

HOMOGENIZATION APPROACH FOR MODELING OF REACTIVE TRANSPORT IN POROUS MEDIA

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1. Introduction on homogenization
2. Reactive transport: Taylor dispersion
3. Numerical results
4. Non-equilibrium model
5. Generalizations and conclusion

**SIAM Conference on Mathematical & Computational Issues in the
Geosciences, March 11-14, 2019, Houston**

-I- INTRODUCTION

DEFINITION OF HOMOGENIZATION

- ☞ Rigorous version of *averaging*, or *upscaling*
- ☞ Process of *asymptotic analysis* when a scale parameter $\epsilon \rightarrow 0$

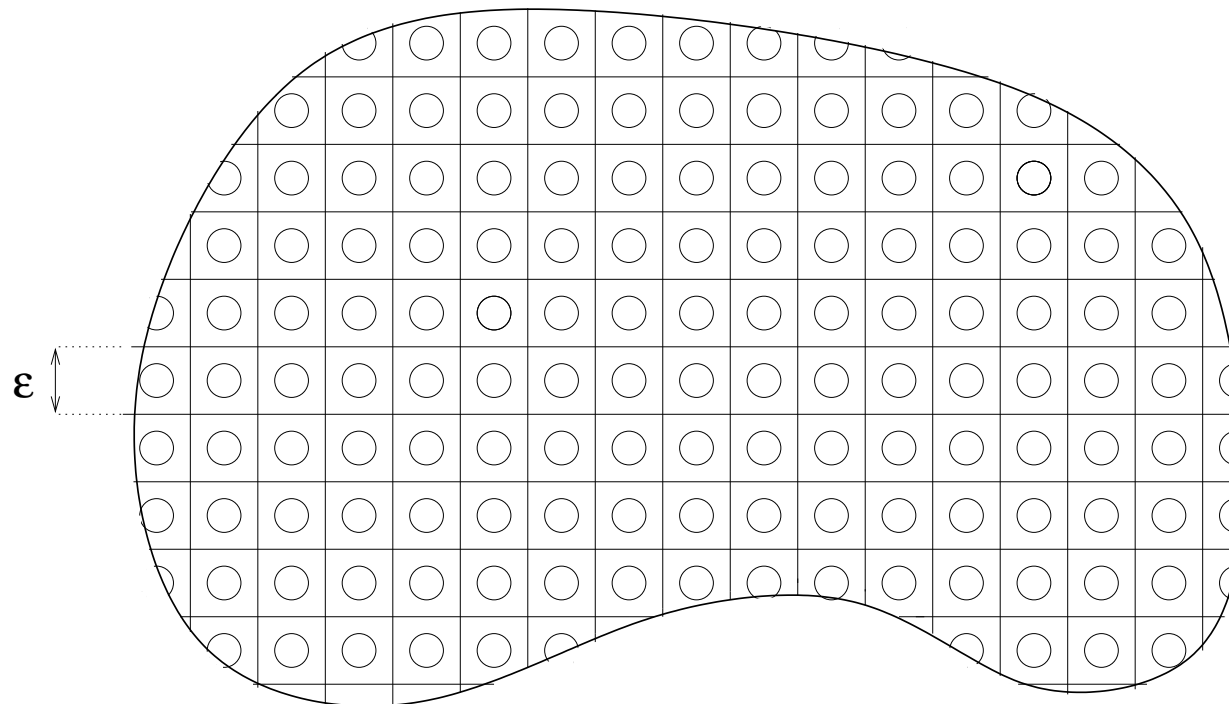
GOAL OF HOMOGENIZATION

- ☞ Extract *effective or homogenized parameters* for heterogeneous media
- ☞ Derive simpler *macroscopic models* from complicated *microscopic models*
- ☞ Basis for *multiscale numerical methods*

Various methods of homogenization (rigorous or not):

for simplicity, I focus on two-scale asymptotic expansions for periodic media.

PERIODIC HOMOGENIZATION



Ω

Main assumption: the heterogeneous medium is periodic. The small parameter ϵ is the ratio between the period and a characteristic size of the domain.

Model problem

Stationary diffusion equation

$$\begin{cases} -\operatorname{div} \left(A \left(\frac{x}{\epsilon} \right) \nabla u_\epsilon \right) = f(x) & \text{in } \Omega \\ u_\epsilon = 0 & \text{on } \partial\Omega \end{cases}$$

with a coefficient tensor $A(y)$ which is periodic in the unit cell $Y = (0, 1)^N$, uniformly coercive and bounded (not necessarily symmetric)

$$\alpha |\xi|^2 \leq \sum_{i,j=1}^N A_{ij}(y) \xi_i \xi_j \leq \beta |\xi|^2, \quad \forall \xi \in \mathbb{R}^N, \forall y \in Y \quad (\beta \geq \alpha > 0).$$

$$y \rightarrow A(y) \text{ 1-periodic} \Rightarrow x \rightarrow A \left(\frac{x}{\epsilon} \right) \text{ } \epsilon\text{-periodic}$$

Reference books

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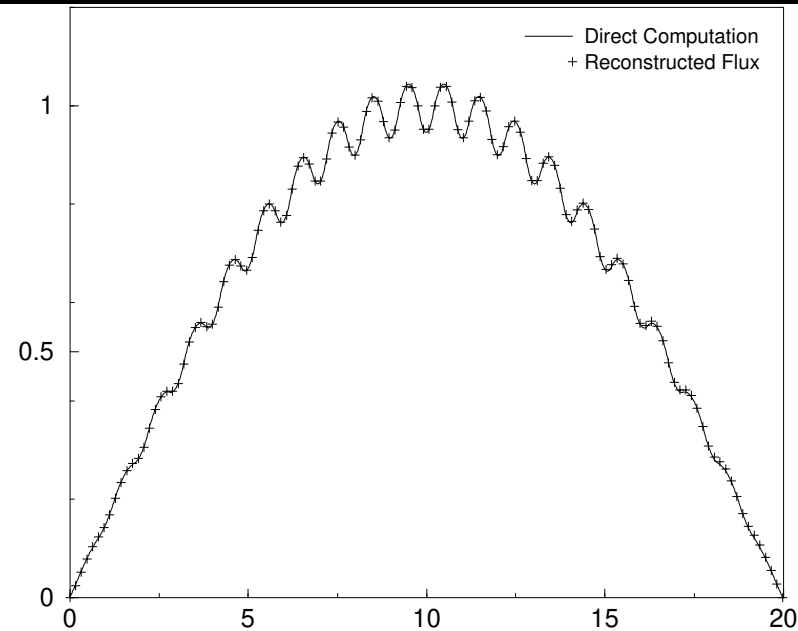
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JIKOV V., KOZLOV S., OLEINIK O., *Homogenization of differential operators and integral functionals*, Springer, Berlin, (1995).

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TWO-SCALE ASYMPTOTIC EXPANSIONS



Ansatz for the solution

$$u_\epsilon(x) = \sum_{i=0}^{+\infty} \epsilon^i u_i \left(x, \frac{x}{\epsilon} \right)$$

with $u_i(x, y)$ function of both variables x and y , periodic in y (see figure above).

