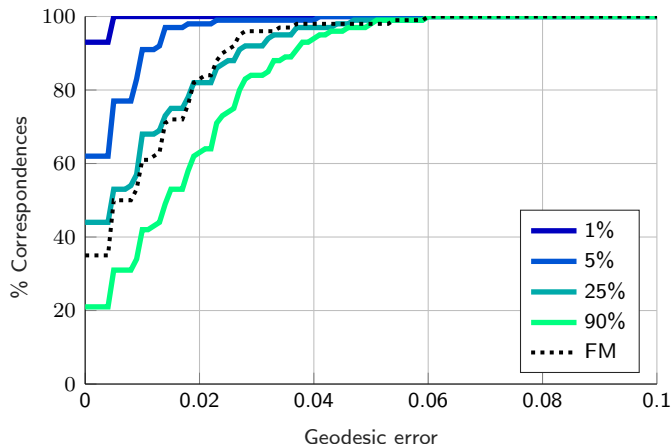


Source



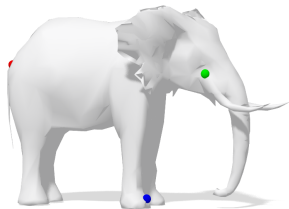
Delta function transfer using functional map on the product space computed in **localized basis (1% area)**. Groundtruth correspondence shown in black.

Example: 1D correspondence



Quality of correspondence on product manifold using different basis localization

Example: 2D correspondence



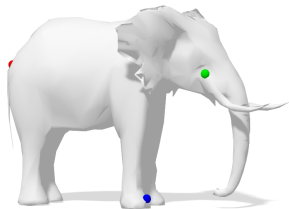
Source



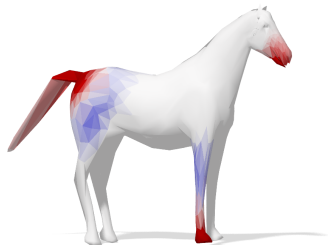
Target

Delta function transfer using functional map on the product space computed in **separable basis**.

Example: 2D correspondence



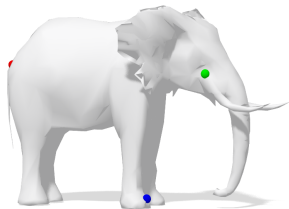
Source



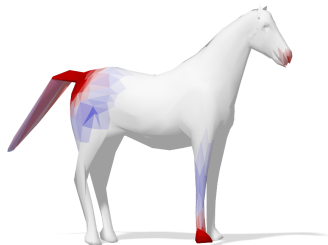
Target

Delta function transfer using functional map on the product space computed in **localized basis (15% area)**.

Example: 2D correspondence



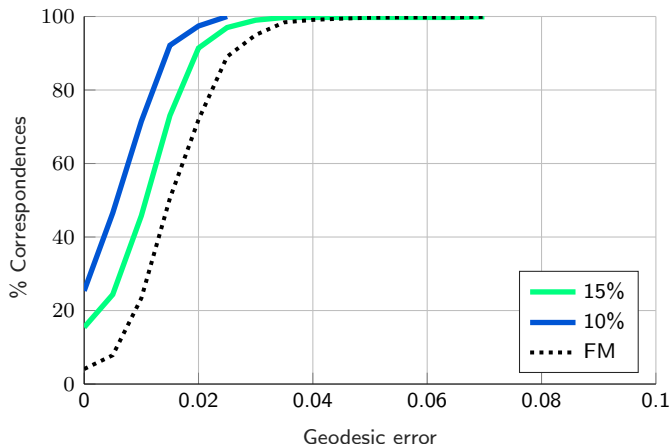
Source



Target

Delta function transfer using functional map on the product space computed in **localized basis (10% area)**.

Example: 2D correspondence



Quality of correspondence on product manifold using different basis localization

Two completely different uses of products yield novel and interesting representations of functional maps and shed new light on old problems

Functional maps + products = ♡



E. Rodolà



M. Ovsjanikov



D. Nogneng



U. Castellani



S. Melzi



Z. Löhner



A. Bronstein



J. Solomon



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Thank you!