Derivation rule

$$\nabla \left(u_i \left(x, \frac{x}{\epsilon} \right) \right) = \left(\epsilon^{-1} \nabla_y u_i + \nabla_x u_i \right) \left(x, \frac{x}{\epsilon} \right)$$

CASCADE OF EQUATIONS

$$-\epsilon^{-2} [\operatorname{div}_y A \nabla_y u_0] \left(x, \frac{x}{\epsilon} \right)$$

$$-\epsilon^{-1} [\operatorname{div}_y A (\nabla_x u_0 + \nabla_y u_1) + \operatorname{div}_x A \nabla_y u_0] \left(x, \frac{x}{\epsilon} \right)$$

$$-\epsilon^0 [\operatorname{div}_x A (\nabla_x u_0 + \nabla_y u_1) + \operatorname{div}_y A (\nabla_x u_1 + \nabla_y u_2)] \left(x, \frac{x}{\epsilon} \right)$$

$$-\sum_{i=1}^{+\infty} \epsilon^i [\operatorname{div}_x A (\nabla_x u_i + \nabla_y u_{i+1}) + \operatorname{div}_y A (\nabla_x u_{i+1} + \nabla_y u_{i+2})] \left(x, \frac{x}{\epsilon} \right)$$

$$= f(x).$$

Interpretation of the cascade of equations

In this series, each power ϵ^i is identified to zero:

$$-\operatorname{div}_y \left(A(y) \nabla_y u_{i+2}(x, y) \right) = F(u_i, u_{i+1})(x, y) \quad \text{in } Y$$

- ⇒ This is a partial differential equation in the **variable y** for the unknown u_{i+2} .
- ⇒ We supplement it with **periodic boundary conditions**.
- ⇒ The macroscopic variable x is just a **parameter**.
- ⇒ Only the 3 first equations are necessary.

ϵ^{-2} equation

$$u_0(x, y) \equiv u(x)$$

ϵ^{-1} equation

$$u_1(x, y) = \sum_{i=1}^N \frac{\partial u}{\partial x_i}(x) w_i(y).$$

where the w_i 's are the solutions of the [cell problems](#)

$$\begin{cases} -\operatorname{div}_y \left(A(y) (e_i + \nabla_y w_i(y)) \right) = 0 & \text{in } Y \\ y \rightarrow w_i(y) & Y\text{-periodic,} \end{cases}$$

ϵ^0 equation

\Rightarrow [homogenized equation](#)

$$\begin{cases} -\operatorname{div}_x \left(A^* \nabla_x u(x) \right) = f(x) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

Homogenized or effective tensor:

$$A_{ji}^* = \int_Y A(y) (e_i + \nabla_y w_i(y)) \cdot (e_j + \nabla_y w_j(y)) dy.$$

- ⇒ Explicit formula for A^* (depending on the [cell problems](#)).
- ⇒ A^* does not depend on ϵ , f , u or the boundary conditions.
- ⇒ A^* is positive definite (not necessarily isotropic even if $A(y)$ was so).

Theorem.

$$u_\epsilon(x) = u(x) + \epsilon u_1\left(x, \frac{x}{\epsilon}\right) + r_\epsilon \quad \text{with} \quad \|r_\epsilon\|_{H^1(\Omega)} \leq C\epsilon^{1/2}$$

In particular $\|u_\epsilon - u\|_{L^2(\Omega)} \leq C\epsilon^{1/2}$.

Remark. The first-order corrector is not negligible for the gradient

$$\nabla u_\epsilon(x) = \nabla_x u(x) + (\nabla_y u_1)\left(x, \frac{x}{\epsilon}\right) + t_\epsilon \quad \text{with} \quad \|t_\epsilon\|_{L^2(\Omega)} \leq C\epsilon^{1/2}$$

The error estimate is limited by boundary layers.

TWO-SCALE CONVERGENCE METHOD

One way of making periodic homogenization rigorous.

Definition. A sequence of functions u_ϵ in $L^2(\Omega)$ is said to **two-scale converge** to a limit $u_0(x, y)$ belonging to $L^2(\Omega \times Y)$ if, for any Y -periodic smooth function $\varphi(x, y)$, it satisfies

$$\lim_{\epsilon \rightarrow 0} \int_{\Omega} u_\epsilon(x) \varphi\left(x, \frac{x}{\epsilon}\right) dx = \int_{\Omega} \int_Y u_0(x, y) \varphi(x, y) dx dy.$$

Theorem (Nguetseng, Allaire). From each bounded sequence u_ϵ in $L^2(\Omega)$ one can extract a subsequence, and there exists a limit $u_0(x, y) \in L^2(\Omega \times Y)$ such that this subsequence two-scale converges to u_0 .

My goal in this lecture

- ☞ To go beyond the previous simple and "text-book" example !
- ☞ To emphasize the role of **scaling** in modeling issues.
- ☞ To work out the details **without too much mathematics...**
- ☞ I made the choice not to discuss the applications: too bad...
- ☞ My motivation was **nuclear waste underground storage**.

I start with the simplest of the complex models I want to address.

In the end, I will say a few words on more complex models...

-II- REACTIVE TRANSPORT

Microscopic model

- ✂ Infinite porous medium: (connected) fluid part $\Omega_f \subset \mathbb{R}^N$.
- ✂ Saturated incompressible single phase flow in Ω_f and a single solute.
- ✂ Linear reaction rates (adsorption/desorption process).
- ✂ Concentrations u in the fluid and v on the solid boundary.

convection diffusion in the bulk:

$$\frac{\partial u}{\partial \tau} + b \cdot \nabla_y u - \operatorname{div}_y (D \nabla_y u) = 0 \quad \text{in } \Omega_f \times (0, \mathcal{T}),$$

linear adsorption process on the pore boundaries:

$$\frac{\partial v}{\partial \tau} = k \left(u - \frac{v}{K} \right) = -D \nabla_y u \cdot n \quad \text{on } \partial \Omega_f \times (0, \mathcal{T}),$$

Assumptions and scaling

Incompressible fluid:

$$\operatorname{div} b = 0 \text{ in } \Omega_f \quad \text{and} \quad b \cdot n = 0 \text{ on } \partial\Omega_f.$$

At the microscopic scale (with characteristic lengthscale ℓ) the **Péclet and Damkohler numbers** are assumed of order 1

$$\mathbf{Pe} = \frac{\ell b}{D} \quad \text{and} \quad \mathbf{Da} = \frac{\ell k}{D}$$

To upscale this model, we define a large **macroscopic scale** ϵ^{-1} and a **long time scale** of order ϵ^{-2} (**parabolic or diffusion scaling**)

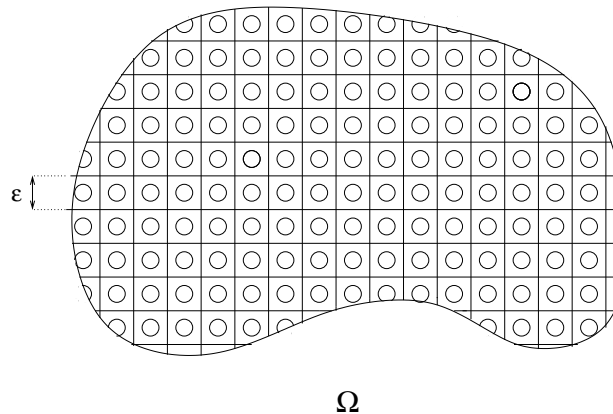
$$x = \epsilon y \quad \text{and} \quad t = \epsilon^2 \tau.$$

We define

$$u_\epsilon(t, x) = u(\tau, y) \quad \text{and} \quad v_\epsilon(t, x) = v(\tau, y).$$

Remark: another possibility is the **hyperbolic scaling** $x = \epsilon y$ and $t = \epsilon \tau$.

Periodicity assumption



- ✗ Periodic unit cell $Y = (0, 1)^N = Y^* \cup \mathcal{O}$ with fluid part Y^*
- ✗ Periodic (infinite) porous media $x \in \Omega_\epsilon \Leftrightarrow y \in Y^*$
- ✗ **Incompressible** periodic flow $b_\epsilon(x) = b\left(\frac{x}{\epsilon}\right)$ with $\operatorname{div}_y b = 0$ in Y^* and $b \cdot n = 0$ on $\partial\mathcal{O}$
- ✗ Periodic symmetric coercive diffusion $D_\epsilon(x) = D\left(\frac{x}{\epsilon}\right)$

Rescaled model

In these rescaled variables (with $T = \epsilon^2 \mathcal{T}$) the reactive transport system is

$$\left\{ \begin{array}{l} \frac{\partial u_\epsilon}{\partial t} + \frac{1}{\epsilon} b_\epsilon \cdot \nabla_x u_\epsilon - \operatorname{div}_x (D_\epsilon \nabla_x u_\epsilon) = 0 \quad \text{in } \Omega_\epsilon \times (0, T) \\ \frac{\partial v_\epsilon}{\partial t} = \frac{k}{\epsilon^2} \left(u_\epsilon - \frac{v_\epsilon}{K} \right) = \frac{-1}{\epsilon} D_\epsilon \nabla_x u_\epsilon \cdot n \quad \text{on } \partial\Omega_\epsilon \times (0, T) \\ u_\epsilon(x, 0) = u_{init}(x) \text{ and } v_\epsilon(x, 0) = v_{init}(x). \end{array} \right.$$

At the macroscopic scale (with characteristic lengthscale L) the **Péclet and Damkohler numbers** are **large**

$$\mathbf{Pe} = \frac{Lb}{D\epsilon} = \mathcal{O}(\epsilon^{-1}) \quad \mathbf{Da} = \frac{Lk}{D\epsilon} = \mathcal{O}(\epsilon^{-1})$$

Goal of homogenization

Find the effective diffusion tensor.

This is the so-called problem of **Taylor dispersion** (1953).

Many previous works, including Adler, Auriault, Choquet, van Duijn, Knabner, Mauri, Mikelic, Pop, Quintard, Rosier, Rubinstein, etc.

Theorem. The solution (u_ϵ, v_ϵ) satisfies

$$u_\epsilon(t, x) \approx u_0 \left(t, x - \frac{b^*}{\epsilon} t \right) \quad \text{and} \quad v_\epsilon(t, x) \approx K u_0 \left(t, x - \frac{b^*}{\epsilon} t \right)$$

with the **effective drift**

$$b^* = \frac{\int_{Y^*} b(y) dy}{|Y^*| + K |\partial\mathcal{O}|_{N-1}}$$

and u_0 the solution of the **homogenized problem**

$$\begin{cases} \frac{\partial u_0}{\partial t} - \operatorname{div}(A^* \nabla u_0) = 0 & \text{in } \mathbb{R}^N \times (0, T) \\ u_0(t=0, x) = \frac{|Y^*| u_{init}(x) + |\partial\mathcal{O}|_{N-1} v_{init}(x)}{|Y^*| + K |\partial\mathcal{O}|_{N-1}} & \text{in } \mathbb{R}^N \end{cases}$$

Remark. Transport and chemistry **cannot be decoupled** for computing effective coefficients.

Remarks

1) Precise convergence:

$$u_\epsilon(t, x) = u_0 \left(t, x - \frac{b^*}{\epsilon} t \right) + r_\epsilon^u(t, x) \quad \text{and} \quad v_\epsilon(t, x) = K u_0 \left(t, x - \frac{b^*}{\epsilon} t \right) + r_\epsilon^v(t, x)$$

with

$$\lim_{\epsilon \rightarrow 0} \int_0^T \int_{\mathbb{R}^N} |r_\epsilon^{u,v}(t, x)|^2 dt dx = 0,$$

2) Equivalent homogenized equation with convection: change coordinates !

Define $\tilde{u}_0(t, x) = u_0 \left(t, x - \frac{b^*}{\epsilon} t \right)$. Then, it is solution of

$$\begin{cases} \frac{\partial \tilde{u}_0}{\partial t} + \frac{1}{\epsilon} b^* \cdot \nabla \tilde{u}_0 - \operatorname{div} (A^* \nabla \tilde{u}_0) = 0 & \text{in } \mathbb{R}^N \times (0, T) \\ \tilde{u}_0(t=0, x) = \frac{|Y^*| u_{init}(x) + |\partial \mathcal{O}|_{N-1} v_{init}(x)}{|Y^*| + K |\partial \mathcal{O}|_{N-1}} & \text{in } \mathbb{R}^N \end{cases}$$

Homogenized diffusion tensor

The homogenized diffusion tensor is

$$A^* = (|Y^*| + K|\partial\mathcal{O}|_{N-1})^{-1} (A_1^* + A_2^*)$$

$$\text{with } A_1^* = \frac{K^2}{k} |\partial\mathcal{O}|_{N-1} b^* \otimes b^* \quad \text{and} \quad A_2^* = \int_{Y^*} D(\mathbf{I} + \nabla_y w(y)) (\mathbf{I} + \nabla_y w(y))^T dy$$

where the components $w_i(y)$, $1 \leq i \leq N$, of $w(y)$ are solutions of the cell problem

$$\left\{ \begin{array}{l} b(y) \cdot \nabla_y w_i - \operatorname{div}_y (D(y) (\nabla_y w_i + e_i)) = (b^* - b(y)) \cdot e_i \text{ in } Y^* \\ D(y) (\nabla_y w_i + e_i) \cdot n = Kb^* \cdot e_i \text{ on } \partial\mathcal{O} \\ y \rightarrow w_i(y) \text{ } Y\text{-periodic} \end{array} \right.$$

Remark that the value of b^* is exactly the compatibility condition for the existence of w_i .

TWO-SCALE ANSATZ WITH DRIFT

Formal proof of this homogenization result.

Standard two-scale asymptotic expansions must be modified to introduce an **unknown large drift** $b^* \in \mathbb{R}^N$

$$u_\epsilon(t, x) = \sum_{i=0}^{+\infty} \epsilon^i u_i \left(t, x - \frac{b^* t}{\epsilon}, \frac{x}{\epsilon} \right),$$

with $u_i(t, x, y)$ a function of the macroscopic variable x and of the periodic microscopic variable $y \in Y = (0, 1)^N$.

Similarly

$$v_\epsilon(t, x) = \sum_{i=0}^{+\infty} \epsilon^i v_i \left(t, x - \frac{b^* t}{\epsilon}, \frac{x}{\epsilon} \right)$$

We plug these ansatz in the system of equations and use the usual chain rule derivation

$$\nabla \left(u_i \left(t, x - \frac{b^*t}{\epsilon}, \frac{x}{\epsilon} \right) \right) = \left(\epsilon^{-1} \nabla_y u_i + \nabla_x u_i \right) \left(t, x - \frac{b^*t}{\epsilon}, \frac{x}{\epsilon} \right),$$

plus a **new** contribution

$$\frac{\partial}{\partial t} \left(u_i \left(t, x - \frac{b^*t}{\epsilon}, \frac{x}{\epsilon} \right) \right) = \left(\frac{\partial u_i}{\partial t} - \underbrace{\epsilon^{-1} b^* \cdot \nabla_x u_i}_{\text{new term}} \right) \left(t, x - \frac{b^*t}{\epsilon}, \frac{x}{\epsilon} \right)$$

$$\left\{ \begin{array}{l} \frac{\partial u_\epsilon}{\partial t} + \frac{1}{\epsilon} b_\epsilon \cdot \nabla_x u_\epsilon - \operatorname{div}_x (D_\epsilon \nabla_x u_\epsilon) = 0 \quad \text{in } \Omega_\epsilon \times (0, T) \\ u_\epsilon(x, 0) = u_{init}(x), \quad x \in \Omega_\epsilon, \\ \frac{\partial v_\epsilon}{\partial t} = \frac{k}{\epsilon^2} \left(u_\epsilon - \frac{v_\epsilon}{K} \right) = -\frac{1}{\epsilon} D_\epsilon \nabla_x u_\epsilon \cdot n \quad \text{on } \partial\Omega_\epsilon \times (0, T) \\ v_\epsilon(x, 0) = v_{init}(x), \quad x \in \partial\Omega_\epsilon \end{array} \right.$$

Fredholm alternative in the unit cell

Lemma. The boundary value problem

$$\begin{cases} b(y) \cdot \nabla_y v(y) - \operatorname{div}_y (D(y) \nabla_y v(y)) = g(y) \text{ in } Y^* \\ D(y) \nabla_y v(y) \cdot n = h(y) \text{ on } \partial \mathcal{O} \\ y \rightarrow v(y) \text{ } Y\text{-periodic} \end{cases}$$

admits a unique solution in $H^1(Y^*)$, up to an additive constant, **if and only if**

$$\int_{Y^*} g(y) dy + \int_{\partial \mathcal{O}} h(y) ds = 0.$$

Cascade of equations

Equation of order ϵ^{-2} :

$$\begin{cases} b(y) \cdot \nabla_y u_0 - \operatorname{div}_y (D(y) \nabla_y u_0) = 0 \text{ in } Y^* \\ D(y) \nabla_y u_0 \cdot n = 0 = k \left(u_0 - \frac{v_0}{K} \right) \text{ on } \partial \mathcal{O} \\ y \rightarrow u_0, v_0(t, x, y) \text{ } Y\text{-periodic} \end{cases}$$

We deduce

$$u_0(t, x, y) \equiv u_0(t, x) \text{ and } v_0(t, x, y) \equiv K u_0(t, x)$$

Equation of order ϵ^{-1} :

$$\left\{ \begin{array}{l} -b^* \cdot \nabla_x u_0 + b(y) \cdot (\nabla_x u_0 + \nabla_y u_1) - \operatorname{div}_y (D(y) (\nabla_x u_0 + \nabla_y u_1)) = 0 \text{ in } Y^* \\ -D(y) (\nabla_x u_0 + \nabla_y u_1) \cdot n = -b^* \cdot \nabla_x v_0 \cdot n = k \left(u_1 - \frac{v_1}{K} \right) \text{ on } \partial \mathcal{O} \\ y \rightarrow u_1, v_1(t, x, y) \text{ } Y\text{-periodic} \end{array} \right.$$

We deduce

$$u_1(t, x, y) = \sum_{i=1}^n \frac{\partial u_0}{\partial x_i}(t, x) w_i(y) \quad \text{and} \quad v_1 = K u_1 + \frac{K^2}{k} b^* \cdot \nabla_x u_0$$

Cell problem

$$\left\{ \begin{array}{l} b(y) \cdot \nabla_y w_i - \operatorname{div}_y (D(y) (\nabla_y w_i + e_i)) = (b^* - b(y)) \cdot e_i \text{ in } Y^* \\ D(y) (\nabla_y w_i + e_i) \cdot n = Kb^* \cdot e_i \text{ on } \partial\mathcal{O} \\ y \rightarrow w_i(y) \text{ } Y\text{-periodic} \end{array} \right.$$

The compatibility condition (Fredholm alternative) for the existence of w_i gives the value of the drift velocity:

$$b^* = (|Y^*| + |\partial\mathcal{O}|_{N-1}K)^{-1} \int_{Y^*} b(y) dy.$$

Equation of order ϵ^0 :

$$\left\{ \begin{array}{l} b \cdot \nabla_y u_2 - \operatorname{div}_y (D \nabla_y u_2) = b^* \cdot \nabla_x u_1 - b \cdot \nabla_x u_1 \\ + \operatorname{div}_y (D \nabla_x u_1) + \operatorname{div}_x (D(\nabla_y u_1 + \nabla_x u_0)) - \frac{\partial u_0}{\partial t} \quad \text{in } Y^* \\ -D(y) (\nabla_y u_2 + \nabla_x u_1) \cdot n = \frac{\partial v_0}{\partial t} - b^* \cdot \nabla_x v_1 = k \left(u_2 - \frac{v_2}{K} \right) \quad \text{on } \partial \mathcal{O} \\ y \rightarrow u_2, v_2(t, x, y) \text{ } Y\text{-periodic} \end{array} \right.$$

Compatibility condition for the existence of u_2 :

$$\int_{Y^*} \left(b^* \cdot \nabla_x u_1 - b \cdot \nabla_x u_1 + \operatorname{div}_y (D \nabla_x u_1) + \operatorname{div}_x (D(\nabla_y u_1 + \nabla_x u_0)) - \frac{\partial u_0}{\partial t} \right) dy - \int_{\partial \mathcal{O}} \left(D \nabla_x u_1 \cdot n + \frac{\partial v_0}{\partial t} - b^* \cdot \nabla_x v_1 \right) ds = 0$$

Replacing u_1 by its previous value in terms of $\nabla_x u_0$ we obtain the **homogenized problem**.

Homogenized equation

$$\left\{ \begin{array}{l} \frac{\partial u_0}{\partial t} - \operatorname{div} (A^* \nabla u_0) = 0 \\ u_0(t = 0, x) = \frac{|Y^*| u^0(x) + |\partial \mathcal{O}|_{N-1} v^0(x)}{|Y^*| + K |\partial \mathcal{O}|_{N-1}} \end{array} \right. \begin{array}{l} \text{in } \mathbb{R}^N \times (0, T) \\ \text{in } \mathbb{R}^N, \end{array}$$

The initial condition is an **average** of

$$u_0(t = 0, x) \approx u_\epsilon(t = 0, x) = u^0(x) \text{ in } Y^*$$

and

$$v_0(t = 0, x) = K u_0(t = 0, x) \approx v_\epsilon(t = 0, x) = v^0(x) \text{ on } \partial \mathcal{O}$$

How to make a rigorous proof

The proof is made of 3 steps

1. A priori estimates.
2. Passing to the limit by two-scale convergence with drift.
3. Strong convergence.

A priori estimate

The model is well-posed: it is a standard parabolic system of equations.

Energy estimate: multiply the bulk equation by u_ϵ and the surface equation by $\epsilon v_\epsilon/K$, integrate by parts to get

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \left(\int_{\Omega_\epsilon} |u_\epsilon|^2 dx + \frac{\epsilon}{K} \int_{\partial\Omega_\epsilon} |v_\epsilon|^2 ds \right) \\ & + \int_{\Omega_\epsilon} D_\epsilon \nabla u_\epsilon \cdot \nabla u_\epsilon dx + \frac{k}{\epsilon} \int_{\partial\Omega_\epsilon} \left(u_\epsilon - \frac{v_\epsilon}{K} \right)^2 ds = 0 \end{aligned}$$

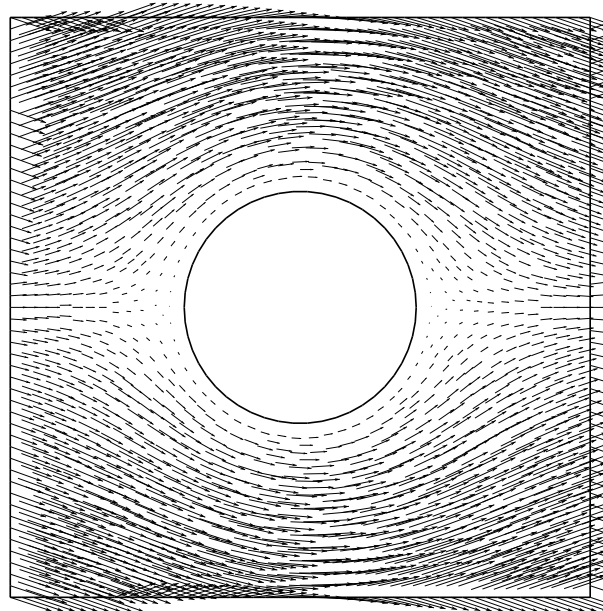
Two-scale convergence with drift

Proposition (Marusic-Paloka, Piatnitski). Let $b^* \in \mathbb{R}^N$ be a given drift velocity. Let w_ϵ be a bounded sequence in $L^2((0, T) \times \mathbb{R}^N)$. Up to a subsequence, there exist a limit $w_0(t, x, y) \in L^2((0, T) \times \mathbb{R}^N \times \mathbb{T}^N)$ such that w_ϵ **two-scale converges with drift** weakly to w_0 in the sense that

$$\lim_{\epsilon \rightarrow 0} \int_0^T \int_{\mathbb{R}^N} w_\epsilon(t, x) \phi \left(t, x - \frac{b^*}{\epsilon} t, \frac{x}{\epsilon} \right) dt dx = \int_0^T \int_{\mathbb{R}^N} \int_{\mathbb{T}^N} w_0(t, x, y) \phi(t, x, y) dt dx dy$$

for all functions $\phi(t, x, y) \in L^2((0, T) \times \mathbb{R}^N; C(\mathbb{T}^N))$.

-III- NUMERICAL RESULTS



Academic geometry for [qualitative](#) study. For real applications go for a [Representative Volume Element](#).

Numerical computations with FreeFem++ in 2-d for circular obstacles.

The incompressible velocity $b(y)$ is a Stokes solution in the unit cell Y .

Cell problem

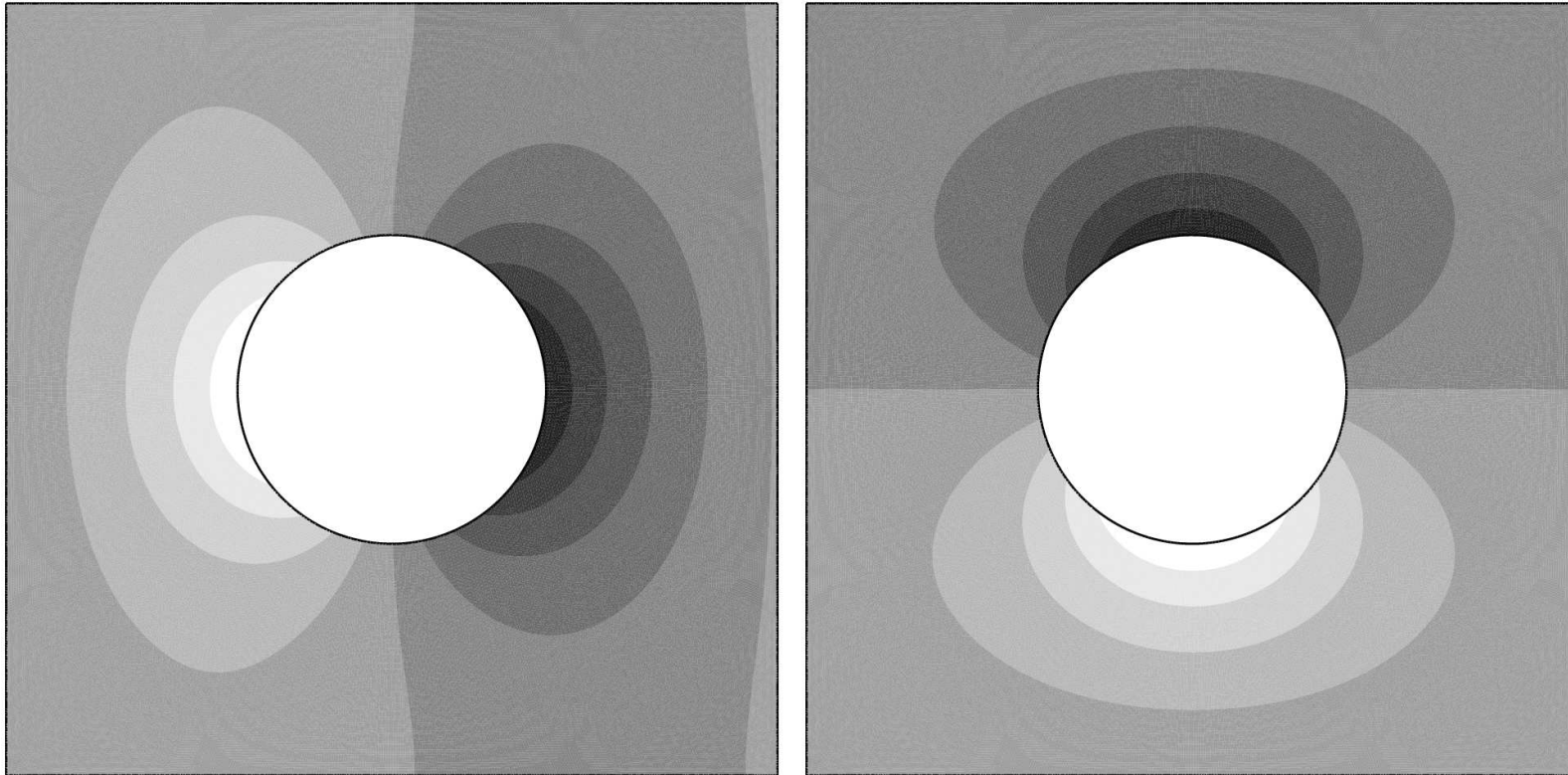
$$\left\{ \begin{array}{l} b(y) \cdot \nabla_y \chi_i - D \Delta_y \chi_i = (b^* - b(y)) \cdot e_i \text{ in } Y^* \\ D (\nabla_y \chi_i + e_i) \cdot n = K b^* \cdot e_i \text{ on } \partial \mathcal{O} \\ y \rightarrow \chi_i(y) \text{ } Y\text{-periodic} \end{array} \right.$$

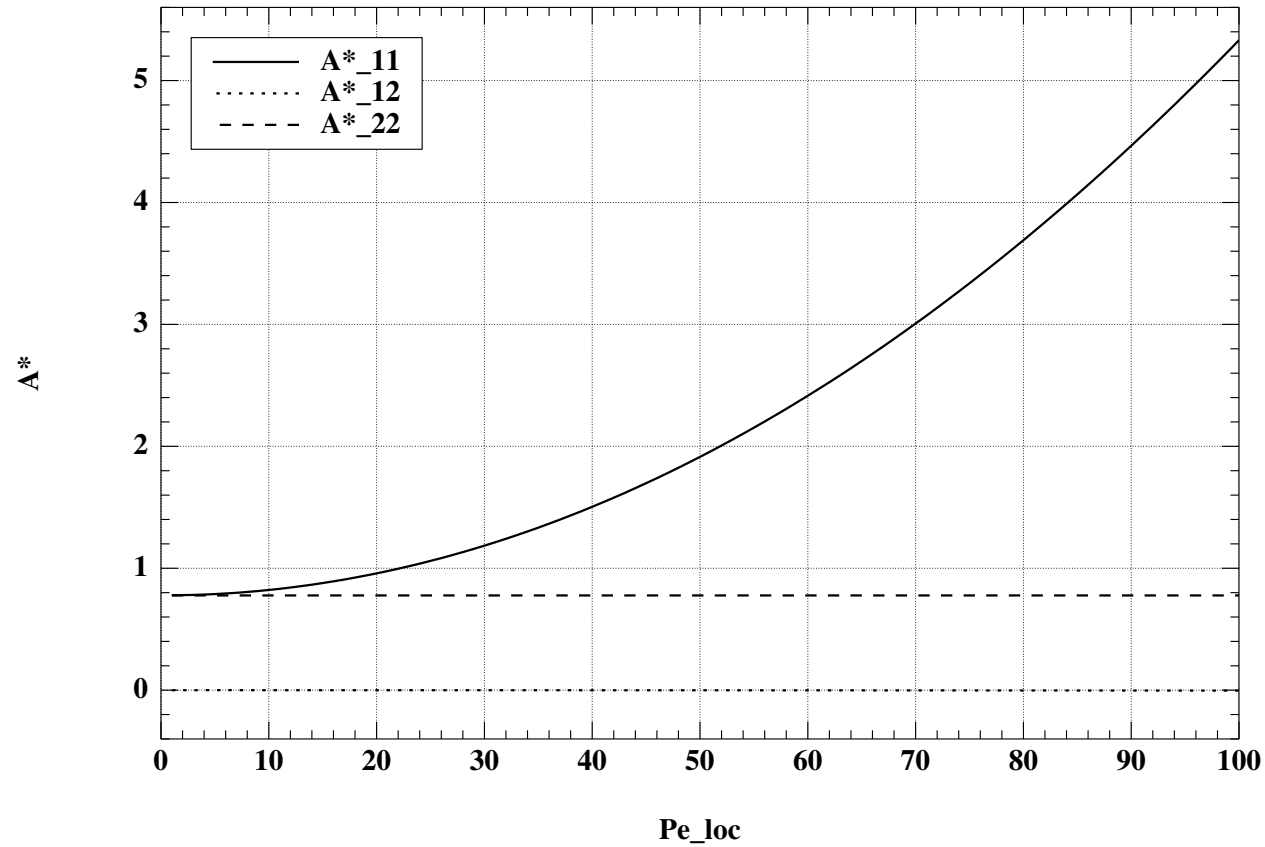
The homogenized velocity is

$$\mathbf{b}^* = \begin{pmatrix} 0.01808 \\ -6.759 \cdot 10^{-6} \end{pmatrix}$$

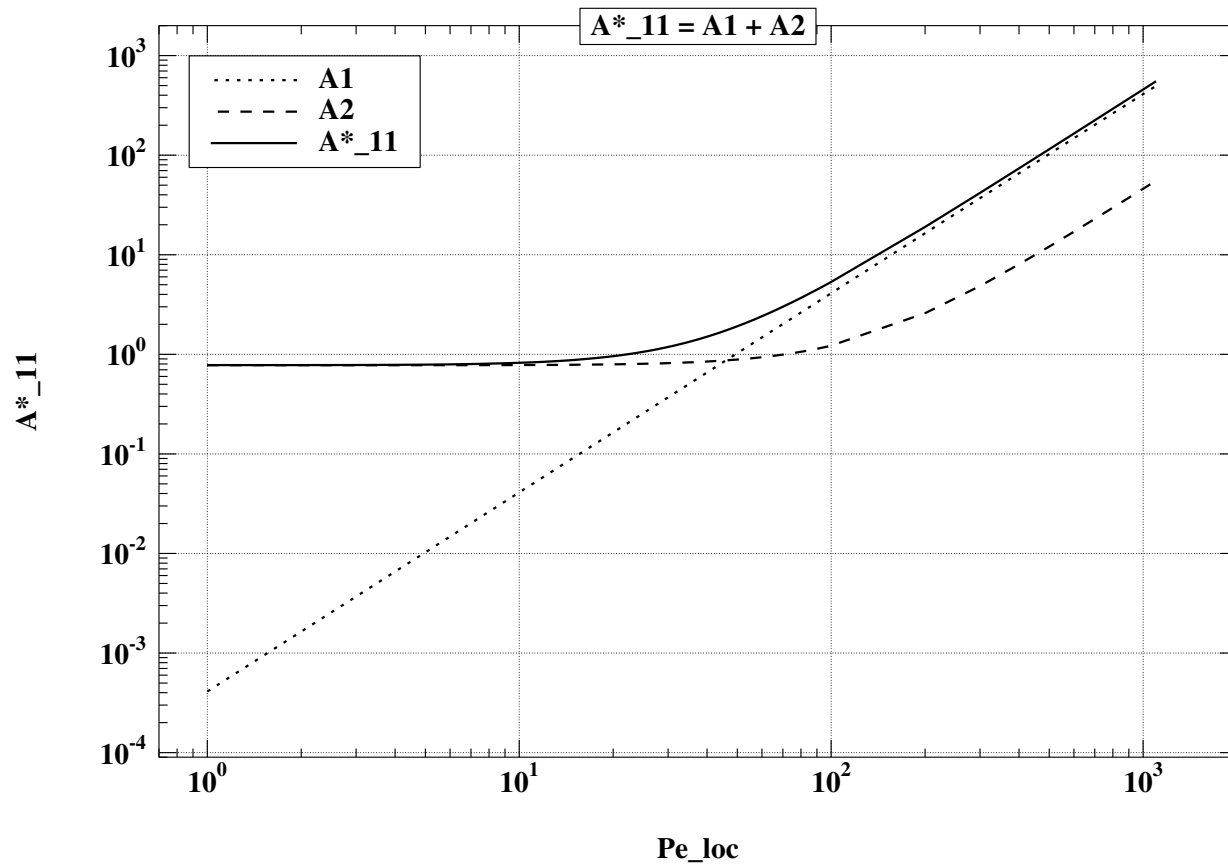
We plot the dispersion tensor A^* for increasing values of the Péclet number (multiplying the velocity field $b(y)$ by \mathbf{Pe}).

χ_1, χ_2

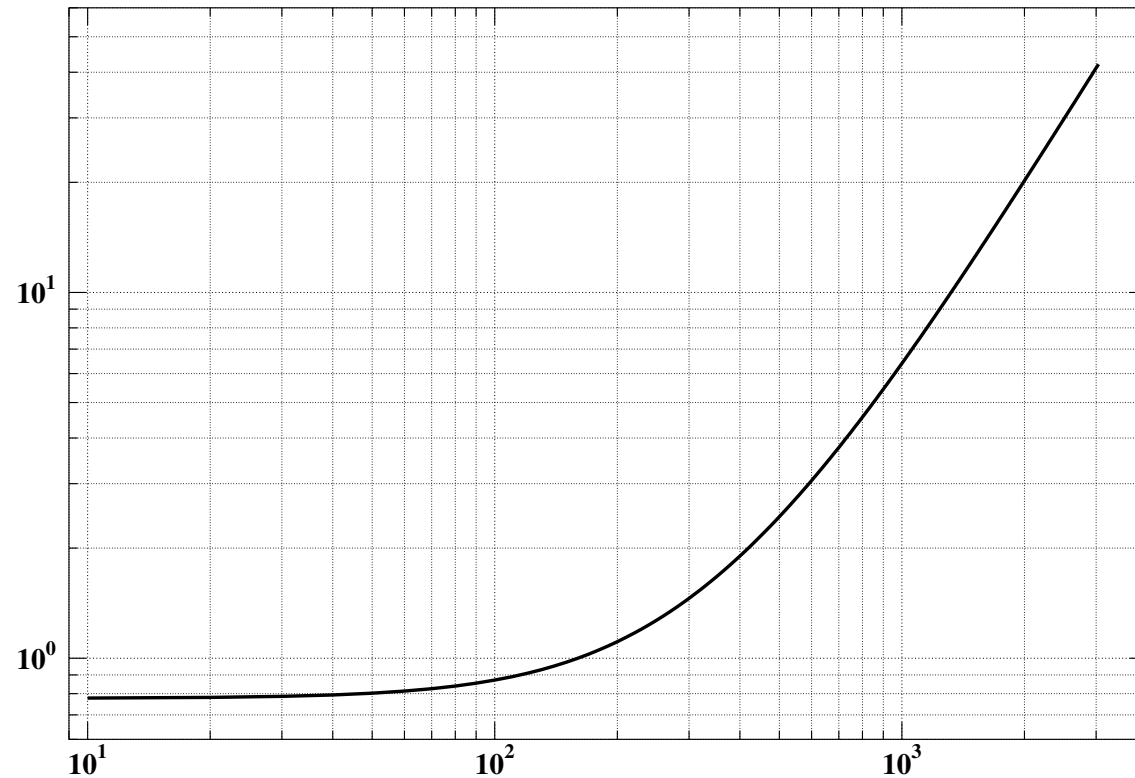




Entries A^*_{11} , A^*_{12} and A^*_{22} of the dispersion matrix A^* as a function of the local Péclet number, for $Da_{loc} = 1$.

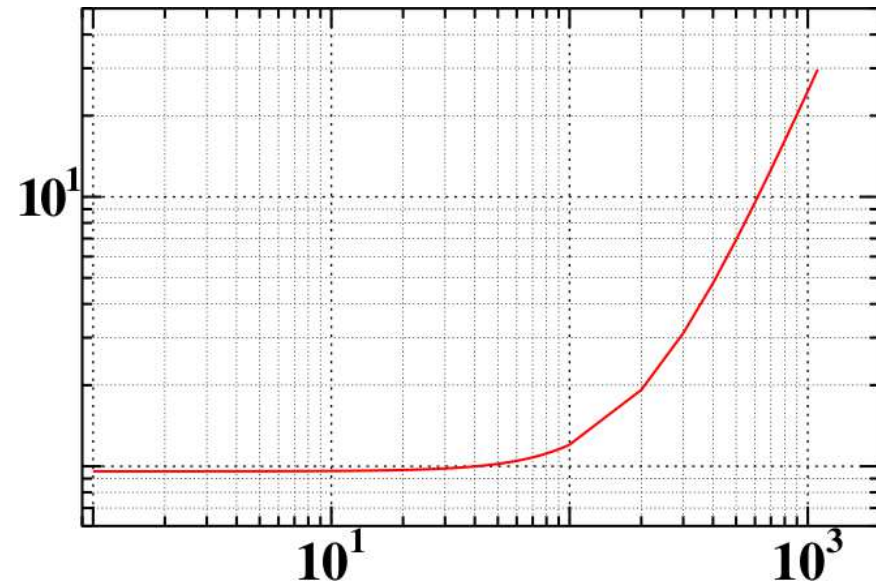
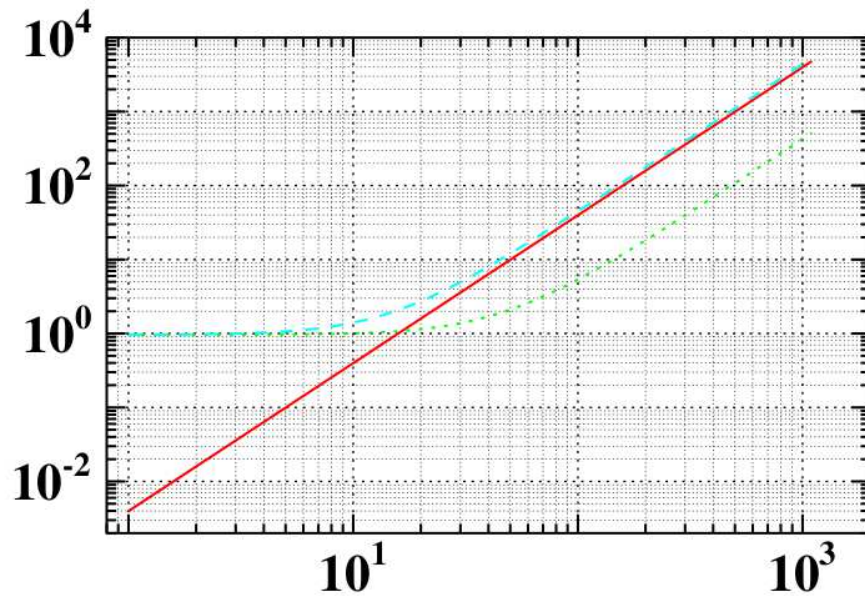


Log-log plot of the (1,1) entry of the dispersion matrix $A^* = A_1 + A_2$, together with its 2 components A_1 and A_2 , as a function of the local Péclet number, for $Da_{loc} = 1$.



Log-log plot of the longitudinal dispersion A_{11}^* as a function of the local Péclet number, in the **absence** of chemical reactions, $K = 0$ (asymptotic slope ≈ 1.7).

3-d case: obstacles are balls



Same log-log plot of the longitudinal dispersion A_{11}^* with (left) and without (right) chemical reactions in 3-d for a ball (asymptotic slope ≈ 1.9).

-IV- A NON-EQUILIBRIUM MODEL

- ✗ What if the velocity is not divergence-free ?
- ✗ What if reactions take place in the bulk ?
- ✗ For simplicity we address these issues on a simpler model **without surface concentration**.

convection diffusion reaction in the bulk:

$$\frac{\partial u}{\partial \tau} + b \cdot \nabla_y u - \operatorname{div}_y (D \nabla_y u) + r u = 0 \quad \text{in } \Omega_f \times (0, \mathcal{T}),$$

boundary condition:

$$-D \nabla_y u \cdot n = k u \quad \text{on } \partial \Omega_f \times (0, \mathcal{T}),$$

No assumption on the velocity $b(y)$ and on the reaction coefficient $r(y)$!

Scaling

To upscale this model, we define a large **macroscopic scale** ϵ^{-1} and a **long time scale** of order ϵ^{-2} (parabolic or diffusion scaling) $x = \epsilon y$ and $t = \epsilon^2 \tau$. We define $u_\epsilon(t, x) = u(\tau, y)$ which is a solution of

$$\left\{ \begin{array}{l} \frac{\partial u_\epsilon}{\partial t} + \frac{1}{\epsilon} b_\epsilon \cdot \nabla_x u_\epsilon - \operatorname{div}_x (D_\epsilon \nabla_x u_\epsilon) + \frac{1}{\epsilon^2} r_\epsilon u_\epsilon = 0 \quad \text{in } \Omega_\epsilon \times (0, T) \\ u_\epsilon(x, 0) = u_{init}(x), \quad x \in \Omega_\epsilon, \\ -D_\epsilon \nabla_x u_\epsilon \cdot n = \frac{k}{\epsilon} u_\epsilon \quad \text{on } \partial\Omega_\epsilon \times (0, T). \end{array} \right.$$

New ansatz: (unknown) drift $b^* \in \mathbb{R}^N$ and (unknown) reaction rate $r^* \in \mathbb{R}$

$$u_\epsilon(t, x) = e^{-r^* \epsilon^{-2} t} \sum_{i=0}^{+\infty} \epsilon^i u_i \left(t, x - \frac{b^* t}{\epsilon}, \frac{x}{\epsilon} \right),$$

with $u_i(t, x, y)$ Y -periodic with respect to y .

New ϵ^{-2} equation:

$$\begin{cases} b(y) \cdot \nabla_y u_0 - \operatorname{div}_y (D(y) \nabla_y u_0) + r(y) u_0 = r^* u_0 & \text{in } Y^* \\ D(y) \nabla_y u_0 \cdot n + k u_0 = 0 & \text{on } \partial \mathcal{O} \\ y \rightarrow u_0(x, y) & Y\text{-periodic} \end{cases}$$

It is a spectral problem ! The parameter r^* is the **first eigenvalue**:

$$\begin{cases} b \cdot \nabla_y \psi - \operatorname{div}_y (D \nabla_y \psi) + r \psi = r^* \psi & \text{in } Y^* \\ D \nabla_y \psi \cdot n + k \psi = 0 & \text{on } \partial \mathcal{O} \\ y \rightarrow \psi(y) & Y\text{-periodic} \end{cases}$$

By uniqueness of the first cell eigenfunction ψ (Krein-Rutman), we deduce

$$u_0(x, y) \equiv u(x) \psi(y)$$

Only the first eigenfunction is positive and can be interpreted as a local equilibrium concentration.

New ϵ^{-1} equation: (cell problem)

$$\left\{ \begin{array}{l} b(y) \cdot \nabla_y u_1 - \operatorname{div}_y (D(y) \nabla_y u_1) + r(y) u_1 - r^* u_1 = \\ \quad b^* \cdot \nabla_x u_0 - b(y) \cdot \nabla_x u_0 + \operatorname{div}_y (D(y) \nabla_x u_0) \text{ in } Y^* \\ \\ D(y) \nabla_y u_1(x, y) \cdot n + k u_1 = -D(y) \nabla_x u_0 \cdot n \text{ on } \partial \mathcal{O} \\ \\ y \rightarrow u_1(x, y) \text{ } Y\text{-periodic} \end{array} \right.$$

We define b^* such that the Fredholm alternative holds true, i.e. the right hand side is orthogonal to ψ^* the first adjoint eigenfunction.

We deduce that u_1 depends linearly on $\nabla_x u_0(x, y) = \psi(y) \nabla_x u(x)$:

$$u_1(x, y) = \sum_{i=1}^N \frac{\partial u}{\partial x_i}(x) \psi(y) w_i(y)$$

New ϵ^0 equation:

$$\left\{ \begin{array}{l} b \cdot \nabla_y u_2 - \operatorname{div}_y (D \nabla_y u_2) + r u_2 - r^* u_2 = b^* \cdot \nabla_x u_1 - b \cdot \nabla_x u_1 \\ \quad + \operatorname{div}_y (D \nabla_x u_1) + \operatorname{div}_x (D (\nabla_y u_1 + \nabla_x u_0)) - \frac{\partial u_0}{\partial t} + f \text{ in } Y^* \\ \\ D(y) \nabla_y u_2 \cdot n + k u_2 = -D(y) \nabla_x u_1 \cdot n \text{ on } \partial \mathcal{O} \\ \\ y \rightarrow u_2(x, y) \text{ } Y\text{-periodic} \end{array} \right.$$

Fredholm condition for the existence of u_2 :

$$\int_{Y^*} \left(b^* \cdot \nabla_x u_1 - b \cdot \nabla_x u_1 + \operatorname{div}_y (D \nabla_x u_1) + \operatorname{div}_x (D (\nabla_y u_1 + \nabla_x u_0)) - \frac{\partial u_0}{\partial t} + f \right) \psi^* dy - \int_{\partial \mathcal{O}} \psi^* D \nabla_x u_1 \cdot n ds = 0$$

We replace u_1 by its value in terms of $\nabla_x u$ and we find the **homogenized problem**.

Theorem.

$$u_\epsilon(t, x) \approx e^{-r^* \epsilon^{-2} t} \psi\left(\frac{x}{\epsilon}\right) u\left(t, x - \frac{b^* t}{\epsilon}\right)$$

Homogenized problem:

$$\begin{cases} \frac{\partial u}{\partial t} - \operatorname{div}(D^* \nabla u) = 0 & \text{in } \mathbb{R}^N \\ u(0) = u_{init} & \text{in } \mathbb{R}^N \end{cases}$$

with a new formula for D^* , and the effective velocity

$$b^* = \int_{Y^*} [\psi \psi^* b + \psi D \nabla \psi^* - \psi^* D \nabla \psi](y) dy$$

Equivalent statement of the same theorem

$$u_\epsilon(t, x) \approx \psi\left(\frac{x}{\epsilon}\right) \tilde{u}(t, x)$$

with $\tilde{u}(t, x) = e^{-r^* \epsilon^{-2} t} u\left(t, x - \frac{b^* t}{\epsilon}\right)$

Modified homogenized problem:

$$\begin{cases} \frac{\partial \tilde{u}}{\partial t} + \epsilon^{-1} b^* \cdot \nabla \tilde{u} - \operatorname{div}(D^* \nabla \tilde{u}) + \epsilon^{-2} r^* \tilde{u} = 0 & \text{in } \mathbb{R}^N \\ \tilde{u}(0) = u_{init} & \text{in } \mathbb{R}^N \end{cases}$$

Remark. Cf. H. Brenner - P. Adler (1982), R. Mauri (1991), P. Donato - A. Piatnitski (2006), G. Allaire - A.-L. Raphael (2007).

-V- GENERALIZATIONS AND CONCLUSION

Known generalizations:

- ★ Nonlinear effects: Langmuir isotherm for adsorption
- ★ Multiphase or multicomponents transport
- ★ Electrokinetics

Open problems:

- ★ Nonlinear effects with spatially varying drift
- ★ Multicomponent transport with non-linear reactions (law of mass action)
- ★ Stochastic setting rather than periodic (still with separation of scales)

G. Allaire, A.-L. Raphael, *Homogenization of a convection-diffusion model with reaction in a porous medium*, C. R. Acad. Sci. Paris, Série I, 344, 523-528 (2007).

G. Allaire, A. Mikelic, A. Piatnitski, *Homogenization approach to the dispersion theory for reactive transport through porous media*, SIAM J. Math. Anal. 42, 125-144 (2010).

G. Allaire, R. Brizzi, A. Mikelic, A. Piatnitski, *Two-scale expansion with drift approach to the Taylor dispersion for reactive transport through porous media*, Chemical Engineering Science, 65, pp.2292-2300 (2010).

G. Allaire, H. Hutridurga, *Homogenization of reactive flows in porous media and competition between bulk and surface diffusion*, IMA J. Appl. Math., 77, 788-815 (2012).

G. Allaire, A. Mikelic, A. Piatnitski, *Homogenization of The Linearized Ionic Transport Equations in Rigid Periodic Porous Media*, J. of Math. Physics, 51, 123103 (2010).

G. Allaire, R. Brizzi, J.-F. Dufrière, A. Mikelic, A. Piatnitski, *Role of non-ideality for the ion transport in porous media: derivation of the macroscopic equations using upscaling*, Physica D, 282, pp.39-60 (2014).

Cell problem for computing D^* and $u_1(x, y) = \sum_{i=1}^N \frac{\partial u}{\partial x_i}(x) \psi(y) w_i(y)$:

$$\begin{cases} \tilde{b} \cdot (e_i + \nabla_y w_i) - \operatorname{div}_y \left(\tilde{D} (e_i + \nabla_y w_i) \right) = b^* \cdot e_i & \text{in } Y^* \\ \tilde{D} (e_i + \nabla_y w_i) \cdot n = 0 & \text{on } \partial\mathcal{O} \\ y \rightarrow w_i(y) & Y\text{-periodic} \end{cases}$$

with $\tilde{D} = D\psi\psi^*$ and $\tilde{b} = [\psi\psi^*b + \psi D\nabla\psi^* - \psi^* D\nabla\psi]$ which satisfies

$$\operatorname{div}_y \tilde{b} = 0 \text{ in } Y^*, \quad \tilde{b} \cdot n = 0 \text{ on } \partial\mathcal{O}, \quad b^* = \frac{1}{|Y^*|} \int_{Y^*} \tilde{b}(y) dy.$$

Therefore the Fredholm condition is satisfied for w_i !

Homogenized diffusion tensor:

$$D_{ij}^* = \frac{1}{|Y^*|} \int_{Y^*} \tilde{D} (e_i + \nabla_y w_i) \cdot (e_j + \nabla_y w_j) dy.$$